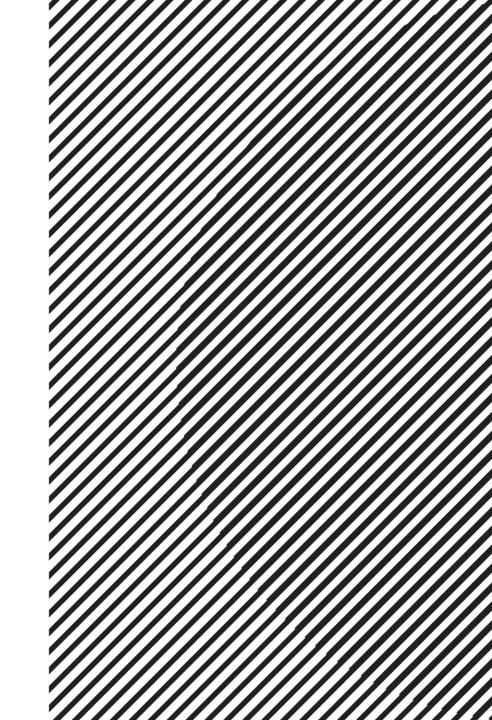
#### Linear Algebra

주재걸 고려대학교 컴퓨터학과





#### **Lecture Overview**

- Elements in linear algebra
- Linear system
- Linear combination, vector equation, Four views of matrix multiplication
- Linear independence, span, and subspace
- Linear transformation
- Least squares
- Eigendecomposition
- Singular value decomposition

#### Scalar, Vector, and Matrix

- 17521: SULP 1 521
- Scalar: a single number  $s \in \mathbb{R}$  (lower case), e.g., 3.8
- Vector: an ordered list of numbers, e.g.  $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \in \mathbb{R}^n$  (boldface, lower-case), e.g.,  $\mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} \in \mathbb{R}^3$  3234461 / 324461 Matrix: a two-dimensional array of numbers, e.g.  $A = \begin{bmatrix} 1 \\ 3 \end{bmatrix} \in \mathbb{R}^{3 \times 2}$  (capital letter)

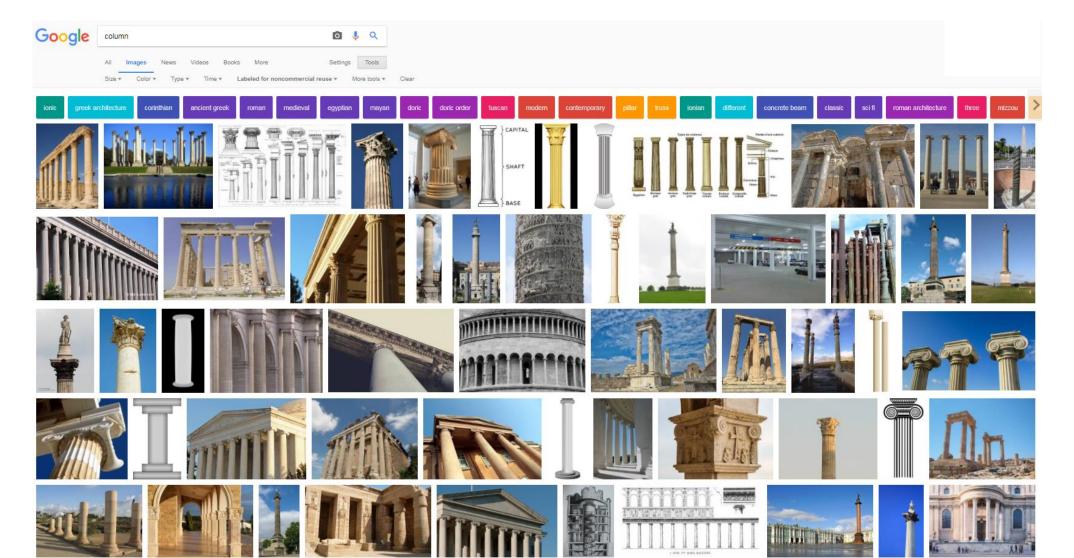
lower-case), e.g., 
$$\mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} \in \mathbb{R}^3$$
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- - (capital letter)
    - Matrix size: 3 × 2 means 3 rows and 2 columns
    - Row vector: a horizontal vector
  - Column vector: a vertical vector



# Column is Vertical Vector (Don't be Confused!)

(column: 71号(知至)





#### **Column Vector and Row Vector**

• A vector of *n*-dimension is usually a column vector, i.e., a matrix of the size  $n \times 1$ 

• 
$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \in \mathbb{R}^n = \mathbb{R}^{n \times 1}$$

Thus, a row vector is usually written as its transpose, i.e.,

$$\bullet \mathbf{x}^{T} = \begin{bmatrix} x_{1} \\ x_{2} \\ \vdots \\ x_{n} \end{bmatrix}^{T} = \begin{bmatrix} x_{1} & x_{2} & \cdots & x_{n} \end{bmatrix} \in \mathbb{R}^{1 \times n}$$

$$\overset{(a)}{=} \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}^{T} = \begin{pmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{pmatrix}$$

$$(m,n) \rightarrow (n,m)$$

#### **Matrix Notations**

- $A \in \mathbb{R}^{n \times n}$ : Square matrix (#rows = #columns)
  - e.g.,  $B = \begin{bmatrix} 1 & 6 \\ 3 & 4 \end{bmatrix}$
- $A \in \mathbb{R}^{m \times n}$ : Rectangular matrix (possible: #rows  $\neq$  #columns)
- e.g.,  $A = \begin{bmatrix} 1 & 6 \\ 3 & 4 \\ 5 & 2 \end{bmatrix}$   $A^T$ : Transpose of matrix (mirroring across the main diagonal)
  - e.g.,  $A^T = \begin{bmatrix} 1 & 3 & 5 \\ 6 & 4 & 2 \end{bmatrix}$
- $A_{ij}:(i,j)$ -th component of A, e.g.,  $A_{2,1}=3 \rightarrow i$
- $A_{i::}: i$ -th row vector of A, e.g.,  $A_{2::}=\begin{bmatrix}3&4\end{bmatrix} \rightarrow i$
- $A_{:,i}$ : i-th column vector of A, e.g.,  $A_{:,2} = \begin{bmatrix} 6 \\ 4 \\ 2 \end{bmatrix} \rightarrow \mathfrak{R}$

## **Vector/Matrix Additions and Multiplications**

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- C = A + B: Element-wise addition, i.e.,  $C_{ij} = A_{ij} + B_{ij}$ 
  - A, B, C should have the same size, i.e.,  $A, B, C \in \mathbb{R}^{m \times n}$
- ca, cA: Scalar multiple of vector/matrix ಆ ಕೆಲ್ ರಕ್ಷಣೆ

• e.g., 
$$2\begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 4 \\ 2 \end{bmatrix}$$
,  $2\begin{bmatrix} 1 & 6 \\ 3 & 4 \\ 5 & 2 \end{bmatrix} = \begin{bmatrix} 2 & 12 \\ 6 & 8 \\ 10 & 4 \end{bmatrix}$ 

• C = AB: Matrix-matrix multiplication, i.e.,  $C_{ij} = \sum_{k} A_{i,k} B_{k,j}$ 

• e.g., 
$$\begin{bmatrix} 1 & 6 \\ 3 & 4 \\ 5 & 2 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 2 & 1 \end{bmatrix} = \begin{bmatrix} 13 & 5 \\ 11 & 1 \\ 9 & -3 \end{bmatrix}$$
,  $\begin{bmatrix} 3 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 14 \end{bmatrix}$ ,  $\begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 3 & 6 \\ 5 & 10 \end{bmatrix}$ 

Size: 
$$(3 \times 2)(2 \times 2) = 3 \times 2$$
,

Size: 
$$(3 \times \cancel{2})(\cancel{2} \times 2) = 3 \times 2$$
,  $(1 \times \cancel{3})(\cancel{3} \times 1) = 1 \times 1$ ,  $(3 \times \cancel{1})(\cancel{1} \times 2) = 3 \times 2$ 

### Matrix multiplication is NOT commutative

可处陷对

- $AB \neq BA$ : Matrix multiplication is NOT commutative.
- e.g., Given  $A \in \mathbb{R}^{2\times 3}$  and  $B \in \mathbb{R}^{3\times 5}$ , AB is defined, but BA is not even defined.
- What if BA is defined, e.g.,  $A \in \mathbb{R}^{2\times 3}$  and  $B \in \mathbb{R}^{3\times 2}$ ? Still, the sizes of  $AB \in \mathbb{R}^{2\times 2}$  and  $BA \in \mathbb{R}^{3\times 3}$  does not match, so  $AB \neq BA$ .
- What if the sizes of AB and BA match, e.g.,  $A \in \mathbb{R}^{2 \times 2}$  and  $B \in \mathbb{R}^{2 \times 2}$ ? Still in this case, generally,  $AB \neq BA$ .

• E.g., 
$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 5 & 6 \\ 7 & 8 \end{bmatrix} = \begin{bmatrix} 19 & 22 \\ 43 & 50 \end{bmatrix}$$

$$\begin{bmatrix} 5 & 6 \\ 7 & 8 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \begin{bmatrix} 23 & 34 \\ 31 & 46 \end{bmatrix}$$

#### **Other Properties**

- A(B+C)=AB+AC: Distributive
- A(BC) = (AB)C: Associative শুল খুন
- $(AB)^T = B^T A^T$ : Property of transpose