

Department
Of
Mechanical
Engineering

MEng Mechanical Engineering

# Identifying Dynamic Systems with Probabilistic Numerics

Harvey WALTON

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Supervisor: Dr Tim Rogers

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## 1 Background and Understanding of the Problem

Problems in engineering are usually described using a framework of continuous mathematical functions. This means that their output has no jumps or gaps in values, and they can be evaluated using input values that are on a sliding scale of a continuous input domain. For example, time in the real world is on a continuous sliding scale, which means that any interval in time can always be subdivided into a smaller interval. Continuous functions in turn can often be manipulated analytically using mathematics. For example, if the velocity of a particle is given as a continuous function of time, a continuous acceleration function can be derived from the velocity analytically through a mathematical process called differentiation.

However, there are many situations where this analytical approach is unsuitable. The first reason for this is that the analytical approach may be too complex for anyone to have solved. A good example of this is the Gaussian (normal) distribution. This definite integral of this is often needed to be found in order to find the cumulative distribution function. This process can be visualised as finding the area underneath th

However, to collect data for real world events, it must be sampled or else the amount of information needed to represent the event, as well as the amount of computing power to perform analysis on the event, would tend to infinity. Similarly, many problems in the real world are too complex to be solved analytically and so numerical methods are used to approximate the solution to these problems. However, what if there was a better approach? What if instead of resorting to numerical methods to solve the problem discretely, the original continous data could be reconstructed in "closed form".

However, these methods are not perfect, and introduce error into the solutions. This error can be quantified, and is often done so using error bounds

However, instead, what if the error was quantified using a probability distribution

Instead, what if we use uncertainty define a pdf of result using (mean and standard deviation) in this case, it may be easier to quantify concepts like risk and improve automation of decision-making within engineering

#### 1.1

## 2 Aims and Objectives

Your text goes here.

## 3 Work completed to date

Your text goes here. [1]

#### 4 Plan for future work

Your text goes here.

## A The use of generative AI (ChatGPT)

OpenAI's ChatGPT interface, powered by the GPT-4 large language model, was used to create some code.

#### A.1 \_inverse\_triangluar\_matrix function

This method is used to calculate the inverse of R in my method that computes the NLML in my FITC sparse GP approximation. It was generated using ChatGPT using the prompt: "Write a Python function named \_inverse\_upper\_triangular that calculates the inverse of an upper triangular matrix in a faster and more numerically stable way than the standard np.linalg.inv function". The output is provided below:

```
# Python code sample
def factorial(n):
    """Compute the factorial of a number."""
    if n <= 1:
        return 1
    else:
        return n * factorial(n-1)

print(factorial(5))</pre>
```

### A.2 Figures for the report

#### **A.2.1** Cumulative Distribution Function

Put prompt and output

#### References

[1] J. Quinonero-Candela and C. Rasmussen. "A Unifying View of Sparse Approximate Gaussian Process Regression". In: *Journal of Machine Learning Research* 6 (2005).

#### ChatGPT

Based on your prompt, here's the Python function '\_inverse\_upper\_triangular' that meets the \_t meets specified requirements:

```
python
                                                                          Copy code
import numpy as np
def _inverse_upper_triangular(matrix):
   # Convert the input matrix to a NumPy array for easier manipulation
    A = np.array(matrix, dtype=float)
    # Check if the matrix is square
   rows, cols = A.shape
   if rows != cols:
       raise ValueError("Input matrix is not square")
    # Check if the matrix is upper triangular
    if not np.allclose(np.tril(A, k=-1), 0):
        raise ValueError("Input matrix is not upper triangular")
    # Check for zeros on the main diagonal
    if any(np.isclose(np.diag(A), 0)):
        raise ValueError("Matrix is singular and has no inverse")
    # Create an identity matrix of the same size
   I = np.identity(rows)
    # Compute the inverse
   for i in reversed(range(rows)):
       I[i, i] = 1 / A[i, i]
       for j in reversed(range(i + 1, rows)):
           I[i, j] = -sum(A[i, k] * I[k, j] for k in range(i + 1, j + 1)) / A[i, i]
    return I
# Example usage
matrix = [[1, 2, 3], [0, 4, 5], [0, 0, 6]]
inverse_matrix = _inverse_upper_triangular(matrix)
print(inverse_matrix)
```

Figure 1: ChatGPT output providing a function used to inverse an upper triangular matrix in a faster and more numerically stable way