Computer Vision HW10

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Description

I implemented Laplacian, Minimum Variance Laplacian, Laplacian of Gaussian, and Difference of Gaussian(inhibitory sigma=1, excitatory sigma=3, kernel size 11x11 [1][1])

Parameters

```
int headerLength = 172;
int imageWidth = 512;
int imageHeight = 512;
```

Kernels

 $\{2.0f/3, -1.0f/3, 2.0f/3\}$

},1,1);

```
Kernel LoGKernel = new Kernel(new float[][]{
```

},5,5);

Kernel DoGKernel = new Kernel(new float[][]{

,,0,0,

Threshold Values listed below:

Laplace Mask Type1: 15 Laplace Mask Type2: 15

Minimum variance Laplacian: 20

Laplace of Gaussian: 3000 Difference of Gaussian: 1

Principal code

```
public static ArrayList<Integer> CrossingEdgeDetector(ArrayList<Integer>
origin, int headerLength, int width, int height, Kernel kernel, int
threshold)
     {
           ArrayList<Integer> results =
InitWhite(origin, headerLength, width, height);
           ArrayList<Integer> temp =
InitWhite(origin, headerLength, width, height);
           for(int y = 0; y < height; y++)
                 for(int x = 0; x < width; x++)
                 {
                      float tempValue =
CalculateKernel(origin, headerLength, width, height, kernel, x, y);
                      temp.set(headerLength+y*width+x,(int)tempValue);
                 }
           }
           for(int y = 0; y < height; y++)
                 for(int x = 0; x < width; x++)
                 {
                      for(int y2 = -1; y2 < 2; y2++)
                            //System.out.println(x+":"+y);
                            for(int x2 = -1; x2 < 2; x2++)
if(isDifferenceGreaterThan(temp,headerLength,width,height,x,y,x2,y2,thre
shold))
                                  {
                                       results.set(headerLength+y*width
+x,0);
                                  }
                            }
                      }
                 }
           }
           return results;
     }
```

```
public static boolean isDifferenceGreaterThan(ArrayList<Integer>
origin, int headerLength, int width, int height, int x, int y, int x2, int
y2, int threshold)
           int newIndexX = x + x2;
           int newIndexY = y + y2;
           if(newIndexX < 0) return false;</pre>
           if(newIndexY < 0) return false;</pre>
           if(newIndexX >= width) return false;
           if(newIndexY >= height) return false;
           int originValue = origin.get(headerLength+width*y+x);
           int nearValue = origin.get(headerLength+width*newIndexY
+newIndexX);
           if(originValue > threshold && nearValue < -threshold)</pre>
           {
                 return true;
           }
           else
           {
                 return false;
           }
     }
```

Results



Laplacian Mask Type 1 - Threshold : 15



Laplacian Mask Type 2 - Threshold : 15



Minimum Variance Laplacian - Threshold: 20



Laplace of Gaussian - Threshold : 3000



Difference of Gaussian - Threshold : 1