

Probability Review Topics

1D distributions

discrete (pmf) vs continuous (pdf)

normalized vs unnormalized

examples [1 2 1] ; uniform(0,1); $1-x^2 \mid -1 \leq x \leq 1$; $N(0,1)$

2D (bivariate) distributions

joint distribution (with examples of discrete and continuous)

examples [0 5 5; 10 0 0; 2 4 6];

[1 1 1; 1 1 1; 1 1 1];

[1 2 1; 2 4 2; 1 2 1];

bivariate Gaussian

marginal distributions

conditional distributions

independence

conditional independence

Multivariate distributions

(vector of random variables $X=[x_1 \ x_2 \ x_3 \ \dots \ x_n]$)

Cumulative Distribution Function (cdf)

[note: tie in with integral images!]

Expectation / Expected Values

moments and central moments

mean, variance, covariance

"one-pass" computation of central moments

(useful for sequences / time series)

moments of binary images = shape descriptors

Probability distribution functions

Let $X = \{x_1, x_2, \dots, x_n\}$ discrete set
 $f_X(x_i)$ is a pmf (prob mass function)

if $f(x_i) \geq 0$

$$\sum_{i=1}^n f(x_i) = 1$$

$$P(X=x_i) = f(x_i)$$

Let $X = \mathbb{R}$ continuous

$f_X(x)$ is a pdf (prob density function)

if $f(x) \geq 0$

$$\int_{-\infty}^{\infty} f(x) dx = 1$$

$$P(a \leq x \leq b) = \int_a^b f(x) dx$$

note: $P(X=x_i) = 0$ for continuous variables!

Important concept: normalized vs unnormalized

$$f(x) \geq 0$$

$$\int_{-\infty}^{\infty} f(x) dx < \infty$$

Can be treated as an unnormalized distribution

we can turn it into a pdf by dividing by appropriate normalizing constant $C = \int_{-\infty}^{\infty} f(x) dx$

$$p(x) = f(x) / \int_{-\infty}^{\infty} f(x) dx$$

- after we learn distributions in unnormalized form (e.g. histograms)

~~some methods of inference can use unnormalized distributions directly~~

- a lot of sound & fury in statistical estimation has to do with computing the normalizing constant for high-dimensional distributions

- however some methods of inference & sampling can use unnormalized distributions directly!

Bivariate distribution

pmt $f(x, y) = P(X=x, Y=y) = \text{Prob } X=x \text{ and } Y=y$

so-called Joint distribution (2)

pdf $f(x, y)$: $P((x, y) \in A) = \iint_A f(x, y) dx dy$
some region of \mathbb{R}^2

running example pmts

$$\begin{bmatrix} 0 & 5 & 5 \\ 10 & 0 & 0 \\ 2 & 4 & 6 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$$

Marginal distributions.

Let $f(x, y)$ be a joint distribution

or $\int_y f(x, y) dy$

$$f_X(x) = P(X=x) = \sum_y P(X=x, Y=y) = \sum_y f(x, y)$$

similarly

$$f_Y(y) = P(Y=y) = \sum_x P(X=x, Y=y) = \sum_x f(x, y) \quad \text{or } \int_x f(x, y) dx$$

Simplified notation (that helps to derive algebraic manipulations)

$$P(X) = \sum_y P(X, y)$$

$$P(Y) = \sum_x P(X, y)$$

(2) Note: every meaningful statistical question can be answered (computed) from the joint distribution

Conditional distribution

$$P(x|y) = \frac{P(x, y)}{P(y)} = \frac{P(x, y)}{\sum_x P(x, y)}$$

also note: $P(x, y) = P(x|y)P(y) = P(y|x)P(x)$
 example of factoring a joint distribution.

Statistical Independence

r.v.'s x and y are independent if

$$P(x, y) = P(x)P(y)$$

note, in that case

$$P(x|y) = \frac{P(x, y)}{P(y)} = \frac{P(x)P(y)}{P(y)} = P(x)$$

Conditional Independence

a more subtle form of independence

$$P(x, y|z) = P(x|z)P(y|z)$$

note: This does not imply nor is it implied by
 statistical independence

cdf (cumulative distribution function)

$$P(X \leq x) \begin{cases} \sum_{t=0}^x P(X=t) & \text{discrete } p \\ \int_{-\infty}^x P(t) dt & \text{continuous } p \end{cases}$$

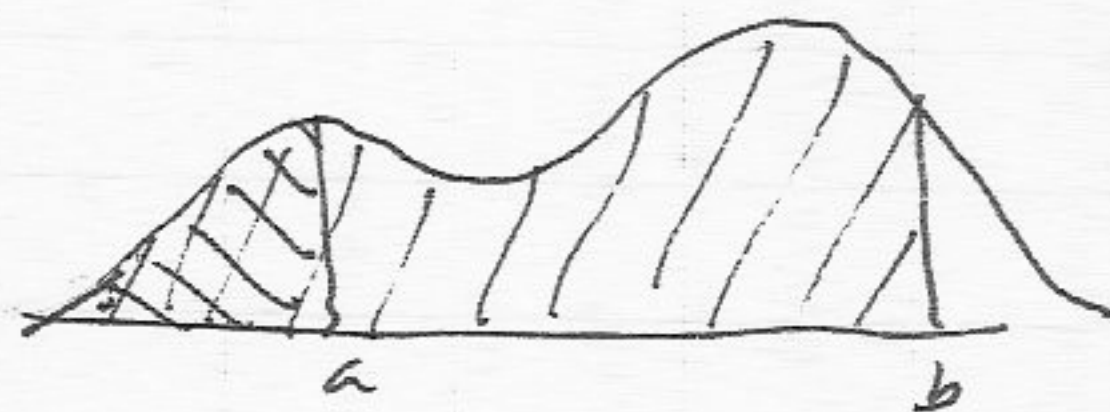
note: The cdf is a continuous function (defined over \mathbb{R}) even for discrete probability distributions

example $P_X(x) = \begin{bmatrix} 1/4 & 1/2 & 1/4 \end{bmatrix}$
 $x=0 \quad x=1 \quad x=2$

$$\text{cdf}(x) = F(x) = \begin{cases} 0 & x < 0 \\ 1/4 & 0 \leq x < 1 \\ 3/4 & 1 \leq x < 2 \\ 1 & x \geq 2 \end{cases}$$

note:

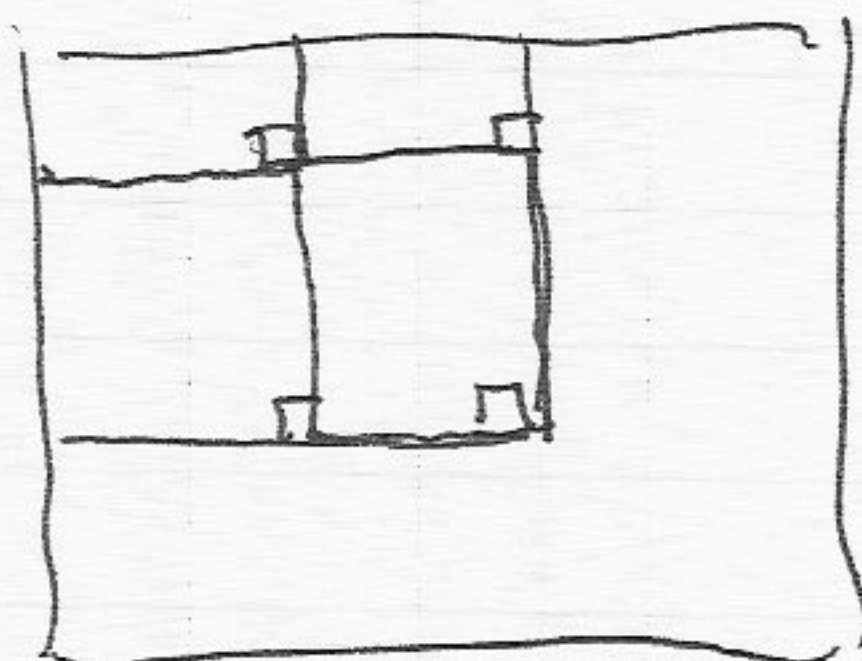
$$P(a \leq x \leq b) = F(b) - F(a) \\ = P(X \leq b) - P(X \leq a)$$



The in with integral images in vision

$$F(x, y) = \sum_{x=1}^x \sum_{y=1}^y I(x, y)$$

$$P(x_2 \leq x \leq x_H, y_2 \leq y \leq y_H)$$



$$F(x_H, y_H) - F(x_H, y_2-1) \\ - F(x_2-1, y_H) + F(x_2-1, y_2-1)$$

Expected values

$$E_x(g(x)) = \int_{-\infty}^{\infty} g(x) f(x) dx \quad \leftarrow \text{expected value}$$

examples

"mean" $E_x(x) = \int_{-\infty}^{\infty} x f(x) dx$ also known as 1st moment

discrete example of mean $P(x) = \begin{matrix} x=0 & x=1 & x=2 \\ 1 & 2 & 3 \end{matrix} \times \frac{1}{6}$

$$E(x) = 0 \cdot \frac{1}{6} + 1 \cdot \frac{2}{6} + 2 \cdot \frac{3}{6}$$

$$= \frac{1}{3} + 1 = \frac{4}{3}$$

Note that this is not a value (in this example) that can be taken by this discrete random variable!

mode of this example = argument of largest probability = 2
it is the "most probable" value

~~2nd central moment~~ vs variance

$$E(x^2) \quad \text{vs} \quad E((x-\mu)^2)$$

$$E[(x-\mu)^2] = E[x^2 - 2\mu x + \mu^2]$$

$$= E[x^2] - 2\mu \underbrace{E[x]}_{\mu} + \mu^2$$

$$= E[x^2] - (E[x])^2$$

note: expectation is a linear operator!

a function of 1st & 2nd central moments

$$\text{cov}(x, y) = E_{xy}[(x-\mu_x)(y-\mu_y)]$$