

Heaps

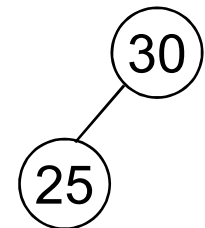
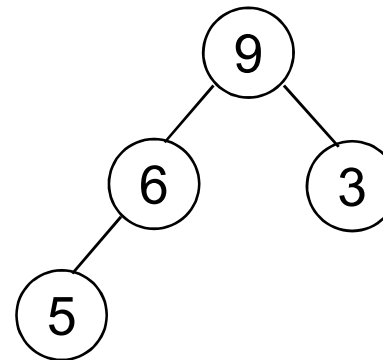
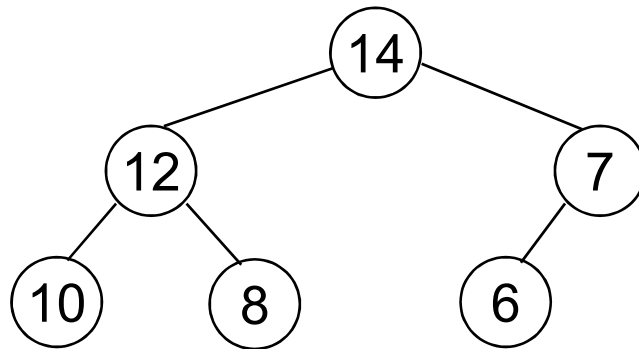
Prof. Ki-Hoon Lee
Dept. of Computer Engineering
Kwangwoon University

Heap

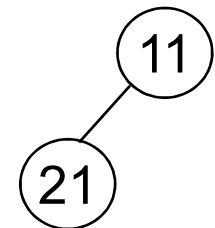
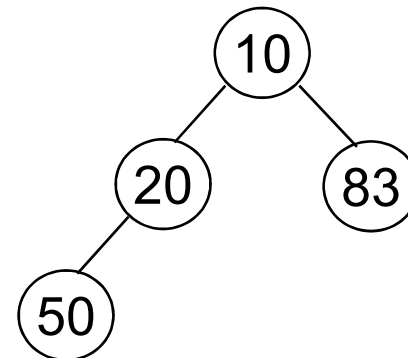
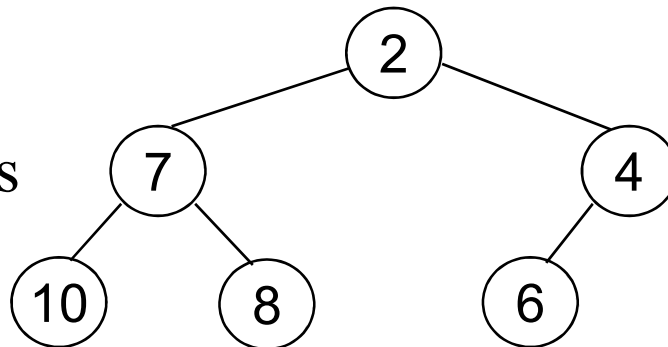
- A *max* (*min*) *tree* is a tree in which the key value in each node is no *smaller* (*larger*) than the key values in its children (if any)
- The key in the root of a *max* (*min*) *tree* is the *largest* (*smallest*) key in the tree
- A *max* (*min*) *heap* is a *complete binary tree* that is also a *max* (*min*) *tree*

Heap (cont.)

max heaps



min heaps



Heap (cont.)

- Basic Operations
 - Creation of an empty heap
 - Insertion
 - Deletion of the root

Heap Height

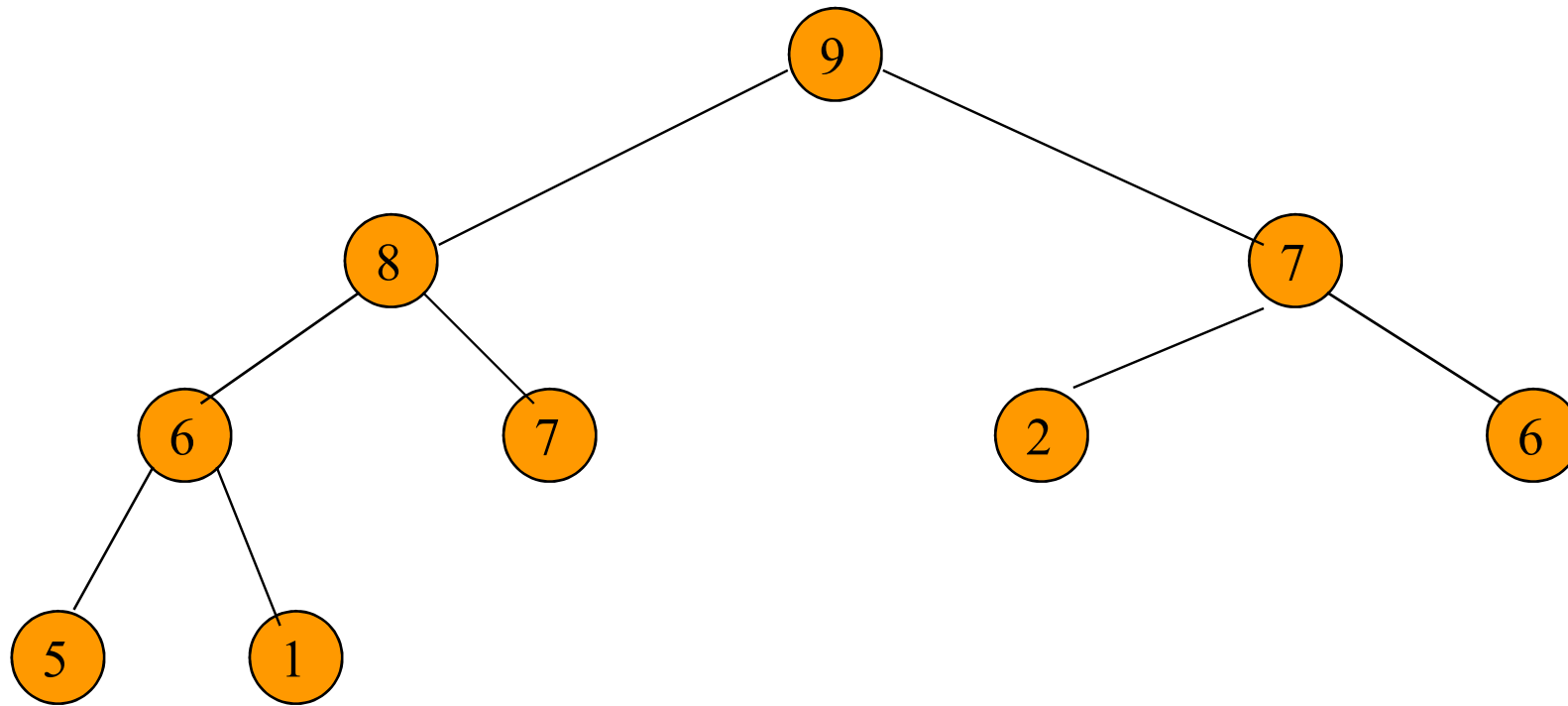
- Since a heap is a complete binary tree, the height of an n node heap is $\lceil \log_2(n+1) \rceil$

Maximum number of nodes

$$= 1 + 2 + 4 + 8 + \dots + 2^{h-1}$$

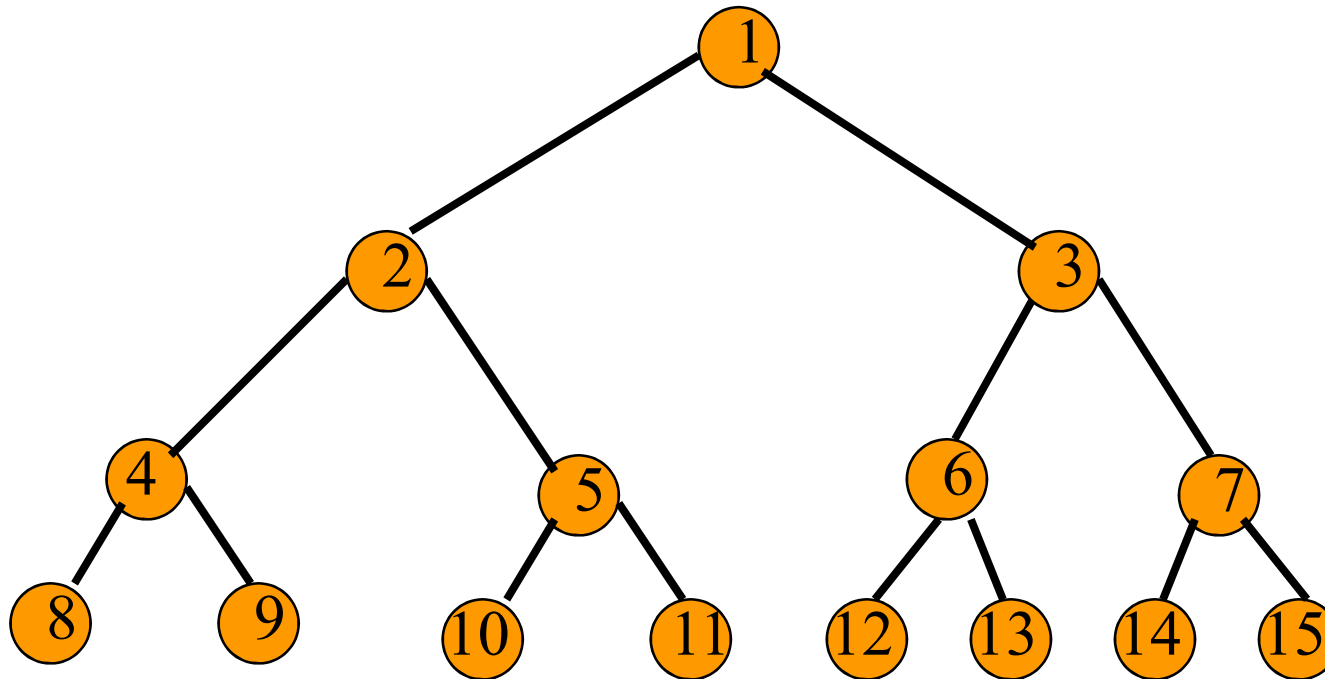
$$= 2^h - 1$$

A Heap Represented as an Array



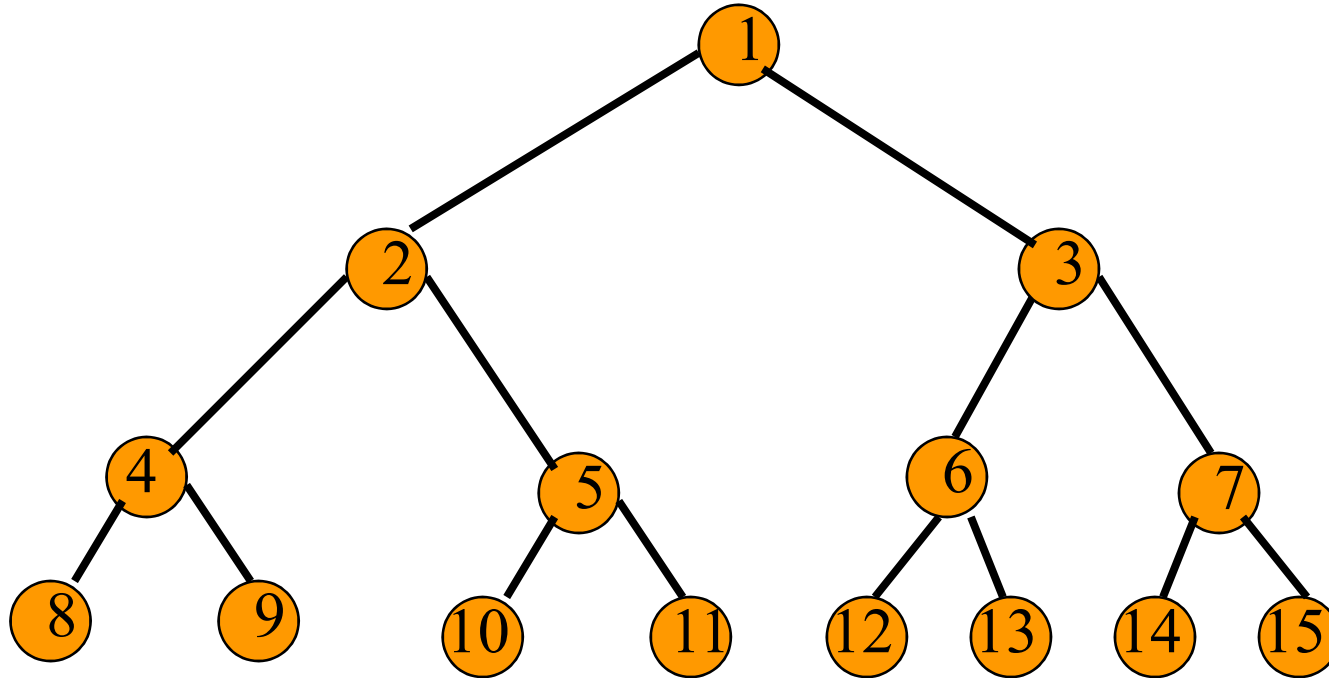
	9	8	7	6	7	2	6	5	1
0	1	2	3	4	5	6	7	8	9

Node Number Properties



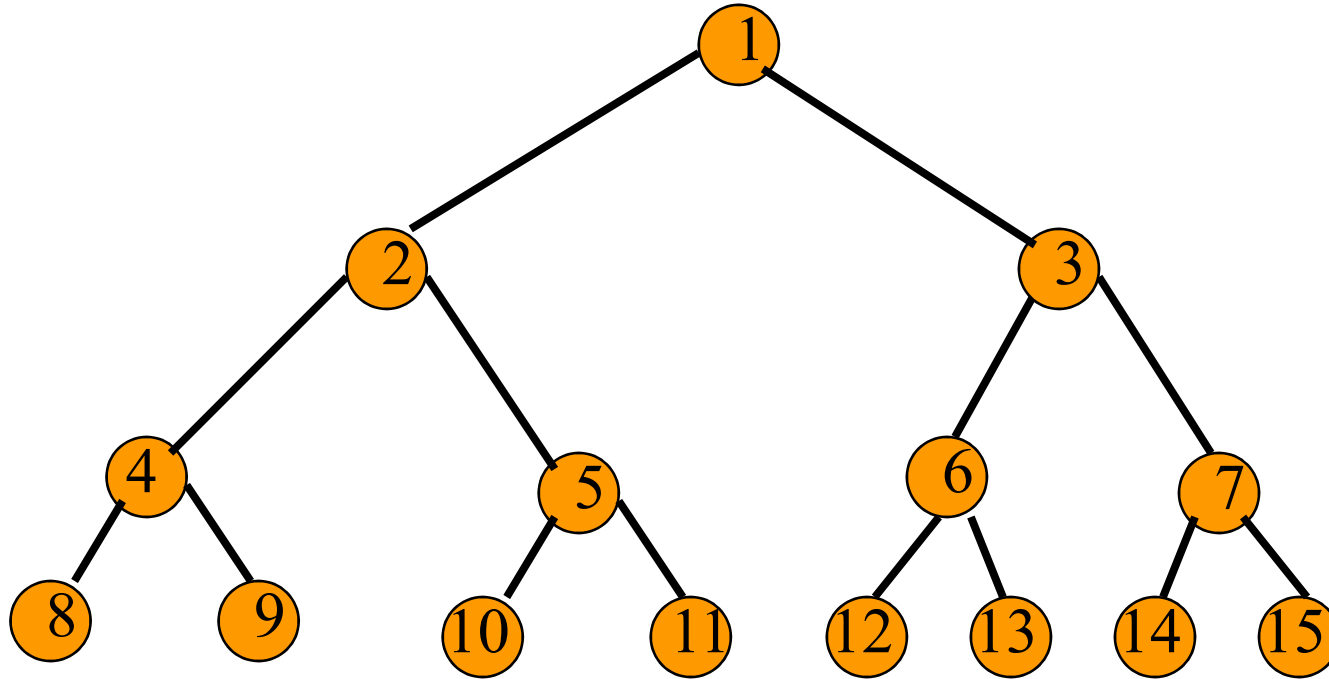
- Parent of node i is node $i / 2$, unless $i = 1$.
- Node 1 is the root and has no parent.

Node Number Properties (Cont.)



- Left child of node i is node $2i$, unless $2i > n$, where n is the number of nodes.
- If $2i > n$, node i has no left child.

Node Number Properties (Cont.)



- Right child of node i is node $2i+1$, unless $2i+1 > n$, where n is the number of nodes.
- If $2i+1 > n$, node i has no right child.

Template Class MaxHeap

private:

T *heap; // element array

int heapSize; // number of elements in heap

int capacity; // size of the array heap

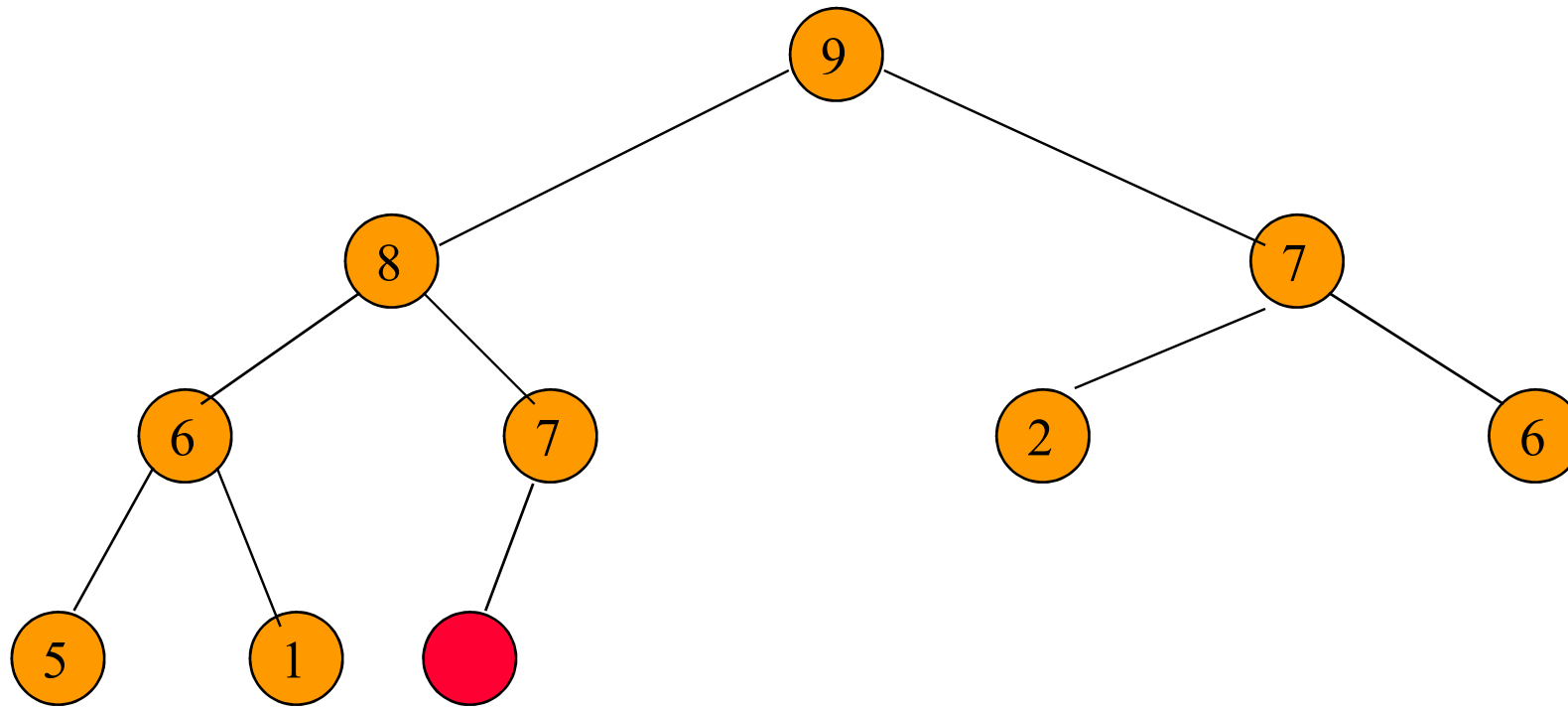
Template Class MaxHeap (cont.)

```
template <class T>
MaxHeap<T>::MaxHeap (int theCapacity = 10)
{
    if (theCapacity < 1) throw "Capacity must be >= 1.";
    capacity = theCapacity;
    heapSize = 0;
    heap = new T[capacity + 1]; // heap[0] is not used
}
```

Insertion

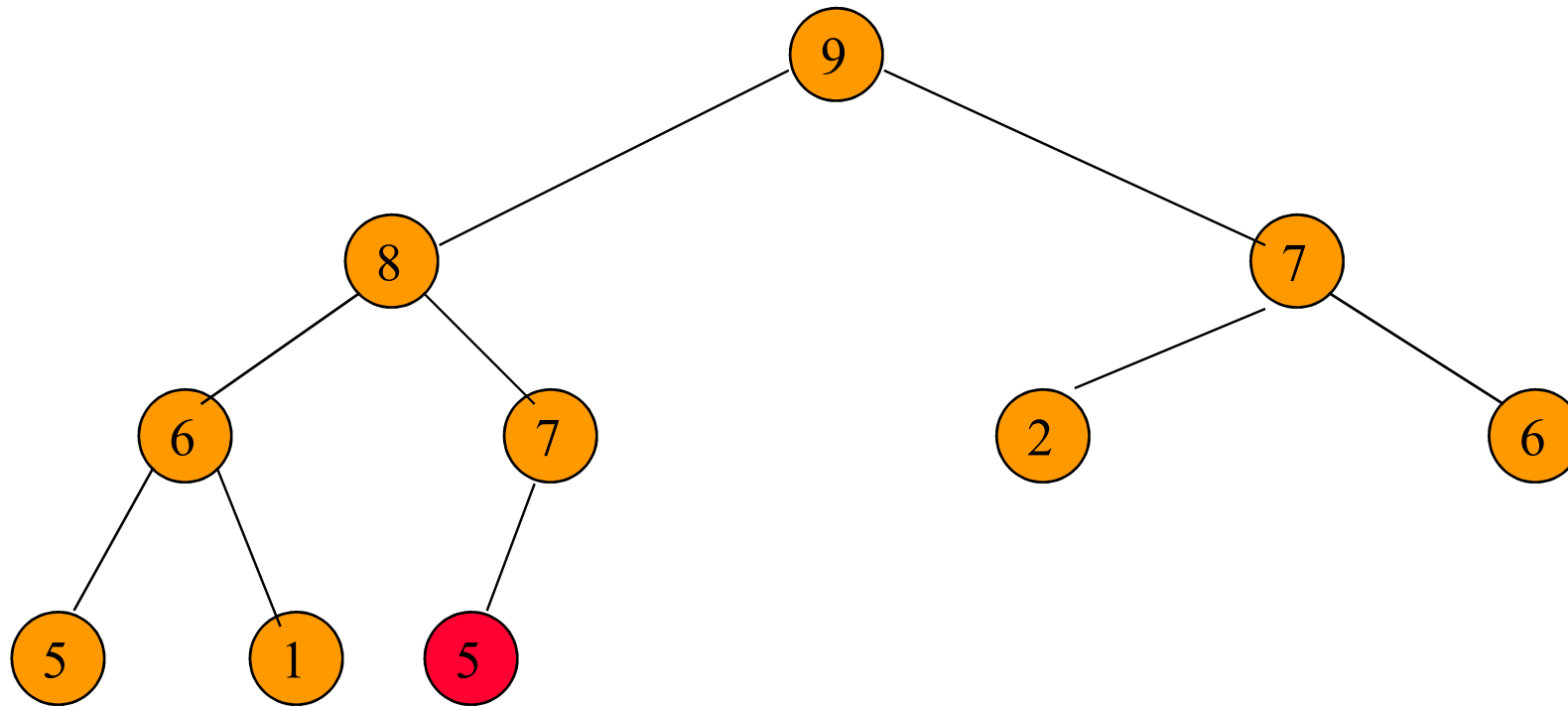
- To determine the correct place for the element being inserted, we use a *bubbling up* process
- The bubbling up process begins at a new leaf node and moves up toward the root
- The element to be inserted bubbles up as far as is necessary to ensure a max (min) heap

Inserting an Element into a Max Heap



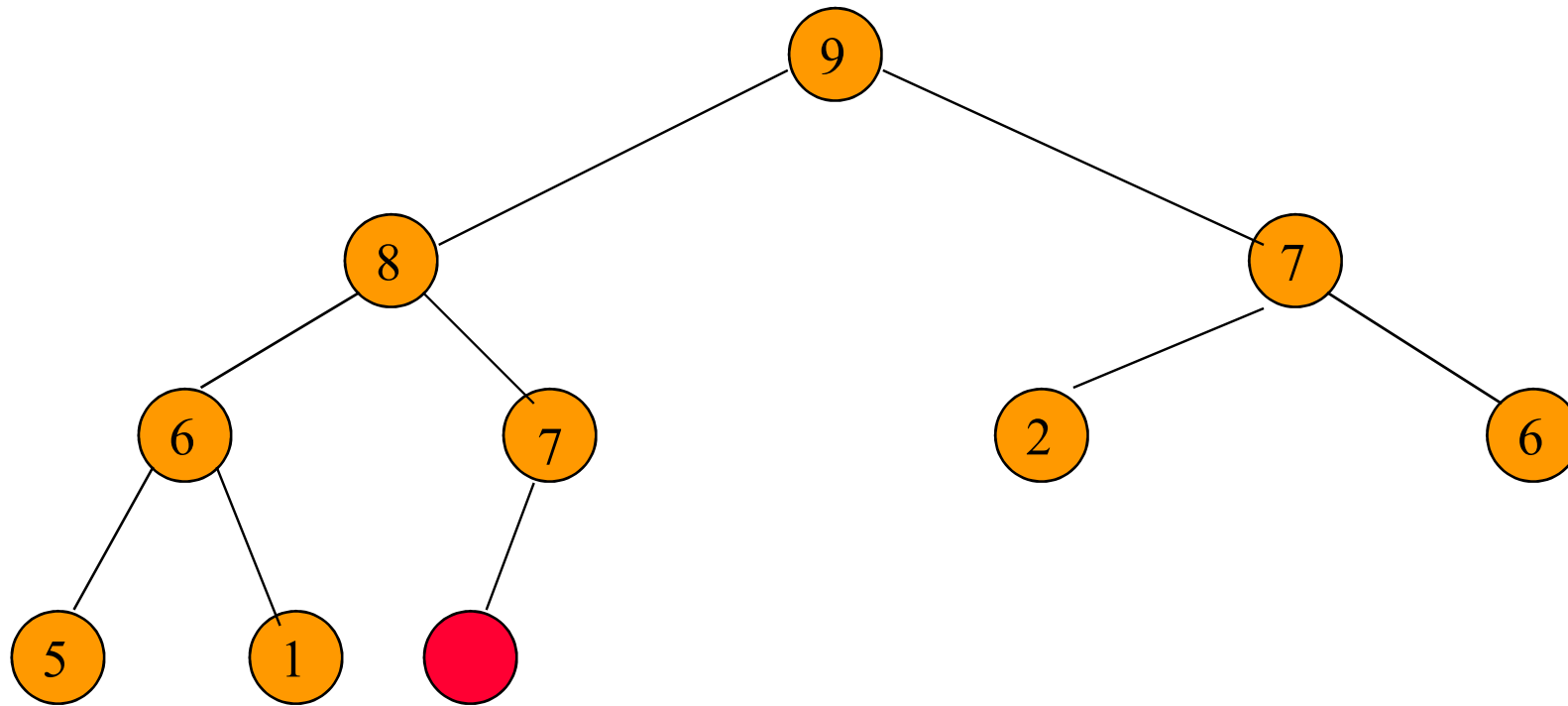
Complete binary tree with 10 nodes.

Inserting an Element into a Max Heap



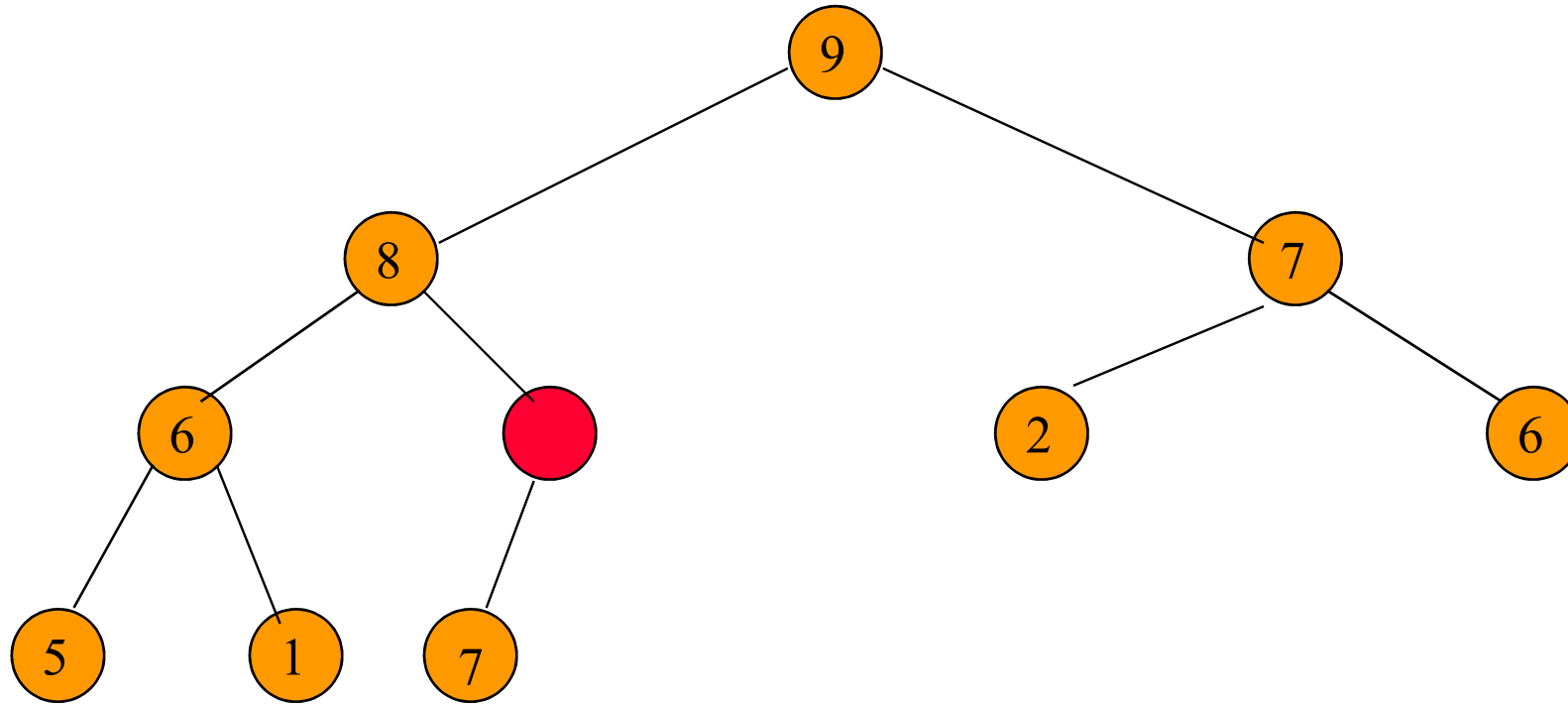
New element is 5.

Inserting an Element into a Max Heap



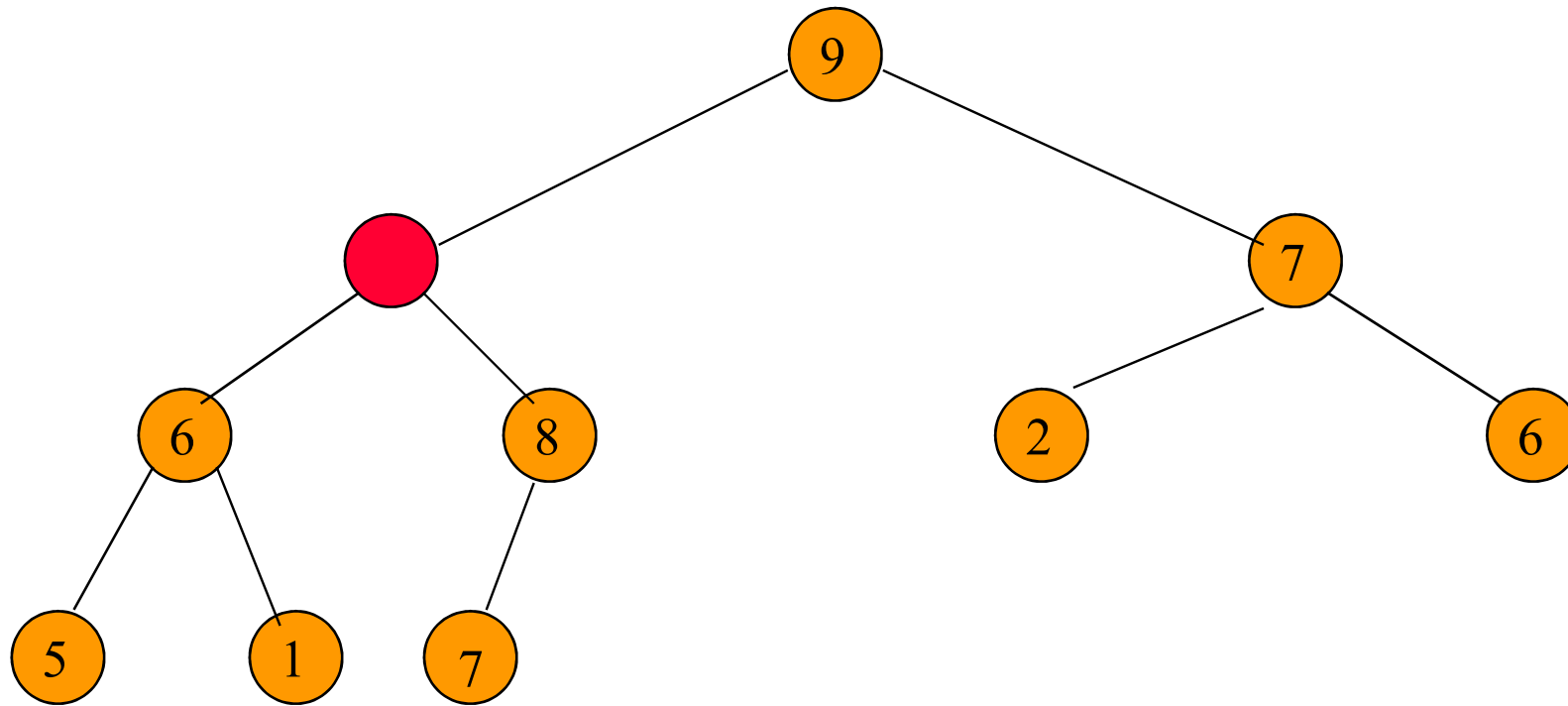
New element is 20.

Inserting an Element into a Max Heap



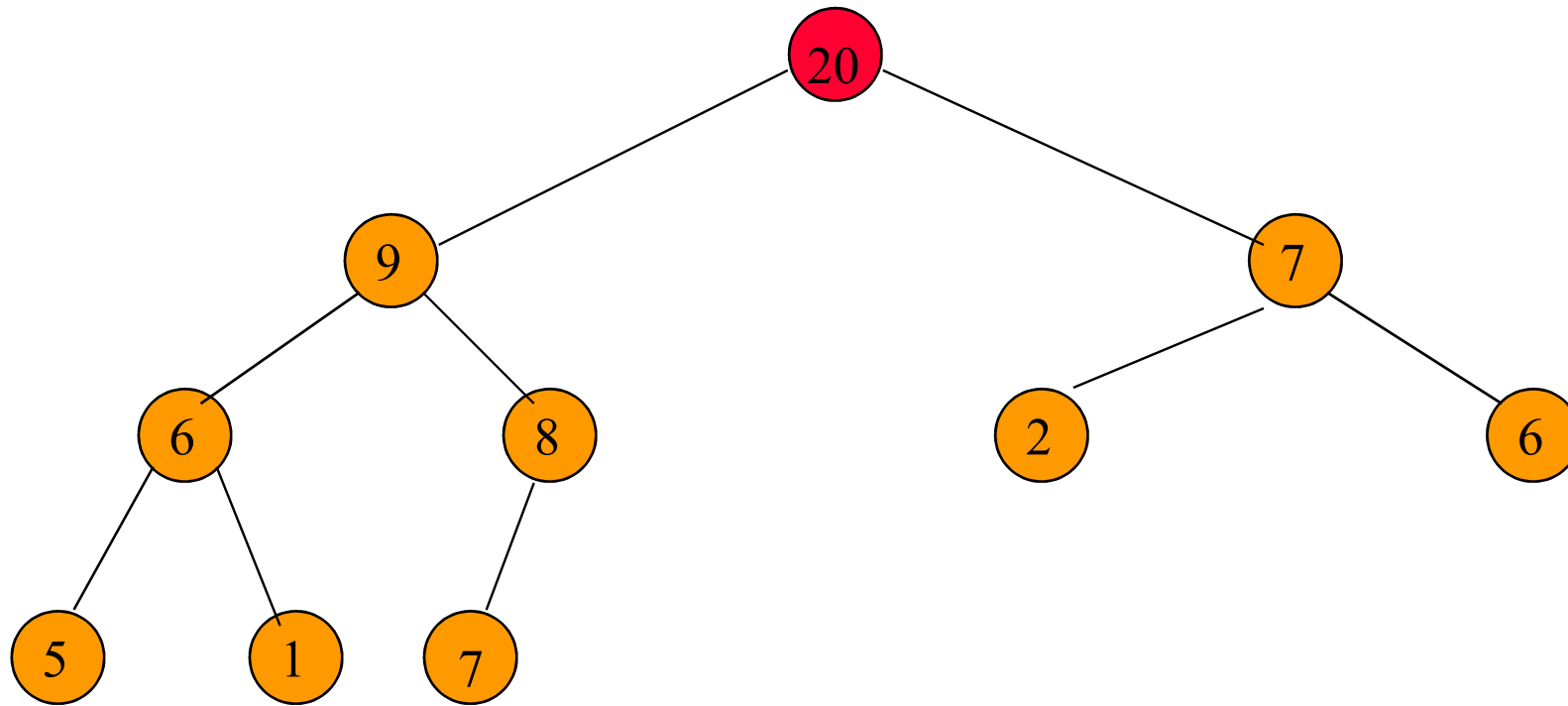
New element is 20.

Inserting an Element into a Max Heap



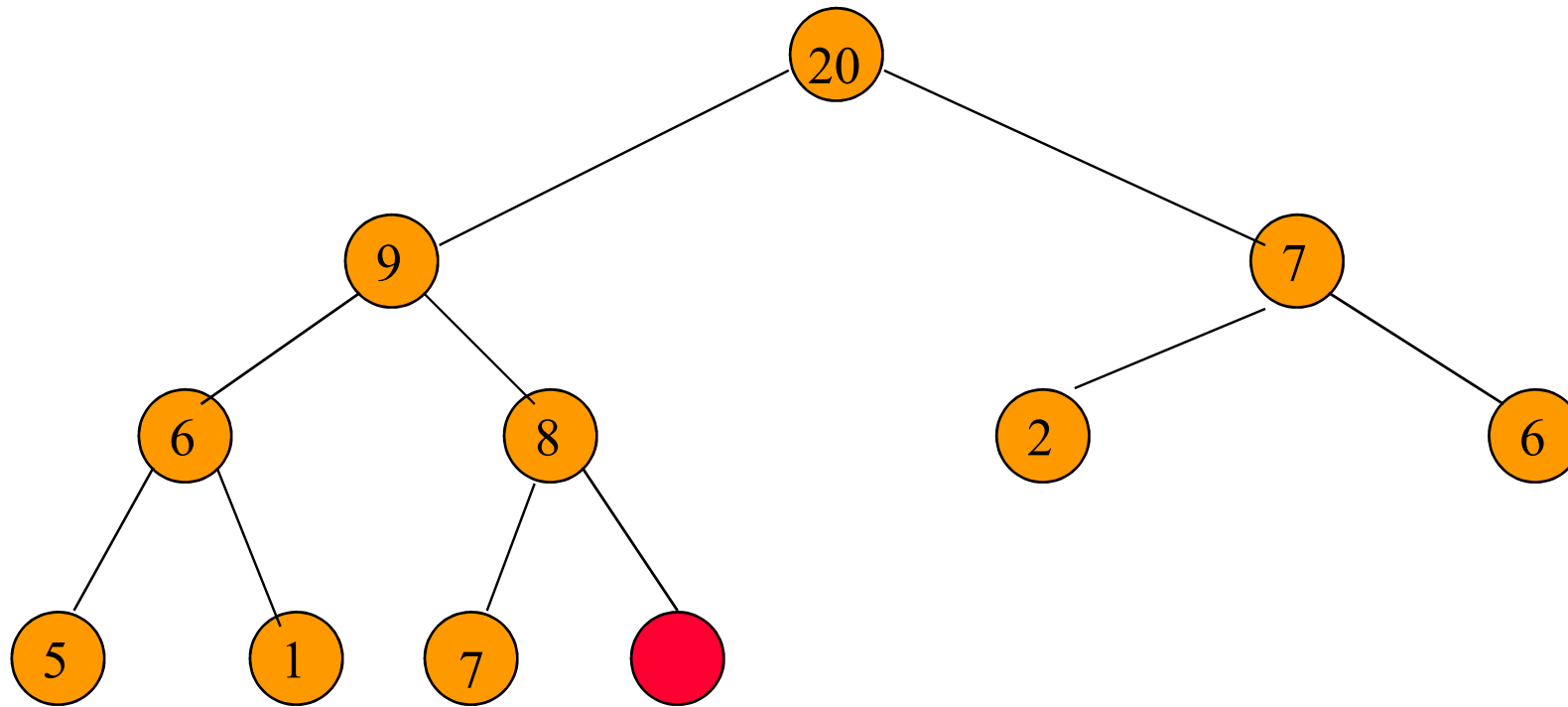
New element is 20.

Inserting an Element into a Max Heap



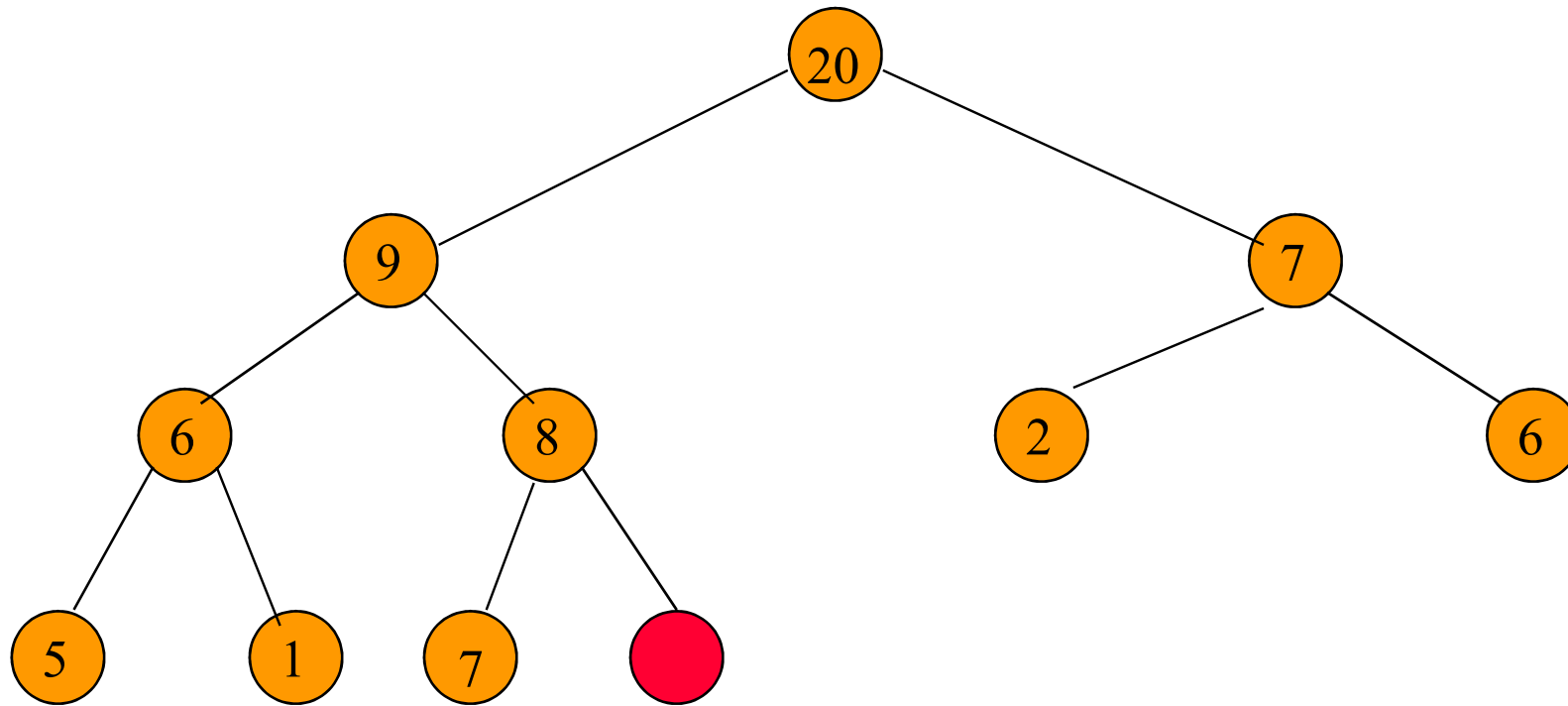
New element is 20.

Inserting an Element into a Max Heap



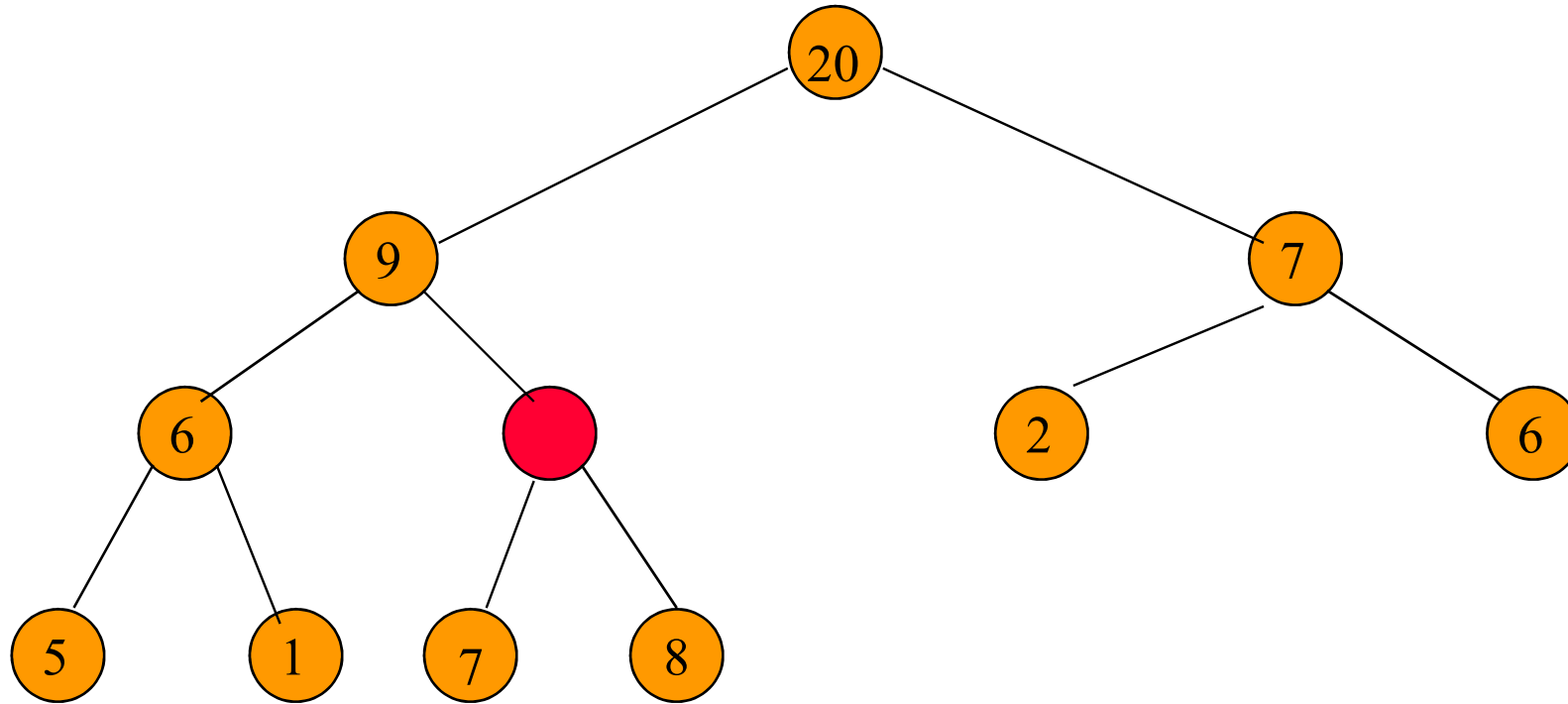
Complete binary tree with **11** nodes.

Inserting an Element into a Max Heap



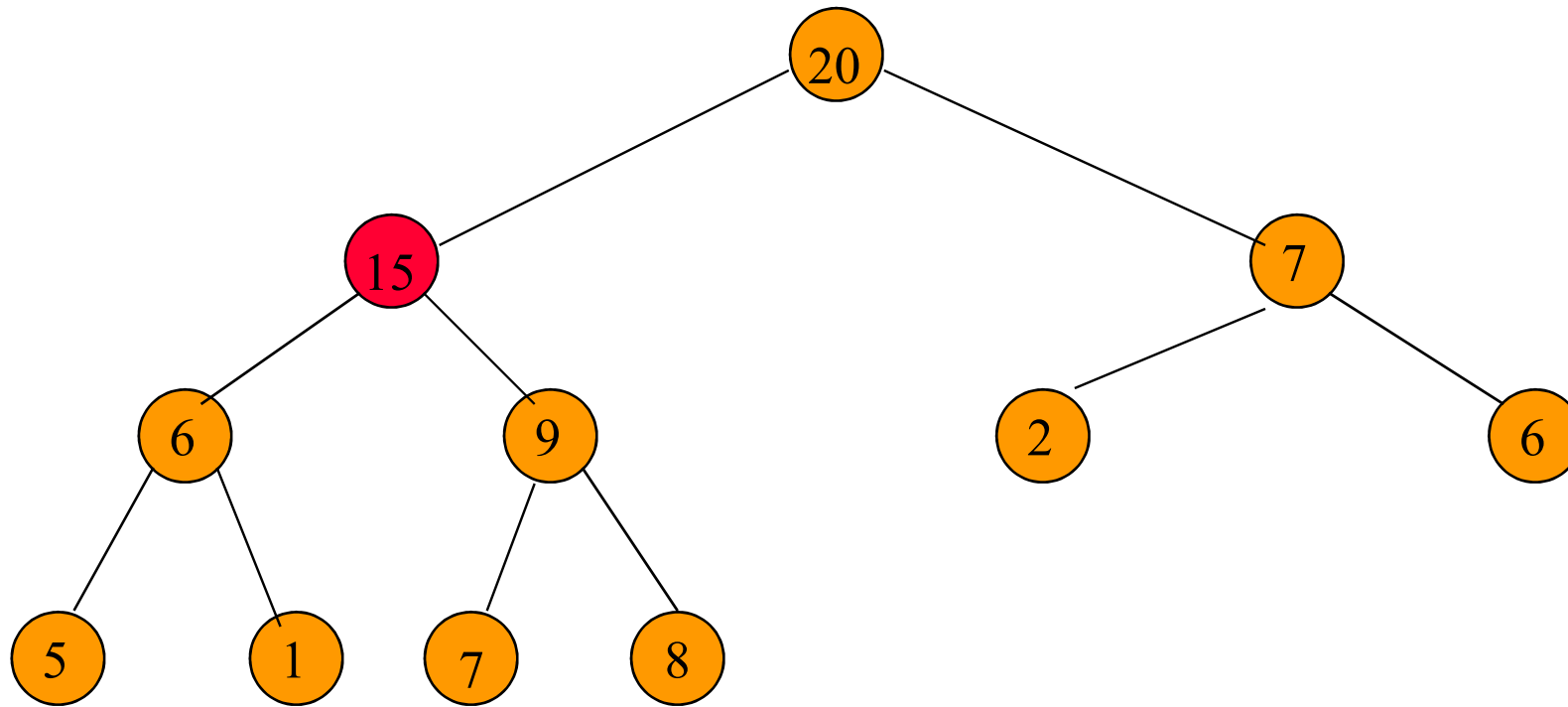
New element is 15.

Inserting an Element into a Max Heap



New element is 15.

Inserting an Element into a Max Heap



New element is 15.

Inserting an Element into a Max Heap

```
template <class T>
void MaxHeap<T>::Push(const T& e)
{
    // Insert e into the max heap.
    if (heapSize == capacity) { // double the capacity
        ChangeSize1D(heap, capacity, 2 * capacity);
        capacity *= 2;
    }
    int currentNode = ++heapSize;
    while (currentNode != 1 && heap[currentNode / 2] < e)
    {
        // bubble up
        heap[currentNode] = heap[currentNode/2]; // move parent down
        currentNode /= 2; // move to parent
    }
    heap[currentNode] = e;
}
```

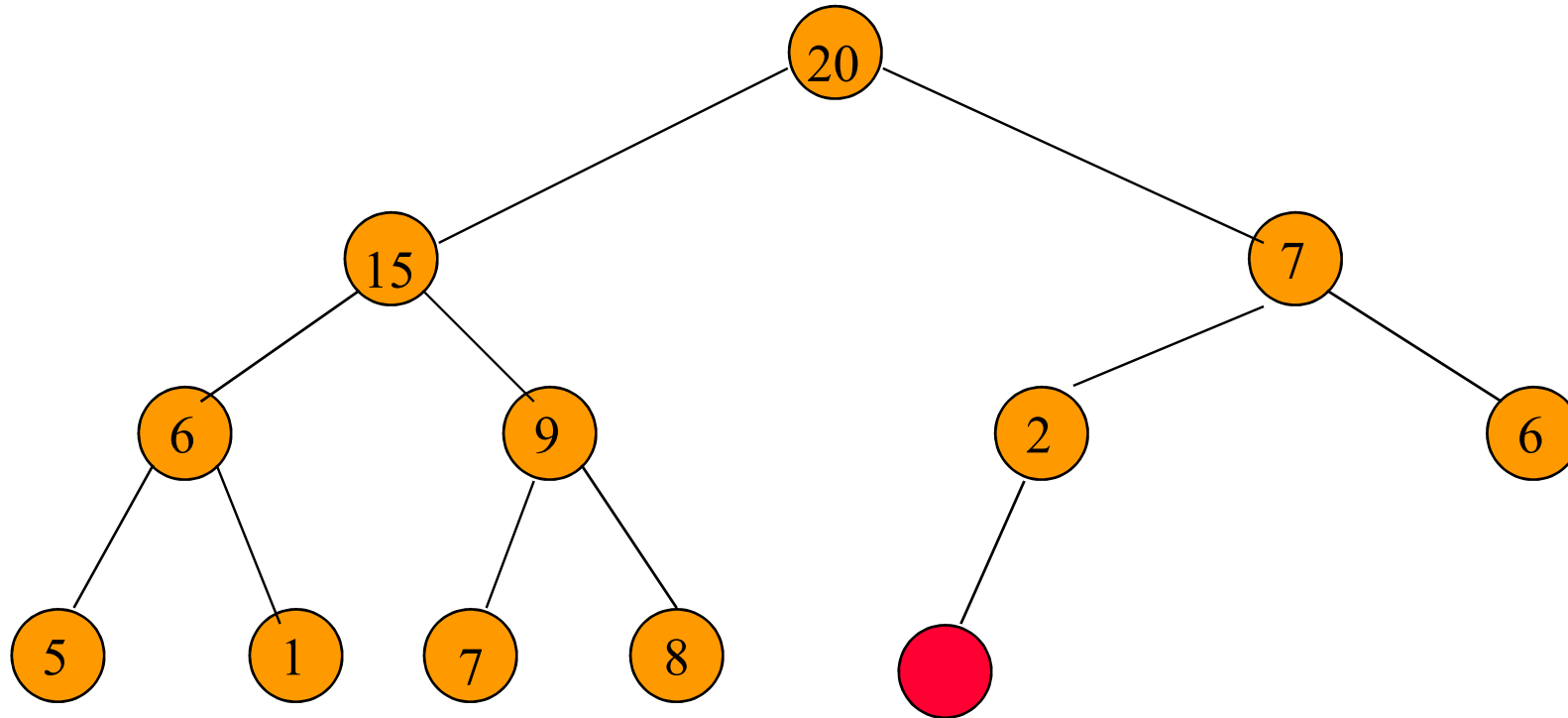
```
#pragma warning(disable:4996)
#include <algorithm>
using namespace std;
```

```
template <class T>
void ChangeSize1D(T*& a, const int oldSize, const int newSize)
{
    if (newSize < 0) throw "New length must be >= 0";

    T* temp = new T[newSize];           // new array
    int number = min(oldSize, newSize); // number to copy
    copy(a, a + number, temp);
    delete [] a;                        // deallocate old memory
    a = temp;
}
```

<http://www.cplusplus.com/reference/algorithm/copy/>

Complexity of Insert

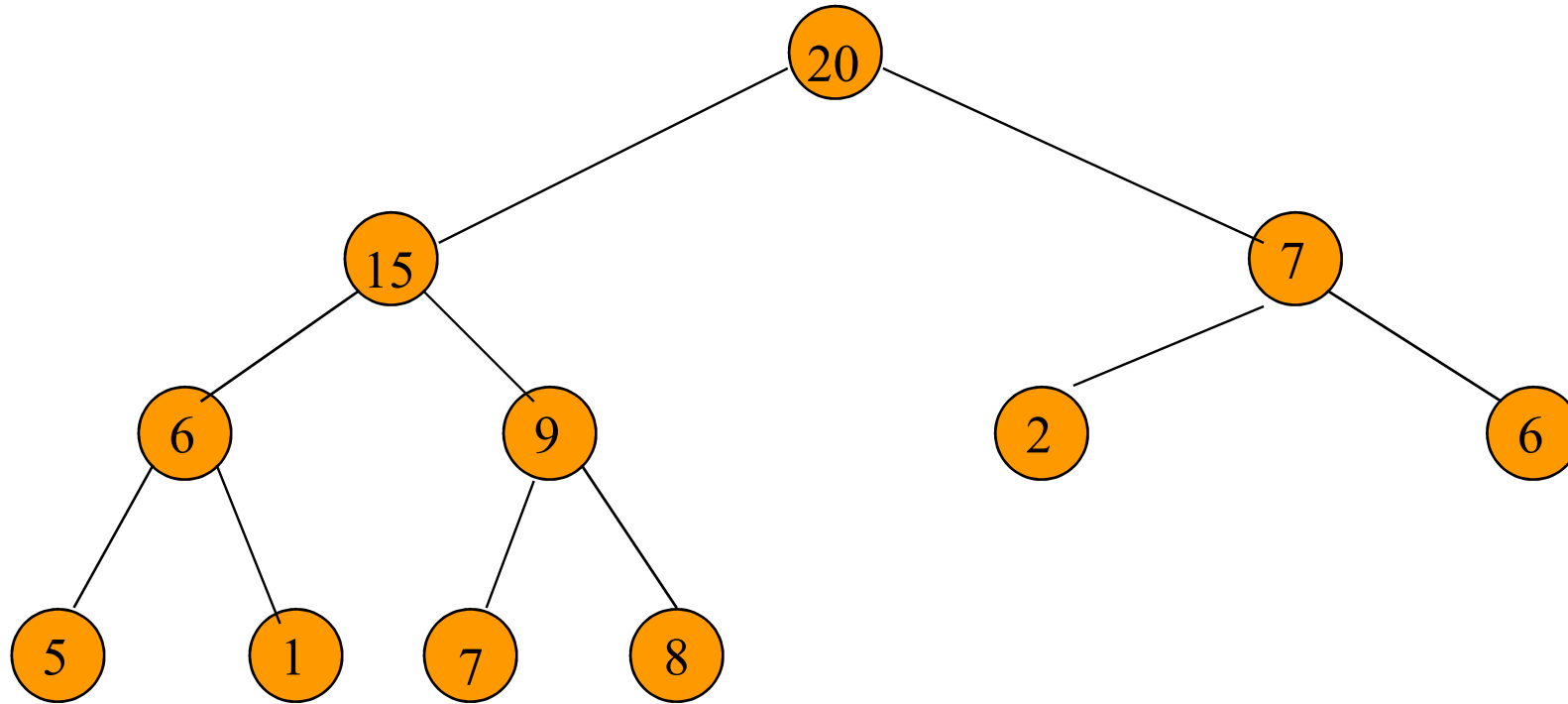


Complexity is $O(\log n)$, where n is heap size.

Deletion of the Root from a Max Heap

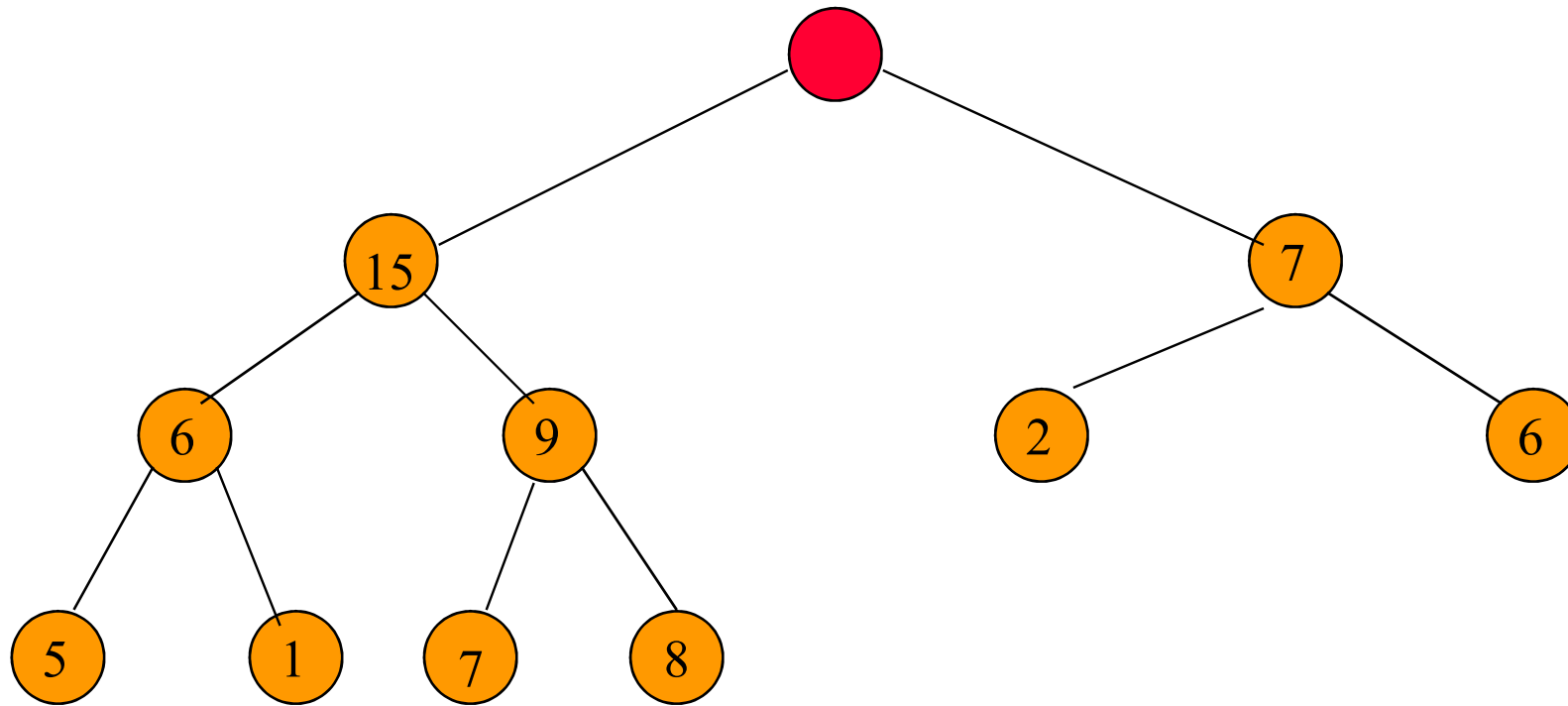
1. Replace the root of the heap with the last element on the last level
2. Compare the new root with its children; if they are in the correct order, stop
3. If not, swap the element with one of its children and return to the previous step
 - Swap with its smaller child in a min-heap and its larger child in a max-heap.

Removing the Max Element



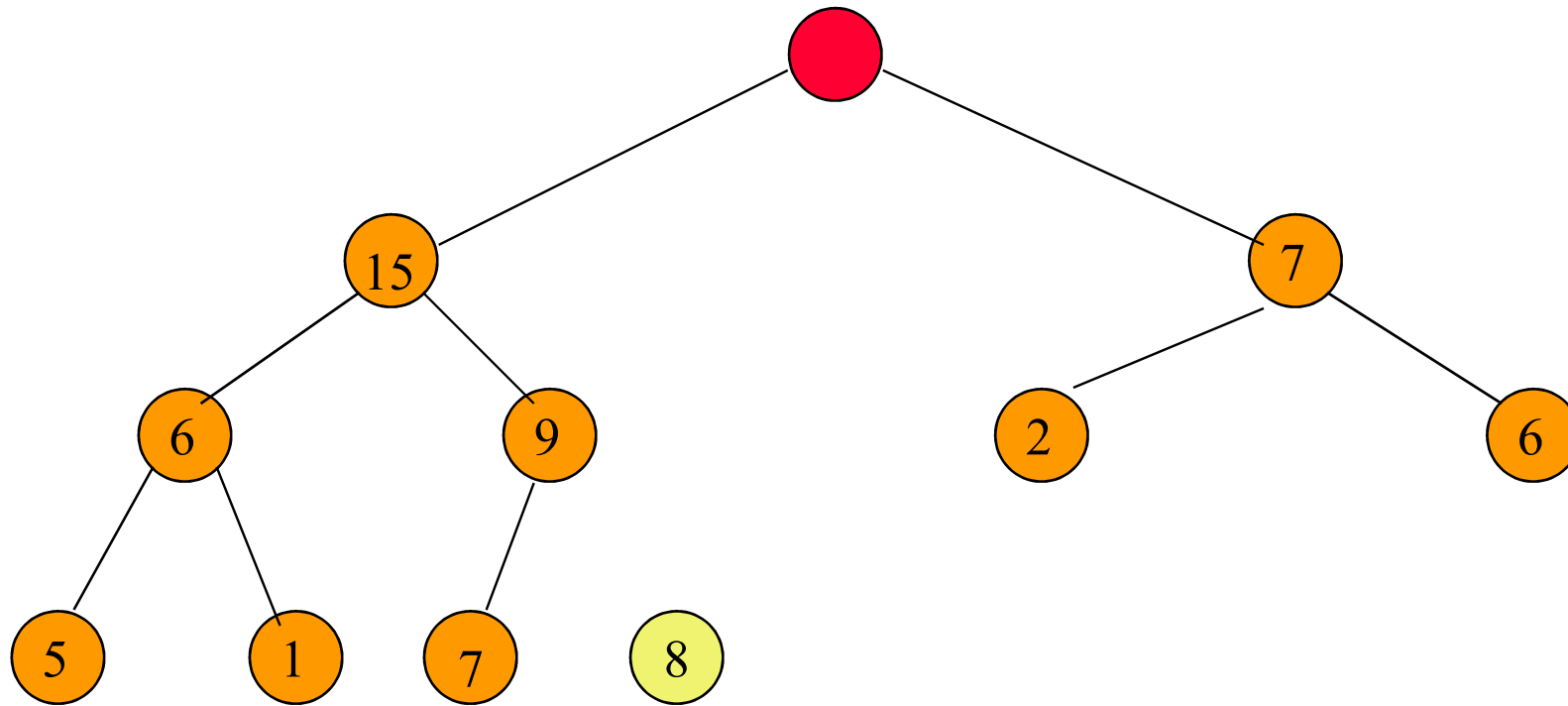
Max element is in the root.

Removing the Max Element



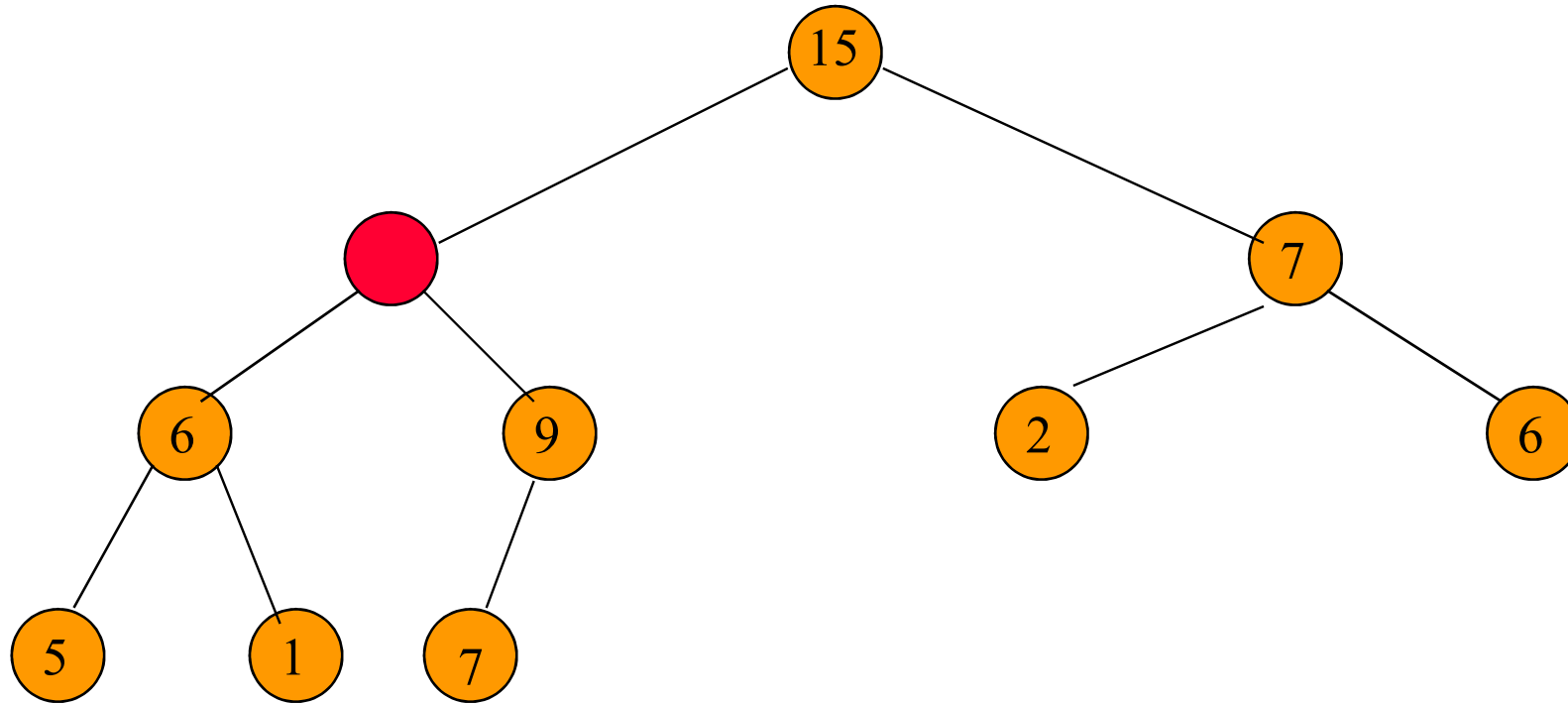
After max element is removed.

Removing the Max Element



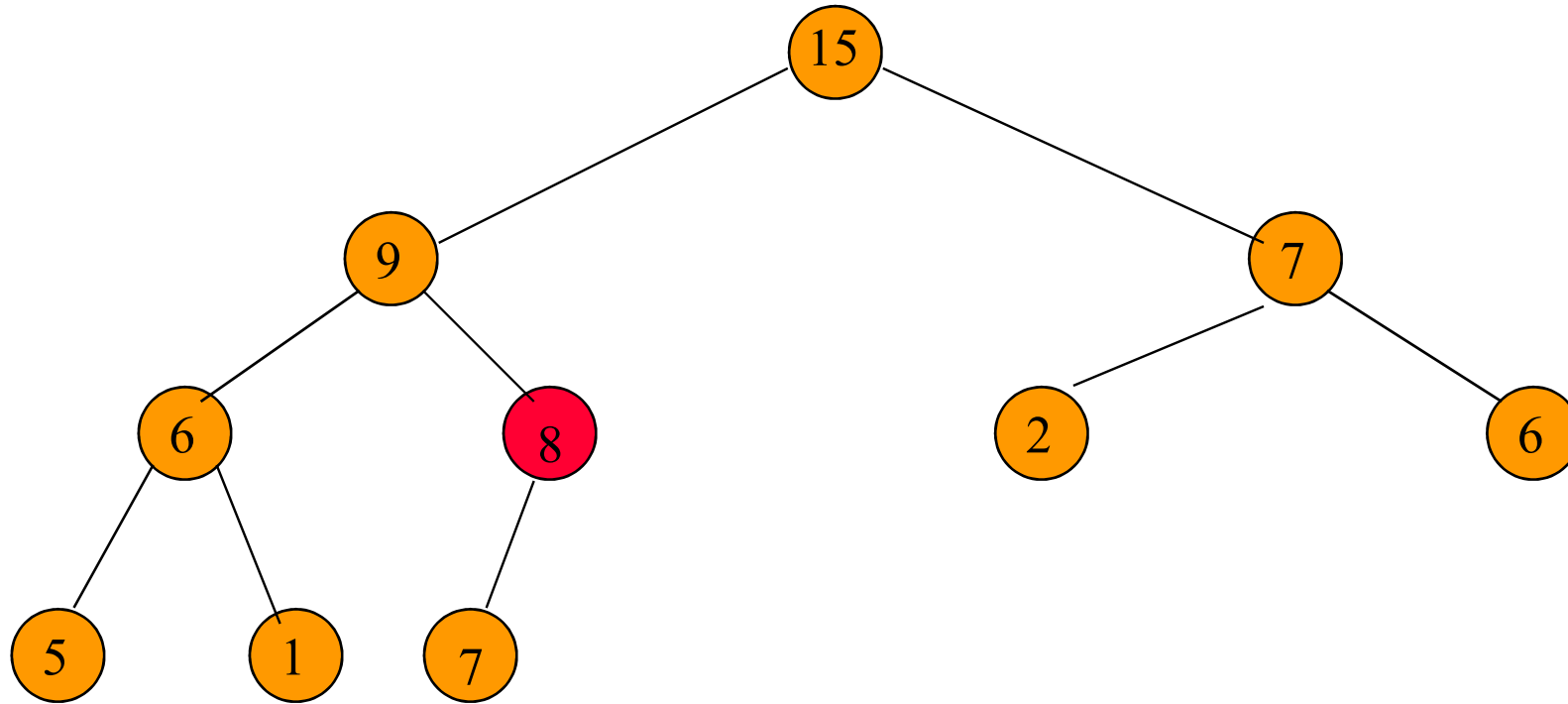
Reinsert **8** into the heap.

Removing the Max Element



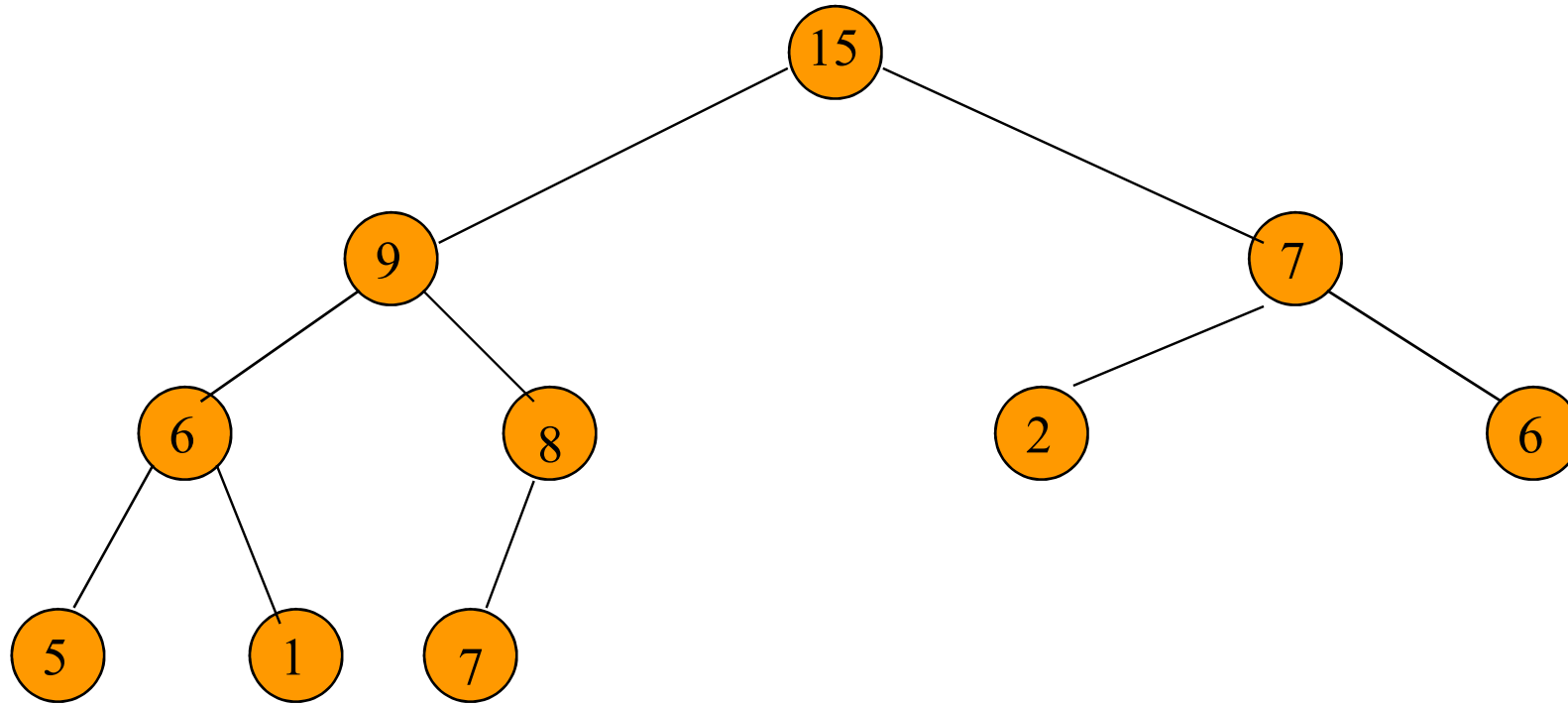
Reinsert **8** into the heap.

Removing the Max Element



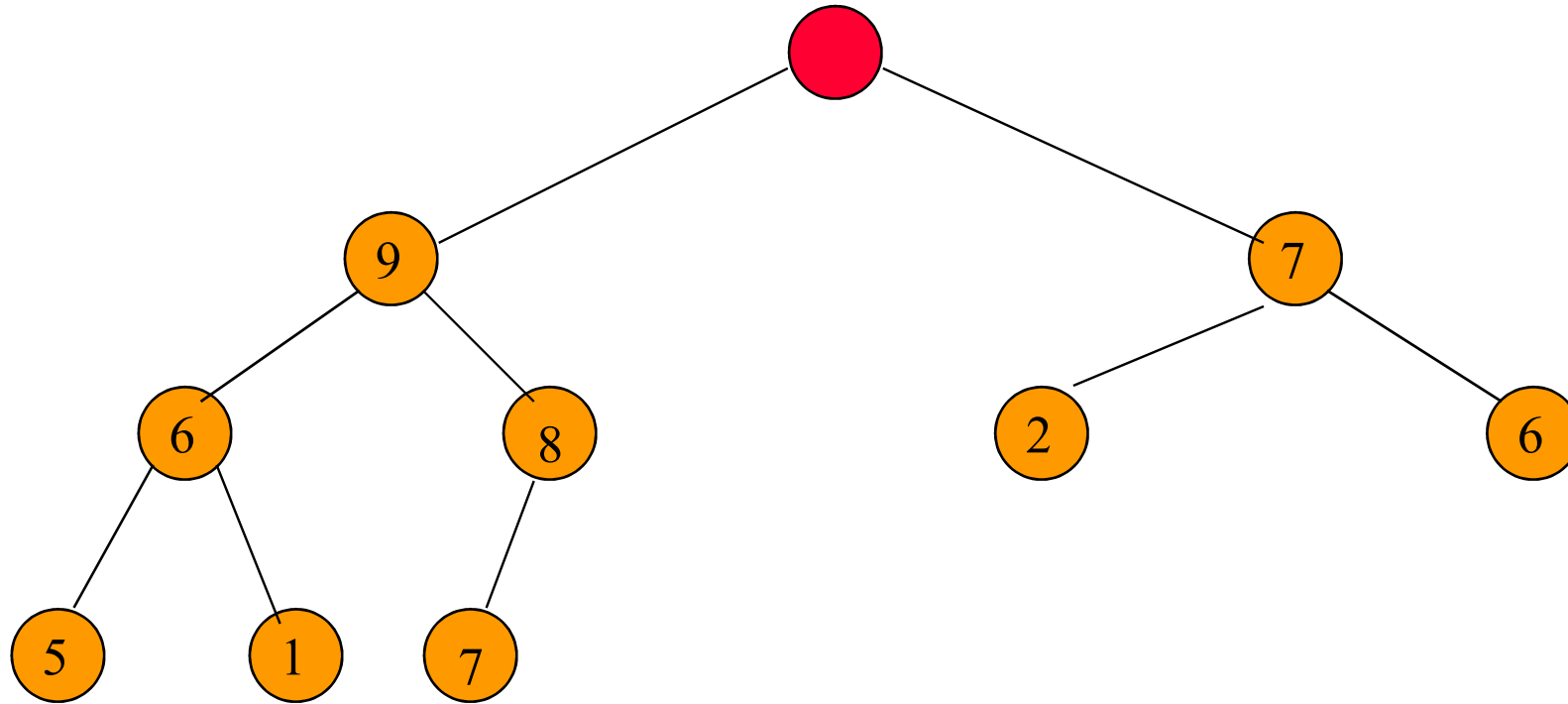
Reinsert **8** into the heap.

Removing the Max Element



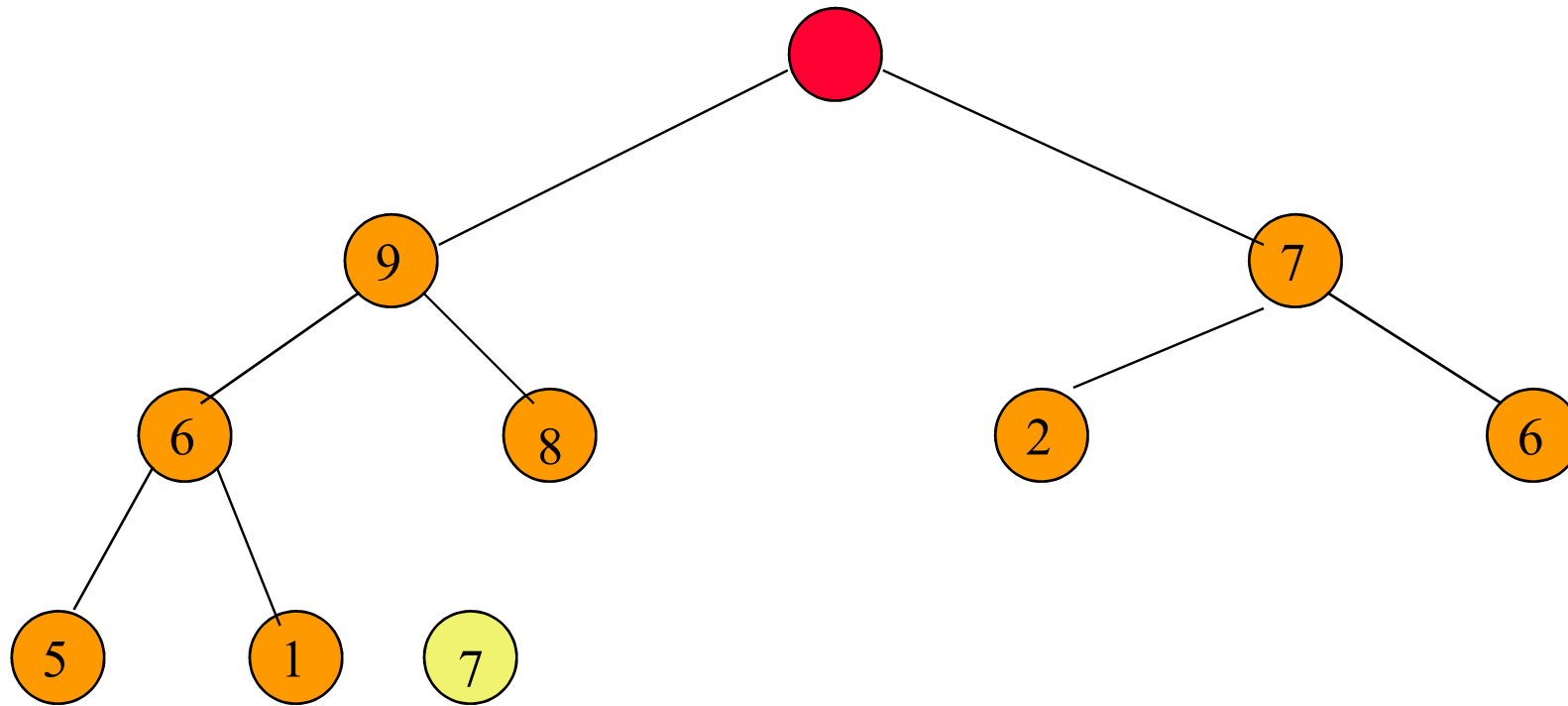
Max element is 15.

Removing the Max Element



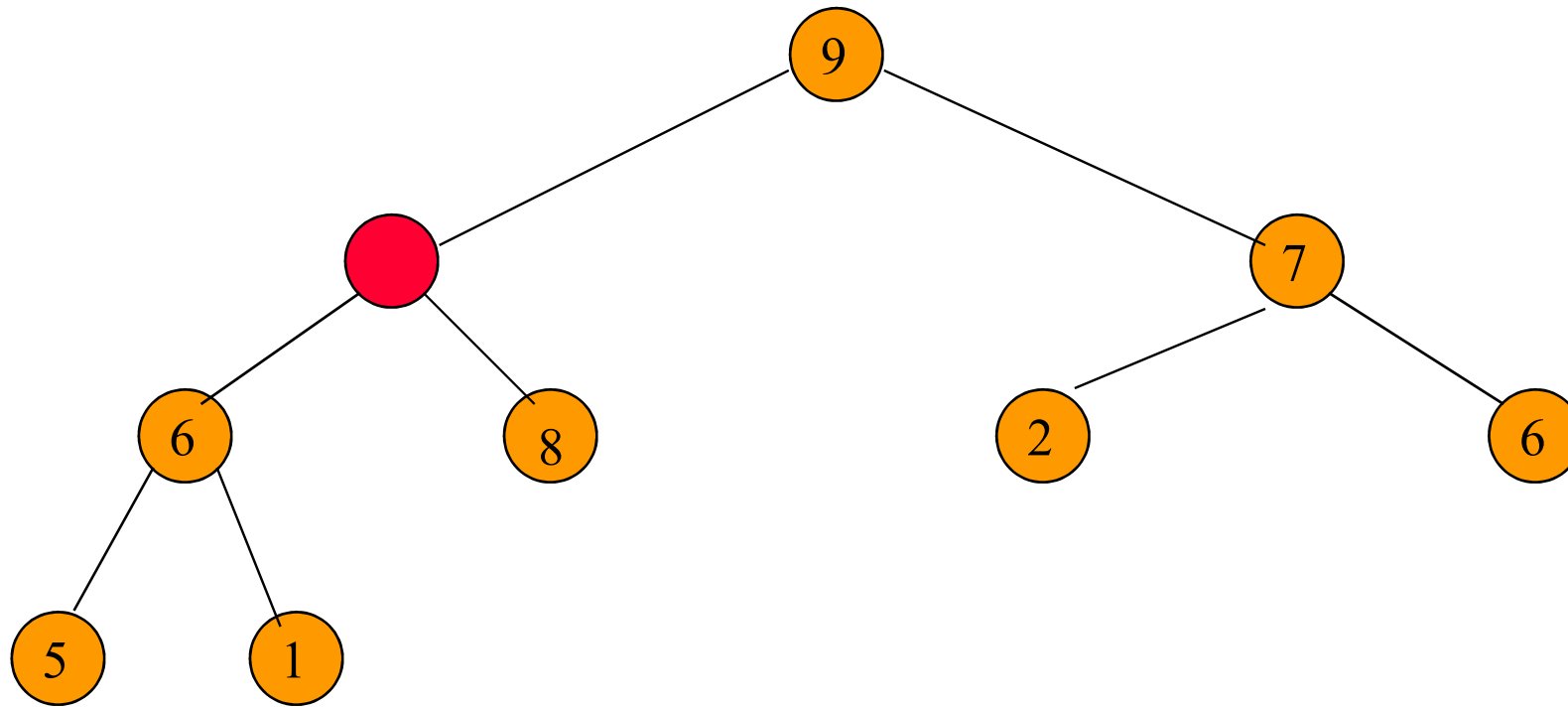
After max element is removed.

Removing the Max Element



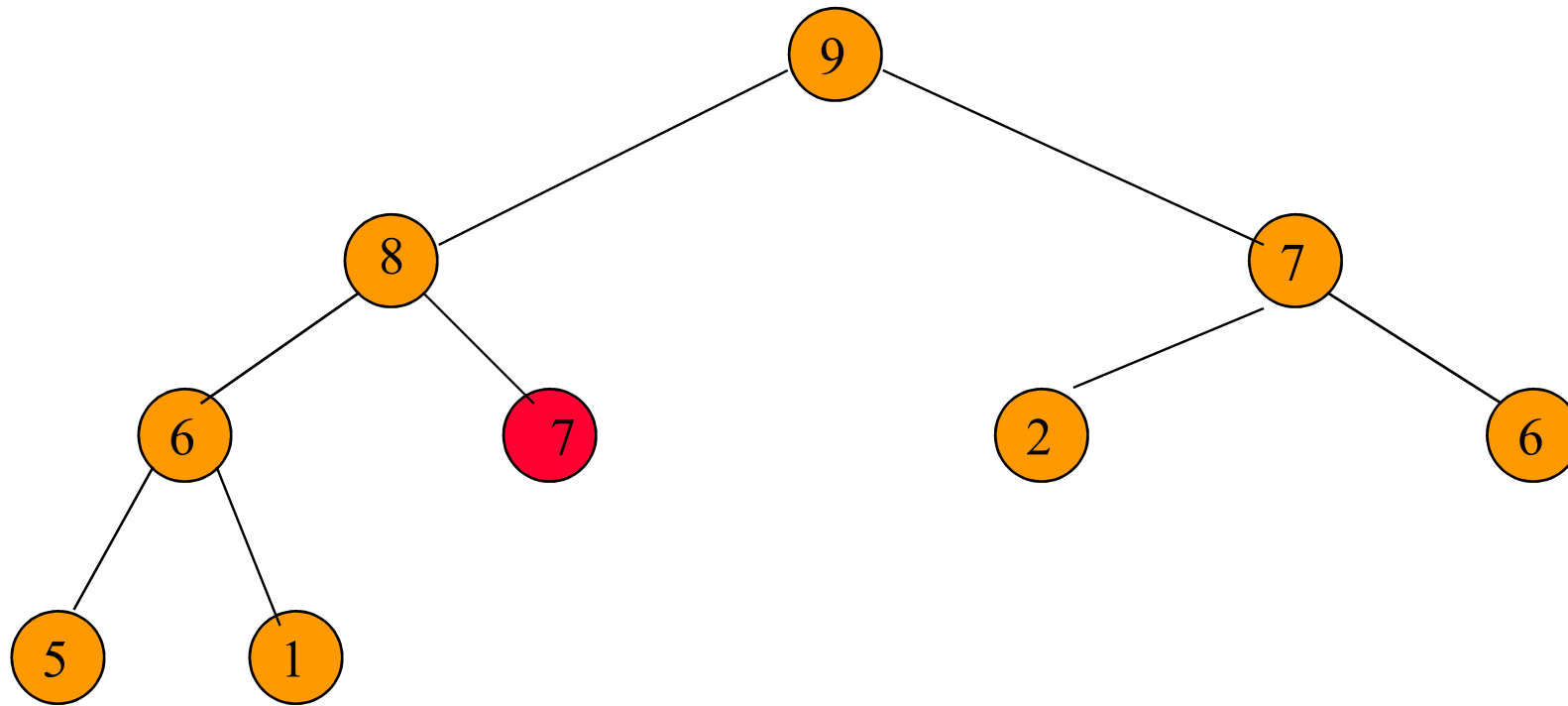
Reinsert **7**.

Removing the Max Element



Reinsert **7**.

Removing the Max Element



Reinsert **7**.

Deletion from a max heap

```
template <class T>
void MaxHeap<T>::Pop()
{ // Delete max element.
    if (IsEmpty()) throw "Heap is empty. Cannot delete.";
    heap[1].~T(); // delete max element

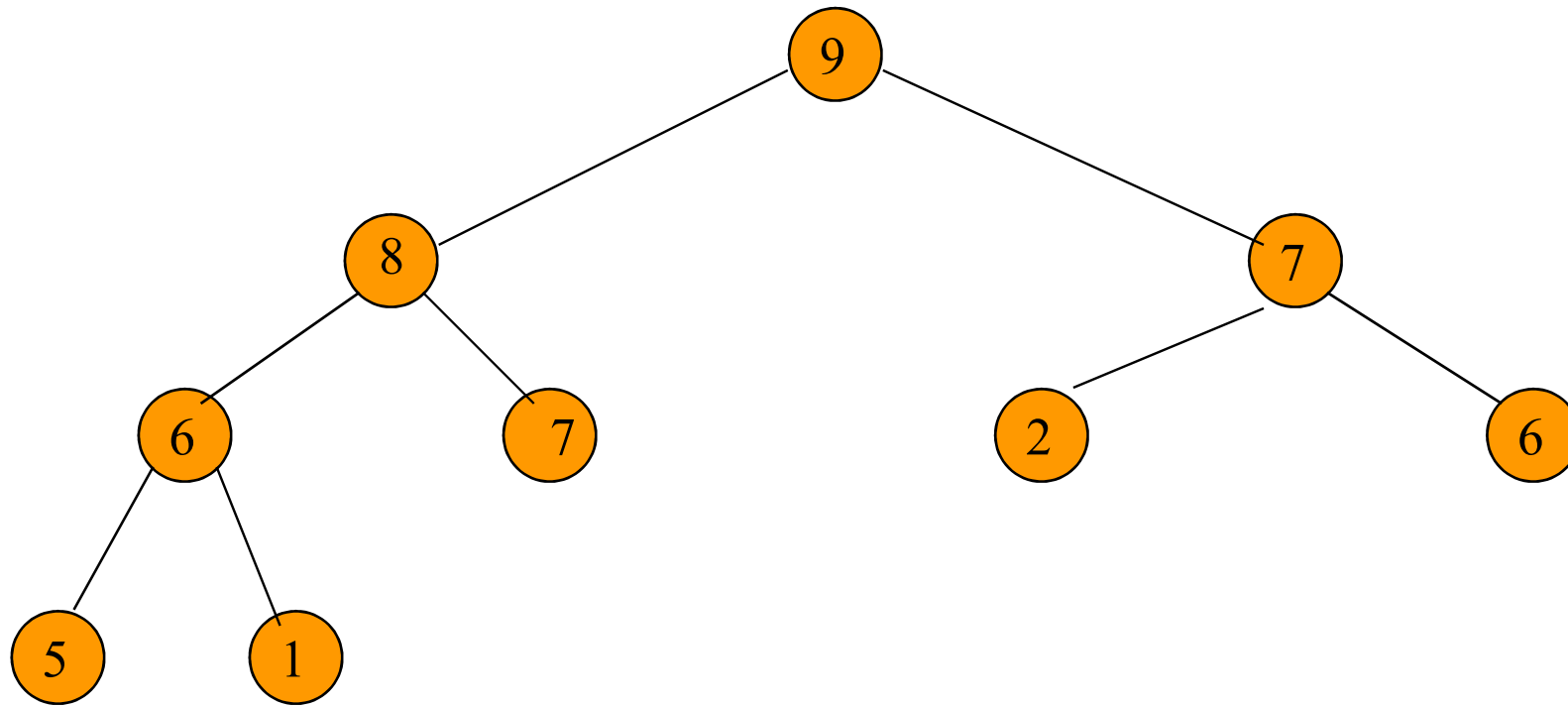
    // remove last element from heap
    T lastE = heap[heapSize--];

    // trickle down
    int currentNode = 1; // root
    int child = 2; // a child of currentNode
    while (child <= heapSize)
    {
        // set child to larger child of currentNode
        if (child < heapSize && heap[child] < heap[child+1]) child++;

        // can we put lastE in currentNode?
        if (lastE >= heap[child]) break; // yes

        // no
        heap[currentNode] = heap[child]; // move child up
        currentNode = child; child *= 2; // move down a level
    }
    heap[currentNode] = lastE;
}
```

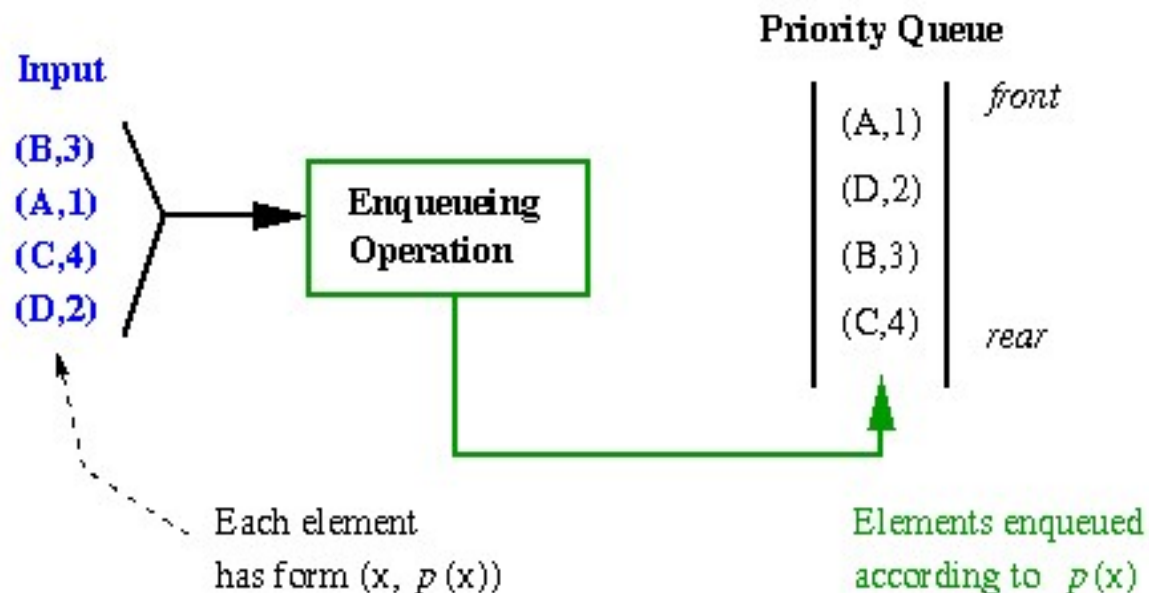
Complexity of Deletion



Complexity is $O(\log n)$.

Priority Queues

- The element to be deleted is the one with highest (or lowest) priority
- At any time, an element with arbitrary priority can be inserted into the queue



Priority Queues (cont.)

Two kinds of priority queues:

- Min priority queue
- Max priority queue

Max Priority Queue

- Collection of elements
- Each element has a priority
- Supports following operations:
 - empty
 - size
 - insert an element into the priority queue (**push**)
 - get element with **max** priority (**top**)
 - remove element with **max** priority (**pop**)

Complexity of Operations

Use a heap

empty, size, and top $\Rightarrow O(1)$ time

insert (push) and remove (pop) \Rightarrow

$O(\log n)$ time where n is the size of the priority queue

Applications of Priority Queues

- Sorting
 - use element key as priority
 - insert elements to be sorted into a priority queue
 - remove/pop elements in priority order
 - if a min priority queue is used, elements are extracted in ascending order of priority (or key)
 - if a max priority queue is used, elements are extracted in descending order of priority (or key)
- Scheduler of an OS

Heap Sort

- Uses a max (or min) priority queue that is implemented as a heap
- Complexity of sorting n elements.
 - n insert operations $\Rightarrow O(n \log n)$ time.
 - n remove max operations $\Rightarrow O(n \log n)$ time.
 - total time is $O(n \log n)$.
 - compare with $O(n^2)$ for insertion or bubble sort

Homework #3

Due: 10/1일(월) 자정까지

1. Implement and test
 - Programs 5.15, 5.16, 5.17
2. 예외 처리(try, throw, catch)에 대해 공부하고 예를 들어 설명할 것