# **Anthony Lowhur**

# **Education**

Rutgers University, New Brunswick

Bachelors of Science in Computer Science

New Brunswick, New Jersey September 2014 - May 2018

### **Online Course Work**

Coursera, Udacity edX, MIT OCW

Used Massive Online Open Courseware (MOOC) platforms, took higher level CS courses to aid in AI self-studies from top universities (Stanford, MIT, UC Berekley). Knowledge acquired: Techniques, math, and theory in machine learning, path finding algorithms and thought / reaction process of AI agents, reinforcement learning, and parallel programming

# Research Experience

### Rutgers University, New Brunswick

New Brunswick, New Jersey

Research Assistant

January 2015 -

- Designing intelligence of a robot that will compete in the Amazon Picking Challenge through computer vision and machine learning
- Currently researching in object detection in 3D space using depth maps produced by a Microsoft Kinect.

### Rutgers University, New Brunswick

New Brunswick, New Jersey

Research Assistant

September 2015 - December 2015

- -Researched in image processing / computer vision and machine learning to have autonomous drone to analyze and recognize the shape of trash on the beach and pick them up accordingly.
- Implemented by using histogram backprojection and morphological transform for segmentation.
- Implemented bag of words model and support vector machines as well as creating own dataset.

### Lehigh University

Bethlehem, Pennsylvania

Research Assistant

May 2015 - August 2015

- Worked on an emotion recognition program on a robot by using computer vision and machine learning
- Implemented dense optical flow and support vector machines to create robust classifier resistant to unique facial appearance and poort lighting
- Research paper presented at the IEEE MASS 2015 REUNS workshop in Dallas, Texas. Publication in process.

### Skills

### Technical Skills......

- Programming / Scripting Languages: Python, Java, JavaScript, SQL, PHP, Unity3D C Sharp, MATLAB
- Markup Languages: HTML, CSS
- Artificial Intelligence: Image Processing, Computer Vision, Machine Learning (including Neural Networks), ROS + Gazebo
- o Hardware: Arduino, Raspberry Pi, Leap Motion, Kinect

# Personal Programming / Hardware Projects...

### Al Melody Generator

- Created an algorithmic music generator that takes in a song from a midi, analyzes patterns of the musical structure, and composing its own original melodies based on the patterns it had learned.
- Accomplished that by implementing Long Short Term Memory (LSTM) Neural Network
- Attempting to make full AI song composer, an AI that can generate entire songs with a series melodies.
- Currently experimenting with restricted boltzmann machines and LSTM layer.

### Road Segmentation for Autonomous Vehicles

- Uses computer vision and processing algorithms such as histogram backprojection and morphological filtering in order to preform road segmentation in order to detect and recognize roads in a noisy environment.
- Made to be implemented in the DriveAl project, an initiative for open-source autonomous vehicles. (Python)

## Face Tracking via Haar Classification and Lucas Kanade

- Improved face tracking sample from OpenCV documentation by combining both Harr Classifcation and Lucas Kanade optical flow algorithm.
- This allowed the computer to track the face/head in various different angles (front face to side face) even with limited face dataset (Python)

### Markov Lyrics Generator

- Implemented markov chains on lyrics data scrapped from the web to create program that can generate its own unique set of lyrics based on genre.
- Have the capability of creating lyrics based on syllable count per line. Part of a long term project to create a full AI song composer. (Python)

#### Kinect Helper

- Programmed the Kinect in order to create a workspace that is aware of the user's presence.
- By using real-time detection, Kinect senses those who are using the computer and will automatically put the computer to sleep if the user leaves the workspace. (C++, Bash)

#### Sword Fighting Multiplayer game with Myo

- Created a sword fighting multiplayer game where multiple people can log into the same server and engage sword combat with each other.
- Programmed the Myo so that users are able to preform sword attacks through sword cutting like hand gestures. (Unity3D C Sharp)

### Force VR Gauntlet

- Used a motor (with rope tethered to arm) controlled by the Arduino to make a virtual reality wearable that allows the wearer to experience physical forces.
- Whenever the user moves / swings his arm in the VR game and a hit is detected, it creates a locking effect and imitation of a physical force. Solves the issue of the lack of representation of physical forces in VR(C, Python)
- I have more projects on my website and on GitHub. You can also see demo videos of my projects listed here on as well.