

Calibration results

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Camera-system parameters:

cam0 (/image):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.07422772 0.0771713 0.00041969 0.00101847] +- [0.00157593 0.00251097 0.00025089 0.00027114]

projection: [874.12678401 873.94839467 667.26419083 513.08823924] +- [2.26030955 2.23137756 1.1287005
1.07233137]

reprojection error: [0.000000, -0.000001] +- [0.148856, 0.115432]

Target configuration

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Type: aprilgrid

Tags:

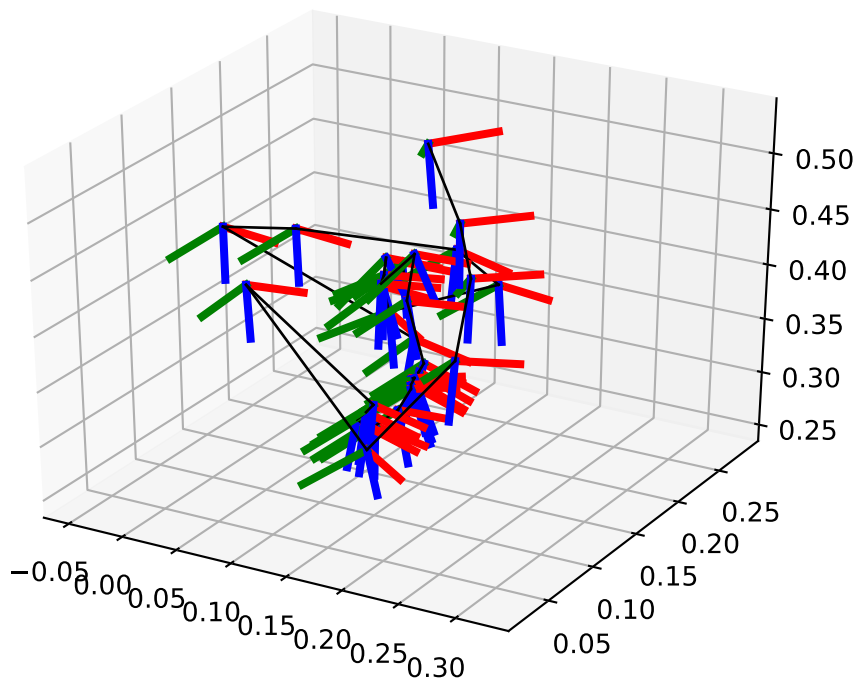
Rows: 6

Cols: 6

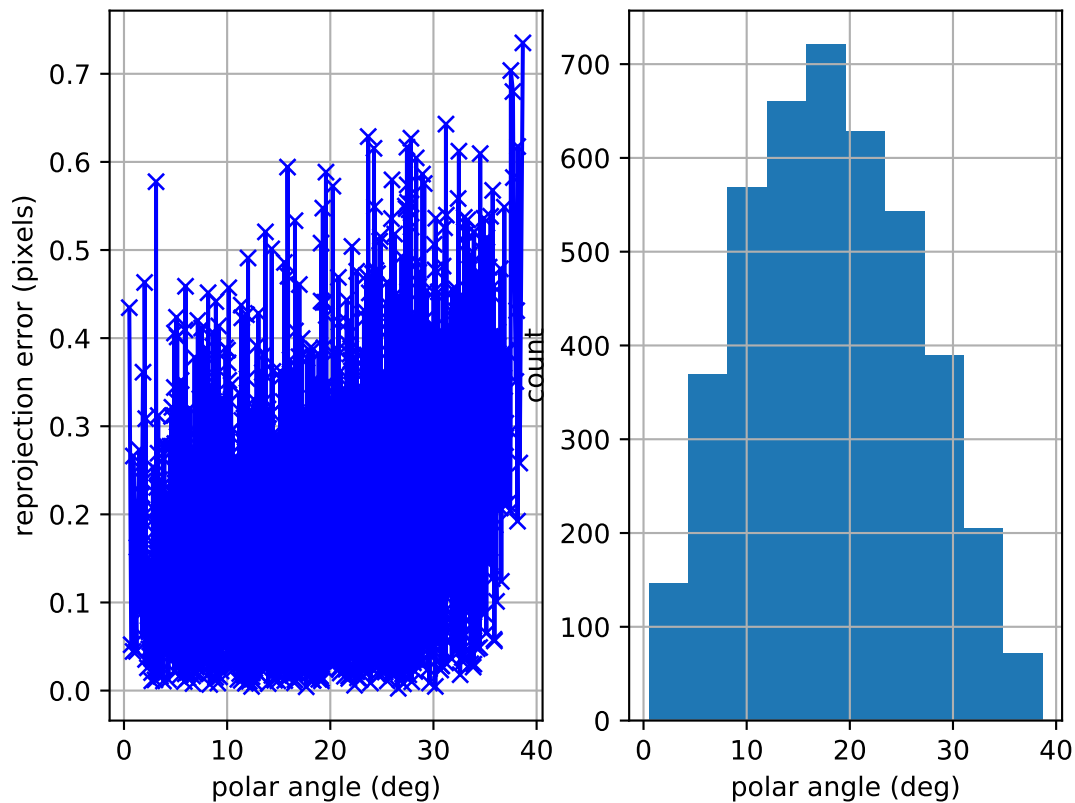
Size: 0.0352 [m]

Spacing 0.01056 [m]

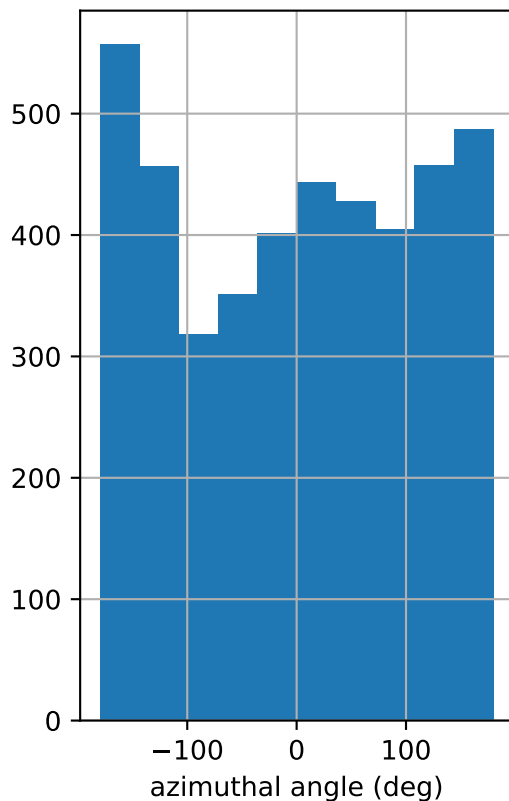
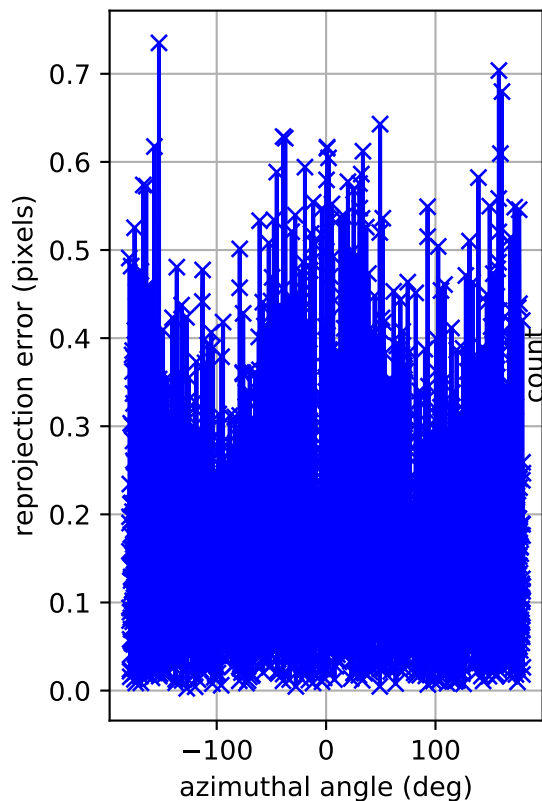
cam0: estimated poses



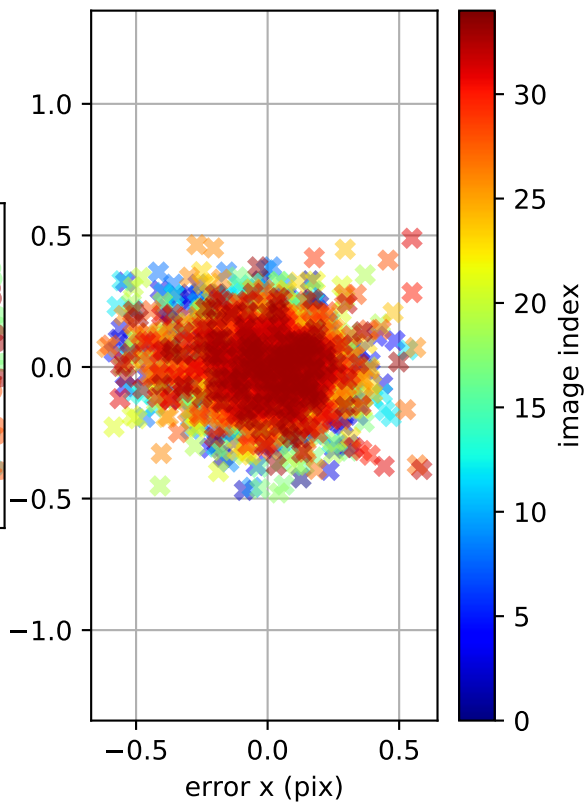
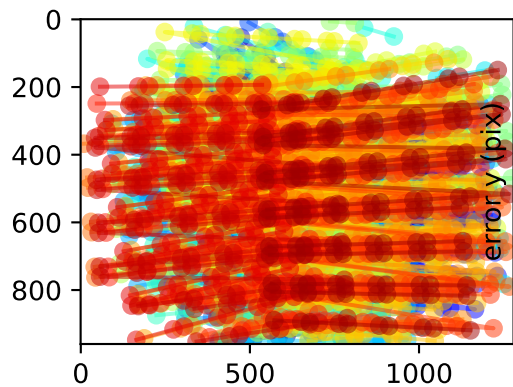
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

