Operating System Review

胡祥龙 (Xianglong Hu) 07/29/2018

Contents

1 2.3 Interprocess Communication

2

1 2.3 Interprocess Communication

race conditions 121

critical regions 121

disable interrupts too much privilege, cannot be applied to multicore processors.

lock variables race is still there.

busy waiting the lock is called the spin lock, 但是 Process A 会在 Process B 不在 critical region 的时候等待,导致浪费了时间。

```
while (TRUE) {
    while (turn != 0) / loop /;
    critical region();

turn = 1;
    noncritical region();

while (TRUE) {
    while (turn != 1) / loop /;
    critical region();

turn = 0;
    noncritical region();
}
```

Peterson's solution 这个不错,但是似乎只能用于两个 Processes?

```
#define FALSE 0
           #define TRUE 1
           #define N 2 / number of processes
           int turn; / whose turn is it? /
           int interested[N]; / all values initially 0 (FALSE)
           void enter region(int process); / process is 0 or 1
           {
           int other; / number of the other process /
           other = 1 - process; / the opposite of process
           [TRUE; / Show that you are interested]
           tur n = process; / set flag /
           while (turn == process && interested[other] == TRUE) / null statement
      / ;
           void leave region(int process) / process: who is leaving
           interested [process] = FALSE; / indicate departure from critical region
           }
17
```