

Chapter 3. Direct Methods for Linear Systems.

Section 1. Gauss Elimination Method.

$$\begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3 \\ 3 \end{pmatrix} \rightarrow (2) - (1) \times \frac{1}{2}$$

$$\begin{pmatrix} 2 & 1 \\ 0 & \frac{3}{2} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3 \\ \frac{3}{2} \end{pmatrix} \rightarrow \frac{3}{2}y = \frac{3}{2} \Rightarrow y = 1$$

$$2x + y = 3$$

$$\Rightarrow 2x = 3 - y = 2 \Rightarrow x = 1$$

$$A = (a_{ij})_{n \times n} = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix} \in \mathbb{R}^n$$

Linear System: $Ax = b$ (1).

$$x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n \quad b = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} \in \mathbb{R}^n$$

Assume A is invertible

Idea: eliminate the entries in the lower part of the matrix.

For $k = 1, 2, \dots, n-1$ do (as follows)

For $i = k+1, k+2, \dots, n$ do $\left\{ \begin{array}{l} \text{let } l_{ik} = a_{ik}/a_{kk} \\ \text{For } j = k, k+1, \dots, n \text{ do } b_i^{(k+1)} \leftarrow b_i^{(k)} - l_{ik}b_k^{(k)} \end{array} \right.$

$$a_{ij}^{(k+1)} \leftarrow a_{ij}^{(k)} - l_{ik} a_{kj}^{(k)}$$

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ & a_{22}^{(2)} & \dots & a_{2n}^{(2)} \\ & & a_{33}^{(3)} & \dots & a_{3n}^{(3)} \\ & & & \ddots & \ddots \\ & & & & a_{nn}^{(n)} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2^{(2)} \\ b_3^{(3)} \\ \vdots \\ b_n^{(n)} \end{pmatrix} \quad (2)$$

Assumption: The diagonal entries are always non-zero in the elimination process.
 $a_{kk}^{(k)} \neq 0$.

$$\begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad (X)$$

The upper right triangular system can be solved by the backward substitution method.

For $k = n, n-1, \dots, 1$, do

$$a_{kk}^{(k)} x_k = b_k^{(k)} - \sum_{j=k+1}^n a_{kj}^{(k)} x_j$$

$$x_k = (b_k^{(k)} - \sum_{j=k+1}^n a_{kj}^{(k)} x_j) / a_{kk}^{(k)} \quad (*)$$

algorithm complexity.

$$O(n^3) + O(n^2).$$

section 2. LU-decomposition Method.

Decompose A into the product of a lower triangular and an upper triangular matrix.

Denote the lower and upper triangular matrix by L and U , respectively.

$$A = LU \quad \text{with} \quad L = \begin{pmatrix} 1 & & & & \\ l_{21} & 1 & & & \\ l_{31} & l_{32} & 1 & & \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ l_{n1} & l_{n2} & \vdots & \ddots & 1 \end{pmatrix}$$

$$U = \begin{pmatrix} u_{11} & u_{12} & \cdots & \cdots & u_{1n} \\ & u_{22} & \cdots & \cdots & u_{2n} \\ & & \ddots & \ddots & \vdots \\ & & & \ddots & \vdots \\ & & & & u_{nn} \end{pmatrix}$$

l_{ik}

$$Ax = b \Rightarrow LUx = b.$$

$$\text{Let } Ux = y. \quad \Rightarrow \quad Ly = b.$$

step 1. solve $Ly = b$. by forward substitution.

$$\begin{pmatrix} 1 & & & & \\ l_{21} & 1 & & & \\ l_{31} & l_{32} & 1 & & \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \vdots & 1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} \quad \checkmark$$

$$O(n^2)$$

Step 2, solve $Ux = y$ by backward substitution.

$$\begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ & u_{22} & \dots & u_{2n} \\ & & \ddots & \\ & & & u_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}.$$

$O(n^2)$

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} = \begin{pmatrix} 1 & & & \\ l_{21} & 1 & & \\ l_{31} & l_{32} & 1 & \\ \vdots & \vdots & \vdots & \ddots & 1 \end{pmatrix} \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ & u_{22} & \dots & u_{2n} \\ & & \ddots & \\ & & & u_{nn} \end{pmatrix}$$

$$a_{11} = u_{11} \quad a_{12} = u_{12} \quad a_{1j} = u_{1j} \quad j = 1, 2, \dots, n$$

$$l_{i1} u_{11} = a_{i1} \quad i = 2, 3, \dots, n \Rightarrow u_{i1} = a_{i1} / u_{11}$$

For $k = 1, 2, \dots, n$.

$$u_{kj} = ? \quad a_{kj} = \sum_{m=1}^k l_{km} u_{mj} \quad j = k, k+1, \dots, n$$

$$= u_{kj} + \sum_{m=1}^{k-1} l_{km} u_{mj}$$

$$u_{kj} = a_{kj} - \sum_{m=1}^{k-1} l_{km} u_{mj} \quad j = k, k+1, \dots, n$$

$$l_{ik} = ? \quad a_{ik} = \sum_{m=1}^k l_{im} u_{mk}, \quad i = k+1, \dots, n$$

$$l_{ik} \cdot u_{kk} = a_{ik} - \sum_{m=1}^{k-1} l_{im} u_{mk}$$

$i = k+1, k+2, \dots, n$

$$\Rightarrow l_{ik} = (a_{ik} - \sum_{m=1}^{k-1} l_{im} u_{mk}) / u_{kk}$$

Doolittle decomposition.

Section 3. QR decomposition

$$A = QR.$$

First, decompose a matrix A into the product of an orthogonal matrix Q and a right triangular matrix R .

$$Ax = b \Rightarrow QRx = b.$$

$$\text{Let } Rx = y, \quad Qy = b.$$

$$\Downarrow \\ y = Q^T b.$$

$$\Rightarrow Rx = Q^T b.$$

$$R = \begin{pmatrix} r_{11} & r_{12} & \dots & r_{1n} \\ & r_{22} & \dots & r_{2n} \\ & & \ddots & \vdots \\ & & & r_{nn} \end{pmatrix}.$$

$$Q = (q_1, q_2, \dots, q_n)$$

q_j : j^{th} column vector of Q .
 $q_j \in \mathbb{R}^n$.

$$(q_1, q_2, \dots, q_n) \begin{pmatrix} r_{11} & r_{12} & \dots & r_{1n} \\ & r_{22} & \dots & r_{2n} \\ & & \ddots & \vdots \\ & & & r_{nn} \end{pmatrix} = (a_1, a_2, \dots, a_n)$$

$$q_i^T q_j = \begin{cases} 1 & j=i \\ 0 & j \neq i \end{cases}$$

$$\|q_j\|_2 = 1.$$

a_j : j^{th} column vector of A .
 $a_j \in \mathbb{R}^n$

$$\begin{cases} q_1 r_{11} = a_1 & (1) & \|r_{11}\| = \|a_1\|_2 \Rightarrow r_{11} = \|a_1\|_2 \\ q_1 r_{12} + q_2 r_{22} = a_2 & (2) & q_1 = \frac{a_1}{r_{11}} \\ q_1 r_{13} + q_2 r_{23} + q_3 r_{33} = a_3 \\ q_1 r_{14} + q_2 r_{24} + q_3 r_{34} + q_4 r_{44} = a_4 \\ \vdots \\ \sum_{i=1}^j q_i r_{ij} = a_j & (3) \end{cases}$$

Take inner product of (2) with q_1

$$(q_1, q_1) r_{12} + \cancel{(q_1, q_2) r_{22}}^0 = (q_1, a_2) \Rightarrow r_{12} = (q_1, a_2).$$

inner product of (2) with q_2 .

$$(q_2, q_1) r_{12} + (q_2, q_2) r_{22} = (q_2, a_2) \Rightarrow r_{22} = \frac{(q_2, a_2) - (q_2, q_1) r_{12}}{1}$$

$$\underline{q_2 r_{22} = a_2 - q_1 r_{12}}$$

$$r_{22} = \|a_2 - q_1 r_{12}\|_2 \quad \checkmark$$

$$q_2 = (a_2 - q_1 r_{12}) / r_{22}$$

Take inner product of (3) with f_m , $m=1, 2, \dots, j-1$.

$$(f_m, \sum_{i=1}^j f_i r_{ij}) = (f_m, a_j).$$

$$(f_m, f_m) r_{mj} = (f_m, a_j)$$

$$\Rightarrow r_{mj} = (f_m, a_j) / (f_m, f_m) \quad m=1, 2, \dots, j-1.$$

$$f_j r_{jj} = a_j - \sum_{i=1}^{j-1} f_i r_{ij}$$

$$r_{jj} = \|a_j - \sum_{i=1}^{j-1} f_i r_{ij}\|_2 \Rightarrow f_j = (a_j - \sum_{i=1}^{j-1} f_i r_{ij}) / r_{jj}$$

Gram-Schmidt orthogonalization

(a_1, a_2, \dots, a_n)

normalize a_1 : $f_1 \leftarrow a_1, \|f_1\|_2 = 1.$

$$a_2 - (a_2, f_1) f_1 = p_2.$$

$$a_1 = r_{11} f_1 \quad r_{11} = \|a_1\|_2$$

$$f_1 = a_1 / r_{11}$$

$$r_{22} = \|p_2\|_2. \quad r_{22} f_2 = p_2 \Rightarrow f_2 = p_2 / r_{22}$$

$$a_j - \sum_{i=1}^{j-1} (a_j, f_i) f_i = p_j$$

$$j=1, 2, \dots, n.$$

$$r_{jj} = \|p_j\|_2 \quad r_{jj} f_j = p_j \Rightarrow f_j = p_j / r_{jj}.$$

QR method to solve linear system:
 $AX = b$

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ a_{31} & a_{32} & \dots & a_{3n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

Householder matrix.

(reflection matrix.)

$$H = I - 2WW^T$$

$$\|W\|_2 = 1. \checkmark$$

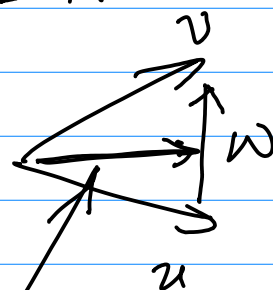
$$u, v \in \mathbb{R}^n$$

$$\|u\|_2 = \|v\|_2$$

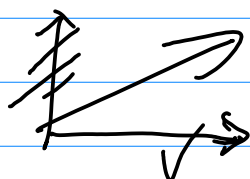
$$W = \frac{u-v}{\|u-v\|_2}$$

$$Hu = v$$

$$Hv = u.$$



$$(I - q_1 q_1^T) a_1 = \underline{a_1 - (q_1^T a_1) q_1}$$



$$(I - WW^T)v \Rightarrow$$

$$Hv = (I - 2WW^T)v = v - 2 \frac{(u-v)(u-v)^T}{\|u-v\|_2^2} v = u$$

H : orthogonal matrix
 \downarrow
 symmetric

$$\begin{aligned} H^T H &= (I - 2WW^T)(I - 2WW^T) \\ &= I - 2WW^T - 2WW^T + 4\underline{WW^T WW^T} = I \end{aligned}$$

$$\begin{pmatrix} u \\ a_{11} \\ a_{21} \\ \vdots \\ a_{n1} \end{pmatrix} \rightarrow \begin{pmatrix} v \\ r_{11} \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$\|u\|_2 = |r_{11}| = \|u\|_2 = \|a_1\|_2.$$

$$r_{11} = \pm \|a_1\|_2$$

$$\tilde{w}_1 = u - v = \begin{pmatrix} a_{11} - r_{11} \\ a_{21} \\ a_{31} \\ \vdots \\ a_{n1} \end{pmatrix}$$

$$w_1 = \frac{\tilde{w}_1}{\|\tilde{w}_1\|_2} = \frac{u - v}{\|u - v\|_2}$$

$$a_{11} - r_{11} = ?$$

$$H_1 = I - 2w_1 w_1^T.$$

Next,

$$\tilde{a}_2 = \begin{pmatrix} a_{22} \\ a_{23} \\ \vdots \\ a_{2n} \end{pmatrix} \in \mathbb{R}^{n-1} \rightarrow \begin{pmatrix} r_2 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$\|u_2\|_2 \qquad \qquad \|v_2\|_2$

$$|r_2| = \pm \|\tilde{a}_2\|_2$$

$$H_1 A x = H_1 b$$

$$w_2 = \frac{u_2 - v_2}{\|u_2 - v_2\|_2} \in \mathbb{R}^{n-1}.$$

$$H_2 = I - 2w_2 w_2^T \in \mathbb{R}^{(n-1) \times (n-1)}$$

$$H_2 H_1 A x = H_2 H_1 b.$$

↓

$$\begin{pmatrix} a_{33} \\ a_{43} \\ \vdots \\ a_{n3} \end{pmatrix} \in \mathbb{R}^{n-2} \rightarrow \begin{pmatrix} r_{33} \\ 0 \\ \vdots \\ 0 \end{pmatrix} \in \mathbb{R}^{n-2}.$$

$$\underbrace{H_{n-1} \cdots H_2 H_1 A x}_{\| \|} = \underbrace{H_{n-1} \cdots H_2 H_1 b}_{\| \|}$$

$$R x = H_{n-1} \cdots H_2 H_1 b.$$

algorithm complexity $O(n^3)$.

section 4. Stability Analysis

$$Ax = b. \quad (\text{original})$$

$$\tilde{A} \tilde{x} = \tilde{b} \quad (\text{practical})$$

step 1. only b is perturbed.

$$A \hat{x} = \hat{b}$$

$$\text{Let } \hat{b} = b + \delta b$$

$$\tilde{x} = x + \delta x.$$

perturbation
 $\delta b \in \mathbb{R}^n.$

δx : error.

$$A(x + \delta x) = b + \delta b$$

$$Ax + A\delta x = b + \delta b$$

$$\Rightarrow A\delta x = \delta b \Rightarrow \delta x = \underline{A^{-1}} \delta b.$$

$\|\delta x\|$: absolute error.

relative error: $\frac{\|\delta x\|}{\|x\|}$

$$\|\delta x\| = \|A^{-1} \delta b\| \leq \|A^{-1}\| \cdot \|\delta b\|.$$

$$\frac{\|\delta x\|}{\|x\|} \leq \frac{\|A^{-1}\| \cdot \|\delta b\|}{\|x\|}$$

$$Ax = b.$$

$$\|b\| = \|Ax\| \leq \|A\| \cdot \|x\| \Rightarrow \|x\| \geq \|b\| / \|A\|.$$

$$\Rightarrow \frac{\|\delta x\|}{\|x\|} \leq \frac{\|A^{-1}\| \cdot \|\delta b\|}{\|b\| / \|A\|} = \underbrace{\|A\| \cdot \|A^{-1}\|}_{\text{condition number}} \cdot \frac{\|\delta b\|}{\|b\|}$$