

“Fall” Detection for Smart Homes

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Abstract

The topic I choose for the “Smart Home” project is the “fall” action detection. I built my own model with VGG16 and some other layers for this detection project. I increased my model’s accuracy by changing parameters such as epochs, steps per epoch, optimizer learning rate, train and test data split rate, batch size and many more. I improved the training process of my model by purchasing the Google CoLab Pro account, which adds more GPU memory and speed. I used the Kinetics 700 (2020 Version) as my training and testing dataset. My model’s overall accuracy is at around 75% with 1600 videos trained.

1. Topic

The topic for my project is action detection on “fall”.

2. Motivation

The reason for choosing this project is because I want to make something that will help people’s safety at home. Falling at home can sometimes result in bad consequences. For example, my grandpa fell at home and had to stay on wheel chair for rest of his time. So, I really wanted to do something about this issue, which is why I picked this topic.

3. Related Works

<https://www.sciencedirect.com/science/article/pii/S0925231212003153>

<https://ieeexplore.ieee.org/abstract/document/4352627>

<https://biomedical-engineering-online.biomedcentral.com/articles/10.1186/1475-925X-12-66>

<https://ieeexplore.ieee.org/abstract/document/4600107>

<https://www.sciencedirect.com/science/article/pii/S1574119212000983>

(Not enough time to read and summarize these papers, will do in future submissions.)

4. Proposed Model

I build my model with learning and code based on the textbook “Deep Learning with Python” and a medium article “Training a neural network with an image sequence — example with a video as input”. For the base model, I used the VGG16 model, which is what I learned from the class textbook. On top of the VGG16, I used suggestions from the medium article, added layers such as GRU, dense, dropout and time distributed layers. The optimizer I used for this model is “Adam”, at learning rate 0.001. A summary of my model looks like:

Model: "sequential_5"

Layer (type)	Output Shape	Param #
time_distributed_2 (TimeDist)	(None, 15, 512)	14714688
gru_2 (GRU)	(None, 64)	110976
dense_10 (Dense)	(None, 1024)	66560
dropout_6 (Dropout)	(None, 1024)	0
dense_11 (Dense)	(None, 512)	524800
dropout_7 (Dropout)	(None, 512)	0
dense_12 (Dense)	(None, 128)	65664
dropout_8 (Dropout)	(None, 128)	0
dense_13 (Dense)	(None, 64)	8256
dense_14 (Dense)	(None, 2)	130
Total params: 15,491,074		
Trainable params: 776,386		
Non-trainable params: 14,714,688		

5. Dataset

The dataset I used to train the model is Kinetics 700 (2020 Version).

A link to this dataset: <https://deepmind.com/research/open-source/kinetics>

This dataset contains 700 classes with at least 700 video clips from different YouTube videos. A sample data looks like:

	label	youtube_id	time_start	time_end	split
0	clay pottery making	---0dWlqevl	19	29	train
1	news anchoring	---aQ-tA5_A	9	19	train
2	using bagging machine	---j12rm3Wl	14	24	train
3	javelin throw	--07WQ2IBlw	1	11	train
4	climbing a rope	--ONTAs-fA0	29	39	train

This dataset contains many labeled actions with its YouTube video ID, start time and end time of the clip. There are in total of 542902 labels in the dataset's training data as shown below:

```
[ ] print(data.label)

0      clay pottery making
1      news anchoring
2      using bagging machine
3      javelin throw
4      climbing a rope
...
542897  washing dishes
542898  juggling fire
542899  taking photo
542900  brush painting
542901  changing oil
Name: label, Length: 542902, dtype: object
```

By using pandas data frame, I was able to take out the label that I need, which is the label named “falling off chair” in this case. There are total of 805 training videos for this label as shown below:

```
[ ] print(data[data.label == ('falling off chair')])

      label  youtube_id  time_start  time_end  split
840  falling off chair  -5hw88bD4mE      3      13  train
944  falling off chair  -6ezg_-7Bck     10      20  train
2029 falling off chair  -Fmo9KhEV7M      0      10  train
2537 falling off chair  -KN260H63WU      5      15  train
2831 falling off chair  -MqpifyByYs      0      10  train
...      ...      ...      ...      ...
539608 falling off chair  zaGM-9_DGe4      0      10  train
539967 falling off chair  zc_uLy45ZJU     10      20  train
541545 falling off chair  znz5A0G_AYY      0      10  train
541902 falling off chair  zqp0wFFiyvM      0      10  train
542363 falling off chair  zumeyo_1LwY     35      45  train

[805 rows x 5 columns]
```

I downloaded all the videos with label of “falling off chair” to use as my training data, also I downloaded the same number of videos with label that isn't “falling off chair” also to used during my training process. So, there are about 1600 videos used to train my model.

6. Model Training and Performance

For my base model, I used VGG16, with input shape (150, 150, 3). I added layers such as below:

```
conv_base = VGG16(weights='imagenet',
                    include_top=False,
                    input_shape=(150, 150, 3))
conv_base.trainable = False

def action_model(shape=(NBFRAME, 150, 150, 3), nbout=2):

    # Flatten output of conv_base
    mod = Sequential()
    mod.add(conv_base)
    mod.add(GlobalMaxPool2D())
    # Build our model for training
    model = Sequential()
    model.add(TimeDistributed(mod, input_shape=shape))
    # LSTM for time series
    model.add(GRU(64))
    # Build the classifier
    model.add(Dense(1024, activation='relu'))
    model.add(Dropout(.5))
    model.add(Dense(512, activation='relu'))
    model.add(Dropout(.5))
    model.add(Dense(128, activation='relu'))
    model.add(Dropout(.5))
    model.add(Dense(64, activation='relu'))
    model.add(Dense(nbout, activation='sigmoid'))
    return model
```

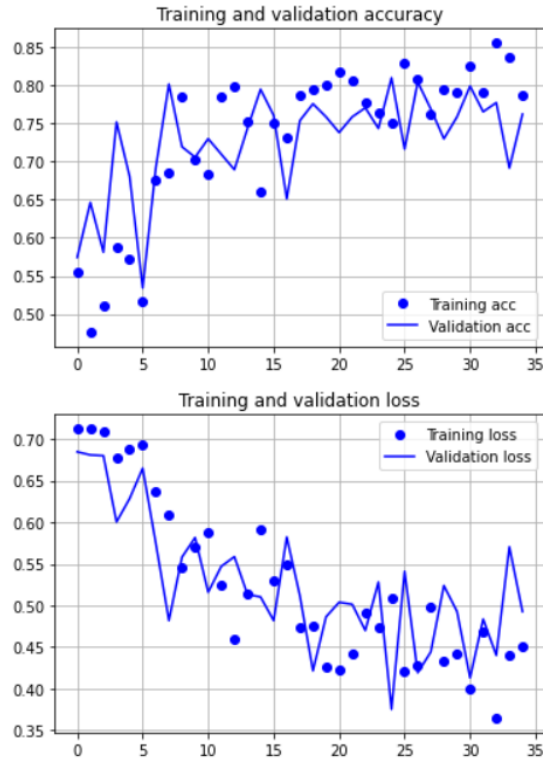
The optimizer I used was Adam, with learning rate 0.001 as shown below:

```
from keras.optimizers import Adam

optimizer= Adam(0.001)
model.compile(optimizer=optimizer ,
              loss='binary_crossentropy',
              metrics=['accuracy'])
```

I choose 35 as the number of my epochs, and 20 steps per epoch. Initially I started with 20 epochs and resulted in underfitting, so I changed to 50 epochs, which resulted in overfitting. Based on the accuracy and loss graphs, I could tell around 30 or 40 epochs was my best result, so I ended up with 35 epochs.

As the results, my model's training and validation accuracy increased and loss decreased as shown in the graphs below:



As you can see, there was no overfit or underfit in both of the categories. And my model accuracy ended up around 75%. The best I've gotten was 78% and worst was 56%. I think a key factor about this model is the quality of videos. I manually looked through some of the training videos, many of them either had bad quality, or bad lighting, or only part of the human body was shown. This could strongly affect the accuracy of my model.

7. Performance on YouTube Videos

7.1 How to detect “moments” of target action

I first choose some videos to test the performance of my model, by doing that, I downloaded those videos from YouTube. Then, I loaded my saved model .h5 file, and made a function where it will check the video with my model. For every two seconds, the model will check if the video contains the target action, if it does, then it will save the 2 second video clip's information such as start and end time, video ID, to a .json file.

7.2 Video Found “Moments” in iLab Website

The label of my target action is “fall”, in total I found 69 moments in 12 videos. You can simply search on the website with “CSCE636Spring2021-heswaggy-2” in the observer filed to see these videos and moments.

7.3 Performance Accuracy

(Will do later)

7.4 Performance: Efficacy of Action Detection

(Will do later)

8. Improve Accuracy and Efficiency

(will do some research on it in the future)

9. Code in TAMU Github

Github Link: <https://github.tamu.edu/hwy893747147/CSCE636-Spring2021-ProjectSubmission2-WangyangHe>