

Announcements -- Poster Session:

- **Monday Allen Center Atrium, 10:00am-1:00pm**
- Attendance is mandatory – one person should be at poster at all times
- Please prepare a 2 minute project pitch and a 5 minute project pitch to give to the TAs/instructor
- Upload your final report on Gradescope by Sunday 23:59pm – no late periods
- Upload your poster PDF on Gradescope by Monday 10am – no late periods
- Arrive on time / early to set up poster
- We'll have coffee, tea, snacks

Mining Data Streams (Part 2)

CS547 Machine Learning for Big Data

Tim Althoff



Today's Lecture

- **More algorithms for streams:**
 - **(1) Filtering a data stream: Bloom filters**
 - Select elements with property x from stream
 - **(2) Counting distinct elements: Flajolet-Martin**
 - Number of distinct elements in the last k elements of the stream
 - **(3) Estimating moments: AMS method**
 - Estimate std. dev. of last k elements

(1) Filtering Data Streams

Filtering Data Streams

- Each element of data stream is a tuple
- Given a list of keys S
- Determine which tuples of stream are in S
- Obvious solution: Hash table
 - But suppose we do not have enough memory to store all of S in a hash table
 - E.g., we might be processing millions of filters on the same stream

Applications

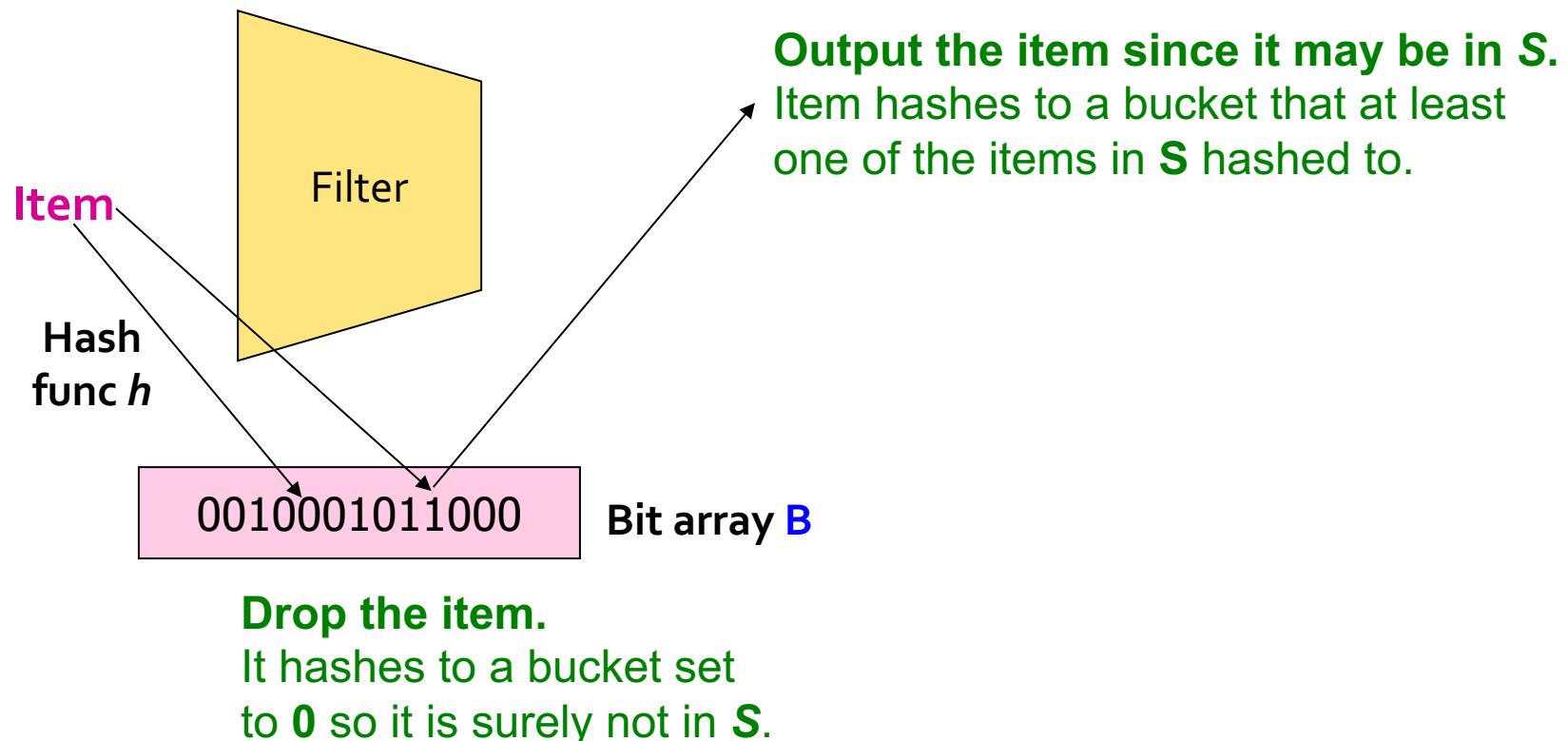
- **Example: Email spam filtering**
 - We know 1 billion “good” email addresses
 - Or, each user has a list of trusted addresses
 - If an email comes from one of these, it is **NOT** spam
- **Publish-subscribe systems**
 - You are collecting lots of messages (news articles)
 - People express interest in certain sets of keywords
 - Determine whether each message matches user’s interest
- **Content filtering:**
 - You want to make sure the user does not see the same ad multiple times

First Cut Solution (1)

Given a set of keys S that we want to filter

- Create a **bit array B** of n bits, initially all **0s**
- Choose a **hash function h** with range **$[0,n)$**
- Hash each member of $s \in S$ to one of n buckets, and set that bit to **1**, i.e., $B[h(s)] = 1$
- Hash each element a of the stream and output only those that hash to bit that was set to **1**
 - **Output a if $B[h(a)] == 1$**

First Cut Solution (2)



- **Creates false positives but no false negatives**
 - If the item is in S we surely output it, if not we may still output it

First Cut Solution (3)

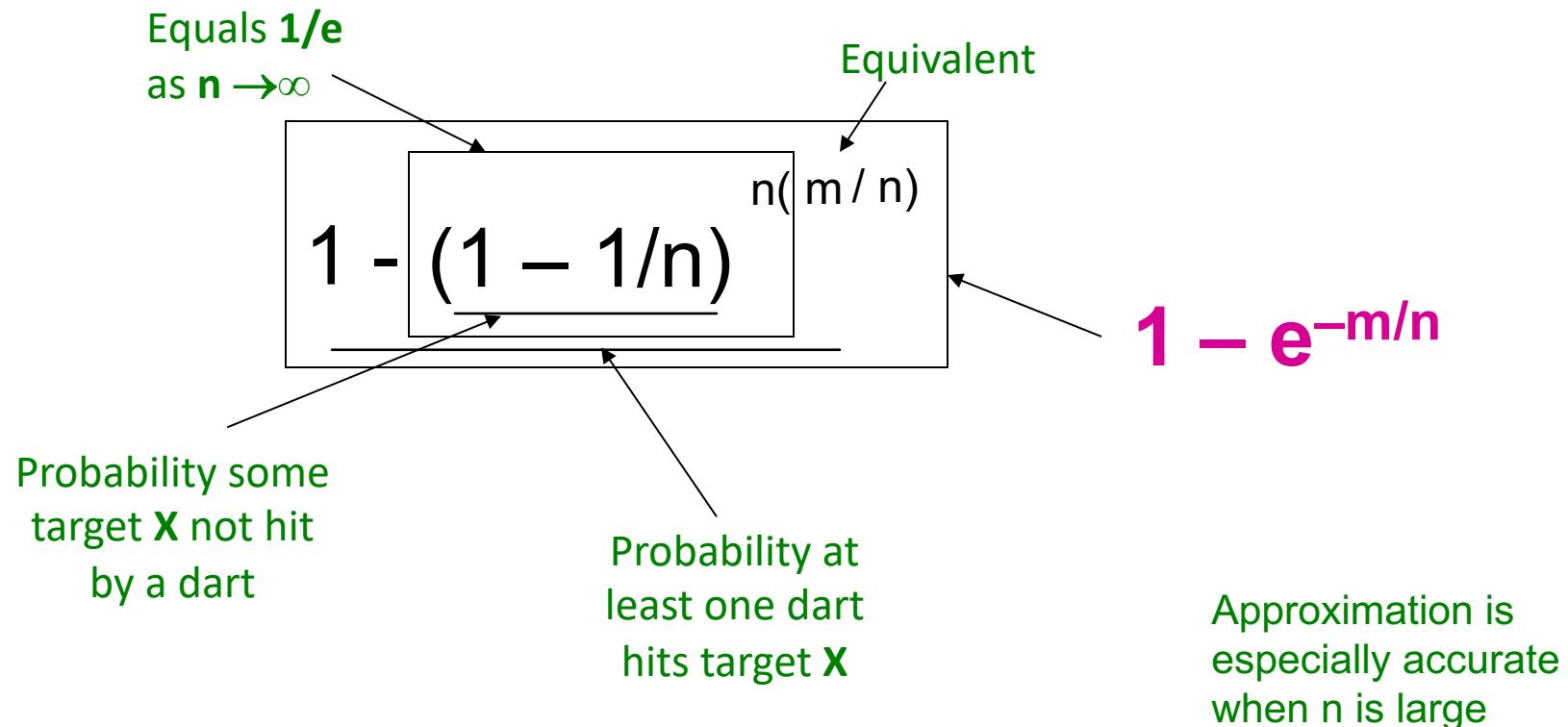
- $|S| = 1 \text{ billion email addresses}$
 $|B| = 1\text{GB} = 8 \text{ billion bits}$
- If the email address is in S , then it surely hashes to a bucket that has the bit set to 1, so it always gets through (*no false negatives*)
- Approximately **1/8** of the bits are set to 1, so about **1/8th** of the addresses not in S get through to the output (*false positives*)
 - Actually, less than **1/8th**, because more than one address might hash to the same bit

Analysis: Throwing Darts (1)

- More accurate analysis for the number of **false positives**
- **Consider:** If we throw m darts into n equally likely targets, **what is the probability that a target gets at least one dart?**
- **In our case:**
 - Targets = bits/buckets
 - Darts = hash values of items

Analysis: Throwing Darts (2)

- We have m darts, n targets
- **What is the probability that a target gets at least one dart?**



Analysis: Throwing Darts (3)

- Fraction of 1s in the array B =
= probability of false positive = $1 - e^{-m/n}$
- Example: 10^9 darts, $8 \cdot 10^9$ targets
 - Fraction of 1s in B = $1 - e^{-1/8} = 0.1175$
 - Compare with our earlier estimate: $1/8 = 0.125$

Bloom Filter

- Consider: $|S| = m$, $|B| = n$
- Use k independent hash functions h_1, \dots, h_k
- **Initialization:**
 - Set B to all 0s
 - Hash each element $s \in S$ using each hash function h_i ,
set $B[h_i(s)] = 1$ (for each $i = 1, \dots, k$)
(note: we have a single array B!)
- **Run-time:**
 - When a stream element with key x arrives
 - If $B[h_i(x)] = 1$ for all $i = 1, \dots, k$ then declare that x is in S
 - That is, x hashes to a bucket set to 1 for every hash function $h_i(x)$
 - Otherwise discard the element x

Bloom Filter – Analysis

- What fraction of the bit vector B are 1s?
 - Throwing $k \cdot m$ darts at n targets
 - So fraction of 1s is $(1 - e^{-km/n})$
- But we have k independent hash functions and we only let the element x through if all k hash element x to a bucket of value 1
- So, false positive probability = $(1 - e^{-km/n})^k$

Bloom Filter – Analysis (2)

- **$m = 1$ billion, $n = 8$ billion**

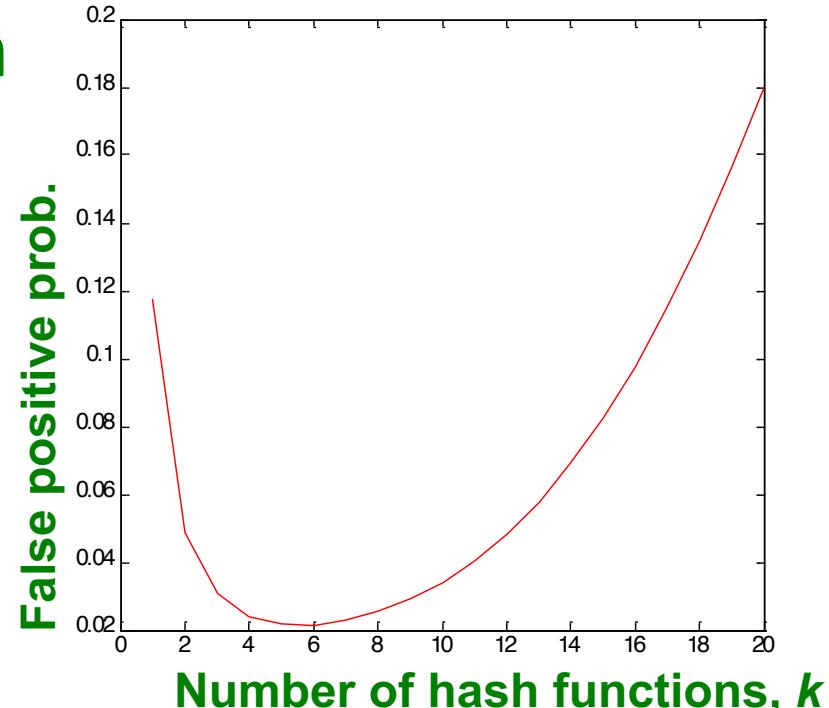
- $k = 1: (1 - e^{-1/8}) = 0.1175$
 - $k = 2: (1 - e^{-1/4})^2 = 0.0493$

- **What happens as we keep increasing k ?**

- Optimal value of k : $n/m \ln(2)$

- **In our case:** Optimal $k = 8 \ln(2) = 5.54 \approx 6$
 - Error at $k = 6: (1 - e^{-3/4})^6 = 0.0216$

Optimal k : k which gives the lowest false positive probability



Bloom Filter: Wrap-up

- Bloom filters allow for filtering / set membership
- **Bloom filters guarantee no false negatives, and use limited memory**
 - Great for pre-processing before more expensive checks
- **Suitable for hardware implementation**
 - Hash function computations can be parallelized
- Is it better to have **1 big B** or **k small Bs**?
 - It is the same: $(1 - e^{-km/n})^k$ vs. $(1 - e^{-m/(n/k)})^k$
 - But keeping **1 big B** is simpler

(2) Counting Distinct Elements

Counting Distinct Elements

■ Problem:

- Data stream consists of a universe of elements chosen from a set of size N
- Maintain a count of the number of distinct elements seen so far

■ Obvious approach:

Maintain the set of elements seen so far

- That is, keep a hash table of all the distinct elements seen so far

Applications

- **How many different words are found among the Web pages being crawled at a site?**
 - Unusually low or high numbers could indicate artificial pages (spam?)
- **How many different Web pages does each customer request in a week?**
- **How many distinct products have we sold in the last week?**

Using Small Storage

- Real problem: What if we do not have space to maintain the set of elements seen so far?
- Estimate the count in an unbiased way
- Accept that the count may have a little error, but limit the probability that the error is large

Flajolet-Martin Approach

- Pick a hash function h that maps each of the N elements to at least $\log_2 N$ bits
- For each stream element a , let $r(a)$ be the number of trailing 0s in $h(a)$
 - $r(a) = \text{position of first 1 counting from the right}$
 - E.g., say $h(a) = 12$, then 12 is 1100 in binary, so $r(a) = 2$
- Record $R = \text{the maximum } r(a) \text{ seen}$
 - $R = \max_a r(a)$, over all the items a seen so far
- **Estimated number of distinct elements = 2^R**

Why It Works: Intuition

- Very rough and heuristic intuition why Flajolet-Martin works:
 - $h(a)$ hashes a with **equal prob.** to any of N values
 - Then $h(a)$ is a sequence of $\log_2 N$ bits, where 2^{-r} fraction of all a s have a tail of r zeros
 - About 50% of a s hash to ***0
 - About 25% of a s hash to **00
 - So, if we saw the longest tail of $r=2$ (i.e., item hash ending *100) then we have probably seen **about 4** distinct items so far
 - **So, it takes to hash about 2^r items before we see one with zero-suffix of length r**

Why It Works: More formally

- Now we show why Flajolet-Martin works
- Formally, we will show that probability of finding a tail of r zeros:
 - Goes to 1 if $m \gg 2^r$
 - Goes to 0 if $m \ll 2^r$
- where m is the number of distinct elements seen so far in the stream
- Thus, 2^R will almost always be around m !

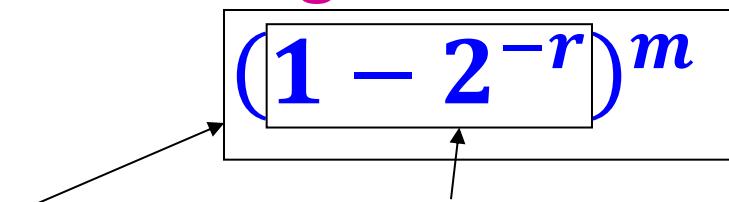
Why It Works: More formally

- What is the probability that a given $h(a)$ ends in at least r zeros? It is 2^{-r}
 - $h(a)$ hashes elements uniformly at random
 - Probability that a random number ends in at least r zeros is 2^{-r}
- Then, the probability of NOT seeing a tail of length r among m distinct elements:

$$(1 - 2^{-r})^m$$

Prob. all m elements end in fewer than r zeros.

Prob. that given $h(a)$ ends in fewer than r zeros



Why It Works: More formally

- **Note:** $(1 - 2^{-r})^m = (1 - 2^{-r})^{2^r(m2^{-r})} \approx e^{-m2^{-r}}$
- **Prob. of NOT finding a tail of length r is:**
 - If $m \ll 2^r$, then prob. tends to **1**
 - $(1 - 2^{-r})^m \approx e^{-m2^{-r}} = 1$ as $m/2^r \rightarrow 0$
 - So, the probability of finding a tail of length r tends to **0**
 - If $m \gg 2^r$, then prob. tends to **0**
 - $(1 - 2^{-r})^m \approx e^{-m2^{-r}} = 0$ as $m/2^r \rightarrow \infty$
 - So, the probability of finding a tail of length r tends to **1**
- **Thus, 2^R will almost always be around m !**

Why It Doesn't Work

- **E[2^R] is actually infinite**
 - Observing R has some probability
 - Probability halves when $R \rightarrow R+1$, but value doubles
 - Each possible large R contributes to exp. value
- **Workaround involves using many hash functions h_i , and getting many samples of R_i**
- **How are samples R_i combined?**
 - **Average?** What if one very large value 2^{R_i} ?
 - **Median?** All estimates are a power of 2
 - **Solution:**
 - Partition your samples into small groups
 - Take the median of groups
 - Then take the average of the medians

(3) Computing Moments

Generalization: Moments

- Suppose a stream has elements chosen from a set A of N values
- Let m_i be the number of times value i occurs in the stream
- The k^{th} **moment** is

$$\sum_{i \in A} (m_i)^k$$

This is the same way as moments are defined in statistics. But there one typically “centers” the moment by subtracting the mean.

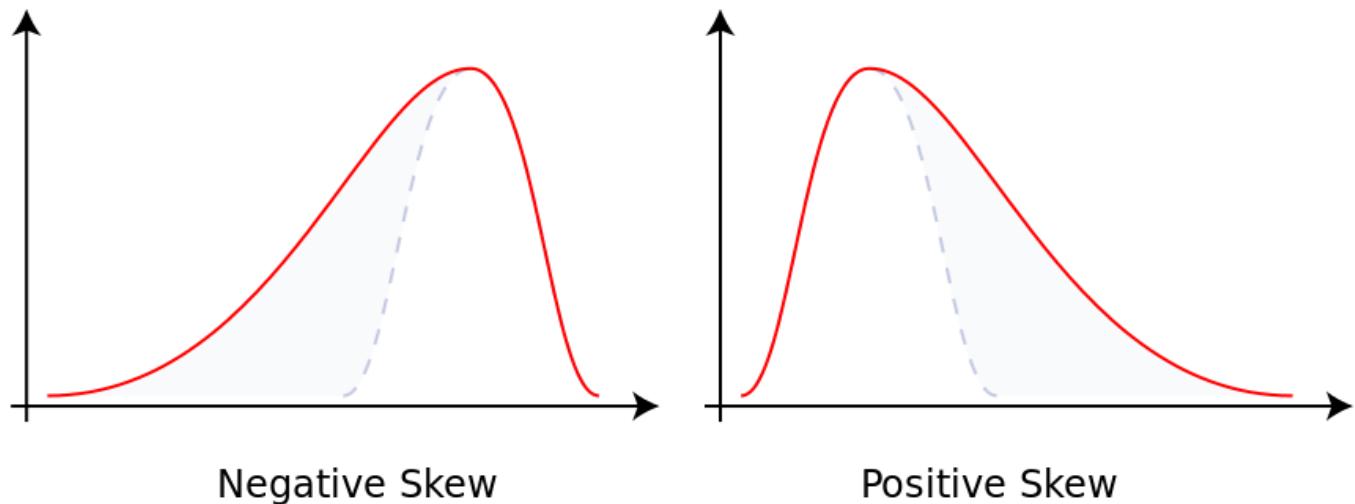
Special Cases

$$\sum_{i \in A} (m_i)^k$$

- **0th moment** = number of distinct elements
 - The problem just considered
- **1st moment** = count of the numbers of elements = length of the stream
 - Easy to compute
- **2nd moment** = *surprise number S* = a measure of how uneven the distribution is

Moments

- **Third Moment is Skew:**



- **Fourth moment: Kurtosis**

- peakedness (width of peak), tail weight, and lack of shoulders (distribution primarily peak and tails, not in between).

Example: Surprise Number

- Measure of how uneven the distribution is
- Stream of length 100
- 11 distinct values
- Item counts m_i : 10, 9, 9, 9, 9, 9, 9, 9, 9, 9, 9
Surprise $S = 910$
- Item counts m_i : 90, 1, 1, 1, 1, 1, 1, 1, 1, 1
Surprise $S = 8,110$

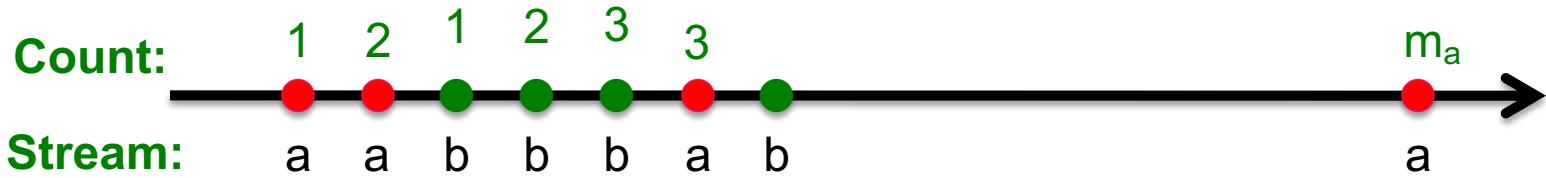
AMS Method

- AMS method works for all moments
- Gives an unbiased estimate
- We will just concentrate on the 2nd moment S
- We pick and keep track of many variables X :
 - For each variable X we store $X.el$ and $X.val$
 - $X.el$ corresponds to the item i
 - $X.val$ corresponds to the count m_i of item i
 - Note this requires a count in main memory,
so number of X s is limited
- Our goal is to compute $S = \sum_i m_i^2$

One Random Variable (X)

- **How to set $X.val$ and $X.el$?**
 - Assume stream has length n (we relax this later)
 - Pick some random time t ($t < n$) to start, so that any time is equally likely
 - Let at time t the stream have item i . **We set $X.el = i$**
 - Then we maintain count c ($X.val = c$) of the number of i s in the stream starting from the chosen time t
- **Then the estimate of the 2nd moment ($\sum_i m_i^2$) is:**
$$S = f(X) = n(2 \cdot c - 1)$$
 - Note, we will keep track of multiple X s, (X_1, X_2, \dots, X_k) and our final estimate will be $S = 1/k \sum_j^k f(X_j)$

Expectation Analysis



- **2nd moment is $S = \sum_i m_i^2$**
- c_t ... number of times item at time t appears from time t onwards ($c_1=m_a$, $c_2=m_a-1$, $c_3=m_b$)

$$E[f(X)] = \frac{1}{n} \sum_{t=1}^n n(2c_t - 1)$$

$$= \frac{1}{n} \sum_i n (1 + 3 + 5 + \dots + 2m_i - 1)$$

Group times by the value seen

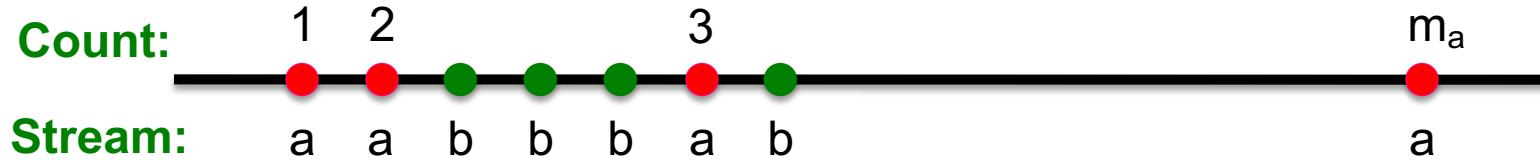
Time t when the last i is seen ($c_t=1$)

Time t when the penultimate i is seen ($c_t=2$)

Time t when the first i is seen ($c_t=m_i$)

m_i ... total count of item i in the stream
(we are assuming stream has length n)

Expectation Analysis



- $E[f(X)] = \frac{1}{n} \sum_i n (1 + 3 + 5 + \dots + 2m_i - 1)$
 - Little side calculation: $(1 + 3 + 5 + \dots + 2m_i - 1) = \sum_{i=1}^{m_i} (2i - 1) = 2 \frac{m_i(m_i+1)}{2} - m_i = (m_i)^2$
- Then $E[f(X)] = \frac{1}{n} \sum_i n (m_i)^2$
- So, $E[f(X)] = \sum_i (m_i)^2 = S$
- We have the second moment (in expectation)!

Higher-Order Moments

- For estimating k^{th} moment we essentially use the same algorithm but change the estimate $f(X)$:
 - For $k=2$ we used $n (2 \cdot c - 1)$
 - For $k=3$ we use: $n (3 \cdot c^2 - 3c + 1)$ (where $c=X.\text{val}$)
- Why?
 - For $k=2$: Remember we had $(1 + 3 + 5 + \dots + 2m_i - 1)$ and we showed terms $2c-1$ (for $c=1, \dots, m$) sum to m^2
 - $\sum_{c=1}^m (2c - 1) = \sum_{c=1}^m c^2 - \sum_{c=1}^m (c - 1)^2 = m^2$
 - So: $2c - 1 = c^2 - (c - 1)^2$
 - For $k=3$: $c^3 - (c-1)^3 = 3c^2 - 3c + 1$
- Generally: Estimate $f(X) = n (c^k - (c - 1)^k)$

Combining Samples

- **In practice:**
 - Compute $f(\mathbf{X}) = \mathbf{n}(2\mathbf{c} - \mathbf{1})$ for as many variables \mathbf{X} as you can fit in memory
 - Average them in groups
 - Take median of averages
- **Problem: Streams never end**
 - We assumed there was a number n , the number of positions in the stream
 - But real streams go on forever, so n is a variable – the number of inputs seen so far

Streams Never End: Fixups

- (1) The variables X have n as a factor – keep n separately; just hold the count in X
- (2) Suppose we can only store k counts. We must throw some X s out as time goes on:
 - **Objective:** Each starting time t is selected with probability k/n
 - **Solution: (fixed-size / reservoir sampling!)**
 - Choose the first k times for k variables
 - When the n^{th} element arrives ($n > k$), choose it with probability k/n
 - If you choose it, throw one of the previously stored variables X out, with equal probability

Problems on Data Streams

- **Filtering a data stream**
 - Select elements with property x from the stream
- **Counting distinct elements**
 - Number of distinct elements in the last k elements of the stream
- **Estimating moments**
 - Estimate avg./std. dev. of elements in stream
- **Remember: No lecture next Tuesday – Project Group meetings instead**