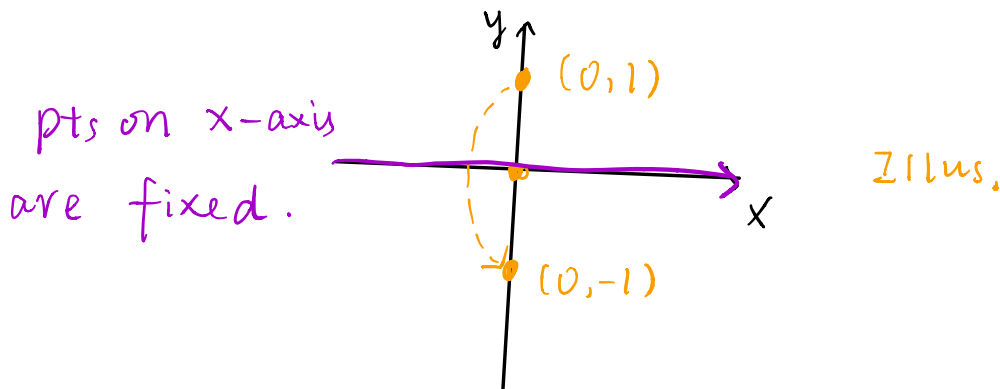


## Lecture 3

§1: Reflection  $\rightarrow$  isometry.

Def: The reflection  $\bar{r}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  along  
x-axis is

$$\bar{r}(x, y) := (x, -y)$$



Lemma  $\bar{r}$  is an isometry.

Pf:  $d(P, Q) = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$

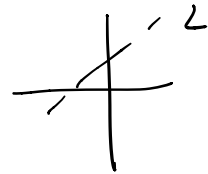
$$d(\bar{r}(P), \bar{r}(Q)) = \sqrt{(x_1 - x_2)^2 + \underbrace{(-y_1 - (-y_2))^2}_{(y_2 - y_1)^2}}$$

preserve!

§2. How to obtain more interesting isometry?

Ex1 Given  $P \in \mathbb{R}^2$ , how do we get rotation on  $\mathbb{R}^2$  of angle  $\theta$  centered at  $P$

Ex2 How to reflect any line  $L$ ?



§3. Composition of Isometries.

Given  $f, g \in \text{Isom}(\mathbb{R}^2) := \{f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$d(P, Q) = d(f(P), f(Q)), \forall P, Q \in \mathbb{R}^2$$

We can consider

↖ Set of isometries

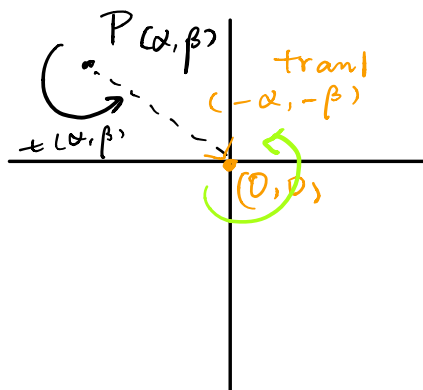
$$\left. \begin{array}{ccc} f \circ g: \mathbb{R}^2 & \xrightarrow{g} & \mathbb{R}^2 \xrightarrow{f} \mathbb{R}^2 \end{array} \right\} \begin{array}{l} \text{is an} \\ \text{isom} \end{array}$$

$$\begin{array}{l} \text{assume } d(P, Q) = d(f(P), f(Q)) \dots d(fg(P), fg(Q)) \\ d(P, Q) = d(g(P), g(Q)) \end{array}$$

### §3.1. Rot. along any center

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Given  $P \in \mathbb{R}^2$ , the rotation of angle  $\theta$  defined at  $P$ .



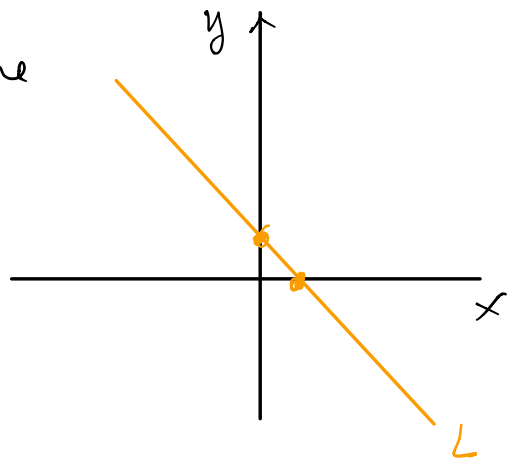
$$R_{\theta, P} := t_{(\alpha, \beta)} \circ R_{\theta} \circ t_{(-\alpha, -\beta)}$$

where  $P(\alpha, \beta)$

### §3.2 Ref. along arbitrary line $L$

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Given  $L \subseteq \mathbb{R}^2$  a line, the reflection  $\bar{F}_L$  along is:



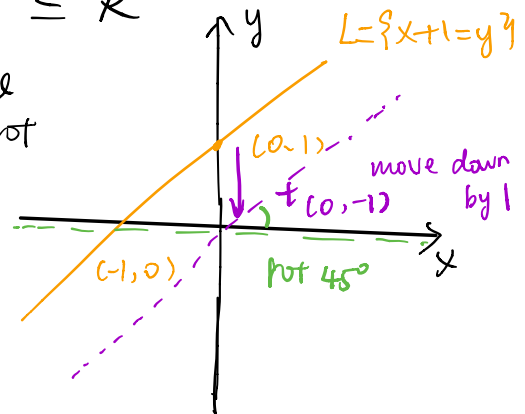
$$\bar{F}_L = f^{-1} \bar{F} f, \text{ where } f$$

is any isometry bring  $L$  to  $x$ -axis

Ex.  $L = \{x+1=y\} \subseteq \mathbb{R}^2$

By def, choosing -clockwise  
positive rot

$$f = R_{\frac{\pi}{4}} \circ t_{(0,-1)}$$



$\bar{\Gamma}_L := t_{(0,1)} \circ R_{\frac{\pi}{4}} \circ \bar{\Gamma} \circ R_{\frac{\pi}{4}} \circ t_{(0,-1)}$

note  $AB = B^{-1}A^{-1}$

the reverse  $f^{-1}$  of  $R_{\frac{\pi}{4}} \circ t_{(0,-1)}$

§4. The set of isometries generated by trans, rot, refl?

$$\{ \text{Rot } R_{\alpha} \} \stackrel{=?}{\subseteq} \langle \text{Rot } R_{\alpha, \beta} \rangle := \left\{ \begin{array}{l} \text{all compo.} \\ \text{of rot } R_{\alpha, \beta} \end{array} \right.$$

$$\{ \text{trans } t_{(\alpha, \beta)} \} \stackrel{=?}{\subseteq} \langle \text{trans } t_{\alpha, \beta} \rangle \quad \text{inclusion}$$

$$\{ \text{refl } \bar{\Gamma}_L \} \stackrel{=?}{\subseteq} \langle \text{refl } \bar{\Gamma}_L \rangle$$

generated by rot

$t_{(\gamma, \delta)} \circ t_{(\alpha, \beta)} = t_{(\delta+\alpha, \gamma+\beta)}$

§4.1 The inclusion  $\{Ref\} \subseteq \langle Ref \rangle$

Ex. We choose two lines  $L = x\text{-axis}$

$M = y\text{-axis}$

ALGEBRA  $\Gamma_M \Gamma_L (x, y) = \Gamma_M (x, -y) = (-x, -y)$

Q: is this ref?

$$\exists N \text{ s.t. } \bar{\Gamma}_N = \bar{\Gamma}_M \bar{\Gamma}_L ?$$