Design of a Photovoltaic Simulator with a Novel Reference Signal Generator and Two-Stage LC Output Filter

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Abstract-This paper presents a systematic design technique for a photovoltaic simulator. The proposed technique helps improve control loop bandwidth and system response. The photovoltaic equivalent circuit is used to generate the current-voltage reference curves. A novel technique is proposed and implemented with analog controllers to simplify the reference signal generator and to avoid sampling time delays in digital controllers. A two-stage LC output filter is implemented to push the resonant frequency higher and thus allowing a higher bandwidth control loop design while keeping the same switching ripple attenuation as in the conventional one-stage LC output filter. Design procedures for both control and power stage circuits are explained. Experimental results verify the steady state and transient performance of the proposed photovoltaic simulator at 2.7 kW output.

Keywords—Analog control, photovoltaic equivalent circuit, photovoltaic simulator, and two-stage LC filter.

I. Introduction

Photovoltaic (PV) technologies are well known for their potential to environmental benefits, and their usage at kW-level is spreading. A photovoltaic system has several advantages such as pollution-free power generation, low maintenance cost, and extremely low operation cost [1-4]. The output voltage and current of a PV panel change non linearly according to the irradiance condition; therefore, a maximum power point tracking (MPPT) algorithm is needed for its power conditioning system [5-11]. Two methods are available for evaluating MPPT algorithm of a PV power conditioning system. The first one is to test using an actual PV panel with direct solar irradiance or an adjustable artificial light. This method is often used for lowpower levels (<100 Watts) because in high-power levels there are some difficulties in power consumption, heat dissipation, and the bulky size of the testing setup. The second method is to test with a PV simulator that has a linear regulator or a switching-mode dc-dc converter along with associated controls. A high-power

PV simulator typically employs aswitching-mode dc-dc converter that emulates the current and voltage output characteristic of an actual PV panel.

Design of a PV simulator can be found in many different ways. Some simulators are implemented with digital controllers that use either a lookup table in a data memory [12-14] or equations based on the semiconductor physics [15-17] to emulate the PV output characteristic. For the first method, if several curves of measured data are stored in advance, the characteristic can match well with actual PV panel's output characteristic. However, a lot of data are needed to get a higher resolution of the PV output characteristic curves. For the second method, the PV characteristic is online processed by inserting the coefficients of the semiconductor equations. These digital controllers have a sampling delay that may limit the system bandwidth [18]. Moreover, an output LC filter with low cut-off frequency will limit the overall system bandwidth. Analog controllers are able to provide a higher bandwidth than digital ones do due to the absence of sampling delays. For this reason, PV simulators with analog controllers were proposed [19-23]. The analog controller based design employs a signal level reference generated by analog circuits and then amplifies it using a linear or switching regulator. To generate the reference signal, a photo diode with an LED [20] or a small PV cell with a light bulb [22,23] can be used. A hybrid PV simulator that has both analog and digital sections was proposed in [24].

In this paper, a PV simulator using a novel analog controller and a two-stage output LC filter is proposed. The simulator consists of a PV equivalent circuit to produce the reference current-voltage characteristic curve and a dc-dc buck converter to amplify it for high-power applications. A novel technique is proposed to emulate the PV equivalent circuit, which consists of a voltage-controlled current-source (VCCS), a voltage-controlled voltage-source (VCVS), a series connected diode stack or an actual PV cell, and a resistors net-

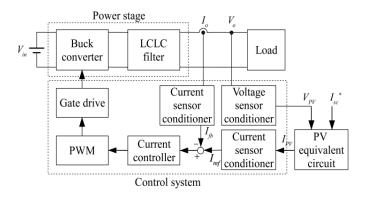


Figure 1: The entire system block diagram

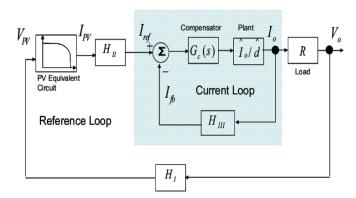


Figure 2: Control system block diagram

work. This equivalent circuit is closed-loop controlled and can generate a reference with higher than 20-kHz bandwidth. The dc-dc buck converter takes the reference signal and amplifies it with pulse-width-modulation (PWM) to produce high voltage and high current at the output, which is then filtered by the proposed two-stage LC filter. As two-stage LC filter's resonant frequency is high, the control-loop bandwidth can be improved while maintaining the same switching ripple attenuation as compared to that of the one-stage LC filter. This paper describes the design procedure in detail. Measured frequency domain response of the PV equivalent circuit, hardware setup, and experimental results will be shown to verify the design concept.

II. SYSTEM DESCRIPTION AND CONTROL STRATEGY

The entire system block diagram is shown in Fig. 1. There are three major circuit sections: (1) PV equivalent circuit, (2) control system circuit, and (3) power stage circuit. The PV equivalent circuit consisting of a VCCS loop and a VCVS loop produces the current-voltage reference curve and feeds it to the power stage circuit through the control system circuit. The power stage circuit is a buck converter switching stage along

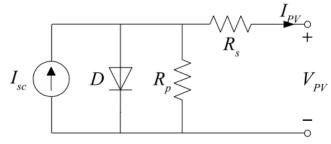


Figure 3: A PV equivalent circuit

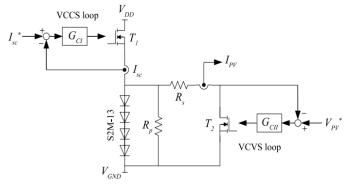


Figure 4: Experimental PV equivalent circuit with diodes

with a two-stage LC filter. Fig. 2 shows the control system block diagram. There are two control loops: (1) inner-current loop and (2) outer-reference loop. The inner-current loop controls the output current Io of the power stage. The outer-reference loop senses the output voltage Vo of the power stage and feeds it back to the PV equivalent circuit. This circuit generates a reference current IPV that will force the power stage to produce an actual PV current-voltage curve. For stability consideration, the inner-current loop should be faster than the outer-reference loop. Conditioning circuit gains HI, HII, and HIII determine the voltage and current values of the power stage. Resistor R represents the equivalent load resistance of the PV power conditioning system. The detailed design procedure for both loops will be discussed in the next section.

III. DESIGN PROCEDURE AND SYSTEM CONFIGURATION

A. PV Equivalent Circuit Design with Diodes

A PV equivalent circuit is shown in Fig. 3 [25]. Current source Isc is proportional to the solar irradiance (W/m2), and diode D is a typical pn junction diode. Resistor Rp represents the leakage current along the cell borders and localized short circuits while resistor Rs represents the resistive paths through the semicon-

ductor material and contacts [26]. The current-voltage characteristic of this circuit can be designed to match with the actual PV cell or PV panel.

Fig. 4 illustrates the experimental version of the PV equivalent circuit. The circuit shown in Fig. 3 is built with analog components to generate the currentvoltage output reference curves. Current source Isc is represented by a voltage-controlled current-source (VCCS) loop. MOSFET T1 operates in the linear region so current Isc will be controlled to follow the current reference Isc*. In the voltage-controlled voltage-source (VCVS) loop, MOSFET T2 operates in the linear region to control the output terminal voltage of the PV equivalent circuit VPV. With the use of VCCS, there is no need to use an external light source. As for the diode D, its I-V characteristic affects the generated PV reference curve. Therefore, it should be selected to match with actual PV characteristic. In this design, four series-connected diodes (model number: S2M-13) were used in the experimental PV equivalent circuit. A high bandwidth for both the VCCS loop and the VCVS loop should allow decoupling between the reference signal and the outer loop dynamics. Fig. 5 shows the measured compensated loop gain for both the VCCS loop and the VCVS loop, respectively. The VCCS loop was designed to have a cross-over frequency of 90kHz and 60o phase margin, and the VCVS loop was designed to have 20-kHz cross-over frequency with 50o phase margin. Since the performance of the VCCS loop affects the desired magnitude and response of IPV, its bandwidth should be faster than that of the VCVS loop.

The VCCS loop controller GCI(s) consists of an integrator and a set of double poles and double zeros, which is known as "type 3" controller [27]. The VCVS loop controller GCII(s) consists of an integrator and a set of pole and zero, which is known as "type 2" controller. Using the controller circuit parameters obtained from the above design, a hardware circuit that emulates PV characteristic is built and tested. Fig. 6 shows the experimental results of the current-voltage reference curves using the PV equivalent circuit shown in Fig. 4.

B. PV Equivalent Circuit Design with Actual PV Cell Another approach to emulate the PV characteristic is to use an actual PV cell as a reference signal generator. Fig. 7 represents the PV equivalent circuit of this approach. This circuit is obtained by the equivalent transformation of the circuit in Fig. 3 using Thévenin's theorem. The left part of the circuit consists of a diode D and resistors Rp and Rs. This part is equivalent to the PV equivalent circuit with Isc = 0. Therefore, this part can be implemented with the actual PV cell under no illumination or in total darkness, while the current

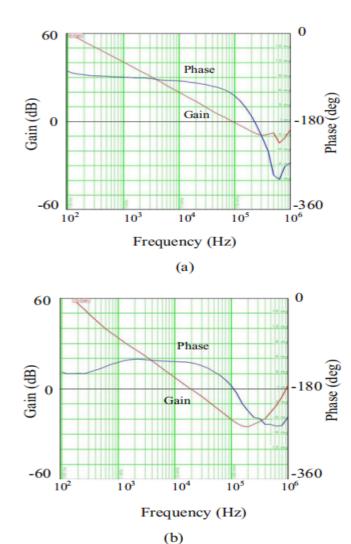


Figure 5: Measured compensated loop gain; (a) Voltage-controlled current-source loop and (b) Voltage-controlled voltage-source loop

source Isc is produced with an external VCCS circuit. In this case, there is no need for any external light source, similar to the previous case using series diodes to emulate the PV cell characteristic. Fig. 8 illustrates the experimental version of this PV equivalent circuit with the use of a small un-illuminated PV cell. The circuit is built with analog

IV. EXPERIMENTAL RESULTS

The proposed PV simulator has been built, and its photograph is shown in Fig. 13. A resistor bank was used as the load. The voltage sensor gain HI and the current sensor gains HII and HIII are set to be 0.014, 4, and 0.2, respectively. Therefore, the open-circuit voltage and short-circuit current will be 250 V (= 3.5 V / 0.014) and 20 A (= 1.0 A * 4 / 0.2).

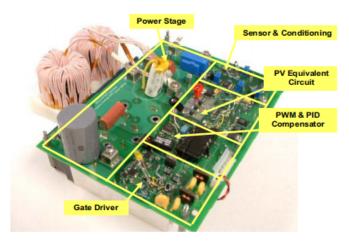


Figure 6: Photograph of the proposed PV simulator

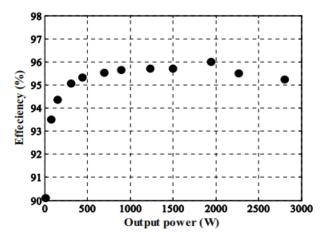


Figure 7: Photovoltaic simulator efficiency measurement curve

The overall power conversion gain is about 1400. The maximum output power was tested up to 2.7 kW. With higher input voltage and sufficient cooling of the power stage, this power level can be further increased. Fig. 14 shows the measured efficiency results of the photovoltaic simulator at different output power levels. The efficiency maintains in between 95to 2.7-kW power output.

A. With PV Equivalent Circuit Using Diodes

This section shows test results using the PV equivalent circuit with series-connected diodes shown in Fig. 4 to generate the reference current signal IPV. The PV curves shown in Fig. 15 were generated by the power stage at different irradiance reference levels. The results match with the current-voltage reference curve in Fig. 6 with the desired conversion ratios. Fig. 16 illustrates the output voltage vo and current io waveforms for a step load change (76 to 9). Response time was recorded to be 3.8 ms.

Fig. 17 shows the output voltage vo and current io waveforms of the PV simulator under different irradiance levels and perturbing frequencies. The current source Isc * corresponds to irradiance level, which is a triangular wave and serves as the reference. The output voltage and current of the power stage vo and io should follow the given reference. Fig. 17(a) shows the results of slow perturbation using a 10- Hz triangular wave as the reference. The output voltage and current follow the reference very well. Fig. 17(b) shows the results of fast perturbation using a 40-Hz triangular wave as the reference. In this case, the output voltage and current can not exactly follow the reference, resulting in waveform distortion. Since the time interval of most MPPT control algorithm is more than one second, and a fast perturbation with higher than 10-Hz frequency rarely occur. Therefore, the response of this photovoltaic simulator is sufficient for evaluating the MPPT control algorithms of the PV power conditioning systems.

B. With PV Equivalent Circuit Using an Actual PV Cell

This section shows the test results using a polycrystalline PV cell based simulator shown in Fig. 8. Fig. 18 shows the current-voltage curve generated by the power stage with Isc *=0.4-A and offset voltage RsIsc =1.0-V. The result matches the basic cell characteristic shown in Fig. 9 with a desired voltage and current conversion ratios. The perturbation test results are not shown because they are the same as those shown in Fig. 17.

V. CONCLUSION

A systematic design approach is proposed and described in detail for a PV simulator, which consists of a PV equivalent circuit and power stage circuit. The PV equivalent circuit is implemented with a novel analog circuit using high bandwidth voltage-controlled current-source and voltage-controlled voltage-source to generate high precision current-voltage reference curves in order to eliminate the sampling time delay in digital controllers. The power stage consists of a buck converter and a two-stage LC output filter with a high cut-off frequency to allow a high control loop bandwidth while keeping the same switching ripple attenuation as a one-stage LC output filter does.

The proposed PV simulator hardware prototype has been designed and built. Two approaches of generating the current-voltage reference signal using a series diode stack and an actual PV cell were implemented. Both approaches show power stage output matches the actual PV characteristic with the desired conversion ratios. Experimental results showed high accuracy and

reasonably fast response. Power level of 2.7 kW has been demonstrated. In summary, the proposed PV simulator has the following features:

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