Contextual Maritime Anomaly Detection

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# Contextual Maritime Anomaly Detection Master Thesis Defense

#### Huub Van de Voort

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July 2025

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### Outline

Contextual Maritime Anomaly Detection

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#### Domain Context

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 There exists a significant interdependence between economic prosperity and access to maritime trade [2]

- Consequences of maritime incidents impose significant national risks [1]
- Maritime Situational Awareness (MSA) systems mitigate adverse outcomes of maritime incidents [6, 4]

#### Problem Statement

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- Deep learning approaches for maritime anomaly detection ignore meteorological context
- Weather-induced shipping patterns are flagged as anomalous
- High false positive rates reduce MSA system usability for Vessel Traffic Monitoring staff [5]

### Research Rationale

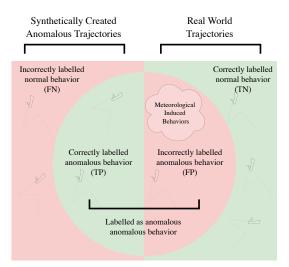
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### Literature Gap

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#### Literature Gap

Current deep learning anomaly detection approaches inadequately address weather-induced behavior, resulting in high false alarm rates

## Research Objective

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#### Main Research Question

How can the integration of meteorological information augment the effectiveness of deep learning approaches in distinguishing weather-induced vessel movements from maritime trajectory anomalies?

## Sub-research Objectives

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#### Sub-research Questions (Summarized)

RQ1: Impact of Model Complexity

**RQ2:** Impact of Meteorological Variables

RQ3: Model Performance by Anomaly Type

**RQ4:** Model Performance Under Varying Weather Conditions

#### **Data Sources**

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#### **AIS Data**

- US West Coast dataset [3]
- January-September 2023
- 7,340 unique vessel trajectories
- Position, speed, course, timestamp

### Meteorological Data

- Fifth generation ECMWF Reanalysis (ERA5)
- Wind components (10m above sea level)
- Wave height, period and direction

### Data Integration

Spatial-temporal joining: AIS trajectories enriched with meteorological statistics ( $\mu$ ,  $\sigma$ ) per trajectory

#### Model Architecture

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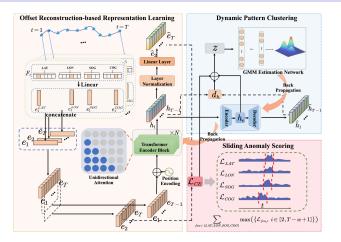


Figure: Model Architecture Adapted from [3]. **Key Enhancement:** Weather statistics  $(\mu, \sigma)$  per trajectory integrated into the Dynamic Pattern Clustering component.

### Experimental Design I

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#### Metrics

- 1 ROC AUC Score: overall discriminative capabilities
- Specificity: true negative rate
- 3 Sensitivity: true positive rate
- 4 McNemar's Statistical Test (Specificity)

### Experimental Design II

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#### **Synthetic Anomaly Types:**

- **1 Shift Deviation:** Lateral/longitudinal displacements
- 2 Abnormal Heading: Lateral/longitudinal displacements and course over ground deviations
- **Abnormal Speeding:** Velocity deviations with Gaussian noise

#### **Evaluation Parameters:**

- *d*: Spatial deviation
- r: Ratio of anomalous trajectories (0.1)

# RQ1: Optimal GMM Components I

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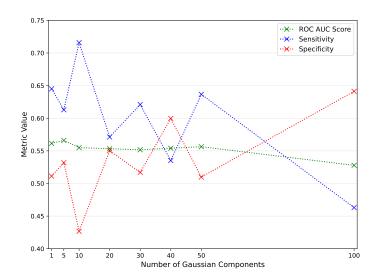
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## RQ1: Optimal GMM Components II

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### **Key Finding**

With added model complexity, ROC AUC Score remains stable; specificity increases at expense of sensitivity.

# RQ2: Impact of Meteorological Variables

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Table: Weather-Enhanced minus Baseline Model Performance

Setup	Specificity	Sensitivity	ROC AUC
$A\;(d\in\{0,1\})$	+0.0372	-0.0276	-0.0096
B $(d \in \{0,2\})$	+0.0574	-0.0617	-0.0161

### **Key Finding**

Consistent improvement in specificity (reduced false alarms)

# RQ3: Performance by Anomaly Type

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Table: Weather-Enhanced minus Baseline Performance

Anomaly Type	ROC AUC	Sensitivity	Specificity
Shift Deviation	-0.0044	+0.1375	-0.1132
Abnormal Heading	-0.0082	-0.1585	+0.1676
Abnormal Speeding	-0.0161	-0.0617	+0.0574

#### **Key Finding**

Synthetic anomalies that have no relation with actual weather-induced behaviors will result in better distinguishability from normal behavior, resulting in less false alarms.

# RQ4: Performance Under Weather Severity

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Table: High Severity minus Low Severity Weather Conditions

Anomaly Type	ROC AUC	Sensitivity	Specificity
Shift Deviation	+0.0637	-0.0545	+0.1044
Abnormal Heading	+0.1099	+0.2571	-0.0384
Abnormal Speeding	+0.0782	-0.0105	+0.1545
Mean	+0.0839	+0.0640	+0.0735

### **Key Finding**

Weather-enhanced model improves overall discriminative performance under severe weather conditions.

### **Key Findings Summary**

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- **Stable Discriminative Capability:** Overall ROC AUC remains stable with weather integration
- Improved Specificity: Consistent reduction in false positives across experimental setups
- **Anomaly-Type Dependent:** Reduction of false positives is most effective for heading and speeding anomalies
- Weather Severity Resilience: Enhanced overall discriminative performance during severe weather conditions

#### Trade-off

Improved specificity (fewer false alarms) comes at the cost of slightly reduced sensitivity (missed anomalies)

### Discussion

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#### **Implications**

- For maritime operations
- For researchers

#### Limitations

- Geographical scope
- Validation framework

### Future Research Directions & Contribution

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#### Future Research

- Generalizability
- Architecture Optimization
- System Usability

#### Contribution

 Successfully demonstrated that meteorological data integration in a multi-model deep learning model can significantly improve the ability to distinguish weather-induced vessel movements from anomalies.

### The End

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### Thank you for your attention!

Questions & Additional discussions

# Backup: Model Hyperparameters

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Parameter	Value
Embedding Dimension	32/48
Transformer Heads	8
Transformer Layers	4
Max Sequence Length	10
GMM Components (C)	20/30
Learning Rate	$1 \times 10^{-5}$
Optimizer	AdamW
Training Epochs	250

## Backup: Statistical Significance Tests

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Statistical Significance (McNemar's test, p < 0.01):

■  $\checkmark$  Shift Deviation:  $p = 2.72 \times 10^{-17}$ 

■  $\checkmark$  Abnormal Heading: p = 8.77  $\times$  10<sup>-3</sup>

•  $\times$  Abnormal Speeding: p = 0.332

## Backup: Test Set Weather Distribution

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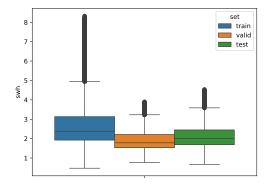
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# Backup: Relationship Between Wave Height and Windspeed

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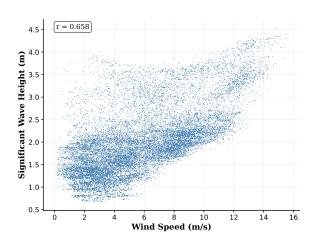
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# Backup: Aggregated Weather Statistics

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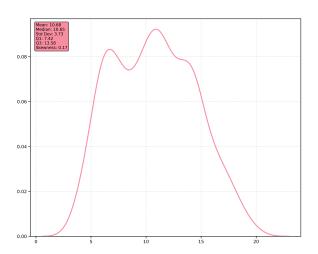
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# Backup: Synthetic Anomalies I

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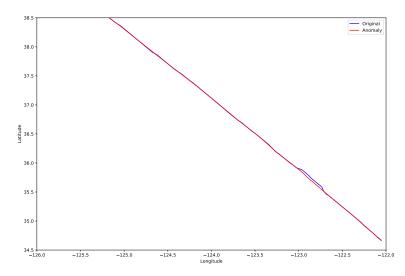
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# Backup: Synthetic Anomalies II

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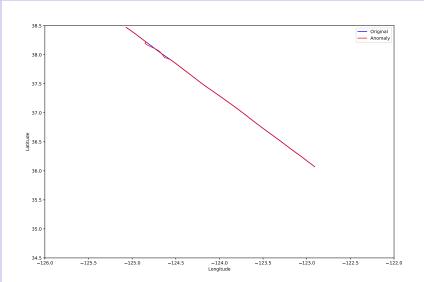
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# Backup: Synthetic Anomalies III

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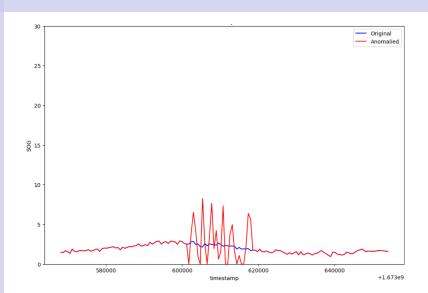
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