

Mathematics Department C4 SOW

Specification	Reference	Notes/Extra Material
1. Algebra and Functions <ul style="list-style-type: none"> Rational functions. Partial fractions (denominators not more complicated than repeated linear terms) 	Heinemann Chapter 1 Section 1:1 to 1.5 <ul style="list-style-type: none"> Exercises 1A, 1B, 1C, 1D & 1E Summary of key points	Partial fractions to include denominators such as $(ax + b)(cx + d)(ex + f)$ and $(ax + b)(cx + d)^2$ The degree of the numerator may equal or exceed the degree of the denominator. Applications to integration, differentiation and series expansions. Quadratic factors in the denominator such as $(x^2 + a)$, $a > 0$ are not required. Mixed Exercise 1F Revision Exercise 1
2. Coordinate geometry in the (x, y) plane <ul style="list-style-type: none"> Parametric equations of curves and conversion between Cartesian and parametric forms. 	Heinemann Chapter 2 Sections 2.1 – 2.4 <ul style="list-style-type: none"> Exercises 2A, 2B, 2C, & 2D Summary of key points	Candidates should be able to find the area under a curve given its parametric equations. Candidates will not be expected to sketch a curve from its parametric equations. Mixed Exercise 2E Revision Exercise 2

<p>3. Sequences & Series</p> <ul style="list-style-type: none"> Binomial series for any rational n. 	<p>Heinemann Chapter 3</p> <p>Sections 3.1 to 3.3 - Exercises 3A, 3B & 3C</p> <p>Summary of key points</p>	<p>For $x < b/a$, candidates should be able to obtain the expansion of $(ax + b)^n$, and the expansion of rational functions by decomposition into partial fractions.</p> <p>Mixed Exercise 3D Revision Exercise 3</p>
<p>4. Differentiation</p> <ul style="list-style-type: none"> Differentiation of simple functions defined implicitly or parametrically Exponential growth and decay. Formation of simple differential equations. 	<p>Heinemann Chapter 4</p> <p>Sections 4.1 to 4.2 - Exercises 4A & 4B</p> <p>Section 4.3 - Exercises 4C</p> <p>Sections 4.4 to 4.5 - Exercises 4D, & 4E</p> <p>Summary of key points</p>	<p>The finding of equations of tangents and normals to curves given parametrically or implicitly is required.</p> <p>Knowledge and use of the result $d/dx (a^x) = a^x \ln a$ is expected.</p> <p>Questions involving connected rates of change may be set.</p> <p>Mixed Exercise 4F Revision Exercise 4</p>

<p>5. Integration</p> <ul style="list-style-type: none"> Integration of e^x, $1/x$, $\sin x$, $\cos x$. Evaluation of volume of revolution Simple cases of integration by substitution and integration by parts. These methods as the reverse processes of the chain and product rules respectively. Simple cases of integration using partial fractions. 	<p>Heinemann Chapter 6</p> <p>Sections 6.1 - Exercise 6A</p> <p>Sections 6.9 - Exercise 6I</p> <p>Sections 6.2, 6.3, 6.6, 6.7 - Exercises 6B, 6C 6F & 6G</p> <p>Sections 6.4 & 6.5 - Exercises 6D & 6E</p>	<p>To include integration o standard functions such as $\sin 3x$, $\sec^2 2x$, $\tan x$, e^{5x}, $1/2x$. Candidates should recognise integrals of the form $\int \frac{f'(x)}{F(x)} dx = \ln f(x) + c$</p> <p>Candidates are expected to be able to sue trigonometric identities to integrate, for example, $\sin^2 x$, $\tan^2 x$, $\cos^2 3x$</p> <p>$\int y^2 dx$ is required but not $\int x^2 dy$. Candidates should be able to find a volume of revolution, given parametric equations.</p> <p>Except in the simplest of cases the substitution will be given. The integral $\int \ln x dx$ is required. More than one application of integration by parts may be required, for example $\int x^2 e^x dx$.</p> <p>Integration of rational expressions such as those arising from partial fractions, e.g. $\frac{2}{3x+5}$, $\frac{3}{(x-1)^2}$</p> <p>Note that the integration of other rational expressions, such as $\frac{x}{x^2+5}$ and $\frac{2}{(2x-1)^4}$ is also required.</p>
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<ul style="list-style-type: none"> Analytical solution of simple first order differential equations with separable variables. Numerical integration of functions 	<p>Sections 6.10 & 6.11</p> <ul style="list-style-type: none"> Exercises 6j & 6K <p>Sections 6.8</p> <ul style="list-style-type: none"> Exercise 6H <p>Summary of key points</p>	<p>General and particular solutions will be required.</p> <p>Application of the trapezium rule to functions covered in C3 & C4. Use of increasing number of trapezia to improve accuracy and estimate error will be required. Questions will not require more than 3 iterations.</p> <p>Simpson's rule is <u>not</u> required.</p> <p>Mixed Exercise 6L Revision Exercise 6</p>
<p>6. Vectors</p> <ul style="list-style-type: none"> Vectors in two and three dimensions Magnitude of a vector Algebraic operations of vector addition and multiplication by scalars, and their geometrical interpretations. Position vectors. 	<p>Heinemann Chapter 5</p> <p>Sections 5.1 to 5.7</p> <ul style="list-style-type: none"> Exercise 5A, 5B, 5C, 5D, 5E, 5F & 5G 	<p>Candidates should be able to find a unit vector in the direction of a, and be familiar with a</p> <p>$\vec{OB} - \vec{OA} = \vec{AB} = \mathbf{b} - \mathbf{a}$</p>

<ul style="list-style-type: none"> • The distance between two points • Vector equations of lines <p>The scalar product. Its use for calculating the angle between two lines.</p>	<p>Sections 5.8 to 5.9 - Exercises 5H & 5I</p> <p>Sections 5.10 - Exercises 5J</p> <p>Summary of key points</p>	<p>The distance d between two points (x_1, y_1, z_1) and (x_2, y_2, z_2) is given by</p> $d^2 = (x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2$ <p>To include the forms $\mathbf{r} = \mathbf{a} + t\mathbf{b}$ and $\mathbf{r} = \mathbf{c} + t(\mathbf{d} - \mathbf{c})$</p> <p>Intersection, or otherwise of two lines.</p> <p>Candidates should know that for</p> $\vec{OA} = \mathbf{a} = a_1\mathbf{i} + a_2\mathbf{j} + a_3\mathbf{k} \quad \text{and}$ $\vec{OB} = \mathbf{b} = b_1\mathbf{i} + b_2\mathbf{j} + b_3\mathbf{k} \quad \text{then}$ $\mathbf{a} \cdot \mathbf{b} = a_1b_1 + a_2b_2 + a_3b_3$ <p>and $\cos AOB = \frac{\mathbf{a} \cdot \mathbf{b}}{ \mathbf{a} \mathbf{b} }$</p> <p>Candidates should know that if $\mathbf{a} \cdot \mathbf{b} = 0$, and that \mathbf{a} and \mathbf{b} are non-zero vectors, then \mathbf{a} and \mathbf{b} are perpendicular.</p> <p>Mixed Exercise 5K Revision Exercise 5</p>
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