

# Aerial Perching

**Prepared by:** Huy Quang Nguyen

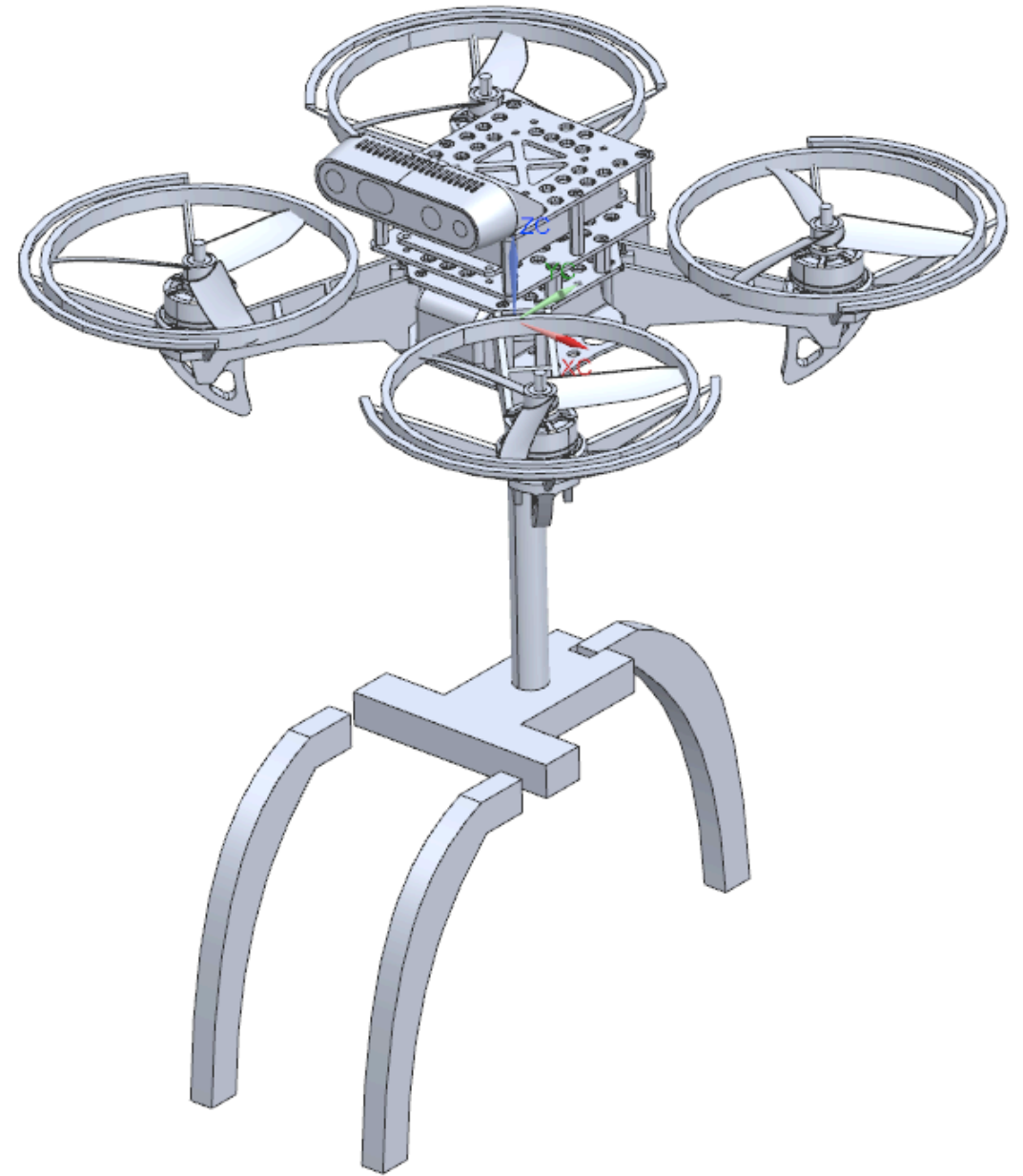
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# Accomplishments

- **Completed Tasks:**
  - Understood the code
  - Controlled the quadcopter to fly from A to B (inside the object)

## Tasks in Progress

- Making the gripper



## Tasks in Progress

- Adding the drone to ISAACSIM

## Next Steps

- Control the quadcopter to fly from A to B