

§ 1.

Thm 1 Every isometry of  $\mathbb{R}^2$  is a product of 1, 2 or 3 reflections

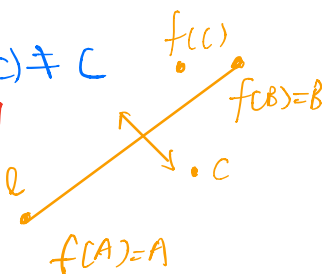
Proof: Consider  $A, B, C$  non collinear.

Then the cases are:

① If  $f(A)=A$ ,  $f(B)=B$ ,  $f(C)=C$ ,  
then  $f = \text{Id}$

②  $f(A)=A$ ,  $f(B)=B$ ,  $f(C) \neq C$

We argue that  $\overline{r}_{L,C}(C) = f(C)$



Indeed,  $r_{L,C}$  satisfies

that  $\overline{r}_{L,C}(C) = f(C)$

$$\overline{r}_L(A) = A$$

If we conclude  $r_{L,C} = f$ ,

$$\overline{r}_L(B) = B$$

then  $\overline{r}_L(C) = f(C)$

$\downarrow$   
 $L$  contains  $A \neq B$

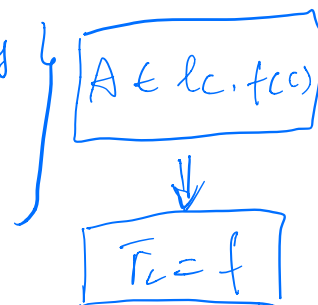
$$d(A, C) = d(A, f(C))$$

$\parallel$

$\parallel \leftarrow$  isometry

$$d(A, f(C)) = d(f(A), f(C))$$

$\uparrow$   
 $A = f(A)$



②  $f(A) = A, f(B) \neq B, f(C) \neq C$

consider  $\ell_B, f(B)$ , then  $\overline{\Gamma}_{\ell_B, f(B)}$   
 $= f(B)$

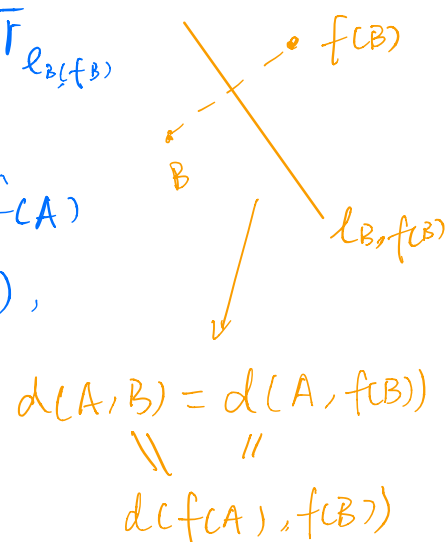
Do we have  $\overline{\Gamma}_{\ell_B, f(B)}(A) = f(A)$

Since  $d(A, B) = d(A, f(B))$ ,

because  $f(A) = A$ .

$A \in \ell_B, f(B)$ , and then

$$\overline{\Gamma}_{\ell_B, f(B)}(A) = A = f(A)$$



Remark: If  $\overline{\Gamma}_{\ell_B, f(B)}(C) = C$ , then  $f = \overline{\Gamma}_{\ell_B, f(B)}$   
 and we are done.

We know  $\overline{\Gamma}_{\ell_B, f(B)}(A) = f(A), \overline{\Gamma}_{\ell_B, f(B)}(B) = f(B)$

In general,  $f(C) \neq \overline{\Gamma}_{\ell_B, f(B)}(C)$

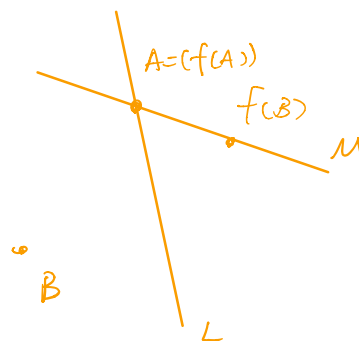
claim  $f = \overline{\Gamma}_M \overline{\Gamma}_L$

→ sufficient to check

$$A = f(A) = \overline{\Gamma}_M \overline{\Gamma}_L(A) = A \checkmark$$

$$f(B) \in M \leftarrow f(B) = f(B) = \overline{\Gamma}_M \overline{\Gamma}_L(B) = f(B) \checkmark$$

$$f(C) = \overline{\Gamma}_M \overline{\Gamma}_L(C)$$



Finally, verify that  $f(c) = \overline{T}_M \overline{T}_L(c)$

It suffices to show that  $M = \ell_{\overline{T}_L(c), f(c)}$

↓

$$\overline{T}_M(\overline{T}_L(c)) = f(c)$$

We know  $A = f(A), f(B) \in M$ . \* Need to

check  $A, f(B) \in \ell_{\overline{T}_L(c), f(c)}$

$$\begin{aligned} \text{Check } A \in \ell_{\overline{T}_L(c), f(c)}: d(A, \overline{T}_L(c)) &= \\ d(A, f(c)) &= d(A, c) \\ \parallel & \\ d(\overline{T}_L(A), \overline{T}_L(c)) &\quad \swarrow A, f(A) \end{aligned}$$

③ Last case:  $f(A) \neq A$   
 $f(B) \neq B$   
 $f(C) \neq C$

HINT: Start by considering  $A, f(A) \in L$ .

Look at  $\overline{T}_L$ . In the end,

$$f = \overline{T}_N \overline{T}_M \overline{T}_L, \text{ where } \begin{cases} A, f(A) \in L \\ B, f(B) \in M \\ C, f(C) \in N \end{cases}$$

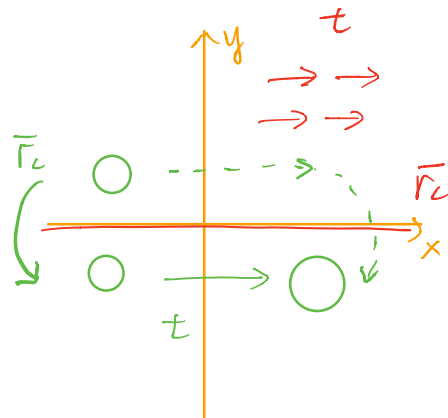
## § 2. GLIDE REFLECTIONS

Thm II Every isometry of  $\mathbb{R}^2$  is a translation,  
<sup>2 refs</sup> rotation, or a glide reflection  $\rightarrow$  <sup>1 or 3 refs</sup>

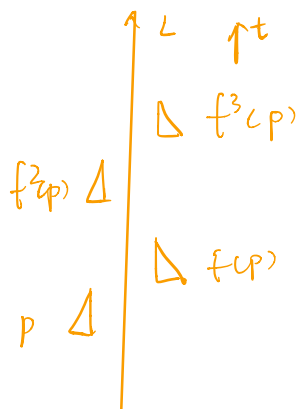
Def of glide ref.

A glide reflection is a composition of a reflection  $\bar{r}_L$  and a translation along the line  $L$ .

Ex 1  $t_{(1,0)} \circ \bar{r}$



Ex. 2 The world's most famous glide ref.



Note, known by Thm I  
 that a glide reflection  
 is a product of refs.  
 How many? 3

Remark: a ref. is a  
glide ref

Prop: The product of 3 reflections is  
a glide reflection.