



Hyeonbeen Lee

Mobile: +82-10-6236-4693
E-Mail: david.hyeonbeen.lee@gmail.com
LinkedIn: linkedin.com/in/hyeonbeen-lee-239500286
GitHub: github.com/hyeonbeenlee

PERSONAL INFORMATION

Name:	Hyeonbeen Lee	Date of birth:	July 4th, 1996
Nationality:	Republic of Korea (South)	Address:	116, Saimdang-ro 17gil, Seoul, South Korea
Military service:	Honorably discharged, Marine Corps Seageant (May 2017~Feb 2019)	Research interest:	Robot learning, Reinforcement learning, Sequential decision

EDUCATION

Banpo High School , Specialized Science Track	Mar 2012 — Feb 2015
Kyung Hee University , Dept. of Mechanical Engineering	Mar 2015 — Feb 2022
Bachelor of Engineering (Supervisor: Shin-kyu Jeong, Jin-gyun Kim)	GPA: 3.87/4.5, GPA(Major): 3.84/4.5
Thesis: <i>Data-driven aerodynamic coefficient prediction using deep neural network and PARSEC airfoil parameterization</i>	
Kyung Hee University , Dept. of Mechanical Engineering	Mar 2022 — Feb 2024
Master of Engineering (Supervisor: Jin-gyun Kim)	GPA: 4.33/4.5
Thesis: <i>Composite neural network with differential propagation for modeling impulsive nonlinear dynamic systems</i>	

SKILLS

- **Programming:** Python, Docker, Linux, Git, L^AT_EX, MATLAB, C#, C++, ROS
- **ML and data analysis:** PyTorch, TensorBoard, Pandas, OpenCV, Torchvision
- *Expertised at handling sequential data and models*
- **English:** Speaks in native level
- **Japanese:** Speaks in intermediate level

Experience Section

PUBLICATIONS

1. S. Han, G.E. Jeong, **H. Lee**, W.S. Choi, J.G. Kim, “Multi-body dynamics model for spent nuclear fuel transportation system under normal transport test conditions”, *Nuclear Engineering and Technology* (IF=2.817), accepted.
2. **H. Lee**, S. Han, H.S. Choi, J.G. Kim. “cNN-DP: Composite neural network with differential propagation for impulsive nonlinear dynamics”, *Journal of Computational Physics* (IF=4.645), accepted.
3. **H. Lee**, J. Han, T. Yeo, J.G. Kim. “Multi-horizon force components forecasting of ocean robot using interpretable Transformer and experimental measurements”, in preparation.

CONFERENCES

2022.12.04 Jeju, South Korea	H. Lee , S. Han, G.E. Jeong, J.G. Kim. “Development of multibody dynamics trailer model using normal transportation test data and DNN based surrogate model generation”, Fall conference, Korean Society for Noise and Vibration Engineering (Oral Presentation).
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2023.02.16 Austin, Texas, USA	H. Lee, S. Han, H.S. Choi, J.G. Kim. “Composite neural network framework for modeling impulsive nonlinear dynamic responses”, IMAC-XLI, Society for Experimental Mechanics (Oral Presentation).
2023.03.23 Jeju, South Korea	H. Lee, S. Han, H.S. Choi, J.G. Kim. “Meta-modeling of nonlinear impulsive dynamics using composite neural network model with differential propagation”, Conference on Dynamics and Control, Korean Society of Mechanical Engineers (Oral Presentation).
2023.05.18 Busan, South Korea	H. Lee, S. Han, H.S. Choi, J.G. Kim. “Meta-modeling of nonlinear impulsive dynamics using composite neural network model with differential propagation”, Conference on Engineering Reliability, Korean Society of Mechanical Engineers (Oral Presentation).
2023.11.01 Incheon, South Korea	H. Lee, J. Han, T. Yeo, J.G. Kim. “Real-time multi-horizon reaction force forecasting of ocean robot using interpretable Transformer”, Annual Conference, Korean Society of Mechanical Engineers (Oral Presentation).

PROJECTS

2021.09 — 2022.10	Development of ground · sea transportation test simulation model using multibody dynamics and DNN-based metamodel, Korea Atomic Energy Research Institute (KAERI).
2021.09 — Present	Metamodel generation and evolution procedures for flexible multibody dynamics, FunctionBay Inc.
2021.11 — Present	cNN-DP: Composite neural network with differential propagation for impulsive nonlinear dynamics, Modeling & Simulation Lab. (github.com/hyeonbeenlee/cNN-DP)
2022.03 — Present	Deep-learning based reaction force and torque prediction model development for underwater ground cutting robot using experimental measurements and dynamic simulation data, Korea Research Institute of Ships and Ocean Engineering (KRISO). (github.com/hyeonbeenlee/TimeSeriesSeq2Seq)
2022.12 — 2023.06	RecurDyn Automation using Python, Modeling & Simulation Lab. (github.com/hyeonbeenlee/RecurDynPython)
2023.03 — 2023.06	Segment Anyone: Fine-tuned Segment-Anything-Model (SAM) for human-collaborative robots, Kyung Hee University Dept. of Artificial Intelligence. (github.com/hyeonbeenlee/segment-anything-fine-tuning)

AWARDS AND CERTIFICATES

- **TOEIC:** 925/990 No.605083, Nov 25 2018
- **New TEPS:** 513/600 No.0111736, May 13 2023
- **Academic Excellence Scholarship (Full tuition)** Kyung Hee University, Mar 01 2021
- **Exellence Paper Award** Korean Society of Mechanical Engineers, No.2023-083, Aug 25 2023

MISCELLANEOUS

ROK-US Marine Corps Joint Operations Translator	1st Marine Div., ROKMC, Sep 2017 — Feb 2019
48th Student Council	Kyung Hee University College of Engineering, Feb 2019 — Jan 2020
Undergraduate Research Internship	Modeling & Simulation Lab, Jan 2021 — Feb 2022
Seminar: AI, Data Driven Models&ML	National Agency Finite Element Methods and Standard, Apr 2021
Seminar: AI Summer School 2021	Korean Society of Mechanical Engineers, Aug 2021
Teaching Assistant (System Dynamics)	Modeling & Simulation Lab, Mar 2022 - Jun 2023
Seminar: AI Summer School 2022	Korean Society of Mechanical Engineers, Aug 2022
Representative Administrative Assistant	Kyung Hee University, Sep 2022 — Present
Seminar: IAS18 Workshop&Tutorials	Intl. Conference on Intelligent Autonomous Systems, Jul 2023