Deep Learning Training on Distributed Embedded Systems

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Introduction

Deep Learning

- Machine learning based on multi-layer artificial neural network
- Largely divided into two: **Training, Inference**

Excellent performance of Deep Learning

 Computer vision, natural language processing, speech recognition, self-driving car, etc.



Introduction

Training

- Generate a model with input data
- Consists of repeatedly calculating multi-layer
- Typically executed on a high-performance distributed system that supports multiple GPUs

Inference

Perform for certain tasks such as object detection

Embedded System has limited resource

 Existing studies are not considered full-training on embedded systems without cloud offloading



Introduction

Smart Home Systems

- Diffusion of Internet-of-Things(IoT)
- Many home appliances are applying deep learning
 - High-performance CPU like quad-core is used for appliances
- Make easier to implement a distributed processing system using embedded systems

Risk of personal information leakage

- Devices collect data from their sensors and then send them to servers for training
- Smart home systems incorporate an amount of sensitive information



Proposal

Distributed Deep Learning using Smart Home System

- In-Home local training, without server
- Online learning about change of environment such as change of furniture layout and change of living pattern of people
- Privacy protection possible
- Reduced server usage costs



Experiment Environment

Distributed Deep Learning framework

- MXNet
 - Provides data and model parallel processing
 - Mobile devices to multi-GPU, multi-Devices
 - Distributed key-value storage based on parameter servers for synchronization

Distributed computing

- Raspberry Pi 3 Model B: 1~11
- Connected with 100 Mbps
 LAN switch





Experiment Environment

MNIST dataset

- Handwritten image of 0-9
- 60,000 32x32 size images



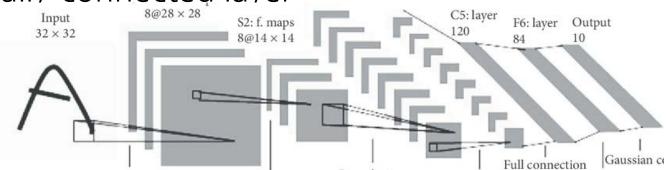






LeNet-5

- 3 Convolution layers
- 2 sub-sampling layers
- 1 fully-connected layer



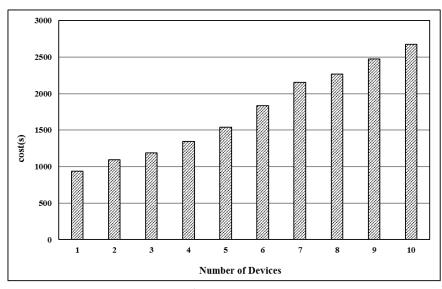


Experiment Result

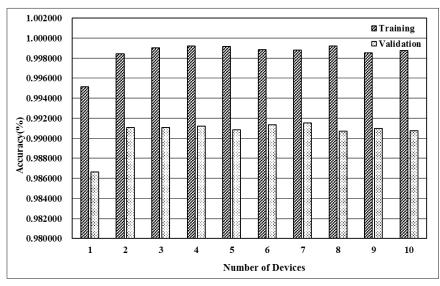
• Layer size: 64

• Learning rate: 0.05

• Number of epochs: 10



Time costs



Training and Validation Accuracy



Conclusion and Future Works

 Trained LeNet model in distributed embedded system and measured execution time and accuracy for a handwritten dataset

- Using a larger model and a heterogeneous embedded system
 - LesNet, AlexNet, etc.

Using Wi-Fi to distributed computing