UM-SJTU Joint Institute, Physics Laboratory I Measurement Uncertainty Analysis Worksheet* Exercise 5

WS-1 Natural Angular Frequency

The uncertainty for ten periods is found first. Then the result for the natural frequency is given along with its uncertainty.

The type-B uncertainty for T is $\Delta_{TB} = 0.001$ s. To find the type-A uncertainty, we first find the standard deviation

$$s_T = \sqrt{\frac{1}{n-1} \sum_{i=1}^{n} (T_i - \overline{T})^2} = 0$$
 [S].

We have $n = \underline{\hspace{1cm}}$, so the type-A uncertainty Δ_{TA} is calculated as

$$\Delta_{TA} = \frac{t_{0.95}}{\sqrt{n}} s_T = 1.59 \times 0 = 0 [S].$$

Hence the uncertainty for T is given by

$$u_T = \sqrt{\Delta_{TA}^2 + \Delta_{TB}^2} =$$
 _ _ _ _ _ _ [_ 3].

Hence the period is given by

$$T = 1.550 \pm 0.00$$

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with relative uncertainty

$$\boxed{u_{\mathrm{r}T}} = \dfrac{u_T}{T} imes 100\% = \boxed{$$
 0.0b $\%$

The natural angular frequency ω_0 is found from the formula $\omega_0 = 2\pi/T$, so by the uncertainty propagation formula and the fact that

$$\frac{\partial \omega_0}{\partial T} = -\frac{2\pi}{T^2},$$

we obtain

$$\begin{bmatrix} u_{\omega_0} \end{bmatrix} = \begin{vmatrix} \frac{\partial \omega_0}{\partial T} u_T \end{vmatrix} =
 \begin{bmatrix} 0.003 \\ 0.003 \\ 0.003 \\ 0.003 \\ 0.003 \end{bmatrix}$$

with the relative uncertainty

WS-2Damping Coefficient

The damping coefficient is found indirectly form measurements of the period T

and the amplitude θ as $\beta = \frac{1}{5T} \ln(\theta_i/\theta_{i+5})$.

The uncertainty each single measurement of the amplitude is $u_{\theta} = \frac{1}{(\theta_i/\theta_{i+5})}$, so the uncertainty of the logarithm of the quotient of them $q_i = \ln(\theta_i/\theta_{i+5})$ is found from the uncertainty propagation formula

$$\Delta_{q_i,B} = \sqrt{\left(\frac{\partial (\ln(\theta_i/\theta_{i+5}))}{\partial \theta_i}\right)^2 u_\theta^2 + \left(\frac{\partial (\ln(\theta_i/\theta_{i+5}))}{\partial \theta_{i+5}}\right)^2 u_\theta^2} = \sqrt{\left(\frac{u_\theta}{\theta_{i+5}}\right)^2 + \left(\frac{u_\theta}{\theta_i}\right)^2}$$

For example, for i = 1,

$$\Delta_{q_1,B} = \sqrt{\left(\frac{1}{b_k}\right)^2 + \left(\frac{1}{b_1}\right)^2} = 0.02.$$

The results for all five sequences of measurements are given in Table WS-1.

\overline{i}	$\Delta_{q_i,B}$	
0	0.021	8,62
1	0-0-23-24	ር የዕጉ
2	0-1-26	0.03
3	لاده و	60.0
4		0.03

Table WS-2: Type-B uncertainties for q_i .

The overall type-B uncertainty for the quotient can be estimated as the maximum of uncertainties listed in in Table WS-2

$$\Delta_{q,B} = \underline{\bullet.o}\underline{\flat}.$$

To estimate the type-A uncertainty of q, the standard deviation of q is calculated as

$$s_q = \sqrt{rac{1}{n-1}\sum_{i=1}^n (q_i - \overline{q})^2} =$$

Hence the type-A uncertainty for n = 5 is calculated as

$$\Delta_{q,A} = \frac{t_{0.95}}{\sqrt{n}} s_q = 1.20 \psi \times 0.00 \% = 6.00 \%,$$

and the combined uncertainty

$$u_q = \sqrt{\Delta_{q,B}^2 + \Delta_{q,A}^2} = \sqrt{0.63^2 \text{ tow}}$$
 = 0.63 .

A single measurement for ten periods is recorded as $T_{10} = 15.550 \pm 0.000 = 1.5500 \pm 0.000 = 1.5500 \pm 0.000 = 1.5500 = 1.5000$

tainty for the damping coefficient $\beta = \frac{1}{5T}q$ as

$$\begin{array}{lll} \boxed{u_{\beta}} & = & \sqrt{\left(\frac{\partial\beta}{\partial T}\right)^2 u_T^2 + \left(\frac{\partial\beta}{\partial q}\right)^2 u_q^2} = \sqrt{\left(-\frac{q}{5T^2}\right)^2 u_T^2 + \left(\frac{1}{5T}\right)^2 u_q^2} \\ & = & \sqrt{\frac{\left(-\frac{0.462}{5\times1.5550}\right)^2 \chi_{0.000}}{5\times1.5550}} = \boxed{\frac{0.004}{5\times1.5550}} = \boxed{\frac{0.00$$

with relative uncertainty

$$u_{\mathrm{r},\beta} = \frac{u_{\beta}}{\beta} \times 100\% = \boxed{} \times \sqrt{}$$

The θ_{st} - ω and φ - ω Characteristics of Forced $m WS ext{-}3$ Oscillations

On the graphs included in the report, the uncertainty is shown in the form of error bars. In both the φ vs. (ω/ω_0) graph and the $\theta_{\rm st}$ vs. (ω/ω_0) graph, the

¹Please follow this part to find the uncertainties and mark them on the graphs of the phase shift φ vs. (ω/ω_0) graph and the amplitude of steady-state oscillations $\theta_{\rm st}$ vs. (ω/ω_0) .

measurements of φ and $\theta_{\rm st}$ are single measurements with uncertainty _____o, determined by the resolution of our equipment. However, to find the uncertainty of (ω/ω_0) we need to derive it from the uncertainty propagation formula. Let us introduce symbols $Q = \frac{\omega}{\omega_0}$, $T_{\rm natural} = N$ and $T_{\rm driven} = D$, where the uncertainty of D is again the minimum scale (resolution) of the equipment used. Since these are single measurements, we have

$$Q = \frac{\omega}{\omega_0} = \frac{T_{\text{natural}}}{T_{\text{driven}}} = \frac{N}{D}$$

and the uncertainty of the ratio Q, found from the uncertainty propagation formula, is

$$u_Q = \sqrt{\left(\frac{\partial Q}{\partial N} u_N\right)^2 + \left(\frac{\partial Q}{\partial D} u_D\right)^2} = \sqrt{\left(\frac{u_N}{D}\right)^2 + \left(\frac{N u_D}{D^2}\right)^2}$$

In particular, with N = 1.556 [S], $u_N = 6.06$ [S], and $u_D = 6.06$ [S], so with every set of N and D a unique uncertainty is generated. For instance, for D = 1.476 [S], we can calculate Q as

$$Q = \frac{N}{D} = \frac{1.556}{1.416} = 1.054$$

with uncertainty u_Q calculated as

²Here, based on your measurement data, give one sample calculation for a chosen value of ω/ω_0 . All values of the calculated uncertainties u_Q that you have used to plot error bars, should be given in the *Results* section, where tables with the data for the plots φ vs. (ω/ω_0) and $\theta_{\rm st}$ vs. (ω/ω_0) is included.