# Xindi Hu

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#### **EDUCATION**

University of Toronto

B.A.Sc Computer Engineering

Toronto, Canada Sep 2021 - Jun 2026

#### **TECHNICAL SKILLS & AWARDS**

Programming Languages: C/C++, Python, SQL, Verilog, MATLAB

Tools: Git, Linux, Unix, Deep Learning, Vim/VS Code

**Awards:** Dean's Honor Lists for semesters

#### **EXPERIENCE**

INDIE SEMICONDUCTOR

Toronto, Canada May 2024 - Aug 2025

# **Embedded Software Engineering Intern**

Collaborated with software/hardware development team to design and implement firmware validation and verification tests for Host Tools API, SDK API, and software tools using **Python, C**, and **Robot Framework**.

- Implemented test cases that interfaced with image sensors and processor chips via SPI, I<sup>2</sup>C, and UART communication protocols to validate on-device drivers and ensure reliable hardware-software integration across various APIs.
- Developed automated scripts to parse and validate 30+ APIs for multiple hardware configurations and features, achieving 100% test automation coverage.
- Utilized Git for version control and integrated Git with JIRA to manage workflows, track development progress, and handle multiple branches efficiently.

#### AOYUN ELECTRICS

Wuhan, China

### **Embedded System Engineer Intern**

May 2023 - Sep 2023

- Engineered an advanced control algorithm using C and Verilog on a TMS320F2812 microcontroller, enhanced the Electric Fuel Car's power performance by 0.52%
- Implemented a function for real-time engine speed calculation, integrated 3 facets of input to build a feed-back algorithm, optimized the vehicle's power efficiency and responsiveness.
- Conducted comprehensive design verifications and collaborated with the team toward project requirements, ensured seamless code function.

## **PROJECTS**

### OBJECT DETECTION MACHINE LEARNING MODEL

Sep 2023 - Dec 2023

- Collaborated in an Agile Scrum team to contribute to the development of a Faster R-CNN based object detection and segmentation model for automated vehicles, focused on enhancing traffic and obstacle detection
- Spearheaded the acquisition and processing of 100,000+ images from the various public dataset, emphasized efficient data pre-processing and conversion to tensors for optimal Pytorch performance.
- Managed the designing the architecture of a foundational model, integrated 30+ convolution layers with multiple pooling techniques to establish a valid comparison case for the main model in our automated vehicle project
- Engaged in thorough theoretical testing and data-driven optimization of the model, focused on enhancing accuracy and robustness for its application in automated driving systems.

### GIS Navigation System

Jan 2023 - Apr 2023

- Led the vision and scope definition through initial planning meetings, established a detailed product roadmap, and
  formulated release plans. Facilitated team progress with regular sprint planning, daily stand-ups, and ensured continuous
  improvement through sprint reviews and retrospectives.
- Cached data from public APIs, including OpenStreetMap (OSM) API, into self-developed data structures, to achieve a response time deduction of 78% in average, 99% in extreme cases according to system timer.
- Enhanced a Dijkstra-based pathfinding algorithm to optimize route calculations, secured a distinguished 7th place ranking among over 90 teams in a competitive class setting.

# "PIXEL WAR" GAME

Jan 2023 - Apr 2023

- Led a two-person team in developing Pixel War Game, an acclaimed arcade-style video game designed for FPGA board. Established a git-based collaborative environment and implemented a 4-phase structured workflow.
- Utilized C programming and hardware interrupts for efficient management of 6 IO devices. Achieved real-time
  response to player inputs by handling interrupts from both the PS/2 keyboard and the DE1-Soc board, enhancing user
  interaction and system responsiveness.
- Crafted an engaging and visually appealing game user interface using a VGA interface, earned an outstanding coursework grade of 85% for its high playability and impressive visual aesthetics.