

Tusk Sinusoidal model, V2 and estimation algorithm

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Description of the sinusoidal model

The observations along the tusk are denoted Y_i for $i = 1, \dots, n$, with the corresponding position along the tusk denoted x_i . The model is the following

$$Y_i = f(x_i, \varphi) + \varepsilon_i$$

with ε_i a random noise assumed to be normally distributed with mean 0 and variance ω^2 . The regression function is a periodic sinusoidal function

$$f(x, \varphi) = A \sin(g(x) + b) + B \sin(2g(x) + 2b + \pi/2)$$

with function g defined as

$$g(x) = \int_0^x \xi_u du$$

and finally ξ_u is assumed to be a random square root process

$$d\xi_u = -\beta(\xi_u - a)du + \sigma\sqrt{\xi_u}dW_u$$

We can calculate the moments of ξ_u :

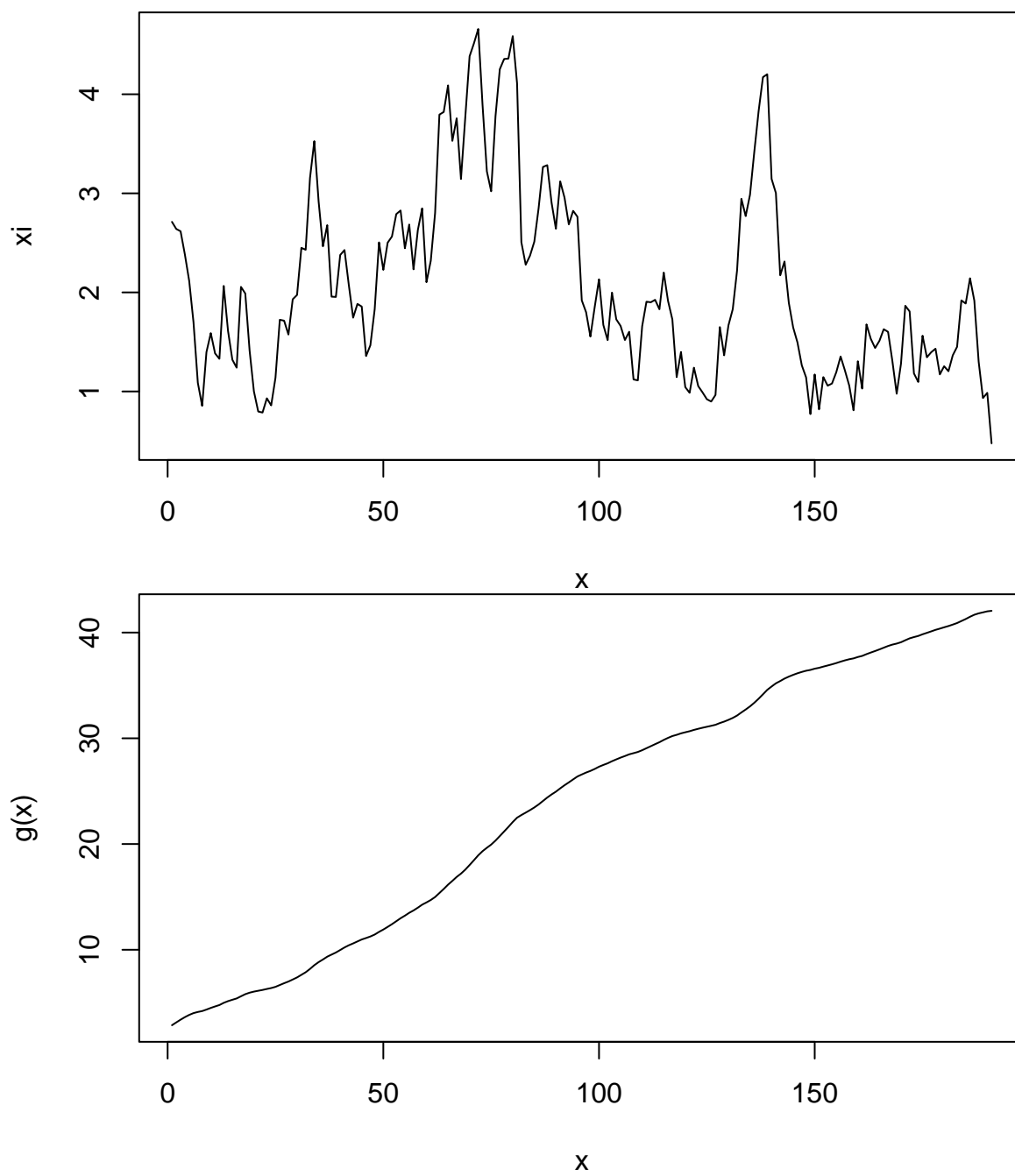
$$\mathbb{E}(\xi_{k\Delta} | \xi_{(k-1)\Delta}) = \xi_{(k-1)\Delta} e^{-\beta\Delta} + a(1 - e^{-\beta\Delta}) \quad (1)$$

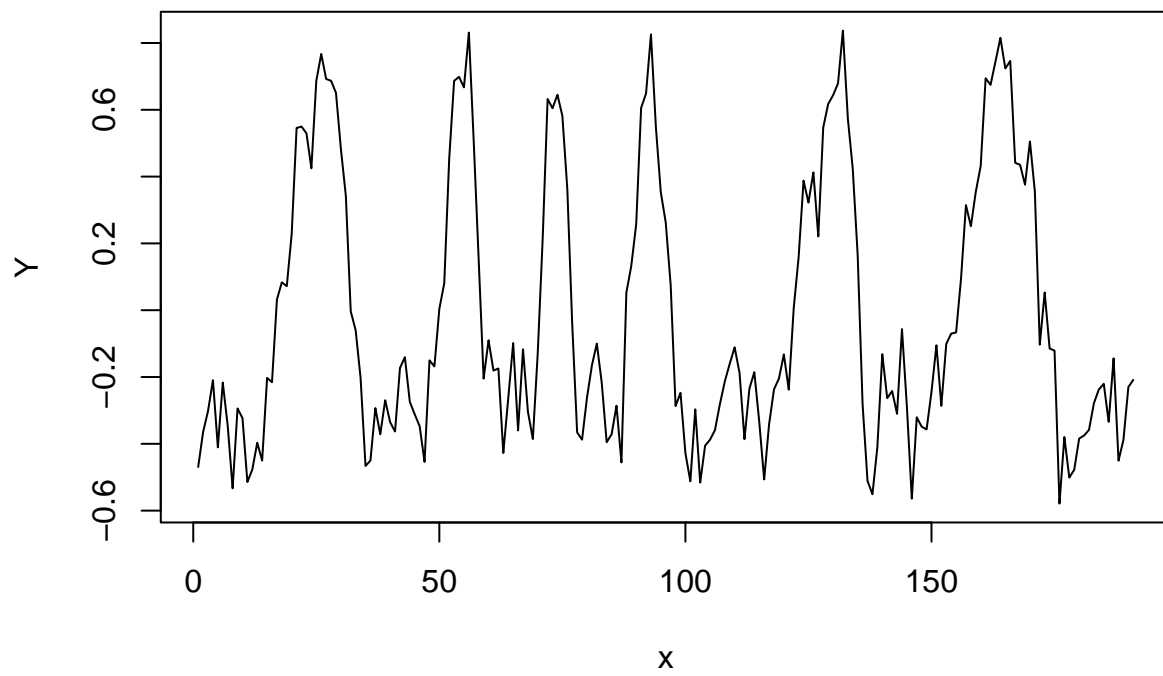
$$Var(\xi_{k\Delta} | \xi_{(k-1)\Delta}) = \xi_{(k-1)\Delta} \frac{\sigma^2}{\beta} \psi(1 - \psi) + \frac{a\sigma^2}{2\beta} (1 - \psi)^2 \quad (2)$$

$$(3)$$

The objective is to estimate the parameters $\varphi = (A, B, a, b)$; $\psi = e^{-\beta\Delta}$ where Δ is the step size between two observations and $\gamma^2 = \frac{\sigma^2}{\beta}(1 - \psi)$.

Simulation of the model





Estimation with the EM algorithm

The EM algorithm is based on the complete log-likelihood of the model. The solution of the hidden process ξ_x is

$$\xi_{x+\Delta} = \xi_x \psi + a * (1 - \psi) + \int_x^{x+\Delta} \sqrt{\xi_s} \sigma e^{\beta(s-x)} dW_s$$

such that the transition density is approximated

$$p(\xi_{x+\delta} | \xi_x) \approx \mathcal{N} \left(\xi_x \psi + a(1 - \psi), \gamma^2 \left(\psi \xi_x + \frac{a(1 - \psi)}{2} \right) \right)$$

The approximate complete log-likelihood is thus

$$\begin{aligned} \log L(Y, \xi, \theta) &= \sum_{i=1}^n \log p(Y_i | \xi_i) + \sum_{i=1}^n \log p(\xi_i | \xi_{i-1}) + \log p(\xi_1) \\ &\approx - \sum_{i=1}^n \frac{(Y_i - f(x_i, \varphi))^2}{2\omega^2} - \frac{n}{2} \log(\omega^2) \\ &\quad - \sum_{i=1}^n \frac{(\xi_i - \xi_{i-1} \psi - a(1 - \psi))^2}{\gamma^2 \left(\psi \xi_{i-1} + \frac{a(1 - \psi)}{2} \right)} - \frac{1}{2} \sum_{i=1}^n \log \left(\gamma^2 \left(\psi \xi_{i-1} + \frac{a(1 - \psi)}{2} \right) \right) \end{aligned}$$

The EM algorithm proceeds at iteration k with the two following steps, given the current value of the parameters θ^k

- E step: calculation of $Q(\theta, \theta^k)$
- M step: update of the parameters $\theta^{k+1} = \arg \max_{\theta} Q(\theta, \theta^k)$

E step

The condition distribution $p(\xi | Y; \theta^k)$ is not explicit because the regression function is not linear. We should proceed with a MCMC algorithm to sample from this distribution. This will lead to a stochastic version of the EM algorithm, namely the SAEM algorithm.

M step

We need the sufficient statistics to update the algorithm.

The statistics are

$$\begin{aligned} S_1(\xi_i) &= \frac{1}{n} \sum_{i=1}^n (Y_i - f(x_i(\xi_i), \varphi))^2 \\ S_2(\xi_i) &= \sum_{i=1}^n \xi_{i-1} \xi_i \\ S_3(\xi_i) &= \sum_{i=1}^n \xi_{i-1}^2 \\ S_4(\xi_i) &= \sum_{i=1}^n \xi_i^2 \end{aligned}$$

The update of the parameters are based on these statistics.

SAEM algorithm

The steps of the SAEM algorithm are

- E step: simulation of a new trajectory ξ^k with a MCMC algorithm targeting $p(\xi|Y; \theta^k)$ as stationary distribution
- SA step: stochastic approximation of the sufficient statistics

$$\begin{aligned} s_1^k &= s_1^{k-1} + (1 - \alpha_k)(S_1(\xi^k) - s_1^{k-1}) \\ s_2^k &= s_2^{k-1} + (1 - \alpha_k)(S_2(\xi^k) - s_2^{k-1}) \\ s_3^k &= s_3^{k-1} + (1 - \alpha_k)(S_3(\xi^k) - s_3^{k-1}) \\ s_4^k &= s_4^{k-1} + (1 - \alpha_k)(S_4(\xi^k) - s_4^{k-1}) \end{aligned}$$

- M step: update of θ^k using the sufficient statistics s^k

$$\begin{aligned} \hat{\varphi}^k &= \arg \min_{\varphi} \sum_{i=1}^n (y_i - f(x_i(\xi_i^k), \varphi))^2 \\ \widehat{\omega^2}^k &= s_1^k \\ \widehat{\gamma^2}^k &= \frac{1}{n} \sum_{i=1}^n \frac{(\xi_i - \xi_{i-1} \hat{\psi} - \hat{a}(1 - \hat{\psi}))^2}{\hat{\psi} \xi_{i-1} + \hat{a}/2(1 - \hat{\psi})} \end{aligned}$$