Quantum Computing Exercise

Name:

1.

$$\begin{split} D_{\vec{n}}(\alpha) &= e^{-i\frac{\alpha}{2}\vec{n}\cdot\vec{\sigma}} = Icos(\frac{\alpha}{2}) - isin(\frac{\alpha}{2})\vec{n}\cdot\vec{\sigma} \\ [D_{\vec{n}}(\alpha)]^{\dagger} &= D_{\vec{n}}(-\alpha) = e^{-i\frac{\alpha}{2}\vec{n}\cdot\vec{\sigma}} = Icos(\frac{\alpha}{2}) + isin(\frac{\alpha}{2})\vec{n}\cdot\vec{\sigma} \\ \rho' &= [D_{\vec{n}}(\alpha)] \dagger \rho D_{\vec{n}}(\alpha) = D_{\vec{n}}(-\alpha)\rho D_{\vec{n}}(\alpha) = [D_{\vec{n}}(\alpha)](I + \vec{x}\cdot\vec{\sigma})D_{\vec{n}}(\alpha) \\ &= \frac{1}{2}I + \frac{1}{2}(Icos(\frac{\alpha}{2}) + isin(\frac{\alpha}{2})\vec{n}\cdot\vec{\sigma})(\vec{x}\cdot\vec{\sigma})(Icos(\frac{\alpha}{2}) - isin(\frac{\alpha}{2})\vec{n}\cdot\vec{\sigma}) \\ &= \frac{1}{2}I + \frac{1}{2}[(e^{-i\frac{\alpha}{2}\vec{n}\cdot\vec{\sigma}} = Icos(\frac{\alpha}{2}))\vec{n}\cdot\vec{\sigma}(cos(\frac{\alpha}{2})\vec{x}\cdot\vec{\sigma}(\vec{n}\cdot\vec{\sigma}))] \\ &= \frac{1}{2}I + \frac{1}{2}[cos^2(\frac{\alpha}{2})\vec{x}\cdot\vec{\sigma} - isin(\frac{\alpha}{2})cos(\frac{\alpha}{2})(\vec{x}\cdot\vec{\sigma}\cdot\vec{n}\cdot\vec{\sigma}) \\ &+ isin(\frac{\alpha}{2})cos(\frac{\alpha}{2})\vec{n}\cdot\vec{\sigma}\cdot\vec{x}\cdot\vec{\sigma} + isin^2(\frac{\alpha}{2})(\vec{n}\cdot\vec{\sigma}\cdot\vec{x}\cdot\vec{\sigma}\vec{n}\cdot\vec{\sigma})] \\ &= \frac{1}{2}I + \frac{1}{2}[cos^2(\frac{\alpha}{2})\vec{x}\cdot\vec{\sigma} + isin(\frac{\alpha}{2})cos(\frac{\alpha}{2})(\vec{x}\cdot\vec{\sigma}\cdot\vec{n}\cdot\vec{\sigma}) \\ &+ isin(\frac{\alpha}{2})cos(\frac{\alpha}{2})(\vec{n}\cdot\vec{x}-\vec{x}\cdot\vec{n}) + sin^2(\frac{\alpha}{2})\vec{n}\cdot\vec{\sigma}\vec{x}\cdot\vec{\sigma}\vec{n}\cdot\vec{\sigma}] \end{split}$$

$$Let Q = \vec{n}\cdot\vec{\sigma}\cdot\vec{x}\cdot\vec{\sigma}\vec{n}\cdot\vec{\sigma} = [\vec{n}\cdot\vec{\sigma},\vec{x}\cdot\vec{\sigma}] = 2i(\vec{n}\times\vec{x}), \\ &= \frac{1}{2}I + \frac{1}{2}[cos^2(\frac{\alpha}{2})\vec{x}\cdot\vec{\sigma} + isin(\frac{\alpha}{2})cos(\frac{\alpha}{2})(\vec{x}\cdot\vec{\sigma}\cdot\vec{n}\cdot\vec{\sigma}) \\ &+ isin(\frac{\alpha}{2})cos(\frac{\alpha}{2})Q + sin^2(\frac{\alpha}{2})\vec{n}\cdot\vec{\sigma}\vec{x}\cdot\vec{\sigma}\vec{n}\cdot\vec{\sigma}] \\ &= \frac{1}{2}I + \frac{1}{2}[cos\alpha + (1-cos\alpha)(\vec{n}\vec{x}\vec{n} - sin\alpha\vec{n}\times\vec{x}]\cdot\vec{\sigma} \\ &= \frac{1}{2} + \frac{1}{2}\vec{y}\cdot\vec{\sigma} \end{split}$$

$$\text{where } cos\alpha\vec{x} + (1-cos\alpha)(\vec{n}\cdot\vec{x}\cdot\vec{n}) - sin\alpha(\vec{n}\times\vec{x}) = O_{\vec{n}}\cdot\vec{x} \\ \text{and } O_{\vec{n}(\alpha)} = \begin{bmatrix} cos\alpha + (1-cos\alpha)n_1^2 & (1-cos\alpha)n_1n_2 + sin\alpha n_3 & (1-cos\alpha) & n_1-n_3 - sin\alpha n_2 \\ (1-cos\alpha)n_1n_2 - sin\alpha n_3 & cos\alpha + (1-cos\alpha)n_2^2 & (1-cos\alpha)n_2n_3 + sin\alpha n_1 \\ (1-cos\alpha)n_1n_3 + sin\alpha n_2 & (1-cos\alpha)n_2n_3 - sin\alpha n_1 & cos\alpha + (1-cos\alpha)n_3^2 \end{bmatrix}$$

2.

• (1) & (2) Reduced states and Schmidt form of ρ_A, ρ_B In order to construct the basis of $|\psi\rangle \in \mathbb{H}^2 \times \mathbb{H}^2$ under the Schmidt decomposition, we can compute the reduced density operator of $|\psi\rangle$ firstly:

$$|\psi
angle = rac{1}{\sqrt{3}}(|00
angle + |01
angle + |10
angle) \ |\psi
angle\langle\psi| = rac{1}{3}(|00
angle + |01
angle + |10
angle)(\langle00| + \langle01| + \langle10|)$$

$$\begin{split} \rho_A &= tr_B(|\psi\rangle\langle\psi|) = \frac{1}{3}(|0\rangle\langle 0|_A \otimes |0\rangle\langle 0|_B + |0\rangle\langle 0|_A \otimes |0\rangle\langle 1|_B + |0\rangle\langle 1|_A \otimes |0\rangle\langle 0|_B \\ &+ |0\rangle\langle 0|_A \otimes |1\rangle\langle 0|_B + |0\rangle\langle 0|_A \otimes |1\rangle\langle 1|_B + |0\rangle\langle 1|_A \otimes |1\rangle\langle 0|_B \\ &+ |1\rangle\langle 0|_A \otimes |0\rangle\langle 0|_B + |1\rangle\langle 0|_A \otimes |0\rangle\langle 1|_B + |1\rangle\langle 1|_A \otimes |0\rangle\langle 0|_B \end{split}$$

Since $tr_B(|i
angle\langle j|)=\langle i|j
angle=\delta_{ij}$,

$$ho_A = rac{1}{3} egin{bmatrix} 2 & 1 \ 1 & 1 \end{bmatrix}$$

Apply the same computatation to $ho_B, \;
ho_B = rac{1}{3} egin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$.

Let $ho_A,
ho_B$ be in the eigen-basis: $ho_A=\sum_i p_i|i\rangle\langle i|,\; \dot{
ho}_B=\sum_j p_j|j\rangle\langle j|,$

and consendering the fact that $ho_A,
ho_B$ share common eigenvalues(that's: $p_i = p_j$), it helps with the Schmidt form:

$$|\psi
angle = \sum_i \sqrt{p_i} |i_A
angle |i_B
angle$$

In this case, we get:

$$ho_A=
ho_B=egin{cases} p_1=rac{3+\sqrt{5}}{2}, & |i_{p_1}
angle=\left[rac{1}{\sqrt{5}-1}
ight] \ p_2=rac{3-\sqrt{5}}{2}, & |i_{p_2}
angle=\left[rac{1}{2}
ight] \ -rac{\sqrt{5}+1}{2} \end{bmatrix}$$

$$\begin{split} \mathsf{hence}, & |\psi\rangle = \tfrac{3+\sqrt{5}}{2} \cdot |i_{p_1}\rangle \otimes |i_{p_1}\rangle + \tfrac{3-\sqrt{5}}{2} \cdot |i_{p_2}\rangle \otimes |i_{p_2}\rangle \\ & = \frac{3+\sqrt{5}}{2} \cdot \begin{bmatrix} 1 \\ \frac{\sqrt{5}-1}{2} \end{bmatrix}_A \otimes \begin{bmatrix} 1 \\ \frac{\sqrt{5}-1}{2} \end{bmatrix}_B + \frac{3-\sqrt{5}}{2} \cdot \begin{bmatrix} 1 \\ -\frac{\sqrt{5}+1}{2} \end{bmatrix}_A \otimes \begin{bmatrix} 1 \\ -\frac{\sqrt{5}+1}{2} \end{bmatrix}_B \end{split}$$

This is the Schmidt form of ρ_A, ρ_B .

- (3)
- 3.
- 4.