HAOYU HAN

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EDUCATION

University of Science and Technology of China (USTC)

09 / 2020 - 07 / 2024(expected)

B.S., Major in Information and Computational Science(Computational Math)

Overall GPA: 4.02/4.30

Relevant core courses: Mathematical Analysis(A+), Data Structures and Database(A+), Differential Equations(A+), Linear Algebra, Numerical analysis(A+), Numerical algebra(A+), Finite Element Method, Computer Graphics(A+), Deep Learning

Harvard University 07/2023 - 12/2023

Visiting intern in Computational Robotics Lab, advised by Professor Heng Yang.

RESAERCH EXPERIENCE

Computation and Analysis on Optimal Control of Pendulum

Harvard University

Individual Contributor Advisor: Prof. Heng Yang

August 2023 - Present

- The first Successfully calculated the cost-to-go function of the pendulum with an HJB error under 1e-4, both with and without control constraints, employing a novel contour line methodology.
- · Discovered a non-smooth spiral line in the cost-to-go function, meticulously calculated its geometry, and rigorously proved its existence.
- · Revealing a 'discontinuous' line in certain regions, exhibiting a $\frac{1}{x}$ rate of increase
- · Compared with other optimal cost-to-go functions, achieved superior results, and further guided the network to attain enhanced performance.

Residual Dynamics and Observer Design for Robot Bee

Harvard University

Co-Contributor Advisor: Prof. Heng Yang

July 2023 - Present

- · Transformed the dynamics of various systems including cartpole, arcbot, and 3D rigid-body into high-gain standard form, and successfully implemented the high-gain observer
- · Established a tighter bound for the high-gain observer and demonstrated its superior performance effectively.
- · Proved an error bound for residual dynamics through network analysis.
- · Conducted experiments on real robots and demonstrated that the observer error adhered to the established bound.

Cloth Shadow Art USTC

Indivisual Contributor Advisor: Prof. Ligang Liu

March 2023 - Present

- · Aimed at using differential simulation to design a square fabric with a arbitrary hole in it. Optimized the hole such that, under certain given inputs (e.g., control or wind), the dynamic shape of the hole emulates a cartoon character.
- · Implemented the Finite Element Method (FEM) for cloth simulation, incorporating StVK, ARAP, and bending energy models. The first computed the full Hessian, including the differentiation of 3D-2D projection.
- Implemented various simulation methods including Implicit Euler, Explicit Euler, Projective Dynamics (PD), PBD. Conducted a comparative analysis among them, concluded that FEM is the most authenticity.
- · optimized a simple example of a waving wing.

PROJECTS

· Reproduce several papers such as possion image edit, ARAP/ASAP, fast simulation, path-tracing, shader, etc.

Reproduce Several projects in computer vision

USTC

- · Reproduce several papers such as camera calibration, video stabilization, image stitching, Nerf etc.
- · Did a survey on image generation through GAN.

Kaggle competition: Natural Language Processing with Disaster Tweets

USTC

- · Successfully fine-tuned the BERT model for disaster verification tasks with rank 134/1289.
- · Applied parameter freezing in conjunction with Ensemble Learning for enhanced model performance.

SKILLS

English TOEFL 101(R27/L26/S23/W25)

GRE math subject 910(94%)

Computer Languages C, C++, C#, Java

Tools Later Text, Matlab, Mathematica, pytorch, Unity, QT, OpenCV, MarkDown

AWARDS

China National Scholarship(highest Scholarship from Ministry of Education of China)09/2022The China Optics Valley Scholarship09/2023Outstanding Student Scholarship Grade 2(Top 10%)09/2021Endeavor Scholarship09/2021Outstanding Freshman Scholarship09/2020

EXTRACURRICULAR

member of USTC Programming club , USTC paper folding club member of Student Union of School of the Gifted Young DIY an AR glass and a light cube

09/2020 - Present

09/2020 - 09/2021

09/2020