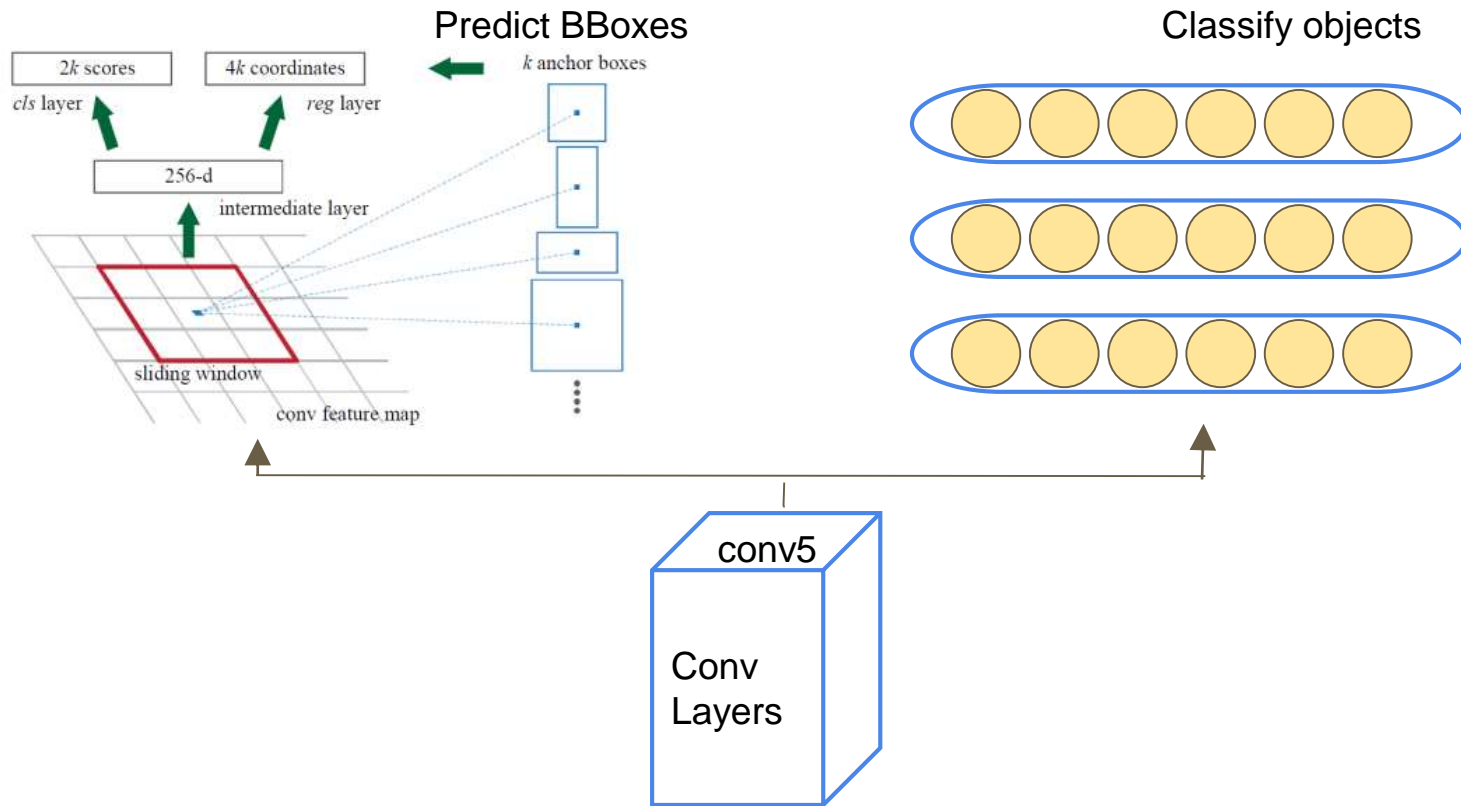
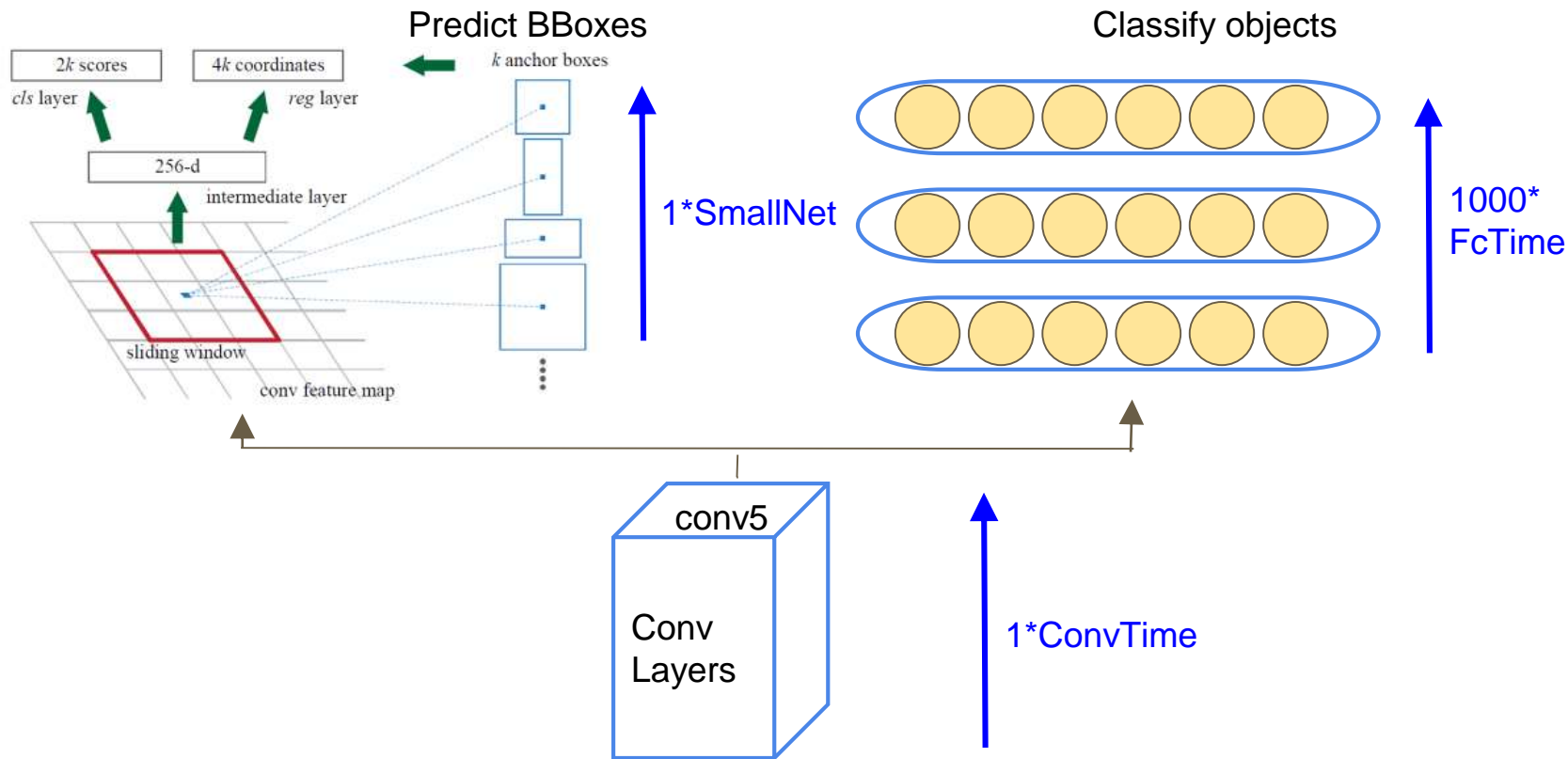

Faster R-CNN: Towards Real-Time Object detection

— Microsoft Research, NIPS2015 —
Presenter: Andy Tsai

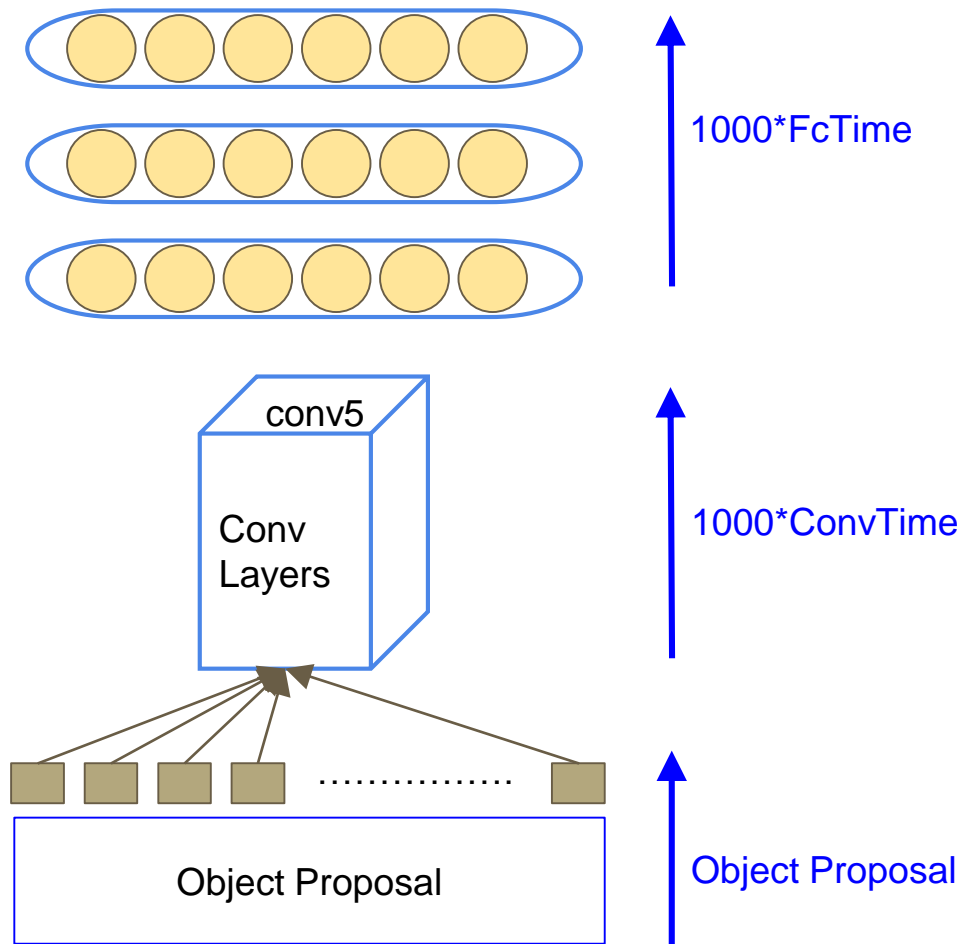
Key Idea: Region Proposal Net (RPN) layer



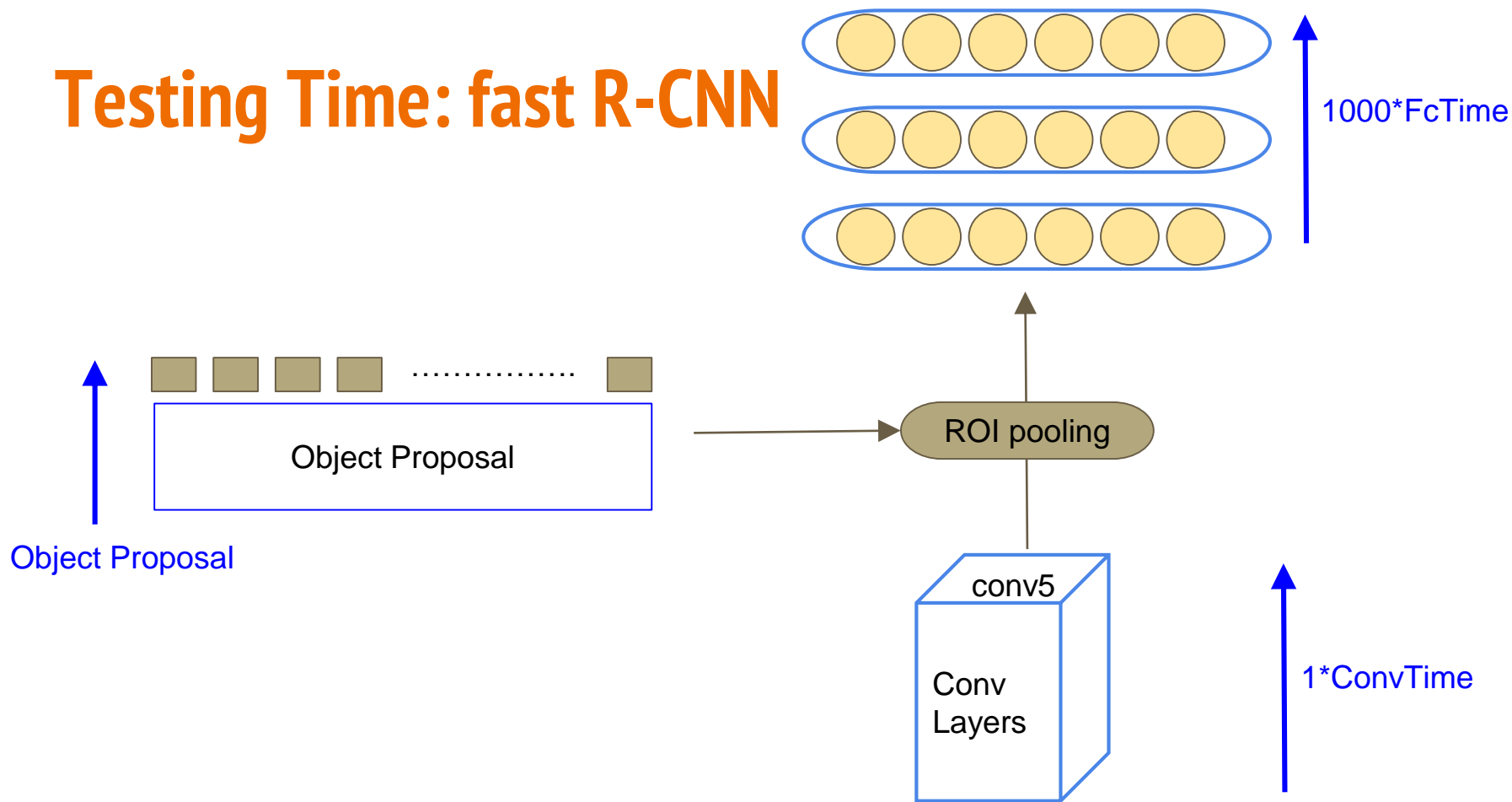
Testing Time: faster R-CNN



Testing Time: R-CNN



Testing Time: fast R-CNN



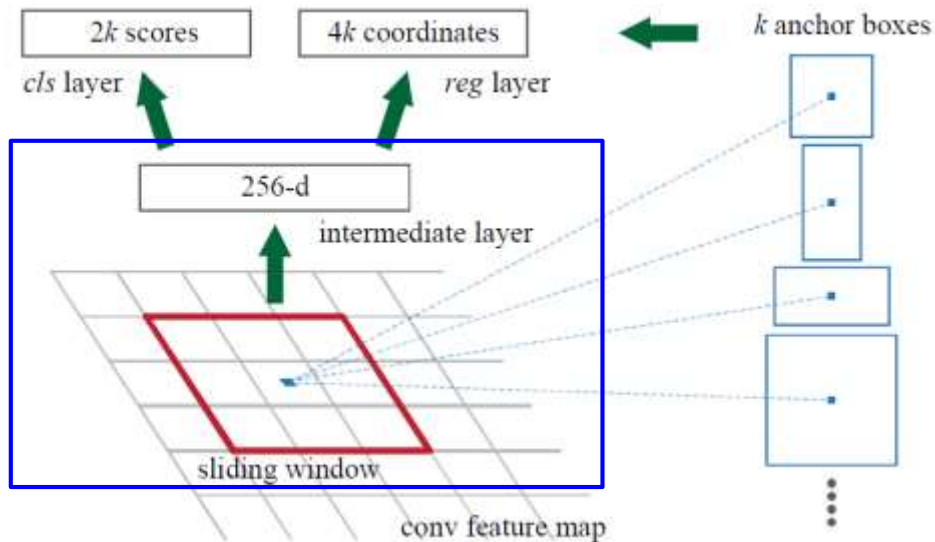
Fast, Accurate Object Detection

- fastest region proposal method: Edge Boxes [4fps, 1000 proposal]
- Testing stage

Model	Time
Edge boxes + R-CNN	$0.25 \text{ sec} + 1000 * \text{ConvTime} + 1000 * \text{FcTime}$
Edge boxes + fast R-CNN	$0.25 \text{ sec} + 1 * \text{ConvTime} + 1000 * \text{FcTime}$
faster R-CNN	$1 * \text{ConvTime} + 1000 * \text{FcTime}$

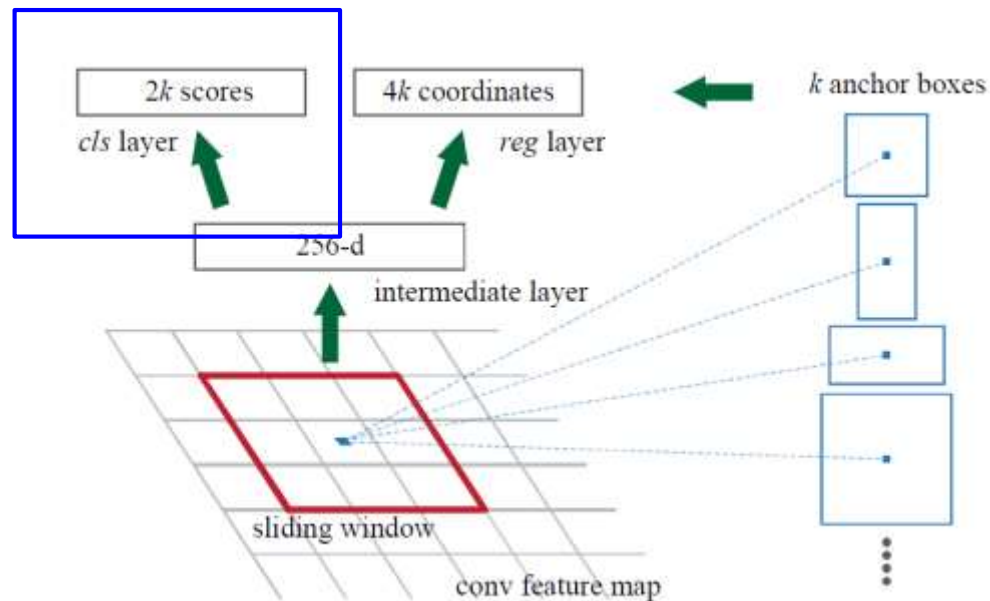
RPN layer

```
368 layer {
369   name: "rpn_conv/3x3"
370   type: "Convolution"
371   bottom: "conv5_3"
372   top: "rpn/output"
373   param { lr_mult: 1.0 }
374   param { lr_mult: 2.0 }
375   convolution_param {
376     num_output: 512
377     kernel_size: 3 pad: 1 stride: 1
378     weight_filler { type: "gaussian" std: 0.01 }
379     bias_filler { type: "constant" value: 0 }
380   }
381 }
382 layer {
383   name: "rpn_relu/3x3"
384   type: "ReLU"
385   bottom: "rpn/output"
386   top: "rpn/output"
387 }
```



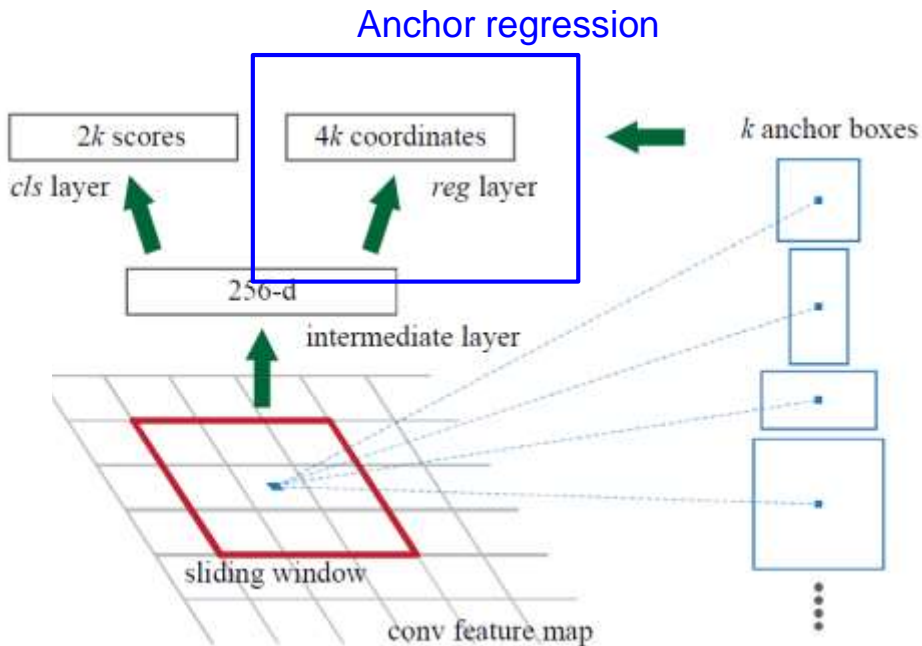
RPN layer

```
389 layer {
390   name: "rpn_cls_score"
391   type: "Convolution"
392   bottom: "rpn/output"
393   top: "rpn_cls_score"
394   param { lr_mult: 1.0 }
395   param { lr_mult: 2.0 }
396   convolution_param {
397     num_output: 18 # 2(bg/fg) * 9(anchors)
398     kernel_size: 1 pad: 0 stride: 1
399     weight_filler { type: "gaussian" std: 0.01 }
400     bias_filler { type: "constant" value: 0 }
401   }
402 }
```



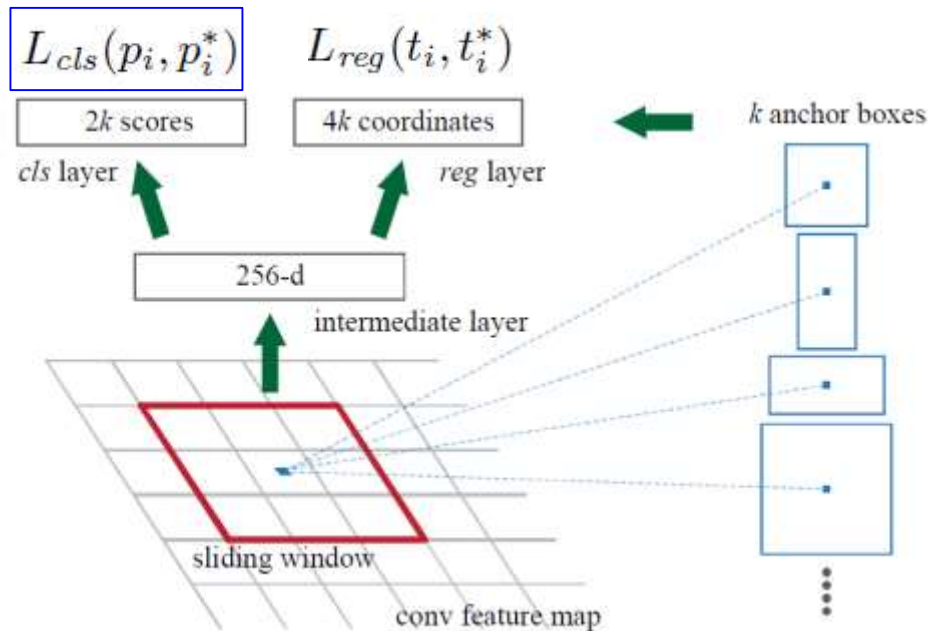
RPN layer

```
404 layer {  
405   name: "rpn_bbox_pred"  
406   type: "Convolution"  
407   bottom: "rpn/output"  
408   top: "rpn_bbox_pred"  
409   param { lr_mult: 1.0 }  
410   param { lr_mult: 2.0 }  
411   convolution_param {  
412     num_output: 36 # 4 * 9(anchors)  
413     kernel_size: 1 pad: 0 stride: 1  
414     weight_filler { type: "gaussian" std: 0.01 }  
415     bias_filler { type: "constant" value: 0 }  
416   }  
417 }
```



RPN: Loss Function

- 2 class Softmax cross entropy loss
- Discriminative training:
 - $p_i^* = 1$ if IoU > 0.7
 - $p_i^* = 0$ if IoU < 0.3
 - otherwise, do not contribute to loss



$$L(\{p_i\}, \{t_i\}) = \frac{1}{N_{cls}} \sum_i L_{cls}(p_i, p_i^*) + \lambda \frac{1}{N_{reg}} \sum_i p_i^* L_{reg}(t_i, t_i^*).$$

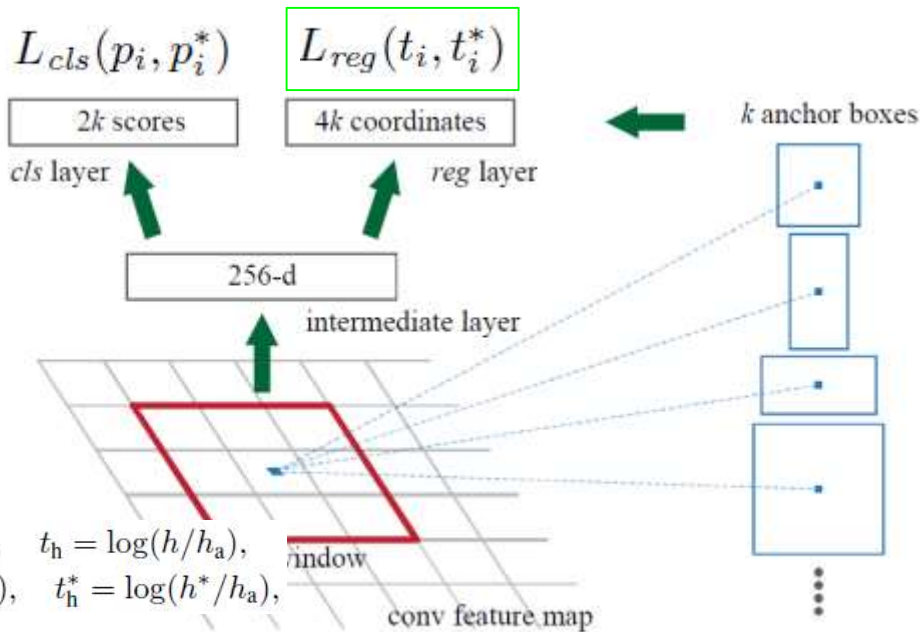
RPN: Loss Function

$$L_{\text{loc}}(t, t^*) = \sum_{i \in \{x, y, w, h\}} \text{smooth}_{L_1}(t_i, t_i^*), \quad (2)$$

in which

$$\text{smooth}_{L_1}(x) = \begin{cases} 0.5x^2 & \text{if } |x| < 1 \\ |x| - 0.5 & \text{otherwise,} \end{cases} \quad (3)$$

$$\begin{aligned} t_x &= (x - x_a)/w_a, & t_y &= (y - y_a)/h_a, & t_w &= \log(w/w_a), & t_h &= \log(h/h_a), \\ t_x^* &= (x^* - x_a)/w_a, & t_y^* &= (y^* - y_a)/h_a, & t_w^* &= \log(w^*/w_a), & t_h^* &= \log(h^*/h_a), \end{aligned}$$



$$L(\{p_i\}, \{t_i\}) = \frac{1}{N_{cls}} \sum_i L_{cls}(p_i, p_i^*) + \lambda \frac{1}{N_{reg}} \sum_i p_i^* L_{reg}(t_i, t_i^*).$$

only positive sample contribute to reg. Loss

How to train faster R-CNN ?

- balance sampling (neg. vs pos. = 1:1)
- joint training is almost impossible (conv update alternating)
- 4 step training !

How to train faster R-CNN ?

1. train RPN with ImageNet pre-trained model
2. train fast R-CNN using proposal generated by 1. [no params. sharing]
3. use conv trained by 2. to initialize model, fix shared conv, update RPN
4. fix shared conv, fine-tune fc

Result - MAP

- VOC2007, ZF ConvNet

train-time region proposals		test-time region proposals		mAP (%)
method	# boxes	method	# proposals	
SS	2k	SS	2k	58.7
EB	2k	EB	2k	58.6
RPN+ZF, shared	2k	RPN+ZF, shared	300	59.9
<i>ablation experiments follow below</i>				
RPN+ZF, unshared	2k	RPN+ZF, unshared	300	58.7

Result - MAP

Using VGG ConvNet, fast R-CNN vs faster R-CNN

method	# proposals	data	mAP (%)	time (ms)
SS	2k	07	66.9 [†]	1830
SS	2k	07+12	70.0	1830
RPN+VGG, unshared	300	07	68.5	342
RPN+VGG, shared	300	07	69.9	198
RPN+VGG, shared	300	07+12	73.2	198

Result - Time

VOC 2007, fast R-CNN vs faster R-CNN

	model	system	conv	proposal	region-wise	total	rate
70.0%	VGG	SS + Fast R-CNN	146	1510	174	1830	0.5 fps
73.2%	VGG	RPN + Fast R-CNN	141	10	47	198	5 fps
59.9%	ZF	RPN + Fast R-CNN	31	3	25	59	17 fps

Official Leader Board Score

Table 6: Results on PASCAL VOC 2007 test set with Fast R-CNN detectors and VGG-16. For RPN, the train-time proposals for Fast R-CNN are 2k. RPN* denotes the unsharing feature version.

method	# box	data	mAP	areo	bike	bird	boat	bottle	bus	car	cat	chair	cow	table	dog	horse	mbike	person	plant	sheep	sofa	train	tv
SS	2k	07	66.9	74.5	78.3	69.2	53.2	36.6	77.3	78.2	82.0	40.7	72.7	67.9	79.6	79.2	73.0	69.0	30.1	65.4	70.2	75.8	65.8
SS	2k	07+12	70.0	77.0	78.1	69.3	59.4	38.3	81.6	78.6	86.7	42.8	78.8	68.9	84.7	82.0	76.6	69.9	31.8	70.1	74.8	80.4	70.4
RPN*	300	07	68.5	74.1	77.2	67.7	53.9	51.0	75.1	79.2	78.9	50.7	78.0	61.1	79.1	81.9	72.2	75.9	37.2	71.4	62.5	77.4	66.4
RPN	300	07	69.9	70.0	80.6	70.1	57.3	49.9	78.2	80.4	82.0	52.2	75.3	67.2	80.3	79.8	75.0	76.3	39.1	68.3	67.3	81.1	67.6
RPN	300	07+12	73.2	76.5	79.0	70.9	65.5	52.1	83.1	84.7	86.4	52.0	81.9	65.7	84.8	84.6	77.5	76.7	38.8	73.6	73.9	83.0	72.6

Table 7: Results on PASCAL VOC 2012 test set with Fast R-CNN detectors and VGG-16. For RPN, the train-time proposals for Fast R-CNN are 2k.

method	# box	data	mAP	areo	bike	bird	boat	bottle	bus	car	cat	chair	cow	table	dog	horse	mbike	person	plant	sheep	sofa	train	tv
SS	2k	12	65.7	80.3	74.7	66.9	46.9	37.7	73.9	68.6	87.7	41.7	71.1	51.1	86.0	77.8	79.8	69.8	32.1	65.5	63.8	76.4	61.7
SS	2k	07++12	68.4	82.3	78.4	70.8	52.3	38.7	77.8	71.6	89.3	44.2	73.0	55.0	87.5	80.5	80.8	72.0	35.1	68.3	65.7	80.4	64.2
RPN	300	12	67.0	82.3	76.4	71.0	48.4	45.2	72.1	72.3	87.3	42.2	73.7	50.0	86.8	78.7	78.4	77.4	34.5	70.1	57.1	77.1	58.9
RPN	300	07++12	70.4	84.9	79.8	74.3	53.9	49.8	77.5	75.9	88.5	45.6	77.1	55.3	86.9	81.7	80.9	79.6	40.1	72.6	60.9	81.2	61.5

Code available at gitHub

Matlab(faster-rcnn) & python(py-faster-rcnn) version

Thank you :)