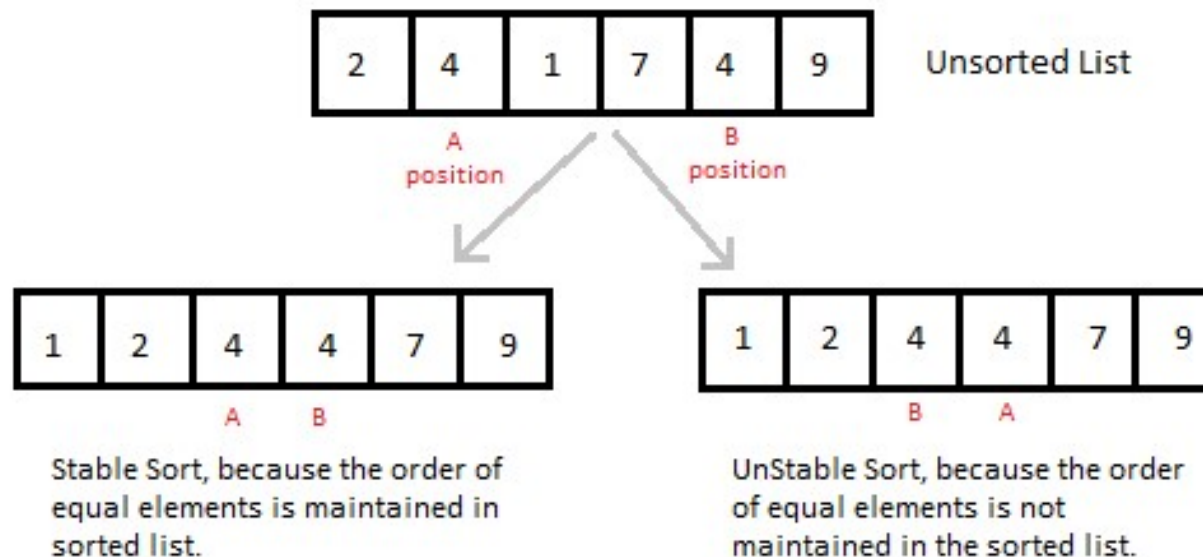


Sorting

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Sorting

- Rearrange **n** elements in a certain order.
 - 7, 3, 6, 2, 1 → 1, 2, 3, 6, 7
- A sorting algorithm is *stable* if whenever there are two records **R** and **S** with the same key, and **R** appears before **S** in the original list, then **R** will always appear before **S** in the sorted list.



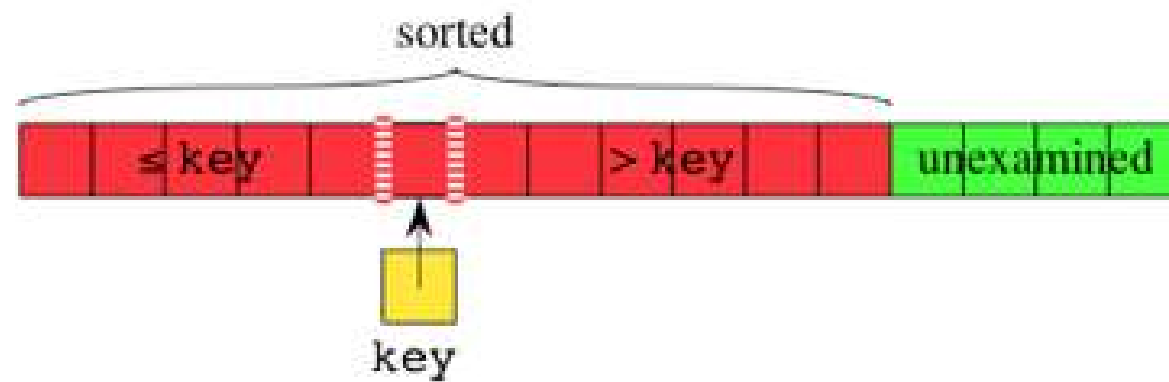
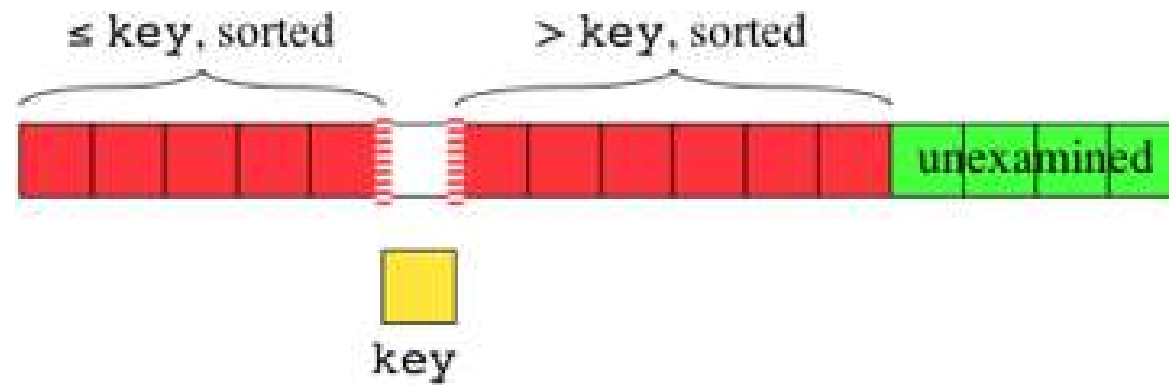
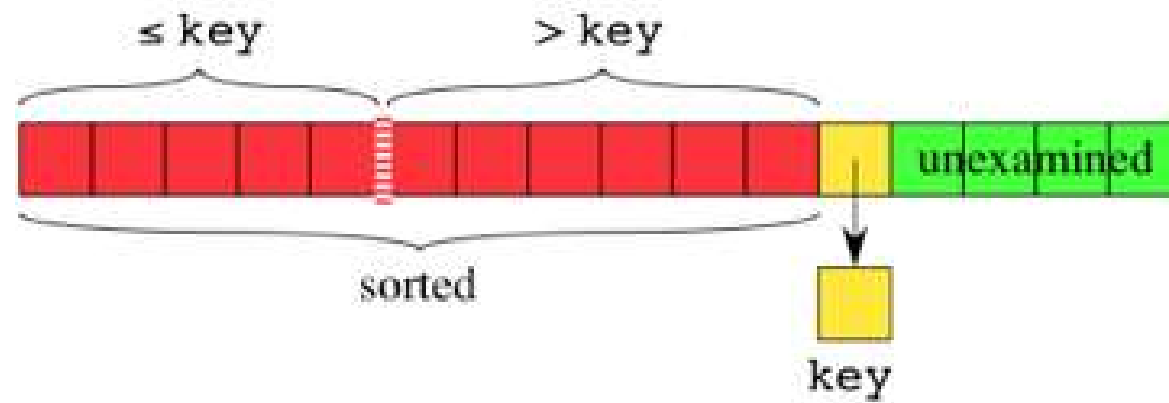
Sorting (cont.)

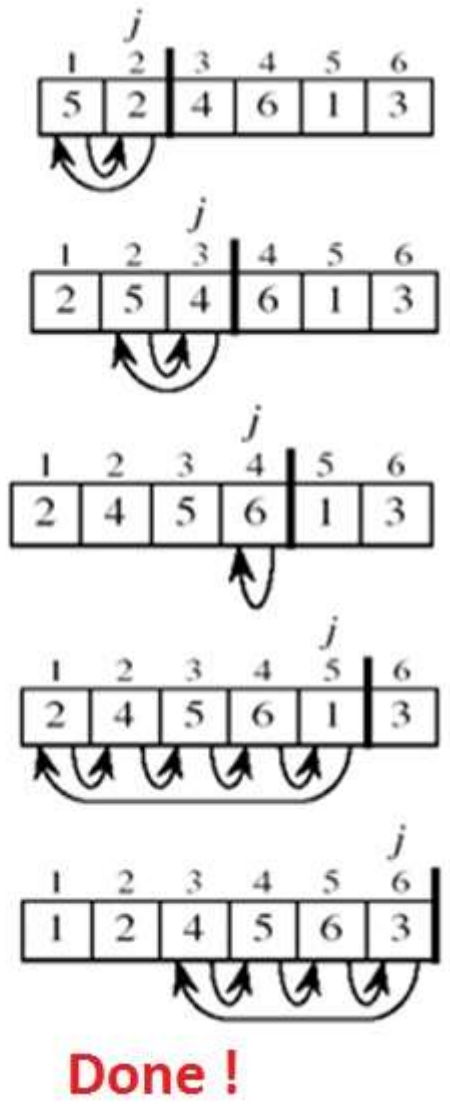
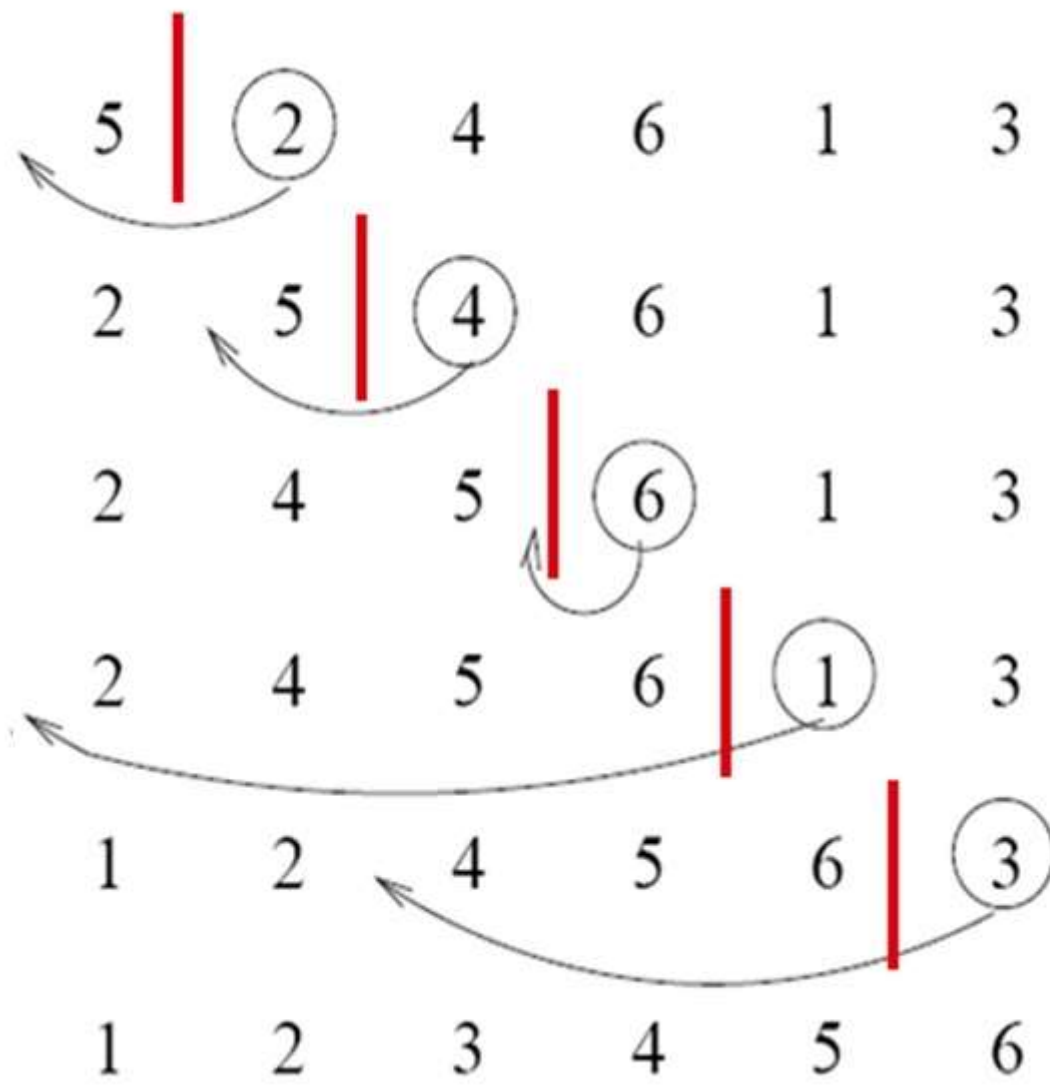
- A sorting algorithm is said to be *in-place* if
 - it updates the input sequence only through replacement or swapping of elements
 - it does not use auxiliary data structures but may require a small though non-constant extra space, usually $O(\log n)$, for its operation

Insertion Sort

- Insert a new record into a sorted sequence of i records in such a way that the resulting sequence of size $i + 1$ is also ordered
- Stable and in-place

i	[1]	[2]	[3]	[4]	[5]
—	5	4	3	2	1
2	4	5	3	2	1
3	3	4	5	2	1
4	2	3	4	5	1
5	1	2	3	4	5





```

template <class T>
void InsertionSort(T *a, const int n)
{
    // Sort a[1:n] into nondecreasing order.
    for (int j = 2; j <= n; j++) {
        T temp = a[j];
        Insert(temp, a, j-1);
    }
}

template <class T>
void Insert(const T& e, T *a, int i)
{
    // Insert e into the ordered sequence a[1:i] such that the
    // resulting sequence a[1:i+1] is also ordered.
    // The array a must have space allocated for at least i+2 elements.
    // The use of a[0] enables us to simplify the while loop,
    // avoiding a test for end of list (i.e., i < 1)
    a[0] = e;
    while (e < a[i])
    {
        a[i+1] = a[i];
        i--;
    }
    a[i+1] = e;
}

```

Time complexity: $O(n^2)$

Space complexity: $O(1)$

Quick Sort

- When implemented well, it can be about two or three times faster than its main competitors, merge sort and heapsort
- On average, the algorithm takes $O(n \log n)$ comparisons to sort n items.
- In the worst case, it makes $O(n^2)$ comparisons, though this behavior is rare.
- In-place but not stable

Quick Sort (cont.)

- When $n \leq 1$, the list is sorted.
- When $n > 1$, select a **pivot** element from out of the n elements.
- Partition the n elements into 3 segments **left**, **middle** and **right**.
 - All elements in the **left** segment are \leq **pivot**.
 - The **middle** segment contains only the **pivot** element.
 - All elements in the **right** segment are \geq **pivot**.
- Sort **left** and **right** segments recursively.
- Answer is sorted **left** segment, followed by **middle** segment followed by sorted **right** segment.

Example

6	2	8	5	11	10	4	1	9	7	3
---	---	---	---	----	----	---	---	---	---	---

Use 6 as the pivot.

equal values can go either way

≤ 6 $6 \leq$

2	5	4	1	3	6	7	9	10	11	8
---	---	---	---	---	---	---	---	----	----	---

Sort left and right segments recursively.

Choice of Pivot

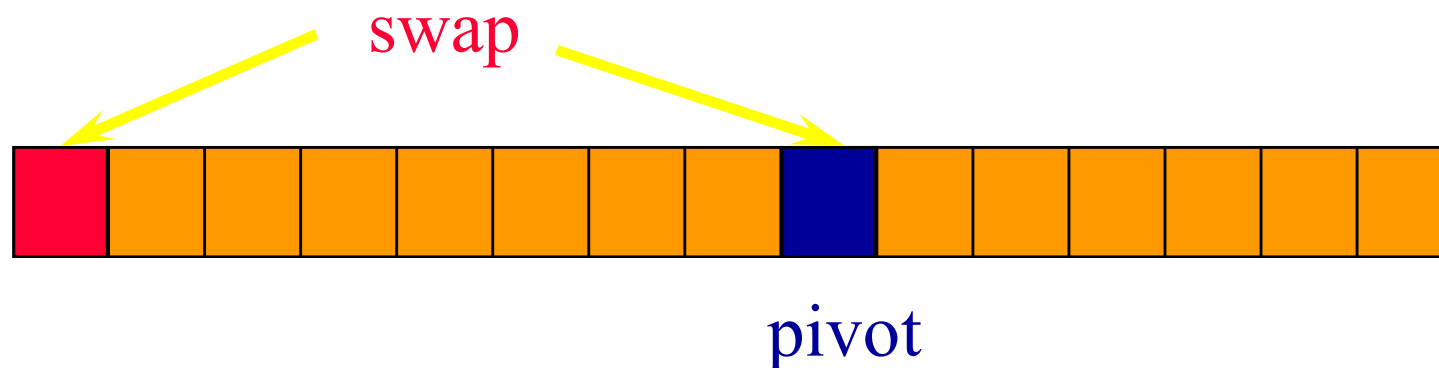
- Pivot is **leftmost** element in list that is to be sorted.
 - When sorting $a[6:20]$, use $a[6]$ as the pivot.
 - Text implementation does this.
- **Randomly** select one of the elements to be sorted as the pivot.
 - When sorting $a[6:20]$, generate a random number r in the range $[6, 20]$. Use $a[r]$ as the pivot.

Choice of Pivot (cont.)

- **Median-of-Three rule.** From the leftmost, middle, and rightmost elements of the list to be sorted, select the one with median key as the pivot.
 - When sorting $a[6:20]$, examine $a[6]$, $a[13]$ $((6+20)/2)$, and $a[20]$. Select the element with median (i.e., middle) key.
 - If $a[6].key = 30$, $a[13].key = 2$, and $a[20].key = 10$, $a[20]$ becomes the pivot.
 - If $a[6].key = 3$, $a[13].key = 2$, and $a[20].key = 10$, $a[6]$ becomes the pivot.

Choice of Pivot (cont.)

- If $a[6].key = 30$, $a[13].key = 25$, and $a[20].key = 10$, $a[13]$ becomes the pivot.
- When the pivot is picked at random or when the median-of-three rule is used, we can use the quick sort code of the text provided we first swap the leftmost element and the chosen pivot.



Partitioning into Three Segments

- Sort $a = [6, 2, 8, 5, 11, 10, 4, 1, 9, 7, 3]$.
- Leftmost element (6) is the pivot.
- When another array b is available:
 - Scan a from left to right (omit the pivot in this scan), placing elements \leq pivot at the left end of b and the remaining elements at the right end of b .
 - The pivot is placed at the remaining position of the b .

Partitioning Example Using Additional Array

a

6	2	8	5	11	10	4	1	9	7	3
---	---	---	---	----	----	---	---	---	---	---

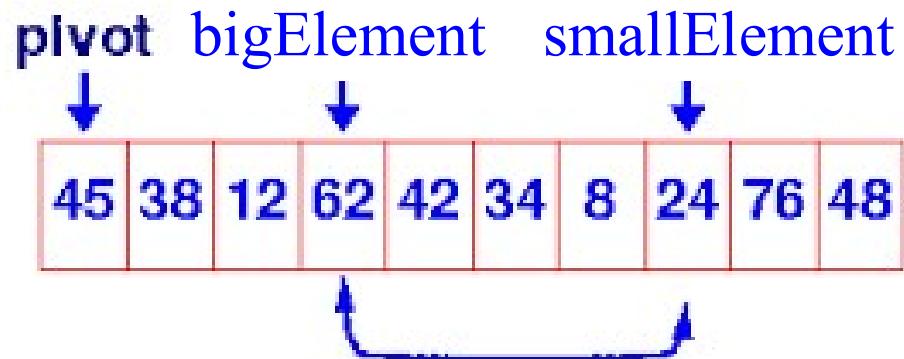
b

2	5	4	1	3	6	7	9	10	11	8
---	---	---	---	---	---	---	---	----	----	---

Sort left and right segments recursively.

In-Place Partitioning

- Find leftmost element (**bigElement**) $>$ pivot.
- Find rightmost element (**smallElement**) $<$ pivot.
- Swap **bigElement** and **smallElement**.
- Repeat.



In-Place Partitioning Example

a

6	2	8	5	11	10	4	1	9	7	3
---	---	---	---	----	----	---	---	---	---	---

a

6	2	3	5	11	10	4	1	9	7	8
---	---	---	---	----	----	---	---	---	---	---

a

6	2	3	5	1	10	4	11	9	7	8
---	---	---	---	---	----	---	----	---	---	---

a

6	2	3	5	1	4	10	11	9	7	8
---	---	---	---	---	---	----	----	---	---	---

 ↑ ↑

bigElement is not to left of smallElement,
terminate process. Swap pivot and smallElement.

a

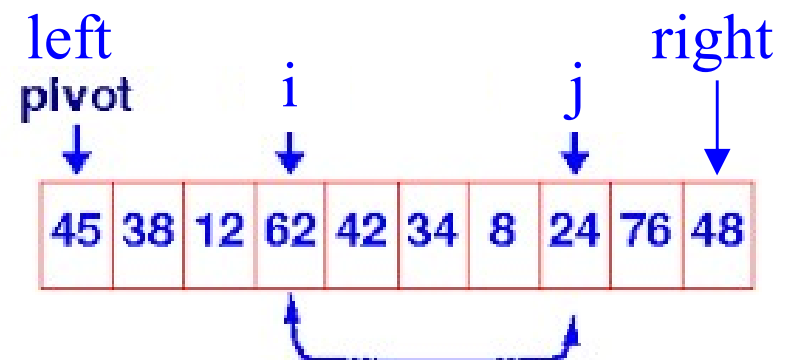
4	2	3	5	1	6	10	11	9	7	8
---	---	---	---	---	---	----	----	---	---	---

```

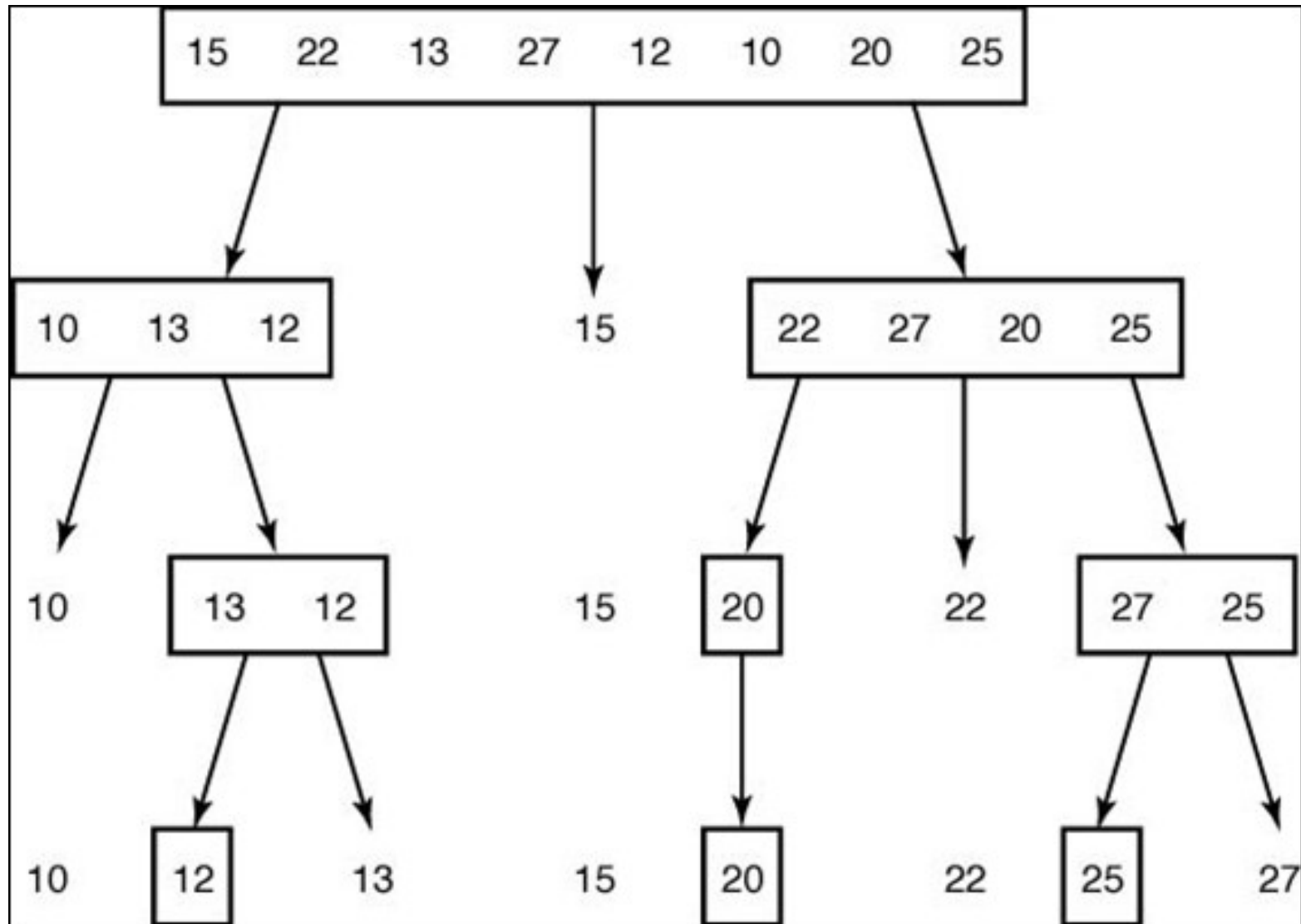
template <class T>
void QuickSort(T *a, const int left, const int right)
{
    // Sort a[left:right] into nondecreasing order.
    // a[left] is arbitrarily chosen as the pivot.
    // Variables i and j are used to partition the subarray
    // so that at any time a[m] <= pivot, m < i,
    // and a[m] >= pivot, m > j.
    // It is assumed that a[left] <= a[right + 1].
    if (left < right) {
        int i = left,
            j = right + 1,
            pivot = a[left];
        do {
            do i++; while (a[i] < pivot);
            do j--; while (a[j] > pivot);
            if (i < j) swap(a[i], a[j]);
        } while (i < j);
        swap(a[left], a[j]);

        QuickSort(a, left, j-1);
        QuickSort(a, j+1, right);
    }
}

```



Quick Sort Example



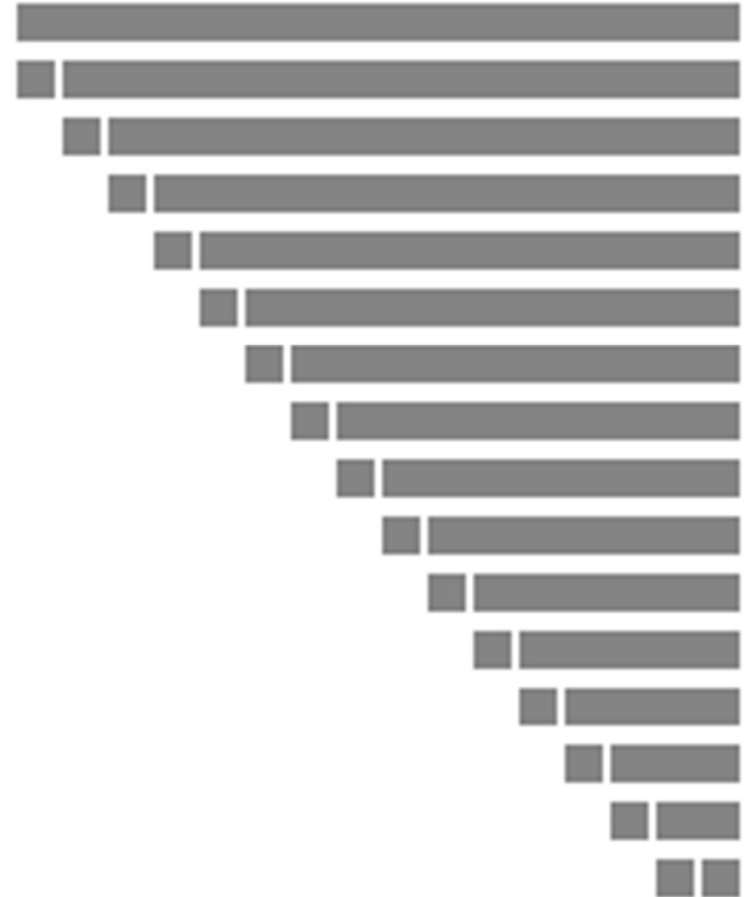
Complexity



a) best case



b) average case



c) worst case

Time Complexity

- $O(n)$ time to partition an array of n elements.
- Let $T(n)$ be the time needed to sort n elements.
- $T(0) = T(1) = b$, where b is a constant.
- When $n > 1$,

$$T(n) = c*n + T(|\text{left}|) + T(|\text{right}|),$$

where c is a constant.

– Hereafter, we will assume $c = 1$ for simplicity

Worst Case

- This happens when the **pivot** is always the smallest element.

- |left segment| = **0**

- |middle segment| = **1**

- |right segment| = **n - 1**

- For the worst-case time,

$$T(n) = n + T(n-1), n > 1$$

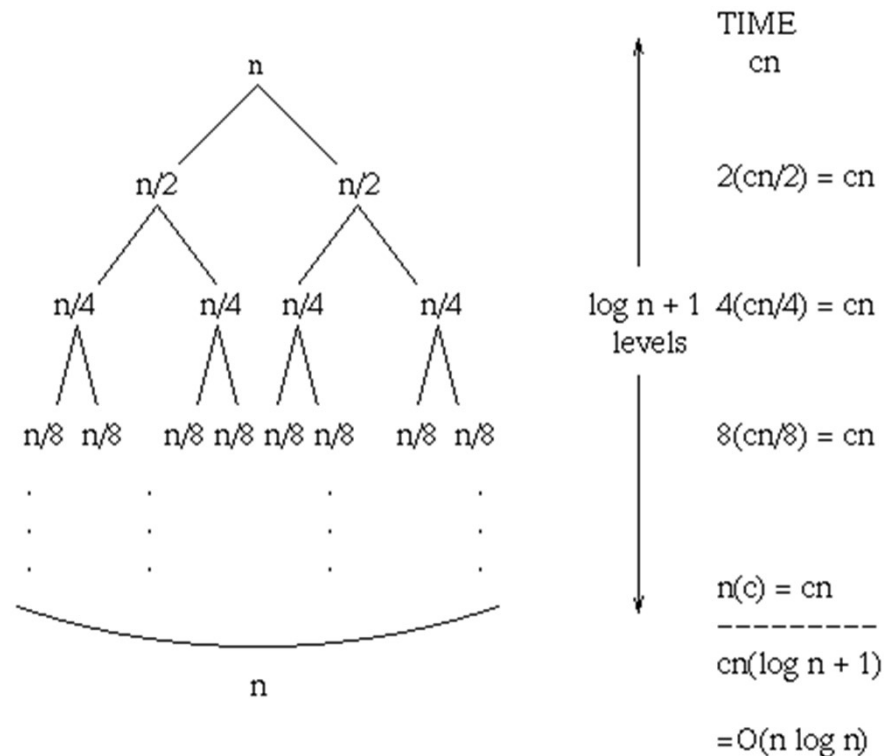
- Use repeated substitution to get

$$T(n) = O(n^2)$$



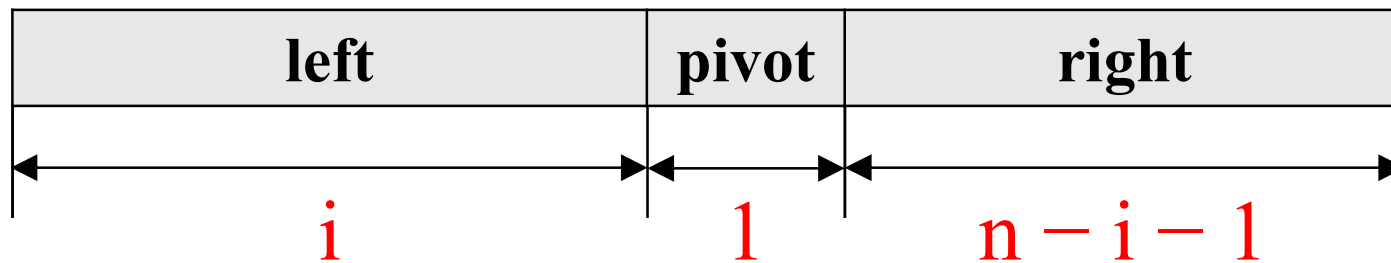
Best Case

- The best case arises when **|left|** and **|right|** are equal (or differ by 1) following each partitioning.
- **$T(n) = n + 2 T(n/2)$, $n > 1$**
- So the best-case complexity is **$O(n \log_2 n)$** .



Average Case

- Average complexity is also $O(n \log_2 n)$.
- When the input is a random permutation, the resulting segments of the partition have sizes i and $n - i - 1$, and i is uniform random from 0 to $n - 1$.



$$T(n) = n + T(i) + T(n - i - 1), n > 1$$

Average Case (cont.)

- The average number of comparisons over all permutations of the input sequence can be estimated accurately by solving the recurrence relation:

$$T_{\text{avg}}(n) = n + \frac{1}{n} \sum_{i=0}^{n-1} (T_{\text{avg}}(i) + T_{\text{avg}}(n - i - 1))$$

- Since i may take on any of $0, \dots, n - 1$

$$T_{\text{avg}}(n) = n + \frac{2}{n} \sum_{i=0}^{n-1} T_{\text{avg}}(i)$$

- Solving the recurrence gives

$$T_{\text{avg}}(n) = 2n \ln n \approx 1.39n \log_2 n$$

Space Complexity

- Extra space for the recursion stack
 - Each recursive call will create a stack frame on the call stack, which takes up space
- Worst case: $O(n)$ space
 - Optimized version: $O(\log n)$ space
- Best and average case: $O(\log n)$ space

In Practice

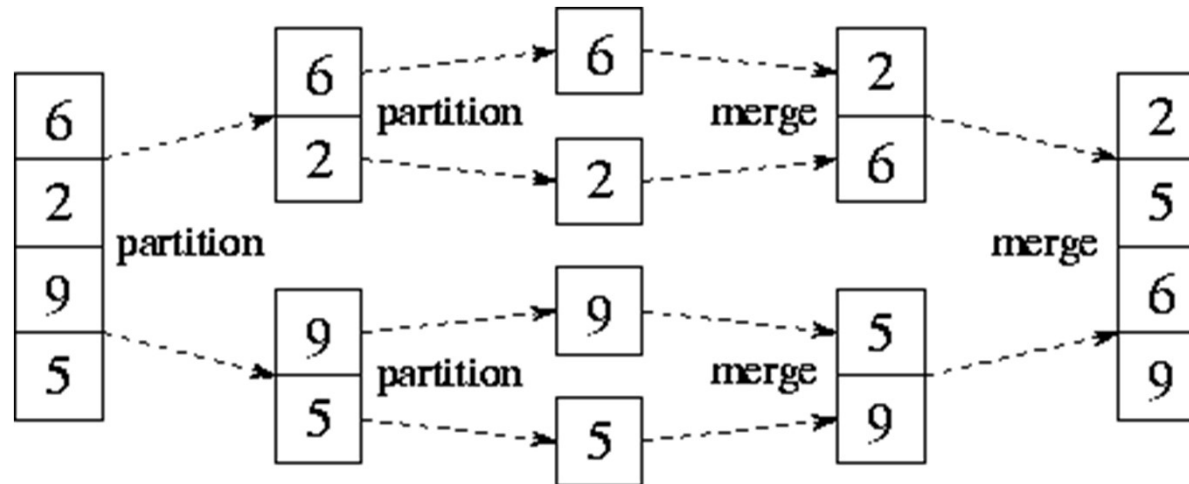
- To improve performance, stop recursion when segment size is ≤ 15 (say) and sort these small segments using insertion sort.

C++ STL sort Function

- Quick sort.
 - Switch to heap sort when the recursion goes too deep
 - Switch to insertion sort when segment size becomes small.

Merge Sort

- Recursively splits the unsorted list into sublists until sublist size is 1, then merges those sublists to produce a sorted list



Merge Sort (cont.)

- Partition the $n > 1$ elements into two smaller instances.
- Each of the two smaller instances is sorted recursively.
- The sorted smaller instances are combined using a process called **merge**.
- Complexity is $O(n \log n)$.
- Usually implemented non-recursively.
- **Stable but not in-place**

Merge Two Sorted Lists

- $A = (2, 5, 6)$
 $B = (1, 3, 8, 9, 10)$
 $C = ()$
- Compare smallest elements of A and B and merge smaller into C .
- $A = (2, 5, 6)$
 $B = (3, 8, 9, 10)$
 $C = (1)$

Merge Two Sorted Lists

- $A = (5, 6)$
 $B = (3, 8, 9, 10)$
 $C = (1, 2)$
- $A = (5, 6)$
 $B = (8, 9, 10)$
 $C = (1, 2, 3)$
- $A = (6)$
 $B = (8, 9, 10)$
 $C = (1, 2, 3, 5)$

Merge Two Sorted Lists

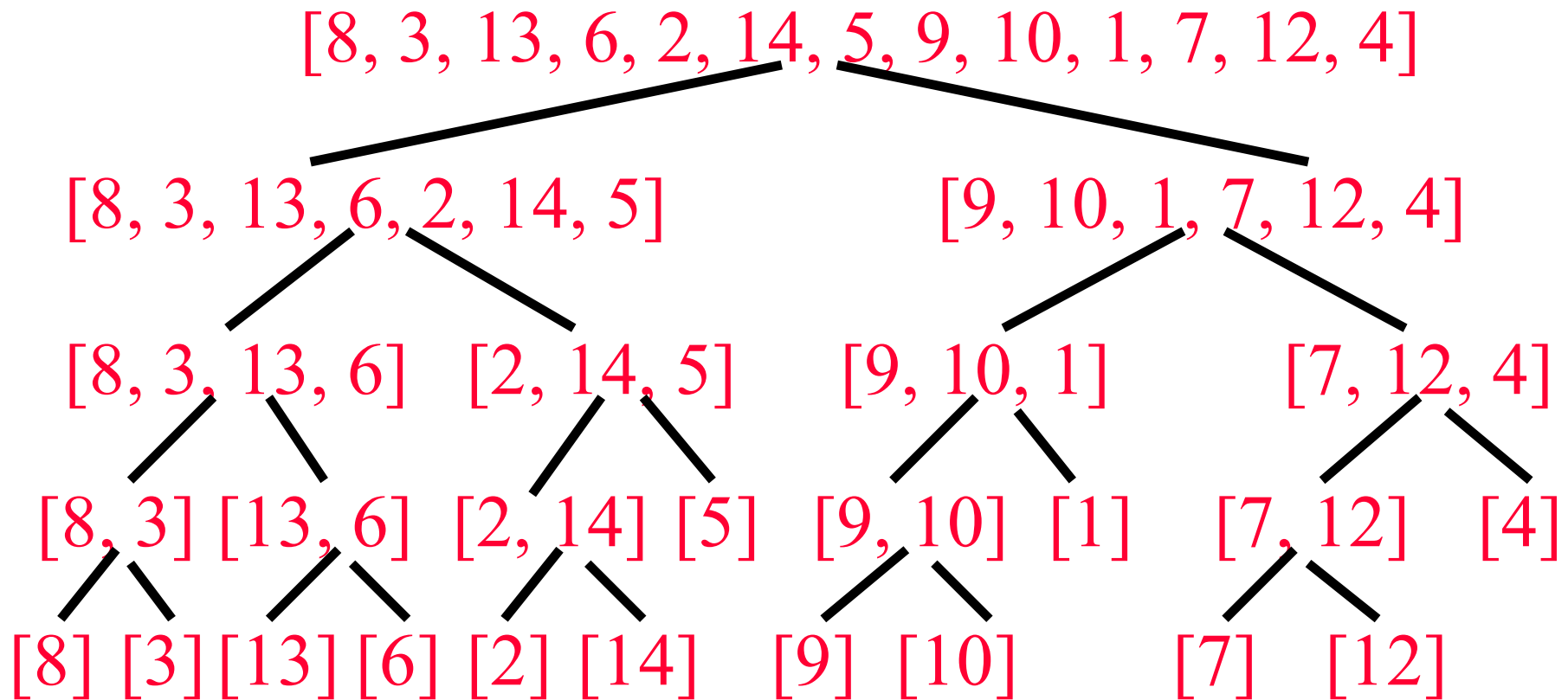
- $A = ()$
 $B = (8, 9, 10)$
 $C = (1, 2, 3, 5, 6)$
- When one of A and B becomes empty, append the other list to C .
- $O(1)$ time needed to move an element into C .
- Total time is $O(n + m)$, where n and m are, respectively, the number of elements initially in A and B .

Recursive Merge Sort

```
procedure mergesort( $L = a_1, a_2, \dots, a_n$ )  
if  $n > 1$  then  
     $m := \lfloor n/2 \rfloor$   
     $L_1 := a_1, a_2, \dots, a_m$   
     $L_2 := a_{m+1}, a_{m+2}, \dots, a_n$   
     $L := \text{merge}(\text{mergesort}(L_1), \text{mergesort}(L_2))$   
{ $L$  is now sorted into elements in increasing order}
```

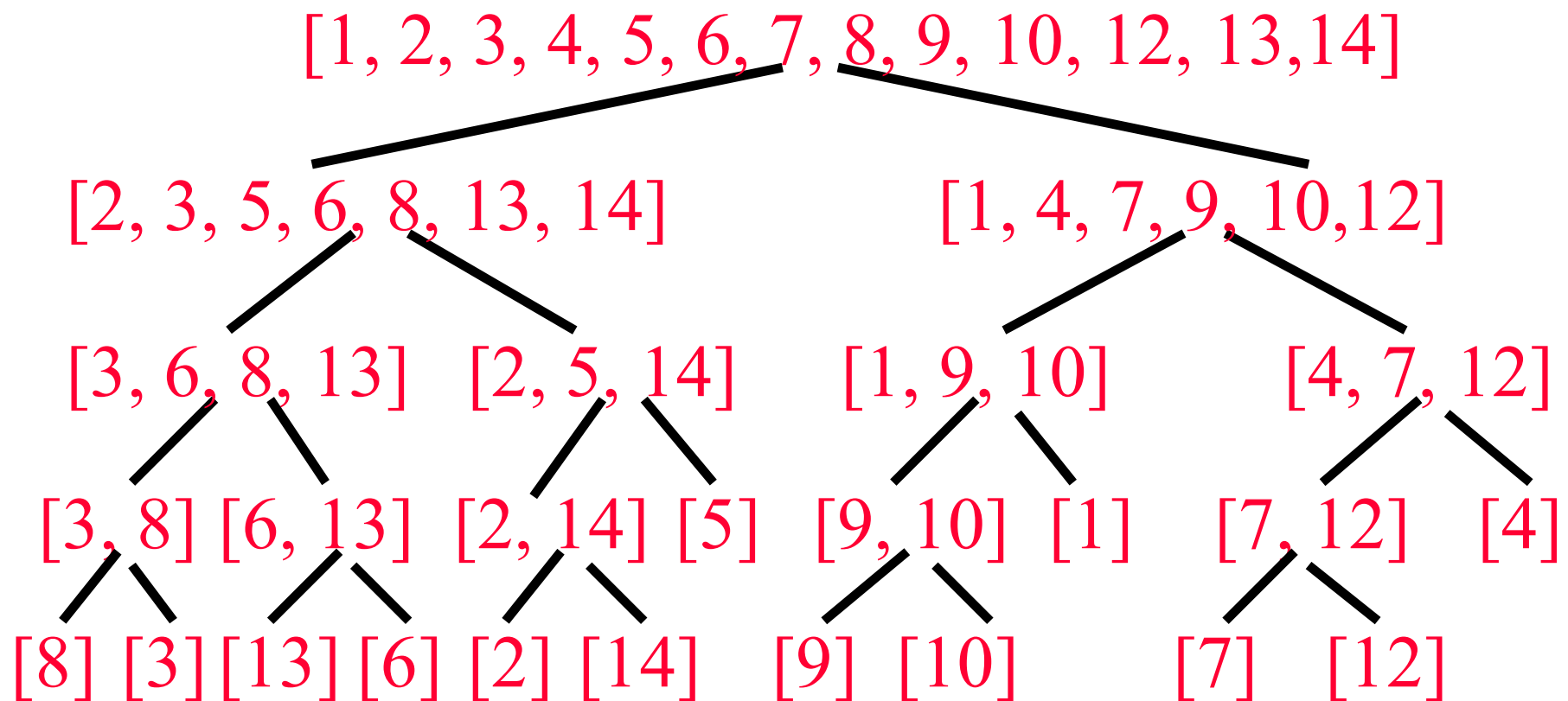
Downward Pass

- Downward pass over the recursion tree.
 - Divide large instances into small ones.



Upward Pass

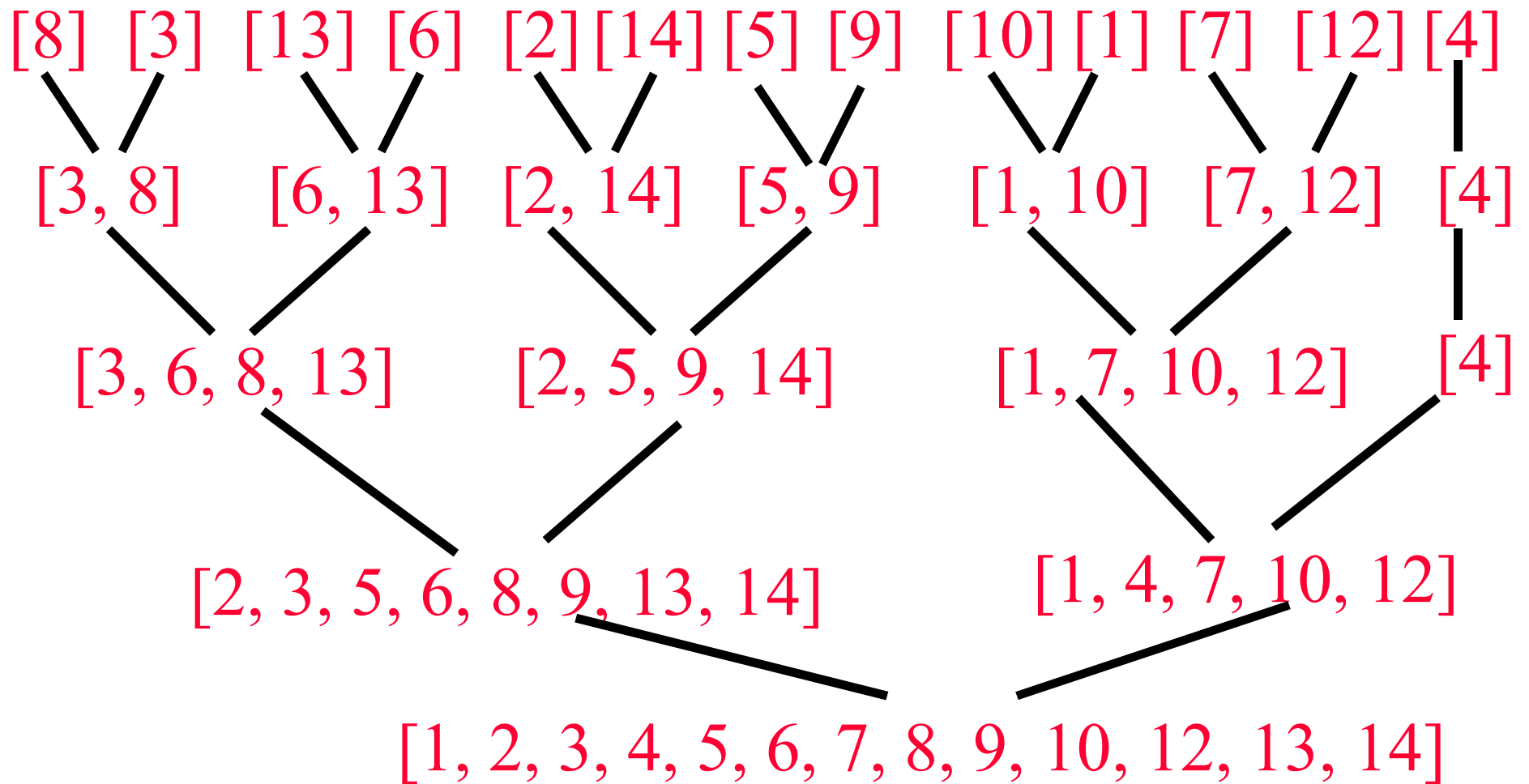
- Upward pass over the recursion tree.
 - Merge pairs of sorted lists.



Nonrecursive Version

- Eliminate downward pass.
- Start with sorted lists of size 1 and do pairwise merging of these sorted lists as in the upward pass.

Nonrecursive Merge Sort



Time Complexity

- Let $T(n)$ be the time required to sort n elements.
- $T(0) = T(1) = b$, where b is a constant.
- When $n > 1$,
$$T(n) = 2 * T(n/2) + c * n,$$
where c is a constant.
- To solve the recurrence, assume n is a power of 2 and use repeated substitution.
- $T(n) = O(n \log_2 n)$.

C++ STL `stable_sort` Function

- Merge sort is **stable** (relative order of elements with equal keys is not changed).
- Quick sort is not stable.
- STL's `stable_sort` is a merge sort that switches to insertion sort when segment size is small.


```

template <class T>
void Merge(T *initList, T *mergedList, const int l, const int m, const int n)
{
    // initList[l:m] and initList[m+1:n] are sorted lists.
    // They are merged to obtain the sorted list mergedList[l:n].
    // i1, i2, and iResult are list positions.
    for (int i1 = l, iResult = l, i2 = m+1;
        i1 <= m && i2 <= n; // neither input list is exhausted.
        iResult++)
        if (initList[i1] <= initList[i2])
        {
            mergedList[iResult] = initList[i1];
            i1++;
        }
        else
        {
            mergedList[iResult] = initList[i2];
            i2++;
        }
    // copy remaining records, if any, of the first list.
    copy(initList+i1, initList+m+1, mergedList+iResult);

    // copy remaining records, if any, of the second list.
    copy(initList+i2, initList+n+1, mergedList+iResult);
}

```

Program 7.8:Merge pass

```
=====
template <class T>
void MergePass(T *initList, T *resultList, const int n, const int s)
{
    // Adjacent pairs of sublists of size s are merged from
    // initList to resultList. n is the number of records in initList.
    for (int i = 1; // i is first position in first of the sublists being merged
         i <= n - 2*s + 1; // enough elements for two sublists of length s?
         i += 2*s)
        Merge(initList, resultList, i, i + s - 1, i + 2 * s - 1);

    // merge remaining list of size < 2 * s
    if ((i + s - 1) < n) Merge(initList, resultList, i, i + s - 1, n);
    else copy(initList + i, initList + n + 1, resultList + i);
}
=====
```

```
template <class T>
void MergeSort(T *a, const int n)
{
    // Sort a[1:n] into nondecreasing order.
    T *tempList = new T[n+1];
    // l is the length of the sublist currently being merged
    for (int l = 1; l < n; l *= 2)
    {
        MergePass(a, tempList, n, l);
        l *= 2;
        MergePass(tempList, a, n, l); // interchange role of a and tempList
    }
    delete [ ] tempList;
}
=====
```

```

template <class T>
int rMergeSort(T* a, int* link, const int left, const int right)
{
    // a[left:right] is to be sorted. link[i] is initially 0 for all i.
    // rMergeSort returns the index of the first element in the sorted chain.
    if (left >= right) return left;
    int mid = (left + right) / 2;
    return ListMerge(a, link,
                    rMergeSort(a, link, left, mid), // sort left half
                    rMergeSort(a, link, mid + 1, right)); // sort right half
}

template <class T>
int ListMerge(T* a, int* link, const int start1, const int start2)
{
    // The sorted chains beginning at start1 and start2, respectively, are merged.
    // link[0] is used as a temporary header. Return start of merged chain.
    int iResult = 0; // last record of result chain
    for (int i1 = start1, i2 = start2; i1 && i2; )
    {
        if (a[i1] <= a[i2]) {
            link[iResult] = i1;
            iResult = i1; i1 = link[i1];
        }
        else {
            link[iResult] = i2;
            iResult = i2; i2 = link[i2];
        }
    }

    // attach remaining records to result chain
    if (i1 == 0) link[iResult] = i2;
    else link[iResult] = i1;
    return link[0];
}

```