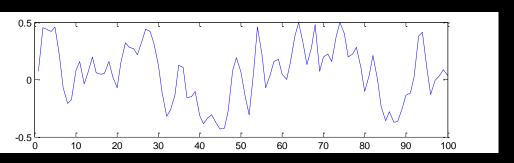
# CS4495/6495 Introduction to Computer Vision

2A-L4 Filters as templates

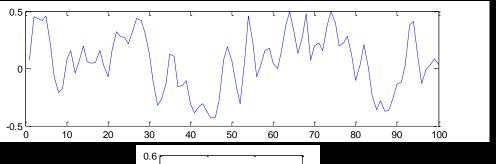
# 1D (nx)correlation



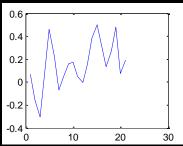


## 1D (nx)correlation





**Filter** 

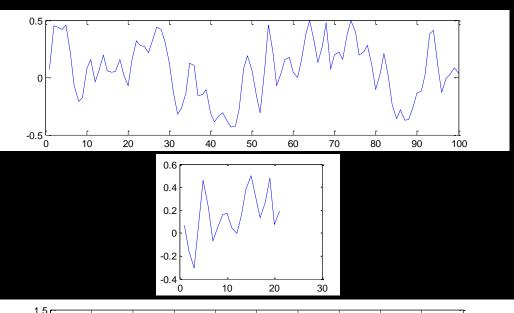


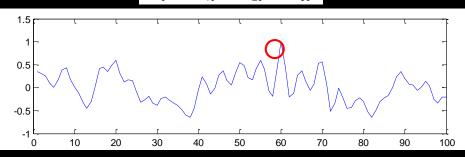
## 1D (nx)correlation



Filter

Normalized cross-correlation





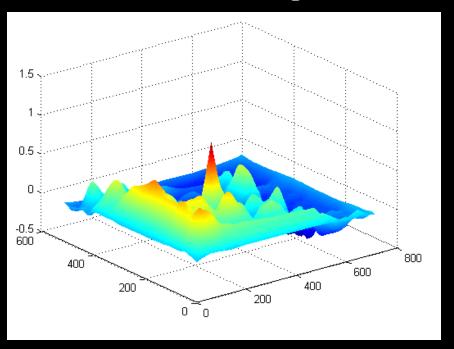
#### Matlab cross-correlation doc

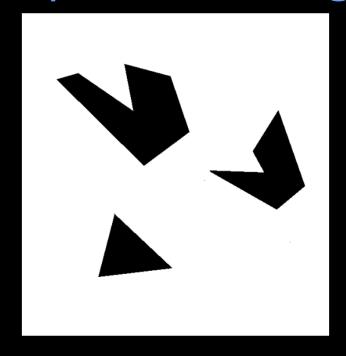
```
onion = rgb2gray(imread('onion.png'));
peppers = rgb2gray(imread('peppers.png'));
imshowpair(peppers,onion,'montage')
```



#### Matlab cross-correlation doc

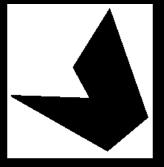
```
c = normxcorr2(onion,peppers);
figure, surf(c), shading flat;
```



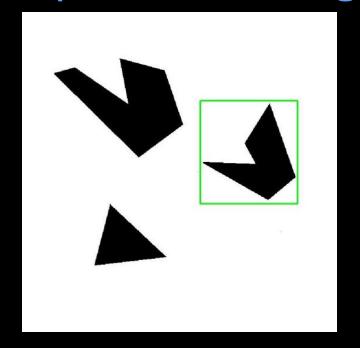


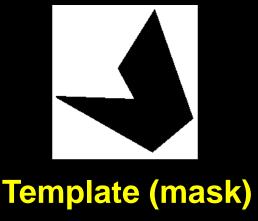
Scene

#### A toy example

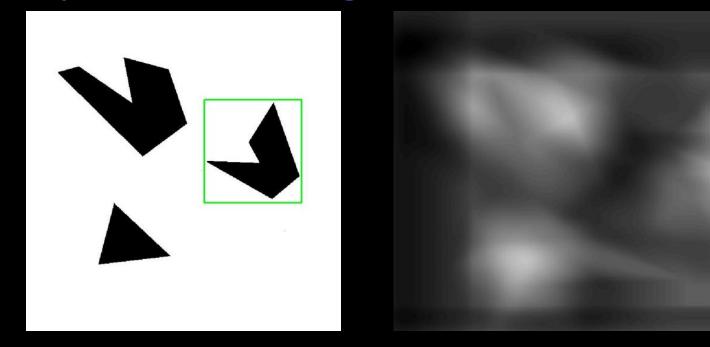


Template (mask)





**Detected template** 

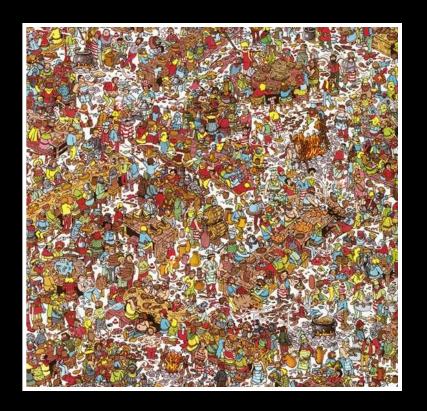


**Detected template** 

**Correlation map** 

## Where's Waldo?

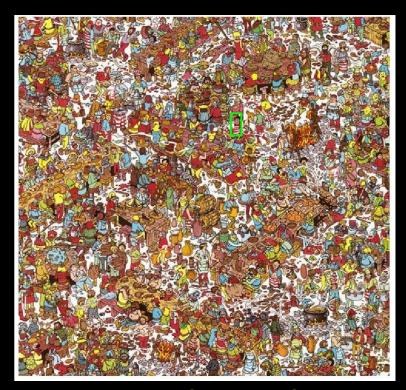
Scene





**Template** 

## Where's Waldo?

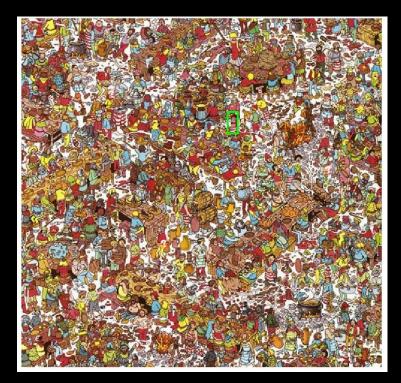




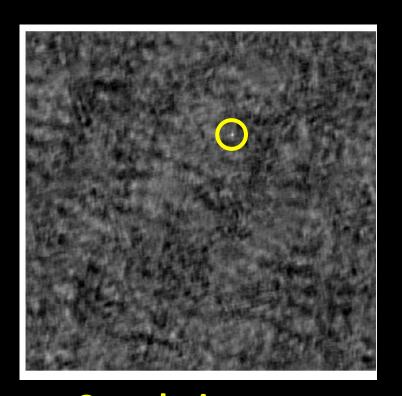
**Template** 

**Detected Template** 

### Where's Waldo?



**Detected template** 



**Correlation map** 

#### Quiz

Would this method work for finding Waldo in most situations?

- Yes normalized correlation is powerful.
- No we don't have the right template.
- Partially explain how?

What if the template is not identical to some subimage in the scene?

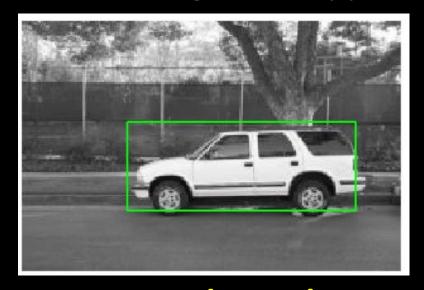




**Template** 

Scene

Match can be meaningful, if scale, orientation, and general appearance is right.





**Template** 

**Detected template** 

#### Summary

 We can use filters to localize "interesting" areas in an image by looking at how well a filter responds at different locations.

 Going forward we will use filters both to compute functions (like the smoothing) and to find strong responses to those functions (like templates).