

# Module Interface Specification for Optimal EM Placement

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# 1 Revision History

Date	Version	Notes
April 16, 2025	1.3	Implement instructor suggestions
April 16, 2025	1.2	Add moment and pose modules
April 16, 2025	1.1	Implement domain expert suggestions
March 20, 2025	1.0	Initial Release

## 2 Symbols, Abbreviations and Acronyms

See SRS Documentation at <https://github.com/husseinsd1/optimal-em-arrangement/blob/main/docs/SRS/SRS.pdf>

# Contents

<b>1</b>	<b>Revision History</b>	<b>i</b>
<b>2</b>	<b>Symbols, Abbreviations and Acronyms</b>	<b>ii</b>
<b>3</b>	<b>Introduction</b>	<b>1</b>
<b>4</b>	<b>Notation</b>	<b>1</b>
<b>5</b>	<b>Module Decomposition</b>	<b>1</b>
<b>6</b>	<b>MIS of Constant Parameters Module</b>	<b>3</b>
6.1	Module . . . . .	3
6.2	Uses . . . . .	3
6.3	Syntax . . . . .	3
6.3.1	Exported Constants . . . . .	3
6.3.2	Exported Access Programs . . . . .	3
6.4	Semantics . . . . .	3
6.4.1	State Variables . . . . .	3
6.4.2	Environment Variables . . . . .	3
6.4.3	Assumptions . . . . .	3
6.4.4	Access Routine Semantics . . . . .	3
6.4.5	Local Functions . . . . .	3
<b>7</b>	<b>MIS of Input Parameters Module</b>	<b>4</b>
7.1	Module . . . . .	4
7.2	Uses . . . . .	4
7.3	Syntax . . . . .	4
7.3.1	Exported Constants . . . . .	4
7.3.2	Exported Access Programs . . . . .	4
7.4	Semantics . . . . .	4
7.4.1	State Variables . . . . .	4
7.4.2	Environment Variables . . . . .	5
7.4.3	Assumptions . . . . .	5
7.4.4	Access Routine Semantics . . . . .	5
7.4.5	Local Functions . . . . .	5
<b>8</b>	<b>MIS of Magnetic Moment Module</b>	<b>6</b>
8.1	Module . . . . .	6
8.2	Uses . . . . .	6
8.3	Syntax . . . . .	6
8.3.1	Exported Constants . . . . .	6
8.3.2	Exported Access Programs . . . . .	6

8.4	Semantics . . . . .	6
8.4.1	State Variables . . . . .	6
8.4.2	Environment Variables . . . . .	6
8.4.3	Assumptions . . . . .	6
8.4.4	Access Routine Semantics . . . . .	6
8.4.5	Local Functions . . . . .	7
<b>9</b>	<b>MIS of Magnetic Field Module</b>	<b>8</b>
9.1	Module . . . . .	8
9.2	Uses . . . . .	8
9.3	Syntax . . . . .	8
9.3.1	Exported Constants . . . . .	8
9.3.2	Exported Access Programs . . . . .	8
9.4	Semantics . . . . .	8
9.4.1	State Variables . . . . .	8
9.4.2	Environment Variables . . . . .	8
9.4.3	Assumptions . . . . .	8
9.4.4	Access Routine Semantics . . . . .	8
9.4.5	Local Functions . . . . .	9
<b>10</b>	<b>MIS of Magnetic Force Module</b>	<b>10</b>
10.1	Module . . . . .	10
10.2	Uses . . . . .	10
10.3	Syntax . . . . .	10
10.3.1	Exported Constants . . . . .	10
10.3.2	Exported Access Programs . . . . .	10
10.4	Semantics . . . . .	10
10.4.1	State Variables . . . . .	10
10.4.2	Environment Variables . . . . .	10
10.4.3	Assumptions . . . . .	10
10.4.4	Access Routine Semantics . . . . .	10
10.4.5	Local Functions . . . . .	11
<b>11</b>	<b>MIS of Generate Poses Module</b>	<b>12</b>
11.1	Module . . . . .	12
11.2	Uses . . . . .	12
11.3	Syntax . . . . .	12
11.3.1	Exported Constants . . . . .	12
11.3.2	Exported Access Programs . . . . .	12
11.4	Semantics . . . . .	12
11.4.1	State Variables . . . . .	12
11.4.2	Environment Variables . . . . .	12
11.4.3	Assumptions . . . . .	12

11.4.4	Access Routine Semantics . . . . .	12
11.4.5	Local Functions . . . . .	13
<b>12</b>	<b>MIS of Actuation Matrix Module</b>	<b>14</b>
12.1	Module . . . . .	14
12.2	Uses . . . . .	14
12.3	Syntax . . . . .	14
12.3.1	Exported Constants . . . . .	14
12.3.2	Exported Access Programs . . . . .	14
12.4	Semantics . . . . .	14
12.4.1	State Variables . . . . .	14
12.4.2	Environment Variables . . . . .	14
12.4.3	Assumptions . . . . .	14
12.4.4	Access Routine Semantics . . . . .	14
12.4.5	Local Functions . . . . .	15
<b>13</b>	<b>MIS of Optimal Placement Module</b>	<b>16</b>
13.1	Module . . . . .	16
13.2	Uses . . . . .	16
13.3	Syntax . . . . .	16
13.3.1	Exported Constants . . . . .	16
13.3.2	Exported Access Programs . . . . .	16
13.4	Semantics . . . . .	16
13.4.1	State Variables . . . . .	16
13.4.2	Environment Variables . . . . .	16
13.4.3	Assumptions . . . . .	16
13.4.4	Access Routine Semantics . . . . .	16
13.4.5	Local Functions . . . . .	17
<b>14</b>	<b>MIS of Output Results Module</b>	<b>18</b>
14.1	Module . . . . .	18
14.2	Uses . . . . .	18
14.3	Syntax . . . . .	18
14.3.1	Exported Constants . . . . .	18
14.3.2	Exported Access Programs . . . . .	18
14.4	Semantics . . . . .	18
14.4.1	State Variables . . . . .	18
14.4.2	Environment Variables . . . . .	18
14.4.3	Assumptions . . . . .	18
14.4.4	Access Routine Semantics . . . . .	18
14.4.5	Local Functions . . . . .	19

<b>15 MIS of Main (Control) Module</b>	<b>20</b>
15.1 Module . . . . .	20
15.2 Uses . . . . .	20
15.3 Syntax . . . . .	20
15.3.1 Exported Constants . . . . .	20
15.3.2 Exported Access Programs . . . . .	20
15.4 Semantics . . . . .	20
15.4.1 State Variables . . . . .	20
15.4.2 Environment Variables . . . . .	21
15.4.3 Assumptions . . . . .	21
15.4.4 Access Routine Semantics . . . . .	21
15.4.5 Local Functions . . . . .	21

## 3 Introduction

The following document details the Module Interface Specifications for OEMP (Optimal Electromagnet Placement). This document describes, in detail, how the interfaces, assumptions and interactions among the modules of the program.

Complementary documents include the [System Requirement Specifications](#) and [Module Guide](#). The full documentation and implementation can be found at <https://github.com/husseinsd1/optimal-em-arrangement>.

## 4 Notation

The structure of the MIS for modules comes from [Hoffman and Strooper \(1995\)](#), with the addition that template modules have been adapted from [Ghezzi et al. \(2003\)](#). The mathematical notation comes from Chapter 3 of [Hoffman and Strooper \(1995\)](#). For instance, the symbol  $:=$  is used for a multiple assignment statement and conditional rules follow the form  $(c_1 \Rightarrow r_1 | c_2 \Rightarrow r_2 | \dots | c_n \Rightarrow r_n)$ .

The following table summarizes the primitive data types used by Optimal EM Placement.

Data Type	Notation	Description
character	char	a single symbol or digit
integer	$\mathbb{Z}$	a number without a fractional component in $(-\infty, \infty)$
natural number	$\mathbb{N}$	a number without a fractional component in $[1, \infty)$
real	$\mathbb{R}$	any number in $(-\infty, \infty)$

The specification of Optimal EM Placement uses some derived data types: sequences, strings, tuples, and vectors. Sequences are lists filled with elements of the same data type. Strings are sequences of characters. Tuples contain a list of values, potentially of different types. An  $n$ -dimensional vector is a list of  $n$  real numbers. In addition, Optimal EM Placement uses functions, which are defined by the data types of their inputs and outputs. Local functions are described by giving their type signature followed by their specification.

## 5 Module Decomposition

The following table is taken directly from the Module Guide document for this project.



Level 1	Level 2
Hardware-Hiding Module	
	Constant Parameters Module
	Input Parameters Module
	Magnetic Moment Module
Behaviour-Hiding Module	Magnetic Field Module
	Magnetic Force Module
	Generate Poses Module
	Actuation Matrix Module
	Output Results Module
	Main (Control) Module
Software Decision Module	Optimal Placement Module

Table 1: Module Hierarchy

## 6 MIS of Constant Parameters Module

### 6.1 Module

ConstantParams

### 6.2 Uses

None

### 6.3 Syntax

#### 6.3.1 Exported Constants

Label	Symbol	Value	Description
MU0	$\mu_0$	$4\pi \times 10^{-7}$	Permeability of free space
MAX_CURR	$I_{\max}$	20000	Maximum EM current allowed

#### 6.3.2 Exported Access Programs

None

### 6.4 Semantics

#### 6.4.1 State Variables

None

#### 6.4.2 Environment Variables

None

#### 6.4.3 Assumptions

Constant values are assumed immutable.

#### 6.4.4 Access Routine Semantics

None

#### 6.4.5 Local Functions

None

## 7 MIS of Input Parameters Module

### 7.1 Module

InputParams

### 7.2 Uses

- Hardware-Hiding Module

### 7.3 Syntax

#### 7.3.1 Exported Constants

None

#### 7.3.2 Exported Access Programs

Name	In	Out	Exceptions
loadParams	String	params of type Params	fileNotFound, inputError

### 7.4 Semantics

Params is a data structure used to store the parameter values the user enters into the program.

#### 7.4.1 State Variables

```
params : Params = [  
  N :  $\mathbb{N}$ ,  
  I :  $\mathbb{R}$ ,  
  A :  $\mathbb{R}$ ,  
  M :  $\mathbb{N}$ ,  
  K :  $\mathbb{N}$ ,  
  V :  $\mathbb{R}$ ,  
  t :  $\mathbb{R}^3$ ,  
  mt :  $\mathbb{R}^3$   
  l :  $\mathbb{R}$   
  eml :  $\mathbb{R}$   
]
```

The description of the elements of the above array is found in Section 1.2 of the [SRS](#).

### 7.4.2 Environment Variables

- A console: The medium through which the user will enter the parameter values.
- A keyboard: The module takes input from the user's keyboard.

### 7.4.3 Assumptions

None

### 7.4.4 Access Routine Semantics

takeInputs():

- transition:
  - Display prompt (on the console) for user to enter the config file path.
  - Extract parameters from file and use them to create an instance of **Params**.
- output: params : **Params**
- exception: exc =

Exception	When
fileNotFound	When no JSON file is found at the given path.
inputError	When any of the inputs does not satisfy the constraints given in Table 2 of the <a href="#">SRS</a>

### 7.4.5 Local Functions

None

## 8 MIS of Magnetic Moment Module

### 8.1 Module

MagMoment

### 8.2 Uses

None

### 8.3 Syntax

#### 8.3.1 Exported Constants

None

#### 8.3.2 Exported Access Programs

Name	In	Out	Exceptions
calculateMoment	$N : \mathbb{N}, I : \mathbb{R}, A : \mathbb{R}$	$\mathbb{R}$	None

### 8.4 Semantics

#### 8.4.1 State Variables

None

#### 8.4.2 Environment Variables

None

#### 8.4.3 Assumptions

None

#### 8.4.4 Access Routine Semantics

calculateMoment( $N : \mathbb{N}, I : \mathbb{R}, A : \mathbb{R}$ ):

- transition: N/A
- output: The result of using the given inputs in the magnetic moment formula described in TM1 of the [SRS](#).
- exception: N/A

#### 8.4.5 Local Functions

None

## 9 MIS of Magnetic Field Module

### 9.1 Module

MagField

### 9.2 Uses

- Constant Parameters Module

### 9.3 Syntax

#### 9.3.1 Exported Constants

None

#### 9.3.2 Exported Access Programs

Name	In	Out	Exceptions
calculateField	$m : \mathbb{R}, t : \mathbb{R}^3, p : \mathbb{R}^3, R : \mathbb{R}^{3 \times 3}$	$\mathbb{R}^3$	None

### 9.4 Semantics

#### 9.4.1 State Variables

None

#### 9.4.2 Environment Variables

None

#### 9.4.3 Assumptions

None

#### 9.4.4 Access Routine Semantics

calculateField( $m : \mathbb{R}, t : \mathbb{R}^3, p : \mathbb{R}^3, R : \mathbb{R}^{3 \times 3}$ ):

- transition: N/A.
- output: This module outputs a real 3D vector describing the magnetic field at some distance  $t$  (retrieved from params), by doing the following:
  - Calculate the vector  $r$  by subtracting  $t - p$ .

- Find  $\hat{r} = \frac{r}{||r||}$
- Find the magnetic field with the given parameters, the calculated  $r$  and  $\hat{r}$  vectors, and  $\mu_0$  from the Constant Parameters Module using the equation defined in TM2 of the [SRS](#).
- exception: N/A

#### 9.4.5 Local Functions

None



## 10 MIS of Magnetic Force Module

### 10.1 Module

MagForce

### 10.2 Uses

None

### 10.3 Syntax

#### 10.3.1 Exported Constants

None

#### 10.3.2 Exported Access Programs

Name	In	Out	Exceptions
calculateForce	$B : \mathbb{R}^{3 \times 3}, m_t : \mathbb{R}^{3 \times 3}$	$\mathbb{R}^3$	None

### 10.4 Semantics

#### 10.4.1 State Variables

None

#### 10.4.2 Environment Variables

None

#### 10.4.3 Assumptions

None

#### 10.4.4 Access Routine Semantics

calculateForce( $B : \mathbb{R}^{3 \times 3}, m_t : \mathbb{R}^{3 \times 3}$ ):

- transition: N/A.
- output: A real 3D vector describing the magnetic force on some target, calculated using the formula in TM3 of the [SRS](#)
- exception: N/A.

### 10.4.5 Local Functions

None

## 11 MIS of Generate Poses Module

### 11.1 Module

GeneratePoses

### 11.2 Uses

None

### 11.3 Syntax

#### 11.3.1 Exported Constants

None

#### 11.3.2 Exported Access Programs

Name	In	Out	Exceptions
generatePoses	$M : \mathbb{N}, l : \mathbb{R}$	array of $M$ pairs	None

### 11.4 Semantics

#### 11.4.1 State Variables

None

#### 11.4.2 Environment Variables

None

#### 11.4.3 Assumptions

None

#### 11.4.4 Access Routine Semantics

generatePoses( $M : \mathbb{N}, l : \mathbb{R}$ ):

- transition: N/A
- output: An  $M$  sized array of random poses, each generated with the **generatePose** function defined below.
- exception: N/A

#### 11.4.5 Local Functions

**generatePose**( $l : \mathbb{R}$ ): A function to generate a single random pose.

- output: A random 3D coordinate within the under-the-table space, and a 3D rotation matrix.
- exception: None

## 12 MIS of Actuation Matrix Module

### 12.1 Module

ActuationMatrix

### 12.2 Uses

- Magnetic Field Module
- Magnetic Force Module

### 12.3 Syntax

#### 12.3.1 Exported Constants

None

#### 12.3.2 Exported Access Programs

Name	In	Out	Exceptions
constructMatrix	poses : Array, $m : \mathbb{R}$ , $m_t : \mathbb{R}^3, t : \mathbb{R}^3$	$\mathbb{R}^6$	None

### 12.4 Semantics

#### 12.4.1 State Variables

None

#### 12.4.2 Environment Variables

None

#### 12.4.3 Assumptions

None

#### 12.4.4 Access Routine Semantics

constructMatrix(poses : Array,  $m : \mathbb{R}$ ,  $m_t : \mathbb{R}^3$ ,  $t : \mathbb{R}^3$ ):

- transition: N/A.
- output: A  $6 \times 1$  real matrix constructed through the following steps:

- For each position ( $p$ ) and rotation ( $R$ ) in poses, calculate the magnetic force and field vectors using Magnetic Force Module and Magnetic Field Module, respectively.
  - Sum up the force and field vectors of all poses. This is two 3D vectors.
  - Concatenate the two vectors such that a  $6 \times 1$  matrix is formed.
- exception: N/A

#### **12.4.5 Local Functions**

None

## 13 MIS of Optimal Placement Module

### 13.1 Module

FindOptPositions

### 13.2 Uses

None

### 13.3 Syntax

#### 13.3.1 Exported Constants

None

#### 13.3.2 Exported Access Programs

Name	In	Out	Exceptions
solve	$M : \mathbb{N}, K : \mathbb{N}, \mathcal{U} : \mathbb{R}^6,$ $poses : \text{Array}, em_l : \mathbb{R}$	binary vector in $\mathbb{R}^M$	SolverException

### 13.4 Semantics

#### 13.4.1 State Variables

None

#### 13.4.2 Environment Variables

None

#### 13.4.3 Assumptions

None

#### 13.4.4 Access Routine Semantics

$\text{solve}(\mathbb{N}, K : \mathbb{N}, \mathcal{U} : \mathbb{R}^6, poses : \text{Array}, em_l : \mathbb{R})$ :

- transition: N/A.
- output: A vector  $x \in \{0, 1\}^M$  such that:
  - $\mathbf{1}_M^\top x = K$  ( $\mathbf{1}$  is a ones vector).
  - $\lambda_{\min}$  of  $\sum_{i=1}^K x_i \mathcal{U}_i \mathcal{U}_i^\top$  is maximized.

The vector is found by applying the following:

- Compute and store  $\mathcal{U}\mathcal{U}^\top$
- Pass  $\mathcal{U}\mathcal{U}^\top$ ,  $M$  and  $K$  into a `cvxpy` solver.
- exception: Any exceptions raised by the solver.

#### **13.4.5 Local Functions**

None



## 14 MIS of Output Results Module

### 14.1 Module

OutputResults

### 14.2 Uses

- Hardware-Hiding Module

### 14.3 Syntax

#### 14.3.1 Exported Constants

None

#### 14.3.2 Exported Access Programs

Name	In	Out	Exceptions
output	$x \in \{0,1\}^M$ , $K : \mathbb{N}$ , poses : Array	-	None

### 14.4 Semantics

#### 14.4.1 State Variables

None

#### 14.4.2 Environment Variables

Console: this module prints elements of  $x$  and poses onto the console for the user to see.

#### 14.4.3 Assumptions

None

#### 14.4.4 Access Routine Semantics

output( $x \in \{0,1\}^M$ ,  $K : \mathbb{N}$ , poses : Array):

- transition:
  - Prints the vector  $x$  onto the console.
  - Prints the poses corresponding to the selected ( $= 1$ ) indices in  $x$ .
- output: N/A
- exception: None

#### 14.4.5 Local Functions

None

## 15 MIS of Main (Control) Module

### 15.1 Module

main

### 15.2 Uses

- Hardware-Hiding Module
- Constant Parameter Module
- Input Parameters Module
- Magnetic Field Module
- Magnetic Force Module
- Actuation Matrix Module
- Optimal Placement Module
- Output Results Module
- Magnetic Moment Module
- Generate Poses Module

### 15.3 Syntax

#### 15.3.1 Exported Constants

None

#### 15.3.2 Exported Access Programs

Name	In	Out	Exceptions
main	-	-	Various

### 15.4 Semantics

#### 15.4.1 State Variables

- `params` : Params
- `moment` :  $\mathbb{R}$
- `poses` : Array

- $\mathcal{U} : \mathbb{R}^6$
- $x \in \{0, 1\}^M$

#### 15.4.2 Environment Variables

None

#### 15.4.3 Assumptions

None

#### 15.4.4 Access Routine Semantics

main():

- transition:
  - Call and store params from Input Parameters Module.
  - Store the magnetic moment calculated using the Magnetic Moment Module.
  - Generate and store poses using the Generate Poses Module.
  - Invoke the Actuation Matrix Module and store the returned  $\mathcal{U}$  vector (Actuation Matrix will itself invoke the modules responsible for the magnetic field/force and constant parameters).
  - Provide the  $\mathcal{U}$  vector and params to Optimal Placement Module, and store the returned  $x$  vector.
  - Pass the returned  $x$  vector to Output Results Module.
- output: N/A
- exception: Exceptions arising from submodules.

#### 15.4.5 Local Functions

None

## References

- Carlo Ghezzi, Mehdi Jazayeri, and Dino Mandrioli. *Fundamentals of Software Engineering*. Prentice Hall, Upper Saddle River, NJ, USA, 2nd edition, 2003.
- Daniel M. Hoffman and Paul A. Strooper. *Software Design, Automated Testing, and Maintenance: A Practical Approach*. International Thomson Computer Press, New York, NY, USA, 1995. URL <http://citeseer.ist.psu.edu/428727.html>.