# Roadmap, Jan 20

#### **SRTE Quote:**

The course kind of felt like it was in disarray most of the time, but it worked out in the end.

### What We've Done so Far

- Reading: Chaps 2-4 of Prince Book
- Review of probability theory
- MLE vs MAP
  - Frequentist vs Bayesian

## Where we are Heading

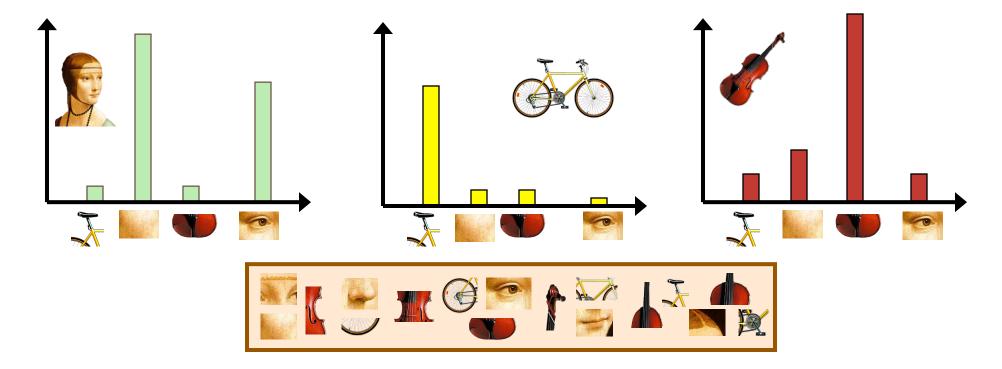
- Bag of (Visual) Words Modeling
  - Scene recognition; Object recognition





### Bag of Words Overview

- Extract features sparse or dense points in continuous vector space
- Learn "visual vocabulary" Training set. Clustering to get visual "words" e.g. K-means
- Quantize features using visual vocabulary 3.
- Represent images by frequencies of 4. MAP estimate of categorical distribution "visual words"



## Where we are Heading

- MLE/MAP estimation of Categorical Distribution
  - Today: revisit Bernoulli with new notation that more easily generalizes to Categorical (Homework 1)
- Feature Extraction (Read 13.1-13.3 of Prince)
- Clustering
  - K-means derivation (most common)
  - Other alternatives: mean-shift, K-medoids, quickshift
- Bag of Words (Read 20.1-20.2 of Prince)
- Also, Readings and Critiques of BoW papers.

## Where we are Heading

- MLE/MAP estimation of Categorical Distribution
  - Today: revisit Bernoulli with new notation that more easily generalizes to Categorical (Homework 1)
- Feature Extraction (Read 13.1-13.3 of Prince)
- Clustering
  - K-means derivation (most common)
  - Other alternatives: mean-shift, K-medoids, quickshift
- Bag of Words (Read 20.1-20.2 of Prince)
- Also, Readings and Critiques of BoW papers.

### **Conjugate Distributions**

We need probability distributions over model parameters as well as over data and world state. Hence, some distributions describe the parameters of others:

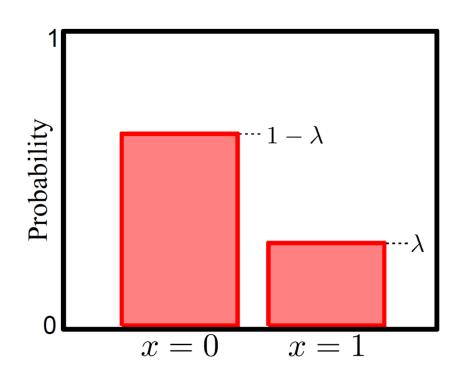
Distribution	Domain	Parameters modeled by
Bernoulli	$x \in \{0, 1\}$	beta
categorical	$x \in \{1, 2, \dots, K\}$	Dirichlet
univariate normal	$x \in \mathbb{R}$	normal inverse gamma
multivariate normal	$\mathbf{x} \in \mathbb{R}^k$	normal inverse Wishart

### **Conjugate Distributions**

We need probability distributions over model parameters as well as over data and world state. Hence, some distributions describe the parameters of others:

	Distribution	Domain	Parameters modeled by
П	Bernoulli	$x \in \{0, 1\}$	beta
	categorical	$x \in \{1, 2, \dots, K\}$	Dirichlet
	univariate normal	$x \in \mathbb{R}$	normal inverse gamma
	multivariate normal	$\mathbf{x} \in \mathbb{R}^k$	normal inverse Wishart

### Bernoulli Distribution



$$Pr(x=0) = 1 - \lambda$$

$$Pr(x=1) = \lambda.$$

or

$$Pr(x) = \lambda^x (1 - \lambda)^{1 - x}$$

For short we write:

$$Pr(x) = \operatorname{Bern}_x[\lambda]$$

Bernoulli distribution describes situation where only two possible outcomes y=0/y=1 or failure/success

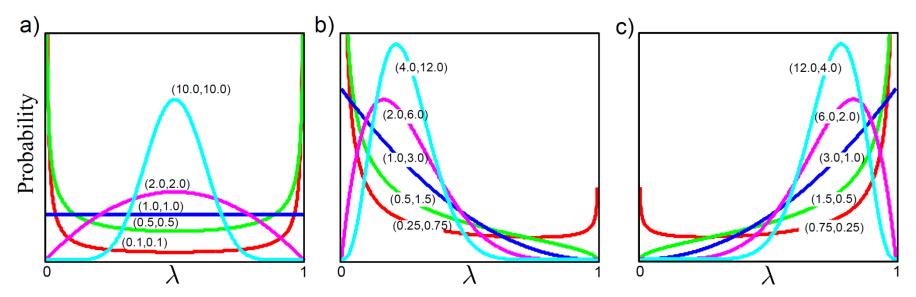
Takes a single parameter  $\lambda \in [0,1]$ 

#### **Beta Distribution**

Defined over data  $\lambda \in [0,1]$  (i.e. parameter of Bernoulli)

$$Pr(\lambda) = \frac{\Gamma[\alpha + \beta]}{\Gamma[\alpha]\Gamma[\beta]} \lambda^{\alpha - 1} (1 - \lambda)^{\beta - 1}$$

$$\Gamma(z) = \int_0^\infty t^{z-1} e^{-t} dt$$
$$\Gamma(z) = (z-1)!$$

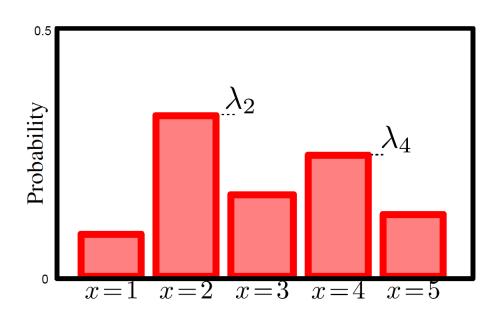


- Two parameters  $\alpha, \beta$  both > 0
- Mean depends on relative values  $E[\lambda] = \alpha/(\alpha + \beta)$ .
- Concentration depends on magnitude

For short we write:

$$Pr(\lambda) = \text{Beta}_{\lambda}[\alpha, \beta]$$

## Categorical Distribution



$$Pr(x=k)=\lambda_k$$

or can think of data as vector with all elements zero except  $k^{th}$  e.g.  $e_4$  = [0,0,0,1,0]

$$Pr(\mathbf{x} = \mathbf{e}_k) = \prod_{j=1}^K \lambda_j^{x_j} = \lambda_k$$

For short we write:

$$Pr(x) = \operatorname{Cat}_x [\boldsymbol{\lambda}]$$

Categorical distribution describes situation where K possible outcomes y=1...y=k.

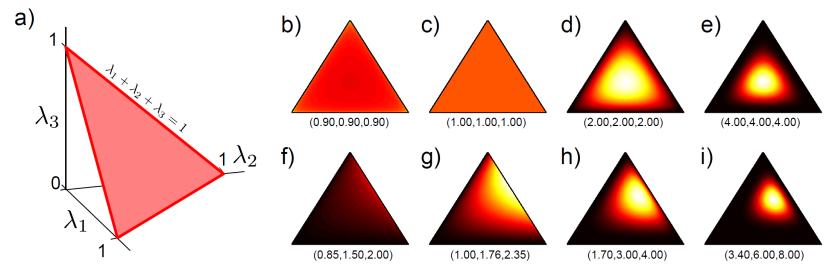
Takes K parameters  $\lambda_k \in [0,1]$  where  $\sum_k \lambda_k = 1$ 

### Dirichlet Distribution

$$Pr(\lambda_1 \dots \lambda_K) = \frac{\Gamma[\sum_{k=1}^K \alpha_k]}{\prod_{k=1}^K \Gamma[\alpha_k]} \prod_{k=1}^K \lambda_k^{\alpha_k - 1}$$

Or for short:  $Pr(\lambda_1 \dots \lambda_K) = \operatorname{Dir}_{\lambda_1 \dots K} [\alpha_1, \alpha_2, \dots, \alpha_K]$ 

Has k parameters  $\alpha_k > 0$ 



Computer vision: models, learning and inference. ©2011 Simon J.D. Prince