

In[91]:= G[u0_, u1_, u2_, u3_, u4_, u5_] :=

$$\begin{aligned} & u0^3 * u1^3 * u2^3 * u3^3 * u4^3 * u5^3 - u0^3 * u1^3 * u2^2 * u3^2 * u4^2 * u5^2 - \\ & u0^3 * u1^2 * u2^3 * u3^2 * u4^2 * u5^2 - u0^2 * u1^3 * u2^3 * u3^2 * u4^2 * u5^2 - \\ & u0^3 * u1^2 * u2^2 * u3^3 * u4^2 * u5^2 - u0^2 * u1^3 * u2^2 * u3^3 * u4^2 * u5^2 - \\ & u0^2 * u1^2 * u2^3 * u3^3 * u4^2 * u5^2 - u0^3 * u1^2 * u2^2 * u3^2 * u4^3 * u5^2 - \\ & u0^2 * u1^3 * u2^2 * u3^2 * u4^3 * u5^2 - u0^2 * u1^2 * u2^3 * u3^2 * u4^3 * u5^2 - \\ & u0^2 * u1^2 * u2^2 * u3^3 * u4^3 * u5^2 - u0^3 * u1^2 * u2^2 * u3^2 * u4^2 * u5^3 - \\ & u0^2 * u1^3 * u2^2 * u3^2 * u4^2 * u5^3 - u0^2 * u1^2 * u2^3 * u3^2 * u4^2 * u5^3 - \\ & u0^2 * u1^2 * u2^2 * u3^3 * u4^2 * u5^3 - u0^2 * u1^2 * u2^2 * u3^2 * u4^3 * u5^3 + \\ & u0^3 * u1^2 * u2^2 * u3^2 * u4^2 * u5 + u0^2 * u1^3 * u2^2 * u3^2 * u4^2 * u5 + \\ & u0^2 * u1^2 * u2^3 * u3^2 * u4^2 * u5 + u0^2 * u1^2 * u2^2 * u3^3 * u4^2 * u5 + \\ & u0^2 * u1^2 * u2^2 * u3^2 * u4^3 * u5 + u0^3 * u1^2 * u2^2 * u3^2 * u4 * u5^2 + \\ & u0^2 * u1^3 * u2^2 * u3^2 * u4 * u5^2 + u0^2 * u1^2 * u2^3 * u3^2 * u4 * u5^2 + \\ & u0^2 * u1^2 * u2^2 * u3^3 * u4 * u5^2 + u0^3 * u1^2 * u2^2 * u3 * u4^2 * u5^2 + \\ & u0^2 * u1^3 * u2^2 * u3 * u4^2 * u5^2 + u0^2 * u1^2 * u2^3 * u3 * u4^2 * u5^2 + \\ & u0^3 * u1^2 * u2 * u3^2 * u4^2 * u5^2 + u0^2 * u1^3 * u2 * u3^2 * u4^2 * u5^2 + \\ & u0^3 * u1 * u2^2 * u3^2 * u4^2 * u5^2 + 5 * u0^2 * u1^2 * u2^2 * u3^2 * u4^2 * u5^2 + \\ & u0 * u1^3 * u2^2 * u3^2 * u4^2 * u5^2 + u0^2 * u1 * u2^3 * u3^2 * u4^2 * u5^2 + \\ & u0 * u1^2 * u2^3 * u3^2 * u4^2 * u5^2 + u0^2 * u1^2 * u2 * u3^3 * u4^2 * u5^2 + \\ & u0^2 * u1 * u2^2 * u3^3 * u4^2 * u5^2 + u0 * u1^2 * u2^2 * u3^3 * u4^2 * u5^2 + \\ & u0^2 * u1^2 * u2^2 * u3 * u4^3 * u5^2 + u0^2 * u1^2 * u2 * u3^2 * u4^3 * u5^2 + \\ & u0^2 * u1 * u2^2 * u3^2 * u4^3 * u5^2 + u0 * u1^2 * u2^2 * u3^2 * u4^3 * u5^2 + \\ & u0^2 * u1^2 * u2^2 * u3^2 * u4 * u5^3 + u0^2 * u1^2 * u2^2 * u3 * u4^2 * u5^3 + \\ & u0^2 * u1^2 * u2 * u3^2 * u4^2 * u5^3 + u0^2 * u1 * u2^2 * u3^2 * u4^2 * u5^3 + \\ & u0 * u1^2 * u2^2 * u3^2 * u4^2 * u5^3 - u0^2 * u1^2 * u2^2 * u3^2 * u4^2 * u5 - \\ & u0^2 * u1^2 * u2^2 * u3^2 * u4 * u5 - u0^2 * u1^2 * u2^2 * u3 * u4^2 * u5 - \\ & u0^2 * u1^2 * u2 * u3^2 * u4^2 * u5 - u0^2 * u1 * u2^2 * u3^2 * u4^2 * u5 - \\ & u0 * u1^2 * u2^2 * u3^2 * u4^2 * u5 - u0^2 * u1^2 * u2^2 * u3^2 * u5^2 - \\ & u0^2 * u1^2 * u2^2 * u3 * u4 * u5^2 - u0^2 * u1^2 * u2 * u3^2 * u4 * u5^2 - \\ & u0^2 * u1 * u2^2 * u3^2 * u4 * u5^2 - u0 * u1^2 * u2^2 * u3^2 * u4 * u5^2 - \\ & u0^2 * u1^2 * u2^2 * u4^2 * u5^2 - u0^2 * u1^2 * u2 * u3 * u4^2 * u5^2 - \\ & u0^2 * u1 * u2^2 * u3 * u4^2 * u5^2 - u0 * u1^2 * u2^2 * u3 * u4^2 * u5^2 - \\ & u0^2 * u1^2 * u3^2 * u4^2 * u5^2 - u0^2 * u1 * u2 * u3^2 * u4^2 * u5^2 - \\ & u0 * u1^2 * u2 * u3^2 * u4^2 * u5^2 - u0^2 * u2^2 * u3^2 * u4^2 * u5^2 - \\ & u0 * u1 * u2^2 * u3^2 * u4^2 * u5^2 - u1^2 * u2^2 * u3^2 * u4^2 * u5^2 - \\ & u0^3 * u1 * u2 * u3 * u4 * u5 - u0^2 * u1^2 * u2 * u3 * u4 * u5 - u0 * u1^3 * u2 * u3 * u4 * u5 - \\ & u0^2 * u1 * u2^2 * u3 * u4 * u5 - u0 * u1^2 * u2^2 * u3 * u4 * u5 - \\ & u0 * u1 * u2^3 * u3 * u4 * u5 - u0^2 * u1 * u2 * u3^2 * u4 * u5 - \\ & u0 * u1^2 * u2 * u3^2 * u4 * u5 - u0 * u1 * u2^2 * u3^2 * u4 * u5 - \\ & u0 * u1 * u2 * u3^3 * u4 * u5 - u0^2 * u1 * u2 * u3 * u4^2 * u5 - \\ & u0 * u1^2 * u2 * u3 * u4^2 * u5 - u0 * u1 * u2^2 * u3 * u4^2 * u5 - \\ & u0 * u1 * u2 * u3^2 * u4^2 * u5 - u0 * u1 * u2 * u3 * u4^3 * u5 - \\ & u0^2 * u1 * u2 * u3 * u4 * u5^2 - u0 * u1^2 * u2 * u3 * u4 * u5^2 - \\ & u0 * u1 * u2^2 * u3 * u4 * u5^2 - u0 * u1 * u2 * u3^2 * u4 * u5^2 - \\ & u0 * u1 * u2 * u3 * u4^2 * u5^2 - u0 * u1 * u2 * u3 * u4 * u5^3 + u0^2 * u1 * u2 * u3 * u4 + \\ & u0 * u1^2 * u2 * u3 * u4 + u0 * u1 * u2^2 * u3 * u4 + u0 * u1 * u2 * u3^2 * u4 + \\ & u0 * u1 * u2 * u3 * u4^2 + u0^2 * u1 * u2 * u3 * u5 + u0 * u1^2 * u2 * u3 * u5 + \end{aligned}$$

```

u0 * u1 * u2 ^ 2 * u3 * u5 + u0 * u1 * u2 * u3 ^ 2 * u5 + u0 ^ 2 * u1 * u2 * u4 * u5 +
u0 * u1 ^ 2 * u2 * u4 * u5 + u0 * u1 * u2 ^ 2 * u4 * u5 + u0 ^ 2 * u1 * u3 * u4 * u5 +
u0 * u1 ^ 2 * u3 * u4 * u5 + u0 ^ 2 * u2 * u3 * u4 * u5 + 5 * u0 * u1 * u2 * u3 * u4 * u5 +
u1 ^ 2 * u2 * u3 * u4 * u5 + u0 * u2 ^ 2 * u3 * u4 * u5 + u1 * u2 ^ 2 * u3 * u4 * u5 +
u0 * u1 * u3 ^ 2 * u4 * u5 + u0 * u2 * u3 ^ 2 * u4 * u5 + u1 * u2 * u3 ^ 2 * u4 * u5 +
u0 * u1 * u2 * u4 ^ 2 * u5 + u0 * u1 * u3 * u4 ^ 2 * u5 + u0 * u2 * u3 * u4 ^ 2 * u5 +
u1 * u2 * u3 * u4 ^ 2 * u5 + u0 * u1 * u2 * u3 * u5 ^ 2 + u0 * u1 * u2 * u4 * u5 ^ 2 +
u0 * u1 * u3 * u4 * u5 ^ 2 + u0 * u2 * u3 * u4 * u5 ^ 2 + u1 * u2 * u3 * u4 * u5 ^ 2 -
u0 * u1 * u2 * u3 - u0 * u1 * u2 * u4 - u0 * u1 * u3 * u4 - u0 * u2 * u3 * u4 - u1 * u2 * u3 * u4 -
u0 * u1 * u2 * u5 - u0 * u1 * u3 * u5 - u0 * u2 * u3 * u5 - u1 * u2 * u3 * u5 - u0 * u1 * u4 * u5 -
u0 * u2 * u4 * u5 - u1 * u2 * u4 * u5 - u0 * u3 * u4 * u5 - u1 * u3 * u4 * u5 - u2 * u3 * u4 * u5 + 1

```

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In[93]:= Solve[{u1 * u2 == t1, u2 * u4 == t3, u0 * u3 == t2 ^ 2 / t1, u3 * u4 == t2 * t3 / t1,
u0 * u4 == t3 ^ 2 / t1, u1 * u5 == t1 ^ 2 / t2, u0 * u5 == t1, u4 * u5 == t1 * t3 / t2,
u0 * u2 == t2, u1 * u4 == t3 ^ 2 / t2, u2 * u5 == t1 ^ 2 / t3, u3 * u5 == t1 * t2 / t3,
u2 * u3 == t2 ^ 2 / t3, u1 * u3 == t2, u0 * u1 == t3}, {u0, u1, u2, u3, u4, u5}]

```

```

Out[93]= {{u0 -> - (sqrt(t2) sqrt(t3) / sqrt(t1)), u1 -> - (sqrt(t1) sqrt(t3) / sqrt(t2)), u2 -> - (sqrt(t1) sqrt(t2) / sqrt(t3)), u3 -> - (t2 ^ (3/2) / (sqrt(t1) sqrt(t3))),
u4 -> - (t3 ^ (3/2) / (sqrt(t1) sqrt(t2))), u5 -> - (t1 ^ (3/2) / (sqrt(t2) sqrt(t3)))}, {u0 -> (sqrt(t2) sqrt(t3) / sqrt(t1)), u1 -> (sqrt(t1) sqrt(t3) / sqrt(t2)),
u2 -> (sqrt(t1) sqrt(t2) / sqrt(t3)), u3 -> (t2 ^ (3/2) / (sqrt(t1) sqrt(t3))), u4 -> (t3 ^ (3/2) / (sqrt(t1) sqrt(t2))), u5 -> (t1 ^ (3/2) / (sqrt(t2) sqrt(t3)))}}

```

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In[97]:= Together[

```

$$G\left[-\frac{\sqrt{t_2} \sqrt{t_3}}{\sqrt{t_1}}, -\frac{\sqrt{t_1} \sqrt{t_3}}{\sqrt{t_2}}, -\frac{\sqrt{t_1} \sqrt{t_2}}{\sqrt{t_3}}, -\frac{t_2^{3/2}}{\sqrt{t_1} \sqrt{t_3}}, -\frac{t_3^{3/2}}{\sqrt{t_1} \sqrt{t_2}}, -\frac{t_1^{3/2}}{\sqrt{t_2} \sqrt{t_3}}\right]$$

```

Out[97]= 1 / (t1 t2 t3
(- t1^3 t2^2 + t1^4 t2^2 - t1^2 t2^3 + t1^3 t2^3 + t1^2 t2^4 - t1^4 t2^4 + t1 t2 t3 - t1^3 t2 t3 + t1^4 t2 t3 -
t1^5 t2 t3 - 2 t1^2 t2^2 t3 + 3 t1^3 t2^2 t3 - t1^4 t2^2 t3 - t1 t2^3 t3 + 3 t1^2 t2^3 t3 - 2 t1^3 t2^3 t3 -
t1^4 t2^3 t3 + t1^5 t2^3 t3 + t1 t2^4 t3 - t1^2 t2^4 t3 - t1^3 t2^4 t3 + t1^4 t2^4 t3 - t1 t2^5 t3 +
t1^3 t2^5 t3 - t1^3 t3^2 + t1^4 t3^2 - 2 t1^2 t2 t3^2 + 3 t1^3 t2 t3^2 - t1^4 t2 t3^2 - 2 t1 t2^2 t3^2 +
5 t1^2 t2^2 t3^2 - 2 t1^3 t2^2 t3^2 - 2 t1^4 t2^2 t3^2 + t1^5 t2^2 t3^2 - t2^3 t3^2 + 3 t1 t2^3 t3^2 -
2 t1^2 t2^3 t3^2 - 2 t1^3 t2^3 t3^2 + 3 t1^4 t2^3 t3^2 - t1^5 t2^3 t3^2 + t2^4 t3^2 - t1 t2^4 t3^2 -
2 t1^2 t2^4 t3^2 + 3 t1^3 t2^4 t3^2 - t1^4 t2^4 t3^2 + t1^2 t2^5 t3^2 - t1^3 t2^5 t3^2 - t1^2 t3^3 +
t1^3 t3^3 - t1 t2 t3^3 + 3 t1^2 t2 t3^3 - 2 t1^3 t2 t3^3 - t1^4 t2 t3^3 + t1^5 t2 t3^3 - t2^2 t3^3 +
3 t1 t2^2 t3^3 - 2 t1^2 t2^2 t3^3 - 2 t1^3 t2^2 t3^3 + 3 t1^4 t2^2 t3^3 - t1^5 t2^2 t3^3 + t2^3 t3^3 -
2 t1 t2^3 t3^3 - 2 t1^2 t2^3 t3^3 + 5 t1^3 t2^3 t3^3 - 2 t1^4 t2^3 t3^3 - t1 t2^4 t3^3 + 3 t1^2 t2^4 t3^3 -
2 t1^3 t2^4 t3^3 + t1 t2^5 t3^3 - t1^2 t2^5 t3^3 + t1^2 t3^4 - t1^4 t3^4 + t1 t2 t3^4 - t1^2 t2 t3^4 -
t1^3 t2 t3^4 + t1^4 t2 t3^4 + t2^2 t3^4 - t1 t2^2 t3^4 - 2 t1^2 t2^2 t3^4 + 3 t1^3 t2^2 t3^4 - t1^4 t2^2 t3^4 -
t1 t2^3 t3^4 + 3 t1^2 t2^3 t3^4 - 2 t1^3 t2^3 t3^4 - t2^4 t3^4 + t1 t2^4 t3^4 - t1^2 t2^4 t3^4 +
t1^4 t2^4 t3^4 - t1 t2 t3^5 + t1^3 t2 t3^5 + t1^2 t2^2 t3^5 - t1^3 t2^2 t3^5 + t1 t2^3 t3^5 - t1^2 t2^3 t3^5)

```

```

In[161]:= G44tangent[t1_, t2_, t3_] :=
  Det[DiagonalMatrix[{-t1 + 1, -t2 + 1, -t3 + 1, (-t2^2 + t1) / t1,
    (-t2 * t3 + t1) / t1, (-t3^2 + t1) / t1, (-t1^2 + t2) / t2, -t1 + 1,
    (-t1 * t3 + t2) / t2, -t2 + 1, -t3 + 1, (-t3^2 + t2) / t2, (-t1^2 + t3) / t3,
    (-t1 * t2 + t3) / t3, -t1 + 1, (-t2^2 + t3) / t3, -t2 + 1, -t3 + 1}]]

In[160]:=

In[162]:= Together[%97 / G44tangent[t1, t2, t3]]
Out[162]= - ( (t1^2 t2^2 t3^2 (-t1^3 t2^2 - t1^2 t2^3 - t1^3 t2^3 + t1 t2 t3 + t1^2 t2 t3 + t1^4 t2 t3 + t1 t2^2 t3 -
  t1^2 t2^2 t3 + t1^4 t2^2 t3 + t1 t2^4 t3 + t1^2 t2^4 t3 - t1^3 t3^2 + t1 t2 t3^2 -
  t1^2 t2 t3^2 + t1^4 t2 t3^2 - t1 t2^2 t3^2 + t1^3 t2^2 t3^2 - t2^3 t3^2 + t1^2 t2^3 t3^2 -
  t1^3 t2^3 t3^2 + t1 t2^4 t3^2 - t1^2 t3^3 - t1^3 t3^3 - t2^2 t3^3 + t1^2 t2^2 t3^3 - t1^3 t2^2 t3^3 -
  t2^3 t3^3 - t1^2 t2^3 t3^3 - t1^3 t2^3 t3^3 + t1 t2 t3^4 + t1^2 t2 t3^4 + t1 t2^2 t3^4) ) /
  ( (-1 + t1)^2 (t1^2 - t2) (-1 + t2)^2 (t1 - t2^2) (t1^2 - t3) (t1 t2 - t3) (t2^2 - t3)
    (-1 + t3)^2 (-t2 + t1 t3) (t1 - t2 t3) (t1 - t3^2) (t2 - t3^2) ) )

In[168]:= G44[t1_, t2_, t3_] :=
  - ( (t1^2 t2^2 t3^2 (-t1^3 t2^2 - t1^2 t2^3 - t1^3 t2^3 + t1 t2 t3 + t1^2 t2 t3 + t1^4 t2 t3 + t1 t2^2 t3 -
    t1^2 t2^2 t3 + t1^4 t2^2 t3 + t1 t2^4 t3 + t1^2 t2^4 t3 - t1^3 t3^2 + t1 t2 t3^2 -
    t1^2 t2 t3^2 + t1^4 t2 t3^2 - t1 t2^2 t3^2 + t1^3 t2^2 t3^2 - t2^3 t3^2 + t1^2 t2^3 t3^2 -
    t1^3 t2^3 t3^2 + t1 t2^4 t3^2 - t1^2 t3^3 - t1^3 t3^3 - t2^2 t3^3 + t1^2 t2^2 t3^3 - t1^3 t2^2 t3^3 -
    t2^3 t3^3 - t1^2 t2^3 t3^3 - t1^3 t2^3 t3^3 + t1 t2 t3^4 + t1^2 t2 t3^4 + t1 t2^2 t3^4) ) /
    ( (-1 + t1)^2 (t1^2 - t2) (-1 + t2)^2 (t1 - t2^2) (t1^2 - t3) (t1 t2 - t3) (t2^2 - t3)
      (-1 + t3)^2 (-t2 + t1 t3) (t1 - t2 t3) (t1 - t3^2) (t2 - t3^2) ) ) );

In[192]:= T44[t1_, t2_, t3_, u_, v_] :=
  Det[DiagonalMatrix[{-u + 1, -t1 * u + 1, -t2 * u + 1, -t3 * u + 1,
    -v + 1, (t1 - v) / t1, (t2 - v) / t2, (t3 - v) / t3}]]

In[193]:= GT44[t1_, t2_, t3_, u_, v_] := G44[t1, t2, t3] * T44[t1, t2, t3, u, v]

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In[170]:= G4smoothTangentContributions[t1_, t2_, t3_] :=
{
{-t2 + 1, -t3 + 1, -t1^4 + 1, (t1 - t2) / t1,
(t1 - t3) / t1, -t1^3 + 1, (t1^2 - t2) / t1^2, (t1^2 - t3) / t1^2,
-t1^2 + 1, (t1^3 - t2) / t1^3, (t1^3 - t3) / t1^3, -t1 + 1},
{-t3 + 1, (t1 - t3) / t1, -t2 + 1, -t1^2 + 1, (t1^2 - t3) / t1^2, (t1 - t2) / t1, -t1 + 1,
(t1^2 - t2^2) / t1^2, (t2 - t3) / t2, -t1 + 1, (-t1^3 + t2) / t2, -t2 + 1}, {-t3 + 1,
-t1^2 + 1, -t2^2 + 1, (t1 - t3) / t1, -t1 + 1, (-t2^2 + t1) / t1, (t2 - t3) / t2,
(-t1^2 + t2) / t2, -t2 + 1, (t1 * t2 - t3) / (t1 * t2), (-t1 + t2) / t2, (t1 - t2) / t1},
{-t3 + 1, (t1 - t3) / t1, -t1 + 1, -t2 + 1, (-t2^3 + t1) / t1, (t2 - t3) / t2, -t1 + 1,
-t2^2 + 1, (t2^2 - t3) / t2^2, (-t1^2 + t2^2) / t2^2, (-t1 + t2) / t2, -t2 + 1},
{-t1 + 1, -t3 + 1, -t2^4 + 1, (-t1 + t2) / t2, (t2 - t3) / t2,
-t2^3 + 1, (t2^2 - t1) / t2^2, (t2^2 - t3) / t2^2,
-t2^2 + 1, (t2^3 - t1) / t2^3, (t2^3 - t3) / t2^3, -t2 + 1},
{-t2 + 1, (t1 - t2) / t1, -t3 + 1, -t1^2 + 1, (t1^2 - t2) / t1^2, (t1 - t3) / t1,
-t1 + 1, (t1^2 - t3^2) / t1^2, (-t2 + t3) / t3, -t1 + 1, (-t1^3 + t3) / t3, -t3 + 1},
{-t1 + 1, (-t1 + t2) / t2, -t3 + 1, -t2^2 + 1, (t2^2 - t1) / t2^2, (t2 - t3) / t2,
-t2 + 1, (t2^2 - t3^2) / t2^2, (-t1 + t3) / t3, -t2 + 1, (-t2^3 + t3) / t3, -t3 + 1},
{-t2 + 1, -t1^2 + 1, -t3^2 + 1, (t1 - t2) / t1, -t1 + 1, (-t3^2 + t1) / t1,
(-t2 + t3) / t3, (-t1^2 + t3) / t3, -t3 + 1, (t1 * t3 - t2) / (t1 * t3),
(-t1 + t3) / t3, (t1 - t3) / t1}, {-t1 + 1, -t2^2 + 1, -t3^2 + 1,
(-t1 + t2) / t2, -t2 + 1, (-t3^2 + t2) / t2, (-t1 + t3) / t3, (-t2^2 + t3) / t3,
-t3 + 1, (t2 * t3 - t1) / (t2 * t3), (-t2 + t3) / t3, (t2 - t3) / t2},
{-t2 + 1, (t1 - t2) / t1, -t1 + 1, -t3 + 1, (-t3^3 + t1) / t1, (-t2 + t3) / t3, -t1 + 1,
-t3^2 + 1, (t3^2 - t2) / t3^2, (-t1^2 + t3^2) / t3^2, (-t1 + t3) / t3, -t3 + 1},
{-t1 + 1, (-t1 + t2) / t2, -t2 + 1, -t3 + 1, (-t3^3 + t2) / t2, (-t1 + t3) / t3, -t2 + 1,
-t3^2 + 1, (t3^2 - t1) / t3^2, (-t2^2 + t3^2) / t3^2, (-t2 + t3) / t3, -t3 + 1},
{-t1 + 1, -t2 + 1, -t3^4 + 1, (-t1 + t3) / t3, (-t2 + t3) / t3,
-t3^3 + 1, (t3^2 - t1) / t3^2, (t3^2 - t2) / t3^2,
-t3^2 + 1, (t3^3 - t1) / t3^3, (t3^3 - t2) / t3^3, -t3 + 1}}

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In[171]:= Length[G4smoothTangentContributions[t1, t2, t3]]

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Out[171]= 12

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In[194]:= GT4smoothPointsContributions[t1_, t2_, t3_, u_, v_] :=
{
{(-1) / (t2 - 1), (-1) / (t3 - 1), (-1) / (t1^4 - 1), t1 / (t1 - t2),
t1 / (t1 - t3), (-1) / (t1^3 - 1), t1^2 / (t1^2 - t2), t1^2 / (t1^2 - t3),
(-1) / (t1^2 - 1), t1^3 / (t1^3 - t2), t1^3 / (t1^3 - t3),
(-1) / (t1 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t1^3 * u + 1,
-v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2, (t1^3 - v) / t1^3},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t2 - 1), (-1) / (t1^2 - 1), t1^2 / (t1^2 - t3),
t1 / (t1 - t2), (-1) / (t1 - 1), t1^2 / (t1^2 - t2^2), t2 / (t2 - t3),
(-1) / (t1 - 1), (-t2) / (t1^3 - t2), (-1) / (t2 - 1), -u + 1, -t1 * u + 1,
-t1^2 * u + 1, -t2 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2, (t2 - v) / t2},
{(-1) / (t3 - 1), (-1) / (t1^2 - 1), (-1) / (t2^2 - 1), t1 / (t1 - t3),
(-1) / (t1 - 1), (-t1) / (t2^2 - t1), t2 / (t2 - t3), (-t2) / (t1^2 - t2),
(-1) / (t2 - 1), (t1 * t2) / (t1 * t2 - t3), (-t2) / (t1 - t2),
t1 / (t1 - t2), -u + 1, -t1 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1,

```

```

-v+1, (t1-v)/t1, (t2-v)/t2, (t1*t2-v)/(t1*t2)},
{(-1)/(t3-1), t1/(t1-t3), (-1)/(t1-1), (-1)/(t2-1), (-t1)/(t2^3-t1),
t2/(t2-t3), (-1)/(t1-1), (-1)/(t2^2-1), t2^2/(t2^2-t3),
(-t2^2)/(t1^2-t2^2), (-t2)/(t1-t2), (-1)/(t2-1), -u+1, -t1*u+1,
-t2*u+1, -t2^2*u+1, -v+1, (t1-v)/t1, (t2-v)/t2, (t2^2-v)/t2^2},
{(-1)/(t1-1), (-1)/(t3-1), (-1)/(t2^4-1), (-t2)/(t1-t2),
t2/(t2-t3), (-1)/(t2^3-1), t2^2/(t2^2-t1), t2^2/(t2^2-t3),
(-1)/(t2^2-1), t2^3/(t2^3-t1), t2^3/(t2^3-t3),
(-1)/(t2-1), -u+1, -t2*u+1, -t2^2*u+1, -t2^3*u+1,
-v+1, (t2-v)/t2, (t2^2-v)/t2^2, (t2^3-v)/t2^3},
{(-1)/(t2-1), t1/(t1-t2), (-1)/(t3-1), (-1)/(t1^2-1), t1^2/(t1^2-t2),
t1/(t1-t3), (-1)/(t1-1), t1^2/(t1^2-t3^2), (-t3)/(t2-t3),
(-1)/(t1-1), (-t3)/(t1^3-t3), (-1)/(t3-1), -u+1, -t1*u+1,
-t1^2*u+1, -t3*u+1, -v+1, (t1-v)/t1, (t1^2-v)/t1^2, (t3-v)/t3},
{(-1)/(t1-1), (-t2)/(t1-t2), (-1)/(t3-1), (-1)/(t2^2-1),
t2^2/(t2^2-t1), t2/(t2-t3), (-1)/(t2-1), t2^2/(t2^2-t3^2),
(-t3)/(t1-t3), (-1)/(t2-1), (-t3)/(t2^3-t3), (-1)/(t3-1),
-u+1, -t2*u+1, -t2^2*u+1, -t3*u+1, -v+1, (t2-v)/t2,
(t2^2-v)/t2^2, (t3-v)/t3}, {(-1)/(t2-1), (-1)/(t1^2-1),
(-1)/(t3^2-1), t1/(t1-t2), (-1)/(t1-1), (-t1)/(t3^2-t1),
(-t3)/(t2-t3), (-t3)/(t1^2-t3), (-1)/(t3-1), (t1*t3)/(t1*t3-t2),
(-t3)/(t1-t3), t1/(t1-t3), -u+1, -t1*u+1, -t3*u+1,
-t1*t3*u+1, -v+1, (t1-v)/t1, (t3-v)/t3, (t1*t3-v)/(t1*t3)},
{(-1)/(t1-1), (-1)/(t2^2-1), (-1)/(t3^2-1), (-t2)/(t1-t2),
(-1)/(t2-1), (-t2)/(t3^2-t2), (-t3)/(t1-t3), (-t3)/(t2^2-t3),
(-1)/(t3-1), (t2*t3)/(t2*t3-t1), (-t3)/(t2-t3),
t2/(t2-t3), -u+1, -t2*u+1, -t3*u+1, -t2*t3*u+1,
-v+1, (t2-v)/t2, (t3-v)/t3, (t2*t3-v)/(t2*t3)},
{(-1)/(t2-1), t1/(t1-t2), (-1)/(t1-1), (-1)/(t3-1), (-t1)/(t3^3-t1),
(-t3)/(t2-t3), (-1)/(t1-1), (-1)/(t3^2-1), t3^2/(t3^2-t2),
(-t3^2)/(t1^2-t3^2), (-t3)/(t1-t3), (-1)/(t3-1), -u+1, -t1*u+1,
-t3*u+1, -t3^2*u+1, -v+1, (t1-v)/t1, (t3-v)/t3, (t3^2-v)/t3^2},
{(-1)/(t1-1), (-t2)/(t1-t2), (-1)/(t2-1), (-1)/(t3-1),
(-t2)/(t3^3-t2), (-t3)/(t1-t3), (-1)/(t2-1), (-1)/(t3^2-1),
t3^2/(t3^2-t1), (-t3^2)/(t2^2-t3^2), (-t3)/(t2-t3),
(-1)/(t3-1), -u+1, -t2*u+1, -t3*u+1, -t3^2*u+1, -v+1,
(t2-v)/t2, (t3-v)/t3, (t3^2-v)/t3^2}, {(-1)/(t1-1), (-1)/(t2-1),
(-1)/(t3^4-1), (-t3)/(t1-t3), (-t3)/(t2-t3), (-1)/(t3^3-1),
t3^2/(t3^2-t1), t3^2/(t3^2-t2), (-1)/(t3^2-1), t3^3/(t3^3-t1),
t3^3/(t3^3-t2), (-1)/(t3-1), -u+1, -t3*u+1, -t3^2*u+1,
-t3^3*u+1, -v+1, (t3-v)/t3, (t3^2-v)/t3^2, (t3^3-v)/t3^3}}

```

In[195]:= Length[GT4smoothPointsContributions[t1, t2, t3, u, v]]

Out[195]= 12

```

In[174]:= G4smooth[t1_, t2_, t3_] :=
  Sum[1 / Det[DiagonalMatrix[G4smoothTangentContributions[t1, t2, t3][[i]]]],
    {i, 1, 12}];

In[196]:= GT4smooth[t1_, t2_, t3_, u_, v_] :=
  Sum[Det[DiagonalMatrix[GT4smoothPointsContributions[t1, t2, t3, u, v][[i]]]],
    {i, 1, 12}];

In[198]:= Together[GT4smooth[t1, t2, t3, u, v] +
  GT44[t1, t2, t3, u, v] - SeriesCoefficient[Exp[Sum[Q^n * (1 - u^n) *
    (1 - v^n) / (n * (1 - t1^n) * (1 - t2^n) * (1 - t3^n)), {n, 1, 4}]], {Q, 0, 4}]]

```

Out[198]= 0

```

In[106]:= Solve[{u1 * u2 == t1^2, u2 * u4 == t3, u0 * u3 == t2^2 / t1^2, u3 * u4 == t2 * t3 / t1^2,
  u0 * u4 == t3^2 / t1^2, u1 * u5 == t1^3 / t2, u0 * u5 == t1, u4 * u5 == t1 * t3 / t2,
  u0 * u2 == t2, u1 * u4 == t3^2 / t2, u2 * u5 == t1^3 / t3, u3 * u5 == t1 * t2 / t3,
  u2 * u3 == t2^2 / t3, u1 * u3 == t2, u0 * u1 == t3}, {u0, u1, u2, u3, u4, u5}]

```

Out[106]= $\left\{ \left\{ u_0 \rightarrow -\frac{\sqrt{t_2} \sqrt{t_3}}{t_1}, u_1 \rightarrow -\frac{t_1 \sqrt{t_3}}{\sqrt{t_2}}, u_2 \rightarrow -\frac{t_1 \sqrt{t_2}}{\sqrt{t_3}}, u_3 \rightarrow -\frac{t_2^{3/2}}{t_1 \sqrt{t_3}}, \right. \right.$
 $u_4 \rightarrow -\frac{t_3^{3/2}}{t_1 \sqrt{t_2}}, u_5 \rightarrow -\frac{t_1^2}{\sqrt{t_2} \sqrt{t_3}} \Big\}, \left\{ u_0 \rightarrow \frac{\sqrt{t_2} \sqrt{t_3}}{t_1}, u_1 \rightarrow \frac{t_1 \sqrt{t_3}}{\sqrt{t_2}}, \right.$
 $u_2 \rightarrow \frac{t_1 \sqrt{t_2}}{\sqrt{t_3}}, u_3 \rightarrow \frac{t_2^{3/2}}{t_1 \sqrt{t_3}}, u_4 \rightarrow \frac{t_3^{3/2}}{t_1 \sqrt{t_2}}, u_5 \rightarrow \frac{t_1^2}{\sqrt{t_2} \sqrt{t_3}} \Big\} \Big\}$

```

In[107]:= Together[G[-\frac{\sqrt{t_2} \sqrt{t_3}}{t_1}, -\frac{t_1 \sqrt{t_3}}{\sqrt{t_2}}, -\frac{t_1 \sqrt{t_2}}{\sqrt{t_3}}, -\frac{t_2^{3/2}}{t_1 \sqrt{t_3}}, -\frac{t_3^{3/2}}{t_1 \sqrt{t_2}}, -\frac{t_1^2}{\sqrt{t_2} \sqrt{t_3}}]]

```

Out[107]= $\frac{1}{t_1^2 t_2 t_3}$
 $(-t_1^5 t_2^2 + t_1^6 t_2^2 - t_1^3 t_2^3 + t_1^5 t_2^3 + t_1^3 t_2^4 - t_1^6 t_2^4 + t_1^2 t_2 t_3 - t_1^5 t_2 t_3 + t_1^6 t_2 t_3 -$
 $t_1^7 t_2 t_3 - 2 t_1^3 t_2^2 t_3 + t_1^4 t_2^2 t_3 + 2 t_1^5 t_2^2 t_3 - t_1^6 t_2^2 t_3 - t_1^2 t_2^3 t_3 + 3 t_1^3 t_2^3 t_3 -$
 $t_1^4 t_2^3 t_3 - t_1^5 t_2^3 t_3 - t_1^6 t_2^3 t_3 + t_1^7 t_2^3 t_3 + t_1 t_2^4 t_3 - t_1^3 t_2^4 t_3 - t_1^4 t_2^4 t_3 +$
 $t_1^6 t_2^4 t_3 - t_1 t_2^5 t_3 + t_1^4 t_2^5 t_3 - t_1^5 t_3^2 + t_1^6 t_3^2 - 2 t_1^3 t_2 t_3^2 + t_1^4 t_2 t_3^2 +$
 $2 t_1^5 t_2 t_3^2 - t_1^6 t_2 t_3^2 - t_1 t_2^2 t_3^2 - t_1^2 t_2^2 t_3^2 + 5 t_1^3 t_2^2 t_3^2 - t_1^4 t_2^2 t_3^2 -$
 $t_1^5 t_2^2 t_3^2 - 2 t_1^6 t_2^2 t_3^2 + t_1^7 t_2^2 t_3^2 - t_2^3 t_3^2 + 2 t_1 t_2^3 t_3^2 + t_1^2 t_2^3 t_3^2 - 2 t_1^3 t_2^3 t_3^2 -$
 $2 t_1^4 t_2^3 t_3^2 + t_1^5 t_2^3 t_3^2 + 2 t_1^6 t_2^3 t_3^2 - t_1^7 t_2^3 t_3^2 + t_2^4 t_3^2 - t_1 t_2^4 t_3^2 - t_1^2 t_2^4 t_3^2 -$
 $t_1^3 t_2^4 t_3^2 + 3 t_1^4 t_2^4 t_3^2 - t_1^5 t_2^4 t_3^2 + t_1^2 t_2^5 t_3^2 - t_1^4 t_2^5 t_3^2 - t_1^3 t_3^3 + t_1^5 t_3^3 -$
 $t_1^2 t_2 t_3^3 + 3 t_1^3 t_2 t_3^3 - t_1^4 t_2 t_3^3 - t_1^5 t_2 t_3^3 - t_1^6 t_2 t_3^3 + t_1^7 t_2 t_3^3 - t_2^2 t_3^3 +$
 $2 t_1 t_2^2 t_3^3 + t_1^2 t_2^2 t_3^3 - 2 t_1^3 t_2^2 t_3^3 - 2 t_1^4 t_2^2 t_3^3 + t_1^5 t_2^2 t_3^3 + 2 t_1^6 t_2^2 t_3^3 -$
 $t_1^7 t_2^2 t_3^3 + t_2^3 t_3^3 - 2 t_1 t_2^3 t_3^3 - t_1^2 t_2^3 t_3^3 - t_1^3 t_2^3 t_3^3 + 5 t_1^4 t_2^3 t_3^3 -$
 $t_1^5 t_2^3 t_3^3 - t_1^6 t_2^3 t_3^3 - t_1 t_2^4 t_3^3 + 2 t_1^2 t_2^4 t_3^3 + t_1^3 t_2^4 t_3^3 - 2 t_1^4 t_2^4 t_3^3 +$
 $t_1 t_2^5 t_3^3 - t_1^2 t_2^5 t_3^3 + t_1^3 t_3^4 - t_1^6 t_3^4 + t_1 t_2 t_3^4 - t_1^3 t_2 t_3^4 - t_1^4 t_2 t_3^4 +$
 $t_1^6 t_2 t_3^4 + t_2^2 t_3^4 - t_1 t_2^2 t_3^4 - t_1^2 t_2^2 t_3^4 - t_1^3 t_2^2 t_3^4 + 3 t_1^4 t_2^2 t_3^4 - t_1^5 t_2^2 t_3^4 -$
 $t_1 t_2^3 t_3^4 + 2 t_1^2 t_2^3 t_3^4 + t_1^3 t_2^3 t_3^4 - 2 t_1^4 t_2^3 t_3^4 - t_2^4 t_3^4 + t_1 t_2^4 t_3^4 - t_1^2 t_2^4 t_3^4 +$
 $t_1^5 t_2^4 t_3^4 - t_1 t_2 t_3^5 + t_1^4 t_2 t_3^5 + t_1^2 t_2^2 t_3^5 - t_1^4 t_2^2 t_3^5 + t_1 t_2^3 t_3^5 - t_1^2 t_2^3 t_3^5)$

```
In[176]:= G56tangent[t1_, t2_, t3_] :=
  Det[DiagonalMatrix[{-t2 + 1, -t3 + 1, -t1^2 + 1, -t1 + 1, (-t1 * t3 + t2) / t2, -t2 + 1,
    -t3 + 1, (-t3^2 + t2) / t2, (-t1^3 + t2) / t2, (-t1 * t2 + t3) / t3, -t1 + 1,
    (-t2^2 + t3) / t3, -t2 + 1, -t3 + 1, (-t1^3 + t3) / t3, (t1 - t2) / t1, (t1 - t3) / t1,
    (t1^2 - t2^2) / t1^2, (t1^2 - t2 * t3) / t1^2, (t1^2 - t3^2) / t1^2, -t1 + 1}]]]
```

```
In[143]:=
```

```
In[158]:= Together[%107 / G56tangent[t1, t2, t3]]
```

```
Out[158]= (t1^6 t2^2 t3^2
  (-t1^5 t2^2 - t1^3 t2^3 - t1^4 t2^3 - t1^5 t2^3 + t1^2 t2 t3 + t1^3 t2 t3 + t1^4 t2 t3 + t1^6 t2 t3 +
  t1^2 t2^2 t3 - t1^3 t2^2 t3 + t1^6 t2^2 t3 + t1 t2^4 t3 + t1^2 t2^4 t3 + t1^3 t2^4 t3 - t1^5 t3^2 +
  t1^2 t2 t3^2 - t1^3 t2 t3^2 + t1^6 t2 t3^2 - t1 t2^2 t3^2 - t1^2 t2^2 t3^2 + t1^4 t2^2 t3^2 +
  t1^5 t2^2 t3^2 - t2^3 t3^2 + t1^3 t2^3 t3^2 - t1^4 t2^3 t3^2 + t1 t2^4 t3^2 - t1^3 t3^3 -
  t1^4 t3^3 - t1^5 t3^3 - t2^2 t3^3 + t1^3 t2^2 t3^3 - t1^4 t2^2 t3^3 - t2^3 t3^3 - t1^2 t2^3 t3^3 -
  t1^3 t2^3 t3^3 - t1^4 t2^3 t3^3 + t1 t2 t3^4 + t1^2 t2 t3^4 + t1^3 t2 t3^4 + t1 t2^2 t3^4)) /
  ((-1 + t1)^3 (1 + t1) (t1 - t2)^2 (t1^3 - t2) (-1 + t2)^2 (t1 + t2) (t1 - t3)^2
  (t1^3 - t3) (t1 t2 - t3) (t2^2 - t3) (-1 + t3)^2
  (t1 + t3) (-t2 + t1 t3) (t1^2 - t2 t3) (t2 - t3^2))
```

```
In[177]:= G56[t1_, t2_, t3_] :=
  (t1^6 t2^2 t3^2 (-t1^5 t2^2 - t1^3 t2^3 - t1^4 t2^3 - t1^5 t2^3 + t1^2 t2 t3 + t1^3 t2 t3 + t1^4 t2 t3 +
  t1^6 t2 t3 + t1^2 t2^2 t3 - t1^3 t2^2 t3 + t1^6 t2^2 t3 + t1 t2^4 t3 + t1^2 t2^4 t3 +
  t1^3 t2^4 t3 - t1^5 t3^2 + t1^2 t2 t3^2 - t1^3 t2 t3^2 + t1^6 t2 t3^2 - t1 t2^2 t3^2 - t1^2 t2^2 t3^2 +
  t1^4 t2^2 t3^2 + t1^5 t2^2 t3^2 - t2^3 t3^2 + t1^3 t2^3 t3^2 - t1^4 t2^3 t3^2 + t1 t2^4 t3^2 - t1^3 t3^3 -
  t1^4 t3^3 - t1^5 t3^3 - t2^2 t3^3 + t1^3 t2^2 t3^3 - t1^4 t2^2 t3^3 - t2^3 t3^3 - t1^2 t2^3 t3^3 -
  t1^3 t2^3 t3^3 - t1^4 t2^3 t3^3 + t1 t2 t3^4 + t1^2 t2 t3^4 + t1^3 t2 t3^4 + t1 t2^2 t3^4)) /
  ((-1 + t1)^3 (1 + t1) (t1 - t2)^2 (t1^3 - t2) (-1 + t2)^2 (t1 + t2) (t1 - t3)^2 (t1^3 - t3)
  (t1 t2 - t3) (t2^2 - t3) (-1 + t3)^2 (t1 + t3) (-t2 + t1 t3) (t1^2 - t2 t3) (t2 - t3^2))
```

```
In[185]:= T56[t1_, t2_, t3_, u_, v_] :=
  Det[DiagonalMatrix[{-u + 1, -t1 * u + 1, -t2 * u + 1, -t3 * u + 1, -t1^2 * u + 1,
    -v + 1, (t1 - v) / t1, (t2 - v) / t2, (t3 - v) / t3, (t1^2 - v) / t1^2}]]]
```

```
In[186]:= GT56[t1_, t2_, t3_, u_, v_] := G56[t1, t2, t3] * T56[t1, t2, t3, u, v]
```

```
In[178]:= G5smoothTangentContributions[t1_, t2_, t3_] :=
  {{-t2 + 1, -t3 + 1, -t1^5 + 1, (t1 - t2) / t1, (t1 - t3) / t1, -t1^4 + 1,
    (t1^2 - t2) / t1^2, (t1^2 - t3) / t1^2, -t1^3 + 1, (t1^3 - t2) / t1^3,
    (t1^3 - t3) / t1^3, -t1^2 + 1, (t1^4 - t2) / t1^4, (t1^4 - t3) / t1^4, -t1 + 1},
  {-t3 + 1, (t1 - t3) / t1, -t2 + 1, -t1^3 + 1, (t1^2 - t3) / t1^2,
    (t1 - t2) / t1, -t1^2 + 1, (t1^3 - t3) / t1^3, (t1^2 - t2) / t1^2, -t1 + 1,
    (t1^3 - t2^2) / t1^3, (t2 - t3) / t2, -t1 + 1, (-t1^4 + t2) / t2, -t2 + 1},
  {-t3 + 1, (t1 - t3) / t1, -t1^2 + 1, (-t2^2 + t1) / t1, (t1^2 - t3) / t1^2,
    -t1 + 1, -t2 + 1, (t1^2 - t2^2) / t1^2, (t2 - t3) / t2, (-t1^3 + t2) / t2,
    -t2 + 1, (t1 * t2 - t3) / (t1 * t2), (-t1^2 + t2) / t2, -t1 + 1, (t1 - t2) / t1},
```

```

{-t3+1, (t1-t3)/t1, -t2+1, -t1^2+1, (t1^2-t3)/t1^2, (t1-t2)/t1,
-t1+1, (-t2^3+t1^2)/t1^2, (t2-t3)/t2, -t1+1, -t2^2+1,
(t2^2-t3)/t2^2, (-t1+t2)/t2, (-t1^3+t2^2)/t2^2, -t2+1},
{-t3+1, (t1-t3)/t1, -t1+1, -t2^2+1, (-t2^3+t1)/t1, (t2-t3)/t2,
(-t1^2+t2)/t2, (t1*t2-t3)/(t1*t2), (-t1+t2)/t2, -t2+1,
(-t2^2+t1)/t1, (t2^2-t3)/t2^2, (-t1^2+t2^2)/t2^2, -t1+1, -t2+1},
{-t3+1, (t1-t3)/t1, -t1+1, -t2+1, (-t2^4+t1)/t1, (t2-t3)/t2,
-t1+1, -t2^3+1, (t2^2-t3)/t2^2, (-t1+t2)/t2, -t2^2+1,
(t2^3-t3)/t2^3, (t2^3-t1^2)/t2^3, (t2^2-t1)/t2^2, -t2+1},
{-t1+1, -t3+1, -t2^5+1, (-t1+t2)/t2, (t2-t3)/t2, -t2^4+1,
(t2^2-t1)/t2^2, (t2^2-t3)/t2^2, -t2^3+1, (t2^3-t1)/t2^3,
(t2^3-t3)/t2^3, -t2^2+1, (t2^4-t1)/t2^4, (t2^4-t3)/t2^4, -t2+1},
{-t2+1, (t1-t2)/t1, -t3+1, -t1^3+1, (t1^2-t2)/t1^2,
(t1-t3)/t1, -t1^2+1, (t1^3-t2)/t1^3, (t1^2-t3)/t1^2, -t1+1,
(t1^3-t3^2)/t1^3, (-t2+t3)/t3, -t1+1, (-t1^4+t3)/t3, -t3+1},
{-t1+1, -t3+1, (-t2^2+t1)/t1, (-t1^2+t2)/t2, -t2+1, (-t1+t2)/t2,
(t2-t3)/t2, (t1-t2)/t1, (t1-t3)/t1, (t1*t2-t3^2)/(t1*t2),
(-t1^2+t3)/t3, -t1+1, (-t2^2+t3)/t3, -t2+1, -t3+1},
{-t1+1, (-t1+t2)/t2, -t3+1, -t2^3+1, (t2^2-t1)/t2^2,
(t2-t3)/t2, -t2^2+1, (t2^3-t1)/t2^3, (t2^2-t3)/t2^2, -t2+1,
(t2^3-t3^2)/t2^3, (-t1+t3)/t3, -t2+1, (-t2^4+t3)/t3, -t3+1},
{-t2+1, (t1-t2)/t1, -t1^2+1, (-t3^2+t1)/t1, (t1^2-t2)/t1^2,
-t1+1, -t3+1, (t1^2-t3^2)/t1^2, (-t2+t3)/t3, (-t1^3+t3)/t3,
-t3+1, (t1*t3-t2)/(t1*t3), (-t1^2+t3)/t3, -t1+1, (t1-t3)/t1},
{-t1+1, -t2+1, -t3+1, (-t2^2+t1)/t1, (-t3^2+t1)/t1, -t1+1, -t2+1,
(-t3^2+t2)/t2, (-t2^2+t3)/t3, -t3+1, (-t1^2+t2*t3)/(t2*t3),
(-t1+t3)/t3, (-t1+t2)/t2, (-t2+t3)/t3, (t2-t3)/t2},
{-t1+1, -t2+1, (-t3^2+t1)/t1, (-t1^2+t2)/t2, -t1+1, -t2+1,
-t3+1, (-t3^2+t2)/t2, (-t1^2+t3)/t3, -t3+1, (-t1+t3)/t3,
(-t2+t3)/t3, (-t2^2+t1*t3)/(t1*t3), (t1-t2)/t1, (t1-t3)/t1},
{-t1+1, (-t1+t2)/t2, -t2^2+1, (-t3^2+t2)/t2, (t2^2-t1)/t2^2,
-t2+1, -t3+1, (t2^2-t3^2)/t2^2, (-t1+t3)/t3, (-t2^3+t3)/t3,
-t3+1, (t2*t3-t1)/(t2*t3), (-t2^2+t3)/t3, -t2+1, (t2-t3)/t2},
{-t2+1, (t1-t2)/t1, -t3+1, -t1^2+1, (t1^2-t2)/t1^2, (t1-t3)/t1,
-t1+1, (-t3^3+t1^2)/t1^2, (-t2+t3)/t3, -t1+1, -t3^2+1,
(t3^2-t2)/t3^2, (-t1+t3)/t3, (-t1^3+t3^2)/t3^2, -t3+1},
{-t1+1, (-t1+t2)/t2, -t3+1, -t2^2+1, (t2^2-t1)/t2^2, (t2-t3)/t2,
-t2+1, (-t3^3+t2^2)/t2^2, (-t1+t3)/t3, -t2+1, -t3^2+1,
(t3^2-t1)/t3^2, (-t2+t3)/t3, (-t2^3+t3^2)/t3^2, -t3+1},
{-t2+1, (t1-t2)/t1, -t1+1, -t3^2+1, (-t3^3+t1)/t1, (-t2+t3)/t3,
(-t1^2+t3)/t3, (t1*t3-t2)/(t1*t3), (-t1+t3)/t3, -t3+1,
(-t3^2+t1)/t1, (t3^2-t2)/t3^2, (-t1^2+t3^2)/t3^2, -t1+1, -t3+1},
{-t1+1, (-t1+t2)/t2, -t2+1, -t3^2+1, (-t3^3+t2)/t2, (-t1+t3)/t3,
(-t2^2+t3)/t3, (t2*t3-t1)/(t2*t3), (-t2+t3)/t3, -t3+1,
(-t3^2+t2)/t2, (t3^2-t1)/t3^2, (-t2^2+t3^2)/t3^2, -t2+1, -t3+1},
{-t2+1, (t1-t2)/t1, -t1+1, -t3+1, (-t3^4+t1)/t1, (-t2+t3)/t3,
-t1+1, -t3^3+1, (t3^2-t2)/t3^2, (-t1+t3)/t3, -t3^2+1,

```



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(t3^3 - t2) / t3^3, (t3^3 - t1^2) / t3^3, (t3^2 - t1) / t3^2, -t3 + 1},
{-t1 + 1, (-t1 + t2) / t2, -t2 + 1, -t3 + 1, (-t3^4 + t2) / t2, (-t1 + t3) / t3,
-t2 + 1, -t3^3 + 1, (t3^2 - t1) / t3^2, (-t2 + t3) / t3, -t3^2 + 1,
(t3^3 - t1) / t3^3, (t3^3 - t2^2) / t3^3, (t3^2 - t2) / t3^2, -t3 + 1},
{-t1 + 1, -t2 + 1, -t3^5 + 1, (-t1 + t3) / t3, (-t2 + t3) / t3, -t3^4 + 1,
(t3^2 - t1) / t3^2, (t3^2 - t2) / t3^2, -t3^3 + 1, (t3^3 - t1) / t3^3,
(t3^3 - t2) / t3^3, -t3^2 + 1, (t3^4 - t1) / t3^4, (t3^4 - t2) / t3^4, -t3 + 1}}

```

```
In[149]:= Length[G5smoothTangentContributions[t1, t2, t3]]
```

```
Out[149]= 21
```

```
In[187]:= GT5smoothPointsContributions[t1_, t2_, t3_, u_, v_] :=
```

```

{{(-1) / (t2 - 1), (-1) / (t3 - 1), (-1) / (t1^5 - 1), t1 / (t1 - t2),
t1 / (t1 - t3), (-1) / (t1^4 - 1), t1^2 / (t1^2 - t2), t1^2 / (t1^2 - t3),
(-1) / (t1^3 - 1), t1^3 / (t1^3 - t2), t1^3 / (t1^3 - t3),
(-1) / (t1^2 - 1), t1^4 / (t1^4 - t2), t1^4 / (t1^4 - t3), (-1) / (t1 - 1),
-u + 1, -t1*u + 1, -t1^2*u + 1, -t1^3*u + 1, -t1^4*u + 1, -v + 1,
(t1 - v) / t1, (t1^2 - v) / t1^2, (t1^3 - v) / t1^3, (t1^4 - v) / t1^4},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t2 - 1), (-1) / (t1^3 - 1), t1^2 / (t1^2 - t3),
t1 / (t1 - t2), (-1) / (t1^2 - 1), t1^3 / (t1^3 - t3), t1^2 / (t1^2 - t2),
(-1) / (t1 - 1), t1^3 / (t1^3 - t2^2), t2 / (t2 - t3), (-1) / (t1 - 1),
(-t2) / (t1^4 - t2), (-1) / (t2 - 1), -u + 1, -t1*u + 1, -t1^2*u + 1, -t1^3*u + 1,
-t2*u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2, (t1^3 - v) / t1^3, (t2 - v) / t2},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t1^2 - 1), (-t1) / (t2^2 - t1),
t1^2 / (t1^2 - t3), (-1) / (t1 - 1), (-1) / (t2 - 1), t1^2 / (t1^2 - t2^2),
t2 / (t2 - t3), (-t2) / (t1^3 - t2), (-1) / (t2 - 1), (t1*t2) / (t1*t2 - t3),
(-t2) / (t1^2 - t2), (-1) / (t1 - 1), t1 / (t1 - t2), -u + 1, -t1*u + 1,
-t1^2*u + 1, -t2*u + 1, -t1*t2*u + 1, -v + 1, (t1 - v) / t1,
(t1^2 - v) / t1^2, (t2 - v) / t2, (t1*t2 - v) / (t1*t2)},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t2 - 1), (-1) / (t1^2 - 1),
t1^2 / (t1^2 - t3), t1 / (t1 - t2), (-1) / (t1 - 1), (-t1^2) / (t2^3 - t1^2),
t2 / (t2 - t3), (-1) / (t1 - 1), (-1) / (t2^2 - 1), t2^2 / (t2^2 - t3),
(-t2) / (t1 - t2), (-t2^2) / (t1^3 - t2^2), (-1) / (t2 - 1),
-u + 1, -t1*u + 1, -t1^2*u + 1, -t2*u + 1, -t2^2*u + 1, -v + 1,
(t1 - v) / t1, (t1^2 - v) / t1^2, (t2 - v) / t2, (t2^2 - v) / t2^2},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t1 - 1), (-1) / (t2^2 - 1),
(-t1) / (t2^3 - t1), t2 / (t2 - t3), (-t2) / (t1^2 - t2), (t1*t2) / (t1*t2 - t3),
(-t2) / (t1 - t2), (-1) / (t2 - 1), (-t1) / (t2^2 - t1), t2^2 / (t2^2 - t3),
(-t2^2) / (t1^2 - t2^2), (-1) / (t1 - 1), (-1) / (t2 - 1), -u + 1,
-t1*u + 1, -t2*u + 1, -t1*t2*u + 1, -t2^2*u + 1, -v + 1,
(t1 - v) / t1, (t2 - v) / t2, (t1*t2 - v) / (t1*t2), (t2^2 - v) / t2^2},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t1 - 1), (-1) / (t2 - 1),
(-t1) / (t2^4 - t1), t2 / (t2 - t3), (-1) / (t1 - 1), (-1) / (t2^3 - 1),
t2^2 / (t2^2 - t3), (-t2) / (t1 - t2), (-1) / (t2^2 - 1), t2^3 / (t2^3 - t3),
t2^3 / (t2^3 - t1^2), t2^2 / (t2^2 - t1), (-1) / (t2 - 1),
-u + 1, -t1*u + 1, -t2*u + 1, -t2^2*u + 1, -t2^3*u + 1, -v + 1,
(t1 - v) / t1, (t2 - v) / t2, (t2^2 - v) / t2^2, (t2^3 - v) / t2^3},
{(-1) / (t1 - 1), (-1) / (t3 - 1), (-1) / (t2^5 - 1), (-t2) / (t1 - t2),

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t2 / (t2 - t3), (-1) / (t2^4 - 1), t2^2 / (t2^2 - t1), t2^2 / (t2^2 - t3),
(-1) / (t2^3 - 1), t2^3 / (t2^3 - t1), t2^3 / (t2^3 - t3),
(-1) / (t2^2 - 1), t2^4 / (t2^4 - t1), t2^4 / (t2^4 - t3), (-1) / (t2 - 1),
-u + 1, -t2 * u + 1, -t2^2 * u + 1, -t2^3 * u + 1, -t2^4 * u + 1, -v + 1,
(t2 - v) / t2, (t2^2 - v) / t2^2, (t2^3 - v) / t2^3, (t2^4 - v) / t2^4},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t3 - 1), (-1) / (t1^3 - 1), t1^2 / (t1^2 - t2),
t1 / (t1 - t3), (-1) / (t1^2 - 1), t1^3 / (t1^3 - t2), t1^2 / (t1^2 - t3),
(-1) / (t1 - 1), t1^3 / (t1^3 - t3^2), (-t3) / (t2 - t3), (-1) / (t1 - 1),
(-t3) / (t1^4 - t3), (-1) / (t3 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t1^3 * u + 1,
-t3 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2, (t1^3 - v) / t1^3, (t3 - v) / t3},
{(-1) / (t1 - 1), (-1) / (t3 - 1), (-t1) / (t2^2 - t1), (-t2) / (t1^2 - t2),
(-1) / (t2 - 1), (-t2) / (t1 - t2), t2 / (t2 - t3), t1 / (t1 - t2), t1 / (t1 - t3),
(t1 * t2) / (t1 * t2 - t3^2), (-t3) / (t1^2 - t3), (-1) / (t1 - 1), (-t3) / (t2^2 - t3),
(-1) / (t2 - 1), (-1) / (t3 - 1), -u + 1, -t1 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1,
-t3 * u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2, (t1 * t2 - v) / (t1 * t2), (t3 - v) / t3},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t3 - 1), (-1) / (t2^3 - 1),
t2^2 / (t2^2 - t1), t2 / (t2 - t3), (-1) / (t2^2 - 1), t2^3 / (t2^3 - t1),
t2^2 / (t2^2 - t3), (-1) / (t2 - 1), t2^3 / (t2^3 - t3^2),
(-t3) / (t1 - t3), (-1) / (t2 - 1), (-t3) / (t2^4 - t3), (-1) / (t3 - 1),
-u + 1, -t2 * u + 1, -t2^2 * u + 1, -t2^3 * u + 1, -t3 * u + 1, -v + 1,
(t2 - v) / t2, (t2^2 - v) / t2^2, (t2^3 - v) / t2^3, (t3 - v) / t3},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t1^2 - 1), (-t1) / (t3^2 - t1),
t1^2 / (t1^2 - t2), (-1) / (t1 - 1), (-1) / (t3 - 1), t1^2 / (t1^2 - t3^2),
(-t3) / (t2 - t3), (-t3) / (t1^3 - t3), (-1) / (t3 - 1),
(t1 * t3) / (t1 * t3 - t2), (-t3) / (t1^2 - t3), (-1) / (t1 - 1), t1 / (t1 - t3),
-u + 1, -t1 * u + 1, -t1^2 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1, -v + 1,
(t1 - v) / t1, (t1^2 - v) / t1^2, (t3 - v) / t3, (t1 * t3 - v) / (t1 * t3)},
{(-1) / (t1 - 1), (-1) / (t2 - 1), (-1) / (t3 - 1), (-t1) / (t2^2 - t1),
(-t1) / (t3^2 - t1), (-1) / (t1 - 1), (-1) / (t2 - 1), (-t2) / (t3^2 - t2),
(-t3) / (t2^2 - t3), (-1) / (t3 - 1), (-t2 * t3) / (t1^2 - t2 * t3),
(-t3) / (t1 - t3), (-t2) / (t1 - t2), (-t3) / (t2 - t3), t2 / (t2 - t3),
-u + 1, -t1 * u + 1, -t2 * u + 1, -t3 * u + 1, -t2 * t3 * u + 1, -v + 1,
(t1 - v) / t1, (t2 - v) / t2, (t3 - v) / t3, (t2 * t3 - v) / (t2 * t3)},
{(-1) / (t1 - 1), (-1) / (t2 - 1), (-t1) / (t3^2 - t1), (-t2) / (t1^2 - t2),
(-1) / (t1 - 1), (-1) / (t2 - 1), (-1) / (t3 - 1), (-t2) / (t3^2 - t2),
(-t3) / (t1^2 - t3), (-1) / (t3 - 1), (-t3) / (t1 - t3), (-t3) / (t2 - t3),
(-t1 * t3) / (t2^2 - t1 * t3), t1 / (t1 - t2), t1 / (t1 - t3),
-u + 1, -t1 * u + 1, -t2 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1, -v + 1,
(t1 - v) / t1, (t2 - v) / t2, (t3 - v) / t3, (t1 * t3 - v) / (t1 * t3)},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t2^2 - 1), (-t2) / (t3^2 - t2),
t2^2 / (t2^2 - t1), (-1) / (t2 - 1), (-1) / (t3 - 1), t2^2 / (t2^2 - t3^2),
(-t3) / (t1 - t3), (-t3) / (t2^3 - t3), (-1) / (t3 - 1),
(t2 * t3) / (t2 * t3 - t1), (-t3) / (t2^2 - t3), (-1) / (t2 - 1), t2 / (t2 - t3),
-u + 1, -t2 * u + 1, -t2^2 * u + 1, -t3 * u + 1, -t2 * t3 * u + 1, -v + 1,
(t2 - v) / t2, (t2^2 - v) / t2^2, (t3 - v) / t3, (t2 * t3 - v) / (t2 * t3)},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t3 - 1), (-1) / (t1^2 - 1),
t1^2 / (t1^2 - t2), t1 / (t1 - t3), (-1) / (t1 - 1), (-t1^2) / (t3^3 - t1^2),

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(-t3) / (t2 - t3), (-1) / (t1 - 1), (-1) / (t3^2 - 1), t3^2 / (t3^2 - t2),
(-t3) / (t1 - t3), (-t3^2) / (t1^3 - t3^2), (-1) / (t3 - 1),
-u+1, -t1*u+1, -t1^2*u+1, -t3*u+1, -t3^2*u+1, -v+1,
(t1-v) / t1, (t1^2-v) / t1^2, (t3-v) / t3, (t3^2-v) / t3^2,
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t3 - 1), (-1) / (t2^2 - 1),
t2^2 / (t2^2 - t1), t2 / (t2 - t3), (-1) / (t2 - 1), (-t2^2) / (t3^3 - t2^2),
(-t3) / (t1 - t3), (-1) / (t2 - 1), (-1) / (t3^2 - 1), t3^2 / (t3^2 - t1),
(-t3) / (t2 - t3), (-t3^2) / (t2^3 - t3^2), (-1) / (t3 - 1),
-u+1, -t2*u+1, -t2^2*u+1, -t3*u+1, -t3^2*u+1, -v+1,
(t2-v) / t2, (t2^2-v) / t2^2, (t3-v) / t3, (t3^2-v) / t3^2,
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t1 - 1), (-1) / (t3^2 - 1),
(-t1) / (t3^3 - t1), (-t3) / (t2 - t3), (-t3) / (t1^2 - t3),
(t1*t3) / (t1*t3 - t2), (-t3) / (t1 - t3), (-1) / (t3 - 1), (-t1) / (t3^2 - t1),
t3^2 / (t3^2 - t2), (-t3^2) / (t1^2 - t3^2), (-1) / (t1 - 1), (-1) / (t3 - 1),
-u+1, -t1*u+1, -t3*u+1, -t1*t3*u+1, -t3^2*u+1, -v+1,
(t1-v) / t1, (t3-v) / t3, (t1*t3-v) / (t1*t3), (t3^2-v) / t3^2,
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t2 - 1), (-1) / (t3^2 - 1),
(-t2) / (t3^3 - t2), (-t3) / (t1 - t3), (-t3) / (t2^2 - t3),
(t2*t3) / (t2*t3 - t1), (-t3) / (t2 - t3), (-1) / (t3 - 1), (-t2) / (t3^2 - t2),
t3^2 / (t3^2 - t1), (-t3^2) / (t2^2 - t3^2), (-1) / (t2 - 1), (-1) / (t3 - 1),
-u+1, -t2*u+1, -t3*u+1, -t2*t3*u+1, -t3^2*u+1, -v+1,
(t2-v) / t2, (t3-v) / t3, (t2*t3-v) / (t2*t3), (t3^2-v) / t3^2,
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t1 - 1), (-1) / (t3 - 1),
(-t1) / (t3^4 - t1), (-t3) / (t2 - t3), (-1) / (t1 - 1), (-1) / (t3^3 - 1),
t3^2 / (t3^2 - t2), (-t3) / (t1 - t3), (-1) / (t3^2 - 1), t3^3 / (t3^3 - t2),
t3^3 / (t3^3 - t1^2), t3^2 / (t3^2 - t1), (-1) / (t3 - 1),
-u+1, -t1*u+1, -t3*u+1, -t3^2*u+1, -t3^3*u+1, -v+1,
(t1-v) / t1, (t3-v) / t3, (t3^2-v) / t3^2, (t3^3-v) / t3^3,
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t2 - 1), (-1) / (t3 - 1),
(-t2) / (t3^4 - t2), (-t3) / (t1 - t3), (-1) / (t2 - 1), (-1) / (t3^3 - 1),
t3^2 / (t3^2 - t1), (-t3) / (t2 - t3), (-1) / (t3^2 - 1), t3^3 / (t3^3 - t1),
t3^3 / (t3^3 - t2^2), t3^2 / (t3^2 - t2), (-1) / (t3 - 1),
-u+1, -t2*u+1, -t3*u+1, -t3^2*u+1, -t3^3*u+1, -v+1,
(t2-v) / t2, (t3-v) / t3, (t3^2-v) / t3^2, (t3^3-v) / t3^3,
{(-1) / (t1 - 1), (-1) / (t2 - 1), (-1) / (t3^5 - 1), (-t3) / (t1 - t3),
(-t3) / (t2 - t3), (-1) / (t3^4 - 1), t3^2 / (t3^2 - t1), t3^2 / (t3^2 - t2),
(-1) / (t3^3 - 1), t3^3 / (t3^3 - t1), t3^3 / (t3^3 - t2),
(-1) / (t3^2 - 1), t3^4 / (t3^4 - t1), t3^4 / (t3^4 - t2), (-1) / (t3 - 1),
-u+1, -t3*u+1, -t3^2*u+1, -t3^3*u+1, -t3^4*u+1, -v+1,
(t3-v) / t3, (t3^2-v) / t3^2, (t3^3-v) / t3^3, (t3^4-v) / t3^4}}

```

```
In[188]:= Length[GT5smoothPointsContributions[t1, t2, t3, u, v]]
```

```
Out[188]:= 21
```

```
In[179]:= G5smooth[t1_, t2_, t3_] :=
  Sum[1 / Det[DiagonalMatrix[G5smoothTangentContributions[t1, t2, t3][[i]]]],
    {i, 1, 21}];
```

In[189]:= GT5smooth[t1_, t2_, t3_, u_, v_] :=

Sum[Det[DiagonalMatrix[GT5smoothPointsContributions[t1, t2, t3, u, v][[i]]]],
{i, 1, 21}];

In[190]:= Together[GT5smooth[t1, t2, t3, u, v] + GT56[t1, t2, t3, u, v] + GT56[t2, t3, t1, u, v] +

GT56[t3, t1, t2, u, v] - SeriesCoefficient[Exp[Sum[Q^n * (1 - u^n) *
(1 - v^n) / (n * (1 - t1^n) * (1 - t2^n) * (1 - t3^n)), {n, 1, 5}]], {Q, 0, 5}]]

Out[190]= 0

In[113]:= Solve[{u1 * u2 == t1^3, u2 * u4 == t3, u0 * u3 == t2^2 / t1^3, u3 * u4 == t2 * t3 / t1^3,

u0 * u4 == t3^2 / t1^3, u1 * u5 == t1^4 / t2, u0 * u5 == t1, u4 * u5 == t1 * t3 / t2,

u0 * u2 == t2, u1 * u4 == t3^2 / t2, u2 * u5 == t1^4 / t3, u3 * u5 == t1 * t2 / t3,

u2 * u3 == t2^2 / t3, u1 * u3 == t2, u0 * u1 == t3}, {u0, u1, u2, u3, u4, u5}]

Out[113]= $\left\{ \left\{ u_0 \rightarrow -\frac{\sqrt{t_2} \sqrt{t_3}}{t_1^{3/2}}, u_1 \rightarrow -\frac{t_1^{3/2} \sqrt{t_3}}{\sqrt{t_2}}, u_2 \rightarrow -\frac{t_1^{3/2} \sqrt{t_2}}{\sqrt{t_3}}, u_3 \rightarrow -\frac{t_2^{3/2}}{t_1^{3/2} \sqrt{t_3}}, \right. \right.$
 $u_4 \rightarrow -\frac{t_3^{3/2}}{t_1^{3/2} \sqrt{t_2}}, u_5 \rightarrow -\frac{t_1^{5/2}}{\sqrt{t_2} \sqrt{t_3}} \Big\}, \left\{ u_0 \rightarrow \frac{\sqrt{t_2} \sqrt{t_3}}{t_1^{3/2}}, u_1 \rightarrow \frac{t_1^{3/2} \sqrt{t_3}}{\sqrt{t_2}}, \right.$
 $u_2 \rightarrow \frac{t_1^{3/2} \sqrt{t_2}}{\sqrt{t_3}}, u_3 \rightarrow \frac{t_2^{3/2}}{t_1^{3/2} \sqrt{t_3}}, u_4 \rightarrow \frac{t_3^{3/2}}{t_1^{3/2} \sqrt{t_2}}, u_5 \rightarrow \frac{t_1^{5/2}}{\sqrt{t_2} \sqrt{t_3}} \Big\} \Big\}$

Together $\left[G \left[\frac{\sqrt{t_2} \sqrt{t_3}}{t_1^{3/2}}, \frac{t_1^{3/2} \sqrt{t_3}}{\sqrt{t_2}}, \frac{t_1^{3/2} \sqrt{t_2}}{\sqrt{t_3}}, \frac{t_2^{3/2}}{t_1^{3/2} \sqrt{t_3}}, \frac{t_3^{3/2}}{t_1^{3/2} \sqrt{t_2}}, \frac{t_1^{5/2}}{\sqrt{t_2} \sqrt{t_3}} \right] \right]$

Out[114]= $\frac{1}{t_1^3 t_2 t_3}$

$(-t_1^7 t_2^2 + t_1^8 t_2^2 - t_1^4 t_2^3 + t_1^7 t_2^3 + t_1^4 t_2^4 - t_1^8 t_2^4 + t_1^3 t_2 t_3 - t_1^7 t_2 t_3 + t_1^8 t_2 t_3 -$
 $t_1^9 t_2 t_3 - 2 t_1^4 t_2^2 t_3 + t_1^5 t_2^2 t_3 + 2 t_1^7 t_2^2 t_3 - t_1^8 t_2^2 t_3 - t_1^3 t_2^3 t_3 + 3 t_1^4 t_2^3 t_3 -$
 $t_1^5 t_2^3 t_3 - t_1^7 t_2^3 t_3 - t_1^8 t_2^3 t_3 + t_1^9 t_2^3 t_3 + t_1 t_2^4 t_3 - t_1^4 t_2^4 t_3 - t_1^5 t_2^4 t_3 +$
 $t_1^8 t_2^4 t_3 - t_1 t_2^5 t_3 + t_1^5 t_2^5 t_3 - t_1^7 t_2^5 t_3 + t_1^8 t_2^5 t_3 - 2 t_1^4 t_2 t_3^2 + t_1^5 t_2 t_3^2 +$
 $2 t_1^7 t_2 t_3^2 - t_1^8 t_2 t_3^2 - t_1 t_2^2 t_3^2 - t_1^3 t_2^2 t_3^2 + 5 t_1^4 t_2^2 t_3^2 - t_1^5 t_2^2 t_3^2 -$
 $t_1^7 t_2^2 t_3^2 - 2 t_1^8 t_2^2 t_3^2 + t_1^9 t_2^2 t_3^2 - t_2^3 t_3^2 + 2 t_1 t_2^3 t_3^2 + t_1^3 t_2^3 t_3^2 - 2 t_1^4 t_2^3 t_3^2 -$
 $2 t_1^5 t_2^3 t_3^2 + t_1^6 t_2^3 t_3^2 + 2 t_1^8 t_2^3 t_3^2 - t_1^9 t_2^3 t_3^2 + t_2^4 t_3^2 - t_1 t_2^4 t_3^2 - t_1^2 t_2^4 t_3^2 -$
 $t_1^4 t_2^4 t_3^2 + 3 t_1^5 t_2^4 t_3^2 - t_1^6 t_2^4 t_3^2 + t_1^2 t_2^5 t_3^2 - t_1^5 t_2^5 t_3^2 - t_1^4 t_3^3 + t_1^7 t_3^3 -$
 $t_1^3 t_2 t_3^3 + 3 t_1^4 t_2 t_3^3 - t_1^5 t_2 t_3^3 - t_1^7 t_2 t_3^3 - t_1^8 t_2 t_3^3 + t_1^9 t_2 t_3^3 - t_2^2 t_3^3 +$
 $2 t_1 t_2^2 t_3^3 + t_1^3 t_2^2 t_3^3 - 2 t_1^4 t_2^2 t_3^3 - 2 t_1^5 t_2^2 t_3^3 + t_1^6 t_2^2 t_3^3 + 2 t_1^8 t_2^2 t_3^3 -$
 $t_1^9 t_2^2 t_3^3 + t_2^3 t_3^3 - 2 t_1 t_2^3 t_3^3 - t_1^2 t_2^3 t_3^3 - t_1^4 t_2^3 t_3^3 + 5 t_1^5 t_2^3 t_3^3 -$
 $t_1^6 t_2^3 t_3^3 - t_1^8 t_2^3 t_3^3 - t_1 t_2^4 t_3^3 + 2 t_1^2 t_2^4 t_3^3 + t_1^4 t_2^4 t_3^3 - 2 t_1^5 t_2^4 t_3^3 +$
 $t_1 t_2^5 t_3^3 - t_1^2 t_2^5 t_3^3 + t_1^4 t_3^4 - t_1^8 t_3^4 + t_1 t_2 t_3^4 - t_1^4 t_2 t_3^4 - t_1^5 t_2 t_3^4 +$
 $t_1^8 t_2 t_3^4 + t_2^2 t_3^4 - t_1 t_2^2 t_3^4 - t_1^2 t_2^2 t_3^4 - t_1^4 t_2^2 t_3^4 + 3 t_1^5 t_2^2 t_3^4 - t_1^6 t_2^2 t_3^4 -$
 $t_1 t_2^3 t_3^4 + 2 t_1^2 t_2^3 t_3^4 + t_1^4 t_2^3 t_3^4 - 2 t_1^5 t_2^3 t_3^4 - t_2^4 t_3^4 + t_1 t_2^4 t_3^4 - t_1^2 t_2^4 t_3^4 +$
 $t_1^6 t_2^4 t_3^4 - t_1 t_2 t_3^5 + t_1^5 t_2 t_3^5 + t_1^2 t_2^2 t_3^5 - t_1^5 t_2^2 t_3^5 + t_1 t_2^3 t_3^5 - t_1^2 t_2^3 t_3^5)$

In[127]:= G61tangent[t1_, t2_, t3_] :=

Det[DiagonalMatrix[{-t2 + 1, -t3 + 1, -t1^3 + 1, (t1 - t2) / t1, (t1 - t3) / t1,
-t1^2 + 1, (t1^2 - t2) / t1^2, (t1^2 - t3) / t1^2, -t1 + 1, (t1^3 - t2^2) / t1^3,
(t1^3 - t2 * t3) / t1^3, (t1^3 - t3^2) / t1^3, -t1 + 1, (-t1 * t3 + t2) / t2,
(-t1^4 + t2) / t2, -t2 + 1, -t3 + 1, (-t3^2 + t2) / t2, (-t1 * t2 + t3) / t3,
-t1 + 1, (-t1^4 + t3) / t3, (-t2^2 + t3) / t3, -t2 + 1, -t3 + 1}]]

In[120]:= Together[%114 / G61tangent[t1, t2, t3]]

Out[120]=
$$-\left((t_1^{12} t_2^2 t_3^2 \right. \\ \left. (-t_1^7 t_2^2 - t_1^4 t_2^3 - t_1^5 t_2^3 - t_1^6 t_2^3 - t_1^7 t_2^3 + t_1^3 t_2 t_3 + t_1^4 t_2 t_3 + t_1^5 t_2 t_3 + \right. \\ \left. t_1^6 t_2 t_3 + t_1^8 t_2 t_3 + t_1^3 t_2^2 t_3 - t_1^4 t_2^2 t_3 + t_1^8 t_2^2 t_3 + t_1 t_2^4 t_3 + t_1^2 t_2^4 t_3 + \right. \\ \left. t_1^3 t_2^4 t_3 + t_1^4 t_2^4 t_3 - t_1^7 t_3^2 + t_1^3 t_2 t_3^2 - t_1^4 t_2 t_3^2 + t_1^8 t_2 t_3^2 - t_1 t_2^2 t_3^2 - \right. \\ \left. t_1^2 t_2^2 t_3^2 - t_1^3 t_2^2 t_3^2 + t_1^5 t_2^2 t_3^2 + t_1^6 t_2^2 t_3^2 + t_1^7 t_2^2 t_3^2 - t_2^3 t_3^2 + \right. \\ \left. t_1^4 t_2^3 t_3^2 - t_1^5 t_2^3 t_3^2 + t_1 t_2^4 t_3^2 - t_1^4 t_3^3 - t_1^5 t_3^3 - t_1^6 t_3^3 - t_1^7 t_3^3 - \right. \\ \left. t_2^2 t_3^3 + t_1^4 t_2^2 t_3^3 - t_1^5 t_2^2 t_3^3 - t_2^3 t_3^3 - t_1^2 t_2^3 t_3^3 - t_1^3 t_2^3 t_3^3 - t_1^4 t_2^3 t_3^3 - \right. \\ \left. t_1^5 t_2^3 t_3^3 + t_1 t_2 t_3^4 + t_1^2 t_2 t_3^4 + t_1^3 t_2 t_3^4 + t_1^4 t_2 t_3^4 + t_1 t_2^2 t_3^4) \right) / \\ \left((-1 + t_1)^4 (1 + t_1) (1 + t_1 + t_1^2) (t_1 - t_2) (t_1^2 - t_2) (t_1^4 - t_2) (-1 + t_2)^2 \right. \\ \left. (t_1^3 - t_2^2) (t_1 - t_3) (t_1^2 - t_3) (t_1^4 - t_3) (t_1 t_2 - t_3) (t_2^2 - t_3) \right. \\ \left. (-1 + t_3)^2 (-t_2 + t_1 t_3) (t_1^3 - t_2 t_3) (t_1^3 - t_3^2) (t_2 - t_3^2) \right)$$

In[118]:= G61[t1_, t2_, t3_] :=

$$-\left((t_1^{12} t_2^2 t_3^2 \right. \\ \left. (-t_1^7 t_2^2 - t_1^4 t_2^3 - t_1^5 t_2^3 - t_1^6 t_2^3 - t_1^7 t_2^3 + t_1^3 t_2 t_3 + \right. \\ \left. t_1^4 t_2 t_3 + t_1^5 t_2 t_3 + t_1^6 t_2 t_3 + t_1^8 t_2 t_3 + t_1^3 t_2^2 t_3 - t_1^4 t_2^2 t_3 + \right. \\ \left. t_1^8 t_2^2 t_3 + t_1 t_2^4 t_3 + t_1^2 t_2^4 t_3 + t_1^3 t_2^4 t_3 + t_1^4 t_2^4 t_3 - t_1^7 t_3^2 + \right. \\ \left. t_1^3 t_2 t_3^2 - t_1^4 t_2 t_3^2 + t_1^8 t_2 t_3^2 - t_1 t_2^2 t_3^2 - t_1^2 t_2^2 t_3^2 - t_1^3 t_2^2 t_3^2 + \right. \\ \left. t_1^5 t_2^2 t_3^2 + t_1^6 t_2^2 t_3^2 + t_1^7 t_2^2 t_3^2 - t_2^3 t_3^2 + t_1^4 t_2^3 t_3^2 - t_1^5 t_2^3 t_3^2 + \right. \\ \left. t_1 t_2^4 t_3^2 - t_1^4 t_3^3 - t_1^5 t_3^3 - t_1^6 t_3^3 - t_1^7 t_3^3 - t_2^2 t_3^3 + t_1^4 t_2^2 t_3^3 - \right. \\ \left. t_1^5 t_2^2 t_3^3 - t_2^3 t_3^3 - t_1^2 t_2^3 t_3^3 - t_1^3 t_2^3 t_3^3 - t_1^4 t_2^3 t_3^3 - t_1^5 t_2^3 t_3^3 + \right. \\ \left. t_1 t_2 t_3^4 + t_1^2 t_2 t_3^4 + t_1^3 t_2 t_3^4 + t_1^4 t_2 t_3^4 + t_1 t_2^2 t_3^4) \right) / \\ \left((-1 + t_1)^4 (1 + t_1) (1 + t_1 + t_1^2) (t_1 - t_2) (t_1^2 - t_2) (t_1^4 - t_2) (-1 + t_2)^2 \right. \\ \left. (t_1^3 - t_2^2) (t_1 - t_3) (t_1^2 - t_3) (t_1^4 - t_3) (t_1 t_2 - t_3) (t_2^2 - t_3) \right. \\ \left. (-1 + t_3)^2 (-t_2 + t_1 t_3) (t_1^3 - t_2 t_3) (t_1^3 - t_3^2) (t_2 - t_3^2) \right);$$

In[199]:= T61[t1_, t2_, t3_, u_, v_] := Det[DiagonalMatrix[

{-u + 1, -t1 * u + 1, -t1^2 * u + 1, -t1^3 * u + 1, -t2 * u + 1, -t3 * u + 1, -v + 1,
(t1 - v) / t1, (t1^2 - v) / t1^2, (t1^3 - v) / t1^3, (t2 - v) / t2, (t3 - v) / t3}]]

In[200]:= GT61[t1_, t2_, t3_, u_, v_] := G61[t1, t2, t3] * T61[t1, t2, t3, u, v]

```
In[124]:= Solve[{u1 * u3 == t2 && u0 * u5 == t1^2 && u1 * u2 == t1 &&
  u3 * u5 == t1^2 * t2 / t3 && u2 * u4 == t3 / t1 && u0 * u3 == t2^2 / t1 &&
  u1 * u5 == t1^3 / t2 && u0 * u4 == t3^2 / t1^2 && u1 * u4 == t3^2 / (t1 * t2) &&
  u3 * u4 == t2 * t3 / (t1^2) && u2 * u3 == t2^2 / t3 && u0 * u1 == t3 &&
  u4 * u5 == t1 * t3 / t2 && u2 * u5 == t1^3 / t3 && u0 * u2 == t2}, {u0, u1, u2, u3, u4, u5}]
```

$$\text{Out[124]} = \left\{ \left\{ u_0 \rightarrow -\frac{\sqrt{t_2} \sqrt{t_3}}{\sqrt{t_1}}, u_1 \rightarrow -\frac{\sqrt{t_1} \sqrt{t_3}}{\sqrt{t_2}}, u_2 \rightarrow -\frac{\sqrt{t_1} \sqrt{t_2}}{\sqrt{t_3}}, u_3 \rightarrow -\frac{t_2^{3/2}}{\sqrt{t_1} \sqrt{t_3}}, \right. \right. \\ \left. u_4 \rightarrow -\frac{t_3^{3/2}}{t_1^{3/2} \sqrt{t_2}}, u_5 \rightarrow -\frac{t_1^{5/2}}{\sqrt{t_2} \sqrt{t_3}} \right\}, \left\{ u_0 \rightarrow \frac{\sqrt{t_2} \sqrt{t_3}}{\sqrt{t_1}}, u_1 \rightarrow \frac{\sqrt{t_1} \sqrt{t_3}}{\sqrt{t_2}}, \right. \\ \left. u_2 \rightarrow \frac{\sqrt{t_1} \sqrt{t_2}}{\sqrt{t_3}}, u_3 \rightarrow \frac{t_2^{3/2}}{\sqrt{t_1} \sqrt{t_3}}, u_4 \rightarrow \frac{t_3^{3/2}}{t_1^{3/2} \sqrt{t_2}}, u_5 \rightarrow \frac{t_1^{5/2}}{\sqrt{t_2} \sqrt{t_3}} \right\} \}$$

```
In[125]:= Together[
  G[-\frac{\sqrt{t_2} \sqrt{t_3}}{\sqrt{t_1}}, -\frac{\sqrt{t_1} \sqrt{t_3}}{\sqrt{t_2}}, -\frac{\sqrt{t_1} \sqrt{t_2}}{\sqrt{t_3}}, -\frac{t_2^{3/2}}{\sqrt{t_1} \sqrt{t_3}}, -\frac{t_3^{3/2}}{t_1^{3/2} \sqrt{t_2}}, -\frac{t_1^{5/2}}{\sqrt{t_2} \sqrt{t_3}}]]
```

$$\text{Out[125]} = \frac{1}{t_1^3 t_2 t_3} \\ (-t_1^6 t_2^2 + t_1^8 t_2^2 - t_1^5 t_2^3 + t_1^6 t_2^3 + t_1^5 t_2^4 - t_1^8 t_2^4 + t_1^3 t_2 t_3 - t_1^6 t_2 t_3 + t_1^7 t_2 t_3 - \\ t_1^9 t_2 t_3 - t_1^4 t_2^2 t_3 + 2 t_1^6 t_2^2 t_3 - t_1^7 t_2^2 t_3 - t_1^3 t_2^3 t_3 + 2 t_1^4 t_2^3 t_3 - t_1^6 t_2^3 t_3 - \\ t_1^7 t_2^3 t_3 + t_1^9 t_2^3 t_3 + t_1^3 t_2^4 t_3 - t_1^4 t_2^4 t_3 - t_1^6 t_2^4 t_3 + t_1^7 t_2^4 t_3 - t_1^3 t_2^5 t_3 + \\ t_1^6 t_2^5 t_3 - t_1^5 t_3^2 + t_1^7 t_3^2 - 2 t_1^4 t_2 t_3^2 + 2 t_1^5 t_2 t_3^2 + t_1^6 t_2 t_3^2 - t_1^7 t_2 t_3^2 - \\ t_1^2 t_2^2 t_3^2 - t_1^3 t_2^2 t_3^2 + 5 t_1^4 t_2^2 t_3^2 - t_1^5 t_2^2 t_3^2 - 2 t_1^6 t_2^2 t_3^2 - t_1^7 t_2^2 t_3^2 + \\ t_1^8 t_2^2 t_3^2 - t_1 t_2^3 t_3^2 + t_1^2 t_2^3 t_3^2 + 2 t_1^3 t_2^3 t_3^2 - 2 t_1^4 t_2^3 t_3^2 - t_1^5 t_2^3 t_3^2 + \\ 2 t_1^7 t_2^3 t_3^2 - t_1^8 t_2^3 t_3^2 + t_1 t_2^4 t_3^2 - t_1^3 t_2^4 t_3^2 - 2 t_1^4 t_2^4 t_3^2 + 2 t_1^5 t_2^4 t_3^2 + \\ t_1^6 t_2^4 t_3^2 - t_1^7 t_2^4 t_3^2 + t_1^4 t_2^5 t_3^2 - t_1^5 t_2^5 t_3^2 - t_1^4 t_3^3 + t_1^5 t_3^3 - t_1^2 t_2 t_3^3 + \\ t_1^3 t_2 t_3^3 + 2 t_1^4 t_2 t_3^3 - 2 t_1^5 t_2 t_3^3 - t_1^6 t_2 t_3^3 + t_1^8 t_2 t_3^3 - t_1 t_2^2 t_3^3 + \\ 2 t_1^2 t_2^2 t_3^3 - t_1^4 t_2^2 t_3^3 - 2 t_1^5 t_2^2 t_3^3 + 2 t_1^6 t_2^2 t_3^3 + t_1^7 t_2^2 t_3^3 - t_1^8 t_2^2 t_3^3 + \\ t_1 t_2^3 t_3^3 - t_1^2 t_2^3 t_3^3 - 2 t_1^3 t_2^3 t_3^3 - t_1^4 t_2^3 t_3^3 + 5 t_1^5 t_2^3 t_3^3 - t_1^6 t_2^3 t_3^3 - \\ t_1^7 t_2^3 t_3^3 - t_1^2 t_2^4 t_3^3 + t_1^3 t_2^4 t_3^3 + 2 t_1^4 t_2^4 t_3^3 - 2 t_1^5 t_2^4 t_3^3 + t_1^2 t_2^5 t_3^3 - \\ t_1^4 t_2^5 t_3^3 + t_1^3 t_3^4 - t_1^6 t_3^4 + t_1^2 t_2 t_3^4 - t_1^3 t_2 t_3^4 - t_1^5 t_2 t_3^4 + t_1^6 t_2 t_3^4 + \\ t_2^2 t_3^4 - t_1^2 t_2^2 t_3^4 - t_1^3 t_2^2 t_3^4 + 2 t_1^5 t_2^2 t_3^4 - t_1^6 t_2^2 t_3^4 - t_1^2 t_2^3 t_3^4 + \\ 2 t_1^3 t_2^3 t_3^4 - t_1^5 t_2^3 t_3^4 - t_2^4 t_3^4 + t_1^2 t_2^4 t_3^4 - t_1^3 t_2^4 t_3^4 + t_1^6 t_2^4 t_3^4 - \\ t_1 t_2 t_3^5 + t_1^4 t_2 t_3^5 + t_1^3 t_2^2 t_3^5 - t_1^4 t_2^2 t_3^5 + t_1 t_2^3 t_3^5 - t_1^3 t_2^3 t_3^5)$$

```
In[126]:= G62tangent[t1_, t2_, t3_] :=
  Det[DiagonalMatrix[{-t3 + 1, -t1^2 + 1, (-t2^2 + t1) / t1, (t1 - t3) / t1, -t1 + 1,
    -t2 + 1, (t1^2 - t2^2) / t1^2, (t1^2 - t2 * t3) / t1^2, (t1^2 - t3^2) / t1^2,
    (-t1 * t3 + t2) / t2, (-t1^3 + t2) / t2, -t2 + 1, (t2 - t3) / t2, (-t1^2 + t2) / t2,
    -t1 + 1, (t1 - t2) / t1, (t1 - t3) / t1, (t1 * t2 - t3^2) / (t1 * t2), -t1 + 1,
    (-t1^3 + t3) / t3, (-t1^2 * t2 + t3) / t3, (-t2^2 + t3) / t3, -t2 + 1, -t3 + 1}]]
```

In[128]:= Together[%125 / G62tangent[t1, t2, t3]]

$$\begin{aligned} \text{Out[128]} = & - \left((t_1^8 t_2^4 t_3^2 \right. \\ & (-t_1^6 t_2^2 - t_1^7 t_2^2 - t_1^5 t_2^3 - t_1^6 t_2^3 - t_1^7 t_2^3 + t_1^3 t_2 t_3 + t_1^4 t_2 t_3 + t_1^5 t_2 t_3 + \\ & t_1^7 t_2 t_3 + t_1^8 t_2 t_3 + t_1^3 t_2^2 t_3 + t_1^6 t_2^2 t_3 + t_1^7 t_2^2 t_3 + t_1^8 t_2^2 t_3 + t_1^4 t_2^3 t_3 + \\ & t_1^5 t_2^3 t_3 + t_1^6 t_2^3 t_3 + t_1^3 t_2^4 t_3 + t_1^4 t_2^4 t_3 + t_1^5 t_2^4 t_3 - t_1^5 t_3^2 - t_1^6 t_3^2 - \\ & 2 t_1^4 t_2 t_3^2 - t_1^5 t_2 t_3^2 - t_1^2 t_2^2 t_3^2 - 2 t_1^3 t_2^2 t_3^2 + t_1^4 t_2^2 t_3^2 + t_1^5 t_2^2 t_3^2 - \\ & t_1^7 t_2^2 t_3^2 - t_1 t_2^3 t_3^2 - t_1^2 t_2^3 t_3^2 + t_1^4 t_2^3 t_3^2 - t_1^6 t_2^3 t_3^2 - \\ & t_1^4 t_2^4 t_3^2 - t_1^4 t_3^3 - t_1^2 t_2 t_3^3 + t_1^4 t_2 t_3^3 - t_1^6 t_2 t_3^3 - t_1^7 t_2 t_3^3 - \\ & t_1 t_2^2 t_3^3 + t_1^3 t_2^2 t_3^3 + t_1^4 t_2^2 t_3^3 - 2 t_1^5 t_2^2 t_3^3 - t_1^6 t_2^2 t_3^3 - \\ & t_1^3 t_2^3 t_3^3 - 2 t_1^4 t_2^3 t_3^3 - t_1^2 t_2^4 t_3^3 - t_1^3 t_2^4 t_3^3 + t_1^3 t_3^4 + t_1^4 t_3^4 + \\ & t_1^5 t_3^4 + t_1^2 t_2 t_3^4 + t_1^3 t_2 t_3^4 + t_1^4 t_2 t_3^4 + t_2^2 t_3^4 + t_1 t_2^2 t_3^4 + \\ & t_1^2 t_2^2 t_3^4 + t_1^5 t_2^2 t_3^4 + t_2^3 t_3^4 + t_1 t_2^3 t_3^4 + t_1^3 t_2^3 t_3^4 + t_1^4 t_2^3 t_3^4 + \\ & t_1^5 t_2^3 t_3^4 - t_1 t_2 t_3^5 - t_1^2 t_2 t_3^5 - t_1^3 t_2 t_3^5 - t_1 t_2^2 t_3^5 - t_1^2 t_2^2 t_3^5) \Big) / \\ & ((-1 + t_1)^3 (1 + t_1) (t_1 - t_2)^2 (t_1^2 - t_2) (t_1^3 - t_2) (-1 + t_2)^2 (t_1 + t_2) \\ & (t_1 - t_2^2) (t_1 - t_3)^3 (t_1^3 - t_3) (t_2 - t_3) (t_1^2 t_2 - t_3) (t_2^2 - t_3) \\ & (-1 + t_3)^2 (t_1 + t_3) (-t_2 + t_1 t_3) (t_1^2 - t_2 t_3) (t_1 t_2 - t_3^2)) \end{aligned}$$

In[129]:= G62[t1_, t2_, t3_] :=

$$\begin{aligned} & - \left((t_1^8 t_2^4 t_3^2 (-t_1^6 t_2^2 - t_1^7 t_2^2 - t_1^5 t_2^3 - t_1^6 t_2^3 - t_1^7 t_2^3 + t_1^3 t_2 t_3 + t_1^4 t_2 t_3 + \right. \\ & t_1^5 t_2 t_3 + t_1^7 t_2 t_3 + t_1^8 t_2 t_3 + t_1^3 t_2^2 t_3 + t_1^6 t_2^2 t_3 + t_1^7 t_2^2 t_3 + \\ & t_1^8 t_2^2 t_3 + t_1^4 t_2^3 t_3 + t_1^5 t_2^3 t_3 + t_1^6 t_2^3 t_3 + t_1^3 t_2^4 t_3 + t_1^4 t_2^4 t_3 + \\ & t_1^5 t_2^4 t_3 - t_1^5 t_3^2 - t_1^6 t_3^2 - 2 t_1^4 t_2 t_3^2 - t_1^5 t_2 t_3^2 - t_1^2 t_2^2 t_3^2 - \\ & 2 t_1^3 t_2^2 t_3^2 + t_1^4 t_2^2 t_3^2 + t_1^5 t_2^2 t_3^2 - t_1^7 t_2^2 t_3^2 - t_1 t_2^3 t_3^2 - t_1^2 t_2^3 t_3^2 + \\ & t_1^4 t_2^3 t_3^2 - t_1^6 t_2^3 t_3^2 - t_1^4 t_2^4 t_3^2 - t_1^4 t_3^3 - t_1^2 t_2 t_3^3 + t_1^4 t_2 t_3^3 - \\ & t_1^6 t_2 t_3^3 - t_1^7 t_2 t_3^3 - t_1 t_2^2 t_3^3 + t_1^3 t_2^2 t_3^3 + t_1^4 t_2^2 t_3^3 - 2 t_1^5 t_2^2 t_3^3 - \\ & t_1^6 t_2^2 t_3^3 - t_1^3 t_2^3 t_3^3 - 2 t_1^4 t_2^3 t_3^3 - t_1^2 t_2^4 t_3^3 - t_1^3 t_2^4 t_3^3 + t_1^3 t_3^4 + \\ & t_1^4 t_3^4 + t_1^5 t_3^4 + t_1^2 t_2 t_3^4 + t_1^3 t_2 t_3^4 + t_1^4 t_2 t_3^4 + t_2^2 t_3^4 + t_1 t_2^2 t_3^4 + \\ & t_1^2 t_2^2 t_3^4 + t_1^5 t_2^2 t_3^4 + t_2^3 t_3^4 + t_1 t_2^3 t_3^4 + t_1^3 t_2^3 t_3^4 + t_1^4 t_2^3 t_3^4 + \\ & t_1^5 t_2^3 t_3^4 - t_1 t_2 t_3^5 - t_1^2 t_2 t_3^5 - t_1^3 t_2 t_3^5 - t_1 t_2^2 t_3^5 - t_1^2 t_2^2 t_3^5) \Big) / \\ & ((-1 + t_1)^3 (1 + t_1) (t_1 - t_2)^2 (t_1^2 - t_2) (t_1^3 - t_2) (-1 + t_2)^2 (t_1 + t_2) \\ & (t_1 - t_2^2) (t_1 - t_3)^3 (t_1^3 - t_3) (t_2 - t_3) (t_1^2 t_2 - t_3) (t_2^2 - t_3) \\ & (-1 + t_3)^2 (t_1 + t_3) (-t_2 + t_1 t_3) (t_1^2 - t_2 t_3) (t_1 t_2 - t_3^2)) \end{aligned}$$

In[201]:= T62[t1_, t2_, t3_, u_, v_] :=

$$\begin{aligned} & \text{Det}[\text{DiagonalMatrix}[\{-u + 1, -t_1 * u + 1, -t_1^2 * u + 1, -t_2 * u + 1, \\ & -t_1 * t_2 * u + 1, -t_3 * u + 1, -v + 1, (t_1 - v) / t_1, (t_1^2 - v) / t_1^2, \\ & (t_2 - v) / t_2, (t_1 * t_2 - v) / (t_1 * t_2), (t_3 - v) / t_3\}]] \end{aligned}$$

In[203]:= GT62[t1_, t2_, t3_, u_, v_] := G62[t1, t2, t3] * T62[t1, t2, t3, u, v]

```
In[130]:= Solve[u1 * u3 == t2 && u1 * u2 == t1^2 && u3 * u4 == t2 * t3 / t1^2 &&
  u0 * u3 == t2^3 / t1^2 && u0 * u4 == t3^2 / t1^2 && u0 * u5 == t1 && u2 * u4 == t3 &&
  u0 * u2 == t2^2 && u4 * u5 == t1 * t3 / t2^2 && u1 * u5 == t1^3 / t2^2 &&
  u1 * u4 == t3^2 / t2^2 && u3 * u5 == t1 * t2 / t3 && u2 * u5 == t1^3 / t3 &&
  u2 * u3 == t2^3 / t3 && u0 * u1 == t3, {u0, u1, u2, u3, u4, u5}]
```

$$\text{Out[130]} = \left\{ \left\{ u_0 \rightarrow -\frac{t_2 \sqrt{t_3}}{t_1}, u_1 \rightarrow -\frac{t_1 \sqrt{t_3}}{t_2}, \right. \right. \\ \left. u_2 \rightarrow -\frac{t_1 t_2}{\sqrt{t_3}}, u_3 \rightarrow -\frac{t_2^2}{t_1 \sqrt{t_3}}, u_4 \rightarrow -\frac{t_3^{3/2}}{t_1 t_2}, u_5 \rightarrow -\frac{t_1^2}{t_2 \sqrt{t_3}} \right\}, \\ \left. \left\{ u_0 \rightarrow \frac{t_2 \sqrt{t_3}}{t_1}, u_1 \rightarrow \frac{t_1 \sqrt{t_3}}{t_2}, u_2 \rightarrow \frac{t_1 t_2}{\sqrt{t_3}}, u_3 \rightarrow \frac{t_2^2}{t_1 \sqrt{t_3}}, u_4 \rightarrow \frac{t_3^{3/2}}{t_1 t_2}, u_5 \rightarrow \frac{t_1^2}{t_2 \sqrt{t_3}} \right\} \right\}$$

```
In[131]:= Together[G[-\frac{t_2 \sqrt{t_3}}{t_1}, -\frac{t_1 \sqrt{t_3}}{t_2}, -\frac{t_1 t_2}{\sqrt{t_3}}, -\frac{t_2^2}{t_1 \sqrt{t_3}}, -\frac{t_3^{3/2}}{t_1 t_2}, -\frac{t_1^2}{t_2 \sqrt{t_3}}]]
```

$$\text{Out[131]} = \frac{1}{t_1^2 t_2^2 t_3} \\ (-t_1^5 t_2^3 + t_1^6 t_2^3 - t_1^3 t_2^5 + t_1^5 t_2^5 + t_1^3 t_2^6 - t_1^6 t_2^6 + t_1^6 t_2 t_3 - t_1^7 t_2 t_3 + t_1^2 t_2^2 t_3 - \\ t_1^5 t_2^2 t_3 - 2 t_1^3 t_2^3 t_3 + t_1^4 t_2^3 t_3 + 2 t_1^5 t_2^3 t_3 - t_1^6 t_2^3 t_3 + t_1^3 t_2^4 t_3 - t_1^4 t_2^4 t_3 - \\ t_1^6 t_2^4 t_3 + t_1^7 t_2^4 t_3 - t_1^2 t_2^5 t_3 + 2 t_1^3 t_2^5 t_3 - t_1^5 t_2^5 t_3 + t_1 t_2^6 t_3 - t_1^3 t_2^6 t_3 - \\ t_1^4 t_2^6 t_3 + t_1^6 t_2^6 t_3 - t_1 t_2^7 t_3 + t_1^4 t_2^7 t_3 - t_1^5 t_3^2 + t_1^6 t_3^2 - t_1^3 t_2 t_3^2 + \\ t_1^4 t_2 t_3^2 + t_1^5 t_2 t_3^2 - t_1^6 t_2 t_3^2 - t_1^3 t_2^2 t_3^2 + t_1^5 t_2^2 t_3^2 - t_1^6 t_2^2 t_3^2 + t_1^7 t_2^2 t_3^2 - \\ t_1 t_2^3 t_3^2 - t_1^2 t_2^3 t_3^2 + 5 t_1^3 t_2^3 t_3^2 - t_1^4 t_2^3 t_3^2 - t_1^5 t_2^3 t_3^2 - t_1^6 t_2^3 t_3^2 + \\ t_1 t_2^4 t_3^2 - t_1^3 t_2^4 t_3^2 - 2 t_1^4 t_2^4 t_3^2 + t_1^5 t_2^4 t_3^2 + 2 t_1^6 t_2^4 t_3^2 - t_1^7 t_2^4 t_3^2 - \\ t_2^5 t_3^2 + t_1 t_2^5 t_3^2 + t_1^2 t_2^5 t_3^2 - t_1^3 t_2^5 t_3^2 + t_1^4 t_2^5 t_3^2 - t_1^5 t_2^5 t_3^2 + t_2^6 t_3^2 - \\ t_1 t_2^6 t_3^2 - t_1^2 t_2^6 t_3^2 - t_1^3 t_2^6 t_3^2 + 2 t_1^4 t_2^6 t_3^2 + t_1^2 t_2^7 t_3^2 - t_1^4 t_2^7 t_3^2 - t_1^3 t_3^3 + \\ t_1^5 t_3^3 + 2 t_1^3 t_2 t_3^3 - t_1^4 t_2 t_3^3 - t_1^5 t_2 t_3^3 - t_1^6 t_2 t_3^3 + t_1^7 t_2 t_3^3 - t_1^2 t_2^2 t_3^3 + \\ t_1^3 t_2^2 t_3^3 - t_1^4 t_2^2 t_3^3 + t_1^5 t_2^2 t_3^3 + t_1^6 t_2^2 t_3^3 - t_1^7 t_2^2 t_3^3 - t_2^3 t_3^3 + 2 t_1 t_2^3 t_3^3 + \\ t_1^2 t_2^3 t_3^3 - 2 t_1^3 t_2^3 t_3^3 - t_1^4 t_2^3 t_3^3 + t_1^6 t_2^3 t_3^3 - t_1 t_2^4 t_3^3 - t_1^2 t_2^4 t_3^3 - \\ t_1^3 t_2^4 t_3^3 + 5 t_1^4 t_2^4 t_3^3 - t_1^5 t_2^4 t_3^3 - t_1^6 t_2^4 t_3^3 + t_2^5 t_3^3 - t_1 t_2^5 t_3^3 + t_1^2 t_2^5 t_3^3 - \\ t_1^4 t_2^5 t_3^3 - t_1 t_2^6 t_3^3 + t_1^2 t_2^6 t_3^3 + t_1^3 t_2^6 t_3^3 - t_1^4 t_2^6 t_3^3 + t_1 t_2^7 t_3^3 - t_1^2 t_2^7 t_3^3 + \\ t_1^3 t_3^4 - t_1^6 t_3^4 + t_1 t_2 t_3^4 - t_1^3 t_2 t_3^4 - t_1^4 t_2 t_3^4 + t_1^6 t_2 t_3^4 - t_1^2 t_2^2 t_3^4 + \\ 2 t_1^4 t_2^2 t_3^4 - t_1^5 t_2^2 t_3^4 + t_2^3 t_3^4 - t_1 t_2^3 t_3^4 - t_1^3 t_2^3 t_3^4 + t_1^4 t_2^3 t_3^4 - t_1 t_2^4 t_3^4 + \\ 2 t_1^2 t_2^4 t_3^4 + t_1^3 t_2^4 t_3^4 - 2 t_1^4 t_2^4 t_3^4 - t_1^2 t_2^5 t_3^4 + t_1^5 t_2^5 t_3^4 - t_2^6 t_3^4 + \\ t_1 t_2^6 t_3^4 - t_1 t_2 t_3^5 + t_1^4 t_2 t_3^5 + t_1^2 t_2^2 t_3^5 - t_1^4 t_2^2 t_3^5 + t_1 t_2^4 t_3^5 - t_1^2 t_2^4 t_3^5)$$

```
In[132]:= G63tangent[t1_, t2_, t3_] :=
```

```
Det[DiagonalMatrix[{-t2 + 1, -t3 + 1, -t1^2 + 1, (t1 - t2) / t1, (t1 - t3) / t1,
  -t1 + 1, (t1^2 - t2 * t3) / t1^2, (-t2^3 + t1^2) / t1^2, (t1^2 - t3^2) / t1^2,
  -t1 + 1, -t3 + 1, -t2^2 + 1, (-t1 + t2) / t2, (t2^2 - t1 * t3) / t2^2,
  (-t1^3 + t2^2) / t2^2, (t2 - t3) / t2, -t2 + 1, (t2^2 - t3^2) / t2^2,
  (-t1 * t2 + t3) / t3, -t1 + 1, (-t1^3 + t3) / t3, -t2 + 1, (-t2^3 + t3) / t3, -t3 + 1}]]
```


In[133]:= Together[%131 / G63tangent[t1, t2, t3]]

Out[133]=
$$\frac{\begin{aligned} &(-t_1^5 t_2^3 - t_1^5 t_2^4 - t_1^3 t_2^5 - t_1^4 t_2^5 - t_1^5 t_2^5 + t_1^6 t_2 t_3 + t_1^2 t_2^2 t_3 + t_1^3 t_2^2 t_3 + \\ &t_1^4 t_2^2 t_3 + t_1^6 t_2^2 t_3 + t_1^2 t_2^3 t_3 - t_1^3 t_2^3 t_3 + t_1^6 t_2^3 t_3 + t_1^2 t_2^4 t_3 + t_1 t_2^6 t_3 + \\ &t_1^2 t_2^6 t_3 + t_1^3 t_2^6 t_3 - t_1^5 t_2^3 - t_1^3 t_2 t_3^2 + t_1^6 t_2 t_3^2 + t_1^2 t_2^2 t_3^2 - t_1^3 t_2^2 t_3^2 - \\ &t_1 t_2^3 t_3^2 - t_1^2 t_2^3 t_3^2 + t_1^4 t_2^3 t_3^2 + t_1^5 t_2^3 t_3^2 + t_1^3 t_2^4 t_3^2 - t_1^4 t_2^4 t_3^2 - \\ &t_2^5 t_3^2 + t_1^3 t_2^5 t_3^2 + t_1 t_2^6 t_3^2 - t_1^3 t_3^3 - t_1^4 t_3^3 - t_1^5 t_3^3 - t_1^4 t_2^2 t_3^3 - \\ &t_2^3 t_3^3 + t_1^3 t_2^3 t_3^3 - t_1^4 t_2^3 t_3^3 - t_2^4 t_3^3 - t_1^2 t_2^4 t_3^3 - t_1^3 t_2^4 t_3^3 - t_1^4 t_2^4 t_3^3 - \\ &t_2^5 t_3^3 + t_1 t_2 t_3^4 + t_1^2 t_2 t_3^4 + t_1^3 t_2 t_3^4 + t_1 t_2^2 t_3^4 + t_1 t_2^3 t_3^4) \end{aligned}}{((-1+t_1)^3 (1+t_1) (t_1-t_2)^2 (-1+t_2)^3 (1+t_2) (t_1^3-t_2^2) (t_1^2-t_2^3) (t_1-t_3)^2 (t_1^3-t_3) (t_2-t_3)^2 (t_1 t_2-t_3) (t_2^3-t_3) (-1+t_3)^2 (t_1+t_3) (t_2+t_3) (-t_2^2+t_1 t_3) (t_1^2-t_2 t_3))}$$

In[134]:= G63[t1_, t2_, t3_] :=

$$\begin{aligned} &(t_1^6 t_2^6 t_3^2 (-t_1^5 t_2^3 - t_1^5 t_2^4 - t_1^3 t_2^5 - t_1^4 t_2^5 - t_1^5 t_2^5 + t_1^6 t_2 t_3 + t_1^2 t_2^2 t_3 + \\ &t_1^3 t_2^2 t_3 + t_1^4 t_2^2 t_3 + t_1^6 t_2^2 t_3 + t_1^2 t_2^3 t_3 - t_1^3 t_2^3 t_3 + t_1^6 t_2^3 t_3 + t_1^2 t_2^4 t_3 + \\ &t_1 t_2^6 t_3 + t_1^2 t_2^6 t_3 + t_1^3 t_2^6 t_3 - t_1^5 t_2^3 - t_1^3 t_2 t_3^2 + t_1^6 t_2 t_3^2 + t_1^2 t_2^2 t_3^2 - \\ &t_1^3 t_2^2 t_3^2 - t_1 t_2^3 t_3^2 - t_1^2 t_2^3 t_3^2 + t_1^4 t_2^3 t_3^2 + t_1^5 t_2^3 t_3^2 + t_1^3 t_2^4 t_3^2 - \\ &t_1^4 t_2^4 t_3^2 - t_2^5 t_3^2 + t_1^3 t_2^5 t_3^2 + t_1 t_2^6 t_3^2 - t_1^3 t_3^3 - t_1^4 t_3^3 - t_1^5 t_3^3 - \\ &t_1^4 t_2^2 t_3^3 - t_2^3 t_3^3 + t_1^3 t_2^3 t_3^3 - t_1^4 t_2^3 t_3^3 - t_2^4 t_3^3 - t_1^2 t_2^4 t_3^3 - t_1^3 t_2^4 t_3^3 - \\ &t_1^4 t_2^4 t_3^3 - t_2^5 t_3^3 + t_1 t_2 t_3^4 + t_1^2 t_2 t_3^4 + t_1^3 t_2 t_3^4 + t_1 t_2^2 t_3^4 + t_1 t_2^3 t_3^4) \end{aligned}}{((-1+t_1)^3 (1+t_1) (t_1-t_2)^2 (-1+t_2)^3 (1+t_2) (t_1^3-t_2^2) (t_1^2-t_2^3) (t_1-t_3)^2 (t_1^3-t_3) (t_2-t_3)^2 (t_1 t_2-t_3) (t_2^3-t_3) (-1+t_3)^2 (t_1+t_3) (t_2+t_3) (-t_2^2+t_1 t_3) (t_1^2-t_2 t_3))}$$

In[204]:= T63[t1_, t2_, t3_, u_, v_] := Det[DiagonalMatrix[

{-u+1, -t1*u+1, -t1^2*u+1, -t2*u+1, -t2^2*u+1, -t3*u+1, -v+1, (t1-v)/t1, (t1^2-v)/t1^2, (t2-v)/t2, (t2^2-v)/t2^2, (t3-v)/t3}]]

In[205]:= GT63[t1_, t2_, t3_, u_, v_] := G63[t1, t2, t3] * T63[t1, t2, t3, u, v]

In[181]:= G6smoothTangentContributions[t1_, t2_, t3_] :=

{{-t2+1, -t3+1, -t1^6+1, (t1-t2)/t1, (t1-t3)/t1, -t1^5+1, (t1^2-t2)/t1^2, (t1^2-t3)/t1^2, -t1^4+1, (t1^3-t2)/t1^3, (t1^3-t3)/t1^3, -t1^3+1, (t1^4-t2)/t1^4, (t1^4-t3)/t1^4, -t1^2+1, (t1^5-t2)/t1^5, (t1^5-t3)/t1^5, -t1+1}, {-t3+1, (t1-t3)/t1, -t2+1, -t1^4+1, (t1^2-t3)/t1^2, (t1-t2)/t1, -t1^3+1, (t1^3-t3)/t1^3, (t1^2-t2)/t1^2, -t1^2+1, (t1^4-t3)/t1^4, (t1^3-t2)/t1^3, -t1+1, (t1^4-t2^2)/t1^4, (t2-t3)/t2, -t1+1, (-t1^5+t2)/t2, -t2+1}, {-t3+1, (t1-t3)/t1, (t1^2-t3)/t1^2, -t2+1, -t1^2+1, (t1^2-t2^2)/t1^2, (t1^3-t3)/t1^3, (t1-t2)/t1, -t1+1, (t1^3-t2^2)/t1^3, (t2-t3)/t2, -t1^2+1, (-t1^4+t2)/t2, -t2+1, (t1*t2-t3)/(t1*t2), -t1+1, (-t1^3+t2)/t2, (t1-t2)/t1}, {-t3+1, (t1-t3)/t1, -t2+1, -t1^3+1, (t1^2-t3)/t1^2, (t1-t2)/t1, -t1^2+1, (t1^3-t3)/t1^3, (t1^2-t2)/t1^2, -t1+1, (t1^3-t2^3)/t1^3, (t2-t3)/t2, -t1+1, -t2^2+1,

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(t2^2 - t3) / t2^2, (-t1 + t2) / t2, (-t1^4 + t2^2) / t2^2, -t2 + 1},
{-t3 + 1, -t1^3 + 1, -t2^2 + 1, (t1 - t3) / t1, -t1^2 + 1, (-t2^2 + t1) / t1,
(t1^2 - t3) / t1^2, -t1 + 1, (t1^2 - t2^2) / t1^2, (t2 - t3) / t2,
(-t1^3 + t2) / t2, -t2 + 1, (t1 * t2 - t3) / (t1 * t2), (-t1^2 + t2) / t2,
(t1 - t2) / t1, (t1^2 * t2 - t3) / (t1^2 * t2), (-t1 + t2) / t2, (t1^2 - t2) / t1^2},
{-t3 + 1, (t1 - t3) / t1, (t1^2 - t3) / t1^2, -t1 + 1, -t2 + 1, (-t2^2 + t1) / t1,
(-t2^3 + t1^2) / t1^2, (t2 - t3) / t2, (t1 * t2 - t3) / (t1 * t2),
(-t1^2 + t2) / t2, -t1 + 1, -t2 + 1, (-t2^2 + t1) / t1, (t2^2 - t3) / t2^2,
(-t1^3 + t2^2) / t2^2, (-t1^2 + t2) / t2, -t1 + 1, -t2 + 1},
{-t3 + 1, (t1 - t3) / t1, -t2 + 1, -t1^2 + 1, (t1^2 - t3) / t1^2,
(t1 - t2) / t1, -t1 + 1, (-t2^4 + t1^2) / t1^2, (t2 - t3) / t2,
-t1 + 1, -t2^3 + 1, (t2^2 - t3) / t2^2, (-t1 + t2) / t2, -t2^2 + 1,
(t2^3 - t3) / t2^3, (t2^2 - t1) / t2^2, (-t1^3 + t2^3) / t2^3, -t2 + 1},
{-t3 + 1, -t1^2 + 1, -t2^3 + 1, (t1 - t3) / t1, -t1 + 1, (-t2^3 + t1) / t1,
(t2 - t3) / t2, (-t1^2 + t2) / t2, -t2^2 + 1, (t1 * t2 - t3) / (t1 * t2),
(-t1 + t2) / t2, (-t2^2 + t1) / t1, (t2^2 - t3) / t2^2, (-t1^2 + t2^2) / t2^2,
-t2 + 1, (t1 * t2^2 - t3) / (t1 * t2^2), (t2^2 - t1) / t2^2, (t1 - t2) / t1},
{-t3 + 1, (t1 - t3) / t1, -t1 + 1, -t2^2 + 1, (-t2^4 + t1) / t1, (t2 - t3) / t2,
(t1 * t2 - t3) / (t1 * t2), (-t1 + t2) / t2, -t2 + 1, (-t2^3 + t1) / t1,
(t2^2 - t3) / t2^2, (-t1^2 + t2^2) / t2^2, -t1 + 1, -t2^2 + 1,
(t2^3 - t3) / t2^3, (t2^3 - t1^2) / t2^3, (-t1 + t2) / t2, -t2 + 1},
{-t3 + 1, (t1 - t3) / t1, -t1 + 1, -t2 + 1, (-t2^5 + t1) / t1, (t2 - t3) / t2,
-t1 + 1, -t2^4 + 1, (t2^2 - t3) / t2^2, (-t1 + t2) / t2,
-t2^3 + 1, (t2^3 - t3) / t2^3, (t2^2 - t1) / t2^2, -t2^2 + 1,
(t2^4 - t3) / t2^4, (t2^4 - t1^2) / t2^4, (t2^3 - t1) / t2^3, -t2 + 1},
{-t1 + 1, -t3 + 1, -t2^6 + 1, (-t1 + t2) / t2, (t2 - t3) / t2, -t2^5 + 1,
(t2^2 - t1) / t2^2, (t2^2 - t3) / t2^2, -t2^4 + 1, (t2^3 - t1) / t2^3,
(t2^3 - t3) / t2^3, -t2^3 + 1, (t2^4 - t1) / t2^4, (t2^4 - t3) / t2^4,
-t2^2 + 1, (t2^5 - t1) / t2^5, (t2^5 - t3) / t2^5, -t2 + 1},
{-t2 + 1, (t1 - t2) / t1, -t3 + 1, -t1^4 + 1, (t1^2 - t2) / t1^2,
(t1 - t3) / t1, -t1^3 + 1, (t1^3 - t2) / t1^3, (t1^2 - t3) / t1^2,
-t1^2 + 1, (t1^4 - t2) / t1^4, (t1^3 - t3) / t1^3, -t1 + 1,
(t1^4 - t3^2) / t1^4, (-t2 + t3) / t3, -t1 + 1, (-t1^5 + t3) / t3, -t3 + 1},
{-t1 + 1, (-t1 + t2) / t2, -t3 + 1, -t2^4 + 1, (t2^2 - t1) / t2^2,
(t2 - t3) / t2, -t2^3 + 1, (t2^3 - t1) / t2^3, (t2^2 - t3) / t2^2,
-t2^2 + 1, (t2^4 - t1) / t2^4, (t2^3 - t3) / t2^3, -t2 + 1,
(t2^4 - t3^2) / t2^4, (-t1 + t3) / t3, -t2 + 1, (-t2^5 + t3) / t3, -t3 + 1},
{-t2 + 1, (t1 - t2) / t1, (t1^2 - t2) / t1^2, -t3 + 1, -t1^2 + 1,
(t1^2 - t3^2) / t1^2, (t1^3 - t2) / t1^3, (t1 - t3) / t1, -t1 + 1,
(t1^3 - t3^2) / t1^3, (-t2 + t3) / t3, -t1^2 + 1, (-t1^4 + t3) / t3,
-t3 + 1, (t1 * t3 - t2) / (t1 * t3), -t1 + 1, (-t1^3 + t3) / t3, (t1 - t3) / t1},
{-t2 + 1, -t3 + 1, -t1^2 + 1, (t1 - t2) / t1, (t1 - t3) / t1, -t1 + 1,
(t1^2 - t2^2) / t1^2, (t1^2 - t3^2) / t1^2, -t1 + 1, -t2 + 1,
(-t3^2 + t2) / t2, (-t2^2 + t3) / t3, -t3 + 1, (-t1 + t3) / t3,
(-t1 + t2) / t2, (-t1^3 + t2 * t3) / (t2 * t3), (-t2 + t3) / t3, (t2 - t3) / t2},
{-t2^2 + 1, -t1 + 1, -t3 + 1, (-t2^2 + t1) / t1, (-t3^2 + t1) / t1, -t2 + 1,
(-t1 + t2) / t2, (t2 - t3) / t2, (t1 - t2) / t1, (t1 * t2 - t3^2) / (t1 * t2),

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(-t1^2 + t3) / t3, -t1 + 1, (-t2^2 + t3) / t3, -t3 + 1,
(-t1^2 + t2 * t3) / (t2 * t3), (-t1 + t2) / t2, (-t2 + t3) / t3, (t2 - t3) / t2},
{-t1^2 + 1, -t1 + 1, (-t1^2 + t2) / t2, -t2 + 1, -t3 + 1, (-t3^2 + t2) / t2,
(-t1 + t2) / t2, (t1 - t2) / t1, (t1 - t3) / t1, (t1 * t2 - t3^2) / (t1 * t2),
(-t1^2 + t3) / t3, (-t2^2 + t3) / t3, -t2 + 1, -t3 + 1, (-t1 + t3) / t3,
(-t2^2 + t1 * t3) / (t1 * t3), (t1 - t2) / t1, (t1 - t3) / t1},
{-t1 + 1, -t2 + 1, (-t3^2 + t1) / t1, -t1 + 1, -t3 + 1, -t2^2 + 1,
(-t1^2 + t2^2) / t2^2, (-t1 + t2) / t2, (t2 - t3) / t2, -t2 + 1,
(t2^2 - t3^2) / t2^2, (-t1^2 + t3) / t3, -t3 + 1, (-t1 + t3) / t3,
(-t2 + t3) / t3, (t1 - t2) / t1, (-t2^3 + t1 * t3) / (t1 * t3), (t1 - t3) / t1},
{-t1 + 1, (-t1 + t2) / t2, (t2^2 - t1) / t2^2, -t3 + 1, -t2^2 + 1,
(t2^2 - t3^2) / t2^2, (t2^3 - t1) / t2^3, (t2 - t3) / t2, -t2 + 1,
(t2^3 - t3^2) / t2^3, (-t1 + t3) / t3, -t2^2 + 1, (-t2^4 + t3) / t3,
-t3 + 1, (t2 * t3 - t1) / (t2 * t3), -t2 + 1, (-t2^3 + t3) / t3, (t2 - t3) / t2},
{-t2 + 1, (t1 - t2) / t1, -t3 + 1, -t1^3 + 1, (t1^2 - t2) / t1^2,
(t1 - t3) / t1, -t1^2 + 1, (t1^3 - t2) / t1^3, (t1^2 - t3) / t1^2,
-t1 + 1, (t1^3 - t3^3) / t1^3, (-t2 + t3) / t3, -t1 + 1, -t3^2 + 1,
(t3^2 - t2) / t3^2, (-t1 + t3) / t3, (-t1^4 + t3^2) / t3^2, -t3 + 1},
{-t1 + 1, -t3 + 1, (-t2^2 + t1) / t1, (-t1^2 + t2) / t2, -t2 + 1,
(-t1 + t2) / t2, (t2 - t3) / t2, (t1 - t2) / t1, (t1 - t3) / t1,
(-t3^3 + t1 * t2) / (t1 * t2), -t1 + 1, -t2 + 1, -t3^2 + 1, (-t1^2 + t3^2) / t3^2,
(-t1 + t3) / t3, (-t2^2 + t3^2) / t3^2, (-t2 + t3) / t3, -t3 + 1},
{-t1 + 1, (-t1 + t2) / t2, -t3 + 1, -t2^3 + 1, (t2^2 - t1) / t2^2,
(t2 - t3) / t2, -t2^2 + 1, (t2^3 - t1) / t2^3, (t2^2 - t3) / t2^2,
-t2 + 1, (t2^3 - t3^3) / t2^3, (-t1 + t3) / t3, -t2 + 1, -t3^2 + 1,
(t3^2 - t1) / t3^2, (-t2 + t3) / t3, (-t2^4 + t3^2) / t3^2, -t3 + 1},
{-t2 + 1, -t1^3 + 1, -t3^2 + 1, (t1 - t2) / t1, -t1^2 + 1, (-t3^2 + t1) / t1,
(t1^2 - t2) / t1^2, -t1 + 1, (t1^2 - t3^2) / t1^2, (-t2 + t3) / t3,
(-t1^3 + t3) / t3, -t3 + 1, (t1 * t3 - t2) / (t1 * t3), (-t1^2 + t3) / t3,
(t1 - t3) / t1, (t1^2 * t3 - t2) / (t1^2 * t3), (-t1 + t3) / t3, (t1^2 - t3) / t1^2},
{-t3^2 + 1, -t1 + 1, -t2 + 1, (-t2^2 + t1) / t1, (-t3^2 + t1) / t1,
(-t1^2 + t2) / t2, -t1 + 1, -t2 + 1, (-t3^2 + t2) / t2, -t3 + 1,
(-t1 + t3) / t3, (-t2 + t3) / t3, (-t2^2 + t1 * t3) / (t1 * t3), (t1 - t3) / t1,
(-t1^2 + t2 * t3) / (t2 * t3), (-t1 + t3) / t3, (-t2 + t3) / t3, (t2 - t3) / t2},
{-t1 + 1, -t2^3 + 1, -t3^2 + 1, (-t1 + t2) / t2, -t2^2 + 1, (-t3^2 + t2) / t2,
(t2^2 - t1) / t2^2, -t2 + 1, (t2^2 - t3^2) / t2^2, (-t1 + t3) / t3,
(-t2^3 + t3) / t3, -t3 + 1, (t2 * t3 - t1) / (t2 * t3), (-t2^2 + t3) / t3,
(t2 - t3) / t2, (t2^2 * t3 - t1) / (t2^2 * t3), (-t2 + t3) / t3, (t2^2 - t3) / t2^2},
{-t2 + 1, (t1 - t2) / t1, (t1^2 - t2) / t1^2, -t1 + 1, -t3 + 1, (-t3^2 + t1) / t1,
(-t3^3 + t1^2) / t1^2, (-t2 + t3) / t3, (t1 * t3 - t2) / (t1 * t3),
(-t1^2 + t3) / t3, -t1 + 1, -t3 + 1, (-t3^2 + t1) / t1, (t3^2 - t2) / t3^2,
(-t1^3 + t3^2) / t3^2, (-t1^2 + t3) / t3, -t1 + 1, -t3 + 1},
{-t1 + 1, (-t1 + t2) / t2, (t2^2 - t1) / t2^2, -t2 + 1, -t3 + 1, (-t3^2 + t2) / t2,
(-t3^3 + t2^2) / t2^2, (-t1 + t3) / t3, (t2 * t3 - t1) / (t2 * t3),
(-t2^2 + t3) / t3, -t2 + 1, -t3 + 1, (-t3^2 + t2) / t2, (t3^2 - t1) / t3^2,
(-t2^3 + t3^2) / t3^2, (-t2^2 + t3) / t3, -t2 + 1, -t3 + 1},
{-t2 + 1, (t1 - t2) / t1, -t3 + 1, -t1^2 + 1, (t1^2 - t2) / t1^2,

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(t1 - t3) / t1, -t1 + 1, (-t3^4 + t1^2) / t1^2, (-t2 + t3) / t3,
-t1 + 1, -t3^3 + 1, (t3^2 - t2) / t3^2, (-t1 + t3) / t3, -t3^2 + 1,
(t3^3 - t2) / t3^3, (t3^2 - t1) / t3^2, (-t1^3 + t3^3) / t3^3, -t3 + 1},
{-t1 + 1, (-t1 + t2) / t2, -t3 + 1, -t2^2 + 1, (t2^2 - t1) / t2^2,
(t2 - t3) / t2, -t2 + 1, (-t3^4 + t2^2) / t2^2, (-t1 + t3) / t3,
-t2 + 1, -t3^3 + 1, (t3^2 - t1) / t3^2, (-t2 + t3) / t3, -t3^2 + 1,
(t3^3 - t1) / t3^3, (t3^2 - t2) / t3^2, (-t2^3 + t3^3) / t3^3, -t3 + 1},
{-t2 + 1, -t1^2 + 1, -t3^3 + 1, (t1 - t2) / t1, -t1 + 1, (-t3^3 + t1) / t1,
(-t2 + t3) / t3, (-t1^2 + t3) / t3, -t3^2 + 1, (t1 * t3 - t2) / (t1 * t3),
(-t1 + t3) / t3, (-t3^2 + t1) / t1, (t3^2 - t2) / t3^2, (-t1^2 + t3^2) / t3^2,
-t3 + 1, (t1 * t3^2 - t2) / (t1 * t3^2), (t3^2 - t1) / t3^2, (t1 - t3) / t1},
{-t1 + 1, -t2^2 + 1, -t3^3 + 1, (-t1 + t2) / t2, -t2 + 1, (-t3^3 + t2) / t2,
(-t1 + t3) / t3, (-t2^2 + t3) / t3, -t3^2 + 1, (t2 * t3 - t1) / (t2 * t3),
(-t2 + t3) / t3, (-t3^2 + t2) / t2, (t3^2 - t1) / t3^2, (-t2^2 + t3^2) / t3^2,
-t3 + 1, (t2 * t3^2 - t1) / (t2 * t3^2), (t3^2 - t2) / t3^2, (t2 - t3) / t2},
{-t2 + 1, (t1 - t2) / t1, -t1 + 1, -t3^2 + 1, (-t3^4 + t1) / t1, (-t2 + t3) / t3,
(t1 * t3 - t2) / (t1 * t3), (-t1 + t3) / t3, -t3 + 1, (-t3^3 + t1) / t1,
(t3^2 - t2) / t3^2, (-t1^2 + t3^2) / t3^2, -t1 + 1, -t3^2 + 1,
(t3^3 - t2) / t3^3, (t3^3 - t1^2) / t3^3, (-t1 + t3) / t3, -t3 + 1},
{-t1 + 1, (-t1 + t2) / t2, -t2 + 1, -t3^2 + 1, (-t3^4 + t2) / t2, (-t1 + t3) / t3,
(t2 * t3 - t1) / (t2 * t3), (-t2 + t3) / t3, -t3 + 1, (-t3^3 + t2) / t2,
(t3^2 - t1) / t3^2, (-t2^2 + t3^2) / t3^2, -t2 + 1, -t3^2 + 1,
(t3^3 - t1) / t3^3, (t3^3 - t2^2) / t3^3, (-t2 + t3) / t3, -t3 + 1},
{-t2 + 1, (t1 - t2) / t1, -t1 + 1, -t3 + 1, (-t3^5 + t1) / t1, (-t2 + t3) / t3,
-t1 + 1, -t3^4 + 1, (t3^2 - t2) / t3^2, (-t1 + t3) / t3,
-t3^3 + 1, (t3^3 - t2) / t3^3, (t3^2 - t1) / t3^2, -t3^2 + 1,
(t3^4 - t2) / t3^4, (t3^4 - t1^2) / t3^4, (t3^3 - t1) / t3^3, -t3 + 1},
{-t1 + 1, (-t1 + t2) / t2, -t2 + 1, -t3 + 1, (-t3^5 + t2) / t2,
(-t1 + t3) / t3, -t2 + 1, -t3^4 + 1, (t3^2 - t1) / t3^2, (-t2 + t3) / t3,
-t3^3 + 1, (t3^3 - t1) / t3^3, (t3^2 - t2) / t3^2, -t3^2 + 1,
(t3^4 - t1) / t3^4, (t3^4 - t2^2) / t3^4, (t3^3 - t2) / t3^3, -t3 + 1},
{-t1 + 1, -t2 + 1, -t3^6 + 1, (-t1 + t3) / t3, (-t2 + t3) / t3, -t3^5 + 1,
(t3^2 - t1) / t3^2, (t3^2 - t2) / t3^2, -t3^4 + 1, (t3^3 - t1) / t3^3,
(t3^3 - t2) / t3^3, -t3^3 + 1, (t3^4 - t1) / t3^4, (t3^4 - t2) / t3^4,
-t3^2 + 1, (t3^5 - t1) / t3^5, (t3^5 - t2) / t3^5, -t3 + 1}}

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In[137]:= Length[G6smoothTangentContributions[t1, t2, t3]]
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Out[137]= 36
```

```
In[206]:= GT6smoothPointsContributions[t1_, t2_, t3_, u_, v_] :=
```

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{((-1) / (t2 - 1), (-1) / (t3 - 1), (-1) / (t1^6 - 1), t1 / (t1 - t2),
t1 / (t1 - t3), (-1) / (t1^5 - 1), t1^2 / (t1^2 - t2), t1^2 / (t1^2 - t3),
(-1) / (t1^4 - 1), t1^3 / (t1^3 - t2), t1^3 / (t1^3 - t3), (-1) / (t1^3 - 1),
t1^4 / (t1^4 - t2), t1^4 / (t1^4 - t3), (-1) / (t1^2 - 1), t1^5 / (t1^5 - t2),
t1^5 / (t1^5 - t3), (-1) / (t1 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1,
-t1^3 * u + 1, -t1^4 * u + 1, -t1^5 * u + 1, -v + 1, (t1 - v) / t1,
(t1^2 - v) / t1^2, (t1^3 - v) / t1^3, (t1^4 - v) / t1^4, (t1^5 - v) / t1^5},
{((-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t2 - 1), (-1) / (t1^4 - 1),

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t1^2 / (t1^2 - t3), t1 / (t1 - t2), (-1) / (t1^3 - 1), t1^3 / (t1^3 - t3),
t1^2 / (t1^2 - t2), (-1) / (t1^2 - 1), t1^4 / (t1^4 - t3),
t1^3 / (t1^3 - t2), (-1) / (t1 - 1), t1^4 / (t1^4 - t2^2), t2 / (t2 - t3),
(-1) / (t1 - 1), (-t2) / (t1^5 - t2), (-1) / (t2 - 1), -u + 1, -t1 * u + 1,
-t1^2 * u + 1, -t1^3 * u + 1, -t1^4 * u + 1, -t2 * u + 1, -v + 1, (t1 - v) / t1,
(t1^2 - v) / t1^2, (t1^3 - v) / t1^3, (t1^4 - v) / t1^4, (t2 - v) / t2},
{(-1) / (t3 - 1), t1 / (t1 - t3), t1^2 / (t1^2 - t3), (-1) / (t2 - 1),
(-1) / (t1^2 - 1), t1^2 / (t1^2 - t2^2), t1^3 / (t1^3 - t3), t1 / (t1 - t2),
(-1) / (t1 - 1), t1^3 / (t1^3 - t2^2), t2 / (t2 - t3), (-1) / (t1^2 - 1),
(-t2) / (t1^4 - t2), (-1) / (t2 - 1), (t1 * t2) / (t1 * t2 - t3),
(-1) / (t1 - 1), (-t2) / (t1^3 - t2), t1 / (t1 - t2), -u + 1, -t1 * u + 1,
-t1^2 * u + 1, -t1^3 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1, -v + 1, (t1 - v) / t1,
(t1^2 - v) / t1^2, (t1^3 - v) / t1^3, (t2 - v) / t2, (t1 * t2 - v) / (t1 * t2)},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t2 - 1), (-1) / (t1^3 - 1),
t1^2 / (t1^2 - t3), t1 / (t1 - t2), (-1) / (t1^2 - 1), t1^3 / (t1^3 - t3),
t1^2 / (t1^2 - t2), (-1) / (t1 - 1), t1^3 / (t1^3 - t2^3), t2 / (t2 - t3),
(-1) / (t1 - 1), (-1) / (t2^2 - 1), t2^2 / (t2^2 - t3), (-t2) / (t1 - t2),
(-t2^2) / (t1^4 - t2^2), (-1) / (t2 - 1), -u + 1, -t1 * u + 1,
-t1^2 * u + 1, -t1^3 * u + 1, -t2 * u + 1, -t2^2 * u + 1, -v + 1, (t1 - v) / t1,
(t1^2 - v) / t1^2, (t1^3 - v) / t1^3, (t2 - v) / t2, (t2^2 - v) / t2^2},
{(-1) / (t3 - 1), (-1) / (t1^3 - 1), (-1) / (t2^2 - 1), t1 / (t1 - t3), (-1) / (t1^2 - 1),
(-t1) / (t2^2 - t1), t1^2 / (t1^2 - t3), (-1) / (t1 - 1), t1^2 / (t1^2 - t2^2),
t2 / (t2 - t3), (-t2) / (t1^3 - t2), (-1) / (t2 - 1), (t1 * t2) / (t1 * t2 - t3),
(-t2) / (t1^2 - t2), t1 / (t1 - t2), (t1^2 * t2) / (t1^2 * t2 - t3),
(-t2) / (t1 - t2), t1^2 / (t1^2 - t2), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t2 * u + 1,
-t1 * t2 * u + 1, -t1^2 * t2 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t2 - v) / t2, (t1 * t2 - v) / (t1 * t2), (t1^2 * t2 - v) / (t1^2 * t2)},
{(-1) / (t3 - 1), t1 / (t1 - t3), t1^2 / (t1^2 - t3), (-1) / (t1 - 1),
(-1) / (t2 - 1), (-t1) / (t2^2 - t1), (-t1^2) / (t2^3 - t1^2), t2 / (t2 - t3),
(t1 * t2) / (t1 * t2 - t3), (-t2) / (t1^2 - t2), (-1) / (t1 - 1), (-1) / (t2 - 1),
(-t1) / (t2^2 - t1), t2^2 / (t2^2 - t3), (-t2^2) / (t1^3 - t2^2),
(-t2) / (t1^2 - t2), (-1) / (t1 - 1), (-1) / (t2 - 1), -u + 1, -t1 * u + 1,
-t1^2 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1, -t2^2 * u + 1, -v + 1, (t1 - v) / t1,
(t1^2 - v) / t1^2, (t2 - v) / t2, (t1 * t2 - v) / (t1 * t2), (t2^2 - v) / t2^2},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t2 - 1), (-1) / (t1^2 - 1),
t1^2 / (t1^2 - t3), t1 / (t1 - t2), (-1) / (t1 - 1), (-t1^2) / (t2^4 - t1^2),
t2 / (t2 - t3), (-1) / (t1 - 1), (-1) / (t2^3 - 1), t2^2 / (t2^2 - t3),
(-t2) / (t1 - t2), (-1) / (t2^2 - 1), t2^3 / (t2^3 - t3), t2^2 / (t2^2 - t1),
(-t2^3) / (t1^3 - t2^3), (-1) / (t2 - 1), -u + 1, -t1 * u + 1,
-t1^2 * u + 1, -t2 * u + 1, -t2^2 * u + 1, -t2^3 * u + 1, -v + 1, (t1 - v) / t1,
(t1^2 - v) / t1^2, (t2 - v) / t2, (t2^2 - v) / t2^2, (t2^3 - v) / t2^3},
{(-1) / (t3 - 1), (-1) / (t1^2 - 1), (-1) / (t2^3 - 1), t1 / (t1 - t3), (-1) / (t1 - 1),
(-t1) / (t2^3 - t1), t2 / (t2 - t3), (-t2) / (t1^2 - t2), (-1) / (t2^2 - 1),
(t1 * t2) / (t1 * t2 - t3), (-t2) / (t1 - t2), (-t1) / (t2^2 - t1), t2^2 / (t2^2 - t3),
(-t2^2) / (t1^2 - t2^2), (-1) / (t2 - 1), (t1 * t2^2) / (t1 * t2^2 - t3),
t2^2 / (t2^2 - t1), t1 / (t1 - t2), -u + 1, -t1 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1,
-t2^2 * u + 1, -t1 * t2^2 * u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2,

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(t1 * t2 - v) / (t1 * t2), (t2^2 - v) / t2^2, (t1 * t2^2 - v) / (t1 * t2^2)},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t1 - 1), (-1) / (t2^2 - 1),
(-t1) / (t2^4 - t1), t2 / (t2 - t3), (t1 * t2) / (t1 * t2 - t3),
(-t2) / (t1 - t2), (-1) / (t2 - 1), (-t1) / (t2^3 - t1), t2^2 / (t2^2 - t3),
(-t2^2) / (t1^2 - t2^2), (-1) / (t1 - 1), (-1) / (t2^2 - 1), t2^3 / (t2^3 - t3),
t2^3 / (t2^3 - t1^2), (-t2) / (t1 - t2), (-1) / (t2 - 1), -u + 1, -t1 * u + 1,
-t2 * u + 1, -t1 * t2 * u + 1, -t2^2 * u + 1, -t2^3 * u + 1, -v + 1, (t1 - v) / t1,
(t2 - v) / t2, (t1 * t2 - v) / (t1 * t2), (t2^2 - v) / t2^2, (t2^3 - v) / t2^3},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t1 - 1), (-1) / (t2 - 1),
(-t1) / (t2^5 - t1), t2 / (t2 - t3), (-1) / (t1 - 1), (-1) / (t2^4 - 1),
t2^2 / (t2^2 - t3), (-t2) / (t1 - t2), (-1) / (t2^3 - 1), t2^3 / (t2^3 - t3),
t2^2 / (t2^2 - t1), (-1) / (t2^2 - 1), t2^4 / (t2^4 - t3), t2^4 / (t2^4 - t1^2),
t2^3 / (t2^3 - t1), (-1) / (t2 - 1), -u + 1, -t1 * u + 1, -t2 * u + 1,
-t2^2 * u + 1, -t2^3 * u + 1, -t2^4 * u + 1, -v + 1, (t1 - v) / t1,
(t2 - v) / t2, (t2^2 - v) / t2^2, (t2^3 - v) / t2^3, (t2^4 - v) / t2^4},
{(-1) / (t1 - 1), (-1) / (t3 - 1), (-1) / (t2^6 - 1), (-t2) / (t1 - t2),
t2 / (t2 - t3), (-1) / (t2^5 - 1), t2^2 / (t2^2 - t1), t2^2 / (t2^2 - t3),
(-1) / (t2^4 - 1), t2^3 / (t2^3 - t1), t2^3 / (t2^3 - t3), (-1) / (t2^3 - 1),
t2^4 / (t2^4 - t1), t2^4 / (t2^4 - t3), (-1) / (t2^2 - 1), t2^5 / (t2^5 - t1),
t2^5 / (t2^5 - t3), (-1) / (t2 - 1), -u + 1, -t2 * u + 1, -t2^2 * u + 1,
-t2^3 * u + 1, -t2^4 * u + 1, -t2^5 * u + 1, -v + 1, (t2 - v) / t2,
(t2^2 - v) / t2^2, (t2^3 - v) / t2^3, (t2^4 - v) / t2^4, (t2^5 - v) / t2^5},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t3 - 1), (-1) / (t1^4 - 1),
t1^2 / (t1^2 - t2), t1 / (t1 - t3), (-1) / (t1^3 - 1), t1^3 / (t1^3 - t2),
t1^2 / (t1^2 - t3), (-1) / (t1^2 - 1), t1^4 / (t1^4 - t2), t1^3 / (t1^3 - t3),
(-1) / (t1 - 1), t1^4 / (t1^4 - t3^2), (-t3) / (t2 - t3), (-1) / (t1 - 1),
(-t3) / (t1^5 - t3), (-1) / (t3 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1,
-t1^3 * u + 1, -t1^4 * u + 1, -t3 * u + 1, -v + 1, (t1 - v) / t1,
(t1^2 - v) / t1^2, (t1^3 - v) / t1^3, (t1^4 - v) / t1^4, (t3 - v) / t3},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t3 - 1), (-1) / (t2^4 - 1),
t2^2 / (t2^2 - t1), t2 / (t2 - t3), (-1) / (t2^3 - 1), t2^3 / (t2^3 - t1),
t2^2 / (t2^2 - t3), (-1) / (t2^2 - 1), t2^4 / (t2^4 - t1), t2^3 / (t2^3 - t3),
(-1) / (t2 - 1), t2^4 / (t2^4 - t3^2), (-t3) / (t1 - t3), (-1) / (t2 - 1),
(-t3) / (t2^5 - t3), (-1) / (t3 - 1), -u + 1, -t2 * u + 1, -t2^2 * u + 1,
-t2^3 * u + 1, -t2^4 * u + 1, -t3 * u + 1, -v + 1, (t2 - v) / t2,
(t2^2 - v) / t2^2, (t2^3 - v) / t2^3, (t2^4 - v) / t2^4, (t3 - v) / t3},
{(-1) / (t2 - 1), t1 / (t1 - t2), t1^2 / (t1^2 - t2), (-1) / (t3 - 1),
(-1) / (t1^2 - 1), t1^2 / (t1^2 - t3^2), t1^3 / (t1^3 - t2), t1 / (t1 - t3),
(-1) / (t1 - 1), t1^3 / (t1^3 - t3^2), (-t3) / (t2 - t3), (-1) / (t1^2 - 1),
(-t3) / (t1^4 - t3), (-1) / (t3 - 1), (t1 * t3) / (t1 * t3 - t2),
(-1) / (t1 - 1), (-t3) / (t1^3 - t3), t1 / (t1 - t3), -u + 1, -t1 * u + 1,
-t1^2 * u + 1, -t1^3 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1, -v + 1, (t1 - v) / t1,
(t1^2 - v) / t1^2, (t1^3 - v) / t1^3, (t3 - v) / t3, (t1 * t3 - v) / (t1 * t3)},
{(-1) / (t2 - 1), (-1) / (t3 - 1), (-1) / (t1^2 - 1), t1 / (t1 - t2), t1 / (t1 - t3),
(-1) / (t1 - 1), t1^2 / (t1^2 - t2^2), t1^2 / (t1^2 - t3^2), (-1) / (t1 - 1),
(-1) / (t2 - 1), (-t2) / (t3^2 - t2), (-t3) / (t2^2 - t3), (-1) / (t3 - 1),
(-t3) / (t1 - t3), (-t2) / (t1 - t2), (-t2 * t3) / (t1^3 - t2 * t3),

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(-t3) / (t2 - t3), t2 / (t2 - t3), -u + 1, -t1 * u + 1, -t1^2 * u + 1,
-t2 * u + 1, -t3 * u + 1, -t2 * t3 * u + 1, -v + 1, (t1 - v) / t1,
(t1^2 - v) / t1^2, (t2 - v) / t2, (t3 - v) / t3, (t2 * t3 - v) / (t2 * t3)},
{(-1) / (t2^2 - 1), (-1) / (t1 - 1), (-1) / (t3 - 1), (-t1) / (t2^2 - t1),
(-t1) / (t3^2 - t1), (-1) / (t2 - 1), (-t2) / (t1 - t2), t2 / (t2 - t3),
t1 / (t1 - t2), (t1 * t2) / (t1 * t2 - t3^2), (-t3) / (t1^2 - t3), (-1) / (t1 - 1),
(-t3) / (t2^2 - t3), (-1) / (t3 - 1), (-t2 * t3) / (t1^2 - t2 * t3),
(-t2) / (t1 - t2), (-t3) / (t2 - t3), t2 / (t2 - t3), -u + 1, -t1 * u + 1,
-t2 * u + 1, -t1 * t2 * u + 1, -t3 * u + 1, -t2 * t3 * u + 1, -v + 1, (t1 - v) / t1,
(t2 - v) / t2, (t1 * t2 - v) / (t1 * t2), (t3 - v) / t3, (t2 * t3 - v) / (t2 * t3)},
{(-1) / (t1^2 - 1), (-1) / (t1 - 1), (-t2) / (t1^2 - t2), (-1) / (t2 - 1),
(-1) / (t3 - 1), (-t2) / (t3^2 - t2), (-t2) / (t1 - t2), t1 / (t1 - t2),
t1 / (t1 - t3), (t1 * t2) / (t1 * t2 - t3^2), (-t3) / (t1^2 - t3),
(-t3) / (t2^2 - t3), (-1) / (t2 - 1), (-1) / (t3 - 1), (-t3) / (t1 - t3),
(-t1 * t3) / (t2^2 - t1 * t3), t1 / (t1 - t2), t1 / (t1 - t3), -u + 1, -t1 * u + 1,
-t2 * u + 1, -t1 * t2 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1, -v + 1, (t1 - v) / t1,
(t2 - v) / t2, (t1 * t2 - v) / (t1 * t2), (t3 - v) / t3, (t1 * t3 - v) / (t1 * t3)},
{(-1) / (t1 - 1), (-1) / (t2 - 1), (-t1) / (t3^2 - t1), (-1) / (t1 - 1),
(-1) / (t3 - 1), (-1) / (t2^2 - 1), (-t2^2) / (t1^2 - t2^2),
(-t2) / (t1 - t2), t2 / (t2 - t3), (-1) / (t2 - 1), t2^2 / (t2^2 - t3^2),
(-t3) / (t1^2 - t3), (-1) / (t3 - 1), (-t3) / (t1 - t3), (-t3) / (t2 - t3),
t1 / (t1 - t2), (-t1 * t3) / (t2^3 - t1 * t3), t1 / (t1 - t3), -u + 1, -t1 * u + 1,
-t2 * u + 1, -t2^2 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1, -v + 1, (t1 - v) / t1,
(t2 - v) / t2, (t2^2 - v) / t2^2, (t3 - v) / t3, (t1 * t3 - v) / (t1 * t3)},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), t2^2 / (t2^2 - t1), (-1) / (t3 - 1),
(-1) / (t2^2 - 1), t2^2 / (t2^2 - t3^2), t2^3 / (t2^3 - t1), t2 / (t2 - t3),
(-1) / (t2 - 1), t2^3 / (t2^3 - t3^2), (-t3) / (t1 - t3), (-1) / (t2^2 - 1),
(-t3) / (t2^4 - t3), (-1) / (t3 - 1), (t2 * t3) / (t2 * t3 - t1),
(-1) / (t2 - 1), (-t3) / (t2^3 - t3), t2 / (t2 - t3), -u + 1, -t2 * u + 1,
-t2^2 * u + 1, -t2^3 * u + 1, -t3 * u + 1, -t2 * t3 * u + 1, -v + 1, (t2 - v) / t2,
(t2^2 - v) / t2^2, (t2^3 - v) / t2^3, (t3 - v) / t3, (t2 * t3 - v) / (t2 * t3)},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t3 - 1), (-1) / (t1^3 - 1),
t1^2 / (t1^2 - t2), t1 / (t1 - t3), (-1) / (t1^2 - 1), t1^3 / (t1^3 - t2),
t1^2 / (t1^2 - t3), (-1) / (t1 - 1), t1^3 / (t1^3 - t3^3), (-t3) / (t2 - t3),
(-1) / (t1 - 1), (-1) / (t3^2 - 1), t3^2 / (t3^2 - t2), (-t3) / (t1 - t3),
(-t3^2) / (t1^4 - t3^2), (-1) / (t3 - 1), -u + 1, -t1 * u + 1,
-t1^2 * u + 1, -t1^3 * u + 1, -t3 * u + 1, -t3^2 * u + 1, -v + 1, (t1 - v) / t1,
(t1^2 - v) / t1^2, (t1^3 - v) / t1^3, (t3 - v) / t3, (t3^2 - v) / t3^2},
{(-1) / (t1 - 1), (-1) / (t3 - 1), (-t1) / (t2^2 - t1), (-t2) / (t1^2 - t2),
(-1) / (t2 - 1), (-t2) / (t1 - t2), t2 / (t2 - t3), t1 / (t1 - t2),
t1 / (t1 - t3), (-t1 * t2) / (t3^3 - t1 * t2), (-1) / (t1 - 1), (-1) / (t2 - 1),
(-1) / (t3^2 - 1), (-t3^2) / (t1^2 - t3^2), (-t3) / (t1 - t3),
(-t3^2) / (t2^2 - t3^2), (-t3) / (t2 - t3), (-1) / (t3 - 1), -u + 1, -t1 * u + 1,
-t2 * u + 1, -t1 * t2 * u + 1, -t3 * u + 1, -t3^2 * u + 1, -v + 1, (t1 - v) / t1,
(t2 - v) / t2, (t1 * t2 - v) / (t1 * t2), (t3 - v) / t3, (t3^2 - v) / t3^2},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t3 - 1), (-1) / (t2^3 - 1),
t2^2 / (t2^2 - t1), t2 / (t2 - t3), (-1) / (t2^2 - 1), t2^3 / (t2^3 - t1),

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t2^2 / (t2^2 - t3), (-1) / (t2 - 1), t2^3 / (t2^3 - t3^3), (-t3) / (t1 - t3),
(-1) / (t2 - 1), (-1) / (t3^2 - 1), t3^2 / (t3^2 - t1), (-t3) / (t2 - t3),
(-t3^2) / (t2^4 - t3^2), (-1) / (t3 - 1), -u + 1, -t2 * u + 1,
-t2^2 * u + 1, -t2^3 * u + 1, -t3 * u + 1, -t3^2 * u + 1, -v + 1, (t2 - v) / t2,
(t2^2 - v) / t2^2, (t2^3 - v) / t2^3, (t3 - v) / t3, (t3^2 - v) / t3^2},
{(-1) / (t2 - 1), (-1) / (t1^3 - 1), (-1) / (t3^2 - 1), t1 / (t1 - t2), (-1) / (t1^2 - 1),
(-t1) / (t3^2 - t1), t1^2 / (t1^2 - t2), (-1) / (t1 - 1), t1^2 / (t1^2 - t3^2),
(-t3) / (t2 - t3), (-t3) / (t1^3 - t3), (-1) / (t3 - 1), (t1 * t3) / (t1 * t3 - t2),
(-t3) / (t1^2 - t3), t1 / (t1 - t3), (t1^2 * t3) / (t1^2 * t3 - t2),
(-t3) / (t1 - t3), t1^2 / (t1^2 - t3), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t3 * u + 1,
-t1 * t3 * u + 1, -t1^2 * t3 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t3 - v) / t3, (t1 * t3 - v) / (t1 * t3), (t1^2 * t3 - v) / (t1^2 * t3)},
{(-1) / (t3^2 - 1), (-1) / (t1 - 1), (-1) / (t2 - 1), (-t1) / (t2^2 - t1),
(-t1) / (t3^2 - t1), (-t2) / (t1^2 - t2), (-1) / (t1 - 1), (-1) / (t2 - 1),
(-t2) / (t3^2 - t2), (-1) / (t3 - 1), (-t3) / (t1 - t3), (-t3) / (t2 - t3),
(-t1 * t3) / (t2^2 - t1 * t3), t1 / (t1 - t3), (-t2 * t3) / (t1^2 - t2 * t3),
(-t3) / (t1 - t3), (-t3) / (t2 - t3), t2 / (t2 - t3), -u + 1, -t1 * u + 1,
-t2 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1, -t2 * t3 * u + 1, -v + 1, (t1 - v) / t1,
(t2 - v) / t2, (t3 - v) / t3, (t1 * t3 - v) / (t1 * t3), (t2 * t3 - v) / (t2 * t3)},
{(-1) / (t1 - 1), (-1) / (t2^3 - 1), (-1) / (t3^2 - 1), (-t2) / (t1 - t2),
(-1) / (t2^2 - 1), (-t2) / (t3^2 - t2), t2^2 / (t2^2 - t1), (-1) / (t2 - 1),
t2^2 / (t2^2 - t3^2), (-t3) / (t1 - t3), (-t3) / (t2^3 - t3),
(-1) / (t3 - 1), (t2 * t3) / (t2 * t3 - t1), (-t3) / (t2^2 - t3),
t2 / (t2 - t3), (t2^2 * t3) / (t2^2 * t3 - t1), (-t3) / (t2 - t3),
t2^2 / (t2^2 - t3), -u + 1, -t2 * u + 1, -t2^2 * u + 1, -t3 * u + 1,
-t2 * t3 * u + 1, -t2^2 * t3 * u + 1, -v + 1, (t2 - v) / t2, (t2^2 - v) / t2^2,
(t3 - v) / t3, (t2 * t3 - v) / (t2 * t3), (t2^2 * t3 - v) / (t2^2 * t3)},
{(-1) / (t2 - 1), t1 / (t1 - t2), t1^2 / (t1^2 - t2), (-1) / (t1 - 1),
(-1) / (t3 - 1), (-t1) / (t3^2 - t1), (-t1^2) / (t3^3 - t1^2), (-t3) / (t2 - t3),
(t1 * t3) / (t1 * t3 - t2), (-t3) / (t1^2 - t3), (-1) / (t1 - 1), (-1) / (t3 - 1),
(-t1) / (t3^2 - t1), t3^2 / (t3^2 - t2), (-t3^2) / (t1^3 - t3^2),
(-t3) / (t1^2 - t3), (-1) / (t1 - 1), (-1) / (t3 - 1), -u + 1, -t1 * u + 1,
-t1^2 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1, -t3^2 * u + 1, -v + 1, (t1 - v) / t1,
(t1^2 - v) / t1^2, (t3 - v) / t3, (t1 * t3 - v) / (t1 * t3), (t3^2 - v) / t3^2},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), t2^2 / (t2^2 - t1), (-1) / (t2 - 1),
(-1) / (t3 - 1), (-t2) / (t3^2 - t2), (-t2^2) / (t3^3 - t2^2), (-t3) / (t1 - t3),
(t2 * t3) / (t2 * t3 - t1), (-t3) / (t2^2 - t3), (-1) / (t2 - 1), (-1) / (t3 - 1),
(-t2) / (t3^2 - t2), t3^2 / (t3^2 - t1), (-t3^2) / (t2^3 - t3^2),
(-t3) / (t2^2 - t3), (-1) / (t2 - 1), (-1) / (t3 - 1), -u + 1, -t2 * u + 1,
-t2^2 * u + 1, -t3 * u + 1, -t2 * t3 * u + 1, -t3^2 * u + 1, -v + 1, (t2 - v) / t2,
(t2^2 - v) / t2^2, (t3 - v) / t3, (t2 * t3 - v) / (t2 * t3), (t3^2 - v) / t3^2},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t3 - 1), (-1) / (t1^2 - 1),
t1^2 / (t1^2 - t2), t1 / (t1 - t3), (-1) / (t1 - 1), (-t1^2) / (t3^4 - t1^2),
(-t3) / (t2 - t3), (-1) / (t1 - 1), (-1) / (t3^3 - 1), t3^2 / (t3^2 - t2),
(-t3) / (t1 - t3), (-1) / (t3^2 - 1), t3^3 / (t3^3 - t2), t3^2 / (t3^2 - t1),
(-t3^3) / (t1^3 - t3^3), (-1) / (t3 - 1), -u + 1, -t1 * u + 1,
-t1^2 * u + 1, -t3 * u + 1, -t3^2 * u + 1, -t3^3 * u + 1, -v + 1, (t1 - v) / t1,

```



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(t1^2 - v) / t1^2, (t3 - v) / t3, (t3^2 - v) / t3^2, (t3^3 - v) / t3^3},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t3 - 1), (-1) / (t2^2 - 1),
t2^2 / (t2^2 - t1), t2 / (t2 - t3), (-1) / (t2 - 1), (-t2^2) / (t3^4 - t2^2),
(-t3) / (t1 - t3), (-1) / (t2 - 1), (-1) / (t3^3 - 1), t3^2 / (t3^2 - t1),
(-t3) / (t2 - t3), (-1) / (t3^2 - 1), t3^3 / (t3^3 - t1), t3^2 / (t3^2 - t2),
(-t3^3) / (t2^3 - t3^3), (-1) / (t3 - 1), -u + 1, -t2 * u + 1,
-t2^2 * u + 1, -t3 * u + 1, -t3^2 * u + 1, -t3^3 * u + 1, -v + 1, (t2 - v) / t2,
(t2^2 - v) / t2^2, (t3 - v) / t3, (t3^2 - v) / t3^2, (t3^3 - v) / t3^3},
{(-1) / (t2 - 1), (-1) / (t1^2 - 1), (-1) / (t3^3 - 1), t1 / (t1 - t2), (-1) / (t1 - 1),
(-t1) / (t3^3 - t1), (-t3) / (t2 - t3), (-t3) / (t1^2 - t3), (-1) / (t3^2 - 1),
(t1 * t3) / (t1 * t3 - t2), (-t3) / (t1 - t3), (-t1) / (t3^2 - t1), t3^2 / (t3^2 - t2),
(-t3^2) / (t1^2 - t3^2), (-1) / (t3 - 1), (t1 * t3^2) / (t1 * t3^2 - t2),
t3^2 / (t3^2 - t1), t1 / (t1 - t3), -u + 1, -t1 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1,
-t3^2 * u + 1, -t1 * t3^2 * u + 1, -v + 1, (t1 - v) / t1, (t3 - v) / t3,
(t1 * t3 - v) / (t1 * t3), (t3^2 - v) / t3^2, (t1 * t3^2 - v) / (t1 * t3^2)},
{(-1) / (t1 - 1), (-1) / (t2^2 - 1), (-1) / (t3^3 - 1), (-t2) / (t1 - t2),
(-1) / (t2 - 1), (-t2) / (t3^3 - t2), (-t3) / (t1 - t3), (-t3) / (t2^2 - t3),
(-1) / (t3^2 - 1), (t2 * t3) / (t2 * t3 - t1), (-t3) / (t2 - t3),
(-t2) / (t3^2 - t2), t3^2 / (t3^2 - t1), (-t3^2) / (t2^2 - t3^2),
(-1) / (t3 - 1), (t2 * t3^2) / (t2 * t3^2 - t1), t3^2 / (t3^2 - t2),
t2 / (t2 - t3), -u + 1, -t2 * u + 1, -t3 * u + 1, -t2 * t3 * u + 1,
-t3^2 * u + 1, -t2 * t3^2 * u + 1, -v + 1, (t2 - v) / t2, (t3 - v) / t3,
(t2 * t3 - v) / (t2 * t3), (t3^2 - v) / t3^2, (t2 * t3^2 - v) / (t2 * t3^2)},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t1 - 1), (-1) / (t3^2 - 1),
(-t1) / (t3^4 - t1), (-t3) / (t2 - t3), (t1 * t3) / (t1 * t3 - t2),
(-t3) / (t1 - t3), (-1) / (t3 - 1), (-t1) / (t3^3 - t1), t3^2 / (t3^2 - t2),
(-t3^2) / (t1^2 - t3^2), (-1) / (t1 - 1), (-1) / (t3^2 - 1), t3^3 / (t3^3 - t2),
t3^3 / (t3^3 - t1^2), (-t3) / (t1 - t3), (-1) / (t3 - 1), -u + 1, -t1 * u + 1,
-t3 * u + 1, -t1 * t3 * u + 1, -t3^2 * u + 1, -t3^3 * u + 1, -v + 1, (t1 - v) / t1,
(t3 - v) / t3, (t1 * t3 - v) / (t1 * t3), (t3^2 - v) / t3^2, (t3^3 - v) / t3^3},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t2 - 1), (-1) / (t3^2 - 1),
(-t2) / (t3^4 - t2), (-t3) / (t1 - t3), (t2 * t3) / (t2 * t3 - t1),
(-t3) / (t2 - t3), (-1) / (t3 - 1), (-t2) / (t3^3 - t2), t3^2 / (t3^2 - t1),
(-t3^2) / (t2^2 - t3^2), (-1) / (t2 - 1), (-1) / (t3^2 - 1), t3^3 / (t3^3 - t1),
t3^3 / (t3^3 - t2^2), (-t3) / (t2 - t3), (-1) / (t3 - 1), -u + 1, -t2 * u + 1,
-t3 * u + 1, -t2 * t3 * u + 1, -t3^2 * u + 1, -t3^3 * u + 1, -v + 1, (t2 - v) / t2,
(t3 - v) / t3, (t2 * t3 - v) / (t2 * t3), (t3^2 - v) / t3^2, (t3^3 - v) / t3^3},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t1 - 1), (-1) / (t3 - 1),
(-t1) / (t3^5 - t1), (-t3) / (t2 - t3), (-1) / (t1 - 1), (-1) / (t3^4 - 1),
t3^2 / (t3^2 - t2), (-t3) / (t1 - t3), (-1) / (t3^3 - 1), t3^3 / (t3^3 - t2),
t3^2 / (t3^2 - t1), (-1) / (t3^2 - 1), t3^4 / (t3^4 - t2), t3^4 / (t3^4 - t1^2),
t3^3 / (t3^3 - t1), (-1) / (t3 - 1), -u + 1, -t1 * u + 1, -t3 * u + 1,
-t3^2 * u + 1, -t3^3 * u + 1, -t3^4 * u + 1, -v + 1, (t1 - v) / t1,
(t3 - v) / t3, (t3^2 - v) / t3^2, (t3^3 - v) / t3^3, (t3^4 - v) / t3^4},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t2 - 1), (-1) / (t3 - 1),
(-t2) / (t3^5 - t2), (-t3) / (t1 - t3), (-1) / (t2 - 1), (-1) / (t3^4 - 1),
t3^2 / (t3^2 - t1), (-t3) / (t2 - t3), (-1) / (t3^3 - 1), t3^3 / (t3^3 - t1),

```

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t3^2 / (t3^2 - t2), (-1) / (t3^2 - 1), t3^4 / (t3^4 - t1), t3^4 / (t3^4 - t2^2),
t3^3 / (t3^3 - t2), (-1) / (t3 - 1), -u + 1, -t2 * u + 1, -t3 * u + 1,
-t3^2 * u + 1, -t3^3 * u + 1, -t3^4 * u + 1, -v + 1, (t2 - v) / t2,
(t3 - v) / t3, (t3^2 - v) / t3^2, (t3^3 - v) / t3^3, (t3^4 - v) / t3^4},
{(-1) / (t1 - 1), (-1) / (t2 - 1), (-1) / (t3^6 - 1), (-t3) / (t1 - t3),
(-t3) / (t2 - t3), (-1) / (t3^5 - 1), t3^2 / (t3^2 - t1), t3^2 / (t3^2 - t2),
(-1) / (t3^4 - 1), t3^3 / (t3^3 - t1), t3^3 / (t3^3 - t2), (-1) / (t3^3 - 1),
t3^4 / (t3^4 - t1), t3^4 / (t3^4 - t2), (-1) / (t3^2 - 1), t3^5 / (t3^5 - t1),
t3^5 / (t3^5 - t2), (-1) / (t3 - 1), -u + 1, -t3 * u + 1, -t3^2 * u + 1,
-t3^3 * u + 1, -t3^4 * u + 1, -t3^5 * u + 1, -v + 1, (t3 - v) / t3,
(t3^2 - v) / t3^2, (t3^3 - v) / t3^3, (t3^4 - v) / t3^4, (t3^5 - v) / t3^5}

```

```
In[208]:= Length[GT6smoothPointsContributions[t1, t2, t3, u, v]]
```

```
Out[208]= 36
```

```
In[182]:= G6smooth[t1_, t2_, t3_] :=
  Sum[1 / Det[DiagonalMatrix[G6smoothTangentContributions[t1, t2, t3][[i]]]],
    {i, 1, 36}]
```

```
In[209]:= GT6smooth[t1_, t2_, t3_, u_, v_] :=
  Sum[Det[DiagonalMatrix[GT6smoothPointsContributions[t1, t2, t3, u, v][[i]]]],
    {i, 1, 36}]
```

```
In[211]:= Together[GT6smooth[t1, t2, t3, u, v] + GT61[t1, t2, t3, u, v] + GT61[t2, t3, t1, u, v] +
  GT61[t3, t1, t2, u, v] + GT62[t1, t2, t3, u, v] + GT62[t2, t3, t1, u, v] +
  GT62[t3, t1, t2, u, v] + GT62[t1, t3, t2, u, v] + GT62[t3, t2, t1, u, v] +
  GT62[t2, t1, t3, u, v] + GT63[t1, t2, t3, u, v] + GT63[t2, t3, t1, u, v] +
  GT63[t3, t1, t2, u, v] - SeriesCoefficient[Exp[Sum[Q^n * (1 - u^n) *
    (1 - v^n) / (n * (1 - t1^n) * (1 - t2^n) * (1 - t3^n)), {n, 1, 6}]], {Q, 0, 6}]]
```

```
Out[211]= 0
```

```
In[213]:= Solve[u1 * u2 == t1^4 && u0 * u3 == t2^2 / t1^4 &&
  u3 * u4 == t2 * t3 / t1^4 && u0 * u4 == t3^2 / t1^4 && u4 * u5 == t1 * t3 / t2 &&
  u1 * u5 == t1^5 / t2 && u0 * u2 == t2 && u2 * u4 == t3 && u1 * u4 == t3^2 / t2 &&
  u3 * u5 == t1 * t2 / t3 && u0 * u5 == t1 && u2 * u5 == t1^5 / t3 &&
  u2 * u3 == t2^2 / t3 && u1 * u3 == t2 && u0 * u1 == t3, {u0, u1, u2, u3, u4, u5}]
```

```
Out[213]= {{u0 -> - (sqrt(t2) sqrt(t3) / t1^2), u1 -> - (t1^2 sqrt(t3) / sqrt(t2)), u2 -> - (t1^2 sqrt(t2) / sqrt(t3)), u3 -> - (t2^(3/2) / (t1^2 sqrt(t3)),
  u4 -> - (t3^(3/2) / (t1^2 sqrt(t2)), u5 -> - (t1^3 / (sqrt(t2) sqrt(t3))), {u0 -> sqrt(t2) sqrt(t3) / t1^2, u1 -> t1^2 sqrt(t3) / sqrt(t2),
  u2 -> t1^2 sqrt(t2) / sqrt(t3), u3 -> t2^(3/2) / (t1^2 sqrt(t3)), u4 -> t3^(3/2) / (t1^2 sqrt(t2)), u5 -> t1^3 / (sqrt(t2) sqrt(t3))}}
```

$$\text{In}[214]:= \text{Together}\left[G\left[\frac{\sqrt{t_2} \sqrt{t_3}}{t_1^2}, \frac{t_1^2 \sqrt{t_3}}{\sqrt{t_2}}, \frac{t_1^2 \sqrt{t_2}}{\sqrt{t_3}}, \frac{t_2^{3/2}}{t_1^2 \sqrt{t_3}}, \frac{t_3^{3/2}}{t_1^2 \sqrt{t_2}}, \frac{t_1^3}{\sqrt{t_2} \sqrt{t_3}}\right]\right]$$

$$\begin{aligned} \text{Out}[214]= & \frac{1}{t_1^4 t_2 t_3} \\ & (-t_1^9 t_2^2 + t_1^{10} t_2^2 - t_1^5 t_2^3 + t_1^9 t_2^3 + t_1^5 t_2^4 - t_1^{10} t_2^4 + t_1^4 t_2 t_3 - t_1^9 t_2 t_3 + t_1^{10} t_2 t_3 - \\ & t_1^{11} t_2 t_3 - 2 t_1^5 t_2^2 t_3 + t_1^6 t_2^2 t_3 + 2 t_1^9 t_2^2 t_3 - t_1^{10} t_2^2 t_3 - t_1^4 t_2^3 t_3 + 3 t_1^5 t_2^3 t_3 - \\ & t_1^6 t_2^3 t_3 - t_1^9 t_2^3 t_3 - t_1^{10} t_2^3 t_3 + t_1^{11} t_2^3 t_3 + t_1 t_2^4 t_3 - t_1^5 t_2^4 t_3 - t_1^6 t_2^4 t_3 + \\ & t_1^{10} t_2^4 t_3 - t_1 t_2^5 t_3 + t_1^6 t_2^5 t_3 - t_1^9 t_3^2 + t_1^{10} t_3^2 - 2 t_1^5 t_2 t_3^2 + t_1^6 t_2 t_3^2 + \\ & 2 t_1^9 t_2 t_3^2 - t_1^{10} t_2 t_3^2 - t_1 t_2^2 t_3^2 - t_1^4 t_2^2 t_3^2 + 5 t_1^5 t_2^2 t_3^2 - t_1^6 t_2^2 t_3^2 - \\ & t_1^9 t_2^2 t_3^2 - 2 t_1^{10} t_2^2 t_3^2 + t_1^{11} t_2^2 t_3^2 - t_2^3 t_3^2 + 2 t_1 t_2^3 t_3^2 + t_1^4 t_2^3 t_3^2 - \\ & 2 t_1^5 t_2^3 t_3^2 - 2 t_1^6 t_2^3 t_3^2 + t_1^7 t_2^3 t_3^2 + 2 t_1^{10} t_2^3 t_3^2 - t_1^{11} t_2^3 t_3^2 + t_2^4 t_3^2 - \\ & t_1 t_2^4 t_3^2 - t_1^2 t_2^4 t_3^2 - t_1^5 t_2^4 t_3^2 + 3 t_1^6 t_2^4 t_3^2 - t_1^7 t_2^4 t_3^2 + t_1^2 t_2^5 t_3^2 - \\ & t_1^6 t_2^5 t_3^2 - t_1^5 t_3^3 + t_1^9 t_3^3 - t_1^4 t_2 t_3^3 + 3 t_1^5 t_2 t_3^3 - t_1^6 t_2 t_3^3 - t_1^9 t_2 t_3^3 - \\ & t_1^{10} t_2 t_3^3 + t_1^{11} t_2 t_3^3 - t_2^2 t_3^3 + 2 t_1 t_2^2 t_3^3 + t_1^4 t_2^2 t_3^3 - 2 t_1^5 t_2^2 t_3^3 - \\ & 2 t_1^6 t_2^2 t_3^3 + t_1^7 t_2^2 t_3^3 + 2 t_1^{10} t_2^2 t_3^3 - t_1^{11} t_2^2 t_3^3 + t_2^3 t_3^3 - 2 t_1 t_2^3 t_3^3 - \\ & t_1^2 t_2^3 t_3^3 - t_1^5 t_2^3 t_3^3 + 5 t_1^6 t_2^3 t_3^3 - t_1^7 t_2^3 t_3^3 - t_1^{10} t_2^3 t_3^3 - t_1 t_2^4 t_3^3 + \\ & 2 t_1^2 t_2^4 t_3^3 + t_1^5 t_2^4 t_3^3 - 2 t_1^6 t_2^4 t_3^3 + t_1 t_2^5 t_3^3 - t_1^2 t_2^5 t_3^3 + t_1^5 t_3^4 - \\ & t_1^{10} t_3^4 + t_1 t_2 t_3^4 - t_1^5 t_2 t_3^4 - t_1^6 t_2 t_3^4 + t_1^{10} t_2 t_3^4 + t_2^2 t_3^4 - t_1 t_2^2 t_3^4 - \\ & t_1^2 t_2^2 t_3^4 - t_1^5 t_2^2 t_3^4 + 3 t_1^6 t_2^2 t_3^4 - t_1^7 t_2^2 t_3^4 - t_1 t_2^3 t_3^4 + 2 t_1^2 t_2^3 t_3^4 + \\ & t_1^5 t_2^3 t_3^4 - 2 t_1^6 t_2^3 t_3^4 - t_2^4 t_3^4 + t_1 t_2^4 t_3^4 - t_1^2 t_2^4 t_3^4 + t_1^7 t_2^4 t_3^4 - \\ & t_1 t_2 t_3^5 + t_1^6 t_2 t_3^5 + t_1^2 t_2^2 t_3^5 - t_1^6 t_2^2 t_3^5 + t_1 t_2^3 t_3^5 - t_1^2 t_2^3 t_3^5) \end{aligned}$$

$$\text{In}[215]:= \text{G151tangent}[t_1, t_2, t_3] :=$$

$$\begin{aligned} & \text{Det}[\text{DiagonalMatrix}[\{-t_2 + 1, -t_3 + 1, -t_1^4 + 1, (t_1 - t_2) / t_1, \\ & (t_1 - t_3) / t_1, -t_1^3 + 1, (t_1^2 - t_2) / t_1^2, (t_1^2 - t_3) / t_1^2, -t_1^2 + 1, \\ & (t_1^3 - t_2) / t_1^3, (t_1^3 - t_3) / t_1^3, -t_1 + 1, (t_1^4 - t_2^2) / t_1^4, \\ & (t_1^4 - t_2 t_3) / t_1^4, (t_1^4 - t_3^2) / t_1^4, -t_1 + 1, (-t_1 t_3 + t_2) / t_2, \\ & (-t_1^5 + t_2) / t_2, -t_2 + 1, -t_3 + 1, (-t_3^2 + t_2) / t_2, (-t_1 t_2 + t_3) / t_3, \\ & -t_1 + 1, (-t_1^5 + t_3) / t_3, (-t_2^2 + t_3) / t_3, -t_2 + 1, -t_3 + 1\}]] \end{aligned}$$

$$\text{In}[216]:= \text{Together}[\%214 / \text{G151tangent}[t_1, t_2, t_3]]$$

$$\begin{aligned} \text{Out}[216]= & (t_1^{20} t_2^2 t_3^2 (-t_1^9 t_2^2 - t_1^5 t_2^3 - t_1^6 t_2^3 - t_1^7 t_2^3 - t_1^8 t_2^3 - t_1^9 t_2^3 + t_1^4 t_2 t_3 + t_1^5 t_2 t_3 + \\ & t_1^6 t_2 t_3 + t_1^7 t_2 t_3 + t_1^8 t_2 t_3 + t_1^{10} t_2 t_3 + t_1^4 t_2^2 t_3 - t_1^5 t_2^2 t_3 + t_1^{10} t_2^2 t_3 + \\ & t_1 t_2^4 t_3 + t_1^2 t_2^4 t_3 + t_1^3 t_2^4 t_3 + t_1^4 t_2^4 t_3 + t_1^5 t_2^4 t_3 - t_1^9 t_3^2 + t_1^4 t_2 t_3^2 - \\ & t_1^5 t_2 t_3^2 + t_1^{10} t_2 t_3^2 - t_1 t_2^2 t_3^2 - t_1^2 t_2^2 t_3^2 - t_1^3 t_2^2 t_3^2 - t_1^4 t_2^2 t_3^2 + \\ & t_1^6 t_2^2 t_3^2 + t_1^7 t_2^2 t_3^2 + t_1^8 t_2^2 t_3^2 + t_1^9 t_2^2 t_3^2 - t_2^3 t_3^2 + t_1^5 t_2^3 t_3^2 - t_1^6 t_2^3 t_3^2 + \\ & t_1 t_2^4 t_3^2 - t_1^5 t_3^3 - t_1^6 t_3^3 - t_1^7 t_3^3 - t_1^8 t_3^3 - t_1^9 t_3^3 - t_2^2 t_3^3 + t_1^5 t_2^2 t_3^3 - \\ & t_1^6 t_2^2 t_3^3 - t_2^3 t_3^3 - t_1^2 t_2^3 t_3^3 - t_1^3 t_2^3 t_3^3 - t_1^4 t_2^3 t_3^3 - t_1^5 t_2^3 t_3^3 - t_1^6 t_2^3 t_3^3 + \\ & t_1 t_2 t_3^4 + t_1^2 t_2 t_3^4 + t_1^3 t_2 t_3^4 + t_1^4 t_2 t_3^4 + t_1^5 t_2 t_3^4 + t_1 t_2^2 t_3^4) / \\ & ((-1 + t_1)^5 (1 + t_1)^2 (1 + t_1^2) (1 + t_1 + t_1^2) (t_1 - t_2) (t_1^2 - t_2)^2 \\ & (t_1^3 - t_2) (t_1^5 - t_2) (-1 + t_2)^2 (t_1^2 + t_2) (t_1 - t_3) \\ & (t_1^2 - t_3)^2 (t_1^3 - t_3) (t_1^5 - t_3) (t_1 t_2 - t_3) (t_2^2 - t_3) \\ & (-1 + t_3)^2 (t_1^2 + t_3) (-t_2 + t_1 t_3) (t_1^4 - t_2 t_3) (t_2 - t_3^2)) \end{aligned}$$

```
In[217]:= G151[t1_, t2_, t3_] :=
  (t120 t22 t32 (-t19 t22 - t15 t23 - t16 t23 - t17 t23 - t18 t23 - t19 t23 + t14 t2 t3 +
    t15 t2 t3 + t16 t2 t3 + t17 t2 t3 + t18 t2 t3 + t110 t2 t3 + t14 t22 t3 -
    t15 t22 t3 + t110 t22 t3 + t1 t24 t3 + t12 t24 t3 + t13 t24 t3 + t14 t24 t3 +
    t15 t24 t3 - t19 t32 + t14 t2 t32 - t15 t2 t32 + t110 t2 t32 - t1 t22 t32 -
    t12 t22 t32 - t13 t22 t32 - t14 t22 t32 + t16 t22 t32 + t17 t22 t32 + t18 t22 t32 +
    t19 t22 t32 - t23 t32 + t15 t23 t32 - t16 t23 t32 + t1 t24 t32 - t15 t33 -
    t16 t33 - t17 t33 - t18 t33 - t19 t33 - t22 t33 + t15 t22 t33 - t16 t22 t33 -
    t23 t33 - t12 t23 t33 - t13 t23 t33 - t14 t23 t33 - t15 t23 t33 - t16 t23 t33 +
    t1 t2 t34 + t12 t2 t34 + t13 t2 t34 + t14 t2 t34 + t15 t2 t34 + t1 t22 t34)) /
  ((-1 + t1)5 (1 + t1)2 (1 + t12) (1 + t1 + t12) (t1 - t2) (t12 - t2)2 (t13 - t2)
    (t15 - t2) (-1 + t2)2 (t12 + t2) (t1 - t3) (t12 - t3)2 (t13 - t3) (t15 - t3)
    (t1 t2 - t3) (t22 - t3) (-1 + t3)2 (t12 + t3) (-t2 + t1 t3) (t14 - t2 t3) (t2 - t32))
```

```
In[218]:= T151[t1_, t2_, t3_, u_, v_] :=
  Det[DiagonalMatrix[{-u + 1, -t1 * u + 1, -t1^2 * u + 1, -t1^3 * u + 1,
    -t1^4 * u + 1, -t2 * u + 1, -t3 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
    (t1^3 - v) / t1^3, (t1^4 - v) / t1^4, (t2 - v) / t2, (t3 - v) / t3}]]
```

```
In[219]:= GT151[t1_, t2_, t3_, u_, v_] := G151[t1, t2, t3] * T151[t1, t2, t3, u, v]
```

```
In[221]:= Solve[u0 * u4 == t3 / t1 && u1 * u3 == t2 && u1 * u2 == t1^2 &&
  u0 * u3 == t2^2 / t1^2 && u3 * u4 == t2 * t3 / t1^3 && u0 * u4 == t3^2 / t1^3 &&
  u4 * u5 == t1 * t3 / t2 && u0 * u5 == t1^2 && u1 * u5 == t1^4 / t2 &&
  u1 * u4 == t3^2 / (t1 * t2) && u3 * u5 == t1^2 * t2 / t3 && u2 * u5 == t1^4 / t3 &&
  u2 * u3 == t2^2 / t3 && u0 * u2 == t2 && u0 * u1 == t3, {u0, u1, u2, u3, u4, u5}]
```

```
Out[221]= {{u0 -> - (sqrt(t2) sqrt(t3) / t1), u1 -> - (t1 sqrt(t3) / sqrt(t2)), u2 -> - (t1 sqrt(t2) / sqrt(t3)), u3 -> - (t2^(3/2) / (t1 sqrt(t3))),
  u4 -> - (t3^(3/2) / (t1^2 sqrt(t2))), u5 -> - (t1^3 / (sqrt(t2) sqrt(t3)))}, {u0 -> (sqrt(t2) sqrt(t3) / t1), u1 -> (t1 sqrt(t3) / sqrt(t2)),
  u2 -> (t1 sqrt(t2) / sqrt(t3)), u3 -> (t2^(3/2) / (t1 sqrt(t3))), u4 -> (t3^(3/2) / (t1^2 sqrt(t2))), u5 -> (t1^3 / (sqrt(t2) sqrt(t3)))}}
```

$$\text{In}[222]:= \text{Together}\left[G\left[\frac{\sqrt{t_2} \sqrt{t_3}}{t_1}, \frac{t_1 \sqrt{t_3}}{\sqrt{t_2}}, \frac{t_1 \sqrt{t_2}}{\sqrt{t_3}}, \frac{t_2^{3/2}}{t_1 \sqrt{t_3}}, \frac{t_3^{3/2}}{t_1^2 \sqrt{t_2}}, \frac{t_1^3}{\sqrt{t_2} \sqrt{t_3}}\right]\right]$$

$$\text{Out}[222]= \frac{1}{t_1^4 t_2 t_3} \left(-t_1^8 t_2^2 + t_1^{10} t_2^2 - t_1^6 t_2^3 + t_1^8 t_2^3 + t_1^6 t_2^4 - t_1^{10} t_2^4 + t_1^4 t_2 t_3 - t_1^8 t_2 t_3 + t_1^9 t_2 t_3 - t_1^{11} t_2 t_3 - t_1^5 t_2^2 t_3 - t_1^6 t_2^2 t_3 + 2 t_1^7 t_2^2 t_3 + t_1^8 t_2^2 t_3 - t_1^9 t_2^2 t_3 - t_1^4 t_2^3 t_3 + 2 t_1^5 t_2^3 t_3 + t_1^6 t_2^3 t_3 - 2 t_1^7 t_2^3 t_3 - t_1^9 t_2^3 t_3 + t_1^{11} t_2^3 t_3 + t_1^3 t_2^4 t_3 - t_1^5 t_2^4 t_3 - t_1^7 t_2^4 t_3 + t_1^9 t_2^4 t_3 - t_1^3 t_2^5 t_3 + t_1^7 t_2^5 t_3 - t_1^7 t_3^2 + t_1^9 t_3^2 - 2 t_1^5 t_2 t_3^2 + 3 t_1^7 t_2 t_3^2 - t_1^9 t_2 t_3^2 - 2 t_1^3 t_2^2 t_3^2 + 5 t_1^5 t_2^2 t_3^2 - 2 t_1^7 t_2^2 t_3^2 - t_1^8 t_2^2 t_3^2 - t_1^9 t_2^2 t_3^2 + t_1^{10} t_2^2 t_3^2 - t_1 t_2^3 t_3^2 + 3 t_1^3 t_2^3 t_3^2 - 2 t_1^5 t_2^3 t_3^2 - t_1^6 t_2^3 t_3^2 - t_1^7 t_2^3 t_3^2 + 2 t_1^8 t_2^3 t_3^2 + t_1^9 t_2^3 t_3^2 - t_1^{10} t_2^3 t_3^2 + t_1 t_2^4 t_3^2 - t_1^3 t_2^4 t_3^2 - t_1^4 t_2^4 t_3^2 - t_1^5 t_2^4 t_3^2 + 2 t_1^6 t_2^4 t_3^2 + t_1^7 t_2^4 t_3^2 - t_1^8 t_2^4 t_3^2 + t_1^4 t_2^5 t_3^2 - t_1^6 t_2^5 t_3^2 - t_1^5 t_3^3 + t_1^7 t_3^3 - t_1^3 t_2 t_3^3 + t_1^4 t_2 t_3^3 + 2 t_1^5 t_2 t_3^3 - t_1^6 t_2 t_3^3 - t_1^7 t_2 t_3^3 - t_1^8 t_2 t_3^3 + t_1^{10} t_2 t_3^3 - t_1 t_2^2 t_3^3 + t_1^2 t_2^2 t_3^3 + 2 t_1^3 t_2^2 t_3^3 - t_1^4 t_2^2 t_3^3 - t_1^5 t_2^2 t_3^3 - 2 t_1^6 t_2^2 t_3^3 + 3 t_1^8 t_2^2 t_3^3 - t_1^{10} t_2^2 t_3^3 + t_1 t_2^3 t_3^3 - t_1^2 t_2^3 t_3^3 - t_1^3 t_2^3 t_3^3 - 2 t_1^4 t_2^3 t_3^3 + 5 t_1^6 t_2^3 t_3^3 - 2 t_1^8 t_2^3 t_3^3 - t_1^2 t_2^4 t_3^3 + 3 t_1^4 t_2^4 t_3^3 - 2 t_1^6 t_2^4 t_3^3 + t_1^2 t_2^5 t_3^3 - t_1^4 t_2^5 t_3^3 + t_1^4 t_3^4 - t_1^8 t_3^4 + t_1^2 t_2 t_3^4 - t_1^4 t_2 t_3^4 - t_1^6 t_2 t_3^4 + t_1^8 t_2 t_3^4 + t_2^2 t_3^4 - t_1^2 t_2^2 t_3^4 - 2 t_1^4 t_2^2 t_3^4 + t_1^5 t_2^2 t_3^4 + 2 t_1^6 t_2^2 t_3^4 - t_1^7 t_2^2 t_3^4 - t_1^2 t_2^3 t_3^4 + t_1^3 t_2^3 t_3^4 + 2 t_1^4 t_2^3 t_3^4 - t_1^5 t_2^3 t_3^4 - t_1^6 t_2^3 t_3^4 - t_2^4 t_3^4 + t_1^2 t_2^4 t_3^4 - t_1^3 t_2^4 t_3^4 + t_1^7 t_2^4 t_3^4 - t_1 t_2 t_3^5 + t_1^5 t_2 t_3^5 + t_1^3 t_2^2 t_3^5 - t_1^5 t_2^2 t_3^5 + t_1 t_2^3 t_3^5 - t_1^3 t_2^3 t_3^5 \right)$$

$$\text{In}[223]:= \text{G142tangent}[t_1, t_2, t_3] := \text{Det}[\text{DiagonalMatrix}[\{-t_3 + 1, (t_1 - t_3) / t_1, -t_2 + 1, -t_1^2 + 1, (t_1^2 - t_2^2) / t_1^2, (t_1^2 - t_3) / t_1^2, (t_1 - t_2) / t_1, -t_1 + 1, (t_1^3 - t_2^2) / t_1^3, (t_1^3 - t_2 * t_3) / t_1^3, (t_1^3 - t_3^2) / t_1^3, (-t_1 * t_3 + t_2) / t_2, -t_1^2 + 1, (-t_1^4 + t_2) / t_2, -t_2 + 1, (t_2 - t_3) / t_2, -t_1 + 1, (-t_1^3 + t_2) / t_2, (t_1 - t_2) / t_1, (t_1 - t_3) / t_1, (t_1 * t_2 - t_3^2) / (t_1 * t_2), -t_1 + 1, (-t_1^2 * t_2 + t_3) / t_3, (-t_1^4 + t_3) / t_3, (-t_2^2 + t_3) / t_3, -t_2 + 1, -t_3 + 1\}]]$$

$$\text{In}[224]:= \text{Together}[\%222 / \text{G142tangent}[t_1, t_2, t_3]]$$

$$\text{Out}[224]= \frac{(t_1^{14} t_2^4 t_3^2 (-t_1^8 t_2^2 - t_1^6 t_2^3 - t_1^8 t_2^3 + t_1^4 t_2 t_3 + t_1^6 t_2 t_3 + t_1^9 t_2 t_3 + t_1^4 t_2^2 t_3 - t_1^5 t_2^2 t_3 + t_1^7 t_2^2 t_3 + t_1^9 t_2^2 t_3 + t_1^5 t_2^3 t_3 + t_1^7 t_2^3 t_3 + t_1^3 t_2^4 t_3 + t_1^5 t_2^4 t_3 - t_1^7 t_3^2 - 2 t_1^5 t_2 t_3^2 - 2 t_1^3 t_2^2 t_3^2 + t_1^5 t_2^2 t_3^2 + t_1^7 t_2^2 t_3^2 - t_1^8 t_2^2 t_3^2 - t_1 t_2^3 t_3^2 + t_1^5 t_2^3 t_3^2 - t_1^6 t_2^3 t_3^2 - t_1^4 t_2^4 t_3^2 - t_1^5 t_3^3 - t_1^3 t_2 t_3^3 + t_1^4 t_2 t_3^3 - t_1^8 t_2 t_3^3 - t_1 t_2^2 t_3^3 + t_1^2 t_2^2 t_3^3 + t_1^4 t_2^2 t_3^3 - 2 t_1^6 t_2^2 t_3^3 - 2 t_1^4 t_2^3 t_3^3 - t_1^2 t_2^4 t_3^3 + t_1^4 t_3^4 + t_1^6 t_3^4 + t_1^2 t_2 t_3^4 + t_1^4 t_2 t_3^4 + t_2^2 t_3^4 + t_1^2 t_2^2 t_3^4 - t_1^4 t_2^2 t_3^4 + t_1^5 t_2^2 t_3^4 + t_2^3 t_3^4 + t_1^3 t_2^3 t_3^4 + t_1^5 t_2^3 t_3^4 - t_1 t_2 t_3^5 - t_1^3 t_2 t_3^5 - t_1 t_2^2 t_3^5))}{((-1 + t_1)^4 (1 + t_1) (t_1 - t_2)^3 (t_1^3 - t_2) (t_1^4 - t_2) (-1 + t_2)^2 (t_1 + t_2) (t_1^3 - t_2^2) (t_1 - t_3)^2 (t_1^2 - t_3) (t_1^4 - t_3) (t_2 - t_3) (t_1^2 t_2 - t_3) (t_2^2 - t_3) (-1 + t_3)^2 (-t_2 + t_1 t_3) (t_1^3 - t_2 t_3) (t_1^3 - t_3^2) (t_1 t_2 - t_3^2))}$$

```
In[225]:= G142[t1_, t2_, t3_] :=
  (t114 t24 t32 (-t18 t22 - t16 t23 - t18 t23 + t14 t2 t3 + t16 t2 t3 + t19 t2 t3 +
    t14 t22 t3 - t15 t22 t3 + t17 t22 t3 + t19 t22 t3 + t15 t23 t3 + t17 t23 t3 +
    t13 t24 t3 + t15 t24 t3 - t17 t23 - 2 t15 t2 t32 - 2 t13 t22 t32 + t15 t22 t32 +
    t17 t22 t32 - t18 t22 t32 - t1 t23 t32 + t15 t23 t32 - t16 t23 t32 - t14 t24 t32 -
    t15 t33 - t13 t2 t33 + t14 t2 t33 - t18 t2 t33 - t1 t22 t33 + t12 t22 t33 +
    t14 t22 t33 - 2 t16 t22 t33 - 2 t14 t23 t33 - t12 t24 t33 + t14 t34 + t16 t34 +
    t12 t2 t34 + t14 t2 t34 + t22 t34 + t12 t22 t34 - t14 t22 t34 + t15 t22 t34 +
    t23 t34 + t13 t23 t34 + t15 t23 t34 - t1 t2 t35 - t13 t2 t35 - t1 t22 t35)) /
  ((-1 + t1)4 (1 + t1) (t1 - t2)3 (t13 - t2) (t14 - t2) (-1 + t2)2 (t1 + t2)
    (t13 - t22) (t1 - t3)2 (t12 - t3) (t14 - t3) (t2 - t3) (t12 t2 - t3)
    (t22 - t3) (-1 + t3)2 (-t2 + t1 t3) (t13 - t2 t3) (t13 - t32) (t1 t2 - t32))
```

```
In[226]:= T142[t1_, t2_, t3_, u_, v_] :=
  Det[DiagonalMatrix[{-u + 1, -t1 * u + 1, -t12 * u + 1, -t13 * u + 1, -t2 * u + 1,
    -t1 * t2 * u + 1, -t3 * u + 1, -v + 1, (t1 - v) / t1, (t12 - v) / t12,
    (t13 - v) / t13, (t2 - v) / t2, (t1 * t2 - v) / (t1 * t2), (t3 - v) / t3}]]
```

```
In[227]:= GT142[t1_, t2_, t3_, u_, v_] := G142[t1, t2, t3] * T142[t1, t2, t3, u, v]
```

```
In[228]:= Solve[u1 * u2 == t13 && u3 * u4 == t2 * t3 / t13 &&
  u0 * u3 == t23 / t13 && u0 * u4 == t32 / t13 && u2 * u4 == t3 && u0 * u2 == t22 &&
  u4 * u5 == t1 * t3 / t22 && u1 * u5 == t14 / t22 && u1 * u4 == t32 / t22 &&
  u3 * u5 == t1 * t2 / t3 && u0 * u5 == t1 && u2 * u5 == t14 / t3 && u1 * u3 == t2 &&
  u2 * u3 == t23 / t3 && u0 * u1 == t3, {u0, u1, u2, u3, u4, u5}]
```

```
Out[228]= {{u0 -> -\frac{t2 \sqrt{t3}}{t1^{3/2}}, u1 -> -\frac{t1^{3/2} \sqrt{t3}}{t2}, u2 -> -\frac{t1^{3/2} t2}{\sqrt{t3}}, u3 -> -\frac{t2^2}{t1^{3/2} \sqrt{t3}},
  u4 -> -\frac{t3^{3/2}}{t1^{3/2} t2}, u5 -> -\frac{t1^{5/2}}{t2 \sqrt{t3}}}, {u0 -> \frac{t2 \sqrt{t3}}{t1^{3/2}}, u1 -> \frac{t1^{3/2} \sqrt{t3}}{t2},
  u2 -> \frac{t1^{3/2} t2}{\sqrt{t3}}, u3 -> \frac{t2^2}{t1^{3/2} \sqrt{t3}}, u4 -> \frac{t3^{3/2}}{t1^{3/2} t2}, u5 -> \frac{t1^{5/2}}{t2 \sqrt{t3}}}}
```

$$\text{In[230]:= Together}\left[G\left[\frac{t_2 \sqrt{t_3}}{t_1^{3/2}}, \frac{t_1^{3/2} \sqrt{t_3}}{t_2}, \frac{t_1^{3/2} t_2}{\sqrt{t_3}}, \frac{t_2^2}{t_1^{3/2} \sqrt{t_3}}, \frac{t_3^{3/2}}{t_1^{3/2} t_2}, \frac{t_1^{5/2}}{t_2 \sqrt{t_3}}\right]\right]$$

$$\text{Out[230]= } \frac{1}{t_1^3 t_2^2 t_3} \left(-t_1^7 t_2^3 + t_1^8 t_2^3 - t_1^4 t_2^5 + t_1^7 t_2^5 + t_1^4 t_2^6 - t_1^8 t_2^6 + t_1^8 t_2 t_3 - t_1^9 t_2 t_3 + t_1^3 t_2^2 t_3 - t_1^7 t_2^2 t_3 - 2 t_1^4 t_2^3 t_3 + t_1^5 t_2^3 t_3 + 2 t_1^7 t_2^3 t_3 - t_1^8 t_2^3 t_3 + t_1^4 t_2^4 t_3 - t_1^5 t_2^4 t_3 - t_1^8 t_2^4 t_3 + t_1^9 t_2^4 t_3 - t_1^3 t_2^5 t_3 + 2 t_1^4 t_2^5 t_3 - t_1^7 t_2^5 t_3 + t_1 t_2^6 t_3 - t_1^4 t_2^6 t_3 - t_1^5 t_2^6 t_3 + t_1^8 t_2^6 t_3 - t_1 t_2^7 t_3 + t_1^5 t_2^7 t_3 - t_1^7 t_2^3 t_3^2 + t_1^8 t_2^3 t_3^2 - t_1^4 t_2 t_3^2 + t_1^5 t_2 t_3^2 + t_1^7 t_2 t_3^2 - t_1^8 t_2 t_3^2 - t_1^4 t_2^2 t_3^2 + t_1^7 t_2^2 t_3^2 - t_1^8 t_2^2 t_3^2 + t_1^9 t_2^2 t_3^2 - t_1 t_2^3 t_3^2 - t_1^3 t_2^3 t_3^2 + 5 t_1^4 t_2^3 t_3^2 - t_1^5 t_2^3 t_3^2 - t_1^7 t_2^3 t_3^2 - t_1^8 t_2^3 t_3^2 + t_1 t_2^4 t_3^2 - t_1^4 t_2^4 t_3^2 - 2 t_1^5 t_2^4 t_3^2 + t_1^6 t_2^4 t_3^2 + 2 t_1^8 t_2^4 t_3^2 - t_1^9 t_2^4 t_3^2 - t_2^5 t_3^2 + t_1 t_2^5 t_3^2 + t_1^3 t_2^5 t_3^2 - t_1^4 t_2^5 t_3^2 + t_1^5 t_2^5 t_3^2 - t_1^6 t_2^5 t_3^2 + t_2^6 t_3^2 - t_1 t_2^6 t_3^2 - t_1^2 t_2^6 t_3^2 - t_1^4 t_2^6 t_3^2 + 2 t_1^5 t_2^6 t_3^2 + t_1^2 t_2^7 t_3^2 - t_1^5 t_2^7 t_3^2 - t_1^4 t_3^3 + t_1^7 t_3^3 + 2 t_1^4 t_2 t_3^3 - t_1^5 t_2 t_3^3 - t_1^7 t_2 t_3^3 - t_1^8 t_2 t_3^3 + t_1^9 t_2 t_3^3 - t_1^3 t_2^2 t_3^3 + t_1^4 t_2^2 t_3^3 - t_1^5 t_2^2 t_3^3 + t_1^6 t_2^2 t_3^3 + t_1^8 t_2^2 t_3^3 - t_1^9 t_2^2 t_3^3 - t_2^3 t_3^3 + 2 t_1 t_2^3 t_3^3 + t_1^3 t_2^3 t_3^3 - 2 t_1^4 t_2^3 t_3^3 - t_1^5 t_2^3 t_3^3 + t_1^8 t_2^3 t_3^3 - t_1 t_2^4 t_3^3 - t_1^2 t_2^4 t_3^3 - t_1^4 t_2^4 t_3^3 + 5 t_1^5 t_2^4 t_3^3 - t_1^6 t_2^4 t_3^3 - t_1^8 t_2^4 t_3^3 + t_2^5 t_3^3 - t_1 t_2^5 t_3^3 + t_1^2 t_2^5 t_3^3 - t_1^5 t_2^5 t_3^3 - t_1 t_2^6 t_3^3 + t_1^2 t_2^6 t_3^3 + t_1^4 t_2^6 t_3^3 - t_1^5 t_2^6 t_3^3 + t_1 t_2^7 t_3^3 - t_1^2 t_2^7 t_3^3 + t_1^4 t_3^4 - t_1^8 t_3^4 + t_1 t_2 t_3^4 - t_1^4 t_2 t_3^4 - t_1^5 t_2 t_3^4 + t_1^8 t_2 t_3^4 - t_1^2 t_2^2 t_3^4 + 2 t_1^5 t_2^2 t_3^4 - t_1^6 t_2^2 t_3^4 + t_2^3 t_3^4 - t_1 t_2^3 t_3^4 - t_1^4 t_2^3 t_3^4 + t_1^5 t_2^3 t_3^4 - t_1 t_2^4 t_3^4 + 2 t_1^2 t_2^4 t_3^4 + t_1^4 t_2^4 t_3^4 - 2 t_1^5 t_2^4 t_3^4 - t_1^2 t_2^5 t_3^4 + t_1^6 t_2^5 t_3^4 - t_2^6 t_3^4 + t_1 t_2^6 t_3^4 - t_1 t_2 t_3^5 + t_1^5 t_2 t_3^5 + t_1^2 t_2^2 t_3^5 - t_1^5 t_2^2 t_3^5 + t_1 t_2^4 t_3^5 - t_1^2 t_2^4 t_3^5 \right)$$

$$\text{In[231]:= G1411tangent}[t_1_, t_2_, t_3_] := \text{Det}[\text{DiagonalMatrix}[\{-t_2 + 1, -t_3 + 1, -t_1^3 + 1, (t_1 - t_2) / t_1, (t_1 - t_3) / t_1, -t_1^2 + 1, (t_1^2 - t_2) / t_1^2, (t_1^2 - t_3) / t_1^2, -t_1 + 1, (t_1^3 - t_2 * t_3) / t_1^3, (t_1^3 - t_2^3) / t_1^3, (t_1^3 - t_3^2) / t_1^3, -t_1 + 1, -t_3 + 1, -t_2^2 + 1, (-t_1 + t_2) / t_2, (t_2^2 - t_1 * t_3) / t_2^2, (-t_1^4 + t_2^2) / t_2^2, (t_2 - t_3) / t_2, -t_2 + 1, (t_2^2 - t_3^2) / t_2^2, (-t_1 * t_2 + t_3) / t_3, -t_1 + 1, (-t_1^4 + t_3) / t_3, -t_2 + 1, (-t_2^3 + t_3) / t_3, -t_3 + 1\}]]$$

In[232]:= Together[%230 / G1411tangent[t1, t2, t3]]

$$\begin{aligned} \text{Out[232]} = & - \left((t_1^{12} t_2^6 t_3^2 \right. \\ & (-t_1^7 t_2^3 - t_1^7 t_2^4 - t_1^4 t_2^5 - t_1^5 t_2^5 - t_1^6 t_2^5 - t_1^7 t_2^5 + t_1^8 t_2 t_3 + t_1^3 t_2^2 t_3 + \\ & t_1^4 t_2^2 t_3 + t_1^5 t_2^2 t_3 + t_1^6 t_2^2 t_3 + t_1^8 t_2^2 t_3 + t_1^3 t_2^3 t_3 - t_1^4 t_2^3 t_3 + t_1^8 t_2^3 t_3 + \\ & t_1^3 t_2^4 t_3 + t_1 t_2^6 t_3 + t_1^2 t_2^6 t_3 + t_1^3 t_2^6 t_3 + t_1^4 t_2^6 t_3 - t_1^7 t_3^2 - t_1^4 t_2 t_3^2 + \\ & t_1^8 t_2 t_3^2 + t_1^3 t_2^2 t_3^2 - t_1^4 t_2^2 t_3^2 - t_1 t_2^3 t_3^2 - t_1^2 t_2^3 t_3^2 - t_1^3 t_2^3 t_3^2 + \\ & t_1^5 t_2^3 t_3^2 + t_1^6 t_2^3 t_3^2 + t_1^7 t_2^3 t_3^2 + t_1^4 t_2^4 t_3^2 - t_1^5 t_2^4 t_3^2 - \\ & t_2^5 t_3^2 + t_1^4 t_2^5 t_3^2 + t_1 t_2^6 t_3^2 - t_1^4 t_3^3 - t_1^5 t_3^3 - t_1^6 t_3^3 - \\ & t_1^7 t_3^3 - t_1^5 t_2^2 t_3^3 - t_2^3 t_3^3 + t_1^4 t_2^3 t_3^3 - t_1^5 t_2^3 t_3^3 - t_2^4 t_3^3 - \\ & t_1^2 t_2^4 t_3^3 - t_1^3 t_2^4 t_3^3 - t_1^4 t_2^4 t_3^3 - t_1^5 t_2^4 t_3^3 - t_2^5 t_3^3 + t_1 t_2 t_3^4 + \\ & t_1^2 t_2 t_3^4 + t_1^3 t_2 t_3^4 + t_1^4 t_2 t_3^4 + t_1 t_2^2 t_3^4 + t_1 t_2^3 t_3^4) \Big) / \\ & \left((-1 + t_1)^4 (1 + t_1) (1 + t_1 + t_1^2) (t_1 - t_2)^3 (t_1^2 - t_2)^2 (-1 + t_2)^3 \right. \\ & (1 + t_2) (t_1^2 + t_2) (t_1^2 + t_1 t_2 + t_2^2) (t_1 - t_3) (t_1^2 - t_3) \\ & (t_1^4 - t_3) (t_2 - t_3)^2 (t_1 t_2 - t_3) (t_2^3 - t_3) (-1 + t_3)^2 \\ & \left. (t_2 + t_3) (-t_2^2 + t_1 t_3) (t_1^3 - t_2 t_3) (t_1^3 - t_3^2) \right) \Big) \end{aligned}$$

In[233]:= G1411[t1_, t2_, t3_] :=

$$\begin{aligned} & - \left((t_1^{12} t_2^6 t_3^2 (-t_1^7 t_2^3 - t_1^7 t_2^4 - t_1^4 t_2^5 - t_1^5 t_2^5 - t_1^6 t_2^5 - t_1^7 t_2^5 + t_1^8 t_2 t_3 + \right. \\ & t_1^3 t_2^2 t_3 + t_1^4 t_2^2 t_3 + t_1^5 t_2^2 t_3 + t_1^6 t_2^2 t_3 + t_1^8 t_2^2 t_3 + t_1^3 t_2^3 t_3 - \\ & t_1^4 t_2^3 t_3 + t_1^8 t_2^3 t_3 + t_1^3 t_2^4 t_3 + t_1 t_2^6 t_3 + t_1^2 t_2^6 t_3 + t_1^3 t_2^6 t_3 + \\ & t_1^4 t_2^6 t_3 - t_1^7 t_3^2 - t_1^4 t_2 t_3^2 + t_1^8 t_2 t_3^2 + t_1^3 t_2^2 t_3^2 - t_1^4 t_2^2 t_3^2 - \\ & t_1 t_2^3 t_3^2 - t_1^2 t_2^3 t_3^2 - t_1^3 t_2^3 t_3^2 + t_1^5 t_2^3 t_3^2 + t_1^6 t_2^3 t_3^2 + t_1^7 t_2^3 t_3^2 + \\ & t_1^4 t_2^4 t_3^2 - t_1^5 t_2^4 t_3^2 - t_2^5 t_3^2 + t_1^4 t_2^5 t_3^2 + t_1 t_2^6 t_3^2 - t_1^4 t_3^3 - \\ & t_1^5 t_3^3 - t_1^6 t_3^3 - t_1^7 t_3^3 - t_1^5 t_2^2 t_3^3 - t_2^3 t_3^3 + t_1^4 t_2^3 t_3^3 - t_1^5 t_2^3 t_3^3 - \\ & t_2^4 t_3^3 - t_1^2 t_2^4 t_3^3 - t_1^3 t_2^4 t_3^3 - t_1^4 t_2^4 t_3^3 - t_1^5 t_2^4 t_3^3 - t_2^5 t_3^3 + \\ & t_1 t_2 t_3^4 + t_1^2 t_2 t_3^4 + t_1^3 t_2 t_3^4 + t_1^4 t_2 t_3^4 + t_1 t_2^2 t_3^4 + t_1 t_2^3 t_3^4) \Big) / \\ & \left((-1 + t_1)^4 (1 + t_1) (1 + t_1 + t_1^2) (t_1 - t_2)^3 (t_1^2 - t_2)^2 (-1 + t_2)^3 (1 + t_2) \right. \\ & (t_1^2 + t_2) (t_1^2 + t_1 t_2 + t_2^2) (t_1 - t_3) (t_1^2 - t_3) (t_1^4 - t_3) (t_2 - t_3)^2 (t_1 t_2 - t_3) \\ & \left. (t_2^3 - t_3) (-1 + t_3)^2 (t_2 + t_3) (-t_2^2 + t_1 t_3) (t_1^3 - t_2 t_3) (t_1^3 - t_3^2) \right) \Big) \end{aligned}$$

In[234]:= T1411[t1_, t2_, t3_, u_, v_] :=

$$\begin{aligned} & \text{Det}[\text{DiagonalMatrix}[\{-u + 1, -t_1 * u + 1, -t_1^2 * u + 1, -t_1^3 * u + 1, \\ & -t_2 * u + 1, -t_2^2 * u + 1, -t_3 * u + 1, -v + 1, (t_1 - v) / t_1, (t_1^2 - v) / t_1^2, \\ & (t_1^3 - v) / t_1^3, (t_2 - v) / t_2, (t_2^2 - v) / t_2^2, (t_3 - v) / t_3\}]] \end{aligned}$$

In[235]:= GT1411[t1_, t2_, t3_, u_, v_] := G1411[t1, t2, t3] * T1411[t1, t2, t3, u, v]

In[244]:= **Solve**[$u_1 * u_2 == t_1^2$ && $u_1 * u_3 == t_2$ && $u_2 * u_4 == t_3$ && $u_0 * u_3 == t_2^2 / t_1^2$ &&
 $u_3 * u_4 == t_2 * t_3 / t_1^2$ && $u_0 * u_4 == t_3^2 / t_1^2$ && $u_1 * u_5 == t_1^3 / t_2$ && $u_0 * u_2 == t_2$ &&
 $u_1 * u_4 == t_3^2 / t_2$ && $u_0 * u_5 == t_1$ && $u_4 * u_5 == t_1 * t_3 / t_2$ && $u_2 * u_5 == t_1^3 / t_3$ &&
 $u_2 * u_3 == t_2^2 / t_3$ && $u_0 * u_1 == t_3$ && $u_3 * u_5 == t_1 * t_2 / t_3$, { $u_0, u_1, u_2, u_3, u_4, u_5$ }]

$$\text{Out[244]} = \left\{ \left\{ u_0 \rightarrow -\frac{\sqrt{t_2} \sqrt{t_3}}{t_1}, u_1 \rightarrow -\frac{t_1 \sqrt{t_3}}{\sqrt{t_2}}, u_2 \rightarrow -\frac{t_1 \sqrt{t_2}}{\sqrt{t_3}}, u_3 \rightarrow -\frac{t_2^{3/2}}{t_1 \sqrt{t_3}}, \right. \right. \\ \left. u_4 \rightarrow -\frac{t_3^{3/2}}{t_1 \sqrt{t_2}}, u_5 \rightarrow -\frac{t_1^2}{\sqrt{t_2} \sqrt{t_3}} \right\}, \left\{ u_0 \rightarrow \frac{\sqrt{t_2} \sqrt{t_3}}{t_1}, u_1 \rightarrow \frac{t_1 \sqrt{t_3}}{\sqrt{t_2}}, \right. \\ \left. u_2 \rightarrow \frac{t_1 \sqrt{t_2}}{\sqrt{t_3}}, u_3 \rightarrow \frac{t_2^{3/2}}{t_1 \sqrt{t_3}}, u_4 \rightarrow \frac{t_3^{3/2}}{t_1 \sqrt{t_2}}, u_5 \rightarrow \frac{t_1^2}{\sqrt{t_2} \sqrt{t_3}} \right\} \right\}$$

In[245]:= **Together** $\left[G \left[\frac{\sqrt{t_2} \sqrt{t_3}}{t_1}, \frac{t_1 \sqrt{t_3}}{\sqrt{t_2}}, \frac{t_1 \sqrt{t_2}}{\sqrt{t_3}}, \frac{t_2^{3/2}}{t_1 \sqrt{t_3}}, \frac{t_3^{3/2}}{t_1 \sqrt{t_2}}, \frac{t_1^2}{\sqrt{t_2} \sqrt{t_3}} \right] \right]$

$$\text{Out[245]} = \frac{1}{t_1^2 t_2 t_3} \\ \left(-t_1^5 t_2^2 + t_1^6 t_2^2 - t_1^3 t_2^3 + t_1^5 t_2^3 + t_1^3 t_2^4 - t_1^6 t_2^4 + t_1^2 t_2 t_3 - t_1^5 t_2 t_3 + t_1^6 t_2 t_3 - \right. \\ t_1^7 t_2 t_3 - 2 t_1^3 t_2^2 t_3 + t_1^4 t_2^2 t_3 + 2 t_1^5 t_2^2 t_3 - t_1^6 t_2^2 t_3 - t_1^2 t_2^3 t_3 + 3 t_1^3 t_2^3 t_3 - \\ t_1^4 t_2^3 t_3 - t_1^5 t_2^3 t_3 - t_1^6 t_2^3 t_3 + t_1^7 t_2^3 t_3 + t_1 t_2^4 t_3 - t_1^3 t_2^4 t_3 - t_1^4 t_2^4 t_3 + \\ t_1^6 t_2^4 t_3 - t_1 t_2^5 t_3 + t_1^4 t_2^5 t_3 - t_1^5 t_3^2 + t_1^6 t_3^2 - 2 t_1^3 t_2 t_3^2 + t_1^4 t_2 t_3^2 + \\ 2 t_1^5 t_2 t_3^2 - t_1^6 t_2 t_3^2 - t_1 t_2^2 t_3^2 - t_1^2 t_2^2 t_3^2 + 5 t_1^3 t_2^2 t_3^2 - t_1^4 t_2^2 t_3^2 - \\ t_1^5 t_2^2 t_3^2 - 2 t_1^6 t_2^2 t_3^2 + t_1^7 t_2^2 t_3^2 - t_2^3 t_3^2 + 2 t_1 t_2^3 t_3^2 + t_1^2 t_2^3 t_3^2 - 2 t_1^3 t_2^3 t_3^2 - \\ 2 t_1^4 t_2^3 t_3^2 + t_1^5 t_2^3 t_3^2 + 2 t_1^6 t_2^3 t_3^2 - t_1^7 t_2^3 t_3^2 + t_2^4 t_3^2 - t_1 t_2^4 t_3^2 - t_1^2 t_2^4 t_3^2 - \\ t_1^3 t_2^4 t_3^2 + 3 t_1^4 t_2^4 t_3^2 - t_1^5 t_2^4 t_3^2 + t_1^2 t_2^5 t_3^2 - t_1^4 t_2^5 t_3^2 - t_1^3 t_3^3 + t_1^5 t_3^3 - \\ t_1^2 t_2 t_3^3 + 3 t_1^3 t_2 t_3^3 - t_1^4 t_2 t_3^3 - t_1^5 t_2 t_3^3 - t_1^6 t_2 t_3^3 + t_1^7 t_2 t_3^3 - t_2^2 t_3^3 + \\ 2 t_1 t_2^2 t_3^3 + t_1^2 t_2^2 t_3^3 - 2 t_1^3 t_2^2 t_3^3 - 2 t_1^4 t_2^2 t_3^3 + t_1^5 t_2^2 t_3^3 + 2 t_1^6 t_2^2 t_3^3 - \\ t_1^7 t_2^2 t_3^3 + t_2^3 t_3^3 - 2 t_1 t_2^3 t_3^3 - t_1^2 t_2^3 t_3^3 - t_1^3 t_2^3 t_3^3 + 5 t_1^4 t_2^3 t_3^3 - \\ t_1^5 t_2^3 t_3^3 - t_1^6 t_2^3 t_3^3 - t_1 t_2^4 t_3^3 + 2 t_1^2 t_2^4 t_3^3 + t_1^3 t_2^4 t_3^3 - 2 t_1^4 t_2^4 t_3^3 + \\ t_1 t_2^5 t_3^3 - t_1^2 t_2^5 t_3^3 + t_1^3 t_3^4 - t_1^6 t_3^4 + t_1 t_2 t_3^4 - t_1^3 t_2 t_3^4 - t_1^4 t_2 t_3^4 + \\ t_1^6 t_2 t_3^4 + t_2^2 t_3^4 - t_1 t_2^2 t_3^4 - t_1^2 t_2^2 t_3^4 - t_1^3 t_2^2 t_3^4 + 3 t_1^4 t_2^2 t_3^4 - t_1^5 t_2^2 t_3^4 - \\ t_1 t_2^3 t_3^4 + 2 t_1^2 t_2^3 t_3^4 + t_1^3 t_2^3 t_3^4 - 2 t_1^4 t_2^3 t_3^4 - t_2^4 t_3^4 + t_1 t_2^4 t_3^4 - t_1^2 t_2^4 t_3^4 + \\ \left. t_1^5 t_2^4 t_3^4 - t_1 t_2 t_3^5 + t_1^4 t_2 t_3^5 + t_1^2 t_2^2 t_3^5 - t_1^4 t_2^2 t_3^5 + t_1 t_2^3 t_3^5 - t_1^2 t_2^3 t_3^5 \right)$$

In[255]:= **G232tangent**[t_1 _, t_2 _, t_3 _] :=

Det[**DiagonalMatrix**[{- $t_1^2 + 1$, - $t_1 + 1$, - $t_2 + 1$, - $t_3 + 1$, ($t_1^2 - t_2^2$) / t_1^2 ,
($t_1^2 - t_2 * t_3$) / t_1^2 , ($t_1^2 - t_3^2$) / t_1^2 , (- $t_1^3 + t_2$) / t_2 , - $t_2 + 1$,
- $t_3 + 1$, (- $t_3^2 + t_2$) / t_2 , (- $t_1^2 + t_2$) / t_2 , - $t_1 + 1$, (- $t_1 * t_3 + t_2$) / t_2 ,
($t_1 - t_2$) / t_1 , ($t_1 - t_3$) / t_1 , ($t_1 * t_2 - t_3^2$) / ($t_1 * t_2$), (- $t_1^3 + t_3$) / t_3 ,
(- $t_2^2 + t_3$) / t_3 , - $t_2 + 1$, - $t_3 + 1$, (- $t_1^2 + t_3$) / t_3 , (- $t_1 * t_2 + t_3$) / t_3 ,
- $t_1 + 1$, (- $t_2^2 + t_1 * t_3$) / ($t_1 * t_3$), ($t_1 - t_2$) / t_1 , ($t_1 - t_3$) / t_1 }]]]

In[257]:= Together[%245 / G232tangent[t1, t2, t3]]

Out[257]=
$$\left(t_1^{10} t_2^4 t_3^4 \right. \\ \left(-t_1^5 t_2^2 - t_1^3 t_2^3 - t_1^4 t_2^3 - t_1^5 t_2^3 + t_1^2 t_2 t_3 + t_1^3 t_2 t_3 + t_1^4 t_2 t_3 + t_1^6 t_2 t_3 + \right. \\ \left. t_1^2 t_2^2 t_3 - t_1^3 t_2^2 t_3 + t_1^6 t_2^2 t_3 + t_1 t_2^4 t_3 + t_1^2 t_2^4 t_3 + t_1^3 t_2^4 t_3 - t_1^5 t_3^2 + \right. \\ \left. t_1^2 t_2 t_3^2 - t_1^3 t_2 t_3^2 + t_1^6 t_2 t_3^2 - t_1 t_2^2 t_3^2 - t_1^2 t_2^2 t_3^2 + t_1^4 t_2^2 t_3^2 + \right. \\ \left. t_1^5 t_2^2 t_3^2 - t_2^3 t_3^2 + t_1^3 t_2^3 t_3^2 - t_1^4 t_2^3 t_3^2 + t_1 t_2^4 t_3^2 - t_1^3 t_3^3 - \right. \\ \left. t_1^4 t_3^3 - t_1^5 t_3^3 - t_2^2 t_3^3 + t_1^3 t_2^2 t_3^3 - t_1^4 t_2^2 t_3^3 - t_2^3 t_3^3 - t_1^2 t_2^3 t_3^3 - \right. \\ \left. t_1^3 t_2^3 t_3^3 - t_1^4 t_2^3 t_3^3 + t_1 t_2 t_3^4 + t_1^2 t_2 t_3^4 + t_1^3 t_2 t_3^4 + t_1 t_2^2 t_3^4 \right) \Big) / \\ \left((-1 + t_1)^3 (1 + t_1) (t_1 - t_2)^3 (t_1^2 - t_2) (t_1^3 - t_2) (-1 + t_2)^2 (t_1 + t_2) \right. \\ \left(t_1 - t_3 \right)^3 (t_1^2 - t_3) (t_1^3 - t_3) (t_1 t_2 - t_3) (t_2^2 - t_3) (-1 + t_3)^2 (t_1 + t_3) \\ \left. (-t_2 + t_1 t_3) (-t_2^2 + t_1 t_3) (t_1^2 - t_2 t_3) (t_2 - t_3^2) (t_1 t_2 - t_3^2) \right)$$

In[264]:= G232[t1_, t2_, t3_] :=

$$\left(t_1^{10} t_2^4 t_3^4 \left(-t_1^5 t_2^2 - t_1^3 t_2^3 - t_1^4 t_2^3 - t_1^5 t_2^3 + t_1^2 t_2 t_3 + t_1^3 t_2 t_3 + t_1^4 t_2 t_3 + \right. \right. \\ \left. t_1^6 t_2 t_3 + t_1^2 t_2^2 t_3 - t_1^3 t_2^2 t_3 + t_1^6 t_2^2 t_3 + t_1 t_2^4 t_3 + t_1^2 t_2^4 t_3 + \right. \\ \left. t_1^3 t_2^4 t_3 - t_1^5 t_3^2 + t_1^2 t_2 t_3^2 - t_1^3 t_2 t_3^2 + t_1^6 t_2 t_3^2 - t_1 t_2^2 t_3^2 - t_1^2 t_2^2 t_3^2 + \right. \\ \left. t_1^4 t_2^2 t_3^2 + t_1^5 t_2^2 t_3^2 - t_2^3 t_3^2 + t_1^3 t_2^3 t_3^2 - t_1^4 t_2^3 t_3^2 + t_1 t_2^4 t_3^2 - t_1^3 t_3^3 - \right. \\ \left. t_1^4 t_3^3 - t_1^5 t_3^3 - t_2^2 t_3^3 + t_1^3 t_2^2 t_3^3 - t_1^4 t_2^2 t_3^3 - t_2^3 t_3^3 - t_1^2 t_2^3 t_3^3 - \right. \\ \left. t_1^3 t_2^3 t_3^3 - t_1^4 t_2^3 t_3^3 + t_1 t_2 t_3^4 + t_1^2 t_2 t_3^4 + t_1^3 t_2 t_3^4 + t_1 t_2^2 t_3^4 \right) \Big) / \\ \left((-1 + t_1)^3 (1 + t_1) (t_1 - t_2)^3 (t_1^2 - t_2) (t_1^3 - t_2) (-1 + t_2)^2 (t_1 + t_2) \right. \\ \left(t_1 - t_3 \right)^3 (t_1^2 - t_3) (t_1^3 - t_3) (t_1 t_2 - t_3) (t_2^2 - t_3) (-1 + t_3)^2 (t_1 + t_3) \\ \left. (-t_2 + t_1 t_3) (-t_2^2 + t_1 t_3) (t_1^2 - t_2 t_3) (t_2 - t_3^2) (t_1 t_2 - t_3^2) \right);$$

In[267]:= T232[t1_, t2_, t3_, u_, v_] :=

$$\text{Det}[\text{DiagonalMatrix}\{\{-u + 1, -t_1 * u + 1, -t_1^2 * u + 1, -t_2 * u + 1, -t_1 * t_2 * u + 1, \\ -t_3 * u + 1, -t_1 * t_3 * u + 1, -v + 1, (t_1 - v) / t_1, (t_1^2 - v) / t_1^2, \\ (t_2 - v) / t_2, (t_1 * t_2 - v) / (t_1 * t_2), (t_3 - v) / t_3, (t_1 * t_3 - v) / (t_1 * t_3)\}\}]; \\ \text{GT232}[t_1_, t_2_, t_3_, u_, v_] := \text{G232}[t_1, t_2, t_3] * \text{T232}[t_1, t_2, t_3, u, v]$$

In[237]:= Solve[u0 * u5 == t1^2 && u0 * u4 == t3^2 / t1 && u1 * u2 == t1 &&

u3 * u4 == t2 * t3 / t1^2 && u0 * u3 == t2^3 / t1^2 && u2 * u4 == t3 && \\ u0 * u2 == t2^2 && u1 * u5 == t1^3 / t2^2 && u4 * u5 == t1^2 * t3 / t2^2 && \\ u1 * u4 == t3^2 / t2^2 && u3 * u5 == t1 * t2 / t3 && u2 * u5 == t1^3 / t3 && u0 * u1 == t3 && \\ u1 * u3 == t2 / t1 && u2 * u3 == t2^3 / (t1 * t3), {u0, u1, u2, u3, u4, u5}]

Out[237]=
$$\left\{ \left\{ u_0 \rightarrow -\frac{t_2 \sqrt{t_3}}{\sqrt{t_1}}, u_1 \rightarrow -\frac{\sqrt{t_1} \sqrt{t_3}}{t_2}, u_2 \rightarrow -\frac{\sqrt{t_1} t_2}{\sqrt{t_3}}, u_3 \rightarrow -\frac{t_2^2}{t_1^{3/2} \sqrt{t_3}}, \right. \right. \\ \left. u_4 \rightarrow -\frac{t_3^{3/2}}{\sqrt{t_1} t_2}, u_5 \rightarrow -\frac{t_1^{5/2}}{t_2 \sqrt{t_3}} \right\}, \left\{ u_0 \rightarrow \frac{t_2 \sqrt{t_3}}{\sqrt{t_1}}, u_1 \rightarrow \frac{\sqrt{t_1} \sqrt{t_3}}{t_2}, \right. \\ \left. u_2 \rightarrow \frac{\sqrt{t_1} t_2}{\sqrt{t_3}}, u_3 \rightarrow \frac{t_2^2}{t_1^{3/2} \sqrt{t_3}}, u_4 \rightarrow \frac{t_3^{3/2}}{\sqrt{t_1} t_2}, u_5 \rightarrow \frac{t_1^{5/2}}{t_2 \sqrt{t_3}} \right\} \Big\}$$

$$\text{In}[238]:= \text{Together}\left[G\left[\frac{t_2 \sqrt{t_3}}{\sqrt{t_1}}, \frac{\sqrt{t_1} \sqrt{t_3}}{t_2}, \frac{\sqrt{t_1} t_2}{\sqrt{t_3}}, \frac{t_2^2}{t_1^{3/2} \sqrt{t_3}}, \frac{t_3^{3/2}}{\sqrt{t_1} t_2}, \frac{t_1^{5/2}}{t_2 \sqrt{t_3}}\right]\right]$$

$$\text{Out}[238]= \frac{1}{t_1^3 t_2^2 t_3} \left(-t_1^5 t_2^3 + t_1^7 t_2^3 - t_1^4 t_2^5 + t_1^5 t_2^5 + t_1^3 t_2^6 - t_1^6 t_2^6 + t_1^7 t_2 t_3 - t_1^9 t_2 t_3 + t_1^3 t_2^2 t_3 - t_1^6 t_2^2 t_3 - 2 t_1^4 t_2^3 t_3 + 2 t_1^5 t_2^3 t_3 + t_1^6 t_2^3 t_3 - t_1^7 t_2^3 t_3 + t_1^3 t_2^4 t_3 - t_1^5 t_2^4 t_3 - t_1^6 t_2^4 t_3 + t_1^8 t_2^4 t_3 - t_1^2 t_2^5 t_3 + 2 t_1^4 t_2^5 t_3 - t_1^5 t_2^5 t_3 + t_1^2 t_2^6 t_3 - t_1^3 t_2^6 t_3 - t_1^5 t_2^6 t_3 + t_1^6 t_2^6 t_3 - t_1 t_2^7 t_3 + t_1^4 t_2^7 t_3 - t_1^6 t_3^2 + t_1^8 t_3^2 - t_1^4 t_2 t_3^2 + t_1^5 t_2 t_3^2 + t_1^6 t_2 t_3^2 - t_1^7 t_2 t_3^2 - t_1^5 t_2^2 t_3^2 + t_1^8 t_2^2 t_3^2 - t_1^2 t_2^3 t_3^2 - t_1^3 t_2^3 t_3^2 + 5 t_1^4 t_2^3 t_3^2 - t_1^5 t_2^3 t_3^2 - t_1^6 t_2^3 t_3^2 - t_1^7 t_2^3 t_3^2 + t_1^2 t_2^4 t_3^2 - t_1^3 t_2^4 t_3^2 - 2 t_1^5 t_2^4 t_3^2 + 2 t_1^6 t_2^4 t_3^2 + t_1^7 t_2^4 t_3^2 - t_1^8 t_2^4 t_3^2 - t_1 t_2^5 t_3^2 + t_1^2 t_2^5 t_3^2 + t_1^3 t_2^5 t_3^2 - t_1^6 t_2^5 t_3^2 + t_2^6 t_3^2 - t_1^2 t_2^6 t_3^2 - t_1^3 t_2^6 t_3^2 - t_1^4 t_2^6 t_3^2 + 2 t_1^5 t_2^6 t_3^2 + t_1^3 t_2^7 t_3^2 - t_1^4 t_2^7 t_3^2 - t_1^5 t_3^3 + t_1^6 t_3^3 + 2 t_1^4 t_2 t_3^3 - t_1^5 t_2 t_3^3 - t_1^6 t_2 t_3^3 - t_1^7 t_2 t_3^3 + t_1^9 t_2 t_3^3 - t_1^3 t_2^2 t_3^3 + t_1^6 t_2^2 t_3^3 + t_1^7 t_2^2 t_3^3 - t_1^8 t_2^2 t_3^3 - t_1 t_2^3 t_3^3 + t_1^2 t_2^3 t_3^3 + 2 t_1^3 t_2^3 t_3^3 - 2 t_1^4 t_2^3 t_3^3 - t_1^6 t_2^3 t_3^3 + t_1^7 t_2^3 t_3^3 - t_1^2 t_2^4 t_3^3 - t_1^3 t_2^4 t_3^3 - t_1^4 t_2^4 t_3^3 + 5 t_1^5 t_2^4 t_3^3 - t_1^6 t_2^4 t_3^3 - t_1^7 t_2^4 t_3^3 + t_1 t_2^5 t_3^3 - t_1^4 t_2^5 t_3^3 - t_1^2 t_2^6 t_3^3 + t_1^3 t_2^6 t_3^3 + t_1^4 t_2^6 t_3^3 - t_1^5 t_2^6 t_3^3 + t_1 t_2^7 t_3^3 - t_1^3 t_2^7 t_3^3 + t_1^5 t_3^4 - t_1^8 t_3^4 + t_1^3 t_2 t_3^4 - t_1^4 t_2 t_3^4 - t_1^6 t_2 t_3^4 + t_1^7 t_2 t_3^4 - t_1^4 t_2^2 t_3^4 + 2 t_1^5 t_2^2 t_3^4 - t_1^7 t_2^2 t_3^4 + t_1 t_2^3 t_3^4 - t_1^3 t_2^3 t_3^4 - t_1^4 t_2^3 t_3^4 + t_1^6 t_2^3 t_3^4 - t_1^2 t_2^4 t_3^4 + t_1^3 t_2^4 t_3^4 + 2 t_1^4 t_2^4 t_3^4 - 2 t_1^5 t_2^4 t_3^4 - t_1^3 t_2^5 t_3^4 + t_1^6 t_2^5 t_3^4 - t_2^6 t_3^4 + t_1^2 t_2^6 t_3^4 - t_1^3 t_2 t_3^5 + t_1^6 t_2 t_3^5 + t_1^4 t_2^2 t_3^5 - t_1^5 t_2^2 t_3^5 + t_1^2 t_2^4 t_3^5 - t_1^4 t_2^4 t_3^5 \right)$$

$$\text{In}[239]:= \text{G2311tangent}[t_1_, t_2_, t_3_] := \text{Det}[\text{DiagonalMatrix}[\{-t_2 + 1, -t_1^2 + 1, (-t_3^2 + t_1) / t_1, (t_1 - t_2) / t_1, -t_1 + 1, -t_3 + 1, (t_1^2 - t_2 * t_3) / t_1^2, (-t_2^3 + t_1^2) / t_1^2, (t_1^2 - t_3^2) / t_1^2, -t_1 + 1, -t_3 + 1, -t_2^2 + 1, (-t_1 + t_2) / t_2, (-t_1^3 + t_2^2) / t_2^2, (-t_1^2 * t_3 + t_2^2) / t_2^2, (t_2 - t_3) / t_2, -t_2 + 1, (t_2^2 - t_3^2) / t_2^2, (-t_1 * t_2 + t_3) / t_3, (-t_1^3 + t_3) / t_3, -t_3 + 1, (-t_2 + t_3) / t_3, (-t_1^2 + t_3) / t_3, -t_1 + 1, (t_1 - t_2) / t_1, (-t_2^3 + t_1 * t_3) / (t_1 * t_3), (t_1 - t_3) / t_1\}]]$$

In[240]:= Together[%238 / G2311tangent[t1, t2, t3]]

$$\begin{aligned} \text{Out[240]} = & - \left((t_1^8 t_2^6 t_3^4 (-t_1^5 t_2^3 - t_1^6 t_2^3 - t_1^4 t_2^5 + t_1^3 t_2^6 + t_1^4 t_2^6 + t_1^5 t_2^6 + t_1^7 t_2 t_3 + \right. \\ & t_1^8 t_2 t_3 + t_1^3 t_2^2 t_3 + t_1^4 t_2^2 t_3 + t_1^5 t_2^2 t_3 - 2 t_1^4 t_2^3 t_3 - t_1^5 t_2^3 t_3 + \\ & t_1^3 t_2^4 t_3 + t_1^4 t_2^4 t_3 - t_1^6 t_2^4 t_3 - t_1^7 t_2^4 t_3 - t_1^2 t_2^5 t_3 - t_1^3 t_2^5 t_3 + \\ & t_1^2 t_2^6 t_3 + t_1^3 t_2^6 t_3 + t_1^4 t_2^6 t_3 - t_1 t_2^7 t_3 - t_1^2 t_2^7 t_3 - t_1^3 t_2^7 t_3 - \\ & t_1^6 t_2^3 - t_1^7 t_2^3 - t_1^4 t_2 t_3^2 + t_1^6 t_2 t_3^2 + t_1^7 t_2 t_3^2 + t_1^8 t_2 t_3^2 + t_1^3 t_2^2 t_3^2 + \\ & t_1^4 t_2^2 t_3^2 - t_1^6 t_2^2 t_3^2 - t_1^7 t_2^2 t_3^2 - t_1^2 t_2^3 t_3^2 - 2 t_1^3 t_2^3 t_3^2 + \\ & t_1^4 t_2^3 t_3^2 + t_1^5 t_2^3 t_3^2 + t_1^6 t_2^3 t_3^2 + t_1^2 t_2^4 t_3^2 + t_1^3 t_2^4 t_3^2 + t_1^4 t_2^4 t_3^2 - \\ & 2 t_1^5 t_2^4 t_3^2 - t_1^6 t_2^4 t_3^2 - t_1 t_2^5 t_3^2 - t_1^2 t_2^5 t_3^2 + t_1^4 t_2^5 t_3^2 + t_1^5 t_2^5 t_3^2 + \\ & t_2^6 t_3^2 + t_1 t_2^6 t_3^2 + t_1^2 t_2^6 t_3^2 - t_1^4 t_2^6 t_3^2 - t_1 t_2^7 t_3^2 - t_1^2 t_2^7 t_3^2 - \\ & t_1^5 t_2^3 - t_1^6 t_2^3 - t_1^7 t_2^3 + t_1^4 t_2 t_3^3 + t_1^5 t_2 t_3^3 + t_1^6 t_2 t_3^3 - t_1^5 t_2^2 t_3^3 - \\ & t_1^6 t_2^2 t_3^3 - t_1 t_2^3 t_3^3 - t_1^2 t_2^3 t_3^3 + t_1^4 t_2^3 t_3^3 + t_1^5 t_2^3 t_3^3 - t_1^3 t_2^4 t_3^3 - \\ & 2 t_1^4 t_2^4 t_3^3 + t_1^3 t_2^5 t_3^3 + t_1^4 t_2^5 t_3^3 + t_1^5 t_2^5 t_3^3 + t_2^6 t_3^3 + t_1 t_2^6 t_3^3 + \\ & t_1^3 t_2 t_3^4 + t_1^4 t_2 t_3^4 + t_1^5 t_2 t_3^4 - t_1^4 t_2^2 t_3^4 - t_1^2 t_2^4 t_3^4 - t_1^3 t_2^4 t_3^4) \Big) / \\ & ((-1 + t_1)^3 (1 + t_1) (t_1 - t_2)^3 (-1 + t_2)^3 (1 + t_2) (t_1^3 - t_2^2) (t_1^2 - t_2^3) \\ & (t_1 - t_3)^2 (t_1^2 - t_3) (t_1^3 - t_3) (t_2 - t_3)^3 (t_1 t_2 - t_3) (-1 + t_3)^2 (t_1 + t_3) \\ & (t_2 + t_3) (-t_2^3 + t_1 t_3) (-t_2^2 + t_1^2 t_3) (t_1^2 - t_2 t_3) (t_1 - t_3^2)) \end{aligned}$$

In[241]:= G2311[t1_, t2_, t3_] :=

$$\begin{aligned} & - \left((t_1^8 t_2^6 t_3^4 (-t_1^5 t_2^3 - t_1^6 t_2^3 - t_1^4 t_2^5 + t_1^3 t_2^6 + t_1^4 t_2^6 + t_1^5 t_2^6 + t_1^7 t_2 t_3 + \right. \\ & t_1^8 t_2 t_3 + t_1^3 t_2^2 t_3 + t_1^4 t_2^2 t_3 + t_1^5 t_2^2 t_3 - 2 t_1^4 t_2^3 t_3 - t_1^5 t_2^3 t_3 + \\ & t_1^3 t_2^4 t_3 + t_1^4 t_2^4 t_3 - t_1^6 t_2^4 t_3 - t_1^7 t_2^4 t_3 - t_1^2 t_2^5 t_3 - t_1^3 t_2^5 t_3 + \\ & t_1^2 t_2^6 t_3 + t_1^3 t_2^6 t_3 + t_1^4 t_2^6 t_3 - t_1 t_2^7 t_3 - t_1^2 t_2^7 t_3 - t_1^3 t_2^7 t_3 - \\ & t_1^6 t_2^3 - t_1^7 t_2^3 - t_1^4 t_2 t_3^2 + t_1^6 t_2 t_3^2 + t_1^7 t_2 t_3^2 + t_1^8 t_2 t_3^2 + t_1^3 t_2^2 t_3^2 + \\ & t_1^4 t_2^2 t_3^2 - t_1^6 t_2^2 t_3^2 - t_1^7 t_2^2 t_3^2 - t_1^2 t_2^3 t_3^2 - 2 t_1^3 t_2^3 t_3^2 + \\ & t_1^4 t_2^3 t_3^2 + t_1^5 t_2^3 t_3^2 + t_1^6 t_2^3 t_3^2 + t_1^2 t_2^4 t_3^2 + t_1^3 t_2^4 t_3^2 + t_1^4 t_2^4 t_3^2 - \\ & 2 t_1^5 t_2^4 t_3^2 - t_1^6 t_2^4 t_3^2 - t_1 t_2^5 t_3^2 - t_1^2 t_2^5 t_3^2 + t_1^4 t_2^5 t_3^2 + t_1^5 t_2^5 t_3^2 + \\ & t_2^6 t_3^2 + t_1 t_2^6 t_3^2 + t_1^2 t_2^6 t_3^2 - t_1^4 t_2^6 t_3^2 - t_1 t_2^7 t_3^2 - t_1^2 t_2^7 t_3^2 - \\ & t_1^5 t_2^3 - t_1^6 t_2^3 - t_1^7 t_2^3 + t_1^4 t_2 t_3^3 + t_1^5 t_2 t_3^3 + t_1^6 t_2 t_3^3 - t_1^5 t_2^2 t_3^3 - \\ & t_1^6 t_2^2 t_3^3 - t_1 t_2^3 t_3^3 - t_1^2 t_2^3 t_3^3 + t_1^4 t_2^3 t_3^3 + t_1^5 t_2^3 t_3^3 - t_1^3 t_2^4 t_3^3 - \\ & 2 t_1^4 t_2^4 t_3^3 + t_1^3 t_2^5 t_3^3 + t_1^4 t_2^5 t_3^3 + t_1^5 t_2^5 t_3^3 + t_2^6 t_3^3 + t_1 t_2^6 t_3^3 + \\ & t_1^3 t_2 t_3^4 + t_1^4 t_2 t_3^4 + t_1^5 t_2 t_3^4 - t_1^4 t_2^2 t_3^4 - t_1^2 t_2^4 t_3^4 - t_1^3 t_2^4 t_3^4) \Big) / \\ & ((-1 + t_1)^3 (1 + t_1) (t_1 - t_2)^3 (-1 + t_2)^3 (1 + t_2) (t_1^3 - t_2^2) (t_1^2 - t_2^3) \\ & (t_1 - t_3)^2 (t_1^2 - t_3) (t_1^3 - t_3) (t_2 - t_3)^3 (t_1 t_2 - t_3) (-1 + t_3)^2 (t_1 + t_3) \\ & (t_2 + t_3) (-t_2^3 + t_1 t_3) (-t_2^2 + t_1^2 t_3) (t_1^2 - t_2 t_3) (t_1 - t_3^2)) \end{aligned}$$

In[242]:= T2311[t1_, t2_, t3_, u_, v_] :=

$$\begin{aligned} & \text{Det}[\text{DiagonalMatrix}[\{-u + 1, -t_1 * u + 1, -t_1^2 * u + 1, -t_2 * u + 1, -t_2^2 * u + 1, \\ & -t_3 * u + 1, -t_1 * t_3 * u + 1, -v + 1, (t_1 - v) / t_1, (t_1^2 - v) / t_1^2, \\ & (t_2 - v) / t_2, (t_2^2 - v) / t_2^2, (t_3 - v) / t_3, (t_1 * t_3 - v) / (t_1 * t_3)\}]] \end{aligned}$$

In[243]:= GT2311[t1_, t2_, t3_, u_, v_] := G2311[t1, t2, t3] * T2311[t1, t2, t3, u, v]

In[269]:= Solve[u1 * u2 == t1^2 && u3 * u4 == t2 * t3 / t1^2 &&

u0 * u3 == t2^3 / t1^2 && u0 * u4 == t3^3 / t1^2 && u2 * u4 == t3 && u0 * u2 == t2^2 &&

u4 * u5 == t1 * t3 / t2^2 && u1 * u5 == t1^3 / t2^2 && u1 * u4 == t3^3 / t2^2 &&

u0 * u5 == t1 && u1 * u3 == t2 && u0 * u1 == t3^2 && u3 * u5 == t1 * t2 / t3^2 &&

u2 * u5 == t1^3 / t3^2 && u2 * u3 == t2^3 / t3^2, {u0, u1, u2, u3, u4, u5}]

Out[269]:= $\left\{ \left\{ u_0 \rightarrow -\frac{t_2 t_3}{t_1}, u_1 \rightarrow -\frac{t_1 t_3}{t_2}, u_2 \rightarrow -\frac{t_1 t_2}{t_3}, u_3 \rightarrow -\frac{t_2^2}{t_1 t_3}, u_4 \rightarrow -\frac{t_3^2}{t_1 t_2}, u_5 \rightarrow -\frac{t_1^2}{t_2 t_3} \right\}, \right.$
 $\left. \left\{ u_0 \rightarrow \frac{t_2 t_3}{t_1}, u_1 \rightarrow \frac{t_1 t_3}{t_2}, u_2 \rightarrow \frac{t_1 t_2}{t_3}, u_3 \rightarrow \frac{t_2^2}{t_1 t_3}, u_4 \rightarrow \frac{t_3^2}{t_1 t_2}, u_5 \rightarrow \frac{t_1^2}{t_2 t_3} \right\} \right\}$

In[270]:= Together[G[$\frac{t_2 t_3}{t_1}, \frac{t_1 t_3}{t_2}, \frac{t_1 t_2}{t_3}, \frac{t_2^2}{t_1 t_3}, \frac{t_3^2}{t_1 t_2}, \frac{t_1^2}{t_2 t_3}$]]

Out[270]:=
$$\frac{1}{t_1^2 t_2^2 t_3^2}$$

$$\begin{aligned} & (-t_1^5 t_2^3 + t_1^6 t_2^3 - t_1^3 t_2^5 + t_1^5 t_2^5 + t_1^3 t_2^6 - t_1^6 t_2^6 + t_1^6 t_2 t_3 - t_1^7 t_2 t_3 - t_1^3 t_2^3 t_3 + \\ & t_1^4 t_2^3 t_3 + t_1^5 t_2^3 t_3 - t_1^6 t_2^3 t_3 + t_1^3 t_2^4 t_3 - t_1^4 t_2^4 t_3 - t_1^6 t_2^4 t_3 + t_1^7 t_2^4 t_3 + \\ & t_1^3 t_2^5 t_3 - t_1^5 t_2^5 t_3 + t_1 t_2^6 t_3 - t_1^3 t_2^6 t_3 - t_1^4 t_2^6 t_3 + t_1^6 t_2^6 t_3 - t_1 t_2^7 t_3 + \\ & t_1^4 t_2^7 t_3 + t_1^2 t_2^2 t_3^2 - t_1^5 t_2^2 t_3^2 - t_1^6 t_2^2 t_3^2 + t_1^7 t_2^2 t_3^2 - t_1^3 t_2^3 t_3^2 + \\ & t_1^5 t_2^3 t_3^2 - t_1^4 t_2^4 t_3^2 + t_1^5 t_2^4 t_3^2 + t_1^6 t_2^4 t_3^2 - t_1^7 t_2^4 t_3^2 - t_1^2 t_2^5 t_3^2 + \\ & t_1^3 t_2^5 t_3^2 + t_1^4 t_2^5 t_3^2 - t_1^5 t_2^5 t_3^2 - t_1^2 t_2^6 t_3^2 + t_1^4 t_2^6 t_3^2 + t_1^2 t_2^7 t_3^2 - \\ & t_1^4 t_2^7 t_3^2 - t_1^5 t_3^3 + t_1^6 t_3^3 - t_1^3 t_2 t_3^3 + t_1^4 t_2 t_3^3 + t_1^5 t_2 t_3^3 - t_1^6 t_2 t_3^3 - \\ & t_1^3 t_2^2 t_3^3 + t_1^5 t_2^2 t_3^3 - t_1 t_2^3 t_3^3 - t_1^2 t_2^3 t_3^3 + 5 t_1^3 t_2^3 t_3^3 - t_1^4 t_2^3 t_3^3 - \\ & t_1^5 t_2^3 t_3^3 - t_1^6 t_2^3 t_3^3 + t_1 t_2^4 t_3^3 - t_1^3 t_2^4 t_3^3 - t_1^4 t_2^4 t_3^3 + t_1^6 t_2^4 t_3^3 - t_2^5 t_3^3 + \\ & t_1 t_2^5 t_3^3 + t_1^2 t_2^5 t_3^3 - t_1^3 t_2^5 t_3^3 + t_2^6 t_3^3 - t_1 t_2^6 t_3^3 - t_1^3 t_2^6 t_3^3 + t_1^4 t_2^6 t_3^3 + \\ & t_1^3 t_2 t_3^4 - t_1^4 t_2 t_3^4 - t_1^6 t_2 t_3^4 + t_1^7 t_2 t_3^4 - t_1^4 t_2^2 t_3^4 + t_1^5 t_2^2 t_3^4 + t_1^6 t_2^2 t_3^4 - \\ & t_1^7 t_2^2 t_3^4 + t_1 t_2^3 t_3^4 - t_1^3 t_2^3 t_3^4 - t_1^4 t_2^3 t_3^4 + t_1^6 t_2^3 t_3^4 - t_1 t_2^4 t_3^4 - t_1^2 t_2^4 t_3^4 - \\ & t_1^3 t_2^4 t_3^4 + 5 t_1^4 t_2^4 t_3^4 - t_1^5 t_2^4 t_3^4 - t_1^6 t_2^4 t_3^4 + t_1^2 t_2^5 t_3^4 - t_1^4 t_2^5 t_3^4 - \\ & t_1 t_2^6 t_3^4 + t_1^2 t_2^6 t_3^4 + t_1^3 t_2^6 t_3^4 - t_1^4 t_2^6 t_3^4 + t_1 t_2^7 t_3^4 - t_1^2 t_2^7 t_3^4 - t_1^3 t_3^5 + \\ & t_1^5 t_3^5 + t_1^3 t_2 t_3^5 - t_1^5 t_2 t_3^5 - t_1^2 t_2^2 t_3^5 + t_1^3 t_2^2 t_3^5 + t_1^4 t_2^2 t_3^5 - t_1^5 t_2^2 t_3^5 - \\ & t_2^3 t_3^5 + t_1 t_2^3 t_3^5 + t_1^2 t_2^3 t_3^5 - t_1^3 t_2^3 t_3^5 + t_1^2 t_2^4 t_3^5 - t_1^4 t_2^4 t_3^5 + t_2^5 t_3^5 - \\ & t_1 t_2^5 t_3^5 - t_1^2 t_2^5 t_3^5 + t_1^5 t_2^5 t_3^5 + t_1^3 t_3^6 - t_1^6 t_3^6 + t_1 t_2 t_3^6 - t_1^3 t_2 t_3^6 - \\ & t_1^4 t_2 t_3^6 + t_1^6 t_2 t_3^6 - t_1^2 t_2^2 t_3^6 + t_1^4 t_2^2 t_3^6 + t_2^3 t_3^6 - t_1 t_2^3 t_3^6 - t_1^3 t_2^3 t_3^6 + \\ & t_1^4 t_2^3 t_3^6 - t_1 t_2^4 t_3^6 + t_1^2 t_2^4 t_3^6 + t_1^3 t_2^4 t_3^6 - t_1^4 t_2^4 t_3^6 - t_2^6 t_3^6 + t_1 t_2^6 t_3^6 - \\ & t_1 t_2 t_3^7 + t_1^4 t_2 t_3^7 + t_1^2 t_2^2 t_3^7 - t_1^4 t_2^2 t_3^7 + t_1 t_2^4 t_3^7 - t_1^2 t_2^4 t_3^7) \end{aligned}$$

In[271]:= G11311tangent[t1_, t2_, t3_] :=

Det[DiagonalMatrix[{-t2 + 1, -t3 + 1, -t1^2 + 1, (t1 - t2) / t1, (t1 - t3) / t1, -t1 + 1,
(t1^2 - t2 * t3) / t1^2, (-t2^3 + t1^2) / t1^2, (-t3^3 + t1^2) / t1^2,
-t1 + 1, -t3 + 1, -t2^2 + 1, (-t1 + t2) / t2, (t2^2 - t1 * t3) / t2^2,
(-t1^3 + t2^2) / t2^2, (t2 - t3) / t2, -t2 + 1, (-t3^3 + t2^2) / t2^2,
-t1 + 1, -t2 + 1, -t3^2 + 1, (-t1 * t2 + t3^2) / t3^2, (-t1 + t3) / t3,
(-t1^3 + t3^2) / t3^2, (-t2 + t3) / t3, (-t2^3 + t3^2) / t3^2, -t3 + 1}]]

In[272]:= Together[%270 / G11311tangent[t1, t2, t3]]

Out[272]=
$$-\left(\begin{aligned} & t_1^6 t_2^6 t_3^6 \\ & (-t_1^5 t_2^3 - t_1^5 t_2^4 - t_1^3 t_2^5 - t_1^4 t_2^5 - t_1^5 t_2^5 + t_1^6 t_2 t_3 + t_1^6 t_2^2 t_3 - t_1^3 t_2^3 t_3 + \\ & t_1^6 t_2^3 t_3 + t_1 t_2^6 t_3 + t_1^2 t_2^6 t_3 + t_1^3 t_2^6 t_3 + t_1^6 t_2 t_3^2 + t_1^2 t_2^2 t_3^2 + t_1^3 t_2^2 t_3^2 + \\ & t_1^4 t_2^2 t_3^2 + t_1^2 t_2^3 t_3^2 - t_1^3 t_2^3 t_3^2 + t_1^2 t_2^4 t_3^2 - t_1^4 t_2^4 t_3^2 + t_1 t_2^6 t_3^2 - \\ & t_1^5 t_3^3 - t_1^3 t_2 t_3^3 + t_1^6 t_2 t_3^3 + t_1^2 t_2^2 t_3^3 - t_1^3 t_2^2 t_3^3 - t_1 t_2^3 t_3^3 - \\ & t_1^2 t_2^3 t_3^3 + t_1^4 t_2^3 t_3^3 + t_1^5 t_2^3 t_3^3 + t_1^3 t_2^4 t_3^3 - t_1^4 t_2^4 t_3^3 - \\ & t_2^5 t_3^3 + t_1^3 t_2^5 t_3^3 + t_1 t_2^6 t_3^3 - t_1^5 t_3^4 + t_1^2 t_2^2 t_3^4 - t_1^4 t_2^2 t_3^4 + \\ & t_1^3 t_2^3 t_3^4 - t_1^4 t_2^3 t_3^4 - t_1^2 t_2^4 t_3^4 - t_1^3 t_2^4 t_3^4 - t_1^4 t_2^4 t_3^4 - \\ & t_2^5 t_3^4 - t_1^3 t_3^5 - t_1^4 t_3^5 - t_1^5 t_3^5 - t_2^3 t_3^5 + t_1^3 t_2^3 t_3^5 - t_2^4 t_3^5 - \\ & t_2^5 t_3^5 + t_1 t_2 t_3^6 + t_1^2 t_2 t_3^6 + t_1^3 t_2 t_3^6 + t_1 t_2^2 t_3^6 + t_1 t_2^3 t_3^6) \end{aligned} \right) /$$

$$\begin{aligned} & ((-1 + t_1)^3 (1 + t_1) (t_1 - t_2)^2 (-1 + t_2)^3 (1 + t_2) (t_1^3 - t_2^2) (t_1^2 - t_2^3) \\ & (t_1 - t_3)^2 (t_2 - t_3)^2 (-1 + t_3)^3 (1 + t_3) (-t_2^2 + t_1 t_3) (t_1^2 - t_2 t_3) \\ & (t_1^3 - t_3^2) (t_1 t_2 - t_3^2) (t_2^3 - t_3^2) (t_1^2 - t_3^3) (t_2^2 - t_3^3)) \end{aligned}$$

In[273]:= G11311[t1_, t2_, t3_] :=

$$-\left(\begin{aligned} & (t_1^6 t_2^6 t_3^6 (-t_1^5 t_2^3 - t_1^5 t_2^4 - t_1^3 t_2^5 - t_1^4 t_2^5 - t_1^5 t_2^5 + t_1^6 t_2 t_3 + t_1^6 t_2^2 t_3 - \\ & t_1^3 t_2^3 t_3 + t_1^6 t_2^3 t_3 + t_1 t_2^6 t_3 + t_1^2 t_2^6 t_3 + t_1^3 t_2^6 t_3 + t_1^6 t_2 t_3^2 + \\ & t_1^2 t_2^2 t_3^2 + t_1^3 t_2^2 t_3^2 + t_1^4 t_2^2 t_3^2 + t_1^2 t_2^3 t_3^2 - t_1^3 t_2^3 t_3^2 + t_1^2 t_2^4 t_3^2 - \\ & t_1^4 t_2^4 t_3^2 + t_1 t_2^6 t_3^2 - t_1^5 t_3^3 - t_1^3 t_2 t_3^3 + t_1^6 t_2 t_3^3 + t_1^2 t_2^2 t_3^3 - \\ & t_1^3 t_2^2 t_3^3 - t_1 t_2^3 t_3^3 - t_1^2 t_2^3 t_3^3 + t_1^4 t_2^3 t_3^3 + t_1^5 t_2^3 t_3^3 + t_1^3 t_2^4 t_3^3 - \\ & t_1^4 t_2^4 t_3^3 - t_2^5 t_3^3 + t_1^3 t_2^5 t_3^3 + t_1 t_2^6 t_3^3 - t_1^5 t_3^4 + t_1^2 t_2^2 t_3^4 - \\ & t_1^4 t_2^2 t_3^4 + t_1^3 t_2^3 t_3^4 - t_1^4 t_2^3 t_3^4 - t_1^2 t_2^4 t_3^4 - t_1^3 t_2^4 t_3^4 - t_1^4 t_2^4 t_3^4 - \\ & t_2^5 t_3^4 - t_1^3 t_3^5 - t_1^4 t_3^5 - t_1^5 t_3^5 - t_2^3 t_3^5 + t_1^3 t_2^3 t_3^5 - t_2^4 t_3^5 - \\ & t_2^5 t_3^5 + t_1 t_2 t_3^6 + t_1^2 t_2 t_3^6 + t_1^3 t_2 t_3^6 + t_1 t_2^2 t_3^6 + t_1 t_2^3 t_3^6) \end{aligned} \right) /$$

$$\begin{aligned} & ((-1 + t_1)^3 (1 + t_1) (t_1 - t_2)^2 (-1 + t_2)^3 (1 + t_2) (t_1^3 - t_2^2) (t_1^2 - t_2^3) \\ & (t_1 - t_3)^2 (t_2 - t_3)^2 (-1 + t_3)^3 (1 + t_3) (-t_2^2 + t_1 t_3) (t_1^2 - t_2 t_3) \\ & (t_1^3 - t_3^2) (t_1 t_2 - t_3^2) (t_2^3 - t_3^2) (t_1^2 - t_3^3) (t_2^2 - t_3^3)) \end{aligned}$$

In[274]:= T11311[t1_, t2_, t3_, u_, v_] :=

Det[DiagonalMatrix[{-u + 1, -t1 * u + 1, -t1^2 * u + 1, -t2 * u + 1, -t2^2 * u + 1, -t3 * u + 1, -t3^2 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2, (t2 - v) / t2, (t2^2 - v) / t2^2, (t3 - v) / t3, (t3^2 - v) / t3^2}]]

In[275]:= GT11311[t1_, t2_, t3_, u_, v_] := G11311[t1, t2, t3] * T11311[t1, t2, t3, u, v]

In[276]:= G1321[t1_, t2_, t3_] :=

$$\begin{aligned}
& - \left((t_1^8 t_2^8 t_3^2 (-t_1^8 t_2^6 - t_1^7 t_2^7 - t_1^8 t_2^7 - t_1^6 t_2^8 - t_1^7 t_2^8 - t_1^8 t_2^8 + t_1^6 t_2^4 t_3 + \right. \\
& \quad t_1^7 t_2^4 t_3 + t_1^9 t_2^4 t_3 + t_1^5 t_2^5 t_3 + 2 t_1^6 t_2^5 t_3 + t_1^8 t_2^5 t_3 + t_1^9 t_2^5 t_3 + \\
& \quad t_1^4 t_2^6 t_3 + 2 t_1^5 t_2^6 t_3 + t_1^7 t_2^6 t_3 + t_1^8 t_2^6 t_3 + t_1^9 t_2^6 t_3 + t_1^4 t_2^7 t_3 + \\
& \quad t_1^6 t_2^7 t_3 + t_1^7 t_2^7 t_3 + t_1^8 t_2^7 t_3 + t_1^5 t_2^8 t_3 + t_1^6 t_2^8 t_3 + t_1^7 t_2^8 t_3 + \\
& \quad t_1^4 t_2^9 t_3 + t_1^5 t_2^9 t_3 + t_1^6 t_2^9 t_3 - t_1^8 t_2^2 t_3^2 - t_1^3 t_2^3 t_3^2 - t_1^4 t_2^3 t_3^2 - \\
& \quad t_1^5 t_2^3 t_3^2 - 2 t_1^7 t_2^3 t_3^2 - t_1^8 t_2^3 t_3^2 - t_1^3 t_2^4 t_3^2 + t_1^5 t_2^4 t_3^2 - 3 t_1^6 t_2^4 t_3^2 - \\
& \quad 2 t_1^7 t_2^4 t_3^2 - t_1^3 t_2^5 t_3^2 + t_1^4 t_2^5 t_3^2 - 3 t_1^5 t_2^5 t_3^2 - 3 t_1^6 t_2^5 t_3^2 + \\
& \quad t_1^7 t_2^5 t_3^2 + t_1^8 t_2^5 t_3^2 - t_1^9 t_2^5 t_3^2 - 3 t_1^4 t_2^6 t_3^2 - 3 t_1^5 t_2^6 t_3^2 + t_1^6 t_2^6 t_3^2 + \\
& \quad 2 t_1^7 t_2^6 t_3^2 - 2 t_1^3 t_2^7 t_3^2 - 2 t_1^4 t_2^7 t_3^2 + t_1^5 t_2^7 t_3^2 + 2 t_1^6 t_2^7 t_3^2 - \\
& \quad t_1^7 t_2^7 t_3^2 - t_1^2 t_2^8 t_3^2 - t_1^3 t_2^8 t_3^2 + t_1^5 t_2^8 t_3^2 - t_1^5 t_2^9 t_3^2 + t_1^6 t_2 t_3^3 + \\
& \quad 2 t_1^5 t_2^2 t_3^3 - t_1^7 t_2^2 t_3^3 + 3 t_1^4 t_2^3 t_3^3 - 2 t_1^6 t_2^3 t_3^3 - t_1^9 t_2^3 t_3^3 + \\
& \quad 3 t_1^3 t_2^4 t_3^3 - t_1^4 t_2^4 t_3^3 - 4 t_1^5 t_2^4 t_3^3 + t_1^7 t_2^4 t_3^3 - 2 t_1^8 t_2^4 t_3^3 - t_1^9 t_2^4 t_3^3 + \\
& \quad 2 t_1^2 t_2^5 t_3^3 - 4 t_1^4 t_2^5 t_3^3 + 2 t_1^6 t_2^5 t_3^3 - 3 t_1^7 t_2^5 t_3^3 - 2 t_1^8 t_2^5 t_3^3 + \\
& \quad t_1 t_2^6 t_3^3 - 2 t_1^3 t_2^6 t_3^3 + 2 t_1^5 t_2^6 t_3^3 - 3 t_1^6 t_2^6 t_3^3 - 3 t_1^7 t_2^6 t_3^3 - t_1^2 t_2^7 t_3^3 + \\
& \quad t_1^4 t_2^7 t_3^3 - 3 t_1^5 t_2^7 t_3^3 - 3 t_1^6 t_2^7 t_3^3 - 2 t_1^4 t_2^8 t_3^3 - 2 t_1^5 t_2^8 t_3^3 - \\
& \quad t_1^3 t_2^9 t_3^3 - t_1^4 t_2^9 t_3^3 + t_1^4 t_2 t_3^4 + t_1^5 t_2 t_3^4 + t_1^7 t_2 t_3^4 + t_1^8 t_2 t_3^4 + \\
& \quad t_1^3 t_2^2 t_3^4 + t_1^4 t_2^2 t_3^4 - t_1^5 t_2^2 t_3^4 + t_1^6 t_2^2 t_3^4 + 3 t_1^7 t_2^2 t_3^4 + t_1^8 t_2^2 t_3^4 + \\
& \quad t_1^2 t_2^3 t_3^4 + t_1^3 t_2^3 t_3^4 - 2 t_1^4 t_2^3 t_3^4 + 2 t_1^5 t_2^3 t_3^4 + 6 t_1^6 t_2^3 t_3^4 + t_1^7 t_2^3 t_3^4 + \\
& \quad t_1 t_2^4 t_3^4 + t_1^2 t_2^4 t_3^4 - 2 t_1^3 t_2^4 t_3^4 + t_1^4 t_2^4 t_3^4 + 8 t_1^5 t_2^4 t_3^4 + 2 t_1^6 t_2^4 t_3^4 - \\
& \quad t_1^7 t_2^4 t_3^4 + t_1^8 t_2^4 t_3^4 + t_1 t_2^5 t_3^4 - t_1^2 t_2^5 t_3^4 + 2 t_1^3 t_2^5 t_3^4 + 8 t_1^4 t_2^5 t_3^4 + \\
& \quad t_1^5 t_2^5 t_3^4 - 2 t_1^6 t_2^5 t_3^4 + t_1^7 t_2^5 t_3^4 + t_1^8 t_2^5 t_3^4 + t_1^2 t_2^6 t_3^4 + 6 t_1^3 t_2^6 t_3^4 + \\
& \quad 2 t_1^4 t_2^6 t_3^4 - 2 t_1^5 t_2^6 t_3^4 + t_1^6 t_2^6 t_3^4 + t_1^7 t_2^6 t_3^4 + t_1 t_2^7 t_3^4 + 3 t_1^2 t_2^7 t_3^4 + \\
& \quad t_1^3 t_2^7 t_3^4 - t_1^4 t_2^7 t_3^4 + t_1^5 t_2^7 t_3^4 + t_1^6 t_2^7 t_3^4 + t_1 t_2^8 t_3^4 + t_1^2 t_2^8 t_3^4 + \\
& \quad t_1^4 t_2^8 t_3^4 + t_1^5 t_2^8 t_3^4 - t_1^5 t_3^5 - t_1^6 t_3^5 - 2 t_1^4 t_2 t_3^5 - 2 t_1^5 t_2 t_3^5 - \\
& \quad 3 t_1^3 t_2^2 t_3^5 - 3 t_1^4 t_2^2 t_3^5 + t_1^5 t_2^2 t_3^5 - t_1^7 t_2^2 t_3^5 - 3 t_1^2 t_2^3 t_3^5 - \\
& \quad 3 t_1^3 t_2^3 t_3^5 + 2 t_1^4 t_2^3 t_3^5 - 2 t_1^6 t_2^3 t_3^5 + t_1^8 t_2^3 t_3^5 - 2 t_1 t_2^4 t_3^5 - \\
& \quad 3 t_1^2 t_2^4 t_3^5 + 2 t_1^3 t_2^4 t_3^5 - 4 t_1^5 t_2^4 t_3^5 + 2 t_1^7 t_2^4 t_3^5 - t_2^5 t_3^5 - 2 t_1 t_2^5 t_3^5 + \\
& \quad t_1^2 t_2^5 t_3^5 - 4 t_1^4 t_2^5 t_3^5 - t_1^5 t_2^5 t_3^5 + 3 t_1^6 t_2^5 t_3^5 - t_2^6 t_3^5 - 2 t_1^3 t_2^6 t_3^5 + \\
& \quad 3 t_1^5 t_2^6 t_3^5 - t_1^2 t_2^7 t_3^5 + 2 t_1^4 t_2^7 t_3^5 + t_1^3 t_2^8 t_3^5 - t_1^4 t_3^6 + t_1^4 t_2 t_3^6 - \\
& \quad t_1^6 t_2 t_3^6 - t_1^7 t_2 t_3^6 - t_1^2 t_2^2 t_3^6 + 2 t_1^3 t_2^2 t_3^6 + t_1^4 t_2^2 t_3^6 - 2 t_1^5 t_2^2 t_3^6 - \\
& \quad 2 t_1^6 t_2^2 t_3^6 + 2 t_1^2 t_2^3 t_3^6 + t_1^3 t_2^3 t_3^6 - 3 t_1^4 t_2^3 t_3^6 - 3 t_1^5 t_2^3 t_3^6 - t_2^4 t_3^6 + \\
& \quad t_1 t_2^4 t_3^6 + t_1^2 t_2^4 t_3^6 - 3 t_1^3 t_2^4 t_3^6 - 3 t_1^4 t_2^4 t_3^6 + t_1^5 t_2^4 t_3^6 - t_1^6 t_2^4 t_3^6 - \\
& \quad 2 t_1^2 t_2^5 t_3^6 - 3 t_1^3 t_2^5 t_3^6 + t_1^4 t_2^5 t_3^6 - t_1^6 t_2^5 t_3^6 - t_1 t_2^6 t_3^6 - 2 t_1^2 t_2^6 t_3^6 - \\
& \quad t_1^4 t_2^6 t_3^6 - t_1^5 t_2^6 t_3^6 - t_1^6 t_2^6 t_3^6 - t_1 t_2^7 t_3^6 + t_1^3 t_3^7 + t_1^4 t_3^7 + t_1^5 t_3^7 + \\
& \quad t_1^2 t_2 t_3^7 + t_1^3 t_2 t_3^7 + t_1^4 t_2 t_3^7 + t_1 t_2^2 t_3^7 + t_1^2 t_2^2 t_3^7 + t_1^3 t_2^2 t_3^7 + \\
& \quad t_1^5 t_2^2 t_3^7 + t_2^3 t_3^7 + t_1 t_2^3 t_3^7 + t_1^2 t_2^3 t_3^7 + 2 t_1^4 t_2^3 t_3^7 + t_1^5 t_2^3 t_3^7 + t_2^4 t_3^7 + \\
& \quad t_1 t_2^4 t_3^7 + 2 t_1^3 t_2^4 t_3^7 + t_1^4 t_2^4 t_3^7 + t_2^5 t_3^7 + t_1^2 t_2^5 t_3^7 + t_1^3 t_2^5 t_3^7 - \\
& \quad t_1 t_2 t_3^8 - t_1^2 t_2 t_3^8 - t_1^3 t_2 t_3^8 - t_1 t_2^2 t_3^8 - t_1^2 t_2^2 t_3^8 - t_1 t_2^3 t_3^8) \Big) / \\
& \left((-1 + t_1)^3 (t_1^2 - t_2)^2 (-1 + t_2)^3 (t_1 - t_2^2)^2 (t_1^3 - t_2^2) (t_1^2 - t_2^3) \right. \\
& \quad (t_1 - t_3)^3 (t_1^3 - t_3) (t_2 - t_3)^3 (t_1^2 t_2 - t_3) (t_1 t_2^2 - t_3) (t_2^3 - t_3) \\
& \quad \left. (-1 + t_3)^2 (t_1 + t_3) (t_2 + t_3) (-t_2^2 + t_1 t_3) (t_1^2 - t_2 t_3) (t_1 t_2 - t_3^2) \right)
\end{aligned}$$

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In[277]:= T1321[t1_, t2_, t3_, u_, v_] :=
  Det[DiagonalMatrix[{-u+1, -t1*u+1, -t1^2*u+1, -t2*u+1, -t1*t2*u+1,
    -t2^2*u+1, -t3*u+1, -v+1, (t1-v)/t1, (t1^2-v)/t1^2,
    (t2-v)/t2, (t1*t2-v)/(t1*t2), (t2^2-v)/t2^2, (t3-v)/t3}]]

In[278]:= GT1321[t1_, t2_, t3_, u_, v_] := G1321[t1, t2, t3] * T1321[t1, t2, t3, u, v]

In[279]:= GT7smoothPointsContributions[t1_, t2_, t3_, u_, v_] :=
  {{(-1)/(t2-1), (-1)/(t3-1), (-1)/(t1^7-1), t1/(t1-t2),
    t1/(t1-t3), (-1)/(t1^6-1), t1^2/(t1^2-t2), t1^2/(t1^2-t3),
    (-1)/(t1^5-1), t1^3/(t1^3-t2), t1^3/(t1^3-t3), (-1)/(t1^4-1),
    t1^4/(t1^4-t2), t1^4/(t1^4-t3), (-1)/(t1^3-1), t1^5/(t1^5-t2),
    t1^5/(t1^5-t3), (-1)/(t1^2-1), t1^6/(t1^6-t2), t1^6/(t1^6-t3),
    (-1)/(t1-1), -u+1, -t1*u+1, -t1^2*u+1, -t1^3*u+1, -t1^4*u+1,
    -t1^5*u+1, -t1^6*u+1, -v+1, (t1-v)/t1, (t1^2-v)/t1^2,
    (t1^3-v)/t1^3, (t1^4-v)/t1^4, (t1^5-v)/t1^5, (t1^6-v)/t1^6},
  {(-1)/(t3-1), t1/(t1-t3), (-1)/(t2-1), (-1)/(t1^5-1),
    t1^2/(t1^2-t3), t1/(t1-t2), (-1)/(t1^4-1), t1^3/(t1^3-t3),
    t1^2/(t1^2-t2), (-1)/(t1^3-1), t1^4/(t1^4-t3), t1^3/(t1^3-t2),
    (-1)/(t1^2-1), t1^5/(t1^5-t3), t1^4/(t1^4-t2), (-1)/(t1-1),
    t1^5/(t1^5-t2^2), t2/(t2-t3), (-1)/(t1-1), (-t2)/(t1^6-t2),
    (-1)/(t2-1), -u+1, -t1*u+1, -t1^2*u+1, -t1^3*u+1, -t1^4*u+1,
    -t1^5*u+1, -t2*u+1, -v+1, (t1-v)/t1, (t1^2-v)/t1^2,
    (t1^3-v)/t1^3, (t1^4-v)/t1^4, (t1^5-v)/t1^5, (t2-v)/t2},
  {(-1)/(t3-1), t1/(t1-t3), t1^2/(t1^2-t3), (-1)/(t2-1),
    (-1)/(t1^3-1), t1^3/(t1^3-t3), t1/(t1-t2), (-1)/(t1^2-1),
    t1^3/(t1^3-t2^2), t1^4/(t1^4-t3), t1^2/(t1^2-t2), (-1)/(t1-1),
    t1^4/(t1^4-t2^2), t2/(t2-t3), (-1)/(t1^2-1), (-t2)/(t1^5-t2),
    (-1)/(t2-1), (t1*t2)/(t1*t2-t3), (-1)/(t1-1), (-t2)/(t1^4-t2),
    t1/(t1-t2), -u+1, -t1*u+1, -t1^2*u+1, -t1^3*u+1, -t1^4*u+1,
    -t2*u+1, -t1*t2*u+1, -v+1, (t1-v)/t1, (t1^2-v)/t1^2,
    (t1^3-v)/t1^3, (t1^4-v)/t1^4, (t2-v)/t2, (t1*t2-v)/(t1*t2)},
  {(-1)/(t3-1), t1/(t1-t3), (-1)/(t2-1), (-1)/(t1^4-1),
    t1^2/(t1^2-t3), t1/(t1-t2), (-1)/(t1^3-1), t1^3/(t1^3-t3),
    t1^2/(t1^2-t2), (-1)/(t1^2-1), t1^4/(t1^4-t3), t1^3/(t1^3-t2),
    (-1)/(t1-1), t1^4/(t1^4-t2^3), t2/(t2-t3), (-1)/(t1-1),
    (-1)/(t2^2-1), t2^2/(t2^2-t3), (-t2)/(t1-t2), (-t2^2)/(t1^5-t2^2),
    (-1)/(t2-1), -u+1, -t1*u+1, -t1^2*u+1, -t1^3*u+1, -t1^4*u+1,
    -t2*u+1, -t2^2*u+1, -v+1, (t1-v)/t1, (t1^2-v)/t1^2,
    (t1^3-v)/t1^3, (t1^4-v)/t1^4, (t2-v)/t2, (t2^2-v)/t2^2},
  {(-1)/(t3-1), t1/(t1-t3), (-1)/(t1^3-1), (-t1)/(t2^2-t1),
    t1^2/(t1^2-t3), (-1)/(t1^2-1), t1^2/(t1^2-t2^2),
    t1^3/(t1^3-t3), (-1)/(t1-1), (-1)/(t2-1), t1^3/(t1^3-t2^2),
    t2/(t2-t3), (-t2)/(t1^4-t2), (-1)/(t2-1), (t1*t2)/(t1*t2-t3),
    (-t2)/(t1^3-t2), t1/(t1-t2), (t1^2*t2)/(t1^2*t2-t3),
    (-t2)/(t1^2-t2), (-1)/(t1-1), t1^2/(t1^2-t2), -u+1,
    -t1*u+1, -t1^2*u+1, -t1^3*u+1, -t2*u+1, -t1*t2*u+1,
    -t1^2*t2*u+1, -v+1, (t1-v)/t1, (t1^2-v)/t1^2, (t1^3-v)/t1^3,

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(t2 - v) / t2, (t1 * t2 - v) / (t1 * t2), (t1^2 * t2 - v) / (t1^2 * t2)},
{(-1) / (t3 - 1), t1 / (t1 - t3), t1^2 / (t1^2 - t3), (-1) / (t2 - 1),
(-1) / (t1^2 - 1), t1^3 / (t1^3 - t3), t1 / (t1 - t2), (-1) / (t1 - 1),
t1^2 / (t1^2 - t2^2), t1^3 / (t1^3 - t2^3), t2 / (t2 - t3), (t1 * t2) / (t1 * t2 - t3),
(-1) / (t1 - 1), (-t2) / (t1^3 - t2), (-1) / (t2 - 1), (-t1) / (t2^2 - t1),
t2^2 / (t2^2 - t3), (-t2) / (t1^2 - t2), (-t2^2) / (t1^4 - t2^2), (-1) / (t1 - 1),
(-1) / (t2 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t1^3 * u + 1, -t2 * u + 1,
-t1 * t2 * u + 1, -t2^2 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t1^3 - v) / t1^3, (t2 - v) / t2, (t1 * t2 - v) / (t1 * t2), (t2^2 - v) / t2^2},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t2 - 1), (-1) / (t1^3 - 1),
t1^2 / (t1^2 - t3), t1 / (t1 - t2), (-1) / (t1^2 - 1), t1^3 / (t1^3 - t3),
t1^2 / (t1^2 - t2), (-1) / (t1 - 1), (-t1^3) / (t2^4 - t1^3), t2 / (t2 - t3),
(-1) / (t1 - 1), (-1) / (t2^3 - 1), t2^2 / (t2^2 - t3), (-t2) / (t1 - t2),
(-1) / (t2^2 - 1), t2^3 / (t2^3 - t3), t2^2 / (t2^2 - t1), (-t2^3) / (t1^4 - t2^3),
(-1) / (t2 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t1^3 * u + 1, -t2 * u + 1,
-t2^2 * u + 1, -t2^3 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t1^3 - v) / t1^3, (t2 - v) / t2, (t2^2 - v) / t2^2, (t2^3 - v) / t2^3},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t1^2 - 1), (-1) / (t2^2 - 1),
t1^2 / (t1^2 - t3), (-1) / (t1 - 1), (-t1) / (t2^2 - t1), (-t1^2) / (t2^3 - t1^2),
t2 / (t2 - t3), (-t2) / (t1^3 - t2), (t1 * t2) / (t1 * t2 - t3), (-t2) / (t1^2 - t2),
(-1) / (t2 - 1), (t1^2 * t2) / (t1^2 * t2 - t3), (-t2) / (t1 - t2), t1 / (t1 - t2),
t1^2 / (t1^2 - t2^2), t2^2 / (t2^2 - t3), (-t2^2) / (t1^3 - t2^2), (-1) / (t1 - 1),
(-1) / (t2 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1,
-t1^2 * t2 * u + 1, -t2^2 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2, (t2 - v) / t2,
(t1 * t2 - v) / (t1 * t2), (t1^2 * t2 - v) / (t1^2 * t2), (t2^2 - v) / t2^2},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t1^2 - 1), (-t1) / (t2^3 - t1),
t1^2 / (t1^2 - t3), (-1) / (t1 - 1), (-1) / (t2 - 1), (-t1^2) / (t2^3 - t1^2),
t2 / (t2 - t3), (-1) / (t2^2 - 1), (t1 * t2) / (t1 * t2 - t3),
(-t2) / (t1^2 - t2), (-1) / (t1 - 1), (-t1) / (t2^2 - t1), t2^2 / (t2^2 - t3),
(-t2^2) / (t1^3 - t2^2), (-1) / (t2 - 1), (t1 * t2^2) / (t1 * t2^2 - t3),
(-t2^2) / (t1^2 - t2^2), (-t2) / (t1 - t2), t1 / (t1 - t2), -u + 1,
-t1 * u + 1, -t1^2 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1, -t2^2 * u + 1,
-t1 * t2^2 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2, (t2 - v) / t2,
(t1 * t2 - v) / (t1 * t2), (t2^2 - v) / t2^2, (t1 * t2^2 - v) / (t1 * t2^2)},
{(-1) / (t3 - 1), t1 / (t1 - t3), t1^2 / (t1^2 - t3), (-1) / (t1 - 1),
(-1) / (t2 - 1), (-t1) / (t2^2 - t1), (-t1^2) / (t2^4 - t1^2), t2 / (t2 - t3),
(t1 * t2) / (t1 * t2 - t3), (-t2) / (t1^2 - t2), (-1) / (t1 - 1), (-1) / (t2 - 1),
(-t1) / (t2^3 - t1), t2^2 / (t2^2 - t3), (-1) / (t1 - 1), (-1) / (t2^2 - 1),
t2^3 / (t2^3 - t3), (-t2^3) / (t1^3 - t2^3), (-t2^2) / (t1^2 - t2^2),
(-t2) / (t1 - t2), (-1) / (t2 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t2 * u + 1,
-t1 * t2 * u + 1, -t2^2 * u + 1, -t2^3 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t2 - v) / t2, (t1 * t2 - v) / (t1 * t2), (t2^2 - v) / t2^2, (t2^3 - v) / t2^3},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t2 - 1), (-1) / (t1^2 - 1),
t1^2 / (t1^2 - t3), t1 / (t1 - t2), (-1) / (t1 - 1), (-t1^2) / (t2^5 - t1^2),
t2 / (t2 - t3), (-1) / (t1 - 1), (-1) / (t2^4 - 1), t2^2 / (t2^2 - t3),
(-t2) / (t1 - t2), (-1) / (t2^3 - 1), t2^3 / (t2^3 - t3), t2^2 / (t2^2 - t1),
(-1) / (t2^2 - 1), t2^4 / (t2^4 - t3), t2^3 / (t2^3 - t1), t2^4 / (t2^4 - t1^3)},

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(-1) / (t2 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t2 * u + 1, -t2^2 * u + 1,
-t2^3 * u + 1, -t2^4 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t2 - v) / t2, (t2^2 - v) / t2^2, (t2^3 - v) / t2^3, (t2^4 - v) / t2^4},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t1 - 1), (-1) / (t2^3 - 1),
(-t1) / (t2^4 - t1), t2 / (t2 - t3), (-t2) / (t1^2 - t2), (t1 * t2) / (t1 * t2 - t3),
(-t2) / (t1 - t2), (-1) / (t2^2 - 1), (-t1) / (t2^3 - t1),
t2^2 / (t2^2 - t3), (-t2^2) / (t1^2 - t2^2), (t1 * t2^2) / (t1 * t2^2 - t3),
t2^2 / (t2^2 - t1), (-1) / (t2 - 1), (-t1) / (t2^2 - t1), t2^3 / (t2^3 - t3),
t2^3 / (t2^3 - t1^2), (-1) / (t1 - 1), (-1) / (t2 - 1), -u + 1,
-t1 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1, -t2^2 * u + 1, -t1 * t2^2 * u + 1,
-t2^3 * u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2, (t1 * t2 - v) / (t1 * t2),
(t2^2 - v) / t2^2, (t1 * t2^2 - v) / (t1 * t2^2), (t2^3 - v) / t2^3},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t1 - 1), (-1) / (t2^2 - 1),
(-t1) / (t2^5 - t1), t2 / (t2 - t3), (t1 * t2) / (t1 * t2 - t3), (-t2) / (t1 - t2),
(-1) / (t2 - 1), (-t1) / (t2^4 - t1), t2^2 / (t2^2 - t3), (-1) / (t1 - 1),
(-1) / (t2^3 - 1), t2^3 / (t2^3 - t3), t2^3 / (t2^3 - t1^2), (-t2) / (t1 - t2),
(-1) / (t2^2 - 1), t2^4 / (t2^4 - t3), t2^4 / (t2^4 - t1^2), t2^2 / (t2^2 - t1),
(-1) / (t2 - 1), -u + 1, -t1 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1, -t2^2 * u + 1,
-t2^3 * u + 1, -t2^4 * u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2,
(t1 * t2 - v) / (t1 * t2), (t2^2 - v) / t2^2, (t2^3 - v) / t2^3, (t2^4 - v) / t2^4},
{(-1) / (t3 - 1), t1 / (t1 - t3), (-1) / (t1 - 1), (-1) / (t2 - 1),
(-t1) / (t2^6 - t1), t2 / (t2 - t3), (-1) / (t1 - 1), (-1) / (t2^5 - 1),
t2^2 / (t2^2 - t3), (-t2) / (t1 - t2), (-1) / (t2^4 - 1), t2^3 / (t2^3 - t3),
t2^2 / (t2^2 - t1), (-1) / (t2^3 - 1), t2^4 / (t2^4 - t3), t2^3 / (t2^3 - t1),
(-1) / (t2^2 - 1), t2^5 / (t2^5 - t3), t2^5 / (t2^5 - t1^2), t2^4 / (t2^4 - t1),
(-1) / (t2 - 1), -u + 1, -t1 * u + 1, -t2 * u + 1, -t2^2 * u + 1, -t2^3 * u + 1,
-t2^4 * u + 1, -t2^5 * u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2,
(t2^2 - v) / t2^2, (t2^3 - v) / t2^3, (t2^4 - v) / t2^4, (t2^5 - v) / t2^5},
{(-1) / (t1 - 1), (-1) / (t3 - 1), (-1) / (t2^7 - 1), (-t2) / (t1 - t2),
t2 / (t2 - t3), (-1) / (t2^6 - 1), t2^2 / (t2^2 - t1), t2^2 / (t2^2 - t3),
(-1) / (t2^5 - 1), t2^3 / (t2^3 - t1), t2^3 / (t2^3 - t3), (-1) / (t2^4 - 1),
t2^4 / (t2^4 - t1), t2^4 / (t2^4 - t3), (-1) / (t2^3 - 1), t2^5 / (t2^5 - t1),
t2^5 / (t2^5 - t3), (-1) / (t2^2 - 1), t2^6 / (t2^6 - t1), t2^6 / (t2^6 - t3),
(-1) / (t2 - 1), -u + 1, -t2 * u + 1, -t2^2 * u + 1, -t2^3 * u + 1, -t2^4 * u + 1,
-t2^5 * u + 1, -t2^6 * u + 1, -v + 1, (t2 - v) / t2, (t2^2 - v) / t2^2,
(t2^3 - v) / t2^3, (t2^4 - v) / t2^4, (t2^5 - v) / t2^5, (t2^6 - v) / t2^6},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t3 - 1), (-1) / (t1^5 - 1),
t1^2 / (t1^2 - t2), t1 / (t1 - t3), (-1) / (t1^4 - 1), t1^3 / (t1^3 - t2),
t1^2 / (t1^2 - t3), (-1) / (t1^3 - 1), t1^4 / (t1^4 - t2), t1^3 / (t1^3 - t3),
(-1) / (t1^2 - 1), t1^5 / (t1^5 - t2), t1^4 / (t1^4 - t3), (-1) / (t1 - 1),
t1^5 / (t1^5 - t3^2), (-t3) / (t2 - t3), (-1) / (t1 - 1), (-t3) / (t1^6 - t3),
(-1) / (t3 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t1^3 * u + 1, -t1^4 * u + 1,
-t1^5 * u + 1, -t3 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t1^3 - v) / t1^3, (t1^4 - v) / t1^4, (t1^5 - v) / t1^5, (t3 - v) / t3},
{(-1) / (t3 - 1), (-1) / (t1^2 - 1), (-t1) / (t2^2 - t1), t1 / (t1 - t3), (-1) / (t1 - 1),
t1^2 / (t1^2 - t2^2), (-t2) / (t1^3 - t2), (-1) / (t2 - 1), t2 / (t2 - t3),
(-t2) / (t1^2 - t2), t1 / (t1 - t2), (t1 * t2) / (t1 * t2 - t3), (-t2) / (t1 - t2),

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t1^2 / (t1^2 - t2), t1^2 / (t1^2 - t3), (t1^2 * t2) / (t1^2 * t2 - t3^2),
(-1) / (t1 - 1), (-t3) / (t1^3 - t3), (-t3) / (t2^2 - t3), (-1) / (t2 - 1),
(-1) / (t3 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1,
-t1^2 * t2 * u + 1, -t3 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t2 - v) / t2, (t1 * t2 - v) / (t1 * t2), (t1^2 * t2 - v) / (t1^2 * t2), (t3 - v) / t3,
{(-1) / (t1 - 1), (-1) / (t3 - 1), (-t1) / (t2^3 - t1), (-t2) / (t1^2 - t2),
(-1) / (t2^2 - 1), (-t2) / (t1 - t2), t2 / (t2 - t3), t1 / (t1 - t3),
(-t1) / (t2^2 - t1), (-t2^2) / (t1^2 - t2^2), (-1) / (t2 - 1),
t2^2 / (t2^2 - t1), t2^2 / (t2^2 - t3), (t1 * t2) / (t1 * t2 - t3),
t1 / (t1 - t2), (t1 * t2^2) / (t1 * t2^2 - t3^2), (-t3) / (t1^2 - t3),
(-1) / (t1 - 1), (-1) / (t2 - 1), (-t3) / (t2^3 - t3), (-1) / (t3 - 1), -u + 1,
-t1 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1, -t2^2 * u + 1, -t1 * t2^2 * u + 1,
-t3 * u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2, (t1 * t2 - v) / (t1 * t2),
(t2^2 - v) / t2^2, (t1 * t2^2 - v) / (t1 * t2^2), (t3 - v) / t3},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t3 - 1), (-1) / (t2^5 - 1),
t2^2 / (t2^2 - t1), t2 / (t2 - t3), (-1) / (t2^4 - 1), t2^3 / (t2^3 - t1),
t2^2 / (t2^2 - t3), (-1) / (t2^3 - 1), t2^4 / (t2^4 - t1), t2^3 / (t2^3 - t3),
(-1) / (t2^2 - 1), t2^5 / (t2^5 - t1), t2^4 / (t2^4 - t3), (-1) / (t2 - 1),
t2^5 / (t2^5 - t3^2), (-t3) / (t1 - t3), (-1) / (t2 - 1), (-t3) / (t2^6 - t3),
(-1) / (t3 - 1), -u + 1, -t2 * u + 1, -t2^2 * u + 1, -t2^3 * u + 1, -t2^4 * u + 1,
-t2^5 * u + 1, -t3 * u + 1, -v + 1, (t2 - v) / t2, (t2^2 - v) / t2^2,
(t2^3 - v) / t2^3, (t2^4 - v) / t2^4, (t2^5 - v) / t2^5, (t3 - v) / t3},
{(-1) / (t2 - 1), t1 / (t1 - t2), t1^2 / (t1^2 - t2), (-1) / (t3 - 1),
(-1) / (t1^3 - 1), t1^3 / (t1^3 - t2), t1 / (t1 - t3), (-1) / (t1^2 - 1),
t1^3 / (t1^3 - t3^2), t1^4 / (t1^4 - t2), t1^2 / (t1^2 - t3), (-1) / (t1 - 1),
t1^4 / (t1^4 - t3^2), (-t3) / (t2 - t3), (-1) / (t1^2 - 1), (-t3) / (t1^5 - t3),
(-1) / (t3 - 1), (t1 * t3) / (t1 * t3 - t2), (-1) / (t1 - 1), (-t3) / (t1^4 - t3),
t1 / (t1 - t3), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t1^3 * u + 1, -t1^4 * u + 1,
-t3 * u + 1, -t1 * t3 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t1^3 - v) / t1^3, (t1^4 - v) / t1^4, (t3 - v) / t3, (t1 * t3 - v) / (t1 * t3)},
{(-1) / (t2 - 1), (-1) / (t3 - 1), (-1) / (t1^3 - 1), t1 / (t1 - t2), t1 / (t1 - t3),
(-1) / (t1^2 - 1), t1^2 / (t1^2 - t2), t1^2 / (t1^2 - t3), (-1) / (t1 - 1),
t1^3 / (t1^3 - t2^2), t1^3 / (t1^3 - t3^2), (-1) / (t1 - 1), (-1) / (t2 - 1),
(-t2) / (t3^2 - t2), (-t3) / (t2^2 - t3), (-1) / (t3 - 1), (-t3) / (t1 - t3),
(-t2) / (t1 - t2), (-t2 * t3) / (t1^4 - t2 * t3), (-t3) / (t2 - t3),
t2 / (t2 - t3), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t1^3 * u + 1, -t2 * u + 1,
-t3 * u + 1, -t2 * t3 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t1^3 - v) / t1^3, (t2 - v) / t2, (t3 - v) / t3, (t2 * t3 - v) / (t2 * t3)},
{(-1) / (t3 - 1), (-t1) / (t2^2 - t1), t1 / (t1 - t3), (-1) / (t1 - 1), (-1) / (t2 - 1),
t1^2 / (t1^2 - t2^2), t1^2 / (t1^2 - t3^2), (-1) / (t2 - 1), t2 / (t2 - t3),
(-t2) / (t1^2 - t2), (-1) / (t1 - 1), t1 / (t1 - t2), (t1 * t2) / (t1 * t2 - t3^2),
(-1) / (t1 - 1), (-t3) / (t2^2 - t3), (-1) / (t3 - 1), (-t2) / (t1 - t2),
(-t2 * t3) / (t1^3 - t2 * t3), (-t3) / (t1^2 - t3), (-t3) / (t2 - t3),
t2 / (t2 - t3), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1,
-t3 * u + 1, -t2 * t3 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t2 - v) / t2, (t1 * t2 - v) / (t1 * t2), (t3 - v) / t3, (t2 * t3 - v) / (t2 * t3)},
{(-1) / (t1 - 1), (-t2) / (t1^2 - t2), (-1) / (t3 - 1), (-t2) / (t1 - t2),

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t1 / (t1 - t3), (-1) / (t2 - 1), (-t1) / (t2^2 - t1), (t1 * t2) / (t1 * t2 - t3^2),
(-t2^2) / (t1^2 - t2^2), t2 / (t2 - t3), (-1) / (t1 - 1), (-1) / (t2 - 1),
t2^2 / (t2^2 - t3^2), (-t3) / (t1^2 - t3), (-1) / (t2 - 1), (-1) / (t3 - 1),
(-t3) / (t1 - t3), t1 / (t1 - t2), (-t3) / (t2^2 - t3), (-t1 * t3) / (t2^3 - t1 * t3),
t1 / (t1 - t3), -u + 1, -t1 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1, -t2^2 * u + 1,
-t3 * u + 1, -t1 * t3 * u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2,
(t1 * t2 - v) / (t1 * t2), (t2^2 - v) / t2^2, (t3 - v) / t3, (t1 * t3 - v) / (t1 * t3)},
{(-1) / (t1 - 1), (-1) / (t2 - 1), (-t1) / (t3^2 - t1), (-1) / (t1 - 1),
(-1) / (t3 - 1), (-1) / (t2^3 - 1), (-t2) / (t1 - t2), t2 / (t2 - t3),
(-1) / (t2^2 - 1), t2^3 / (t2^3 - t1^2), t2^2 / (t2^2 - t1), t2^2 / (t2^2 - t3),
(-1) / (t2 - 1), t2^3 / (t2^3 - t3^2), (-t3) / (t1^2 - t3), (-1) / (t3 - 1),
(-t3) / (t1 - t3), (-t3) / (t2 - t3), t1 / (t1 - t2), (-t1 * t3) / (t2^4 - t1 * t3),
t1 / (t1 - t3), -u + 1, -t1 * u + 1, -t2 * u + 1, -t2^2 * u + 1, -t2^3 * u + 1,
-t3 * u + 1, -t1 * t3 * u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2,
(t2^2 - v) / t2^2, (t2^3 - v) / t2^3, (t3 - v) / t3, (t1 * t3 - v) / (t1 * t3)},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), t2^2 / (t2^2 - t1), (-1) / (t3 - 1),
(-1) / (t2^3 - 1), t2^3 / (t2^3 - t1), t2 / (t2 - t3), (-1) / (t2^2 - 1),
t2^3 / (t2^3 - t3^2), t2^4 / (t2^4 - t1), t2^2 / (t2^2 - t3), (-1) / (t2 - 1),
t2^4 / (t2^4 - t3^2), (-t3) / (t1 - t3), (-1) / (t2^2 - 1), (-t3) / (t2^5 - t3),
(-1) / (t3 - 1), (t2 * t3) / (t2 * t3 - t1), (-1) / (t2 - 1), (-t3) / (t2^4 - t3),
t2 / (t2 - t3), -u + 1, -t2 * u + 1, -t2^2 * u + 1, -t2^3 * u + 1, -t2^4 * u + 1,
-t3 * u + 1, -t2 * t3 * u + 1, -v + 1, (t2 - v) / t2, (t2^2 - v) / t2^2,
(t2^3 - v) / t2^3, (t2^4 - v) / t2^4, (t3 - v) / t3, (t2 * t3 - v) / (t2 * t3)},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t3 - 1), (-1) / (t1^4 - 1),
t1^2 / (t1^2 - t2), t1 / (t1 - t3), (-1) / (t1^3 - 1), t1^3 / (t1^3 - t2),
t1^2 / (t1^2 - t3), (-1) / (t1^2 - 1), t1^4 / (t1^4 - t2), t1^3 / (t1^3 - t3),
(-1) / (t1 - 1), t1^4 / (t1^4 - t3^3), (-t3) / (t2 - t3), (-1) / (t1 - 1),
(-1) / (t3^2 - 1), t3^2 / (t3^2 - t2), (-t3) / (t1 - t3), (-t3^2) / (t1^5 - t3^2),
(-1) / (t3 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t1^3 * u + 1, -t1^4 * u + 1,
-t3 * u + 1, -t3^2 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t1^3 - v) / t1^3, (t1^4 - v) / t1^4, (t3 - v) / t3, (t3^2 - v) / t3^2},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t3 - 1), (-1) / (t2^4 - 1),
t2^2 / (t2^2 - t1), t2 / (t2 - t3), (-1) / (t2^3 - 1), t2^3 / (t2^3 - t1),
t2^2 / (t2^2 - t3), (-1) / (t2^2 - 1), t2^4 / (t2^4 - t1), t2^3 / (t2^3 - t3),
(-1) / (t2 - 1), t2^4 / (t2^4 - t3^3), (-t3) / (t1 - t3), (-1) / (t2 - 1),
(-1) / (t3^2 - 1), t3^2 / (t3^2 - t1), (-t3) / (t2 - t3), (-t3^2) / (t2^5 - t3^2),
(-1) / (t3 - 1), -u + 1, -t2 * u + 1, -t2^2 * u + 1, -t2^3 * u + 1, -t2^4 * u + 1,
-t3 * u + 1, -t3^2 * u + 1, -v + 1, (t2 - v) / t2, (t2^2 - v) / t2^2,
(t2^3 - v) / t2^3, (t2^4 - v) / t2^4, (t3 - v) / t3, (t3^2 - v) / t3^2},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t1^3 - 1), (-t1) / (t3^2 - t1),
t1^2 / (t1^2 - t2), (-1) / (t1^2 - 1), t1^2 / (t1^2 - t3^2), t1^3 / (t1^3 - t2),
(-1) / (t1 - 1), (-1) / (t3 - 1), t1^3 / (t1^3 - t3^2), (-t3) / (t2 - t3),
(-t3) / (t1^4 - t3), (-1) / (t3 - 1), (t1 * t3) / (t1 * t3 - t2),
(-t3) / (t1^3 - t3), t1 / (t1 - t3), (t1^2 * t3) / (t1^2 * t3 - t2),
(-t3) / (t1^2 - t3), (-1) / (t1 - 1), t1^2 / (t1^2 - t3), -u + 1,
-t1 * u + 1, -t1^2 * u + 1, -t1^3 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1,
-t1^2 * t3 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2, (t1^3 - v) / t1^3,

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(t3 - v) / t3, (t1 * t3 - v) / (t1 * t3), (t1^2 * t3 - v) / (t1^2 * t3)},
{(-1) / (t2 - 1), (-1) / (t1^2 - 1), (-t1) / (t3^2 - t1), t1 / (t1 - t2),
(-1) / (t1 - 1), t1^2 / (t1^2 - t3^2), (-1) / (t1 - 1), (-t2) / (t1^3 - t2),
(-1) / (t2 - 1), (-1) / (t3 - 1), (-t2) / (t3^2 - t2), (-t3) / (t1^3 - t3),
(-1) / (t3 - 1), (-t3) / (t2 - t3), (-t3) / (t1^2 - t3), t1 / (t1 - t3),
(t1 * t3) / (t1 * t3 - t2), (-t3) / (t1 - t3), (t1^2 * t3) / (t1^2 * t3 - t2^2),
t1^2 / (t1^2 - t2), t1^2 / (t1^2 - t3), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t2 * u + 1,
-t3 * u + 1, -t1 * t3 * u + 1, -t1^2 * t3 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t2 - v) / t2, (t3 - v) / t3, (t1 * t3 - v) / (t1 * t3), (t1^2 * t3 - v) / (t1^2 * t3)},
{(-1) / (t2 - 1), (-t1) / (t3^2 - t1), t1 / (t1 - t2), (-1) / (t1 - 1),
(-1) / (t3 - 1), t1^2 / (t1^2 - t2^2), t1^2 / (t1^2 - t3^2), (-1) / (t1 - 1),
(-1) / (t2 - 1), (-t2) / (t3^2 - t2), (-1) / (t3 - 1), (-t3) / (t2 - t3),
(-t3) / (t1^2 - t3), (-1) / (t1 - 1), (-t1 * t3) / (t2^2 - t1 * t3), t1 / (t1 - t3),
(-t3) / (t1 - t3), (-t2 * t3) / (t1^3 - t2 * t3), (-t2) / (t1^2 - t2),
(-t3) / (t2 - t3), t2 / (t2 - t3), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t2 * u + 1,
-t3 * u + 1, -t1 * t3 * u + 1, -t2 * t3 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t2 - v) / t2, (t3 - v) / t3, (t1 * t3 - v) / (t1 * t3), (t2 * t3 - v) / (t2 * t3)},
{(-1) / (t1 - 1), (-t1) / (t2^2 - t1), (-t1) / (t3^2 - t1), (-t2) / (t1^2 - t2),
(-1) / (t2 - 1), (-t2) / (t3^2 - t2), (-t2) / (t1 - t2), t1 / (t1 - t2), (-1) / (t3 - 1),
(t1 * t2) / (t1 * t2 - t3^2), (-t3) / (t1^2 - t3), (-t3) / (t2^2 - t3), (-1) / (t3 - 1),
(-t3) / (t1 - t3), (-t1 * t3) / (t2^2 - t1 * t3), (-1) / (t2 - 1), t1 / (t1 - t3),
(-t2 * t3) / (t1^2 - t2 * t3), (-t3) / (t2 - t3), (-1) / (t1 - 1), t2 / (t2 - t3),
-u + 1, -t1 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1,
-t2 * t3 * u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2, (t1 * t2 - v) / (t1 * t2),
(t3 - v) / t3, (t1 * t3 - v) / (t1 * t3), (t2 * t3 - v) / (t2 * t3)},
{(-1) / (t1 - 1), (-1) / (t2 - 1), (-t1) / (t3^2 - t1), (-1) / (t1 - 1),
(-t2) / (t3^2 - t2), (-t2^2) / (t1^2 - t2^2), (-t2) / (t1 - t2), (-1) / (t2 - 1),
(-1) / (t3 - 1), t2^2 / (t2^2 - t3^2), (-1) / (t3 - 1), (-t3) / (t1 - t3),
(-t3) / (t2 - t3), (-t1 * t3) / (t2^3 - t1 * t3), (-t1) / (t2^2 - t1), t1 / (t1 - t3),
(-t2 * t3) / (t1^2 - t2 * t3), (-t3) / (t1 - t3), (-t3) / (t2^2 - t3),
(-1) / (t2 - 1), t2 / (t2 - t3), -u + 1, -t1 * u + 1, -t2 * u + 1, -t2^2 * u + 1,
-t3 * u + 1, -t1 * t3 * u + 1, -t2 * t3 * u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2,
(t2^2 - v) / t2^2, (t3 - v) / t3, (t1 * t3 - v) / (t1 * t3), (t2 * t3 - v) / (t2 * t3)},
{(-1) / (t1 - 1), (-1) / (t2 - 1), (-1) / (t3 - 1), (-t1) / (t2^3 - t1),
(-t1) / (t3^2 - t1), (-1) / (t1 - 1), (-1) / (t2^2 - 1), (-t2) / (t3^2 - t2),
(-t2) / (t1 - t2), (-1) / (t2 - 1), t2^2 / (t2^2 - t3^2), (-t3) / (t2^3 - t3),
(-1) / (t3 - 1), (-t3) / (t1 - t3), (-t3) / (t2^2 - t3), t2 / (t2 - t3),
(t2^2 * t3) / (t2^2 * t3 - t1^2), (t2 * t3) / (t2 * t3 - t1),
t2^2 / (t2^2 - t1), (-t3) / (t2 - t3), t2^2 / (t2^2 - t3), -u + 1,
-t1 * u + 1, -t2 * u + 1, -t2^2 * u + 1, -t3 * u + 1, -t2 * t3 * u + 1,
-t2^2 * t3 * u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2, (t2^2 - v) / t2^2,
(t3 - v) / t3, (t2 * t3 - v) / (t2 * t3), (t2^2 * t3 - v) / (t2^2 * t3)},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t2^3 - 1), (-t2) / (t3^2 - t2),
t2^2 / (t2^2 - t1), (-1) / (t2^2 - 1), t2^2 / (t2^2 - t3^2), t2^3 / (t2^3 - t1),
(-1) / (t2 - 1), (-1) / (t3 - 1), t2^3 / (t2^3 - t3^2), (-t3) / (t1 - t3),
(-t3) / (t2^4 - t3), (-1) / (t3 - 1), (t2 * t3) / (t2 * t3 - t1),
(-t3) / (t2^3 - t3), t2 / (t2 - t3), (t2^2 * t3) / (t2^2 * t3 - t1),

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(-t3) / (t2^2 - t3), (-1) / (t2 - 1), t2^2 / (t2^2 - t3), -u + 1,
-t2*u + 1, -t2^2*u + 1, -t2^3*u + 1, -t3*u + 1, -t2*t3*u + 1,
-t2^2*t3*u + 1, -v + 1, (t2 - v) / t2, (t2^2 - v) / t2^2, (t2^3 - v) / t2^3,
(t3 - v) / t3, (t2*t3 - v) / (t2*t3), (t2^2*t3 - v) / (t2^2*t3)},
{(-1) / (t2 - 1), t1 / (t1 - t2), t1^2 / (t1^2 - t2), (-1) / (t3 - 1), (-1) / (t1^2 - 1),
t1^3 / (t1^3 - t2), t1 / (t1 - t3), (-1) / (t1 - 1), t1^2 / (t1^2 - t3^2),
t1^3 / (t1^3 - t3^3), (-t3) / (t2 - t3), (t1*t3) / (t1*t3 - t2),
(-1) / (t1 - 1), (-t3) / (t1^3 - t3), (-1) / (t3 - 1), (-t1) / (t3^2 - t1),
t3^2 / (t3^2 - t2), (-t3) / (t1^2 - t3), (-t3^2) / (t1^4 - t3^2), (-1) / (t1 - 1),
(-1) / (t3 - 1), -u + 1, -t1*u + 1, -t1^2*u + 1, -t1^3*u + 1, -t3*u + 1,
-t1*t3*u + 1, -t3^2*u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t1^3 - v) / t1^3, (t3 - v) / t3, (t1*t3 - v) / (t1*t3), (t3^2 - v) / t3^2},
{(-1) / (t1 - 1), (-1) / (t3 - 1), (-t1) / (t2^2 - t1), (-1) / (t2 - 1),
(-t2) / (t1 - t2), t2 / (t2 - t3), t1 / (t1 - t2), (-t1) / (t3^2 - t1),
(-t1*t2) / (t3^3 - t1*t2), (-1) / (t1 - 1), (-t3) / (t2^2 - t3),
(-t2*t3) / (t1^2 - t2*t3), (-t2) / (t1 - t2), (-t3) / (t2 - t3),
(-1) / (t3 - 1), (-t2) / (t3^2 - t2), (-t3^2) / (t1^2 - t3^2),
(-t3) / (t1 - t3), (-t3^2) / (t2^2 - t3^2), (-1) / (t2 - 1), (-1) / (t3 - 1),
-u + 1, -t1*u + 1, -t2*u + 1, -t1*t2*u + 1, -t3*u + 1, -t2*t3*u + 1,
-t3^2*u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2, (t1*t2 - v) / (t1*t2),
(t3 - v) / t3, (t2*t3 - v) / (t2*t3), (t3^2 - v) / t3^2},
{(-1) / (t1 - 1), (-t2) / (t1^2 - t2), (-1) / (t2 - 1), (-1) / (t3 - 1),
(-t2) / (t1 - t2), t1 / (t1 - t2), t1 / (t1 - t3), (-t2) / (t3^2 - t2),
(-t1*t2) / (t3^3 - t1*t2), (-t3) / (t1^2 - t3), (-1) / (t2 - 1), (-t3) / (t1 - t3),
(-t1*t3) / (t2^2 - t1*t3), t1 / (t1 - t2), (-1) / (t3 - 1), (-t1) / (t3^2 - t1),
(-t3^2) / (t1^2 - t3^2), (-t3^2) / (t2^2 - t3^2), (-t3) / (t2 - t3),
(-1) / (t1 - 1), (-1) / (t3 - 1), -u + 1, -t1*u + 1, -t2*u + 1, -t1*t2*u + 1,
-t3*u + 1, -t1*t3*u + 1, -t3^2*u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2,
(t1*t2 - v) / (t1*t2), (t3 - v) / t3, (t1*t3 - v) / (t1*t3), (t3^2 - v) / t3^2},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), t2^2 / (t2^2 - t1), (-1) / (t3 - 1),
(-1) / (t2^2 - 1), t2^3 / (t2^3 - t1), t2 / (t2 - t3), (-1) / (t2 - 1),
t2^2 / (t2^2 - t3^2), t2^3 / (t2^3 - t3^3), (-t3) / (t1 - t3),
(t2*t3) / (t2*t3 - t1), (-1) / (t2 - 1), (-t3) / (t2^3 - t3),
(-1) / (t3 - 1), (-t2) / (t3^2 - t2), t3^2 / (t3^2 - t1), (-t3) / (t2^2 - t3),
(-t3^2) / (t2^4 - t3^2), (-1) / (t2 - 1), (-1) / (t3 - 1), -u + 1,
-t2*u + 1, -t2^2*u + 1, -t2^3*u + 1, -t3*u + 1, -t2*t3*u + 1,
-t3^2*u + 1, -v + 1, (t2 - v) / t2, (t2^2 - v) / t2^2, (t2^3 - v) / t2^3,
(t3 - v) / t3, (t2*t3 - v) / (t2*t3), (t3^2 - v) / t3^2},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t3 - 1), (-1) / (t1^3 - 1),
t1^2 / (t1^2 - t2), t1 / (t1 - t3), (-1) / (t1^2 - 1), t1^3 / (t1^3 - t2),
t1^2 / (t1^2 - t3), (-1) / (t1 - 1), (-t1^3) / (t3^4 - t1^3), (-t3) / (t2 - t3),
(-1) / (t1 - 1), (-1) / (t3^3 - 1), t3^2 / (t3^2 - t2), (-t3) / (t1 - t3),
(-1) / (t3^2 - 1), t3^3 / (t3^3 - t2), t3^2 / (t3^2 - t1), (-t3^3) / (t1^4 - t3^3),
(-1) / (t3 - 1), -u + 1, -t1*u + 1, -t1^2*u + 1, -t1^3*u + 1, -t3*u + 1,
-t3^2*u + 1, -t3^3*u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t1^3 - v) / t1^3, (t3 - v) / t3, (t3^2 - v) / t3^2, (t3^3 - v) / t3^3},
{(-1) / (t1 - 1), (-1) / (t3 - 1), (-t1) / (t2^2 - t1), (-t2) / (t1^2 - t2),

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(-1) / (t2 - 1), (-t2) / (t1 - t2), t2 / (t2 - t3), t1 / (t1 - t2),
t1 / (t1 - t3), (-t1 * t2) / (t3^4 - t1 * t2), (-1) / (t1 - 1), (-1) / (t2 - 1),
(-1) / (t3^3 - 1), (-t3) / (t1 - t3), (-t3) / (t2 - t3), (-1) / (t3^2 - 1),
t3^3 / (t3^3 - t1^2), t3^2 / (t3^2 - t1), t3^3 / (t3^3 - t2^2),
t3^2 / (t3^2 - t2), (-1) / (t3 - 1), -u + 1, -t1 * u + 1, -t2 * u + 1, -t1 * t2 * u + 1,
-t3 * u + 1, -t3^2 * u + 1, -t3^3 * u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2,
(t1 * t2 - v) / (t1 * t2), (t3 - v) / t3, (t3^2 - v) / t3^2, (t3^3 - v) / t3^3},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t3 - 1), (-1) / (t2^3 - 1),
t2^2 / (t2^2 - t1), t2 / (t2 - t3), (-1) / (t2^2 - 1), t2^3 / (t2^3 - t1),
t2^2 / (t2^2 - t3), (-1) / (t2 - 1), (-t2^3) / (t3^4 - t2^3), (-t3) / (t1 - t3),
(-1) / (t2 - 1), (-1) / (t3^3 - 1), t3^2 / (t3^2 - t1), (-t3) / (t2 - t3),
(-1) / (t3^2 - 1), t3^3 / (t3^3 - t1), t3^2 / (t3^2 - t2), (-t3^3) / (t2^4 - t3^3),
(-1) / (t3 - 1), -u + 1, -t2 * u + 1, -t2^2 * u + 1, -t2^3 * u + 1, -t3 * u + 1,
-t3^2 * u + 1, -t3^3 * u + 1, -v + 1, (t2 - v) / t2, (t2^2 - v) / t2^2,
(t2^3 - v) / t2^3, (t3 - v) / t3, (t3^2 - v) / t3^2, (t3^3 - v) / t3^3},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t1^2 - 1), (-1) / (t3^2 - 1),
t1^2 / (t1^2 - t2), (-1) / (t1 - 1), (-t1) / (t3^2 - t1), (-t1^2) / (t3^3 - t1^2),
(-t3) / (t2 - t3), (-t3) / (t1^3 - t3), (t1 * t3) / (t1 * t3 - t2), (-t3) / (t1^2 - t3),
(-1) / (t3 - 1), (t1^2 * t3) / (t1^2 * t3 - t2), (-t3) / (t1 - t3), t1 / (t1 - t3),
t1^2 / (t1^2 - t3^2), t3^2 / (t3^2 - t2), (-t3^2) / (t1^3 - t3^2), (-1) / (t1 - 1),
(-1) / (t3 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1,
-t1^2 * t3 * u + 1, -t3^2 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2, (t3 - v) / t3,
(t1 * t3 - v) / (t1 * t3), (t1^2 * t3 - v) / (t1^2 * t3), (t3^2 - v) / t3^2},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t2^2 - 1), (-1) / (t3^2 - 1),
t2^2 / (t2^2 - t1), (-1) / (t2 - 1), (-t2) / (t3^2 - t2), (-t2^2) / (t3^3 - t2^2),
(-t3) / (t1 - t3), (-t3) / (t2^3 - t3), (t2 * t3) / (t2 * t3 - t1), (-t3) / (t2^2 - t3),
(-1) / (t3 - 1), (t2^2 * t3) / (t2^2 * t3 - t1), (-t3) / (t2 - t3), t2 / (t2 - t3),
t2^2 / (t2^2 - t3^2), t3^2 / (t3^2 - t1), (-t3^2) / (t2^3 - t3^2), (-1) / (t2 - 1),
(-1) / (t3 - 1), -u + 1, -t2 * u + 1, -t2^2 * u + 1, -t3 * u + 1, -t2 * t3 * u + 1,
-t2^2 * t3 * u + 1, -t3^2 * u + 1, -v + 1, (t2 - v) / t2, (t2^2 - v) / t2^2, (t3 - v) / t3,
(t2 * t3 - v) / (t2 * t3), (t2^2 * t3 - v) / (t2^2 * t3), (t3^2 - v) / t3^2},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t1^2 - 1), (-t1) / (t3^3 - t1),
t1^2 / (t1^2 - t2), (-1) / (t1 - 1), (-1) / (t3 - 1), (-t1^2) / (t3^3 - t1^2),
(-t3) / (t2 - t3), (-1) / (t3^2 - 1), (t1 * t3) / (t1 * t3 - t2),
(-t3) / (t1^2 - t3), (-1) / (t1 - 1), (-t1) / (t3^2 - t1), t3^2 / (t3^2 - t2),
(-t3^2) / (t1^3 - t3^2), (-1) / (t3 - 1), (t1 * t3^2) / (t1 * t3^2 - t2),
(-t3^2) / (t1^2 - t3^2), (-t3) / (t1 - t3), t1 / (t1 - t3), -u + 1,
-t1 * u + 1, -t1^2 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1, -t3^2 * u + 1,
-t1 * t3^2 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2, (t3 - v) / t3,
(t1 * t3 - v) / (t1 * t3), (t3^2 - v) / t3^2, (t1 * t3^2 - v) / (t1 * t3^2)},
{(-1) / (t1 - 1), (-1) / (t2 - 1), (-1) / (t3 - 1), (-t1) / (t2^2 - t1),
(-t1) / (t3^3 - t1), (-1) / (t1 - 1), (-1) / (t2 - 1), (-t2) / (t3^3 - t2),
(-t3) / (t2^2 - t3), (-1) / (t3^2 - 1), (-t3) / (t1 - t3), (-t2) / (t1 - t2),
(-t3) / (t2 - t3), (-t2) / (t3^2 - t2), (-t3^2) / (t2^2 - t3^2),
(-1) / (t3 - 1), (t2 * t3^2) / (t2 * t3^2 - t1^2), t3^2 / (t3^2 - t1),
(t2 * t3) / (t2 * t3 - t1), t3^2 / (t3^2 - t2), t2 / (t2 - t3), -u + 1,
-t1 * u + 1, -t2 * u + 1, -t3 * u + 1, -t2 * t3 * u + 1, -t3^2 * u + 1,

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-t2 * t3^2 * u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2, (t3 - v) / t3,
(t2 * t3 - v) / (t2 * t3), (t3^2 - v) / t3^2, (t2 * t3^2 - v) / (t2 * t3^2)},
{(-1) / (t1 - 1), (-1) / (t2 - 1), (-t1) / (t3^3 - t1), (-t2) / (t1^2 - t2),
(-1) / (t1 - 1), (-1) / (t2 - 1), (-1) / (t3 - 1), (-t2) / (t3^3 - t2),
(-t3) / (t1^2 - t3), (-1) / (t3^2 - 1), (-t3) / (t1 - t3), (-t3) / (t2 - t3),
t1 / (t1 - t2), (-t1) / (t3^2 - t1), (-t3^2) / (t1^2 - t3^2),
(-1) / (t3 - 1), t3^2 / (t3^2 - t1), t3^2 / (t3^2 - t2),
(t1 * t3^2) / (t1 * t3^2 - t2^2), (t1 * t3) / (t1 * t3 - t2), t1 / (t1 - t3),
-u + 1, -t1 * u + 1, -t2 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1, -t3^2 * u + 1,
-t1 * t3^2 * u + 1, -v + 1, (t1 - v) / t1, (t2 - v) / t2, (t3 - v) / t3,
(t1 * t3 - v) / (t1 * t3), (t3^2 - v) / t3^2, (t1 * t3^2 - v) / (t1 * t3^2)},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t2^2 - 1), (-t2) / (t3^3 - t2),
t2^2 / (t2^2 - t1), (-1) / (t2 - 1), (-1) / (t3 - 1), (-t2^2) / (t3^3 - t2^2),
(-t3) / (t1 - t3), (-1) / (t3^2 - 1), (t2 * t3) / (t2 * t3 - t1),
(-t3) / (t2^2 - t3), (-1) / (t2 - 1), (-t2) / (t3^2 - t2), t3^2 / (t3^2 - t1),
(-t3^2) / (t2^3 - t3^2), (-1) / (t3 - 1), (t2 * t3^2) / (t2 * t3^2 - t1),
(-t3^2) / (t2^2 - t3^2), (-t3) / (t2 - t3), t2 / (t2 - t3), -u + 1,
-t2 * u + 1, -t2^2 * u + 1, -t3 * u + 1, -t2 * t3 * u + 1, -t3^2 * u + 1,
-t2 * t3^2 * u + 1, -v + 1, (t2 - v) / t2, (t2^2 - v) / t2^2, (t3 - v) / t3,
(t2 * t3 - v) / (t2 * t3), (t3^2 - v) / t3^2, (t2 * t3^2 - v) / (t2 * t3^2)},
{(-1) / (t2 - 1), t1 / (t1 - t2), t1^2 / (t1^2 - t2), (-1) / (t1 - 1),
(-1) / (t3 - 1), (-t1) / (t3^2 - t1), (-t1^2) / (t3^4 - t1^2), (-t3) / (t2 - t3),
(t1 * t3) / (t1 * t3 - t2), (-t3) / (t1^2 - t3), (-1) / (t1 - 1), (-1) / (t3 - 1),
(-t1) / (t3^3 - t1), t3^2 / (t3^2 - t2), (-1) / (t1 - 1), (-1) / (t3^2 - 1),
t3^3 / (t3^3 - t2), (-t3^3) / (t1^3 - t3^3), (-t3^2) / (t1^2 - t3^2),
(-t3) / (t1 - t3), (-1) / (t3 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t3 * u + 1,
-t1 * t3 * u + 1, -t3^2 * u + 1, -t3^3 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t3 - v) / t3, (t1 * t3 - v) / (t1 * t3), (t3^2 - v) / t3^2, (t3^3 - v) / t3^3},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), t2^2 / (t2^2 - t1), (-1) / (t2 - 1),
(-1) / (t3 - 1), (-t2) / (t3^2 - t2), (-t2^2) / (t3^4 - t2^2), (-t3) / (t1 - t3),
(t2 * t3) / (t2 * t3 - t1), (-t3) / (t2^2 - t3), (-1) / (t2 - 1), (-1) / (t3 - 1),
(-t2) / (t3^3 - t2), t3^2 / (t3^2 - t1), (-1) / (t2 - 1), (-1) / (t3^2 - 1),
t3^3 / (t3^3 - t1), (-t3^3) / (t2^3 - t3^3), (-t3^2) / (t2^2 - t3^2),
(-t3) / (t2 - t3), (-1) / (t3 - 1), -u + 1, -t2 * u + 1, -t2^2 * u + 1, -t3 * u + 1,
-t2 * t3 * u + 1, -t3^2 * u + 1, -t3^3 * u + 1, -v + 1, (t2 - v) / t2, (t2^2 - v) / t2^2,
(t3 - v) / t3, (t2 * t3 - v) / (t2 * t3), (t3^2 - v) / t3^2, (t3^3 - v) / t3^3},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t3 - 1), (-1) / (t1^2 - 1),
t1^2 / (t1^2 - t2), t1 / (t1 - t3), (-1) / (t1 - 1), (-t1^2) / (t3^5 - t1^2),
(-t3) / (t2 - t3), (-1) / (t1 - 1), (-1) / (t3^4 - 1), t3^2 / (t3^2 - t2),
(-t3) / (t1 - t3), (-1) / (t3^3 - 1), t3^3 / (t3^3 - t2), t3^2 / (t3^2 - t1),
(-1) / (t3^2 - 1), t3^4 / (t3^4 - t2), t3^3 / (t3^3 - t1), t3^4 / (t3^4 - t1^3),
(-1) / (t3 - 1), -u + 1, -t1 * u + 1, -t1^2 * u + 1, -t3 * u + 1, -t3^2 * u + 1,
-t3^3 * u + 1, -t3^4 * u + 1, -v + 1, (t1 - v) / t1, (t1^2 - v) / t1^2,
(t3 - v) / t3, (t3^2 - v) / t3^2, (t3^3 - v) / t3^3, (t3^4 - v) / t3^4},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t3 - 1), (-1) / (t2^2 - 1),
t2^2 / (t2^2 - t1), t2 / (t2 - t3), (-1) / (t2 - 1), (-t2^2) / (t3^5 - t2^2),
(-t3) / (t1 - t3), (-1) / (t2 - 1), (-1) / (t3^4 - 1), t3^2 / (t3^2 - t1),

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(-t3) / (t2 - t3), (-1) / (t3^3 - 1), t3^3 / (t3^3 - t1), t3^2 / (t3^2 - t2),
(-1) / (t3^2 - 1), t3^4 / (t3^4 - t1), t3^3 / (t3^3 - t2), t3^4 / (t3^4 - t2^3),
(-1) / (t3 - 1), -u + 1, -t2 * u + 1, -t2^2 * u + 1, -t3 * u + 1, -t3^2 * u + 1,
-t3^3 * u + 1, -t3^4 * u + 1, -v + 1, (t2 - v) / t2, (t2^2 - v) / t2^2,
(t3 - v) / t3, (t3^2 - v) / t3^2, (t3^3 - v) / t3^3, (t3^4 - v) / t3^4},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t1 - 1), (-1) / (t3^3 - 1),
(-t1) / (t3^4 - t1), (-t3) / (t2 - t3), (-t3) / (t1^2 - t3),
(t1 * t3) / (t1 * t3 - t2), (-t3) / (t1 - t3), (-1) / (t3^2 - 1), (-t1) / (t3^3 - t1),
t3^2 / (t3^2 - t2), (-t3^2) / (t1^2 - t3^2), (t1 * t3^2) / (t1 * t3^2 - t2),
t3^2 / (t3^2 - t1), (-1) / (t3 - 1), (-t1) / (t3^2 - t1), t3^3 / (t3^3 - t2),
t3^3 / (t3^3 - t1^2), (-1) / (t1 - 1), (-1) / (t3 - 1), -u + 1,
-t1 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1, -t3^2 * u + 1, -t1 * t3^2 * u + 1,
-t3^3 * u + 1, -v + 1, (t1 - v) / t1, (t3 - v) / t3, (t1 * t3 - v) / (t1 * t3),
(t3^2 - v) / t3^2, (t1 * t3^2 - v) / (t1 * t3^2), (t3^3 - v) / t3^3},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t2 - 1), (-1) / (t3^3 - 1),
(-t2) / (t3^4 - t2), (-t3) / (t1 - t3), (-t3) / (t2^2 - t3),
(t2 * t3) / (t2 * t3 - t1), (-t3) / (t2 - t3), (-1) / (t3^2 - 1), (-t2) / (t3^3 - t2),
t3^2 / (t3^2 - t1), (-t3^2) / (t2^2 - t3^2), (t2 * t3^2) / (t2 * t3^2 - t1),
t3^2 / (t3^2 - t2), (-1) / (t3 - 1), (-t2) / (t3^2 - t2), t3^3 / (t3^3 - t1),
t3^3 / (t3^3 - t2^2), (-1) / (t2 - 1), (-1) / (t3 - 1), -u + 1,
-t2 * u + 1, -t3 * u + 1, -t2 * t3 * u + 1, -t3^2 * u + 1, -t2 * t3^2 * u + 1,
-t3^3 * u + 1, -v + 1, (t2 - v) / t2, (t3 - v) / t3, (t2 * t3 - v) / (t2 * t3),
(t3^2 - v) / t3^2, (t2 * t3^2 - v) / (t2 * t3^2), (t3^3 - v) / t3^3},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t1 - 1), (-1) / (t3^2 - 1),
(-t1) / (t3^5 - t1), (-t3) / (t2 - t3), (t1 * t3) / (t1 * t3 - t2),
(-t3) / (t1 - t3), (-1) / (t3 - 1), (-t1) / (t3^4 - t1), t3^2 / (t3^2 - t2),
(-1) / (t1 - 1), (-1) / (t3^3 - 1), t3^3 / (t3^3 - t2), t3^3 / (t3^3 - t1^2),
(-t3) / (t1 - t3), (-1) / (t3^2 - 1), t3^4 / (t3^4 - t2), t3^4 / (t3^4 - t1^2),
t3^2 / (t3^2 - t1), (-1) / (t3 - 1), -u + 1, -t1 * u + 1, -t3 * u + 1, -t1 * t3 * u + 1,
-t3^2 * u + 1, -t3^3 * u + 1, -t3^4 * u + 1, -v + 1, (t1 - v) / t1, (t3 - v) / t3,
(t1 * t3 - v) / (t1 * t3), (t3^2 - v) / t3^2, (t3^3 - v) / t3^3, (t3^4 - v) / t3^4},
{(-1) / (t1 - 1), (-t2) / (t1 - t2), (-1) / (t2 - 1), (-1) / (t3^2 - 1),
(-t2) / (t3^5 - t2), (-t3) / (t1 - t3), (t2 * t3) / (t2 * t3 - t1),
(-t3) / (t2 - t3), (-1) / (t3 - 1), (-t2) / (t3^4 - t2), t3^2 / (t3^2 - t1),
(-1) / (t2 - 1), (-1) / (t3^3 - 1), t3^3 / (t3^3 - t1), t3^3 / (t3^3 - t2^2),
(-t3) / (t2 - t3), (-1) / (t3^2 - 1), t3^4 / (t3^4 - t1), t3^4 / (t3^4 - t2^2),
t3^2 / (t3^2 - t2), (-1) / (t3 - 1), -u + 1, -t2 * u + 1, -t3 * u + 1, -t2 * t3 * u + 1,
-t3^2 * u + 1, -t3^3 * u + 1, -t3^4 * u + 1, -v + 1, (t2 - v) / t2, (t3 - v) / t3,
(t2 * t3 - v) / (t2 * t3), (t3^2 - v) / t3^2, (t3^3 - v) / t3^3, (t3^4 - v) / t3^4},
{(-1) / (t2 - 1), t1 / (t1 - t2), (-1) / (t1 - 1), (-1) / (t3 - 1),
(-t1) / (t3^6 - t1), (-t3) / (t2 - t3), (-1) / (t1 - 1), (-1) / (t3^5 - 1),
t3^2 / (t3^2 - t2), (-t3) / (t1 - t3), (-1) / (t3^4 - 1), t3^3 / (t3^3 - t2),
t3^2 / (t3^2 - t1), (-1) / (t3^3 - 1), t3^4 / (t3^4 - t2), t3^3 / (t3^3 - t1),
(-1) / (t3^2 - 1), t3^5 / (t3^5 - t2), t3^5 / (t3^5 - t1^2), t3^4 / (t3^4 - t1),
(-1) / (t3 - 1), -u + 1, -t1 * u + 1, -t3 * u + 1, -t3^2 * u + 1, -t3^3 * u + 1,
-t3^4 * u + 1, -t3^5 * u + 1, -v + 1, (t1 - v) / t1, (t3 - v) / t3,
(t3^2 - v) / t3^2, (t3^3 - v) / t3^3, (t3^4 - v) / t3^4, (t3^5 - v) / t3^5},

```

```
{(-1)/(t1-1), (-t2)/(t1-t2), (-1)/(t2-1), (-1)/(t3-1),
  (-t2)/(t3^6-t2), (-t3)/(t1-t3), (-1)/(t2-1), (-1)/(t3^5-1),
  t3^2/(t3^2-t1), (-t3)/(t2-t3), (-1)/(t3^4-1), t3^3/(t3^3-t1),
  t3^2/(t3^2-t2), (-1)/(t3^3-1), t3^4/(t3^4-t1), t3^3/(t3^3-t2),
  (-1)/(t3^2-1), t3^5/(t3^5-t1), t3^5/(t3^5-t2^2), t3^4/(t3^4-t2),
  (-1)/(t3-1), -u+1, -t2*u+1, -t3*u+1, -t3^2*u+1, -t3^3*u+1,
  -t3^4*u+1, -t3^5*u+1, -v+1, (t2-v)/t2, (t3-v)/t3,
  (t3^2-v)/t3^2, (t3^3-v)/t3^3, (t3^4-v)/t3^4, (t3^5-v)/t3^5},
{(-1)/(t1-1), (-1)/(t2-1), (-1)/(t3^7-1), (-t3)/(t1-t3),
  (-t3)/(t2-t3), (-1)/(t3^6-1), t3^2/(t3^2-t1), t3^2/(t3^2-t2),
  (-1)/(t3^5-1), t3^3/(t3^3-t1), t3^3/(t3^3-t2), (-1)/(t3^4-1),
  t3^4/(t3^4-t1), t3^4/(t3^4-t2), (-1)/(t3^3-1), t3^5/(t3^5-t1),
  t3^5/(t3^5-t2), (-1)/(t3^2-1), t3^6/(t3^6-t1), t3^6/(t3^6-t2),
  (-1)/(t3-1), -u+1, -t3*u+1, -t3^2*u+1, -t3^3*u+1, -t3^4*u+1,
  -t3^5*u+1, -t3^6*u+1, -v+1, (t3-v)/t3, (t3^2-v)/t3^2,
  (t3^3-v)/t3^3, (t3^4-v)/t3^4, (t3^5-v)/t3^5, (t3^6-v)/t3^6}}
```

```
In[280]:= Length[GT7smoothPointsContributions[t1, t2, t3, u, v]]
```

```
Out[280]= 58
```

```
In[281]:= GT7smooth[t1_, t2_, t3_, u_, v_] :=
  Sum[Det[DiagonalMatrix[GT7smoothPointsContributions[t1, t2, t3, u, v][[i]]]],
    {i, 1, 58}]
```

```
In[287]:= f[t1_, t2_, t3_, u_, v_] := GT7smooth[t1, t2, t3, u, v] +
  GT151[t1, t2, t3, u, v] + GT151[t2, t3, t1, u, v] + GT151[t3, t1, t2, u, v] +
  GT142[t1, t2, t3, u, v] + GT142[t2, t3, t1, u, v] + GT142[t3, t1, t2, u, v] +
  GT142[t1, t3, t2, u, v] + GT142[t3, t2, t1, u, v] + GT142[t2, t1, t3, u, v] +
  GT1411[t1, t2, t3, u, v] + GT1411[t2, t3, t1, u, v] + GT1411[t3, t1, t2, u, v] +
  GT1411[t1, t3, t2, u, v] + GT1411[t3, t2, t1, u, v] + GT1411[t2, t1, t3, u, v] +
  GT232[t1, t2, t3, u, v] + GT232[t2, t3, t1, u, v] + GT232[t3, t1, t2, u, v] +
  GT2311[t1, t2, t3, u, v] + GT2311[t2, t3, t1, u, v] + GT2311[t3, t1, t2, u, v] +
  GT2311[t1, t3, t2, u, v] + GT2311[t3, t2, t1, u, v] + GT2311[t2, t1, t3, u, v] +
  GT11311[t1, t2, t3, u, v] + GT1321[t1, t2, t3, u, v] + GT1321[t2, t3, t1, u, v] +
  GT1321[t3, t1, t2, u, v] - SeriesCoefficient[Exp[Sum[Q^n * (1 - u^n) *
    (1 - v^n) / (n * (1 - t1^n) * (1 - t2^n) * (1 - t3^n)), {n, 1, 7}]], {Q, 0, 7}]
```

```
In[292]:= f[2, 191, 203, 7, 11] // Timing
```

```
Out[292]= {0.207174, 0}
```

```
In[299]:=
```

```

In[300]:= Together[
  GT7smooth[t1, t2, t3, u, v] + GT151[t1, t2, t3, u, v] + GT151[t2, t3, t1, u, v] +
  GT151[t3, t1, t2, u, v] + GT142[t1, t2, t3, u, v] + GT142[t2, t3, t1, u, v] +
  GT142[t3, t1, t2, u, v] + GT142[t1, t3, t2, u, v] + GT142[t3, t2, t1, u, v] +
  GT142[t2, t1, t3, u, v] + GT1411[t1, t2, t3, u, v] + GT1411[t2, t3, t1, u, v] +
  GT1411[t3, t1, t2, u, v] + GT1411[t1, t3, t2, u, v] + GT1411[t3, t2, t1, u, v] +
  GT1411[t2, t1, t3, u, v] + GT232[t1, t2, t3, u, v] + GT232[t2, t3, t1, u, v] +
  GT232[t3, t1, t2, u, v] + GT2311[t1, t2, t3, u, v] + GT2311[t2, t3, t1, u, v] +
  GT2311[t3, t1, t2, u, v] + GT2311[t1, t3, t2, u, v] + GT2311[t3, t2, t1, u, v] +
  GT2311[t2, t1, t3, u, v] + GT11311[t1, t2, t3, u, v] + GT1321[t1, t2, t3, u, v] +
  GT1321[t2, t3, t1, u, v] + GT1321[t3, t1, t2, u, v] - SeriesCoefficient[
    Exp[Sum[Q^n * (1 - u^n) * (1 - v^n) / (n * (1 - t1^n) * (1 - t2^n) * (1 - t3^n)),
      {n, 1, 7}]], {Q, 0, 7}]] // Timing

Out[300]= {28890.8, 0}

```