

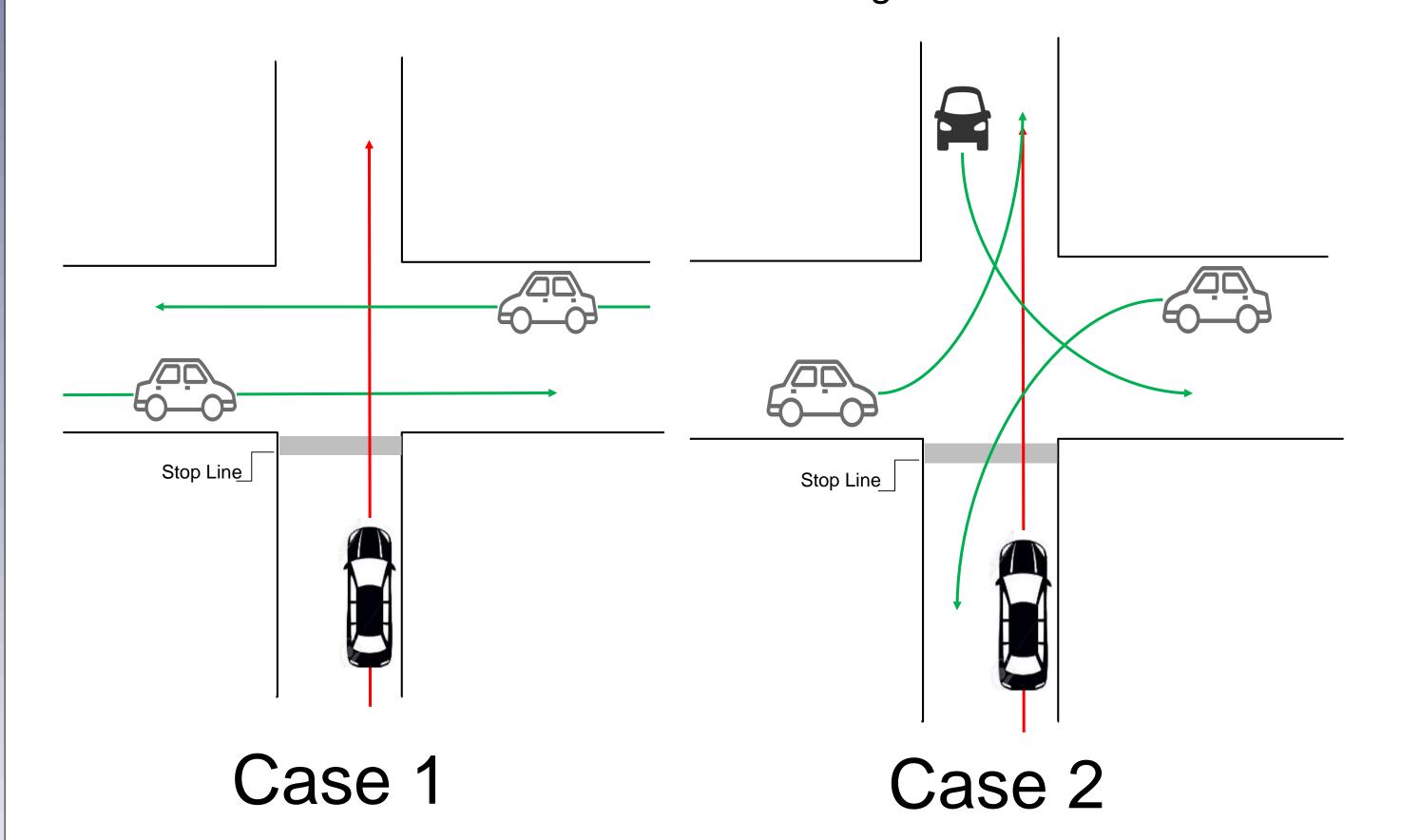
Red Light Running Detect System Jideok Park, Hyein Seo, Sujeong Lee



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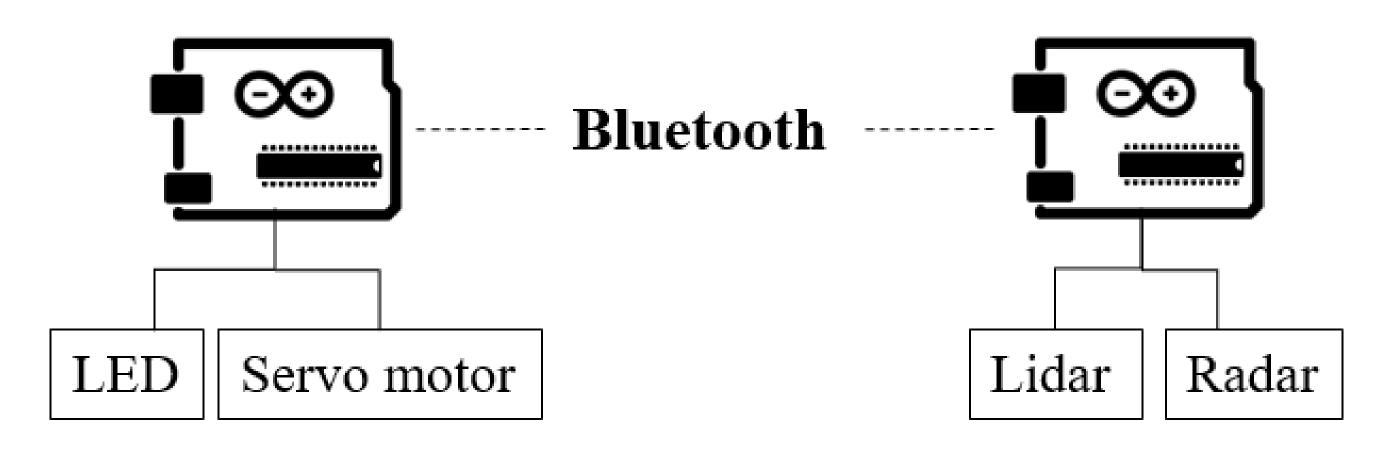
Introduction

Red Light Running is A behavior that drivers run through the red light even though the regulations indicate that driers must stop their vehicles as soon as the traffic light turns red.



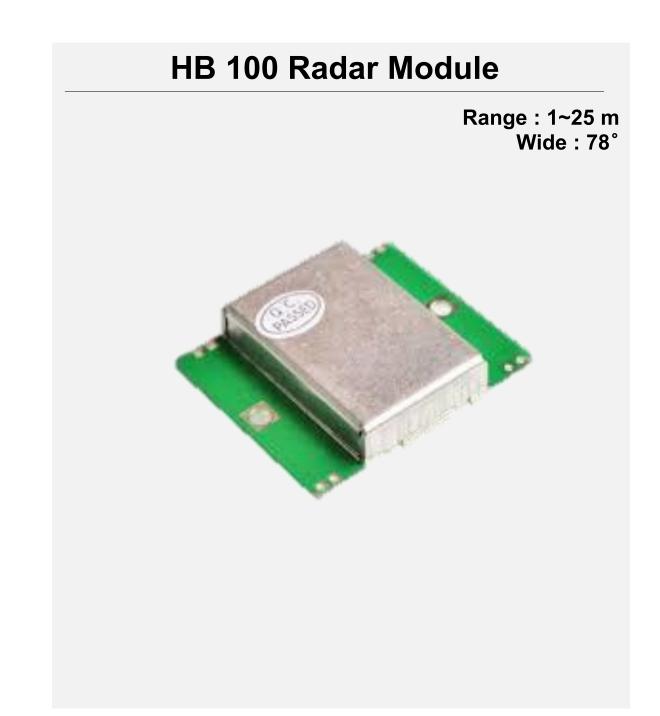
Methods

System Diagram

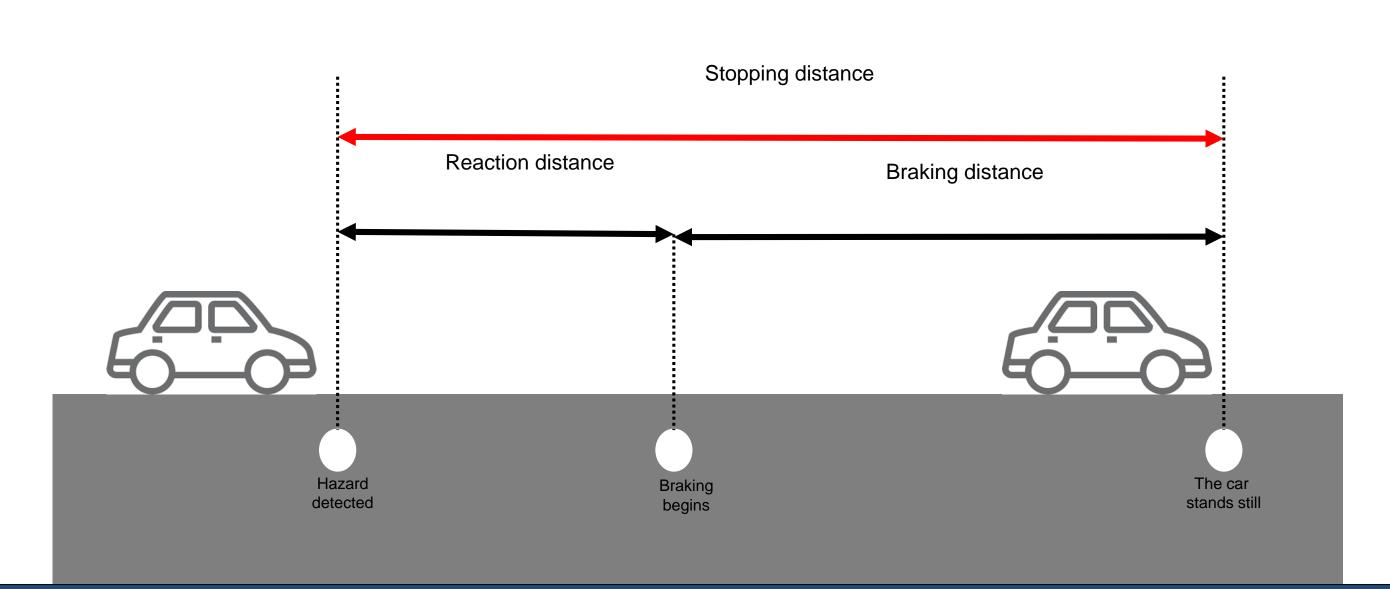


Sensors used in study





Stopping Sight Distance (SSD)



$$SSD = d_{pr} + d_{M}$$

$$= 0.278V_{t} + 0.039 \frac{V^{2}}{a}$$
(1)

$$=0.278V_t + 0.039\frac{V^2}{2} \tag{2}$$

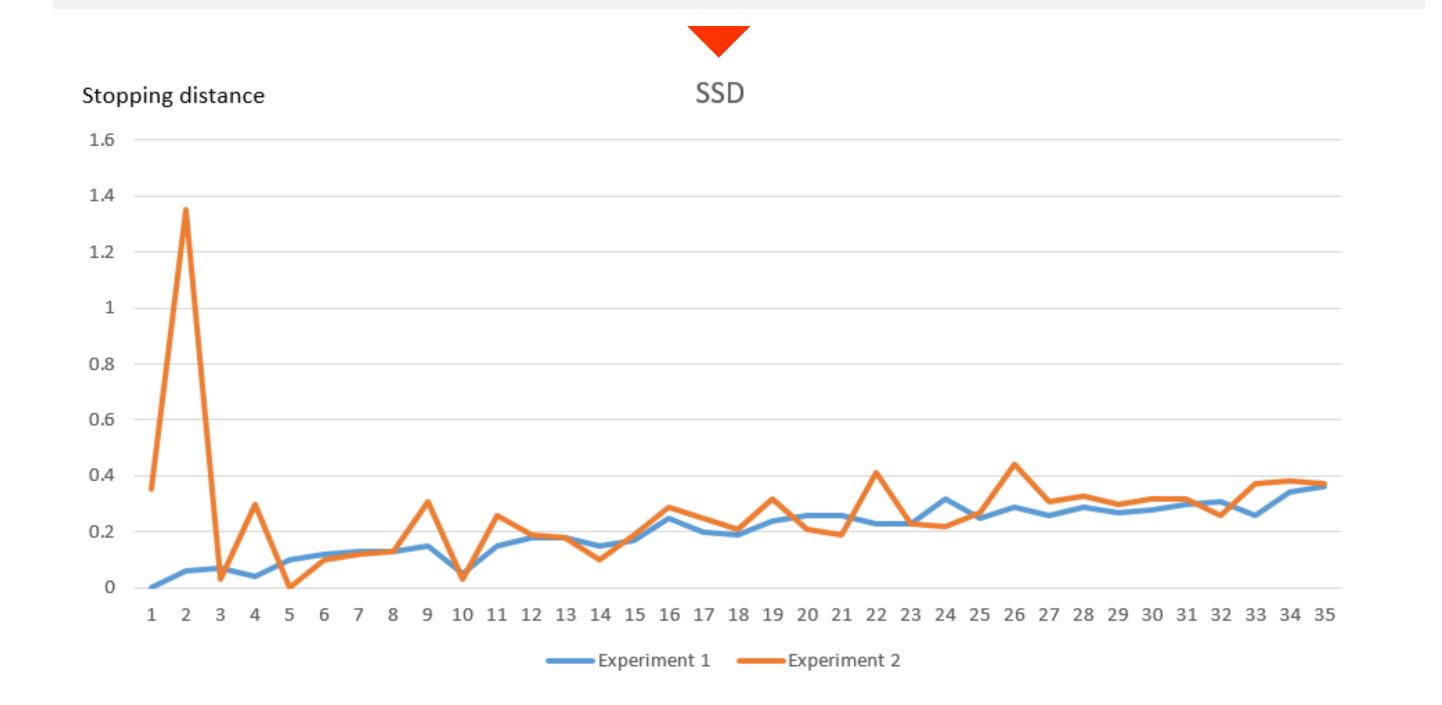
where :

$$\theta = \tan^{-1} \frac{|D_1 - SSD|}{H_1}$$

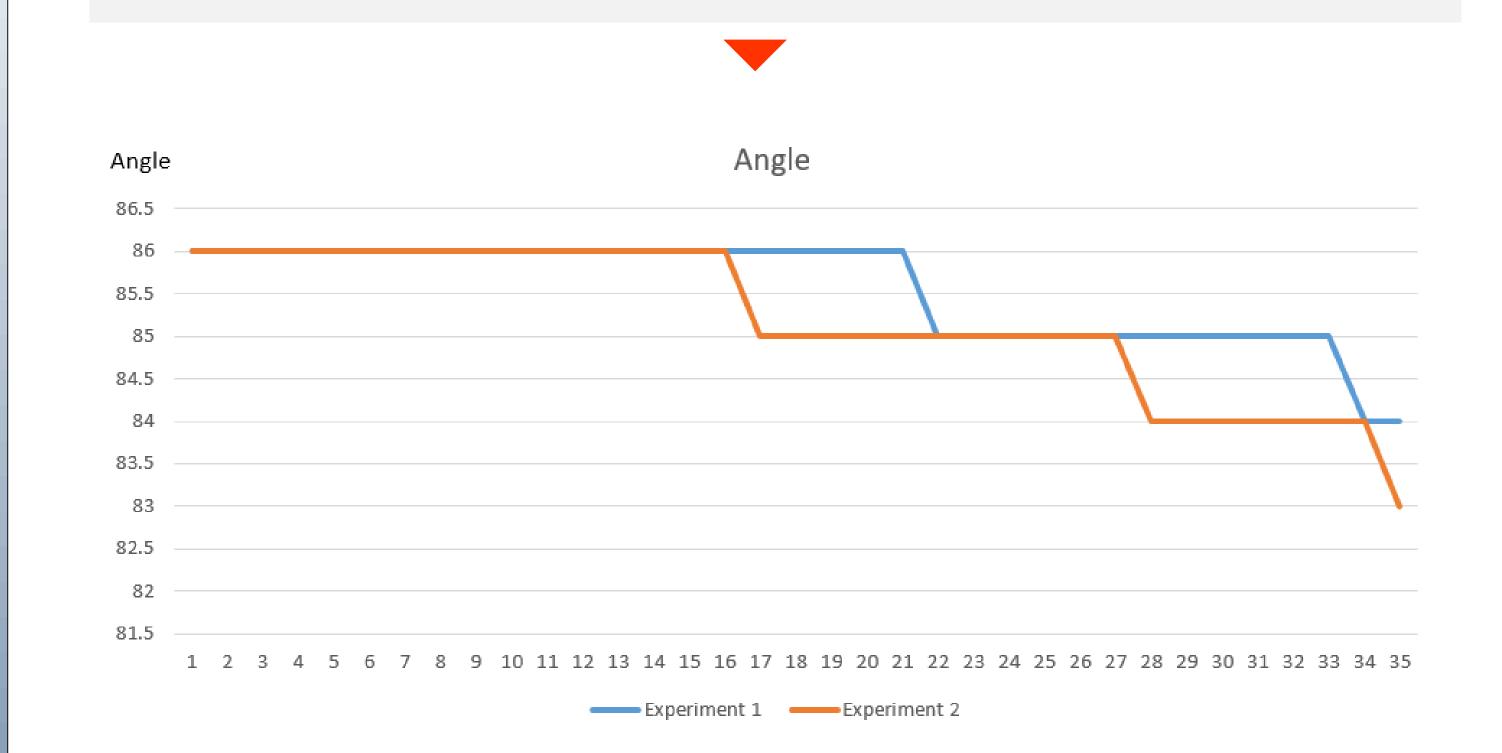
V = design speed, m/s t = brake reaction time, 2.5sec, $a = deceleration rate, m/s^2$

Results

Experiment 1. Get Stopping Sight Distance

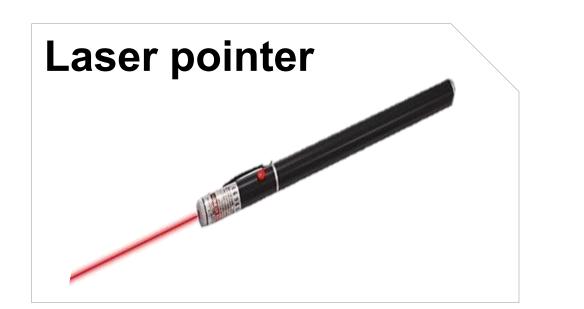


Experiment 2. Get an angle

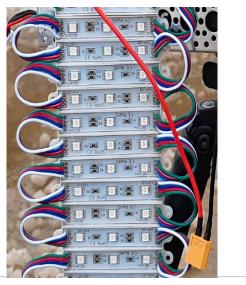


Conclusions

To solve Red Light Running







Reference

1. Yuting Zhang, Xuedong Yan, Xiaoming Li, Jiawei Wu, and Vinayak V. Dixit. International Journal of Environmental Research and Public Health. "Red-Light-Running Crashes' Classification, Comparison, and Risk Analysis Based on General Estimates System (GES) Crash Database". Published June 4, 2018. Retrieved at https://www.ncbi.nlm.nih.gov/pmc/articles/PMC6025625