

Chapter 3. Direct Methods for Linear Systems.

Section 1. Gauss Elimination Method.

$$\begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3 \\ 3 \end{pmatrix} \rightarrow (2) - (1) \times \frac{1}{2}$$

$$\begin{pmatrix} 2 & 1 \\ 0 & \frac{3}{2} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3 \\ \frac{3}{2} \end{pmatrix} \rightarrow \begin{array}{l} \frac{3}{2}y = \frac{3}{2} \Rightarrow y = 1 \\ 2x + y = 3 \\ \Rightarrow 2x = 3 - y = 2 \Rightarrow x = 1 \end{array}$$

$$A = (a_{ij})_{n \times n} = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix} \in \mathbb{R}^n$$

Linear System: $Ax = b$ (1). $x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n$ $b = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} \in \mathbb{R}^n$

Assume A is invertible

Idea: eliminate the entries in the lower part of the matrix.

For $k = 1, 2, \dots, n-1$ do (as follows)

for $i = k+1, k+2, \dots, n$ do

let $l_{ik} = a_{ik}/a_{kk}$

$b_i^{(k+1)} \leftarrow b_i^{(k)} - l_{ik} b_k^{(k)}$

for $j = k, k+1, \dots, n$ do

$$a_{ij}^{(k+1)} \leftarrow a_{ij}^{(k)} - l_{ik} a_{kj}^{(k)}$$

$$\begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21}^{(2)} & \cdots & a_{2n}^{(2)} \\ a_{31}^{(3)} & \cdots & a_{3n}^{(3)} \\ \vdots & \ddots & a_{nn}^{(n)} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2^{(2)} \\ b_3^{(3)} \\ \vdots \\ b_n^{(n)} \end{pmatrix} \quad (2)$$

Assumption: The diagonal entries are always non-zero in the elimination process.

$$a_{kk}^{(k)} \neq 0.$$

$$\begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad (X)$$

The upper/right triangular system can be solved by the backward substitution method.

For $k = n, n-1, \dots, 1$. do

$$a_{kk}^{(k)} x_k = b_k^{(k)} - \sum_{j=k+1}^n a_{kj}^{(k)} x_j$$

$$x_k = \left(b_k^{(k)} - \sum_{j=k+1}^n a_{kj}^{(k)} x_j \right) / a_{kk}^{(k)} \quad (*).$$

algorithm complexity.

$$O(n^3) + O(n^2).$$

Section 2. LU-decomposition Method.

Decompose A into the product of a lower triangular and an upper triangular matrix.

Denote the lower and upper triangular matrix by L and U , respectively.

$$A = LU \quad \text{with} \quad L = \begin{pmatrix} 1 & & & & \\ l_{21} & 1 & & & \\ l_{31} & l_{32} & 1 & & \\ \dots & \dots & \dots & \ddots & \\ l_{n1} & l_{n2} & \dots & \dots & 1 \end{pmatrix}$$

$$U = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{22} & \ddots & \ddots & u_{2n} \\ \vdots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & u_{nn} \end{pmatrix}$$

like

$$Ax = b \Rightarrow LUx = b.$$

$$\text{Let } Ux = y. \quad \Rightarrow \quad Ly = b.$$

Step 1. solve $Ly = b$. by forward substitution.

$$\begin{pmatrix} 1 & & & & \\ l_{21} & 1 & & & \\ l_{31} & l_{32} & 1 & & \\ \dots & \dots & \dots & \ddots & \\ \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} \quad \checkmark$$

$O(n^2)$

Step 2, solve $Ux = y$ by backward substitution.

$$\begin{pmatrix} U_{11} & U_{12} & \cdots & U_{1n} \\ U_{21} & \cdots & \cdots & U_{2n} \\ \vdots & & & \vdots \\ U_{n1} & & & U_{nn} \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{pmatrix} = \begin{pmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{pmatrix}.$$

$O(n^2)$

$$\begin{pmatrix} A_{11} & A_{12} & \cdots & A_{1n} \\ A_{21} & A_{22} & \cdots & A_{2n} \\ \ddots & \ddots & \ddots & \ddots \\ A_{n1} & A_{n2} & \cdots & A_{nn} \end{pmatrix} = \begin{pmatrix} 1 & & & \\ l_{21} & 1 & & \\ l_{31} & l_{32} & 1 & \\ \vdots & \vdots & \vdots & \vdots \\ l_{n1} & l_{n2} & \cdots & 1 \end{pmatrix} \begin{pmatrix} U_{11} & U_{12} & \cdots & U_{1n} \\ U_{21} & \cdots & \cdots & U_{2n} \\ \vdots & & & \vdots \\ U_{n1} & & & U_{nn} \end{pmatrix}$$

$$a_{11} = u_{11} \quad a_{12} = u_{12} \quad a_{ij} = u_{ij} \quad j = 1, 2, \dots, n$$

$$l_{ii} u_{11} = a_{11} \quad i = 2, 3, \dots, n \Rightarrow u_{11} = a_{11} / l_{11}$$

For $k = 1, 2, \dots, n$.

$$u_{kj} = ? \quad a_{kj} = \sum_{m=1}^k l_{km} u_{mj} \quad j = k, k+1, \dots, n$$

$$= u_{kj} + \sum_{m=1}^{k-1} l_{km} u_{mj}$$

$$u_{kj} = a_{kj} - \sum_{m=1}^{k-1} l_{km} u_{mj} \leftarrow j = k, k+1, \dots, n$$

$$l_{ik} = ? \quad a_{ik} = \sum_{m=1}^k l_{im} u_{mk}, \quad i = k+1, \dots, n$$

$$l_{ik} \cdot u_{kk} = a_{ik} - \sum_{m=1}^{k-1} l_{im} u_{mk}$$

$i = k+1, k+2, \dots, n$

$$\Rightarrow l_{ik} = (a_{ik} - \sum_{m=1}^{k-1} l_{im} u_{mk}) / u_{kk}$$

Doolittle decomposition.

Section 3. QR decomposition

$$A = QR.$$

First, decompose a matrix A into the product of an orthogonal matrix Q and a right triangular matrix R .

$$Ax = b \Rightarrow QRx = b.$$

$$\text{Let } Rx = y. \quad Qy = b.$$

$$\downarrow \\ y = Q^T b.$$

$$\Rightarrow Rx = Q^T b.$$

$$R = \begin{pmatrix} r_{11} & r_{12} & \cdots & r_{1n} \\ r_{21} & \cdots & r_{2n} \\ \vdots & \vdots & & \\ r_{n1} & r_{n2} & \cdots & r_{nn} \end{pmatrix}. \quad Q = (q_1, q_2, \dots, q_n)$$

$q_j : j^{\text{th}}$ column vector of Q .
 $q_j \in \mathbb{R}^n$.

$$(q_1, q_2, \dots, q_n) \begin{pmatrix} r_{11} & r_{12} & \cdots & r_{1n} \\ r_{21} & \ddots & \cdots & r_{2n} \\ \ddots & \ddots & \ddots & r_{nn} \end{pmatrix} = (a_1, a_2, \dots, a_n)$$

$$q_i^T q_j = \begin{cases} 1, & j=i \\ 0, & j \neq i \end{cases}$$

$\|q_i\|_2 = 1.$

a_j : j^{th} column vector of A .
 $a_j \in \mathbb{R}^n$

$$\left\{ \begin{array}{l} q_1^T r_{11} = a_1 \quad (1) \quad \|r_{11}\| = \|a_1\|_2 \Rightarrow r_{11} = \|a_1\|_2 \\ q_1^T r_{12} + q_2^T r_{22} = a_2 \quad (2) \quad q_1 = \frac{a_1}{r_{11}} \\ q_1^T r_{13} + q_2^T r_{23} + q_3^T r_{33} = a_3 \\ q_1^T r_{14} + q_2^T r_{24} + q_3^T r_{34} + q_4^T r_{44} = a_4 \\ \vdots \\ \sum_{i=1}^j q_i^T r_{ij} = a_j \quad (3) \end{array} \right.$$

Take inner product of (2) with q_1

$$(q_1^T, q_1) r_{12} + (q_2^T, q_2) r_{22} = (q_1, a_2) \Rightarrow r_{12} = (q_1, a_2).$$

inner product of (2) with q_2 .

$$(q_2^T, q_1) r_{12} + (q_2^T, q_2) r_{22} = (q_2, a_2) \Rightarrow r_{22} = \underline{(q_2, a_2)}.$$

$$\underline{q_2^T r_{22} = a_2 - q_1^T r_{12}}$$

$$r_{22} = \|a_2 - q_1^T r_{12}\|_2 \quad \checkmark$$

$$q_2 = (a_2 - q_1^T r_{12}) / r_{22}$$

Take inner product of (3) with \tilde{q}_m , $m=1, 2, \dots, j-1$.

$$(\tilde{q}_m, \sum_{i=1}^j q_i r_{ij}) = (\tilde{q}_m, a_j).$$

$$(\tilde{q}_m, \tilde{q}_m) r_{mj} = (\tilde{q}_m, a_j)$$

$$\Rightarrow r_{mj} = (\tilde{q}_m, a_j) \\ m=1, 2, \dots, j-1.$$

$$\tilde{q}_j r_{jj} = a_j - \sum_{i=1}^{j-1} q_i r_{ij}$$

$$r_{jj} = \|a_j - \sum_{i=1}^{j-1} q_i r_{ij}\|_2. \Rightarrow \tilde{q}_j = (a_j - \sum_{i=1}^{j-1} q_i r_{ij}) / r_{jj}$$

Gram-Schmidt orthogonalization

$$(a_1, a_2, \dots, a_n)$$

$$\text{normalize } a_1 : \quad \tilde{q}_1 \leftarrow a_1, \quad \|\tilde{q}_1\|_2 = 1.$$

$$a_2 - (a_2, \tilde{q}_1) \tilde{q}_1 = p_2. \quad a_1 = r_{11} \tilde{q}_1 \quad r_{11} = \|a_1\|_2$$

$$r_{22} = \|p_2\|_2. \quad r_{22} \tilde{q}_2 = p_2. \Rightarrow \tilde{q}_2 = p_2 / r_{22}$$

$$a_j - \sum_{i=1}^{j-1} (a_j, \tilde{q}_i) \tilde{q}_i = p_j \quad j=1, 2, \dots, n.$$

$$r_{jj} = \|p_j\|_2 \quad r_{jj} \tilde{q}_j = p_j \Rightarrow \tilde{q}_j = p_j / r_{jj}.$$

QR method to solve linear system:
 $Ax = b$

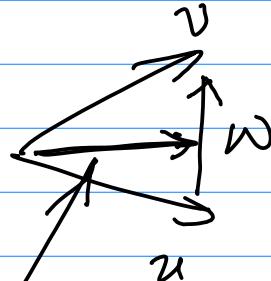
$$\begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ a_{31} & a_{32} & \cdots & a_{3n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

Householder matrix. (reflection matrix.)

$$H = I - 2WW^T \quad \|W\|_2 = 1.$$

$$u, v \in \mathbb{R}^n \quad \|u\|_2 = \|v\|_2$$

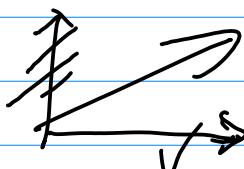
$$W = \frac{u-v}{\|u-v\|_2}$$



$$Hu = v$$



$$Hv = u$$



$$(I - q_1 q_1^T) a_i = a_i - (q_1, a_i) q_1$$

$$(I - W W^T) v \Rightarrow$$

$$Hv = (I - 2WW^T)v = v - 2 \frac{(u-v)(u-v)^T}{\|u-v\|_2^2} v = u$$

H : orthogonal matrix



Symmetric

$$H^T H = (I - 2WW^T)(I - 2WW^T)$$

$$= I - 2WW^T - 2WW^T + 4\underline{WW^TW^T} = I$$

$$\begin{pmatrix} u \\ \| \\ a_{11} \\ a_{21} \\ \vdots \\ a_{n1} \end{pmatrix} \rightarrow \begin{pmatrix} v \\ \| \\ v_{11} \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$\|u\|_2 = |v_{11}| = \|u\|_2 = \|a_1\|_2.$$

$$v_{11} = \pm \|a_1\|_2$$

$$\tilde{w}_1 = u - v_1 = \begin{pmatrix} a_{11} - v_{11} \\ a_{21} \\ a_{31} \\ \vdots \\ a_{n1} \end{pmatrix}$$

$$a_{11} - v_{11} = ?$$

$$w_1 = \frac{\tilde{w}_1}{\|\tilde{w}_1\|_2} = \frac{u - v}{\|u - v\|_2}$$

$$H_1 = I - 2 w_1 w_1^\top.$$

$\cancel{N_{0 \times R_1}}$

$$\tilde{a}_2 = \begin{pmatrix} a_{22} \\ a_{23} \\ \vdots \\ a_{2n} \end{pmatrix} \in \mathbb{R}^{n-1} \rightarrow \begin{pmatrix} v_2 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \quad |v_2| = \pm \|\tilde{a}_2\|_2$$

$$H_r A x = H_r b$$

$$w_2 = \frac{u_2 - v_2}{\|u_2 - v_2\|_2} \in \mathbb{R}^{n-1}. \quad H_2 = I - 2 w_2 w_2^\top \in \mathbb{R}^{(n-1) \times (n-1)}$$

$$\underline{H_2 H_1 A x = H_2 H_1 b}.$$



$$\begin{pmatrix} a_{33} \\ a_{43} \\ \vdots \\ a_{n3} \end{pmatrix} \in \mathbb{R}^{n-2} \rightarrow \begin{pmatrix} v_{33} \\ 0 \\ \vdots \\ 0 \end{pmatrix} \in \mathbb{R}^{n-2}.$$

$$\underline{H_{n-1} \cdots H_2 H_1 A x = H_{n-1} \cdots H_2 H_1 b}$$

$$\underline{R x = H_{n-1} \cdots H_2 H_1 b.}$$

algorithm complexity $O(n^3)$.

section 4. Stability Analysis

$$Ax = b \quad (\text{original})$$

$$\tilde{A} \tilde{x} = \tilde{b} \quad (\text{practical})$$

Step 1. Only b is perturbed.

$$A \tilde{x} = \tilde{b}$$

$$\text{Let } \tilde{b} = b + \delta b \quad \delta b \in \mathbb{R}^n.$$

$$\tilde{x} = x + \delta x. \quad \delta x: \text{ error.}$$

$$A(x + \delta x) = b + \delta b \quad Ax + A\delta x = b + \delta b$$

$$\Rightarrow A\delta x = \delta b \quad \Rightarrow \quad \underline{\delta x = A^{-1}\delta b.}$$

$\|\delta x\|$: absolute error.

$$\text{relative error: } \frac{\|\delta x\|}{\|x\|}$$

$$\|\delta x\| = \|A^{-1}\delta b\| \leq \|A^{-1}\| \cdot \|\delta b\|.$$

$$\frac{\|\delta x\|}{\|x\|} \leq \frac{\|A^{-1}\| \cdot \|\delta b\|}{\|x\|} \quad Ax = b.$$

$$\|b\| = \|Ax\| \leq \|A\| \cdot \|x\| \quad \Rightarrow \quad \|x\| \geq \|b\| / \|A\|.$$

$$\Rightarrow \frac{\|\delta x\|}{\|x\|} \leq \frac{\|A^{-1}\| \cdot \|\delta b\|}{\|b\| / \|A\|} = \circled{(\|A\| \cdot \|A^{-1}\| \cdot)} \frac{\|\delta b\|}{\|b\|}$$