

PCIe Virtual Host Model Test Component

Contents

- [Summary](#)
- [Verilog](#)
- [PCIe API Code](#)
 - [User Output Generation](#)
 - [Input processing](#)
 - [Link Training](#)
 - [Auxiliary Functions](#)
 - [Internal Memory Access](#)
 - [Model Initialisation and Configuration](#)
 - [Structure of a User Program](#)
 - [Summary of API Functions](#)
- [Further Internal Architecture](#)
 - [Other Internal Functions](#)
 - [Internal Memory Structure](#)
 - [Internal Endpoint Configuration Space](#)
- [PCIe Monitor \(PcieDispLink\)](#)
 - [Transaction Layer Only](#)
 - [Transaction and Data Link Layer](#)
 - [Transaction, Data Link and Physical Layer](#)
 - [Protocol Checking](#)
- [Test Environment](#)
- [Download](#)
- [Related Documents](#)

Summary

This model of a PCI Express host (or 'root complex'—with some endpoint features) is based on the Virtual Processor ([VProc](#)) model (see [VProc documentation](#)), with a PCIe API sitting atop the VProc's PLI API. In summary, the model provides the following features:

- All lane widths up to 16
- Internal memory space accessed with incoming write/read requests (can be disabled)
- Auto-generation of read completions (can be disabled)
- Auto-generation of 'unsupported' completions (can be disabled)
- Auto-generation of Acks/Naks (can be disabled)
- Auto-generation of Flow control (can be disabled)
- Auto-generation of Skip OS (can be disabled)
- User generation of all TLP types
 - Memory Reads/Writes
 - Read completions
 - Config Reads/Writes
 - IO Reads/Writes
 - Messages
- User generation of all DLLP types
 - Acks/Naks
 - Flow control
 - Power management
 - Vendor
- User generation of all training sequences
- User generation of all ordered sets
- User generation of idle
- Proper throttling on received flow control
- Lane reversal
- Lane Inversion
- Serial input/output mode
- Programmable FC delay (via Rx packet consumption rates)
- Programmable Ack/Nak delay
- LTSSM
- MSI reception handling (not yet implemented)
- Programmable limit on completion size (splits) (not yet implemented)

The root directory for the PCIe model is `pcieVHost/`, with C source in `src/` and the main verilog in the `verilog/` directory. The package is available for download on [github](#). The C source code files are:

- **pci_express.h** : Generic PCI Express definitions
- **pcie.h** : Main API header for inclusion in user code
- **pcie.c** : API code

- **pcie_utils.h** : Support function header
- **pcie_utils.c** : Support function code
- **ltssm.h** : LTSSM link training header
- **ltssm.c** : LTSSM link training code
- **codec.h** : Header for encode/decoder and scrambler code
- **codec.c** : Encoder/decoder source
- **mem.h** : Local memory header
- **mem.c** : Local memory implementation
- **pcircrc32.c** : CRC functions mapped as PLI verilog functions
- **veriusers.c** : PLI mapping functions and tables for pcieVHost and VProc
- **pcie_vhost_map.h** : definition of VProc register mappings for pciVHost

The verilog files, under verilog/, are:

- **pcieVHost/pcieVHost.v** : The main PCIe host module top level
- **PcieDispLink/PcieDispLink.v** : top level PCIe monitor
- **PcieDispLink/PcieDispLinkLane.v** : Individual lane display logic
- **PcieDispLink/RxLaneDisp.v** : Receive decode structural verilog
- **PcieDispLink/RxLogicDisp.v** : Lowest order receive decode logic
- **lib/Crc16Gen.v** : CRC generation library for PCIe
- **lib/Decoder.v** : 8/10b decode logic library
- **lib/ScrambleCodec.v** : PCIe scramble logic library
- **lib/Serialiser.v** : PCIe serialiser/deserialiser logic library
- **lib/RxDp.v** : Receive data path library
- **headers/pciexpress_header.v** : PCIe spec definitions
- **headers/pciedispheader.v** : Definitions for PcieDispLink
- **headers/timescale.v** : Global time scale definitions
- **headers/pcie_vhost_map.v** : Auto-generated pcieVHost register map for VProc programs

In addition to the pcieVHost and PcieDispLink files, an example [test environment](#) is provided in the package, and these have files in the [verilog/test/](#) directory. In here is the top level test file ([test.v](#)) and a display control component ([ContDisps.v](#)). User code to run on the pcieVHosts is supplied as [VUserMain0.c](#) and [VUserMain0.c](#), in the [verilog/test/usercode/](#) directory. a [makefile](#) is also provided in the test directory which builds everything needed to compile and run on ModelSim.

Verilog

The verilog module simply maps 16, 10 bit registers, connected to the module output pins, into the VProc address space for writing, and the 16, 10 bit module inputs returning read data in the same address space (returned during both reads and writes). Additionally, three write only locations are provided for invoking `$stop`, `$finish` and ``deaf`. Two read locations give access to the modules node number and lane width parameter. An additional paramater can configure the pcieVHost as an endpoint. What this actually means is that it has some memory is put aside for a configurations space (unitialised) that can be written to over the link via a config write, and will generate completions to config reads, with the contents of this memory.

This arrangement gives full control to the software for both outputting PCIe 10 bit codes on the configured number of lanes, as well as access to raw 10 bit input data. Although some amount of encoding and decoding could have been done in verilog (e.g. 10 bit codec, scrambling, physical layer framing etc.) this has been avoided to give maximum control to the VProc software, enabling for greater flexibility and visibility for generating and detecting exception cases. In order to ease construction of test software, however, an API is provided for the generation and processing of PCIe data. This, effectively, constitutes the model and is described in detail in later sections.

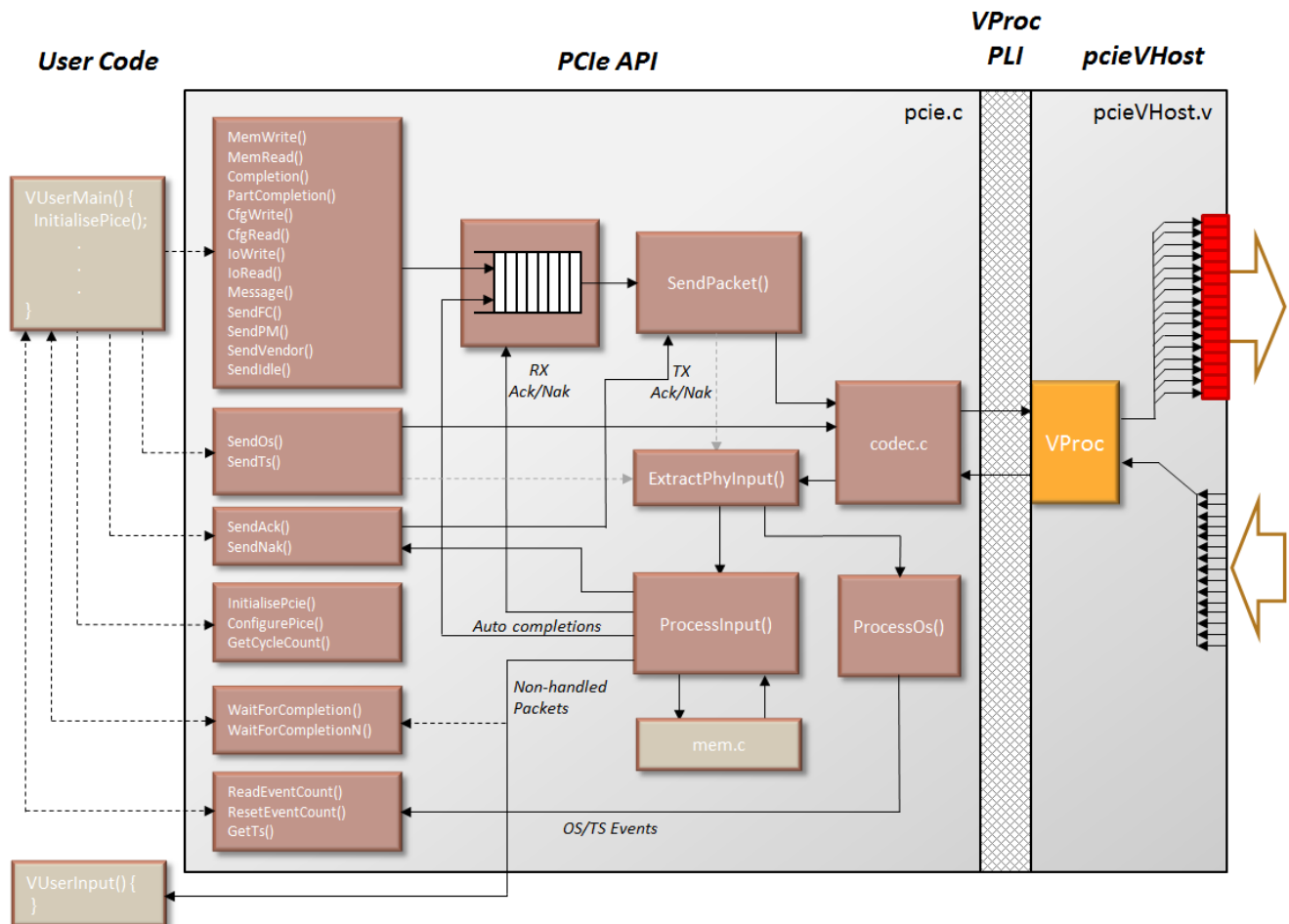
The module definition for the model simply gives a clock and reset input, and the 16 lane input and output 10 bit wide links:

```
module PcieVhost (Clk, notReset,
    LinkIn0, LinkIn1, LinkIn2, LinkIn3,
    LinkIn4, LinkIn5, LinkIn6, LinkIn7,
    LinkIn8, LinkIn9, LinkIn10, LinkIn11,
    LinkIn12, LinkIn13, LinkIn14, LinkIn15,
    LinkOut0, LinkOut1, LinkOut2, LinkOut3,
    LinkOut4, LinkOut5, LinkOut6, LinkOut7,
    LinkOut8, LinkOut9, LinkOut10, LinkOut11,
    LinkOut12, LinkOut13, LinkOut14, LinkOut15);
```

PCIe API Code

The PCIe API software constitutes a set of functions for generating any arbitrary ordered sets, training sequences, data link layer packets or transaction layer packets. Means are provided for constructing a set of packets for transmission before presenting to the output to enable concatenation of packets at the lane level. The input is constantly sampled, and packets extracted and passed to a central processing function. Also, the model has an internal memory space which memory write and read requested get targeted at, and any completion response required gets automatically generated. This can be

disabled at initialisation so that memory reads and writes get passed to user code. When disabled, it is up to the user code to generate the appropriate completion, using the [Completion\(\)](#) API function (see [below](#)).



For user generated output data there are two classes of functions available: Those that are queued (e.g. `MemWrite()` as shown in the top of the left most boxes in the above diagram), and those that output immediately. All user generated output calls go via a function `SendPacket()` except those functions in the box that includes `SendIdle()`. The queued user calls all have the option of adding to the queue and sending to the output, or of simply adding and returning immediately to the user code for other additions to the queue. The queue is of arbitrary length, and so, potentially, any sequence can be built up as a contiguous set of packets before presenting to the output. The `SendPacket()` and the three other direct user functions all call `Encode()` in `codec.c` (as shown in the diagram as the right most box of the PCIe API), which performs the 8b/10b conversion and uses an internal function (`ScrambleAdvance()`) to scramble the data before issuing it to the PCIeVHost verilog via the VProc API.

At each clock the function `ExtractPhyInput()` samples the lanes, and starts to build up packets as they arrive. When it has a whole packet, it calls `ProcessInput()`. What this does with the packet depends on the received packets type. If it is a memory request, it will access the memory functions in `mem.c`. Memory writes are then completed. For reads however, a read completion packet is constructed and added to the output queue. Every received packet requires an acknowledgement. `ProcessInput()` checks the CRC and flags to `SendPacket()` that either an Ack or Nak is waiting. Since `SendPacket()` may be busy outputting another packet from the queue, the Ack or Nak is delayed until the next packet boundary. `ProcessInput()` also receives Acks and Naks for the packets that the model sent out, and these are used to modify the code that controls the queue, such that Naks cause the 'send pointer' to jump back to previously sent packets, whilst Acks cause the head of the queue to move forward and the Acked packets to be deleted from the queue. The only exception to this is that DLLPs are also sent to the output via the queue (again this is so that arbitrary sequences may be built up), but when the send point passes over a DLLP it is removed from the queue immediately.

Two other important functions are provided to the user: `InitialisePcie()` and `WaitForCompletion()`. The first *must* be called before attempting to use any other user outputting functions, and initialises the model. A pointer to a callback function is passed to `InitialisePcie()` for passing up received packets. The second function is a method for stalling the user code until a completion has arrived at the input. A completion does not have to be waited for immediately, and multiple requests can be issued before being a corresponding wait is called.

Other functions are also available for adjusting the model, and are described more fully below.

User Output Generation

Most of the user output functions have a similar set of parameters. (See [Summary of API Functions](#) below). The TLP generation functions all have an address, length (in bytes), tag, requestor ID (`rid`), queue status and node number. The write functions also have a pointer to the data. The `Completion()` functions also requires a status and byte enables (for when a split completion is to be generated), as well as the completer's ID. For completions without a payload, the address, byte enables and length are all set to 0, and the data pointer set to `NULL`. A sister function to `Completion` exists called `PartCompletion()`. This is almost identical, but has an addition `rlength` argument (remaining length) used to calculate the header byte count, which may include additional bytes not present in the completion, for generation of multiple completions. Valid status value for the completion functions are:

- `CPL_SUCCESS`
- `CPL_UNSUPPORTED`
- `CPL_CR3`
- `CPL_ABORT`

Both the completion digest functions have a 'delay' equivalent, with a boolean delay argument for the part-completion function, added to control whether the completion is added to the normal queue, or whether it is added to a special delayed queue. The `CompletionDelay()` function always has the delay, queue and digest flags active. The delay is controlled by user configuration, via `CONFIG_CPL_DELAY_RATE` and `CONFIG_CPL_DELAY_SPREAD` (see [Model Initialisation and Configuration](#)).

All the output functions have a 'digest' equivalent. These are basically the same functions, but with an extra 'digest' parameter to control whether the resulting generated packets have a digest (ECRC) word. The output functions also return a pointer to the packet data generated by the function. This pointer is only valid if the functions are called with the 'queue' parameter set to `QUEUE`. If set to `SEND` then `NULL` is return, since it cannot be guaranteed that the allocated memory containing the packet has not been freed. With a valid pointer returned, the user code has an opportunity to modify the packet (e.g. to deliberately corrupt it) before calling `SendPacket()` to flush the packet onto the link.

The `Message()` function replaces the address with the message code, and the DLLP functions have less parameters, and are specific to the DLLP type.

As mentioned previously, the output functions available to the user code are divided into two categories; queued and non-queued. In addition (hidden from the user code), the functions are also divided by another category, namely template generated or non-template generated. All the queued functions are also templated, but additionally `SendAck()` and `SendNak()` also use templates.

Templates

Within `pcie_utils.c` are two local functions for generating templates for output packets; `CreateTlpTemplate()` and `CreateDllpTemplate()`. A set of parameters are passed into to configure the header, and the function allocates some memory, adequate for the size of the packet, and fills in some default values, as well as the specified parameters. They return a pointer to allocated space, and also, for convenience, a pointer to the start of the data portion of the packet (the byte after the header).

Output Function Structure

Each of the user output functions call the appropriate `CreateTemplate` function and modifies the defaults if required, and calculates the CRC(s). The pointer for this completed packet is then added to an entry of a structure which the function has created, again by requesting some space in memory. This 'packet type' structure (`Pkt_t`) then consists of the pointer for the packet data, an assigned sequence number, and a, as yet, unassigned 'next point' used for constructing the linked list output queue. A `TimeStamp` field is also defined, which is used only on incoming packets (see [below](#)). The `Pkt_t` structure is shown below:

```
typedef struct pkt_struct *pPkt_t;
typedef struct pkt_struct {
    pPkt_t    NextPkt;    // pointer to next packet to be sent
    PktData_t *data;      // pointer to a raw data packet, terminated by -1
    int       seq;        // DLL sequence number for packet (-1 for DLLP)
    uint32_t  TimeStamp;
} sPkt_t;
```

The packet is now ready for adding to the queue, and the output function calls `AddPktToQueue()`, to place it on the output queue. When the user called the output function, a flag `queue` was passed in. If set, the function returns after the packet has been added. If not set, then the newly added packet, along with any previously unsent packets on the queue, are sent to the output by calling `SendPacket()`. This basic operational structure is common to all the output functions except `SendAck()` and `SendNak()`.

Sending of Acks and Naks are not queued because it is not always desirable to send an Ack/Nak for every single packet sequence. The PCI Express specification allows Acks to accumulate such that an Ack of a given sequence number implies an Ack for that sequence number *and* all as yet unacknowledged packets. Since the transmission of Acks can be held up if `SendPacket()` is busy, the `SendAck()` and `SendNak()` functions keep track of what Ack is pending to send, and `SendPacket()` samples this in between the sending of packets (or when idle) and sends whatever acknowledge is indicated

in the cycle. The functions still create a template for the Ack, but if an ack is superseded, the old packet is discarded within the Send functions and a new one created. The `SendAck()` and `SendNak()` functions are usually only called by the `ProcessInput()` function, but they may also be called from the user code if, for instance, an acknowledge error condition is required, or the user has disabled auto-ack generation. However, calling `SendAck()` or `SendNak()` does not guarantee that an acknowledge is sent immediately, but only updates the internal state of pending ACK/NAK sequence.

Output Queue

The output queue is a linked list of 'packet types' (`Pkt_t`) which is managed via three pointers: `head_p`, `send_p` and `end_p`. As one would expect, `head_p` always points to the first unacknowledged packet. The `send_p` pointer always points to the next packet to output, and `end_p` points to the last packet in the queue. When `AddPktToQueue()` is called the packet pointed to by `end_p` has its `NextPtr` field (which would be `NULL`) set to point to the new packet, and `end_p` is updated to also point to the new packet. When `SendPacket()` is called each packet is output, with `send_p` traversing the linked list from its starting point until it hits the `NULL NextPtr` of the end packet. The `send_p` pointer can be modified, however, if a packet receives a Nak. In this case `send_p` is set to the head of the queue, and traverses the list until it points to the packet with the same sequence as the Nak. The `head_p` pointer remains fixed until a successful acknowledge is received. The `head_p` pointer then traverses the list to one beyond the ack sequence (which could be `NULL` if all packets acknowledged).

One deviation from the above procedure occurs. Most DLLPs are also placed on the queue, but aren't acknowledged and mustn't be resent. When the `send_p` passes over a DLLP it must be removed from the queue. The DLLP may be at the head of the queue, in which case `head_p` must move forward one, at the end of the queue, in which case `end_p` must move back one, or in the middle, in which case the `NextPtr` of the previous packet must be set to point to the packet after the DLLP.

In all cases of a packet being removed from the queue, either an acknowledged TLP or a sent DLLP, at that point the memory allocated for the packet is freed so as to prevent a memory leak.

Non-packet Output

The three functions `SendIdle()`, `SendOS()` and `SendTS()` are used to send output that is not within a packet, and is, indeed, sent linearly within the lanes, rather than striped across them. In order for input to be processed correctly, and to correctly comply with output requirements, something must be sent at all times, allowing `SendPacket()` to fetch the input state and send it to `ExtractPhyInput()`. The `SendIdle()` function is used to do this, and can be called with a 'tick' count to indicate for how long it is required to be idle. Also, if `WaitForCompletion()` has been called this implicitly calls `SendIdle()` whilst it is waiting on the completion event. Ordered sets and training sequences can only be sent in between packets, but so long as a `SendPacket()` has been issued before calling them (i.e. `queue` is false on the last call to an output function) then this will be safe.

Input processing

Extracting Data From The Input Link

The input links are constantly sampled, each and every time something is output. Since there is always something output (even if just Idle bytes), the input is sampled every symbol time. As can be seen from the diagram, output only comes directly from two sources—either `SendPacket()`, or the group of low level output functions (`SendIdle()`, `SendTS()` and `SendOS()`). All these functions extract the returned 10 bit word from the input lane as it writes to the corresponding output lane, and places it into an array (`LinkIn`). At the end of the sweep across the lanes, `ExtractPhyInput()` is called, passing in the input array with the new input codewords.

`ExtractPhyInput()` decodes the 10bit words, and monitors for new TLP or DLLP packets. When an `STP` or `SDP` is seen, some memory space is allocated for a maximum size packet. This space is filled with the incoming data until and termination symbol (`END` or `EDB`) is encountered. At this point, the memory is reallocated to reduce to the actual size of the packet. A new packet type structure is created, with a filled in sequence number extracted from the header, and the entire packet is passed to `ProcessInput()`.

Input Packet Processing

All packets are processed through `ProcessInput()`. If the packet is a DLLP, it is CRC checked, then its type is tested and processed internally to `ProcessInput()` if its an Ack or flow control type. Automatic processing of acknowledges can be disabled via `ConfigurePcie()`, in which case the DLLP is sent to the user registered function (if any). For internally handled acknowledges the `curr_ack` or `curr_nak` sequence numbers are updated, and at the next call to `SendPacket()` any acknowledged packets are deleted from the head of the queue, or NAK'ed packets resent by updating the send pointer to include the lowest sequence NAK'ed packet. When acking is disabled, packets are deleted from the queue immediately they are sent and it is the responsibility of the user to resend packets that have been NAK'ed.

For the flow control DLLPs the appropriate `FlowCntlDataCredits` and `FlowCntlHdrCredits` counts are updated, which are used to stall the sending of packets when appropriate. Like acknowledges, flow control may be disabled via

`ConfigurePcie()`, in which case all flow control DLLPs are sent to the user registered function, and the user code must manage throttling of packets. All other DLLPs are not supported and generate a warning upon receipt.

Transaction layer packets are first checked for good CRC(s), and then handled depending on the type. Memory read or write requests access the internal memory (via functions in `mem.c`) when memory is enabled, whilst completions increment a completion count (used by `WaitForCompletion()`—see below) and, if a user function has been registered, is passed to the user code for further processing. Also, packets with failing CRCs, are also passed to the user function, for stats gathering, scoreboarding etc., though the user function may also choose to do nothing with them. All other TLP types are unsupported (presently) and generate a warning message, and get passed up to the user function (if registered). The user function, when finished processing returned packets, must free the memory of the packet to prevent a memory leak. A macro is provided to do this function—`DISCARD_PACKET(_PKT)`. The packets passed to the user registered input function will have the `TimeStamp` field of the `Pkt_t` structure filled in with the clock cycle it was processed. This is useful if user code wishes to implement delaying of responses to these packets by comparing the `TimeStamp` with the current cycle time (accessed using `GetCycleCount()`). If, when internal memory is enabled, a memory read request is processed, `ProcessInput()` generates a read completion packet, which is added to the output queue for transmission. It calls the user API function `Completion()` to do this. If memory is disabled, it is up to the user code to generate any completions.

All the TLP packets generate an acknowledge after the CRC has been checked, with `ProcessInput()` calling either the user API functions `SendAck()` or `SendNak()` as appropriate. Automatic acknowledging can be disabled, however, via `ConfigurePcie()`, in which case the user code must generate the acknowledges as appropriate.

All packets passed to the user callback function are 'whole', in that they contain a flat data structure containing unprocessed physical layer packets (though 8b/10b decoded). In order to extract useful information from the packet as series of macros are provided in `pcie.h`, which take a packet pointer and 'return' a value. Below are shown the currently supplied macros for TLP packets.

```
// Extract header fields
GET_TLP_TYPE(_PKT)
GET_TLP_LENGTH(_PKT)
GET_TLP_FBE(_PKT)
GET_TLP_LBE(_PKT)
GET_TLP_TAG(_PKT)           // Not Completions
GET_TLP_RID(_PKT)           // Not completions
GET_CPL_TAG(_PKT)           // Completions only
GET_CPL_BYTECOUNT(_PKT)    // Completions only
GET_CPL_CID(_PKT)           // Completions only
GET_CPL_STATUS(_PKT)        // Completions only
GET_TLP_ADDRESS(_PKT)       // Get address as 64 bit number (even if 3DW header)
GET_TLP_PAYLOAD_PTR(_PKT)    // Return a pointer to the start of the payload

// Return status
TLP_HAS_DIGEST(_PKT)        // True if an ECRC present (TD bit set)
TLP_HDR_4DW(_PKT)           // True if a 4DW header type
TLP_IS_POSTED(_PKT)         // True if packet is a posted request
```

Bad, as well as good, packets are passed to the user registered callback function, and their status is passed in as the second argument. The value is a bit field indicating different error status types in each bit. The currently supported status bits, as defined in `pcie.h`, are as follows:

- `PKT_STATUS_BAD_LCRC`
- `PKT_STATUS_BAD_ECRC`
- `PKT_STATUS_UNSUPPORTED`
- `PKT_STATUS_NULLIFIED`

Link Training

A couple of high level functions are provided in the `pcieVHost` API, which can be used to do initial link training and flow control initialisation. These are not meant to be full implementations, covering all exceptions and eventualities, but can be used to go from a cold start, power up to L0 state, and set initial flow control values for P, NP and Cpl packets. The example [test environment](#) instantiates two `pcieVHost` modules back-to-back, and calls these API functions from the two test programs to do just this.

To go from a 'Detect' state to 'L0' state, the users program must call `InitLink()`. In addition to the `node` argument (common to all API functions) a `linkwidth` argument is required. This is not left to a default value, as it is essential that the training sequence matches the actual linkwidth that exists on the `pcieVHost` that the program making the call is running from. Other parameters can be set separately with `ConfigurePcie()` (see [Model Initialisation and Configuration](#) section), which can be left to default values if required, or configured to different settings. `CONFIG_LTSSM_LINKNUM` defaults to 0, which is a likely scenario, but this can be updated to be between 0 and 255. The number of fast training sequences set with `CONFIG_LTSSM_N_FTS`, defaults to 255, and has the same range as the link number. The five bit training sequence control field, for hot resets, loopbacks scrambling control etc., can be set via `CONFIG_LTSSM_TS_CTL`. The LTSSM function has abbreviated sequences, due to the time required for some steps (e.g. 24ms). The detect state timeout can be updated with `CONFIG_LTSSM_DETECT_QUIET_TO`. Its units are in clock cycles.

The [CONFIG_LTSSM_ENABLE_TESTS](#) and [CONFIG_LTSSM_FORCE_TESTS](#) configuration types control certain useful test behaviours of the LTSSM. The difference between the enable and force configurations is that the enable will only do the behaviour on average once in every three iterations, whereas a force enables the feature constantly, and thus overrides any equivalent enable setting. The configuration settings are a bit mask, with supported values as listed below:

- [ENABLE_DISABLE](#)
- [ENABLE_COMPLIANCE](#)
- [ENABLE_LOOPBACK](#)

The [ENABLE_DISABLE](#) setting enables/forces going to the 'Disabled' state from configuration start. The [ENABLE_COMPLIANCE](#) bit forces/enables going to polling compliance when entering polling state, instead of polling active. Finally, [ENABLE_LOOPBACK](#) force/enables going to 'Loopback' state from configurations start. Use of these controls is at the discretion of the user, as setting them interrupts the transition from 'Detect' to 'L0' states.

Once a link has been trained, and reached state L0, the initialisation of flow control values over the link can be set with a call to [InitFc\(\)](#). The values advertised are configured via [ConfigurePcie\(\)](#), with relevant types [CONFIG_<type>_HDR_CR](#) and [CONFIG_<type>_DATA_CR](#), with [<type>](#) being one of [POST](#), [NONPOST](#) or [CPL](#).

Auxiliary Functions

[WaitForCompletion\(\)](#), which simply has a [node](#) input argument, is used for stalling the user code until such time as a completion has been seen. It effectively tests a count ([CompletionEvent](#)) which, if zero, will stall in the function, sending out idles, until the count is non-zero. The count is then decremented by the function. With this arrangement, multiple packets (with completions) can be output before waiting on a return. If, at a later time, a wait is called and type count is already non-zero, the [WaitForCompletion\(\)](#) simply drops through, decrementing as it goes. To wait for multiple completions to occur at the same point in the user code, [WaitForCompletionN\(\)](#) is called with the required number completion events as its first argument.

It should be noted that the [WaitForCompletion\(\)](#) function is stalling on a whole completion. That is to say, if the completer returns completion data as multiple completions for the same tag, only the final completion increments the event count. It is up to the user registered input function to process multiple completions, and keep track of earlier partial completion, ready for use by the [VUserMain](#) flow.

Internal Memory Access

The PCIe model's internal memory may be accessed from user code ([VUserMainN\(\)](#) etc.) To write to the memory [WriteRamByteBlock\(\)](#) is used. This takes a 32 bit aligned address, a pointer to a [PktData_t](#) buffer containing bytes, a first and last byte enable (4 bits each) and a byte length which is a multiple of 4 bytes. If it's required to write data not aligned to 32 bits, then the byte enables are used, but the data buffer will start at the 32 bit aligned address and must be padded in the disabled byte positions. To read back data, a similar call ([ReadRamByteBlock\(\)](#)) is made, with the same arguments as [WriteRamByteBlock\(\)](#), but without the byte enables. [ReadRamByteBlock\(\)](#) returns 0 on successfully reading from memory, but returns non-zero if there was an error, such as reading an uninitialised block. In the error case no data is returned, and the buffer remains unchanged. Some simpler functions are provided for individual byte and word reads and write (see [Summary of API Functions](#) for a list of these functions). These return a data value of 0 for accesses to uninitialised memory blocks.

Model Initialisation and Configuration

A single function provides all the initialisation required by the model. [InitilisePcie\(\)](#) *must* be called from the user code before any other API function call is made. It has only two arguments, the first of which allows registration of a user function to be called whenever a completion type packet is received at the input (e.g. read completion, configuration write completion, etc.). The user function is responsible for handling these packets, though they will have been CRC checked and are always delivered valid. This argument may be [NULL](#) if it is not required to process these packets. The second argument is the VProc node number of the program.

The model works 'out of the box' as it were, but may be configured, either immediately after initialisation or at future points during simulation. Only one function is used to provide all configuration access; [ConfigurePcie\(\)](#). Its first argument is a 'type' selecting which parameter is to be altered and the second is an integer value. Some types do not require value, in which case the value argument is a 'don't care' (so usually set to 0 or [NULL](#)). A list of valid types, and whether requiring a value, is given below.

TYPE	VALUE?	UNITS	Description
CONFIG_FC_HDR_RATE	yes	cycles	Rx Header consumption rate (default 4)
CONFIG_FC_DATA_RATE	yes	cycles	Rx Data consumption rate (default 4)
CONFIG_ENABLE_FC	no		Enable auto flow control (default)
CONFIG_DISABLE_FC	no		Disable auto flow control

CONFIG_ENABLE_ACK	yes	cycles	Enable auto acknowledges with processing rate (default rate 1)
CONFIG_DISABLE_ACK	no		Disable auto acknowledges
CONFIG_ENABLE_MEM	no		Enable internal memory (default)
CONFIG_DISABLE_MEM	no		Disable internal memory
CONFIG_ENABLE_SKIPS	yes	cycles	Enable regular Skip ordered sets, with interval (default interval 1180)
CONFIG_DISABLE_SKIPS	no		Disable regular Skip ordered sets
CONFIG_ENABLE_UR_CPL	no		Enable auto unsupported request completions (default)
CONFIG_DISABLE_UR_CPL	no		Disable auto unsupported request completions
CONFIG_POST_HDR_CR†	yes	credits	Initial advertised posted header credits (default 32)
CONFIG_POST_DATA_CR†	yes	credits	Initial advertised posted data credits (default 1K)
CONFIG_NONPOST_HDR_CR†	yes	credits	Initial advertised non-posted header credits (default 32)
CONFIG_NONPOST_DATA_CR†	yes	credits	Initial advertised non-posted data credits (default 1)
CONFIG_CPL_HDR_CR†	yes	credits	Initial advertised completion header credits (default ∞)
CONFIG_CPL_DATA_CR†	yes	credits	Initial advertised non-posted data credits (default ∞)
CONFIG_CPL_DELAY_RATE†	yes	cycles	Auto completion delay rate (default 0)
CONFIG_CPL_DELAY_SPREAD†	yes	cycles	Auto completion delay randomised spread (default 0)
CONFIG_LTSSM_LINKNUM††	yes	integer	Training sequence advertised link number (default 0)
CONFIG_LTSSM_N_FTS††	yes	integer	Training sequence number of fast training sequences (default 255)
CONFIG_LTSSM_TS_CTL††	yes	integer	Five bit TS control field (default 0)
CONFIG_LTSSM_DETECT_QUIET_TO††	yes	cycles	Detect quiet timeout
CONFIG_LTSSM_ENABLE_TESTS††	yes	bit mask	Enable LTSSM test exceptions (default 0)
CONFIG_LTSSM_FORCE_TESTS††	yes	bit mask	Force LTSSM test exceptions (default 0)
† Call immediately after <code>InitialisePcie()</code> to take effect from time 0			
†† Call before calling <code>InitLink()</code> to take effect in training sequences. (see Link Training section.)			

Structure of a User Program

There are many ways that a user program could be constructed to utilise the PCIe model, but there are some common components that would feature in any implementation, which are discussed now. Below is shown an example outline of a basic VUserMain program for the model:

```
#include <stdio.h>
#include <stdlib.h>
#include "pcie.h"

#define RST_DEASSERT_INT 4

static int node = 0;
static unsigned int Interrupt = 0;

static int ResetDeasserted(void)
{
    Interrupt |= RST_DEASSERT_INT;
}

static void VUserInput(pPkt_t pkt, int status, void* usrptr)
{
    /* ---- User processing of received packets here ---- */

    DISCARD_PACKET(pkt);
}

void VUserMain0()
{
    VRegInterrupt(RST_DEASSERT_INT, ResetDeasserted, node);
    InitialisePcie(VUserInput, node);

    do
    {
        SendOs(IDL, node);
    }
    while (!Interrupt);

    Interrupt &= ~RST_DEASSERT_INT;

    InitLink(16, node);
    InitFc(node);
}
```



```

/* ---- User calls to packet generation functions here ---- */

SendIdle(100, node);

VWrite(PVH_FINISH, 0, 0, node);
}

```

The above code assumes that the PCIe model is configured at node 0. The call to `VRegInterrupt()` connects the callback function `ResetDeasserted()` to the reset interrupt so that we can wait until after reset is removed, whilst the `InitialisePcie()` sets up the model for this node and registers `VUserInput()` as the callback for unhandled packets. With no link training startup code, the program simply outputs `IDL` ordered sets (`SendOs()`) until reset is deasserted. A link initialisation is instigated with a call to `InitLink()`, followed by Flow control initialisation with `InitFc()`, and then the model is ready to go. If either link initialisation or configuration needs non-conformant sequences, or different values for testing, etc., the the calls to these functions can be skipped, and replaced with user code to output different patterns as required.

At this point other user functions may be called to implement behaviour, or the user code simply inserted directly into `VUserMain()`. At its simplest, the user code would normally be calls to `MemRead()`, `MemWrite()` and `Completion()` (or possibly `PartCompletion()` if the completion must be split). Also `CfgRead()` and `CfgWrite()` if config space accesses are required. The `WaitForCompletion()` function would be used for synchronising of returned data to non-posted requests. Some of the details of the API calls could be tidied away in user data hiding modules, so that requestor ID, node number etc. are not visible to the user's main program code. With the model configured to its default, the `VUserInput()` should only ever be called with corrupted packets. To receive all transaction layer packets `ConfigurePcie()` is called just after `InitialisePcie()` with `CONFIG_DISABLE_MEM` to pass up memory reads and writes, and with `CONFIG_DISABLE_UR_CPL` to receive unsupported packet types. All data link layer packets are handled automatically by default, so `CONFIG_DISABLE_FC` and `CONFIG_DISABLE_ACK` can be used to receive these. In this way the user code can choose what level of handling it wishes to implement, be it its own memory model, error reporting or link protocol handling.

The user code may be an infinite loop, if required, but if it ever returns it is possible to terminate, stop or `deaf the simulation from within `VUserMain()` using a low level VProc call. In the example, idles are sent for a short time to flush the link, especially for `PcieDisplinks`, and then a VProc write (`VWrite()`) to an address 'PVH_FINISH' terminates the simulation. Two other addresses (`PVH_STOP` and `PVH_DEAF`) perform the equivalent functions.

As has been mentioned elsewhere, `VUserMain()` and the callback function (`VUserInput()`) are not running in separate threads, and so it is safe to share memory between them. If a user program instigates new threads, however, care must be to avoid race conditions and contentions between transmitter and receiver code, and the model's API thread. E.g. it is hazardous to call API code from a separate thread to `VUserMain()`, and proper resynchronisation should be employed.

Summary of API Functions

TLP Output Functions

```

pPktData_t MemWrite      (uint64 addr, PktData_t *data, int length, int tag, uint32 rid, bool queue, int node);
pPktData_t MemRead      (uint64 addr, int length, int tag, uint32 rid, bool queue, int node);
pPktData_t Completion   (uint64 addr, PktData_t *data, int status, int fbe, int lbe,
                          int word_length, int tag, uint32 cid, uint32 rid, bool queue, int node);
pPktData_t PartCompletion (uint64 addr, const PktData_t *data, int status, int fbe, int lbe, int word_rlength, int word_length,
                          int tag, uint32 cid, uint32 rid, bool queue, int node);
pPktData_t CfgWrite      (uint64 addr, PktData_t *data, int length, int tag, uint32 rid, int queue, int node);
pPktData_t CfgRead       (uint64 addr, int length, int tag, uint32 rid, bool queue, int node);
pPktData_t IoWrite       (uint64 addr, PktData_t *data, int length, int tag, uint32 rid, bool queue, int node);
pPktData_t IoRead        (uint64 addr, int length, int tag, uint32 rid, bool queue, int node);
pPktData_t Message       (int code, PktData_t *data, int length, int tag, uint32 rid, bool queue, int node);

pPktData_t MemWriteDigest (uint64 addr, PktData_t *data, int length, int tag, uint32 rid, bool digest, bool queue, int node);
pPktData_t MemReadDigest  (uint64 addr, int length, int tag, uint32 rid, bool digest, bool queue, int node);
pPktData_t CompletionDigest (uint64 addr, PktData_t *data, int status, int fbe, int lbe,
                              int word_length, int tag, uint32 cid, uint32 rid, bool digest, bool queue, int node);
pPktData_t PartCompletionDigest (uint64 addr, const PktData_t *data, int status, int fbe, int lbe, int word_rlength, int word_length,
                              int tag, uint32 cid, uint32 rid, bool digest, bool queue, int node);
pPktData_t CfgWriteDigest (uint64 addr, PktData_t *data, int length, int tag, uint32 rid, bool digest, bool queue, int node);
pPktData_t CfgReadDigest  (uint64 addr, int length, int tag, uint32 rid, int digest, int queue, int node);
pPktData_t IoWriteDigest  (uint64 addr, PktData_t *data, int length, int tag, uint32 rid, bool digest, bool queue, int node);
pPktData_t IoReadDigest   (uint64 addr, int length, int tag, uint32 rid, bool digest, bool queue, int node);
pPktData_t MessageDigest  (int code, PktData_t *data, int length, int tag, uint32 rid, bool digest, bool queue, int node);

pPktData_t CompletionDelay (uint64 addr, PktData_t *data, int status, int fbe, int lbe, int length, int tag,
                           uint32 cid, uint32 rid, int node);
pPktData_t PartCompletionDelay (uint64 addr, PktData_t *data, int status, int fbe, int lbe, int rlength, int length, int tag,
                              uint32 cid, uint32 rid, bool digest, bool delay, bool queue, int node);

void      SendPacket      (void);

```

DLLP Output Functions

```

void SendAck   (int seq, int node);
void SendNak   (int seq, int node);
void SendFC    (int type, int vc, int hdrfc, int datafc, bool queue, int node);

```

```
void SendPM      (int type, bool queue, int node);
void SendVendor (bool queue, int node);
```

Low Level Output

```
void SendIdle (int Ticks, int node);
void SendOs   (int Type, int node);
void SendTs   (int identifier, int lane_num, int link_num, int n_fts, int control, bool is_gen2, int node);
```

Low Level Input

```
int  ResetEventCount (int type, int node);
int  ReadEventCount  (int type, uint32 *ts_data, int node);
TS_t GetTS           (int lane, int node);
```

Link Training

```
void InitLink      (int linkwidth, int node);
void InitFc        (int node);
```

Miscellaneous Functions

```
void    WaitForCompletion (int node);
void    WaitForCompletionN (unsigned int count, int node);
uint32  GetCycleCount    (int node);
void    InitialisePcie    (callback_t cb_func, int node);
void    ConfigurePcie     (int type, int value, int node);
void    PcieRand          (int node);
void    PcieSeed          (int seed, int node);
```

Internal Memory Access Function

```
void    WriteRamByteBlock (uint64 addr, const PktData_t *data, int fbe, int lbe, int byte_length, uint32 node);
int      ReadRamByteBlock (uint64 addr, PktData_t *data, int byte_length, uint32 node);
void    WriteRamByte      (uint64 addr, uint32 data, uint32 node);
void    WriteRamWord      (uint64 addr, uint32 data, int little_endian, uint32 node);
void    WriteRamDWord     (uint64 addr, uint64 data, int little_endian, uint32 node);
uint32  ReadRamByte       (uint64 addr, uint32 node);
uint32  ReadRamWord       (uint64 addr, int little_endian, uint32 node);
uint64  ReadRamDWord      (uint64 addr, int little_endian, uint32 node);

void    WriteConfigSpace  (const uint32 addr, const uint32 data, const uint32 node);
uint32  ReadConfigSpace   (const uint32 addr, const uint32 node);
```

Further Internal Architecture

Some discussion of internal structure has already been made in the description of the API. In particular, [SendPacket\(\)](#), [ExtractPhyInput\(\)](#) and [ProcessInput\(\)](#), as the main Tx/Rx processing routines. Further detail of the rest of the internal code is now given below.

Other Internal Functions

Described above are the main functions which comprise the PCIe model. In addition to these, however, are several other support functions not mentioned previously. These are listed now with a brief synopsis to aid navigation through the source code.

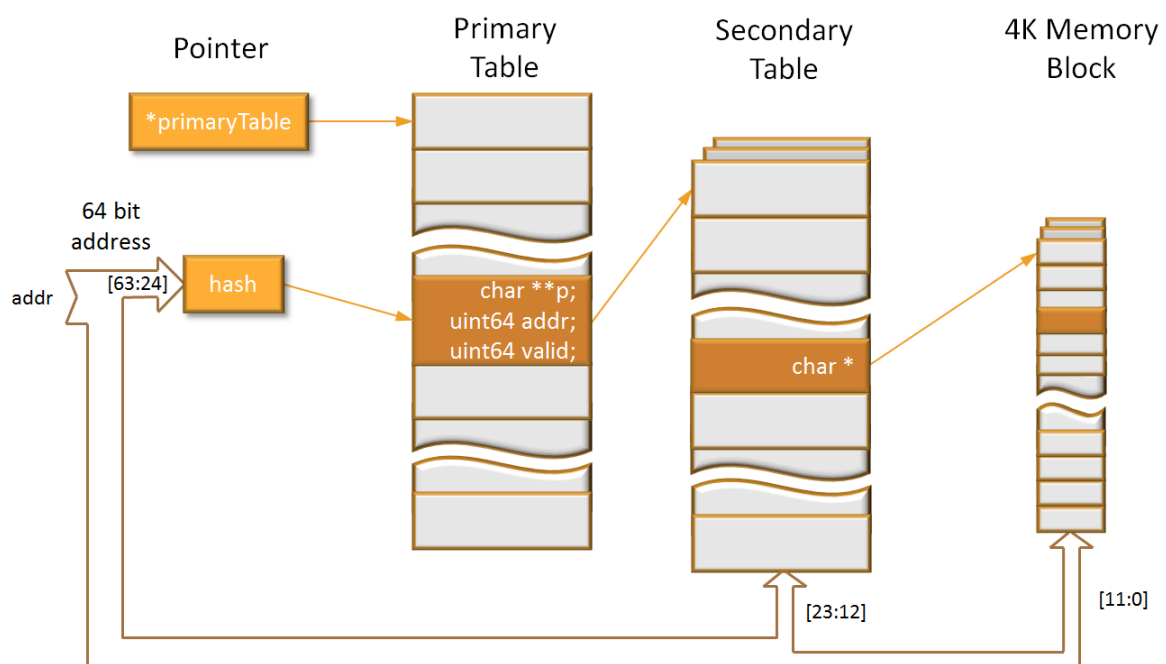
Function	Description
CalcByteCount()	Calculates a completion header byte count from a given length and byte enables
CalcLoAddr()	Calculates a completion headers low address field
CalcBe()	Calculates byte enables from a given address and length
CheckCredits()	Returns true or false on enough available credits for transmission of packet
ProcessRxFlowControl()	Counts received packet credits, and sends out FC updates when required. Called from ProcessInput() for each received packet
UpdateConsumedFC()	Updates consumed header and data credit counts, emulating finite processing time of received packets. Called once a cycle from ExtractPhyInput() .
CalcDllpCrc()	Calculates DLLP crc for given DLLP packet
CalcEcrc()	Calculates ECRC digest for given TLP packet
CalcLcrc()	Calculates LCRC for given TLP packet
AckPkt()	Updates state of received packet acknowledges
NakPkt()	Updates state of received packet not-acknowledges
ProcessOS()	Maintains state on physical set reception. Called from ExtractPhyInput() on reception of an OS/TS.
InitPcieState()	Initialises internal model state to defaults. Called from InitialisePcie()
CalcNewRand()	Platform independent random number function.

[CheckFree\(\)](#) `stdlib free()` function with pre-checking for NULL
[InitFc\(\)](#) Instigates transmission of FC initialisation packets

Internal Memory Structure

The PCIe model (optionally) supports memory access requests for the full 64 bit address space accessible by PCI Express transactions with an internal memory model. It does this with routines defined in `mem.c`, which initialise with no actual memory space allocated. As shown on the diagram, normally only `ProcessInput()` has access to the memory, and `mem.c` provides two functions for writes and reads—`WriteRamByteBlock()` and `ReadRamByteBlock()`. The user code has access to these functions, as well as some byte and word access hybrid versions.

The full 64 bit space capability relies on the fact that a simulation run cannot possibly write to all 2^{64} locations. Instead, the space is divided into 4K byte chunks which get dynamically allocated as required, and are accessed via references in a series of tables which further divided the address space. The starting point for a lookup is the `PrimaryTable`. This table has 4K entries, but maps all the top 40 bits of the address space into this space, using a simple hash, XORing the bits in a certain way and then bit reversing the 12 bit result. The `PrimaryTable` entry structure (`PrimaryTable_t`) has a valid field and an address for storing the top 40 bits of the address that hits on the location. If another address upper 40 bits hashes to the same location, then the index pointing to the table entry is simply incremented until an empty entry is found, or we searched the whole table (an error condition).



The primary table entry also contains a pointer to a pointer, which references a secondary table, dynamically allocated when first written to. The secondary tables sub-divide the address space of the lower 24 bits of the address into the 4K byte blocks required. The upper 12 bits of the lower address index into the secondary table, whose entry points to a 4K byte block of memory, dynamically allocated on first access. Because PCI Express does not allow crossing of 4K boundaries within a transaction, there is never any need to access more than one memory block at a time for a given transaction.

Reading from a location simply involves traversing the table. The top 40 bits of the read address are hashed, and index into the primary table. The Primary table entry address is compared with the read address 40 bits and, if different, the index is incremented until a match, an invalid address is encountered or the whole table is searched. The last two cases are an error condition. The secondary table is then accessed with the next 12 bits and (if pointing to a valid byte block), the lower 12 bits used to retrieve the data. At any point in the traverse, an unallocated table entry of byte block is considered a fatal error—it is not legal to access locations that have not been written.

Internal Endpoint Configuration Space

If the `pcieVHost` is configured as an endpoint, it reserves a page, separate from the other internal memory, that can be accessed via the configuration read and write command over the PCIe link. In addition there are a couple of access functions, `WriteConfigSpace()` and `ReadConfigSpace()`, that allow local word (32 bit) access to this memory from the user programs. When not an endpoint, or if internal memory accesses is disabled, via

PCIe Monitor (PcieDispLink)

The PcieDisLink module is a verilog behavioural test component, that can be attached to the up and down links of the PCIe host model, and any connected test unit's PCIe link. The main purpose of the PCIe DisLink function is to provide logging data for activity on the PCIe link. It is a separate verilog component, rather than integrated into pcieVHost so that it can be used with other modules, such as some verification IP (VIP) and/or an implementation being tested or exercised. It is controlled by bits in the `ContDisp.hex` display control file, located in `verilog/test/hex`, (discussed shortly). A secondary function is to check the link for PCIe protocol violations, and report them to the log file. In this respect it is not an exhaustive protocol checker, with many compliance checklist features unsupported, and no coverage measurements. The `ContDisp.hex` file consists of a list of two numbers, the first being a hex number containing the control bits, followed by a decimal cycle number.

The display output to the log from PcieDisLink is controlled by 4 bits. PCIe has three 'virtual' layers; transaction, data link and physical. Three bits in the `ContDisp.hex` vector enable display of the associated layer. These bits are defined as ``DispTL`, ``DispDL` and ``DispPL` respectively, defined in the file `verilog/headers/pcidisphheader.v`. A fourth separate bit, ``DispRawSym` enables a display of all raw decoded symbol values. In addition to the four individual display controls, a ``DispAll` bit forces all to be displayed, including the extra raw lane data. Some control of the simulation is given by two more bits, ``DispFinish`, ``DispStop`, which activate `$finish` and `$stop` verilog system task calls. An example `ContDisp.hex` file, which enables the TL, DL and PL layers at time zero, and calls `$finish` at cycle 999999999, is shown below:

```
//
// ,--> 7 - 4:   +8      +4      +2      +1
// |,-> 3 - 0:   unused  DispPL   DispDL   DispTL
// || ,-> Time (clock cycles, decimal)
// || |
// || |
// 70 000000000000
// 02 009999999999
```

Below are shown three sample sections of output with only the transaction layer on, then data link layer added and finally the physical layer.

Transaction Layer Only

```
PCIEU1: TL MEM read req Addr=130476dc48383000 (64) RID=0000 TAG=00 FBE=1111 LBE=1111 Len=002
PCIEU1: Traffic Class=0, TLP Digest
PCIEU1: TL Good ECRC (fc9cae82)
PCIED0: TL Completion with Data Successful CID=0008 BCM=0 Byte Count=008 RID=0000 TAG=00 Lower Addr=00
PCIED0: Traffic Class=0, TLP Digest, Payload Length=0x00000002 DW
PCIED0: fedcba89 76543210
PCIED0: TL Good ECRC (af090c09)
```

Transaction and Data Link Layer

```
PCIEU1: DL Sequence number=11
PCIEU1: ...TL MEM read req Addr=130476dc48383000 (64) RID=0000 TAG=00 FBE=1111 LBE=1111 Len=002
PCIEU1: ...Traffic Class=0, TLP Digest
PCIEU1: ...TL Good ECRC (fc9cae82)
PCIEU1: DL Good LCRC (c235be07)
PCIEU1: DL Ack seq 11
PCIEU1: DL Good DLLP CRC (5893)
PCIED0: DL Sequence number=0
PCIED0: ...TL Completion with Data Successful CID=0008 BCM=0 Byte Count=008 RID=0000 TAG=00 Lower Addr=00
PCIED0: ...Traffic Class=0, TLP Digest, Payload Length=0x00000002 DW
PCIED0: ...fedcba89 76543210
PCIED0: ...TL Good ECRC (af090c09)
PCIED0: DL Good LCRC (eed0266)
PCIED0: DL Ack seq 0
PCIED0: DL Good DLLP CRC (b362)
```

Transaction, Data Link and Physical Layer

```
PCIEU1: {STP
PCIEU1: 00 0b 20 00 80 02 00 00 00 ff 13 04 76 dc 48 38 30 00 fc 9c ae 82
PCIEU1: c2 35 be 07
PCIEU1: END}
PCIEU1: ...DL Sequence number=11
PCIEU1: .....TL MEM read req Addr=130476dc48383000 (64) RID=0000 TAG=00 FBE=1111 LBE=1111 Len=002
PCIEU1: .....Traffic Class=0, TLP Digest
PCIEU1: .....TL Good ECRC (fc9cae82)
PCIEU1: ...DL Good LCRC (c235be07)
PCIED0: {SDP
PCIED0: 00 00 00 0b 58 93
PCIED0: END}
PCIEU1: ...DL Ack seq 11
PCIEU1: ...DL Good DLLP CRC (5893)
PCIED0: {STP
PCIED0: 00 00 4a 00 80 02 00 08 00 08 00 00 00 00 fe dc ba 89 76 54 32 10
PCIED0: af 09 0c 09 ee ed 02 66
PCIED0: END}
PCIED0: ...DL Sequence number=0
PCIED0: .....TL Completion with Data Successful CID=0008 BCM=0 Byte Count=008 RID=0000 TAG=00 Lower Addr=00
PCIED0: .....Traffic Class=0, TLP Digest, Payload Length=0x00000002 DW
PCIED0: .....fedcba89 76543210
PCIED0: .....TL Good ECRC (af090c09)
PCIED0: ...DL Good LCRC (eed0266)
```

```

PCIEU1: {SDP
PCIEU1: 00 00 00 00 b3 62
PCIEU1: END}
PCIED0: ...DL Ack seq 0
PCIED0: ...DL Good DLLP CRC (b362)

```

Two key points to note on the output; firstly, as each 'lower' layer is switched on, the layers 'above' are indented to make them easier to scan. Secondly, the up and down links are marked as PCIEU and PCIED respectively, along with the node number, allowing data to be extracted for one direction if desired. However, at the data link layer, acknowledge packets (Ack and Nak DLLPs) are associated with the *opposite* link from which they are issued, so they can be associated with the transaction which they refer to (i.e. their sequence number match). This is *not* true of completion data returning after a request, as this level effectively sits above the link.

Protocol Checking

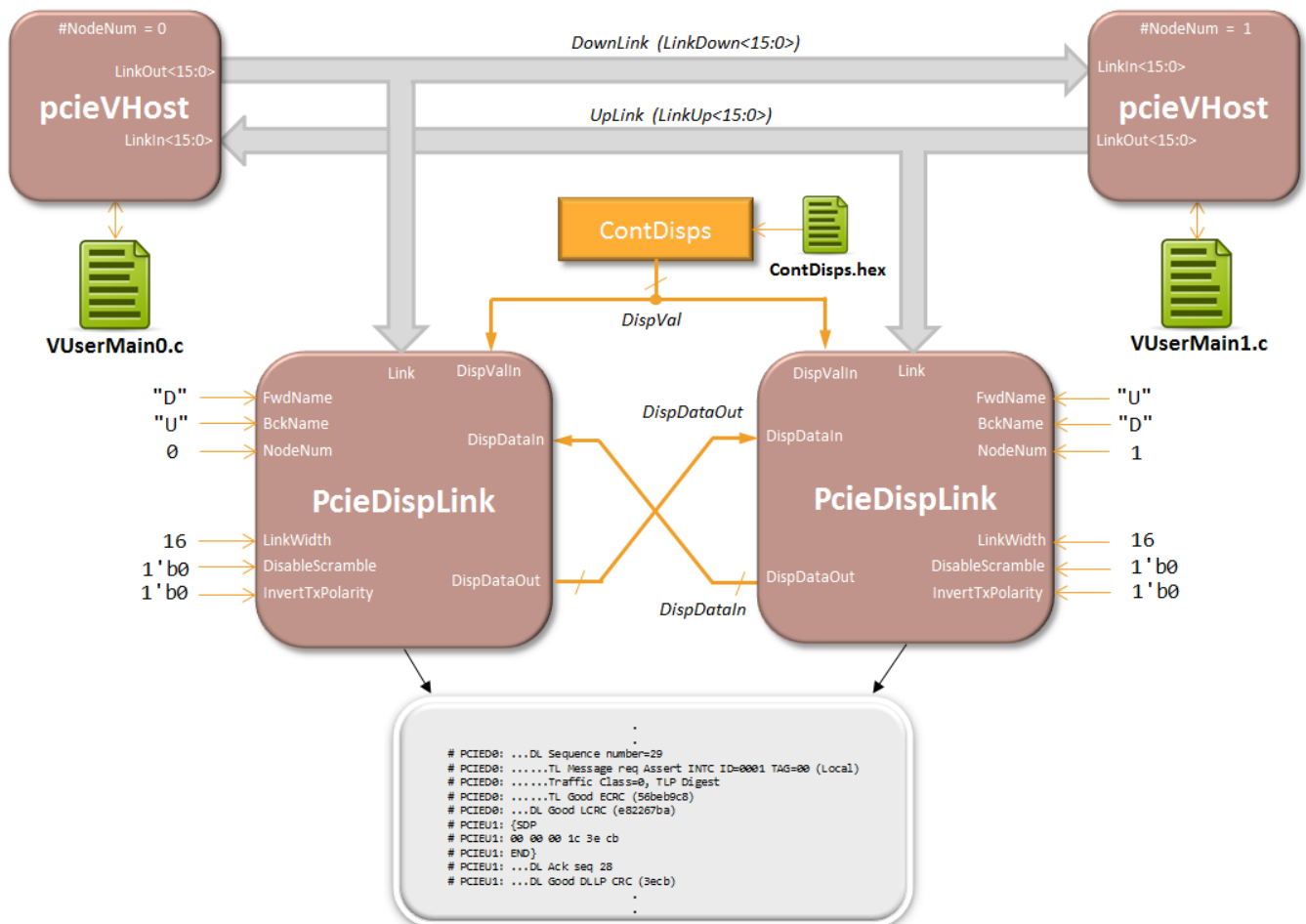
As mentioned above, the PcieDispLink checking of PCIe protocols is not comprehensive, and should not be used as sign off criteria, where a third party 'VIP' module should be used. However, it does check many compliance checklist specifications, and a summary is given below.

- Valid 10b encodings
- Correct running disparity
- Correctly formatted packets
- Reserved fields are 0
- CRCs checked
- Crossing of 4K boundaries
- Reuse of tags
- Valid completion cross referencing

In general terms, what is not covered is compliance with limitations set in the configuration space, ordering rules, and other 'higher level' considerations.

Test Environment

Included in the package is an example test environment that connects two pcieVHost components back to back, and hooks up two PcieDispLink monitors to the up and down links. The configuration is shown in the diagram below.



This example environment is simply meant to illustrate the usage of the various components, and how they are connected up. Two simple test programs `VUserMain0()` and `VUserMain1()` are written to exercise the PCIe link, with the `VUserMain1` code being fairly passive, and various transaction types output from `VUserMain0()`. The whole environment is for a 16 lane interface, and user wide lanes (i.e. unserialised 10 bit codes), for speed of simulation.

The link displays have additional ports, apart from the link inputs and `ContDisp` control. The node number is 0 and 1, where this matches the node number of the `pcieVHost`'s `LinkOut`—one for each host instantiated. The `FwdName` and `BckName` is a string—in this case "D" and "U", where each `PcieDispLink` has the opposite from its counterpart, with node 0 being the 'root', and its `LinkOut` being the downlink. The three other ports, `LinkWidth`, `DisableScramble` and `InvertTxPolarity` are set to constants, as shown. Obviously, in a proper test environment, these can be connected to state that reflects the expected settings if, for a given test say, scrambling were turned off, or the outputs inverted.

Download

The `pcieVHost` is available for download on [github](#). It uses the Virtual processing element `VProc`, which can also be downloaded from [github](#). These two components must be installed with their own top level directories (`VProc` and `pcieVHost`) in a common directory, in order to work 'out of the box'. If the `VProc` component is located elsewhere, then update the `VPROC_TOP` variable in the two `makefile` files, located at `pcieVHost/lib` (for the C compilation) and `pcieVHost/verilog/test` (for the top level test simulation) to the appropriate location, either as an absolute path, or relative to the `pcieVHost` directories.

Related Documents

- [Virtual Processor](#)
- [PCI Express Base Specification 1.1](#)

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