## Algorithm 3 iCaRL UPDATEREPRESENTATION **input** $X^s, \ldots, X^t$ // training images of classes $s, \ldots, t$

require  $\mathcal{P} = (P_1, \dots, P_{s-1})$ // exemplar sets // current model parameters require  $\Theta$ 

// form combined training set:

$$\mathcal{D} \leftarrow \bigcup_{y=s,\dots,t} \{(x,y): x \in X^y\} \ \cup \bigcup_{y=1,\dots,s-1} \{(x,y): x \in P^y\}$$
// store network outputs with pre-update parameters:

for y = 1, ..., s - 1 do

 $q_i^y \leftarrow g_y(x_i)$  for all  $(x_i, \cdot) \in \mathcal{D}$ end for

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 for all  $(x_i, \cdot) \in \mathcal{D}$   
**end for**  
run network training (e.g. BackProp) with loss function
$$\ell(\Theta) = -\sum_{(x_i, y_i) \in \mathcal{D}} \left[ \sum_{y=s}^t \delta_{y=y_i} \log g_y(x_i) + \delta_{y \neq y_i} \log(1 - g_y(x_i)) \right]$$
 $s-1$ 

$$\ell(\Theta) = -\sum_{(x_i, y_i) \in \mathcal{D}} \left[ \sum_{y=s}^{t} \delta_{y=y_i} \log g_y(x_i) + \delta_{y \neq y_i} \log(1 - g_y(x_i)) + \sum_{y=s}^{t} q_i^y \log g_y(x_i) + (1 - q_i^y) \log(1 - g_y(x_i)) \right]$$

that consists of *classification* and *distillation* terms.