Reinforcement Learning

(feat. SARSA, Q-Learning)

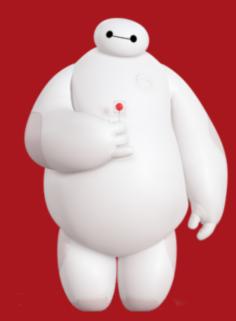
HY-KIERA





What is SARSA / Q-Learning?

Let's code them with PyTorch!



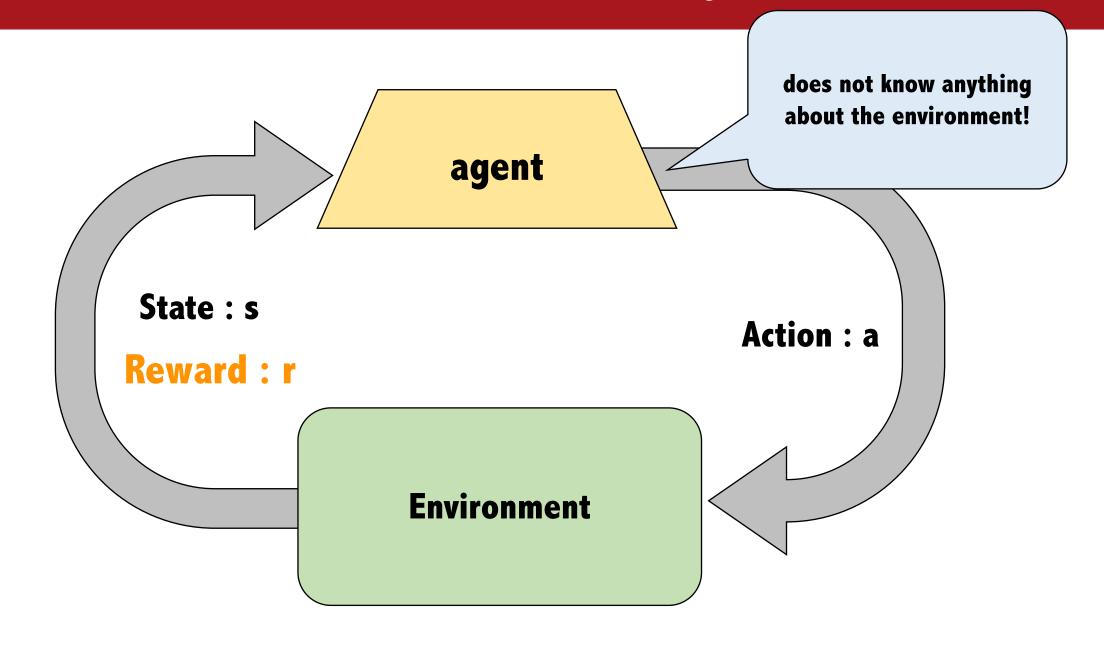
This is Google's DeepMind AI TECH teaching itself how to walk



https://www.youtube.com/watch?v=gn4nRCC9TwQ







Action Value Function

Explore + Exploit

Q(State, Action)
(Q-Table)

 ε -greedy



Monte Carlo + DP

Sarsa

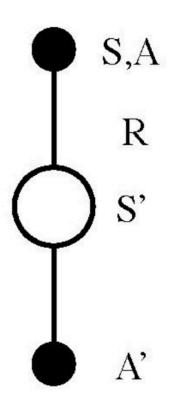
an On-Policy algorithm for TD(Temporal-Difference) Learning

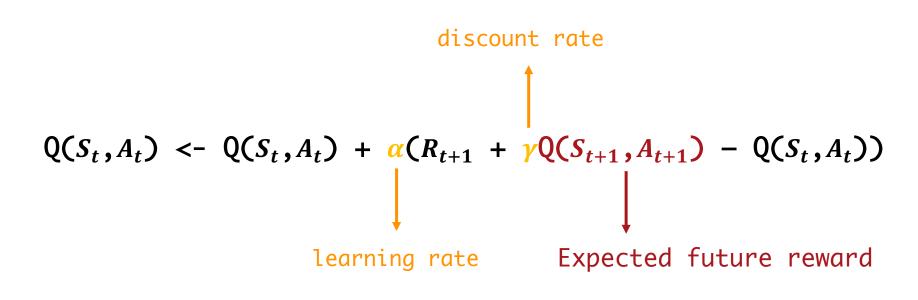
TD will learn using actual rewards and future estimated values for the next step

Sarsa

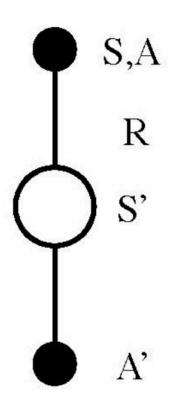
an On-Policy algorithm for TD(Temporal-Difference) Learning

Learning can be done only if learning policy and action policy are the same.



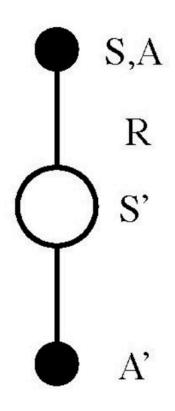


$$[S_t, A_t, R_{t+1}, S_{t+1}, A_{t+1}]$$



TD error
$$\uparrow \\ \mathbb{Q}(S_t,A_t) \leftarrow \mathbb{Q}(S_t,A_t) + \alpha(R_{t+1} + \gamma \mathbb{Q}(S_{t+1},A_{t+1}) - \mathbb{Q}(S_t,A_t))$$

$$[S_t, A_t, R_{t+1}, S_{t+1}, A_{t+1}]$$

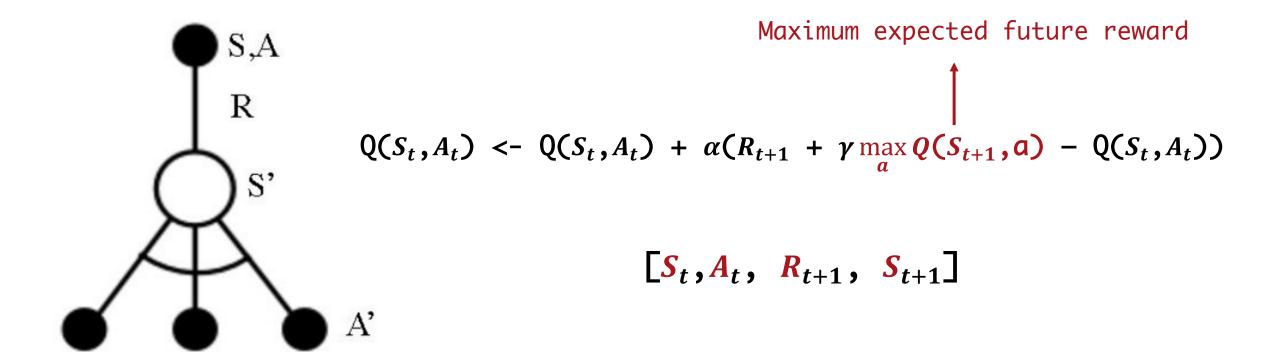


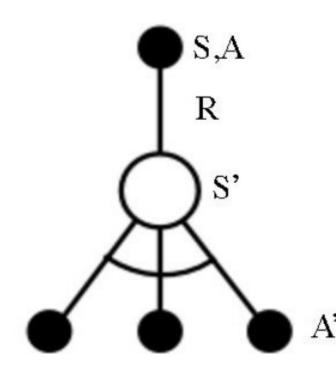
- →The agent starts in S, performs A, and gets R, and goes to S'
- →Now the agent chooses another action A' from S'
- →Then updates the value of A performed in S.

Q-Learning

an Off-Policy algorithm for TD(Temporal Difference) learning

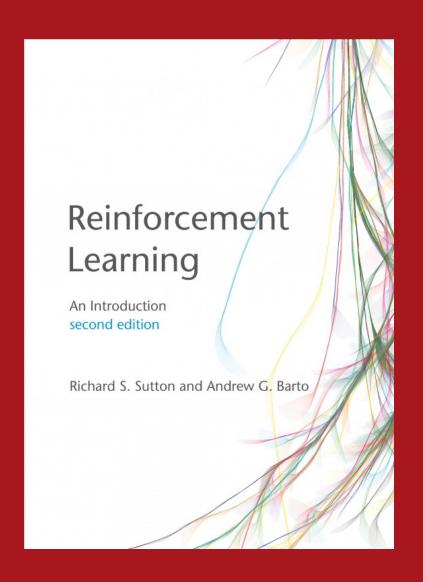
Learning can be done if learning policy and action policy aren't the same.





- →The agent starts in S, performs A, and gets R, and goes to S'
- →Now the agent chooses maximum action A' from S'
- →Then updates the value of A performed in S.

Reference





Let's code them with PyTorch!





QnA

