# Huzayfa Jasat

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### **EDUCATION**

## University Of Waterloo

Sep. 2024 - Apr. 2029

Bachelor of Applied Science in Mechatronics Engineering

Waterloo, ON

Relevant Coursework: Mechatronics Engineering, Digital Computation, Data Structures and Algorithms

#### EXPERIENCE

#### Firmware Team Member

Sep. 2024 – Present

University of Waterloo Formula Electric

- ullet Developed a CLI command to clear motor controller faults, reducing troubleshooting time by 30%
- Integrated fault-clear functionality within diagnostic tools used for electric vehicle motor systems, achieving a 95% success rate in automated fault recovery simulations and ensuring accurate system performance during testing.
- Calibrated motor control systems by analyzing performance data, leading to a 10% increase in motor efficiency
- Proactively identified and adopted emerging tools and technologies, such as advanced debugging software and
  performance monitoring frameworks, driven by a passion for continuous learning and innovation

#### Robotics Club President

Sep. 2023 – Jun. 2024

Pine Ridge Secondary School

- Led a 20-member team in building competitive robots, achieving a top 3 finish in the regional championship
- Secured \$3,000 in funding for club activities and projects, by pitching to over 10 potential sponsors
- Empowered **25+ team members** by organizing **35 workshops** to enhance technical skills in mechatronics and robotics, fostering collaboration and boosting efficiency across diverse roles

**Apprentice** Jul. 2022 – Sep. 2022

Federal Auto Repair

- Inspected and replaced **over 50 mechanical components**, including brakes, rotors, and discs, enhancing vehicle functionality, resulting in a **20% improvement** in vehicle performance and reliability
- Repaired or replaced mechanical units and components using hand and power tools, including soldering mufflers for noise reduction and exhaust efficiency, resulting in improved vehicle operation and reduced emissions
- Operated 5 hydraulic systems, gaining hands-on experience and in-depth knowledge of hydrualic machines

# Projects

## Motion Detecting Walking Stick | TinkerCAD, Arduino

- Integrated motion sensors and vibration components to alert users of nearby obstacles, improving mobility for individuals with visual impairments
- Implemented real-time object detection and trigger vibration feedback within 0.5 seconds
- Utilized 3 motion sensors to cover a detection range of 180 degrees, ensuring comprehensive obstacle detections
- Conducted over 50 tests to calibrate sensor sensitivity, achieving a 95% detection accuracy

#### Automated Pet Feeder | EV3 Robotics, RobotC

- Used an ultrasonic sensor and sound sensor to differentiate between cats and dogs, rotating a turntable to dispense a pre-set amount of food based on the identified pet
- Programmed user input for feeding intervals, ensuring proper nutrition schedules, and implemented real-time checks for empty food hoppers, maintaining functionality and reducing downtime by 20%
- Achieved 98% accuracy in distinguishing between pet types during testing, ensuring reliable operations
- Conducted over 40 trials to optimize dispensing mechanisms, resulting in a 15% reduction in food waste

#### SKILLS

- Languages: Python, Java, C++, Javascript, Typescript
- Tools and Framework: SolidWorks, AutoCAD, Arduino, React
- Concepts: Innovation, Growth Mindset, Problem-Solving, Collaboration, Continuous Learning