

## Modeling and Specification in OTS/CafeOBJ

---

CafeOBJ Team of JAIST

### Topics

---

- What is QLOCK?
- Modeling and Description of QLOCK in OTS
- Formal specification of QLOCK in CafeOBJ
- Formal specification of mutual exclusion

## Modeling, Specifying, and Verifying (MSV) in CafeOBJ

---

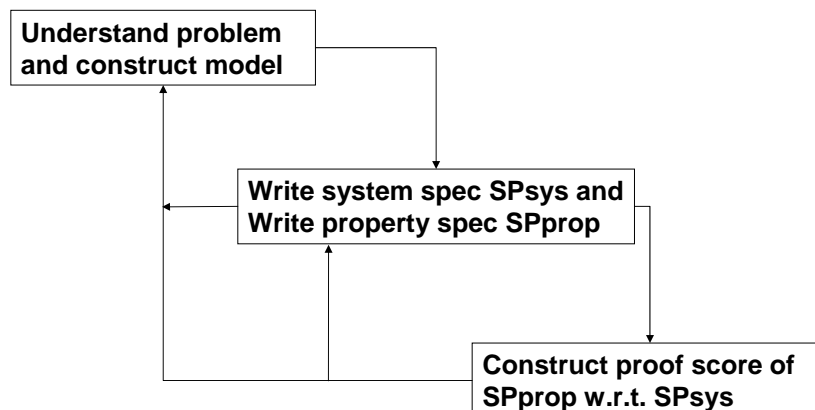
1. By understanding a problem to be modeled/specified, determine **several sorts of objects (entities, data, agents, states) and operations (functions, actions, events) over them** for describing the problem
2. Define the meanings/functions of the operations by declaring **equations over expressions/terms composed of the operations**
3. Write **proof scores** for properties to be verified

LectureNote8, i613-0712

3

## MSV with proof scores in CafeOBJ

---



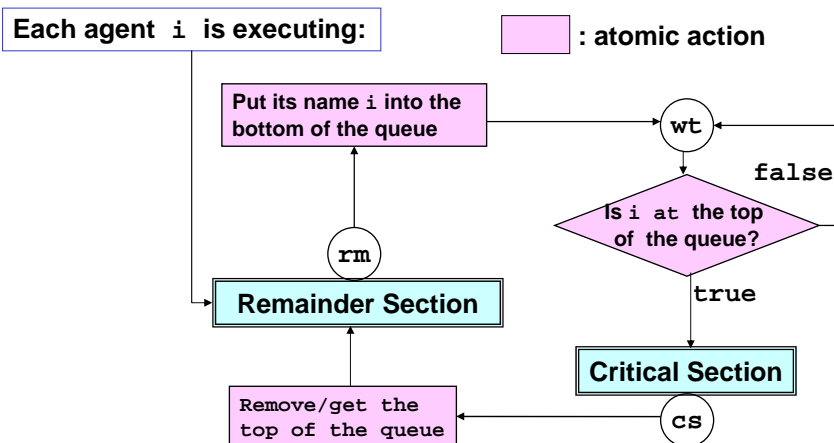
LectureNote8, i613-0712

4

## An example: mutual exclusion protocol

Assume that many agents (or processes) are competing for a common equipment, but at any moment of time only one agent can use the equipment. That is, the agents are mutually excluded in using the equipment. A protocol (mechanism or algorithm) which can achieve the mutual exclusion is called “mutual exclusion protocol”.

## QLOCK (locking with queue): a mutual exclusion protocol

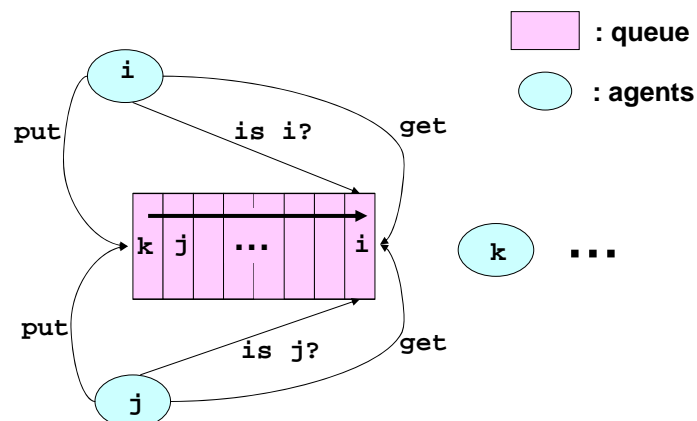


## QLOCK: basic assumptions/characteristics

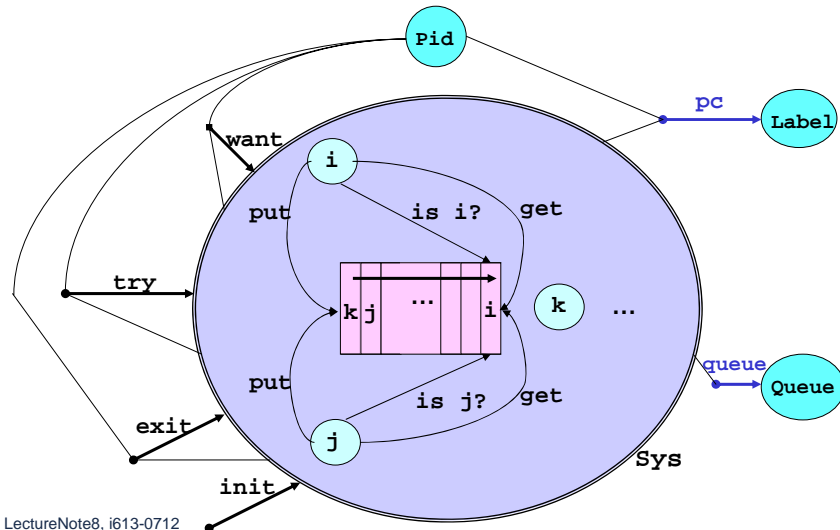
- There is only one queue and all agents/processes share the queue.
- Any basic action on the queue is inseparable (or atomic). That is, when any action is executed on the queue, no other action can be executed until the current action is finished.
- There may be unbounded number of agents.
- In the initial state, every agents are in the remainder section (or at the label  $rm$ ), and the queue is empty.

The property to be shown is that at most one agent is in the critical section (or at the label  $cs$ ) at any moment.

## Global (or macro) view of QLOCK



## Modeling QLOCK (via Signature Diagram) with OTS (Observational Transition System)



9

## Signature for QLOCKwithOTS

- **Sys** is the sort for representing the state space of the system.
- **Pid** is the sort for the set of agent/process names.
- **Label** is the sort for the set of labels; i.e.  $\{rm, wt, cs\}$ .
- **Queue** is the sort for the queues of **Pid**
- **pc** (program counter) is an observer returning a label where each agent resides.
- **queue** is an observer returning the current value of the waiting queue of **Pid**.
- **want** is an action for agent **i** of putting its name/id into the queue.
- **try** is an action for agent **i** of checking whether its name/id is at the top of the queue.
- **exit** is an action for agent **i** of removing/getting its name/id from the top of the queue.

LectureNote8, i613-0712

10

## CafeOBJ signature for QLOCKwithOTS

-- state space of the system *[Sys]*	Hidden sort declaration
-- visible sorts for observation [Queue Pid Label]	visible sort declaration
-- observations bop pc : Sys Pid -> Label bop queue : Sys -> Queue	Observation declaration
-- actions bop want : Sys Pid -> Sys bop try : Sys Pid -> Sys bop exit : Sys Pid -> Sys	action declaration

LectureNote8, i613-0712

11

## Module LABEL specifying (via tight denotation/semantics) "labels" qlock.mod

```
mod! LABEL {  
  [Label]  
  ops rm wt cs : -> Label  
  pred (_=_) : Label Label {comm}  
  var L : Label  
  eq (L = L) = true .  
  eq (rm = wt) = false .  
  eq (rm = cs) = false .  
  eq (wt = cs) = false .  
}
```

Predicate ( $\_ = \_$ ) defines identity relation  
among  $rm$ ,  $wt$ , and  $cs$ .

LectureNote8, i613-0712

12

## Module PID specifying (via loose denotation) “agent/process names/identifiers”

qlock.mod

```
mod* PID {  
  [Pid < PidErr]  
  op none : -> PidErr  
  pred (_=_) : PidErr PidErr {comm}  
  var I : Pid .  
  eq (I = I) = true .  
  eq (none = I) = false .  
  -- (none = none) is not defined intentionally  
}
```

- The constant none of the sort PidErr is intended to indicate the result of getting top of the empty queue.
- Any element in the sort Pid is defined not equal to none, that is, return false for predicate ( $\_ = \_$ ).
- Notice that  $(\text{none} = \text{none})$  does not reduced to true or false.

LectureNote8, i613-0712

13

## Module QUEUE specifying “queue” (1) — an parameterized module

qlock.mod

```
mod* TRIVerr {  
  [Elt < Elterr]  
  op none : -> Elterr  
}  
mod! QUEUE(D :: TRIVerr) {  
  [Queue]  
  -- constructors  
  op empty : -> Queue {constr}  
  op _,_ : Queue Elt.D -> Queue {constr l-assoc}  
  -- operators  
  op put : Elt.D Queue -> Queue  
  op get : Queue -> Queue  
  op top : Queue -> Elterr.D  
  op empty? : Queue -> Bool
```

LectureNote8, i613-0712

14

## Module QUEUE specifying “queue” (2) — an parameterized module

qlock.mod

```
-- CafeOBJ variables
var Q : Queue
vars X Y : Elt.D
-- equations
eq put(X,empty) = empty,X .
eq put(X,(Q,Y)) = put(X,Q),Y .
-- get(empty) is not defined intentionally
eq get((Q,X)) = Q .
eq top(empty) = (none):EltErr.D .
eq top((Q,X)) = X .
eq empty?(empty) = true .
eq empty?((Q,X)) = false .
}
```

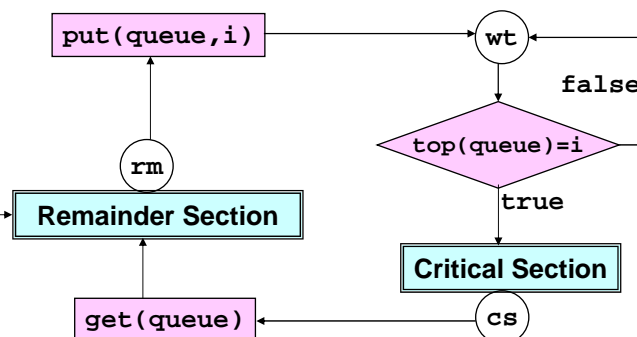
LectureNote8, i613-0712

15

## QLOCK using operators in the CafeOBJ module QUEUE

Each agent *i* is executing:

  : atomic action



LectureNote8, i613-0712

16



## Module QLOCK specifying “QLOCK” (1-1)

qlock.mod

```
view TRIVerr2PID from TRIVerr to PID {
  sort Elt -> Pid,
  sort EltErr -> PidErr,
  op (none):EltErr -> (none):PidErr }
```

```
mod* QLOCK {
  pr(LABEL)
  pr(QUEUE(D <= TRIVerr2PID))
  *[Sys]*
  -- any initial state
  op init : -> Sys
  -- observations
  bop pc : Sys Pid -> Label
  bop queue : Sys -> Queue
  -- actions
  bop want : Sys Pid -> Sys
  bop try : Sys Pid -> Sys
  bop exit : Sys Pid -> Sys
  -- for any initial state
  eq pc(init,I:Pid) = rm .
  eq queue(init) = empty .
```

LectureNote8, i613-0712

17

## Module QLOCK specifying “QLOCK” (1-2)

qlock.mod

```
mod* QLOCK {
  pr(LABEL)
  pr(QUEUE(PID{sort Elt -> Pid,
               sort EltErr -> PidErr,
               op (none):EltErr -> none):PidErr}))
  *[Sys]*
  -- any initial state
  op init : -> Sys
  -- observations
  bop pc : Sys Pid -> Label
  bop queue : Sys -> Queue
  -- actions
  bop want : Sys Pid -> Sys
  bop try : Sys Pid -> Sys
  bop exit : Sys Pid -> Sys
  -- for any initial state
  eq pc(init,I:Pid) = rm .
  eq queue(init) = empty .
```

LectureNote8, i613-0712

18

## Module QLOCK specifying "QLOCK" (2)

qlock.mod

```
var S : Sys . vars I J : Pid .
-- for want
op c-want : Sys Pid -> Bool {strat: (0 1 2)}
eq c-want(S,I) = (pc(S,I) = rm) .
--
ceq pc(want(S,I),J)
    = (if I = J then wt else pc(S,J) fi)
    if c-want(S,I) .
ceq queue(want(S,I)) = put(I,queue(S))
    if c-want(S,I) .
ceq want(S,I) = S
    if not c-want(S,I) .
```

LectureNote8, i613-0712

19

## Module QLOCK specifying "QLOCK" (3)

qlock.mod

```
-- for try
op c-try : Sys Pid -> Bool {strat: (0 1 2)}
eq c-try(S,I) = (pc(S,I) = wt and top(queue(S)) = I) .
--
ceq pc(try(S,I),J)
    = (if I = J then cs else pc(S,J) fi) if c-try(S,I) .
eq queue(try(S,I)) = queue(S) .
ceq try(S,I) = S if not c-try(S,I) .
-- for exit
op c-exit : Sys Pid -> Bool {strat: (0 1 2)}
eq c-exit(S,I) = (pc(S,I) = cs) .
--
ceq pc(exit(S,I),J)
    = (if I = J then rm else pc(S,J) fi) if c-exit(S,I) .
ceq queue(exit(S,I)) = get(queue(S)) if c-exit(S,I) .
ceq exit(S,I) = S if not c-exit(S,I) .
}
```

LectureNote8, i613-0712

20

## $(\_ \models \_)$ is congruent for OTS

The binary relation  $(s1:Sys \models s2:Sys)$  is defined to be true iff  $s1$  and  $s2$  have the same observation values.

OTS style of defining the possible changes of the values of observations is characterized by the equations of the form:

$o(a(s,d),d') = \dots o_1(s,d_1) \dots o_2(s,d_2) \dots o_n(s,d_n) \dots$   
for appropriate data values of  $d, d', d_1, d_2, \dots, d_n$ .

It can be shown that OTS style guarantees that  $(\_ \models \_)$  is congruent with respect to all actions.

## $R_{QLOCK}$ (set of reachable states) of $OTS_{QLOCK}$ (OTS defined by the module QLOCK)

### Signature determining $R_{QLOCK}$

```
-- any initial state
op init : -> Sys
-- actions
bop want : Sys Pid -> Sys
bop try  : Sys Pid -> Sys
bop exit : Sys Pid -> Sys
```

### Recursive definition of $R_{QLOCK}$

$$R_{QLOCK} = \{init\} \cup$$
$$\{want(s,i) \mid s \in R_{QLOCK}, i \in Pid\} \cup$$
$$\{try(s,i) \mid s \in R_{QLOCK}, i \in Pid\} \cup$$
$$\{exit(s,i) \mid s \in R_{QLOCK}, i \in Pid\}$$

## Mutual exclusion property as an invariant

invariants-0.mod

```
mod INV1 {
  pr(QLOCK)
  -- declare a predicate to verify to be an invariant
  pred inv1 : Sys Pid Pid
  -- CafeOBJ variables
  var S : Sys .
  vars I J : Pid .
  -- define inv1 to be the mutual exclusion property
  eq inv1(S,I,J)
    = (((pc(S,I) = cs) and (pc(S,J) = cs)) implies I = J) .
}
```

Formulation of proof goal for mutual exclusion property

$$\text{INV1} \models \forall s \in R_{\text{QLOCK}} \forall i, j \in \text{Pid}. \text{inv1}(s, i, j)$$

LectureNote8, i613-0712

23

## Induction scheme induced by the structure of $R_{\text{QLOCK}}$

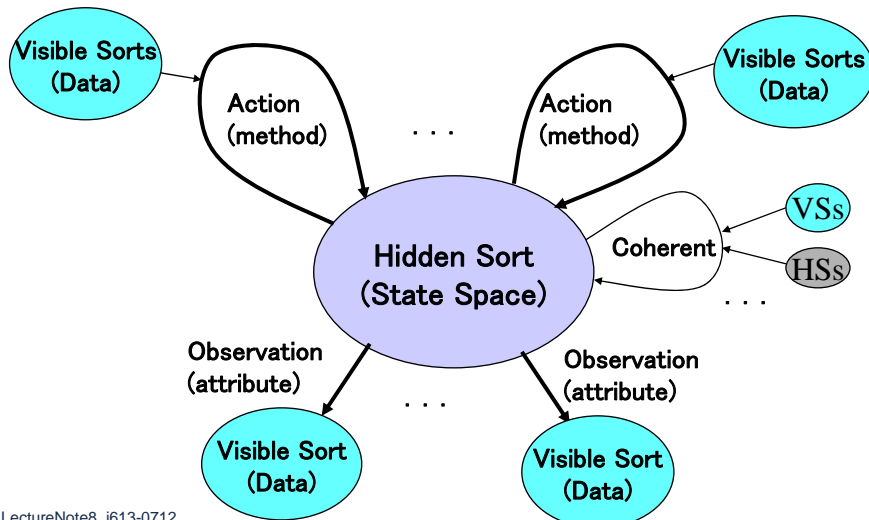
$$\text{mx}(s) \text{ =def= } \forall i, j \in \text{Pid}. \text{inv1}(s, i, j)$$

$$\begin{aligned} & \{ \\ & \quad \text{INV1} \models \text{mx}(\text{init}), \\ & \quad \text{INV1} \cup \{\text{mx}(s) = \text{true}\} \models \forall k. \text{mx}(\text{want}(s, k)), \\ & \quad \text{INV1} \cup \{\text{mx}(s) = \text{true}\} \models \forall k. \text{mx}(\text{try}(s, k)), \\ & \quad \text{INV1} \cup \{\text{mx}(s) = \text{true}\} \models \forall k. \text{mx}(\text{exit}(s, k)) \} \\ & \quad \text{implies} \\ & \quad \text{INV1} \models \forall s \in R_{\text{QLOCK}}. \text{mx}(s) \end{aligned}$$

LectureNote8, i613-0712

24

## Schematic signature diagram for OTS



25