

Core I—Introduction to HPC

Session III: Vectorisation

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Outline





Parallelisation concepts Autovectorisation and compiler feedback Manual vectorisation

Memory architectures



We use two types of machines in this lecture:

Shared Memory Architecture

Communication:

- one core places value in memory
- next core reads it

Memory access conflicts:

- Read-write
- Write-read
- Write-write

We may only read concurrently

Distributed Memory Architecture

Communication:

- one core sends out message
- next core receives it

Algorithmic challenges:

- Deadlock
- Data consistency

Distributed shared memory:

- Pretend that the memory is shared though it is not
- Can be simulated by intermediate software layer
- Can be offered through remote data access

Programming model



Annotations

- Take serial source code
- Insert new comment-like keywords
- Precompiler/source-to-source compiler

Explicit API calls

- ► Take serial source code
- Use new functions
- Link with library

All approaches realise *explicit parallelism* (not automatically done by compiler). Auto-parallelism would be the prime solution!

Concept of building block



- Content
 - Introduce shared vs. distributed memory machines
 - Discuss appropriate programming models
- Expected Learning Outcomes
 - ► The student can describe differences of the machines
 - ► The student can classify new programming techniques/models

Outline



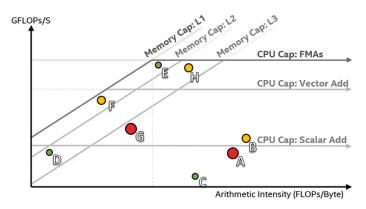
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Parallelisation concepts Autovectorisation and compiler feedback Manual vectorisation

Insights from the roofline model (recap)

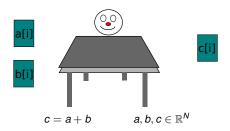




- A Not bandwidth-bound, would benefit from vectorisation
- B Insufficient vectorisation
- D L2 cache-bound
- G Memory bandwidth-bound

SISD (recap)





- ► SISD architecture: One ALU and one activity a time
- ► Runtime: (2 · load + add + store) · N
- Usually load, add, store require multiple cycles (depend both on hardware and environment such as caches; cf. later sessions)

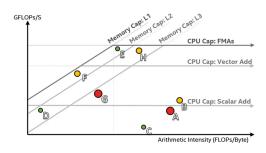
Pseudoassembler code with SISD (recap)



```
c=a+b \hspace{1cm} a,b,c\in \mathbb{R}^N for (int i=0; i<N; i++) { load a[i] load b[i] add store c[i] }
```

Reading roofline plots





With a roofline model and a code analysis we can

- predict impact of vectorisation (move dot up)
- clarify whether vectorisation is worth the effort
- identify code parts which require algorithmic changes (move dot to the right)

Agenda



Compilers today do quite a lot of vectorisation automatically, but

- we have to understand where they succeed and where not
- we have to help them from time to time
- we have to write down code in a proper way

Vectorisable loops



Loops are vectorisation candidates iff

- 1. Countable (cmp. C for to for-loops in theoretical computer science)
- 2. Single entry, single exit
- 3. No branches
- 4. Only inner loops
- 5. No function calls (cmp. inlining)
- 6. No internal dependencies

Most standard library (intrinsic) functions however are allowed as there are vectorised versions available.





```
for (int i=1; i<N; i*=2) {
   if (x[i]<20.0) {
      y[i] = 0.0;
   }
   else {
      y[i] = x[i]/20.0;
   }
   foo( y[i] );
   y[i-1] = y[i] + 1.0;
}</pre>
```

Vectorisation reports (Intel)



Standard translation mode leaves us without a clue about whether the output will use vectorisation facilities, but we can ask the compiler to be verbose:

```
[tobias@phi1 course-GPUProgramming]$ icpc -vec-report2 main.cpp ...

main.cpp(429): (col. 5) remark: loop was not vectorized: existence of vector dependence
main.cpp(106): (col. 3) remark: loop was not vectorized: not inner loop
main.cpp(106): (col. 3) remark: loop was not vectorized: nonstandard loop is not a vectorization candidate
main.cpp(107): (col. 5) remark: loop was not vectorized: nonstandard loop is not a vectorization candidate
main.cpp(108): (col. 7) remark: loop was not vectorized: nonstandard loop is not a vectorization candidate
main.cpp(118): (col. 3) remark: loop was not vectorized: nonstandard loop is not a vectorization candidate
main.cpp(119): (col. 5) remark: loop was not vectorized: nonstandard loop is not a vectorization candidate
main.cpp(120): (col. 7) remark: loop was not vectorized: nonstandard loop is not a vectorization candidate
main.cpp(135): (col. 3) remark: loop was not vectorized: nonstandard loop is not a vectorization candidate
main.cpp(137): (col. 7) remark: loop was not vectorized: nonstandard loop is not a vectorization candidate
main.cpp(137): (col. 7) remark: loop was not vectorized: nonstandard loop is not a vectorization candidate
main.cpp(146): (col. 3) remark: loop was not vectorized: nonstandard loop is not a vectorization candidate
main.cpp(147): (col. 5) remark: loop was not vectorized: nonstandard loop is not a vectorization candidate
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```

▶ We rely on default optimisation level (-02) here

Intel:

- ► Old style: -vec-report2 (different levels available)
- ► Windows: /Qopt-report:1 /Qopt-report-phase:vec
- ► Linux: -qopt-report=1 -qopt-report-phase=vec

GNU:

- -ftree-vectorize switches on vectorisation
- ► Automatically triggered by -03
- -ftree-vectorize-verbose=N yields reports

Countable loops



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Countable loop: The number of iterations is known (and fixed) when we enter the loop.

```
for (int i=0; i<N; i++) {
   if (b[i]<1.5) {
     break;
   }
   c[i] = a[i] * b[i];
}</pre>
```

Translates with -vec-report2:

```
my file.cpp (125): \ remark: \ loop \ was \ not \ vectorized: \ nonstandard \ loop \ is \ not \ a \ vectorization \ candidate.
```

Ideas:

- ► Can you predict a priori whether break holds?
- ► Can you roll-back?
- Can you mask results?





```
for (int i=0; i<N; ) {
   c[i] = a[i] * b[i];
   i++;
}</pre>
```

- Access though array index preferable to pointer arithmetics.
- Loop counter modification in loop body problematic.

Successful vectorisation:

```
myfile.cpp(125): remark: vectorization support: unroll factor set to 4.
myfile.cpp(125): remark: LOOP WAS VECTORIZED.
```

Behind the scenes: unroll factors



Compilers can unroll simple loops even though the looper counter is not known a priori:

```
for (int i=0; i<N; i++) {
  c[i] = a[i] * b[i];
}</pre>
```

Unrolled code fragment for 4-way SIMD instructions (pseudo code):

```
for (int i=0; i<N/4*4; i+=4) {
   c[i+0] = a[i+0] * b[i+0];
   c[i+1] = a[i+1] * b[i+1];
   c[i+2] = a[i+2] * b[i+2];
   c[i+3] = a[i+3] * b[i+3];
}
for (int i=N/4*4; i<N; i++) {
   c[i] = a[i] * b[i];
}</pre>
```

Concept of building block



- Content
 - Reiterte message behind roofline plots
 - Discuss compiler feedback
 - Discuss mandatory loop properties for vectorisation
- Expected Learning Outcomes
 - The student can explain roofline models
 - ► The student can interpret compiler feedback
 - ► The student can explain why certain code snippets vectorise or do not vectorise

Outline





Parallelisation concepts
Autovectorisation and compiler feedback
Manual vectorisation

Vectorisation paradigms



- Automatic (compiler)
 - Rely on compiler only to find vectorisable code fragments
 - CUDA, e.g., pushes this idea
- Assembler
 - Manually load, store data and trigger right calls
 - Portability (Xeon Phi's AVX, e.g., is not Sandy Bridge SSE/AVX)
- Intrinsics
 - Special typedefs and functions provided in header file (library approach)
 - ▶ Replace code fragments by function calls (inlining assembler code)
- Pragmas
 - Augment source code with compiler hints
 - It is up to the compiler to find hardware-specific solution
- Domain-specific languages or language extensions

Why manual vectorisation is tricky



- Hardware changes rapidely
 - Sandy Bridge: 256-bit FMUL and 256-bit FADD per core (DP: 16 values held in registers; 8 Flops/cycle)
 - Haswell: Two 256-bit FMA per core (DP: 16 Flops/cycle)
- ► MIC
 - Four threads share one FPU
 - Scheduling is non-trivial
- Latency
 - Theoretical flops/cycle are upper bound
 - Vectorisation often does not pay off due to latency constraints
- The API (intrinsics) changes
- to be continued
- \Rightarrow We will rely on the compiler to vectorise in this course!

Pragmas in C



The #pragma directive is the method specified by the C standard for providing additional information to the compiler, beyond what is conveyed in the language itself. Three forms of this directive (commonly known as pragmas) are specified by the 1999 C standard. A C compiler is free to attach any meaning it likes to other pragmas.

Pragma example: inlining



Copy 'n' paste function body into calling source code and thus avoid function call overhead.

```
for (int i=0; i<N; i++) {
  c[i] = foo(i/4);
}</pre>
```

If foo is evaluated per loop iteration, we might end up spending all of our precious cycles in call stack administration (call overhead).

- Option 1: inline keyword in C (does work with ipo if ipo works)
- Option 2: Manual inlining by placing foo into header files
- Option 3: Manual inlining by copy 'n' paste yourself
- Option 4: Enforce inlining with pragmas

Inlining with pragmas



```
for (int i=0; i<N; i++) {
    #pragma forceinline recursive
    c[i] = foo(i/4);
}</pre>
```

- #pragma inline Hint to the compiler
- #pragma inline recursive Hint to the compiler to inline recursively
- #pragma forceinline Forces compiler to inline this particular function but not functions called within this function
- #pragma forceinline recursive Forces compiler to inline recursively (complete unroll of call graph)
- #pragma noinline Avoid inlining and reduce code size.
- These are Intel options. GCC requires you to annotate functions (_attribute__((always_inline)))

Compiler inlining: If we use -03, the compiler automatically inlines many small helper functions (cmp. outcome of profiling in second session). Which routines are inlined however depends on a (unknown) heuristic whereas an explicit inline call enforces the compiler to inline.





```
#pragma unroll (5)
for (int i=0; i<N; i++) {
  c[i] = a[i] * b[i];</pre>
```

- Recommends the compiler to unroll loop even though its internal heuristics recommend not to do so (instruction latency).
- ▶ If unroll factor is omitted, optimiser tries to determine/predict good unroll factor.
- Usually only recommended, if vectorisation report tells you that loop is not unrolled though you know that loop body is expensive (due to inlined function; cmp. follow-up discussion).
- Helps you to unroll outer loops and thus enable further optimisations; for inner loops usually useless.

```
#pragma nounroll
for (int i=0; i<N; i++) {
  c[i] = a[i] * b[i];
}</pre>
```





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```
for (int i=0; iN; i++) {
   if (a[i]>=0.0) {
     c[i] = a[i] * b[i];
   }
   else {
     c[i] = a[i] + b[i];
   }
}
```

Handbooks suggest that this code does not vectorise, however:

```
\label{eq:myfile.cpp} $$ myfile.cpp(125): remark: vectorization support: unroll factor set to 4. \\ myfile.cpp(125): remark: LOOP WAS VECTORIZED.
```

Both variants are evaluated, but:

Masking Result of computation is either used or discarded.

Blending Two results are computed but one is discarded.





```
c[i] = a[i-1]*3;
c[i+1] = a[i+1-1]*3;
c[i] = c[i-1]*3;
c[i+1] = c[i+1-1]*3:
```

- Dependencies between computations imply that the code fragment cannot be vectorised.
- Dependency types are:
 - Read after read (no conflict)
 - Write after read
 - Read after write
 - ▶ Write after write (semantics?)
- -vec-report6 plots dependencies





```
for (int i=1; i<N; i++) {
  myA[i] = myA[i-1] * myB[i];
}</pre>
```

```
{\tt myfile.cpp(125):\ remark:\ loop\ was\ not\ vectorized:\ existence\ of\ vector\ dependencies.}
```

myfile.cpp(125): remark: vector dependence: assumed FLOW dependence between myA line 125 and myA line 125.

You can make the compiler ignore this dependency due to

#pragma ivdep

Further pragmas



- #pragma loop_count(10) Tell the compiler about loop count and thus guide heuristics.
- #pragma vector always Force compiler to vectorise even though heuristics indicate that it is inefficient.
- ▶ #pragma simd Enforce vectorisation.

#pragma simd includes ivdep and thus might lead to broken code.

Summary:

- In the end, it is often trial and error.
- Vectorisation reports however guide you through process.
- Often, it does not require major code changes but gives nevertheless that whoa effect.

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