

Analysis  
Edwin Park  
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## 1 Taylor Polynomials

$$\begin{aligned}
 f(\vec{x}) &= f(\vec{x}_0 + (\vec{x} - \vec{x}_0)) \\
 &\approx f(\vec{x}_0) + D_f(\vec{x}_0)(\vec{x} - \vec{x}_0) + \frac{1}{2}(\vec{x} - \vec{x}_0)^\top H_f(\vec{x}_0)(\vec{x} - \vec{x}_0) \\
 &= f(\vec{x}_0) + \begin{bmatrix} f_x(\vec{x}_0) & f_y(\vec{x}_0) \end{bmatrix} \begin{bmatrix} x - x_0 \\ y - y_0 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} x - x_0 & y - y_0 \end{bmatrix} \begin{bmatrix} f_{xx}(\vec{x}_0) & f_{xy}(\vec{x}_0) \\ f_{yx}(\vec{x}_0) & f_{yy}(\vec{x}_0) \end{bmatrix} \begin{bmatrix} x - x_0 \\ y - y_0 \end{bmatrix}
 \end{aligned}$$

Say we wanted to find an upper bound for the error of a first-order approximation at  $\vec{x}$ . The error then is equal to the quadratic term evaluated at some point in between the central point,  $\vec{x}_0$ , and the point of interest,  $\vec{x}$ . In particular, it is, for some  $t \in [0, 1]$ ,

$$\frac{1}{2} [D_{\vec{x}-\vec{x}_0}^2 f](t\vec{x} + (1-t)\vec{x}_0) = \frac{1}{2} \begin{bmatrix} x - x_0 & y - y_0 \end{bmatrix} \begin{bmatrix} f_{xx}(t\vec{x} + (1-t)\vec{x}_0) & f_{xy}(t\vec{x} + (1-t)\vec{x}_0) \\ f_{yx}(t\vec{x} + (1-t)\vec{x}_0) & f_{yy}(t\vec{x} + (1-t)\vec{x}_0) \end{bmatrix} \begin{bmatrix} x - x_0 \\ y - y_0 \end{bmatrix}.$$

## 2 Integral Theorems

We may specify a surface by

$$(x, y, z) = \Phi(a, b).$$

**Theorem 2.0.0.1.**

$$\iint_{\Phi(D)} f \, dS = \iint_D f(\Phi(a, b)) \|\Phi_a \times \Phi_b\| \, da \, db$$

More generally one has the multivariable change of variables formula:

$$\int_{\Phi(D)} f(\vec{r}) \, d\vec{r} = \int_D f(\Phi(\vec{r})) \det D\Phi \, d\vec{r}.$$

**Theorem 2.0.0.2** (Green's Theorem).

$$\int_D \partial_x Y - \partial_y X \, dx \, dy = \int_{\partial D} \begin{bmatrix} X \\ Y \end{bmatrix} \cdot d\vec{r}$$

**Theorem 2.0.0.3** (Divergence Theorem (2D)).

$$\int_C \vec{F} \cdot \hat{n} \, ds = \iint_D \nabla \cdot \vec{F} \, dx \, dy;$$

This is equivalent to Green's theorem.

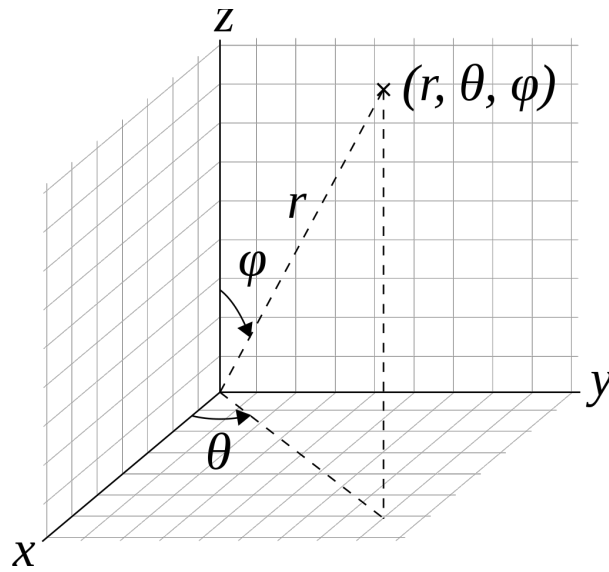
**Theorem 2.0.0.4** (Stokes').

$$\iint_{\Sigma} (\nabla \times \vec{F}) \cdot d\vec{S} = \int_{\partial \Sigma} \vec{F} \cdot d\vec{s}$$

**Theorem 2.0.0.5** (Gauss' Divergence Theorem).

$$\iiint_{\Omega} \nabla \cdot \vec{F} \, dV = \iint_{\partial \Omega} \vec{F} \cdot d\vec{S}$$

### 3 Spherical



$$x = r \sin(\phi) \cos(\theta)$$

$$y = r \sin(\phi) \sin(\theta)$$

$$z = r \cos(\phi)$$

$$\det D\Phi = r^2 \sin(\phi)$$

$$\theta \in [0, 2\pi)$$

$$\phi \in [0, \pi)$$