Functional Programming Assignment Report

Key	Value
Author	Haihao Yan
Date	04/04/2019
Source Code	https://github.com/hyan36/fdr

Introduction

The puzzle requires us to find the coin with different weight. In our implementation, we are going to use a list to represent a pile of coins, the element of the list represents the weight of a coin. For example, given a list of coins [1,1,2,1,1], the coin weighs 2 is the fake coin.

Firstly, we will need to import the required libraries.

```
import Data.List
import Data.Ord
import Test.QuickCheck
```

The following function will weigh 3 coins and spot the fake coin. Assume there are 3 coins in the pile, a, b and c. We will have the following conditions:

```
1. a == b && b == c : all coins are equal in weight

2. a == b && a /= c : c is the fake coin

3. a /= b && a == c : b is the fake coin

4. a /= b && a /= c && b == c : a is the fake coin
```

```
weigh :: [Int] -> Int
weigh (a:b:xs)
    | a == b && a == c = -1
    | a == b && a /= c = c
    | a /= b && a == c = b
    | otherwise = a
    where
        c = head xs
weigh xs = -1
```

My strategy is to weigh 3 coins each time until we spot the fake coin. However, this strategy creates an obstacle, when the size of the pile cannot be mod by 3, we will have 1 or 2 coins left in the pile which cannot be determined whether it is fake or not.

My solution is to take **n** coins from the genuine pile. (Given we have only one fake coin in the pile, if the program hits the last few coins we can assume that all previously tested coins are genuine.)

```
• n = 3 - ((length xs) mod 3)
```

We will then define a function to prefill the original list. So we can split the pile into smaller chunks e.g. [1,2,1],[1,1,1]...[1,1,1]].

The following method will take an n as an input which indicates the size of the chunks and list as original input. It will return a new list which will always be mod by n.

```
prefill::Int -> [Int] -> [Int]
prefill _ [] = []
prefill n xs = xs ++ (take (if size == n then 0 else size) xs)
    where
        size = n - ((length xs) `mod` n)
```

Now that we have a list of test cases for every coin. We just need to weigh every 3 coins until find out the fake coin.

```
findFake::[Int] -> Int
findFake [] = -1
findFake (x:y:z:xs) = if test /= -1 then test else findFake xs
  where
    pile = prefill 3 (x:y:z:xs)
    test = weigh [x,y,z]
```

This is one of the most obvious ways to identify the fake coin. The complexity of this solution is O(n/3). When there are 12 coins we will use 4 weighs to find the fake coin.

Solution

The prime motivation of the assignment is to simulate a physical solution to the problem. The program will calculate all possible strategies of weighing and then choose the most efficient way of weighing coins.

States and test

Firstly, we need to define the data type State and Test to represent the state of the simulation (State) and our strategy of next move (Test).

```
data State = Pair Int Int | Triple Int Int Int deriving (Eq, Show)
```

```
data Test = TPair (Int,Int) (Int,Int) | TTrip (Int,Int,Int) (Int,Int,Int)
  deriving (Eq,Show)
```

Q1 - Define valid

The valid function returns True when it meets the following conditions:

- Pair can only be tested by TPair and Triple can only be tested by TTrip
- **validTest**: A valid test case requires the number of the coins on the right side matches the coins the left. We learn nothing if we weigh 3 coins against 4.
- **validSample**: You can't take more coins than the pile can offer. For example, assume we have a pile of 5 coins. We've taken 3 coins to the left-hand side of the scales. There are 2 coins remaining in the pile. We can't take more than 2 coins for the right side of the scale.

All other situations are invalid.

Thus, we will have the following definition of valid.

```
valid:: State -> Test -> Bool
valid (Pair x y) (TPair (a,b) (c,d)) = validTest && validSample
    where
        validTest = (a + b) == (c + d)
        validSample = (a + c) <= x && (b + d) <= y
valid (Triple x y z) (TTrip (a,b,c) (d,e,f)) = validTest && validSample
    where
        validTest = (a + b + c) == (d + e + f)
        validSample = (a + d) <= x && (b + e) <= y && (c + f) <= z
valid _ _ = False</pre>
```

Choosing and conducting a test

Now that we have a way to determine whether a state and test is valid or not. We will focus on getting the program to simulate the tests.

Q2 - Define outcomes

There will only be 3 outcomes for each test. [lighter, balanced, heavier]. The basic rules of Pair have been explained very well in the assignment requirement. The triple situation is slightly more complicated.

Given (TTrip (a,b,c) (d,e,f)), we will have the following combinations:

- balanced all tested coins go to pile g
- lighter when the left pan is lighter than the right pan, the fake coin can only be in pile a or pile e. All other coins left on the table goes to pile g.
- heavier when the left pan is heavier than the right pan, the fake coin must be in pile b or pile b. All other coins left on the table goes to pile g.

Thus, we will define outcomes as the following:

```
outcomes::State -> Test -> [State]
outcomes s t
    | valid s t = [(lighter s t),(balanced s t),(heavier s t)]
    otherwise = []
        balanced (Pair x y) (TPair (a,b) (c,d)) = Pair (x - a - c) (y + a)
+ c)
        balanced (Triple x y z) (TTrip (a,b,c) (d,e,f)) = Triple (x - a - d) (y - a - b)
b - e) (z + a + d + b + e)
        lighter (Pair x y) (TPair (a,b) (c,d))
                                                   = Triple a c (x - a - c)
        lighter (Triple x y z) (TTrip (a,b,c) (d,e,f)) = Triple a e (x + y + z - y)
a - e)
        heavier (Pair x y) (TPair (a,b) (c,d))
                                                      = Triple c a (x - a - c)
        heavier (Triple x y z) (TTrip (a,b,c) (d,e,f)) = Triple d b (x + y + z -
b - d
```

Q3 - Define weighings Pair

Given TPair (a,b) (c,d), a sensible test must meet following requirements:

- a + b == c + d: in our implementation, a + b == (a+b) + 0, thus there is no need to validate
- a + b > 0 : we will use as it is
- b * d == 0 : in our implementation, d = 0 thus b * d will always equals 0, thus there is no need to validate
- a + c <= u : since c = a + b thus we will translate this condition to 2 * a + b <= u
- b + d <= g : since d = 0 thus, b + d = b. In our implementation b <- [0..g], it will always be smaller than g, thus there is no need to validate that
- $(a,b) \le (c,d)$: since c = a + b, d = 0. We translate the equation to $(a,b) \le (a+b,0)$

Q5 - Define weighings Triple

The strategy is to pick k number of coins for each pans. We will have following conditions:

- $k \le (l + h + g) / 2$: you can't pick more coins than total amount of coins
- a + b + c == d + e + f: both pans need to have identical amount of coins
- a + b + c > 0 : you need to put something on the both pans
- c * f == 0 : don't pull genuine coins in both pans
- a + d <= I: enough light coins
- b + e <= h : enough heavy coins
- c + f <= g : enough genuine coins
- (a,b,c) <= (d,e,f) : symmetry breaker

Q4 - Define choice

In order to achieve the previous function, we need to define a **choice** function which picks k number of coins from Triple 1 h g. Given we are picking i coins from pile 1 and j coins from pile h, a valid pick must meet the following conditions:

- i + j <= k: you can't pick more than k number of coins.
- k i j <= q: you can't pick more coin than the pile can offer.

```
choices::Int -> (Int,Int,Int)->[(Int,Int,Int)]
choices k (l,h,g) = [(i,j,k-i-j) | i <- [0..l], j <-[0..h], k-i-j >= 0, k-i-j <=
g]</pre>
```

Q6 - Define Ord state

For any two State, we will have the following rules:

- Triple always less than Pair Triple always provides more information than pair
- For either Pair to Pair / Triple to Triple we always compare pile g, whoever has more coins in pile g will provide more information than the other.

Q7 - Define productive

A productive test must give more information than the existing State. Thus we will have s' <= s. When there is no legit outcome of a given test, the function always returns False.

```
productive::State -> Test -> Bool
productive s t
    | length results > 0 = foldr (\x y -> x && y) True [ s' < s | s'<-results]
    | otherwise = False
    where
        results = outcomes s t</pre>
```

Q8 - Define tests

We will filter the results of weighings with the following conditions:

- check if a test is valid
- check if a test is productive

```
tests::State -> [Test]
tests s = filter (\t -> (valid s t) && (productive s t)) (weighings s)
```

Decision trees

In this section, we are going to define a decision tree to record the steps of simulation.

Firstly, we will define a recursive Tree data type.

```
data Tree = Stop State | Node Test [Tree]
  deriving (Eq,Show)
```

In the meanwhile, we need a function to determine if a State is final. The final State must meet the following rules:

- 1. For (Pair u g) we will have u == 0 && g > 0: no fake coins on the table
- 2. For (Triple 1 h g) we will have exactly 1 coin in 1 or exactly 1 coin in h
- 3. Otherwise, it is not final

Q10 - Define height

Function height will traverse the tree and count the height of the decision tree.

```
height::Tree -> Int
height (Stop x) = 0
height (Node t xs)
  | length xs > 0 = 1 + (maximum $ map height xs)
  | otherwise = 0
```

Q11 - Define minHeight

Instead of defining our own minimum function, we will just try to utilize the existing minimum function provided by Data.List.

As a result, we will need to define a new instance for Ord Tree. The order of two trees is determined by their height. The benefit of this approach is that we can utilize the "out of box" functions instead of defining our own. However, it changes the default of Ord of t1 < t2. Given we didn't have other requirements of using this expression, I decide to use this approach.

```
instance Ord Tree where
   compare x y = compare (height x) (height y)
minHeight::[Tree] -> Tree
minHeight = minimum
```

O12 - Define mktree

We will define a mktree function to generate the most efficient strategy. The most efficient strategy is the tree which has the lowest height.

Caching heights

In the previous section, we have got mktree to produce the best options of weighings. However, the performance of which is relatively low. It takes 16 sec on my laptop. One of the potential reasons is that we are calculating height recursively. In this section, we are going to try to optimize performance by caching the height of trees.

Firstly, we need to define TreeH to record the height of a tree.

```
data TreeH = StopH State | NodeH Int Test [TreeH]
  deriving (Eq,Show)
```

Secondly, we will define height to calculate the height of TreeH.

```
heightH::TreeH -> Int
heightH (StopH s) = 0
heightH (NodeH h t ts) = h
```

Last but not least, we will define minHeightH function to get the tree with the lowest height.

```
instance Ord TreeH where
    compare x y = compare (heightH x) (heightH y)
minHeightH:: [TreeH] -> TreeH
minHeightH = minimum
```

Q13 - Define treeH2tree

Following function transforms a given Tree to TreeH by mapping nodes recursively.

```
treeH2tree::TreeH -> Tree
treeH2tree (StopH s) = Stop s
treeH2tree (NodeH n t ts) = Node t [ treeH2tree x | x <- ts]</pre>
```

O14 - Define smart constructor nodeH

Following function constructs a NodeH with a given Test and 3 TreeH.

```
nodeH :: Test -> [TreeH] -> TreeH
nodeH t ts = NodeH (1 + maximum (map heightH ts)) t ts
```

Q15 - Define tree2treeH

Following function transforms a given Tree to TreeH (similar to Q13).

```
tree2treeH::Tree -> TreeH
tree2treeH (Stop s) = StopH s
tree2treeH (Node t ts) = nodeH t [ tree2treeH x | x <- ts]</pre>
```

Justify heightH . tree2treeH = height:

- when input t is final, we have heightH t and height t both equals to 0
- when input t is not final, tree2treeH t will calculate the height of each layer recursively (1 + maximum (map heightH ts)) until hit final states. Becaue function heightH equals to height (0) when given t is final, the statement is equivant to height by (1 + (maximum \$ map height xs)).

As a result, I believe heightH . tree2treeH = height.

To increase my confidence level, I've also implemented a quick check test for this assumption. Please see **Appendix** for full implementation.

```
prop_testHeight t = heightH (tree2treeH t) == height t
```

After running the test, we had following result:

```
Main> quickCheck prop_testHeight
+++ OK, passed 100 tests.
```

Q16 - Define mktreeH

I've found three possible approaches to achieve this function.

Approach 1 - using 1st level tree only

Instead of traversing all trees nodes, we only transform the first layer of the trees.

```
mktreeH :: State -> TreeH
mktreeH s = minHeightH ( map ( \t -> nodeH t [ tree2treeH (mktree s') | s' <-
(outcomes s t)]) (tests s))</pre>
```

Approach 2 - traverse all node during generation

This approach will calculate the height of all tree nodes during generation.

```
mktreeH' :: State -> TreeH
mktreeH' s
    | final s || length (tests s) == 0 = StopH s
    | otherwise = minHeightH ( map ( \t -> nodeH t [ mktreeH' s' | s' <- (outcomes s t)]) (tests s))</pre>
```

Approach 3 - convert the final result of mktree

This approach is very straight forward, it converts whatever output of mktree function.

```
mktreeH'' :: State -> TreeH
mktreeH'' = tree2treeH . mktree
```

Peformance Indication

The following table summarized our experiment for each approach.

Test case: Pair 8 0

Function	Performance	Analysis
mktreeH	Almost identical to mktree, with less than 0.1-second difference	According to our experiment in Appendix 2 , the performance of height and heightH is unnoticeable when given tree or data set is small.
mktreeH'	Significantly slower than mktree	We have to calculate the height for all possible nodes during tree generation.
mktreeH''	Slightly slower than mktree	It won't improve the performance because mktree is always executed first. It's a bit slower because it takes time to get the height of a Tree.

As a result, we pick mktreeH as our final submission.

A greedy solution

According to our experiment, our previous attempt didn't optimize the performance as we would hope it would be. In this section, we are going to try a greedy solution which filters the test cases at local bases.

Firstly, we will copy the optimal method from the assignment sheet.

Q17 - Define bestTests

Following function filters the tests by checking if the test case is optimal.

```
bestTests::State -> [Test]
bestTests s = filter (\t -> optimal s t) (tests s)
```

Q18 - Define mktreeG

The following function returns a tree with the best strategy based on all optimal tests. The algorithm is very similar to mktree.

```
mktreeG::State -> TreeH
mktreeG s
    | final s || length (bestTests s) == 0 = StopH s
    | otherwise = minHeightH ( map ( \t -> nodeH t [ mktreeG s' | s' <- (outcomes s t)]) (bestTests s))</pre>
```

Q19 - Define mktreesG

This function returns a list of decision trees based on all optimal tests.

```
mktreesG::State -> [TreeH]
mktreesG s = map (\t -> nodeH t [mktreeG s' | s' <- (outcomes s t)]) (bestTests
s)</pre>
```

There is only 1 tree in the list for Pair 12 0. The reason behind this is because there is only 1 optimal test for bestTests (Pair 12 0).

Appendix 1 - Automated Tests

In order to justify the assumption of question 15, I implemented quick check tests to validate our theory. Although this can not prove the equation is always correct, this still increases the user's confidence significantly.

"as an inverse to treeH2tree. Convince yourself that => heightH . tree2treeH = height"

Firstly, we need to create a new instance for our customized data type State.

```
instance Arbitrary State where
  arbitrary = sized state'
  where
  state' 0 = do
        u <- arbitrary
        g <- arbitrary
        return (Pair u g)
  state' n = do
        l <- arbitrary
        h <- arbitrary
        return (Triple l h g)</pre>
```

Secondly, we need to create a new instance for our customized data type Test.

```
instance Arbitrary Test where
    arbitrary = sized test'
        where
          test' 0 = do
              u <- arbitrary
               g <- arbitrary</pre>
               u' <- arbitrary
               g' <- arbitrary
               return (TPair (u,g) (u',g'))
          test' n = do
               1 <- arbitrary</pre>
               h <- arbitrary
               g <- arbitrary
               l' <- arbitrary</pre>
               h' <- arbitrary
               g' <- arbitrary
               return (TTrip (l,h,g) (l',h',g'))
```

Thirdly, we have to create a new instance for Tree. Tree is a recursive data type. It is important that we control the size of recursion. That is why I choose to use (n div 2) to avoid long test case generation.

Finally, we define our test cases, given a random tree, we will always have the following equation:

heightH (tree2treeH tree) == height tree

```
prop_testHeight t = heightH (tree2treeH t) == height t
```

After execution, we had following result:

```
Main> quickCheck prop_testHeight +++ OK, passed 100 tests.
```

Appendix 2 - Comparing height and heightH

In order to test the performance difference between heighH and height. We designed the following test cases:

Define a as a Tree with height 3.

```
a = Node (TPair (2,0) (2,0)) [Node (TTrip (0,0,1) (0,1,0)) [Stop (Triple 0 1 7),Node (TTrip (1,0,0) (1,0,0)) [Stop (Triple 1 0 7),Stop (Triple 0 1 7),Stop (Triple 1 0 7)],Stop (Triple 0 0 8)],Node (TPair (0,2) (2,0)) [Node (TTrip (0,0,1) (0,1,0)) [Stop (Triple 0 1 3),Stop (Triple 0 1 3),Stop (Triple 0 0 4)],Node (TPair (1,0) (1,0)) [Stop (Triple 1 1 0),Stop (Pair 0 8),Stop (Triple 1 1 0)],Node (TTrip (0,0,1) (1,0,0)) [Stop (Triple 0 0 4),Stop (Triple 1 0 3),Stop (Triple 1 0 3)]],Node (TTrip (0,0,1) (0,1,0)) [Stop (Triple 0 1 7),Node (TTrip (1,0,0) (1,0,0)) [Stop (Triple 1 0 7),Stop (Triple 0 1 7),Stop (Triple 0 0 8)]]
```

Define b as a TreeH with height 3.

```
b = NodeH 3 (TPair (2,0) (2,0)) [NodeH 2 (TTrip (0,0,1) (0,1,0)) [StopH (Triple 0 1 7),NodeH 1 (TTrip (1,0,0) (1,0,0)) [StopH (Triple 1 0 7),StopH (Triple 0 1 7),StopH (Triple 1 0 7)],StopH (Triple 0 0 8)],NodeH 2 (TPair (0,2) (2,0)) [NodeH 1 (TTrip (0,0,1) (0,1,0)) [StopH (Triple 0 1 3),StopH (Triple 0 1 3),StopH (Triple 0 0 4)],NodeH 1 (TPair (1,0) (1,0)) [StopH (Triple 1 1 0),StopH (Pair 0 8),StopH (Triple 1 1 0)],NodeH 1 (TTrip (0,0,1) (1,0,0)) [StopH (Triple 0 0 4),StopH (Triple 1 0 3),StopH (Triple 1 0 3)]],NodeH 2 (TTrip (0,0,1) (0,1,0)) [StopH (Triple 0 1 7),NodeH 1 (TTrip (1,0,0) (1,0,0)) [StopH (Triple 1 0 7),StopH (Triple 0 1 7),StopH (Triple 0 0 8)]]
```

On top of that, we also have a == (treeH2tree b):

For example:

```
*Main> a == (treeH2tree b)
True
```

We've run the following tests:

Test Case	Time Usage
height a	0.00 sec
heightH b	0.00 sec
minimum (map (\x -> a) [0100])	0.04 sec

Test Case	Time Usage
minimum (map (\x -> b) [0100])	0.04 sec
minimum (map (\x -> a) [010000])	0.30 sec
minimum (map (\x -> b) [010000])	0.05 sec

In conclusion, when given data set is small (either a smaller Tree, or smaller dataset), the performance difference between height and heightH is unnoticeable. However, the cached method works a lot better when there are more maps in the list as it doesn't need to traverse all the child nodes. Unfortunately, in our case, this is not the main bottleneck of mktree (Pair 8 0).