

```

157     values, vectors = la.eig(A, B)
158     vectors = nu.array([ vector.reshape(2,1) / nu.linalg.norm(vector) for vector in ve
159
160     return Eigen(values, vectors)
161
162
163 class Projection(ClassData):
164     def __init__(self, classData, vector):
165         vector = vector.reshape(2,1)
166         ndarrayPoints = nu.array([ nu.dot(row.reshape(1,2), vector) * vector for row i
167         self.points = [ XYPoint([float(ndarrayPoint[0]), float(ndarrayPoint[1])]) for
168         self.len = classData.len
169
170
171 def pricipalComponentOf(class1, class2):
172     A = covarianceTotal(class1, class2)
173     B = nu.eye(2)
174     values, vectors = la.eig(A, B)
175     vectors = nu.array([ vector.reshape(2,1) / nu.linalg.norm(vector) for vector in ve
176     return Eigen(values, vectors)
177
178
179
180 # NOTE: - layout of results: ***** layout
181
182 def errataOf(checkList, correctList):
183     checkArray = nu.array(checkList)
184     correctArray = nu.array(correctList)
185     return checkArray == correctArray
186
187
188 def recognitionRateOf(errata):
189     intUniversalFunc = nu.frompyfunc(int, 1, 1)
190     return intUniversalFunc(errata).sum() / len(errata)
191
192
193
194 # NOTE: recognition lines: ***** reco
195
196 RecogLine = namedtuple('RecogLine', 'polyExpr vectorExpr')
197
198 def recogLineOfEu(class1, class2):
199     vector = nu.flipud(class1.mean - class2.mean)
200     vector[0,0] = -vector[0,0]
201
202     x, y = sy.symbols('x,y')
203     midlePoint = (class1.mean + class2.mean) / 2.0
204     poly = y - midlePoint[1,0] - vector[1,0]/vector[0,0] * (x - midlePoint[0,0])

```