



GRENOBLE 19-23.09.2022

Hyperbolic Graph Representation Learning: A Tutorial

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Contents

1. INTRODUCTION (Min, 30 min)

- 1.1 An Overview of Graph Representation Learning
- 1.2 Brief Introduction of Riemannian Geometry
- 1.3 Motivation of Hyperbolic Graph Representation Learning

2. HYPERBOLIC GRAPH REPRESENTATION LEARNING (HGRL) (Menglin, 30 min)

- 2.1 Hyperbolic Shallow Models
- 2.2 Hyperbolic Neural Networks
- 2.3 Hyperbolic Graph Neural Networks

3. APPLICATIONS (Menglin, 45 min)

- 3.1 HGRL for Recommendation Systems
- 3.2 HGRL for Knowledge Graph
- 3.3 HGRL for other Applications

4. ADVANCED TOPICS (Min, 60 min)

- 4.1 Complex Structures
- 4.2 Evolving Interactions
- 4.3 Geometry-aware Learning
- 4.4 Trustworthy and Scalability



GRENOBLE 19-23.09.2022

1. INTRODUCTION

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4.3 Geometry-Aware Learning

4.4 Trustworthy and Scalability

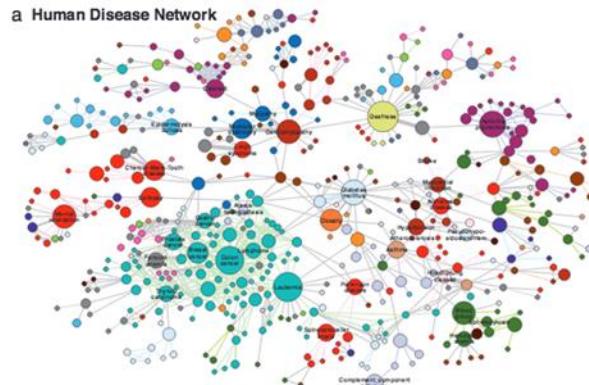
Graphs

Data available in the form of graphs are ubiquitous.

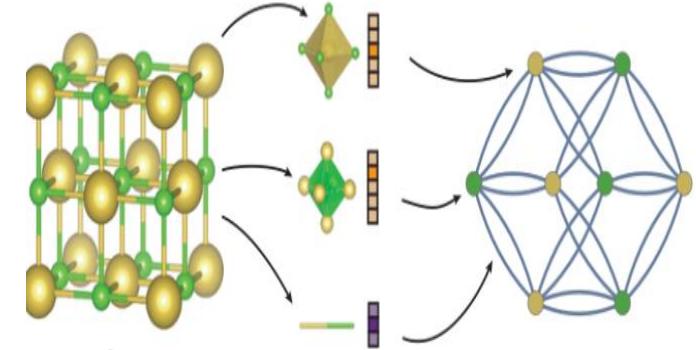
Social networks



Biology network



Atom network

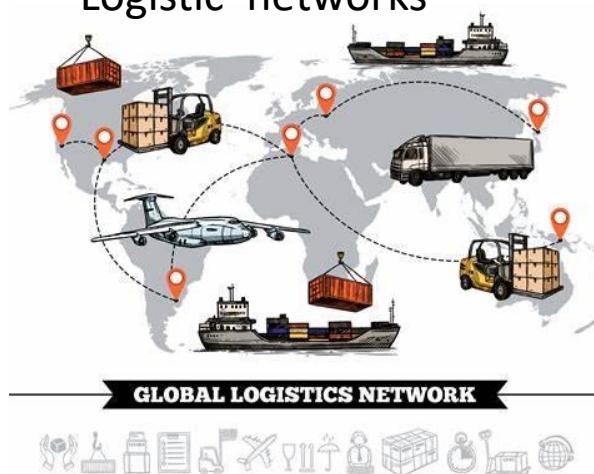


Financial networks

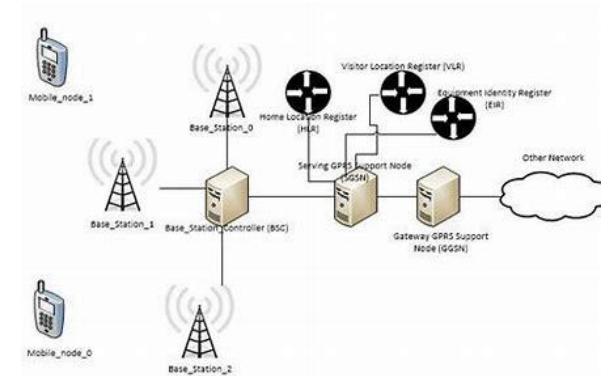


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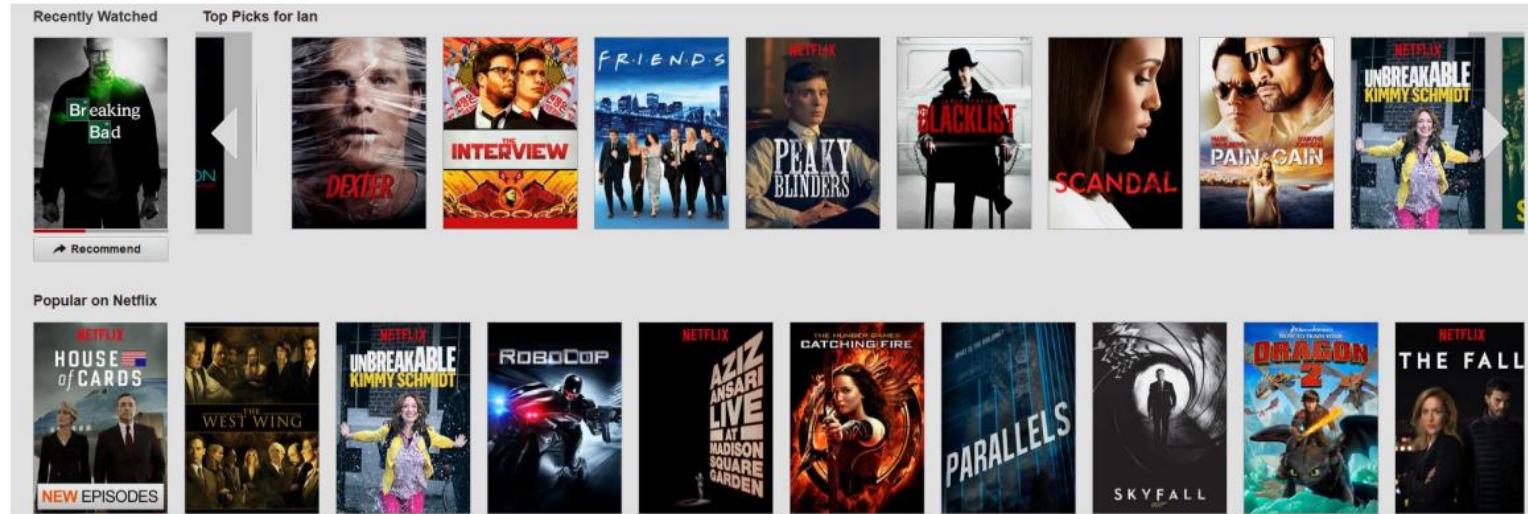
Logistic networks



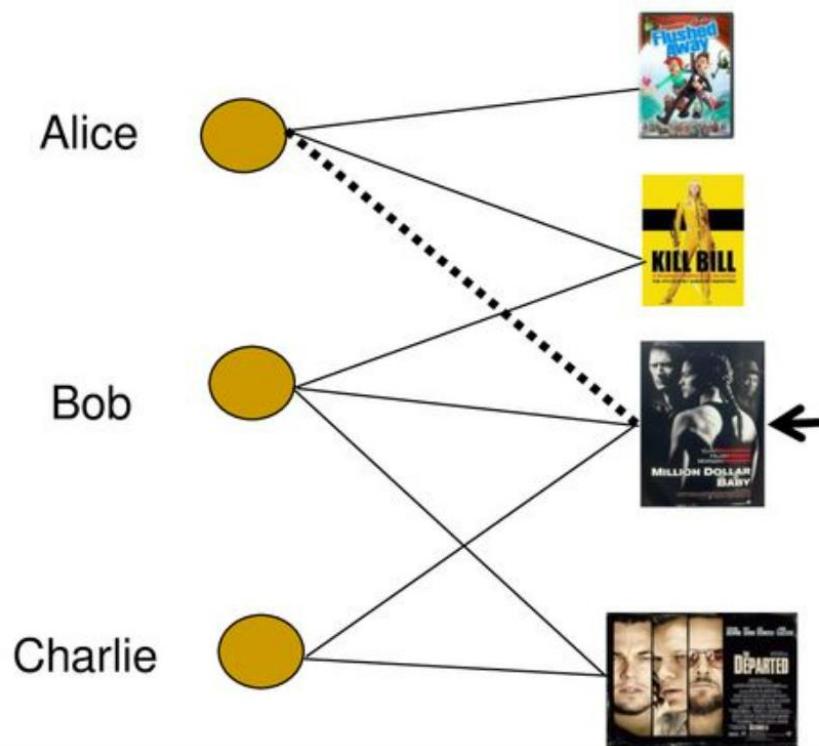
Telecom network



Recommender Systems

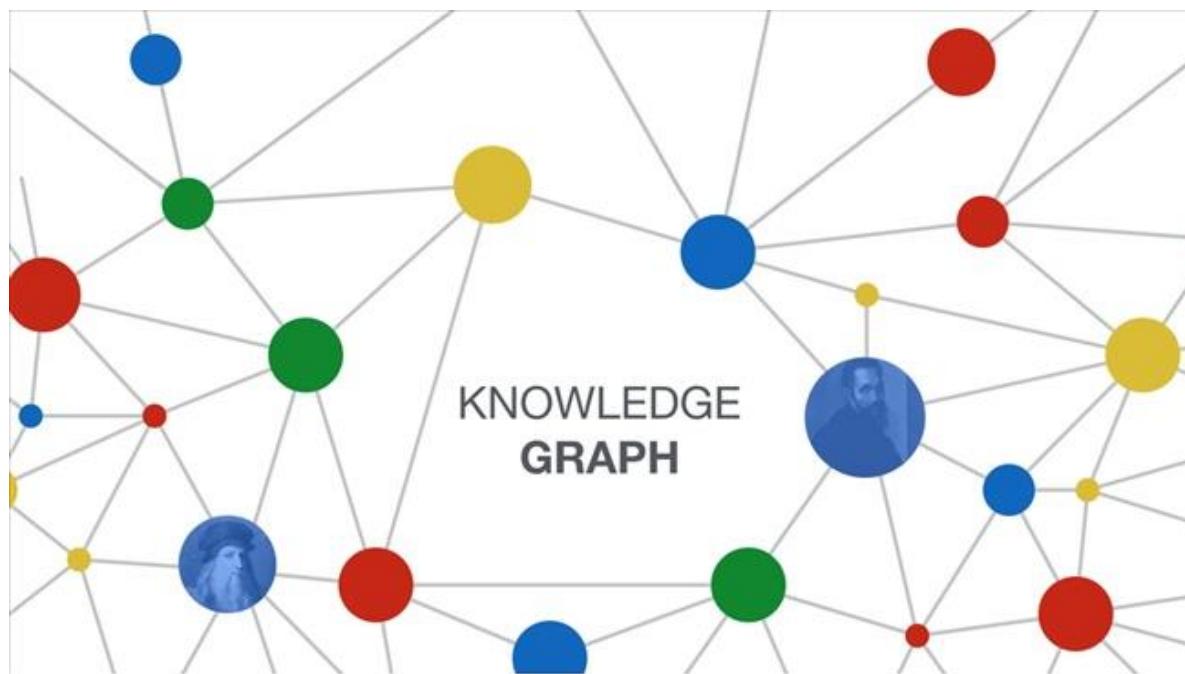


Link Prediction

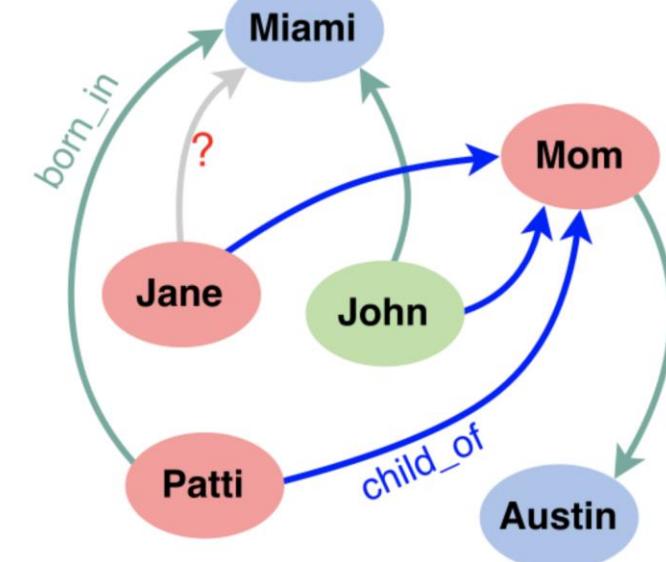


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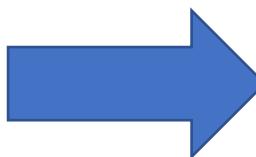
Knowledge Graph Completion



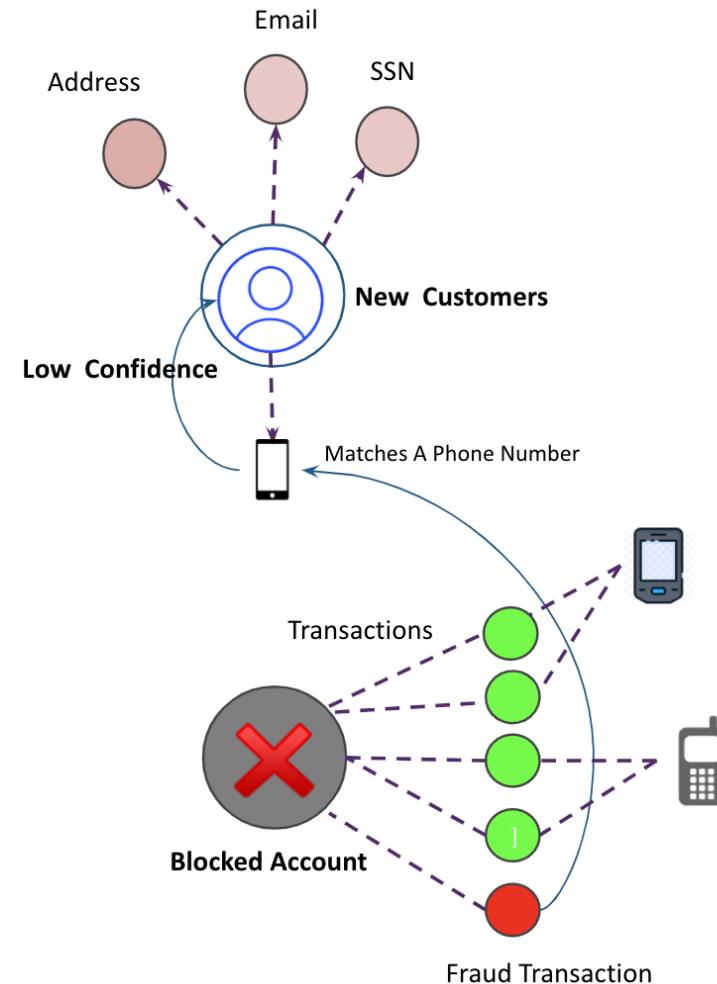
Link prediction



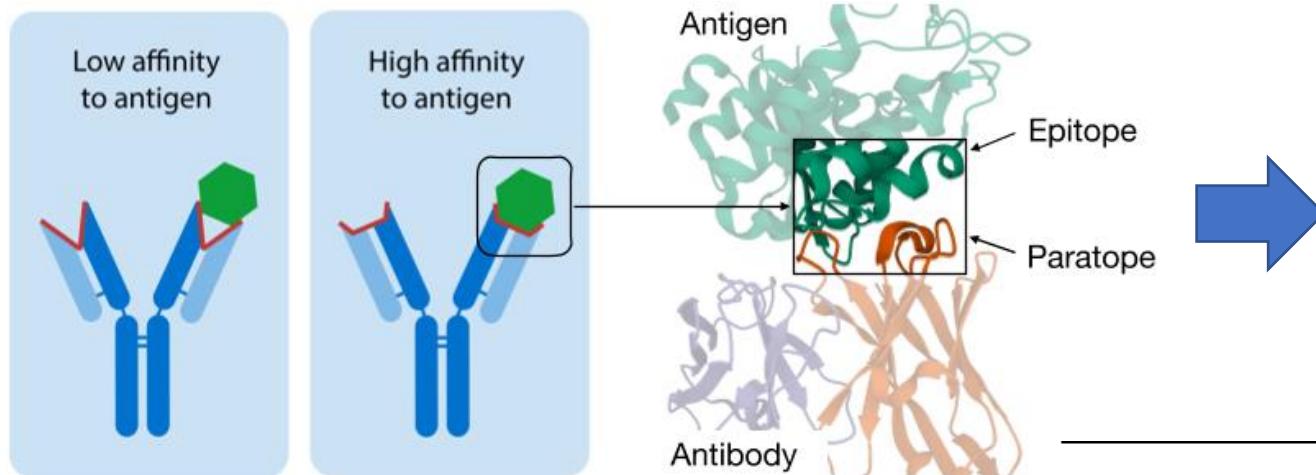
Fraud Detection



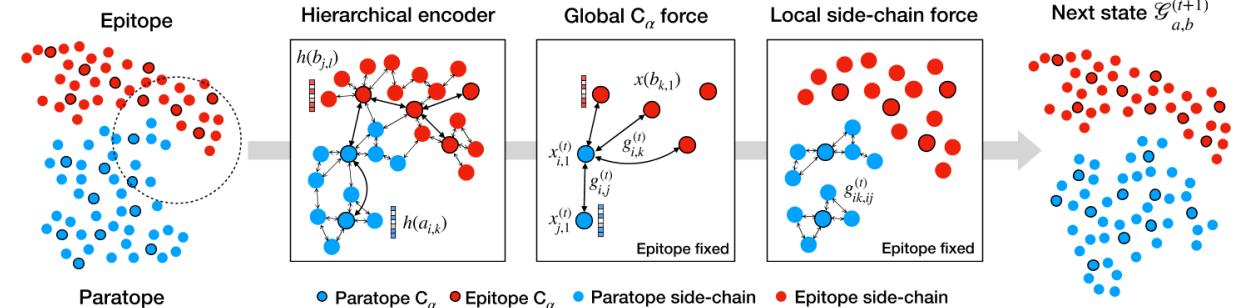
Link prediction,
community detection, etc.



Antibody-Antigen Docking and Design



Graph Generation Task



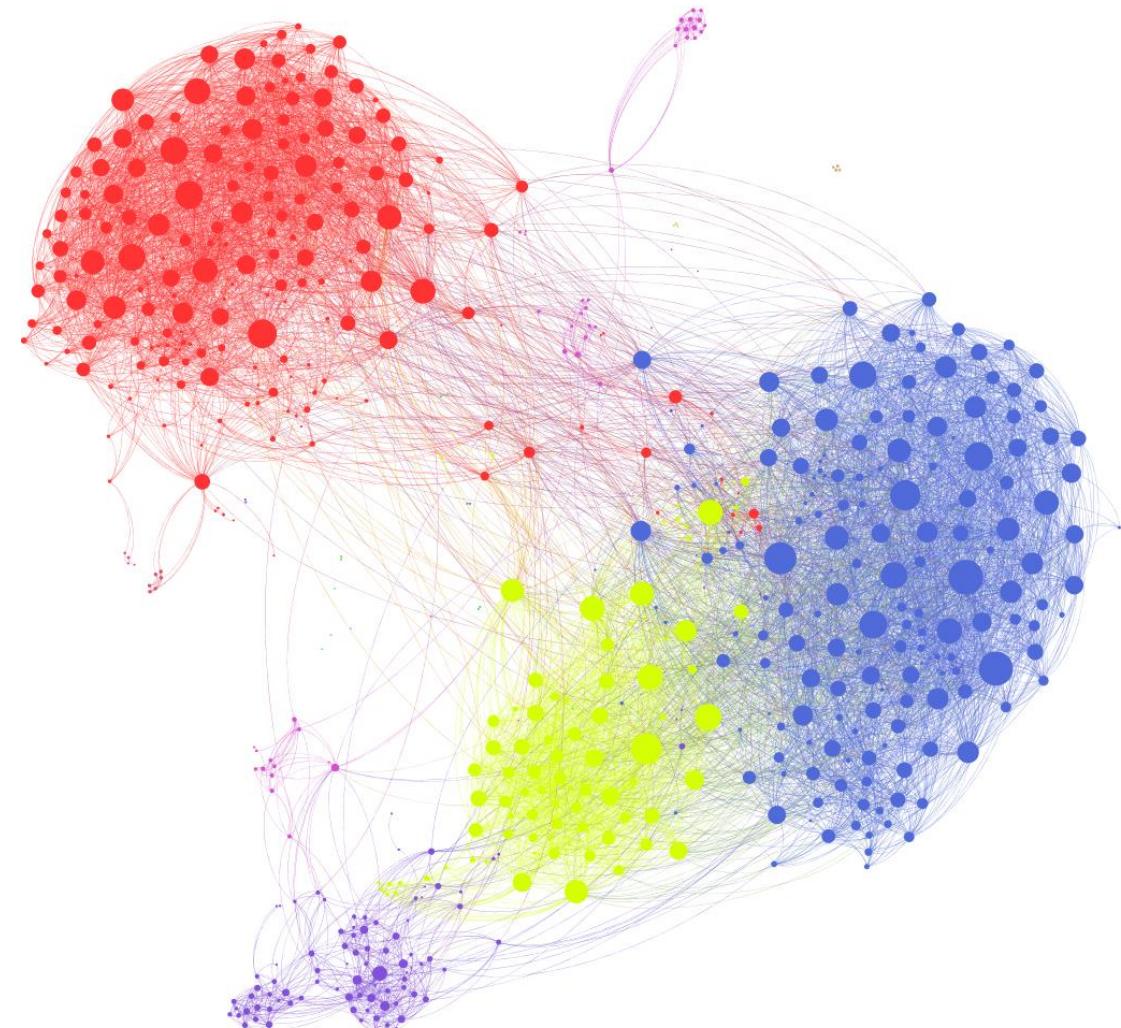
Graph Analysis and Learning

● Graph Analysis

- Degree distribution
- Graph diameter
- Shortest path length
- Sparseness
- Curvature
- Symmetry

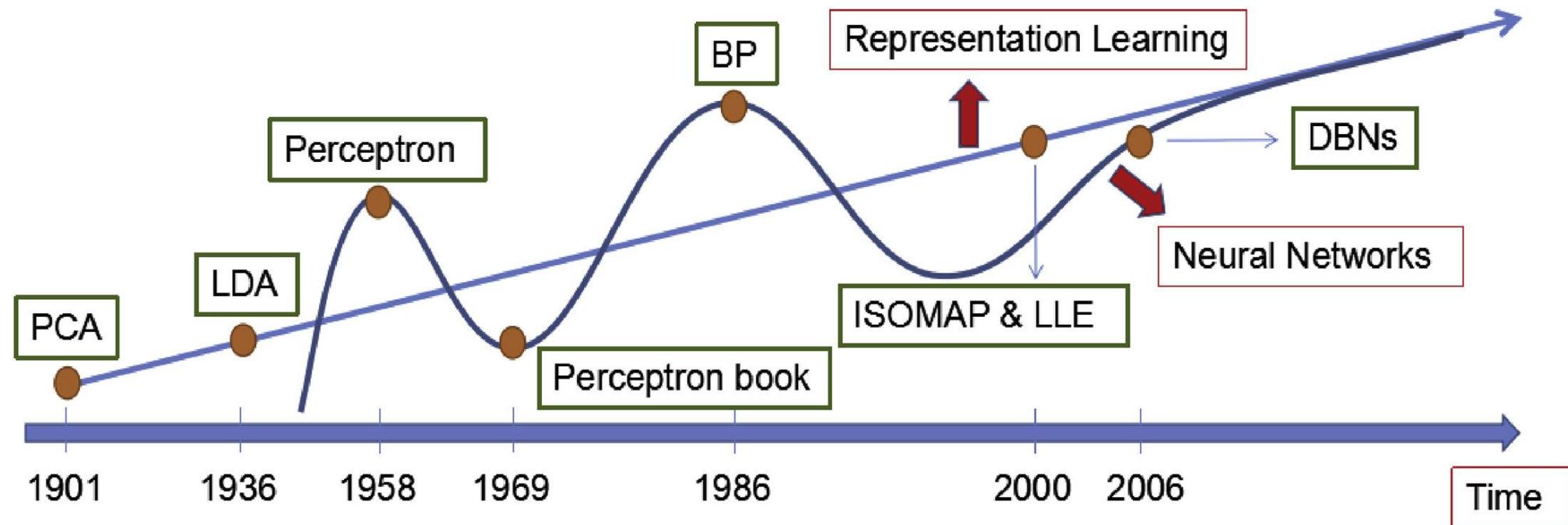
● Representation Learning

- Graph embedding
- Graph neural network



Representation Learning

“Can we automate the learning of useful features from raw data?”



“Deep learning algorithms seek to exploit the unknown structure in the input distribution in order to discover good representations, often at multiple levels, with higher-level learned features defined in terms of lower-level features”

Yoshua Bengio

Representation Learning on Graph

Graph Embedding



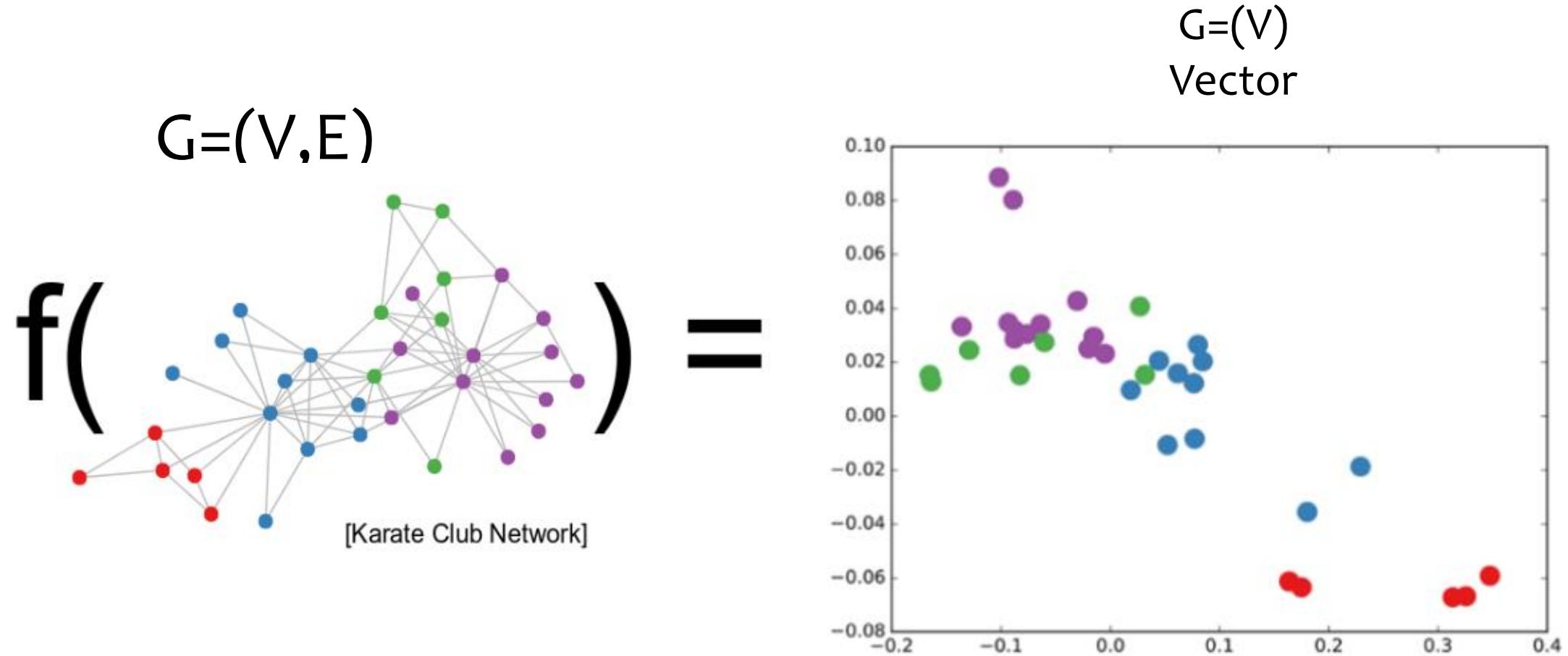
Graph Neural
Network

Representation Learning on Graph

Graph Embedding

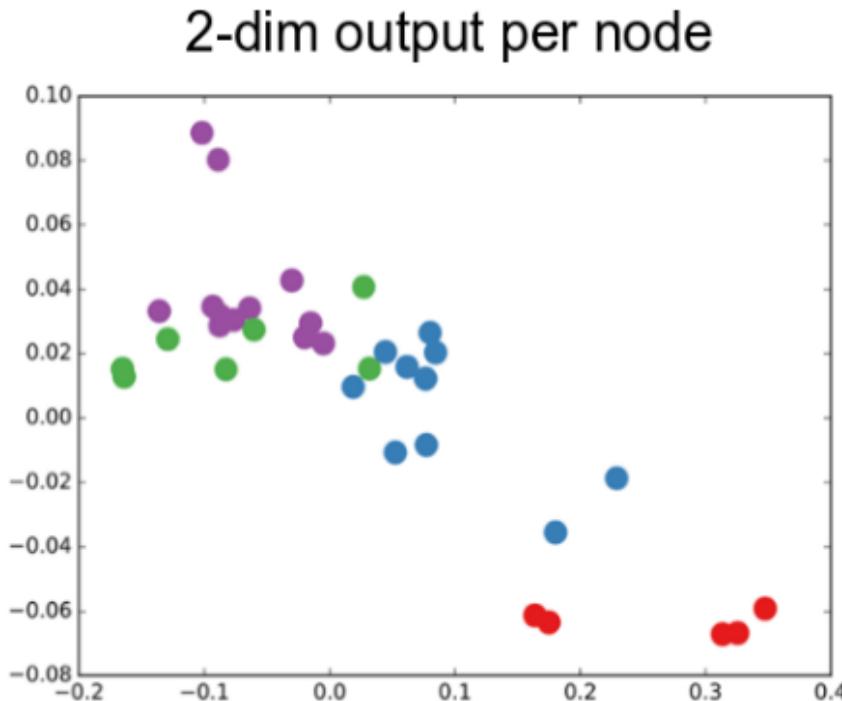
Graph Embedding

Projecting graph data into a continuum space while the graph properties are preserved.



Graph Embedding

Goal: Perform network inference in the low-dimensional vector space

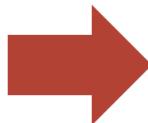


- Node importance
- Community detection
- Link prediction
- Node classification
- Network evolution
-

Graph vs Text

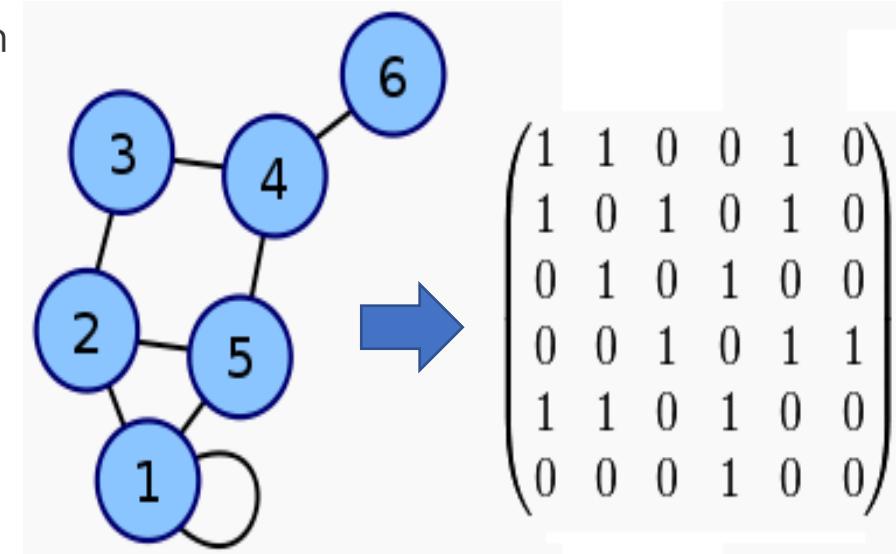
Adjacency List encoding of *edges* vs one-hot encoding of *text tokens*

Vocabulary:
Man, woman, boy,
girl, prince,
princess, queen,
king, monarch



	1	2	3	4	5	6	7	8	9
man	1	0	0	0	0	0	0	0	0
woman	0	1	0	0	0	0	0	0	0
boy	0	0	1	0	0	0	0	0	0
girl	0	0	0	1	0	0	0	0	0
prince	0	0	0	0	1	0	0	0	0
princess	0	0	0	0	0	1	0	0	0
queen	0	0	0	0	0	0	1	0	0
king	0	0	0	0	0	0	0	1	0
monarch	0	0	0	0	0	0	0	0	1

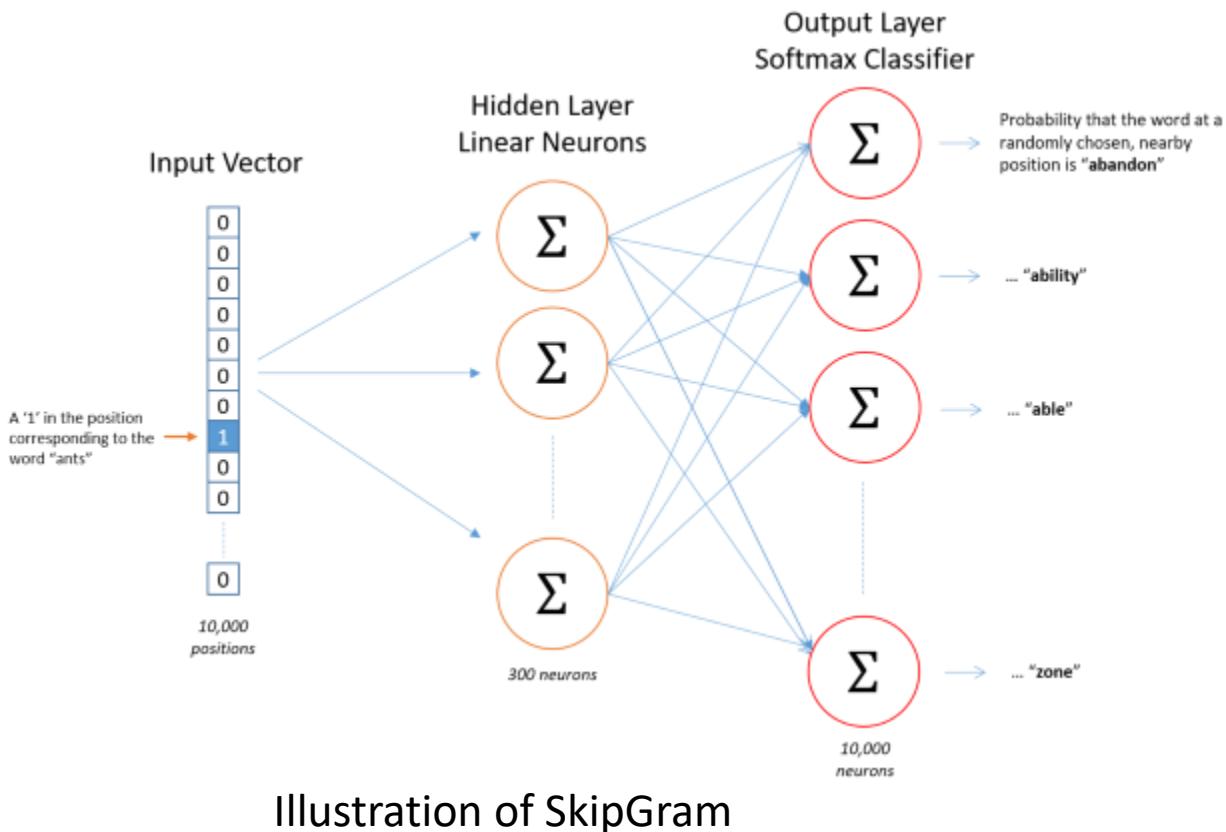
Each word gets
a 1×9 vector
representation



Representing Text

Learns a vector representation for each word that maximized the probability of that word given the previous word.

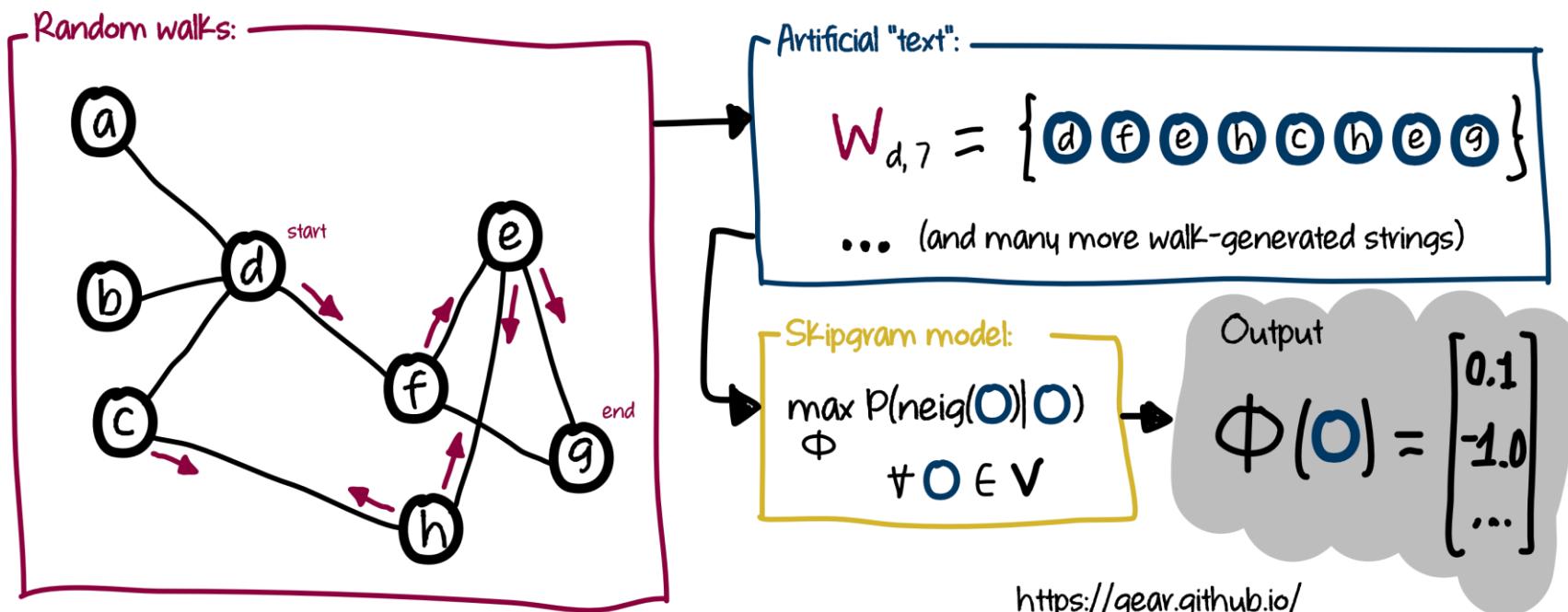
Input: one hot encoded vector



Output:
probability for
each word in
the corpus

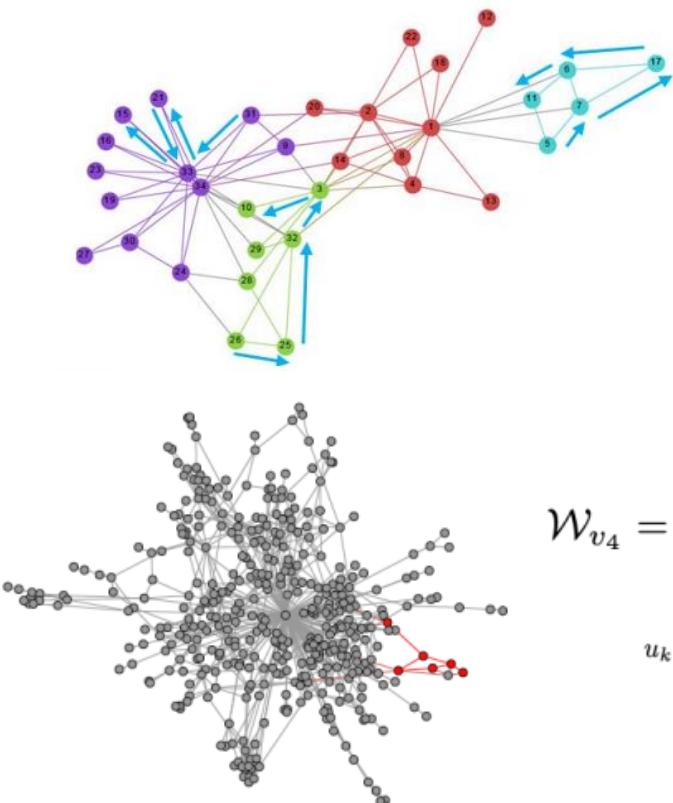
Representing Graph

- How should we represent a node in a graph mathematically?
- Can we mimic word embedding?
 - Treat each node treat as a word
 - Neighborhood around the node as the context window



Deep Walk

- Exploit truncated random walks to define neighborhoods of a node



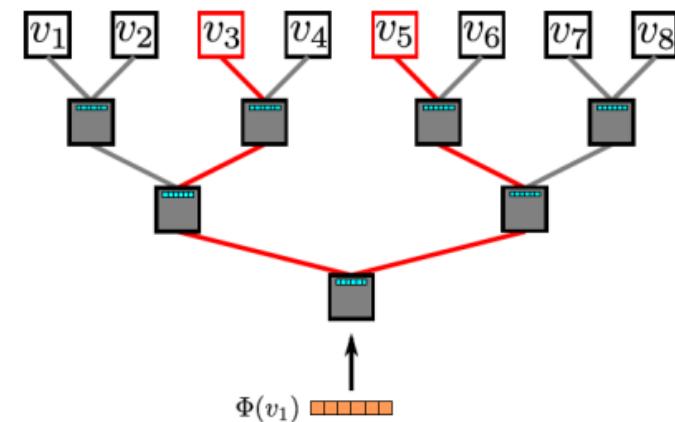
(a) Random walk generation.

Random Walks on Graph

- $V_{26} - V_{25} - V_{32} - V_3 - V_{10} \dots$
- $V_5 - V_7 - V_{17} - V_6 - V_{11} \dots$
- $V_{31} - V_{33} - V_{21} - V_{33} - V_{15}$

$$\mathcal{W}_{v_4} = \begin{bmatrix} 4 \\ 3 \\ 1 \\ 5 \\ 1 \\ \vdots \end{bmatrix} v_j \rightarrow \Phi^d_j$$

(b) Representation mapping.



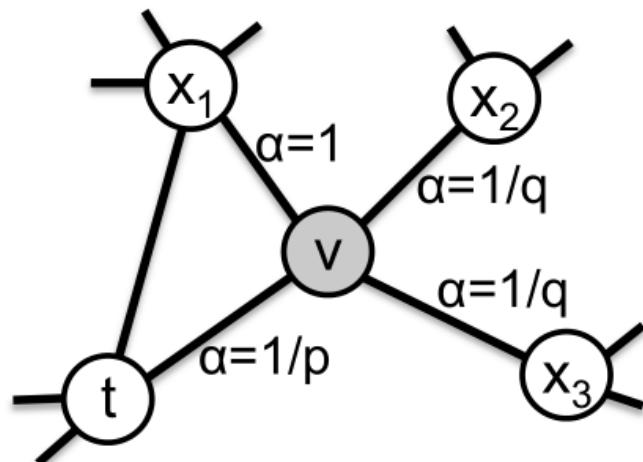
(c) Hierarchical Softmax.

Node2vec

- Generate representations of nodes in the graph via 2nd order (biased) random walk.

- Apply a **bias factor alpha** to reweigh the edge weights depending on the previous state

$$\alpha_{pq}(t, x) = \begin{cases} \frac{1}{p} & \text{if } d_{tx} = 0 \\ 1 & \text{if } d_{tx} = 1 \\ \frac{1}{q} & \text{if } d_{tx} = 2 \end{cases}$$



- Second order transition probability:

$$p(u|v, t) = \frac{\alpha_{pq}(t, u)w(u, v)}{\sum_{u' \in \mathcal{N}_v} \alpha_{pq}(t, u')w(u', v)}$$

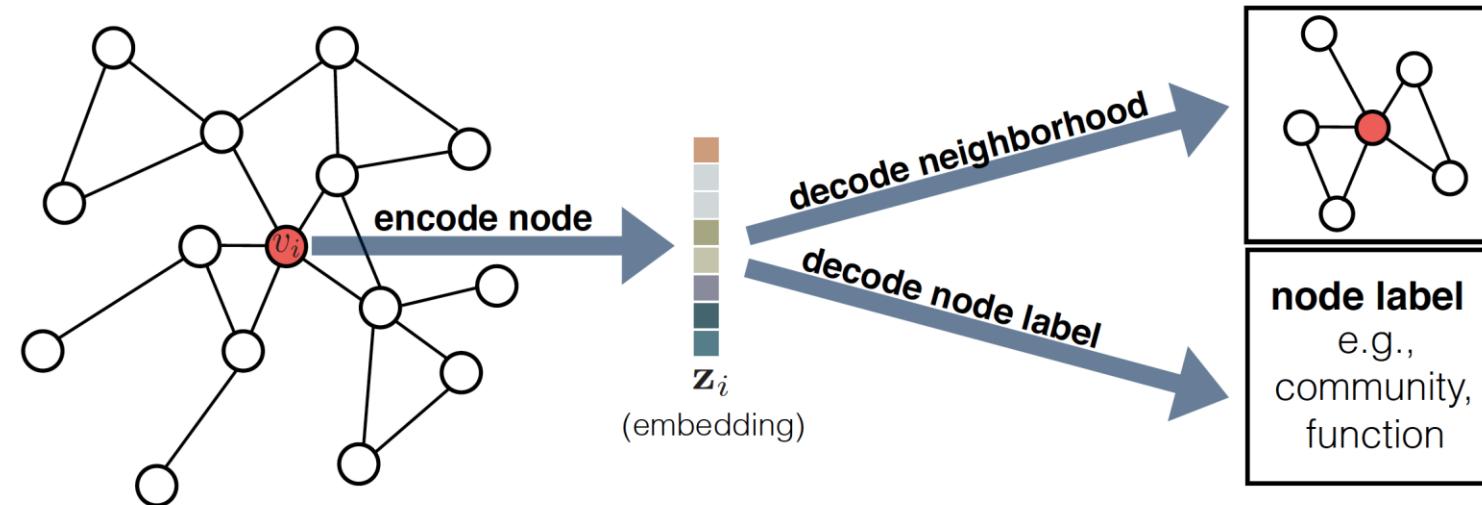
Graph Embedding Summary

- Many different methods:
 - Matrix Factorization
 - Random walk
 - Others

Category	Year	Published	Method	Time Complexity	Properties preserved
Factorization	2000	Science[26]	LLE	$O(E d^2)$	1 st order proximity
	2001	NIPS[25]	Laplacian Eigenmaps	$O(E d^2)$	
	2013	WWW[21]	Graph Factorization	$O(E d)$	
	2015	CIKM[27]	GraRep	$O(V ^3)$	1 – k^{th} order proximities
	2016	KDD[24]	HOPE	$O(E d^2)$	
Random Walk	2014	KDD[28]	DeepWalk	$O(V d)$	1 – k^{th} order proximities, structural equivalence
	2016	KDD[29]	<i>node2vec</i>	$O(V d)$	

Graph Embedding Summary

- Most techniques consist of:

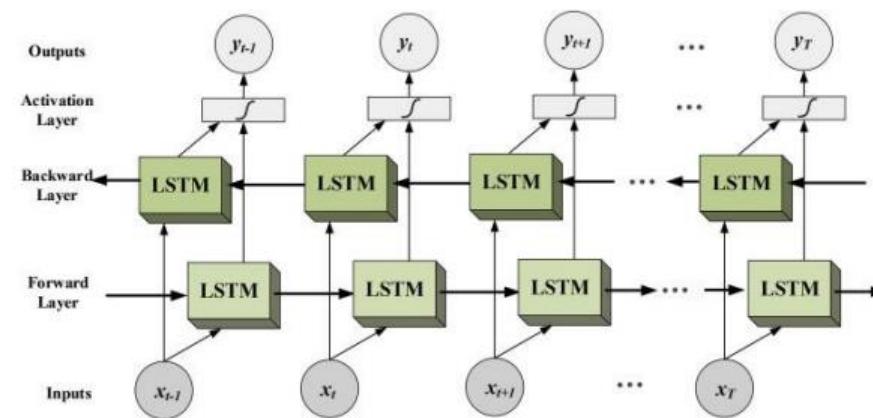
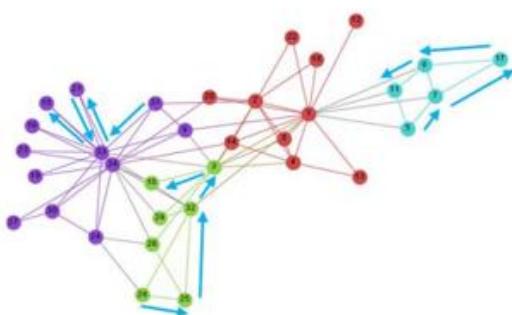
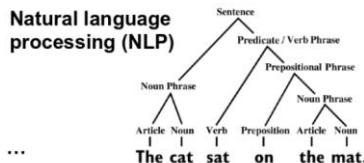
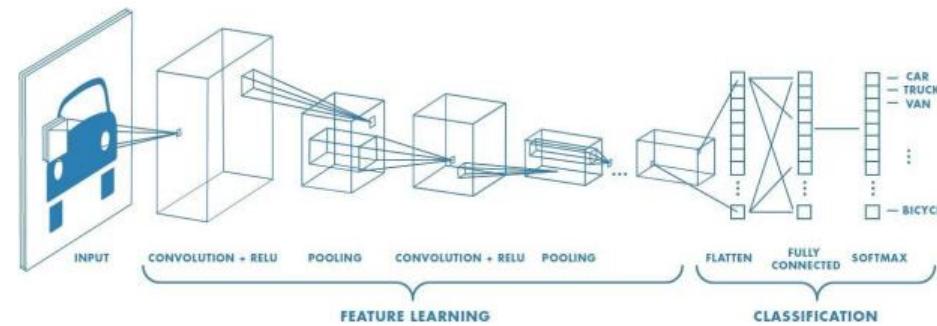


- A **pairwise similarity** function measures the similarity between nodes
- An **encoder function** to generate the node embedding
- A **decoder function** to reconstruct pairwise similarity
- A **loss function** to measure the quality of the pairwise reconstructions

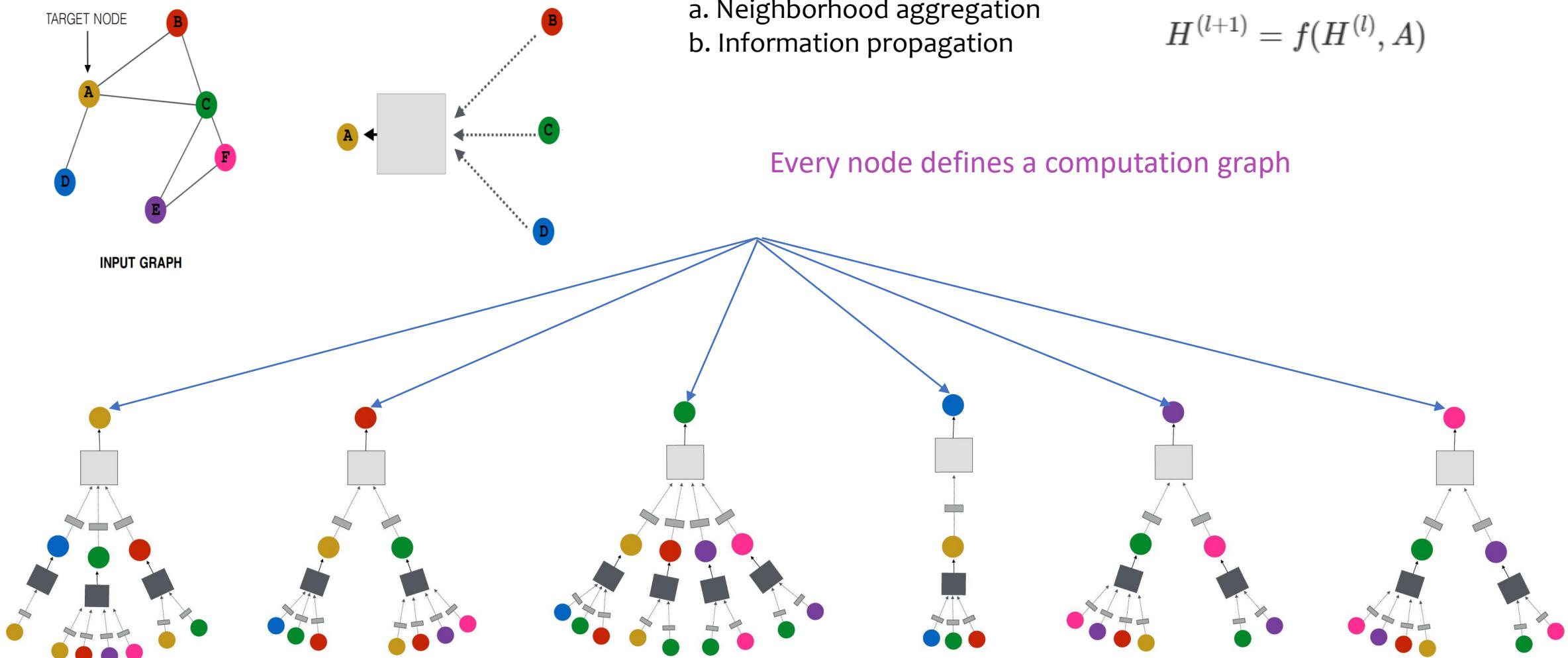
Graph Neural Network

Graph Neural Network

IMAGENET



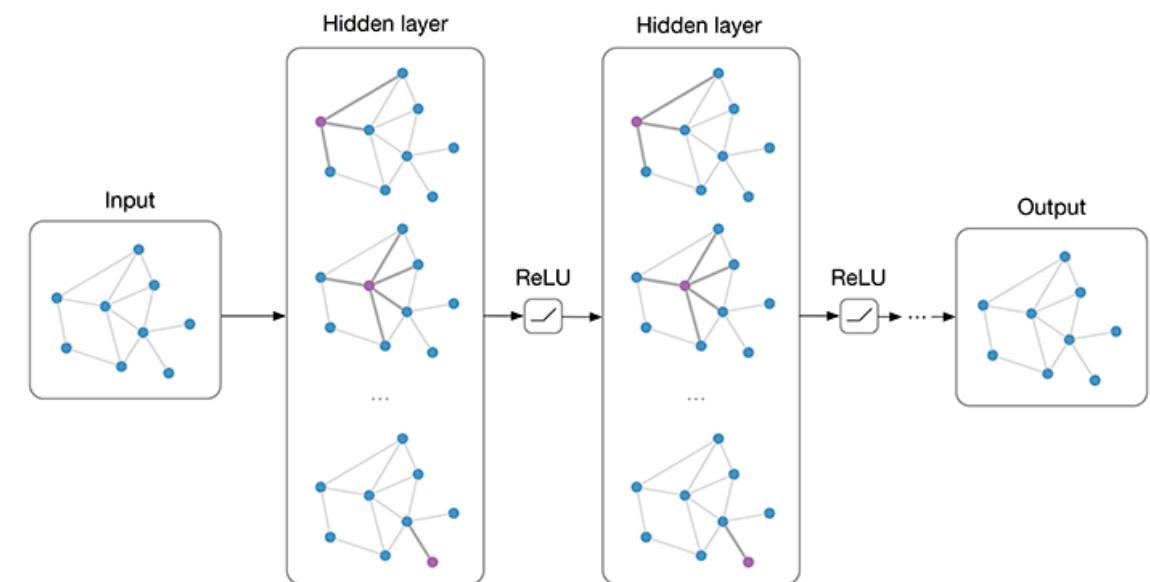
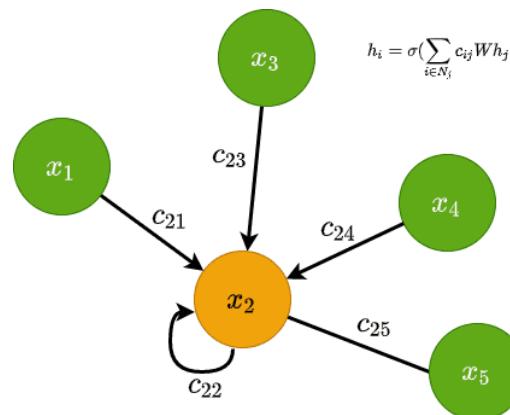
Graph Neural Network



GCN

- Deal with the representation of a graph in the spectral domain
- Aggregate info from neighborhood via the **normalized Laplacian matrix**

$$H^{(l+1)} = \sigma(\tilde{D}^{-\frac{1}{2}} \tilde{A} \tilde{D}^{-\frac{1}{2}} H^{(l)} W^{(l)})$$



- Spectral method & Transductive learning
 - Easy to apply
 - Conduct on the entire graph and computationally inefficient

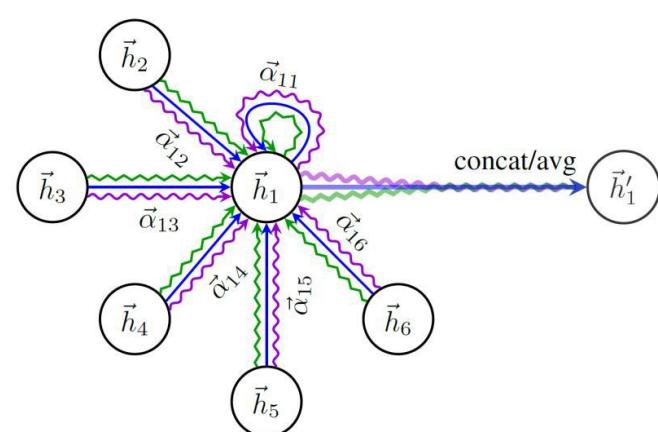
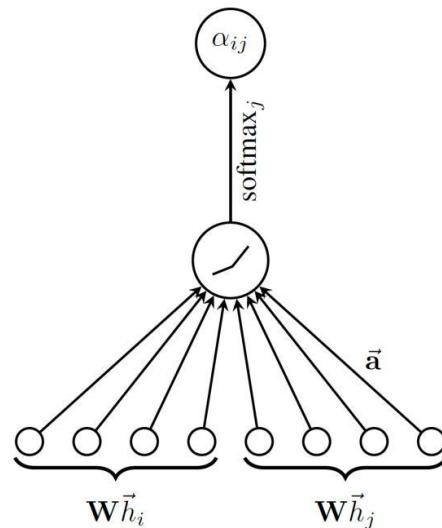
T. N. Kipf and M. Welling. Semi-supervised classification with graph convolutional networks. ICLR, 2017.

- Aggregate info from neighborhood via attention mechanism

$$a_{ij} = \text{attention}(h_i, h_j)$$

$$a_{ij} = \frac{\exp(a_{ij})}{\sum_{k \in N_i} \exp(a_{ik})}$$

$$h_i^{(l)} = \sigma \left(\sum_{j \in N_i} a_{ij} W h_j \right)$$

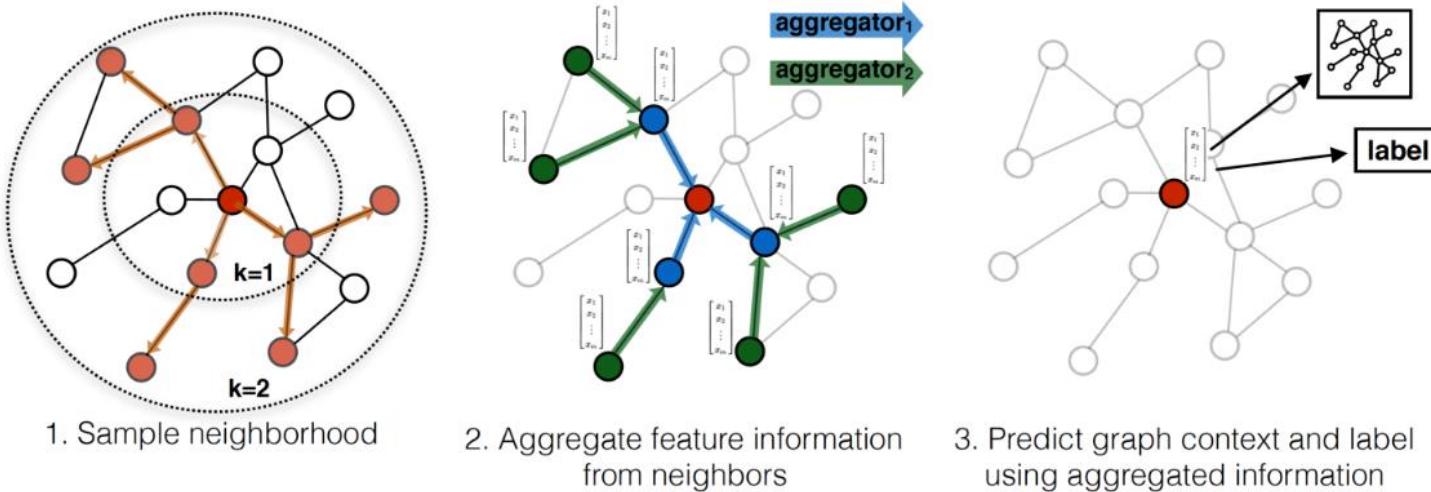


- Spatial method
- More flexible to handle multisource graph inputs

Veličković, Petar, et al. "Graph Attention Networks." ICLR. 2018.

GraphSAGE

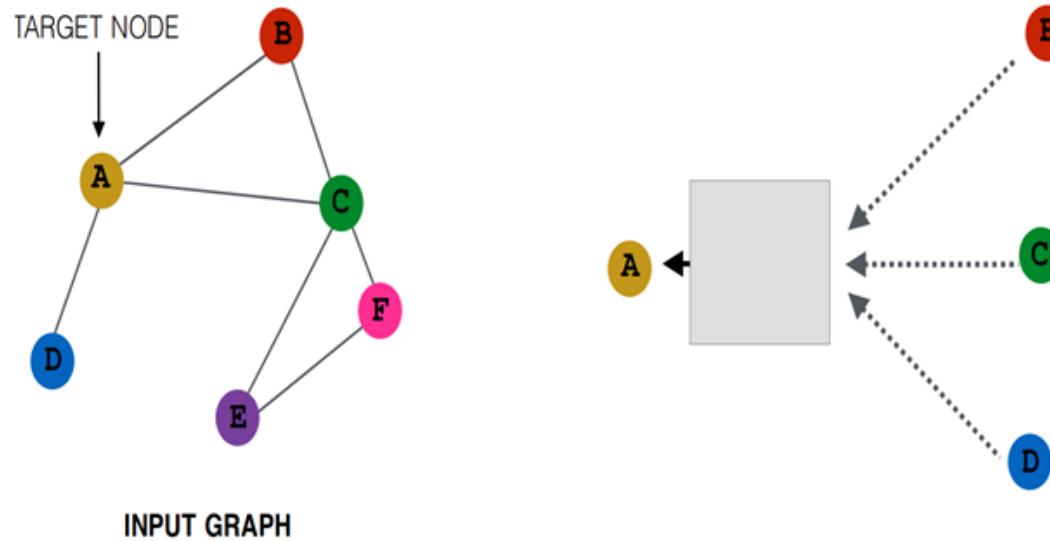
- Sample a subset of node to conduct propagation
- Generalized aggregation: any differentiable function that maps set of vectors to a single vector



- Spatial method with inductive capability

T. N. Kipf and M. Welling. Semi-supervised classification with graph convolutional networks. ICLR, 2017.

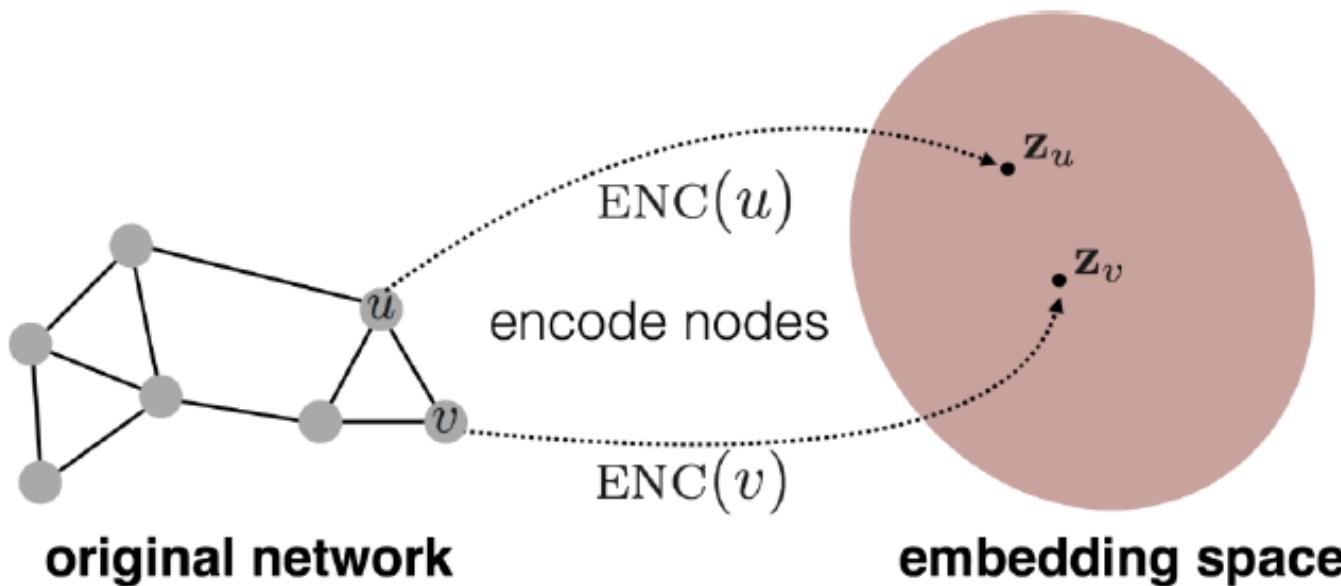
Summary of GNNs



- Characteristics of GNNs
 - Information **aggregation** and **propagation**
 - Trained via **end-to-end manner** according to downstream task
 - Supervised or semi-supervised
 - Utilize **graph structure** and **node features** simultaneously

Pipeline for Graph Learning

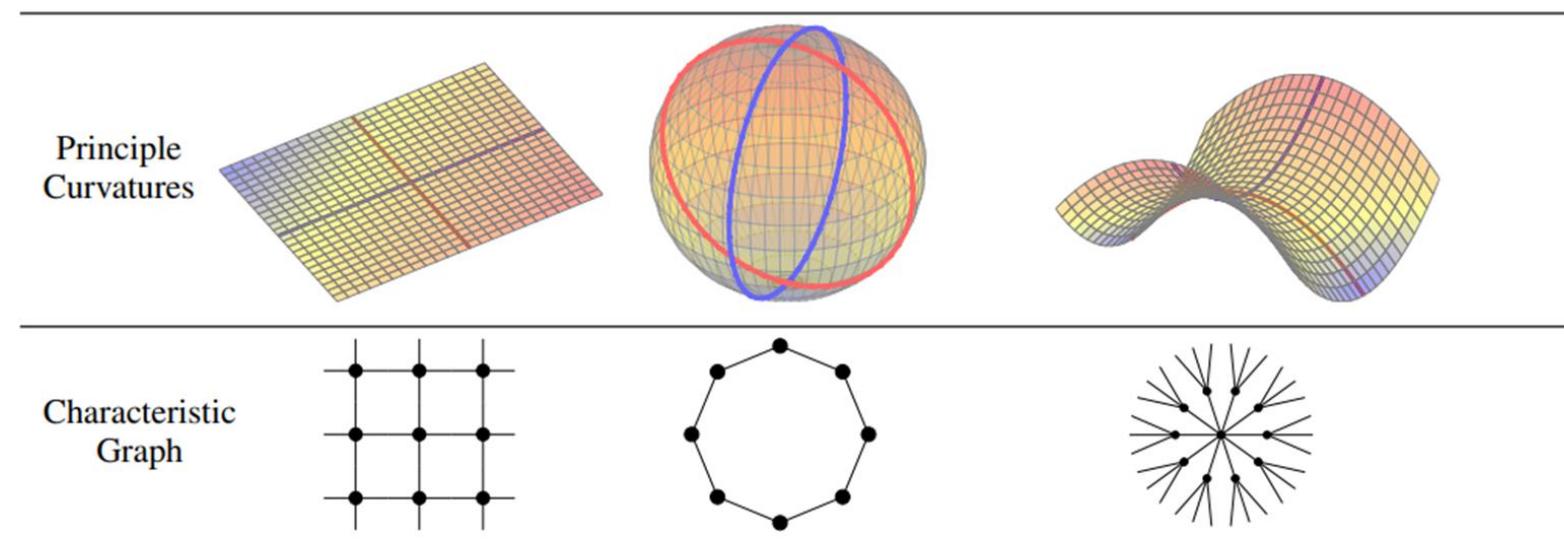
- **Step 1:** Obtain edge or/and node information , possibly with some augmentation
- **Step 2:** Use a parameterized encoder to map nodes in the graph(s) to an embedding space
- **Step 3:** Make predictions on nodes, edges or graphs based on embeddings
- **Step 4:** Compute loss and optimize the parameters



- Graph $G = (V, E)$
- V : Node set,
- E : Edge set
- f_G : Mapping function
- Z : Node embedding

Where to Learn Graphs?

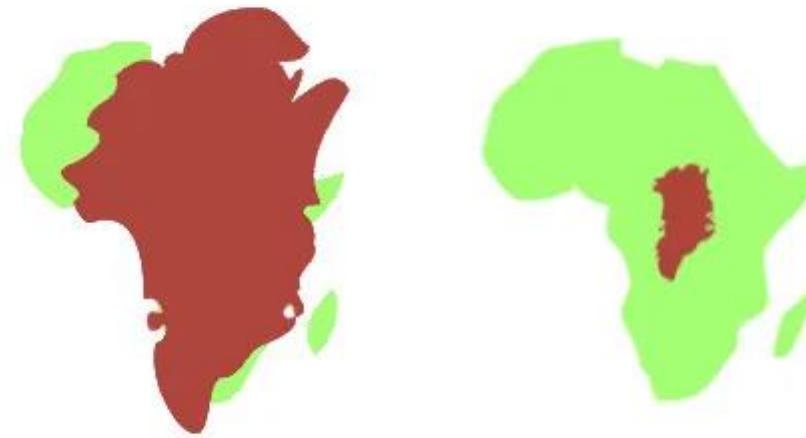
- The quality of embeddings crucially depends on whether the geometry of the learning space matches the dataset.
- What embedding space geometry is optimal for data?



Constraints of Euclidean Geometry



Greenland vs Africa



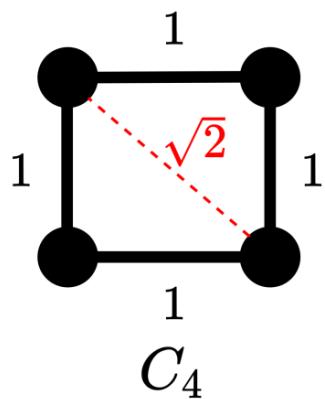
Mercator Projection

Actual Size

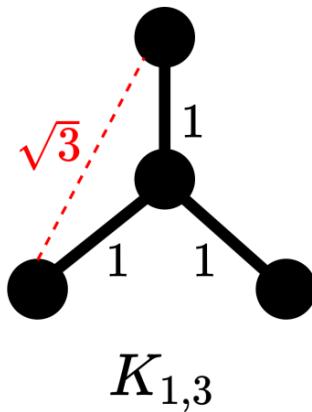
- Many times, we have data lies on non-Euclidean manifold

Constraints of Euclidean Geometry

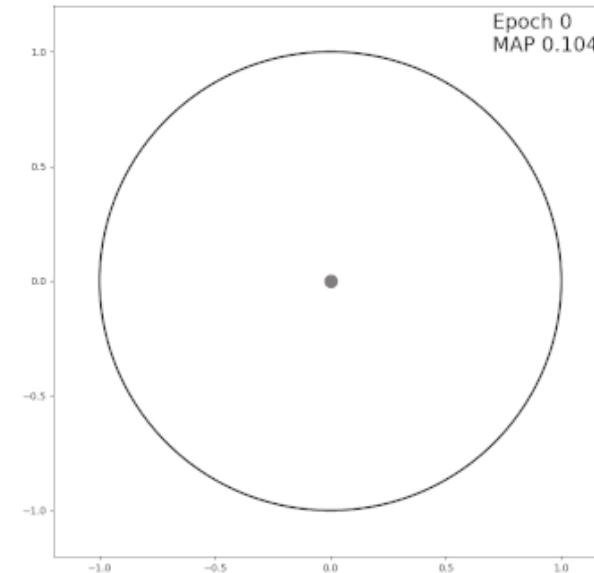
- Cannot embed large classes of graph w/ low distortion or w/o loss of information
 - E.g. cycles, trees



Distortion $\sqrt{2}$



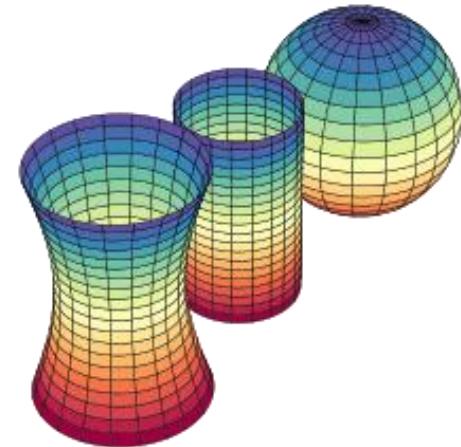
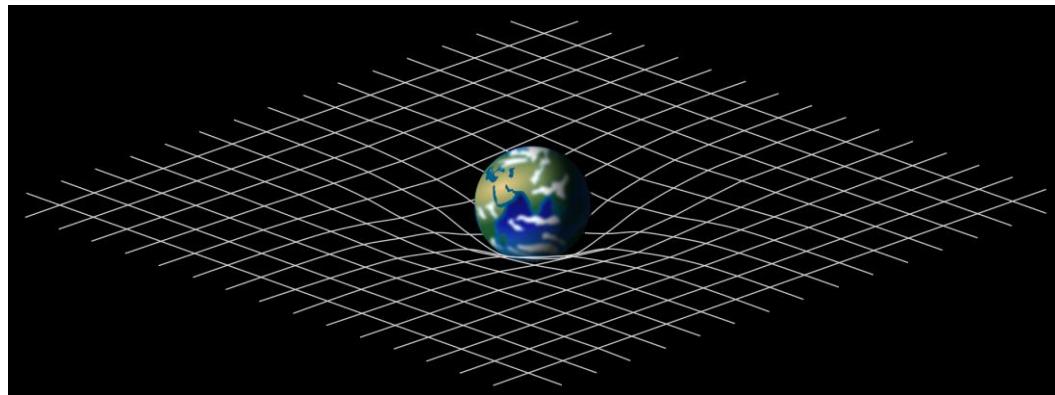
Distortion $\frac{2}{\sqrt{3}}$



- **Graph distance** $d_G(i,j)$ = “shortest path from i to j”

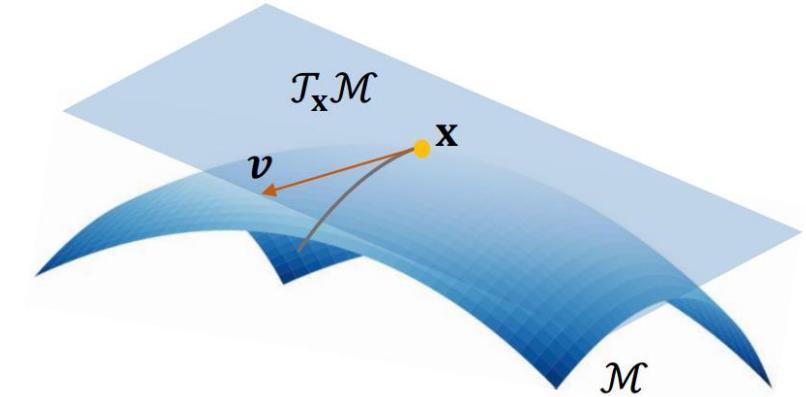
Riemannian Geometry

- Manifolds: high dimensional surface that looks locally-Euclidean
- Riemannian Manifold
 - Equipped with
 - *Inner product* $\langle \cdot, \cdot \rangle$: metric space
 - *Tangent space* \mathcal{T}_x : an \mathbb{R}^n that approximates the manifold at any point x
 - **Curvature**: how much the surface deviates from being a plane
 - **Geodesic**: shortest path in manifold
 - Analogous to straight lines in \mathbb{R}^n



Tangent Spaces

- Tangent Space:
 - $T_p M$ = space of speed vectors of all curves that go through a point x on the manifold
 - A vector space with the same dimension as the manifold

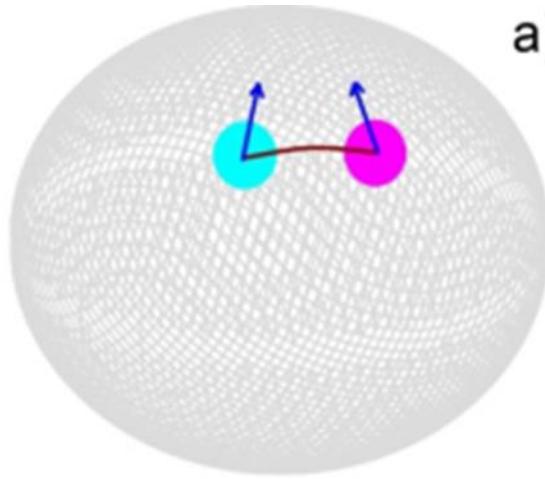


- Exp & Log Maps:

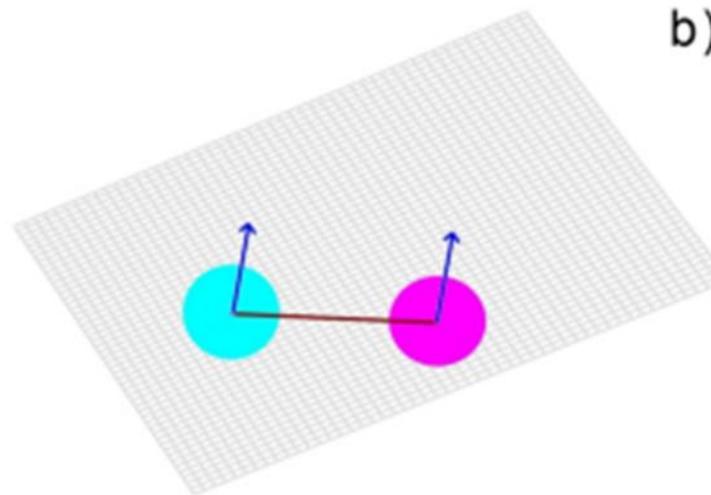
- $\exp_p: T_p M \rightarrow M$
 - $\log_p: M \rightarrow T_p M$
- (1) Map to tangent space
 - (2) Solve problem in the tangent space
 - (3) Map back to the manifold

Curvature

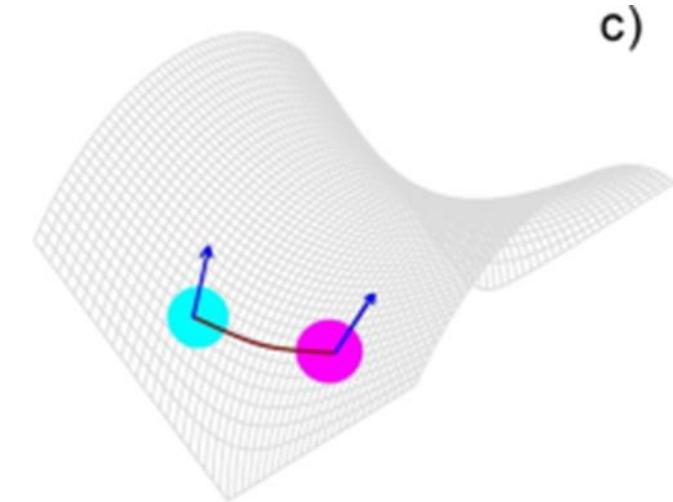
- A geometric property: Flatness of an object
- Geometric intuition: Measure for growth rate of volume of distance ball → “geodesic dispersion”



Positive Curvature



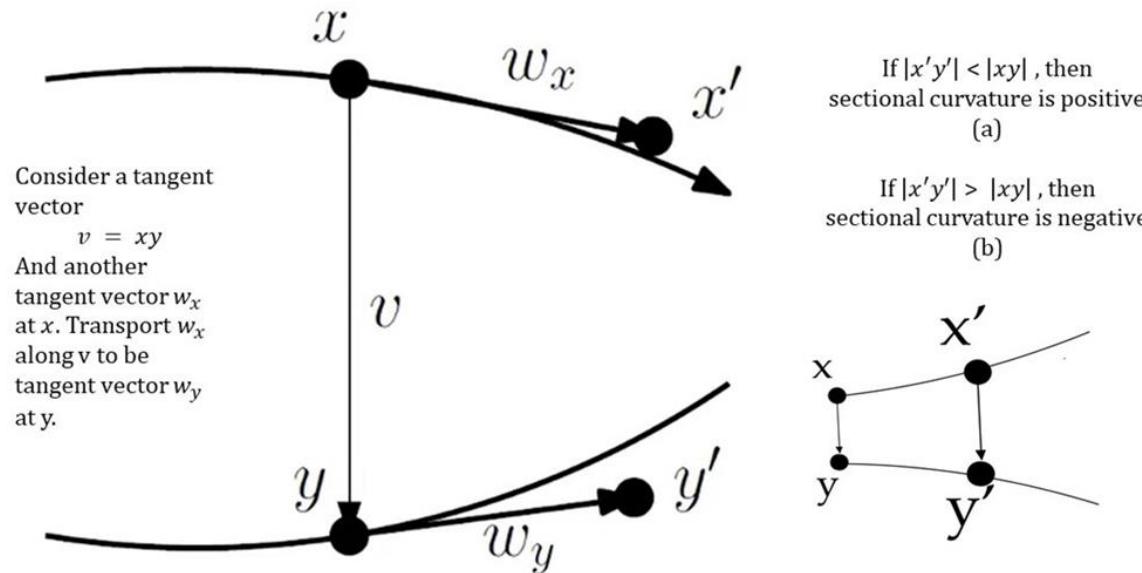
Flat Curvature



Negative Curvature

Sectional Curvature & Ricci Curvature

- Consider a tangent vector $v = xy$ and another tangent vector w_x at x . Transport w_x along v to be a tangent vector w_y at y .

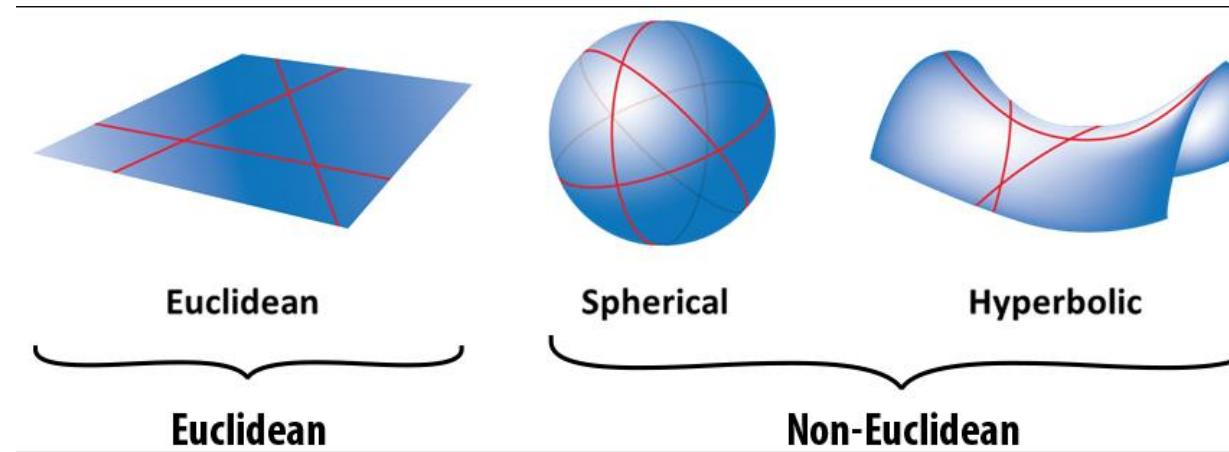


- Ricci Curvature: averaging over all directions w

Ni, Chien-Chun, et al. "Ricci curvature of the internet topology." 2015 IEEE conference on computer communications (INFOCOM). IEEE, 2015.

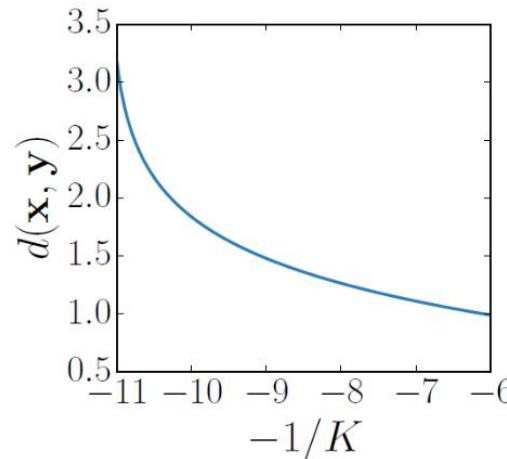
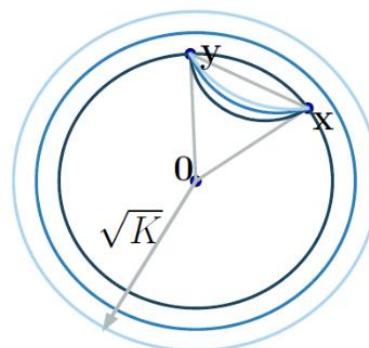
Geodesic Distance

- Geodesic: Shortest path in the manifold



Geodesic Distance

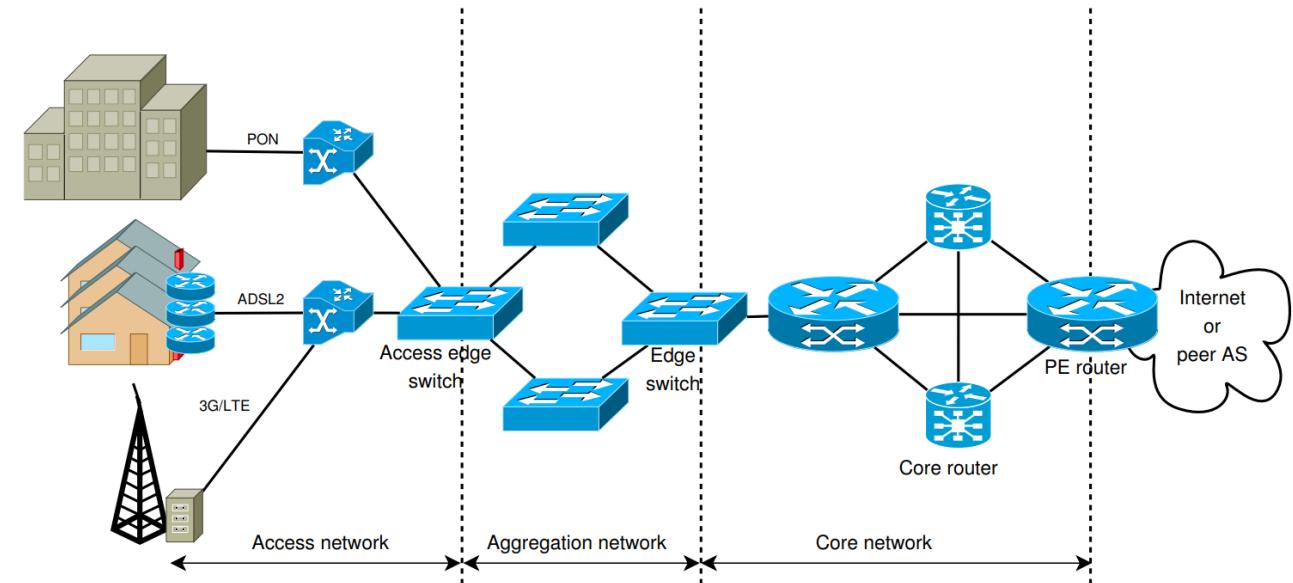
- The more negative the curvature:
 - The more geodesic **bends** inward
 - Distance between two given points also increases

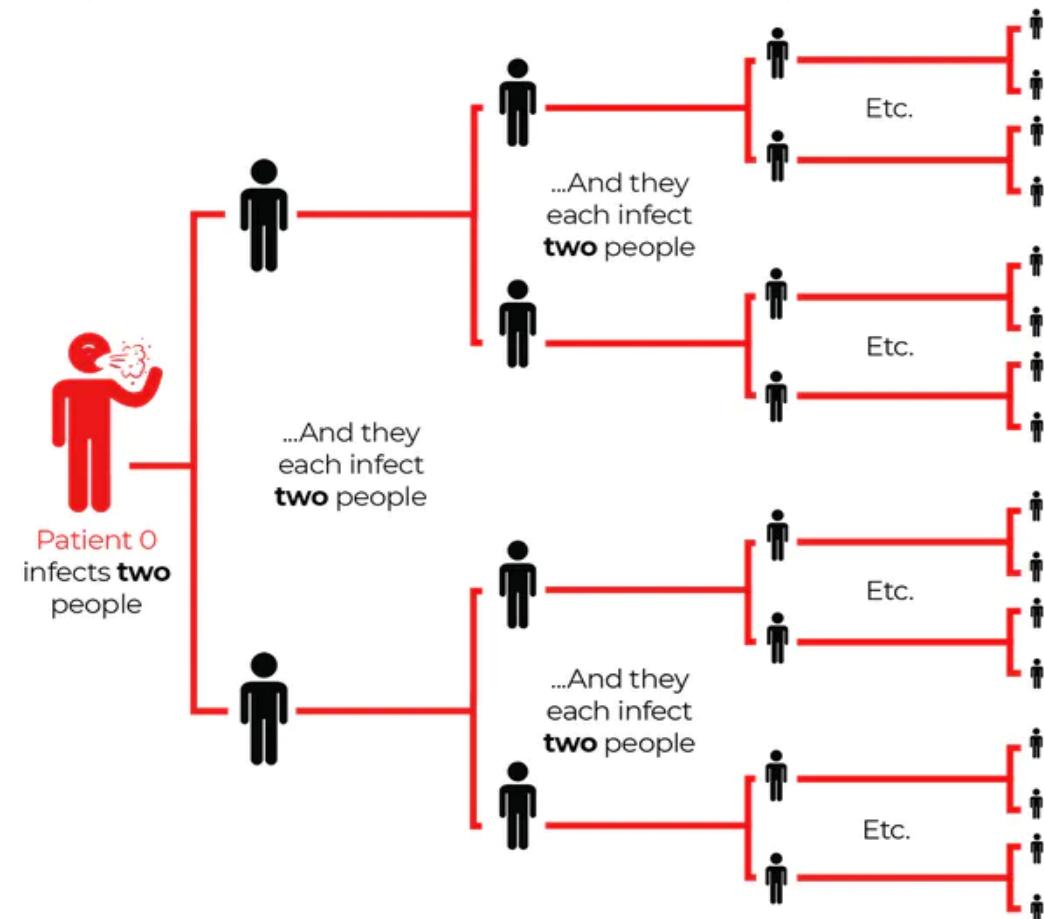


Dark blue: high curvature boundary and geodesics
Light blue: low curvature boundary and geodesics

Why Hyperbolic Space?

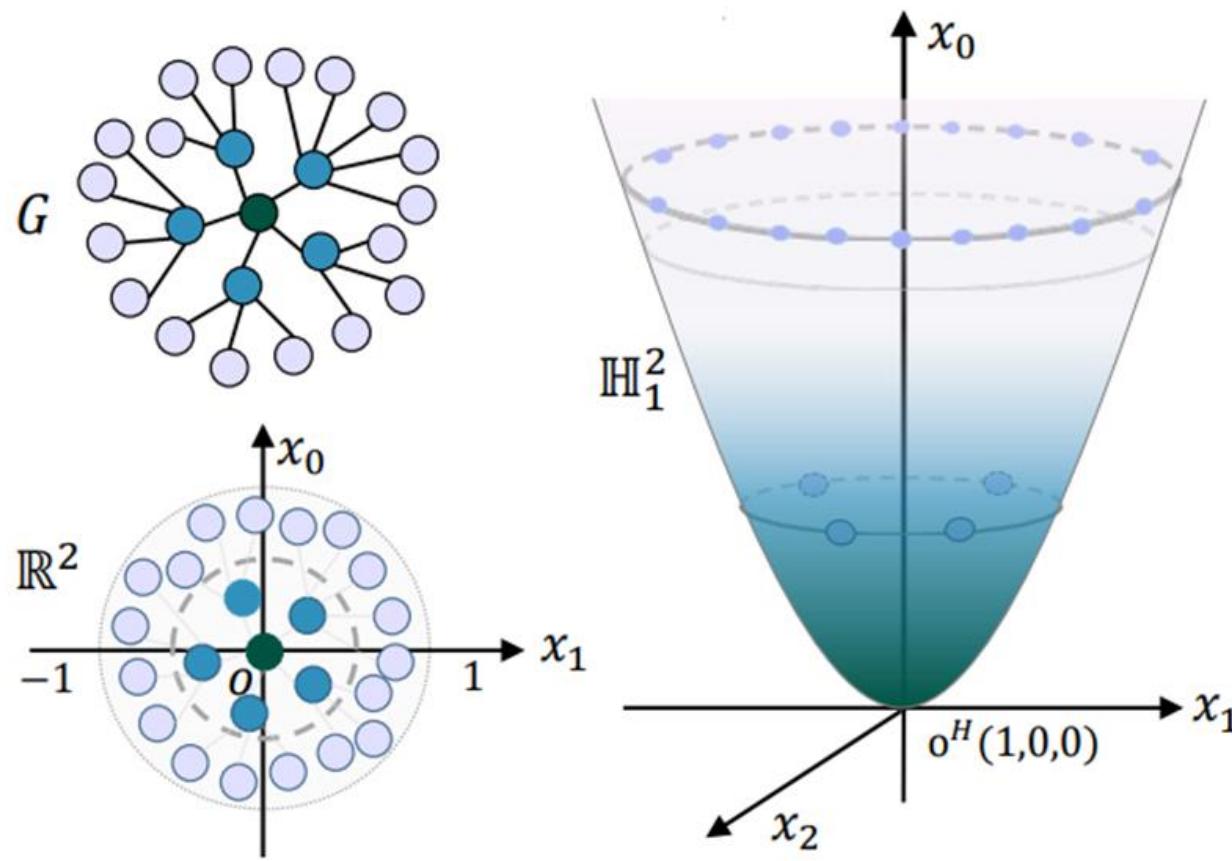
- Many network are with tree-like structures or power-law distributed.





Nodes are exponentially increasing and hierarchical arranged.

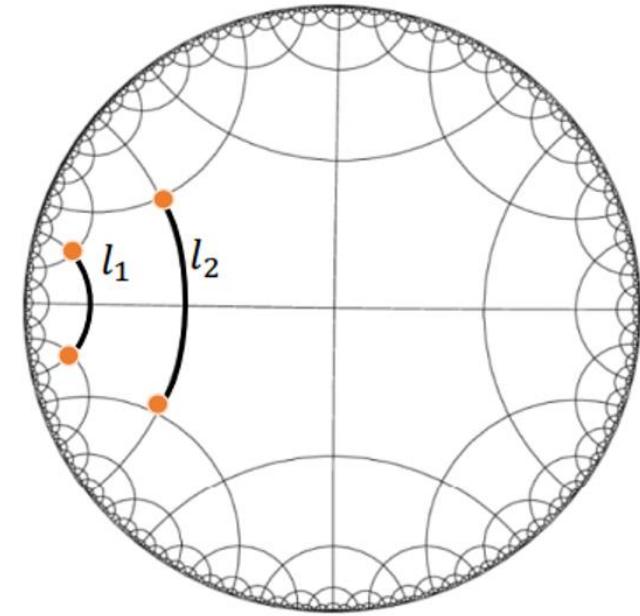
- Figure source: <https://labblog.uofmhealth.org/rounds/how-scientists-quantify-intensity-of-an-outbreak-like-covid-19>



(1) Acts as a geometric prior for hierarchical structures / tree graphs / heavy tailed distributions (e.g. scale-free, power-law). *

$$V_n^{\mathbb{E}}(r) = \frac{\pi^{\frac{n}{2}}}{\Gamma\left(\frac{n}{2} + 1\right)} r^n.$$

$$V_n^{\mathbb{H}}(r) \sim \frac{\text{Vol}(\mathbb{S}^n)}{2^{n-1}} e^{(n-1)r}, \text{ as } r \rightarrow \infty.$$



(2) Larger embedding space ---smaller embedding dimension
and fewer parameter



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2. Hyperbolic Graph Representation Learning (HGRL)

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- 1.2 Brief Introduction of Riemannian Geometry
- 1.3 Motivation of Hyperbolic Graph Representation Learning

2. HYPERBOLIC GRAPH REPRESENTATION LEARNING (HGRL)

- 2.1 Hyperbolic Shallow Models
- 2.2 Hyperbolic Neural Networks
- 2.3 Hyperbolic Graph Neural Networks

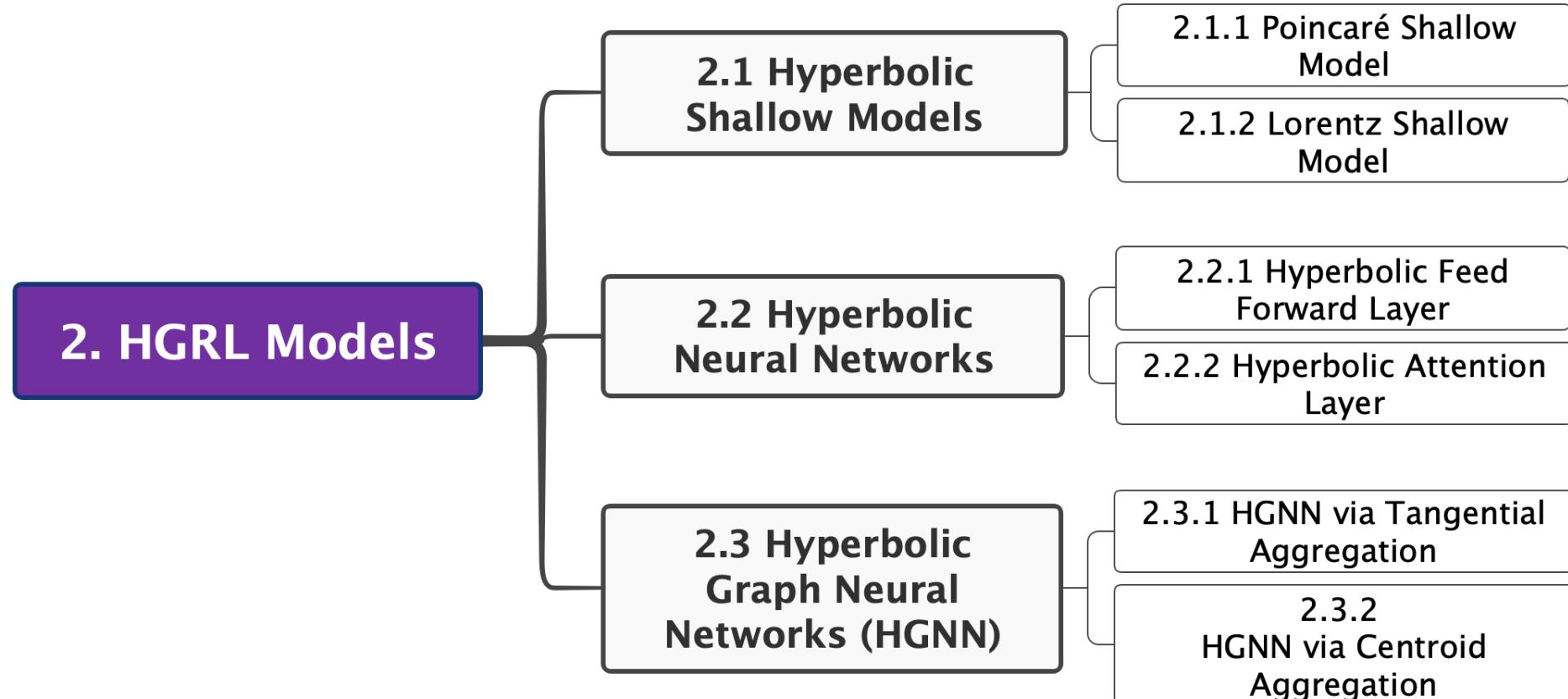
3. APPLICATIONS

- 3.1 HGRL for Recommendation Systems
- 3.2 HGRL for Knowledge Graph
- 3.3 HGRL for other Applications

4. ADVANCED TOPICS

- 4.1 Complex Structures
- 4.2 Evolving Interactions
- 4.3 Geometry-Aware Learning
- 4.4 Trustworthy and Scalability

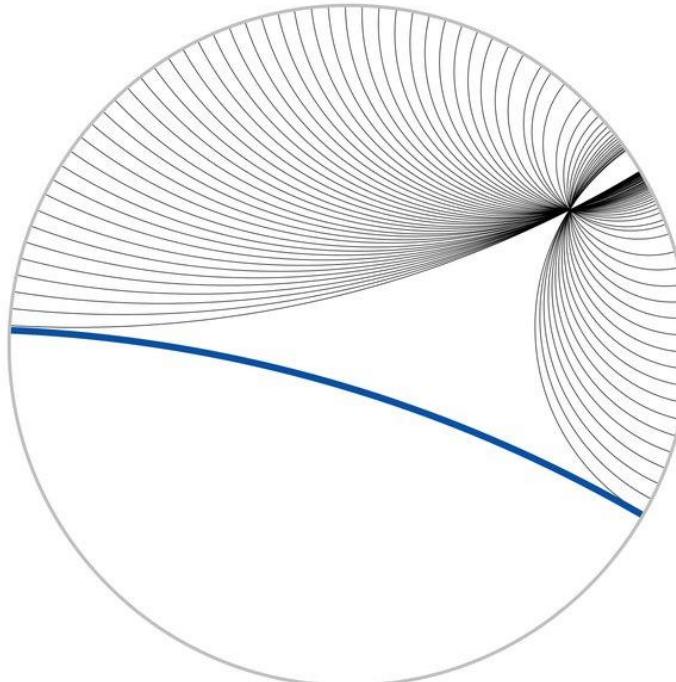
2. HYPERBOLIC GRAPH REPRESENTATION LEARNING (HGRL)



Backgrounds

Hyperbolic Geometry

- A non-Euclidean geometry that reject the validity of Euclid's fifth, the “parallel”, postulate.



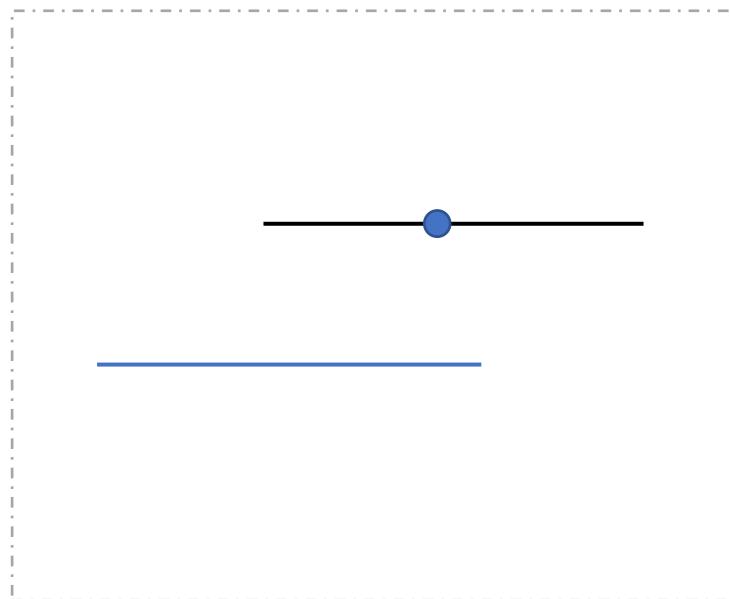
In hyperbolic space, there are at least two lines that parallel a line through a given point.

https://en.wikipedia.org/wiki/Poincar%C3%A9_disk_model

Backgrounds

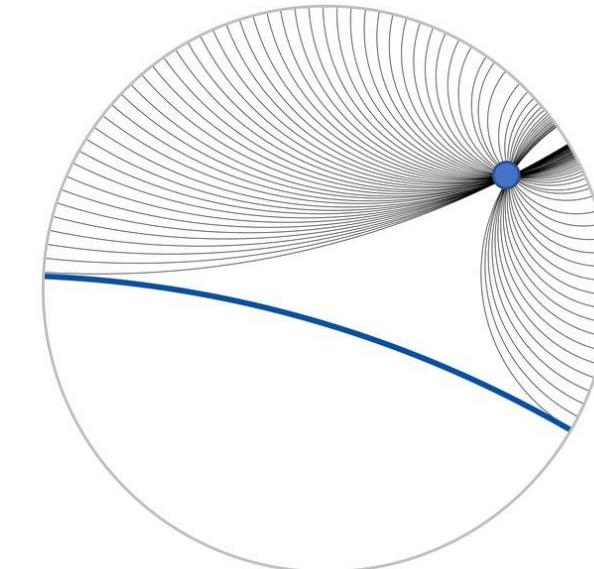
Hyperbolic Geometry

- A non-Euclidean geometry that reject the validity of Euclid's fifth, the “parallel”, postulate.



In Euclidean space, there is only one line that parallels a line through a given point.

https://en.wikipedia.org/wiki/Poincar%C3%A9_disk_model



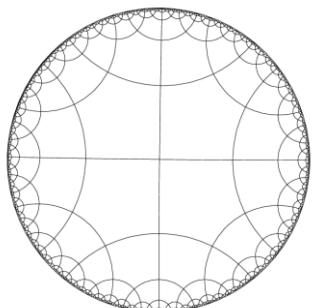
In hyperbolic space, there are at least two lines that parallel a line through a given point.

Backgrounds

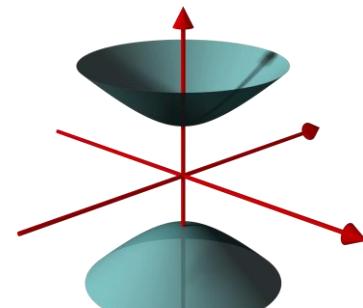
Mathematical Models for Hyperbolic Geometry

Hyperbolic Models

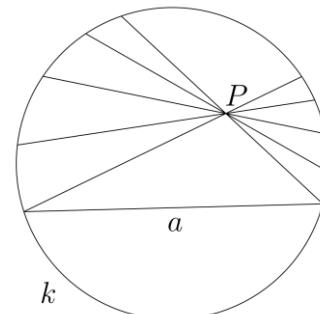
Poincaré Ball Model



Lorentz (Hyperboloid) Model



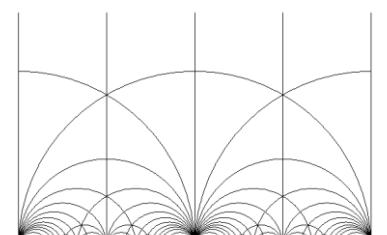
Klein Model



Hemisphere Model

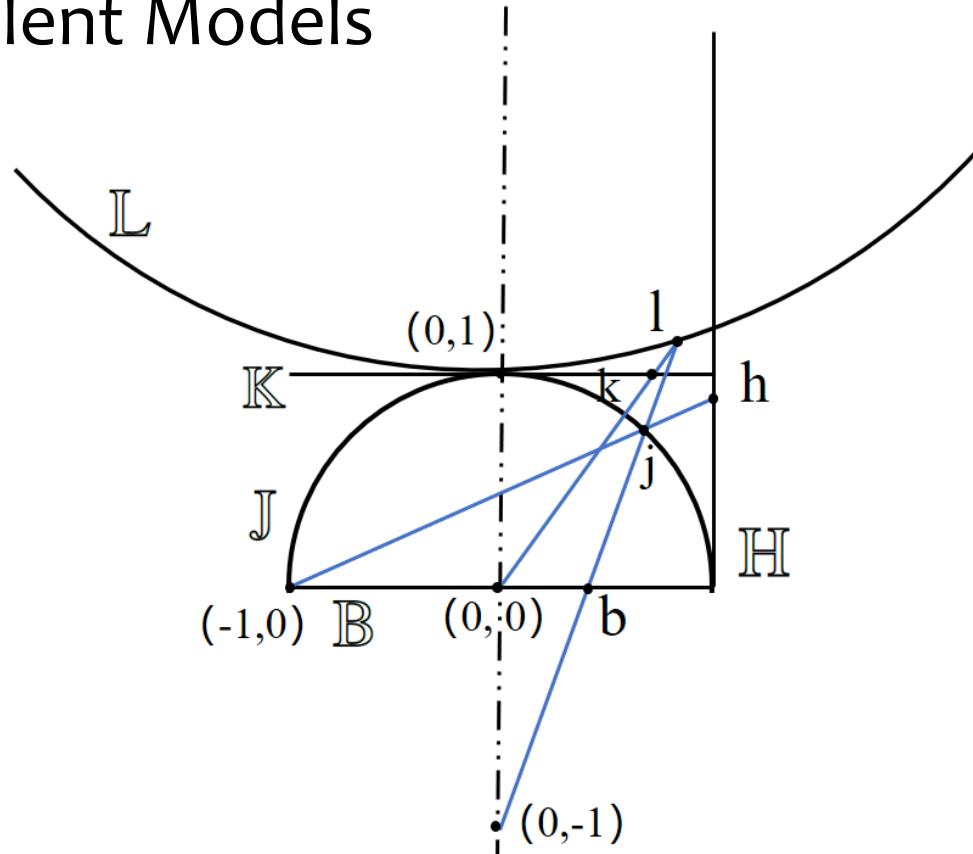


Poincaré Half Plane Model



Backgrounds

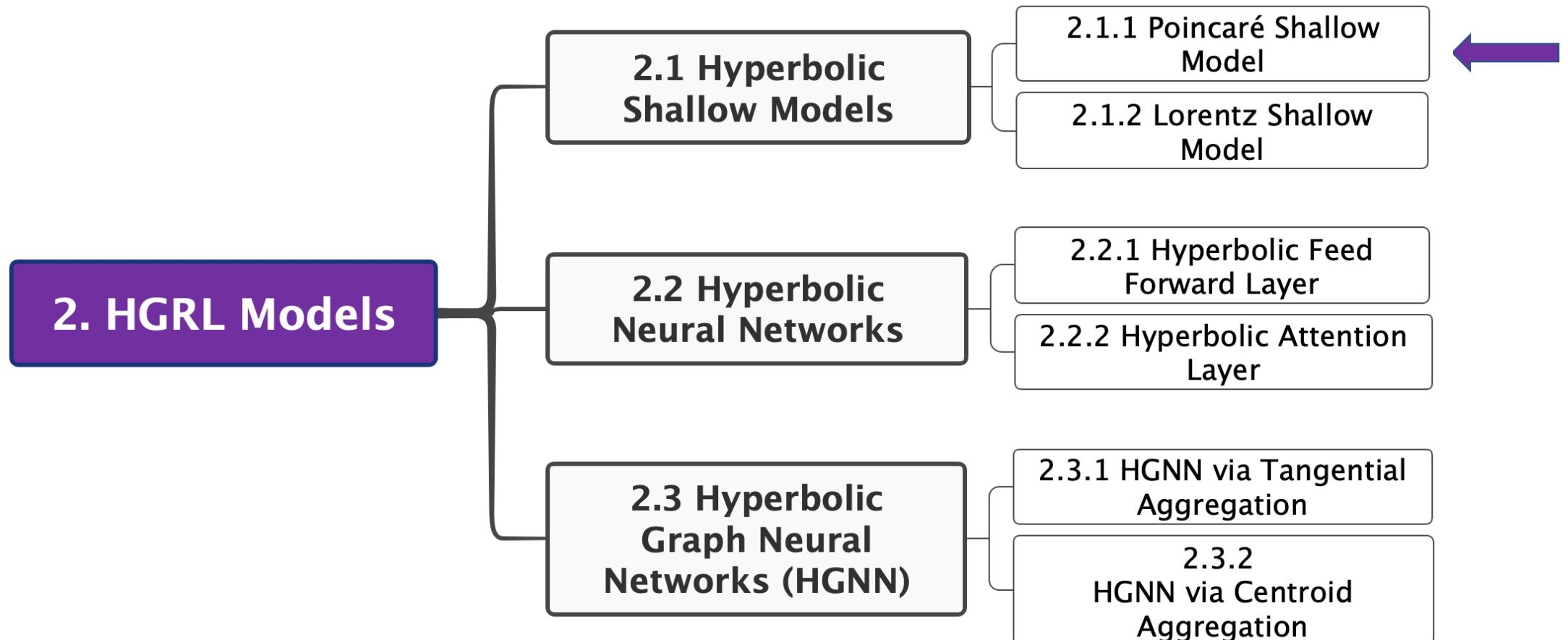
Isometrically Equivalent Models



- \mathbb{L} : Lorentz Model
- \mathbb{K} : Klein Model
- \mathbb{J} : Hemisphere model
- \mathbb{B} : Poincaré Model
- \mathbb{H} : Poincaré half plane Model

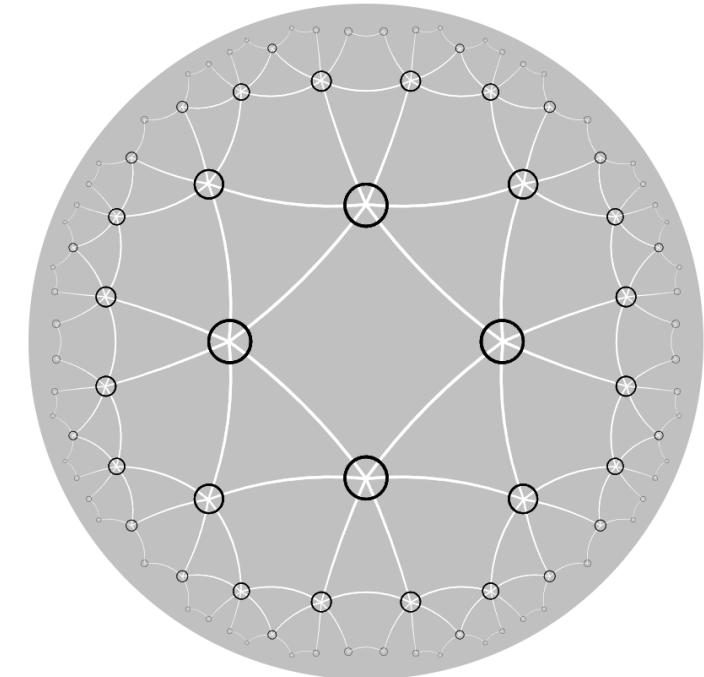
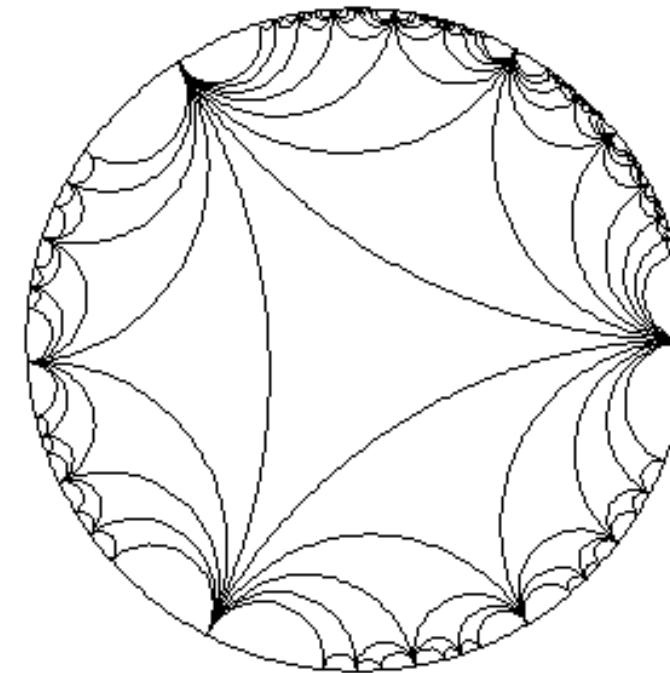
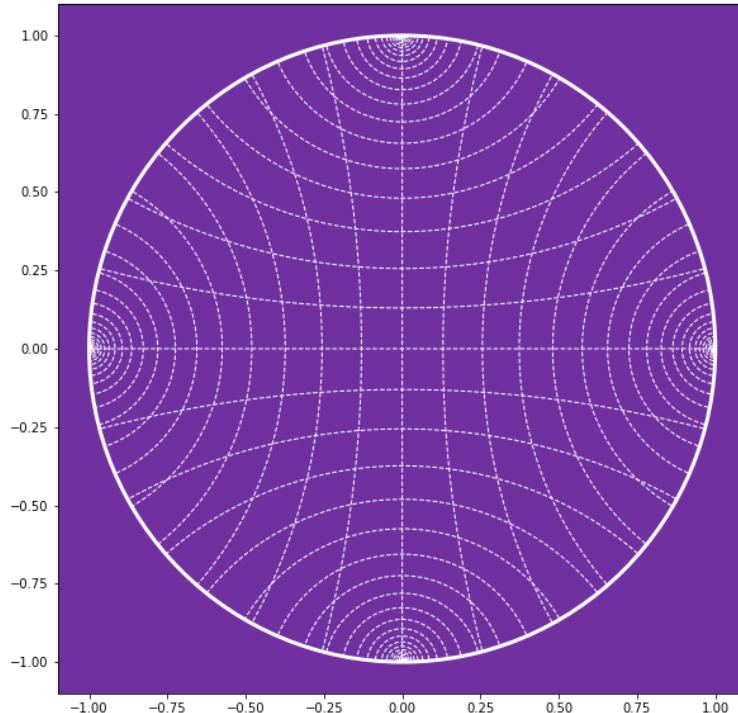
The five hyperbolic models are isometrically equivalent and the points h, b, j, k, l can be thought of as the same point in the hyperbolic space.

2.1 Hyperbolic Shallow Models



2.1.1 Poincaré Shallow Model

Poincaré Ball Model



Radius proportional to K (inverse of curvature), Open ball (exclude boundary)
In the right two figure, each triangle/circle has the same area.

2.1.1 Poincaré Shallow Model

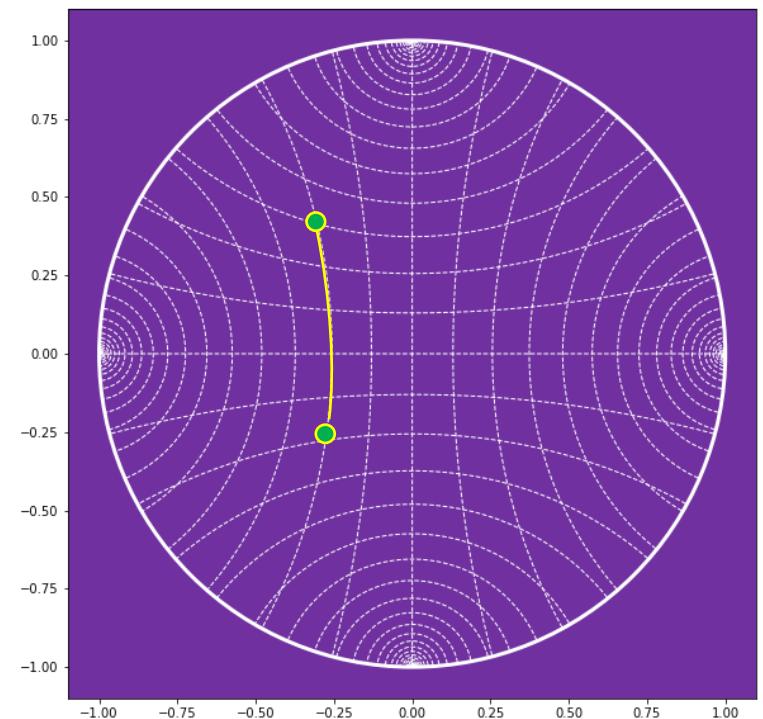
Poincaré Ball Model ([Intuitive Visualization](#))

❖ **Definition** $\mathcal{B}^d = \{x \in \mathbb{R}^d \mid \|x\| < 1\}$,

where $\|x\| = \sqrt{\sum_{i=1}^d x_i^2}$, a Euclidean norm.

❖ **Distance** between $u, v \in \mathcal{B}^d$:

$$d_{\mathcal{B}}(u, v) = \text{arcosh} \left(1 + 2 \cdot \frac{\|u - v\|^2}{(1 - \|u\|^2)(1 - \|v\|^2)} \right).$$

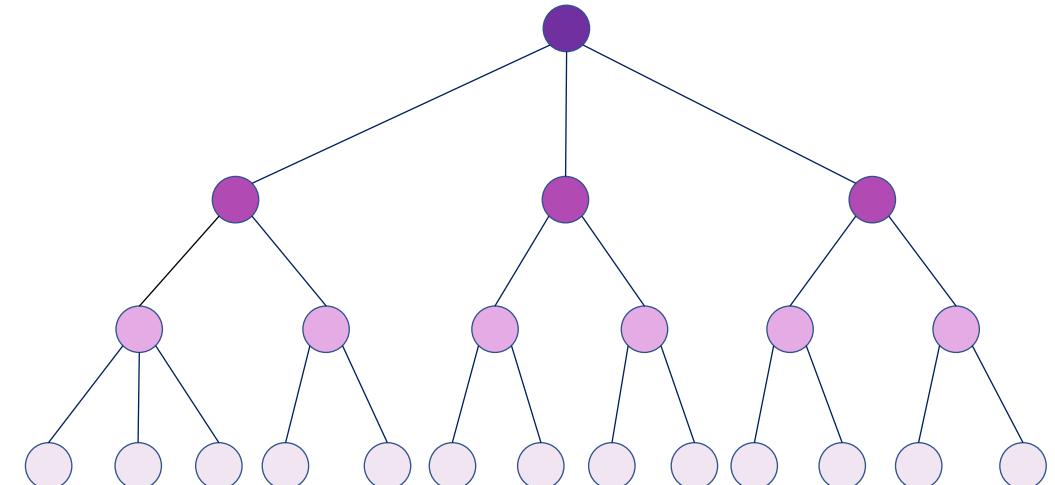


2-dimensional Poincaré ball

2.1.1 Poincaré Shallow Models

Poincaré Shallow Embedding

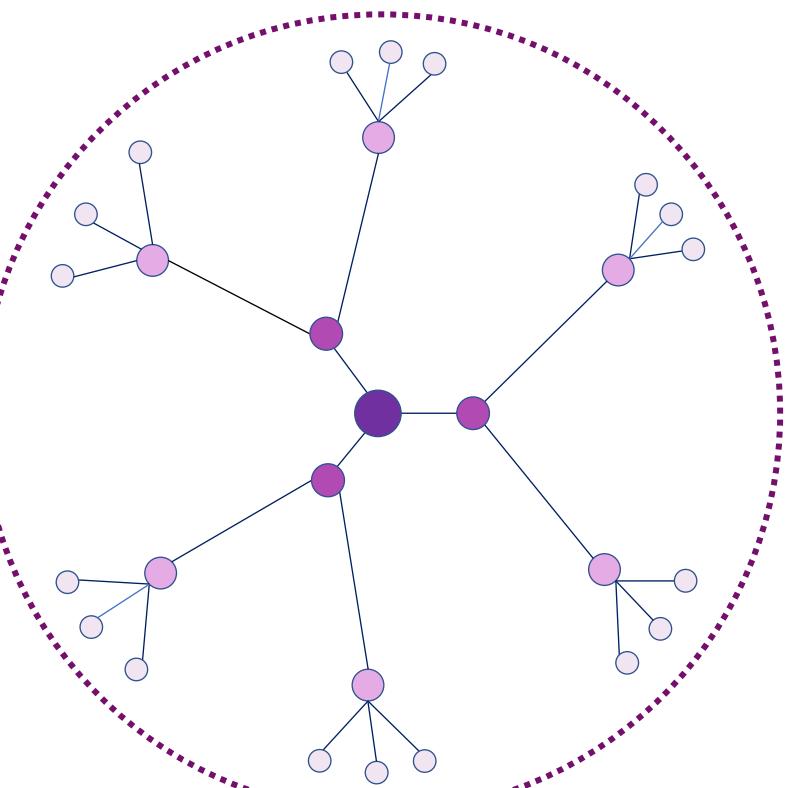
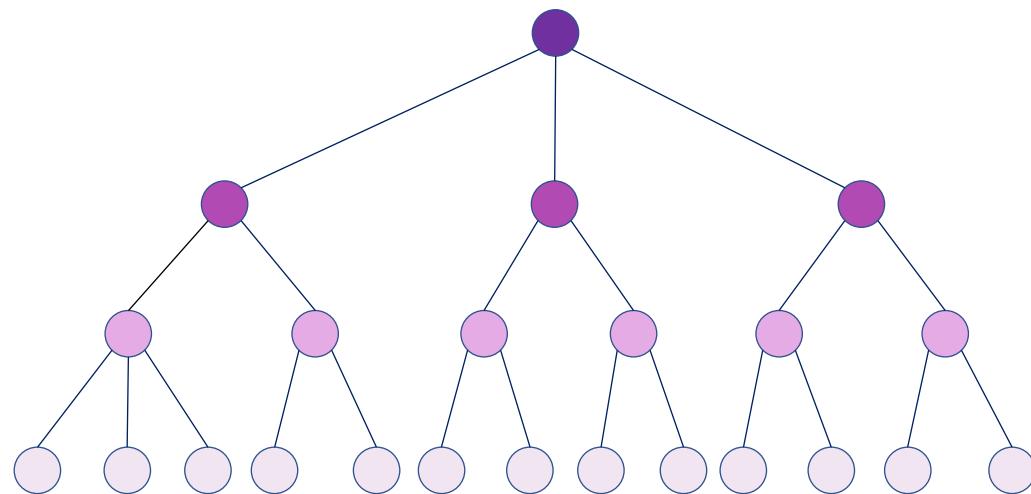
- ❖ **Problem** We have a tree-like graph with set of vertices $\mathcal{N} = \{x_i\}_i^n$, and we want to find embeddings $\Theta = \{\theta_i\}_i^n$, that they
- capture the similarity between vertices (including semantics and structures)
 - encode the latent hierarchical structure
 - have feasible runtime and memory complexity



2.1.1 Poincaré Shallow Models

Poincaré Shallow Embedding

❖ **Problem** We have a tree-like graph with set of vertices $\mathcal{N} = \{x_i\}_i^n$, and we want to find embeddings $\Theta = \{\theta_i\}_i^n$, that they



2.1.1 Poincaré Shallow Models

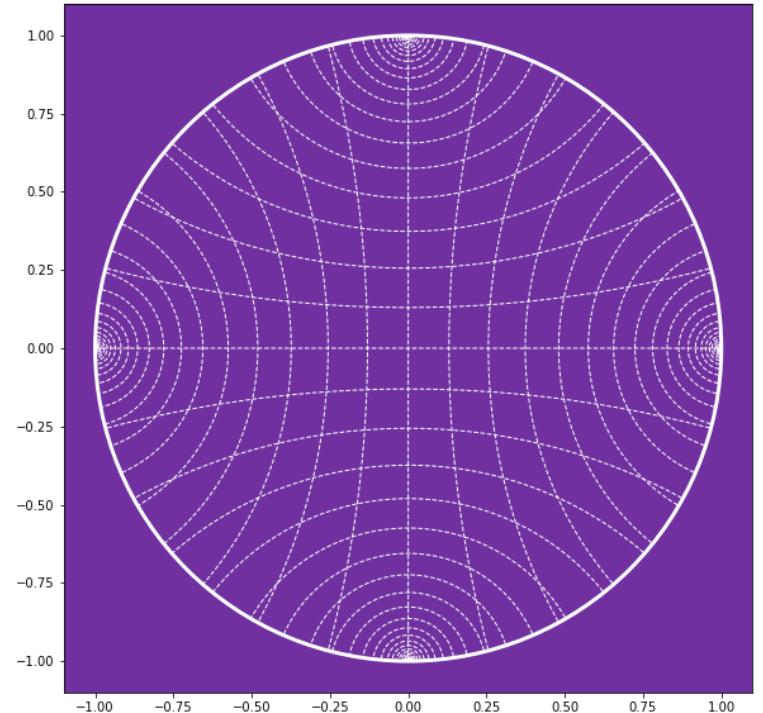
Poincaré Shallow Embedding

❖ Objective

$$\Theta^* \leftarrow \operatorname{argmin}_{\Theta} L(\Theta),$$

$$s.t. \forall \theta_i \in \Theta: |\theta_i| < 1$$

where $L(\Theta)$ is task-specific loss function.



2-dimensional Poincaré ball

2.1.1 Poincaré Shallow Models

Poincaré Shallow Embedding

1. **Initialization:** all node are projected to Poincaré Ball.

- 1) Without node feature: randomly using uniform distribution
- 2) With node feature: using exponential map

2. **Update** θ : $\theta_{t+1} \rightarrow \text{proj} \left(\theta_t - \eta_t \cdot \frac{(1-||\theta_t||^2)^2}{4} \nabla_E \right)$

where

$$\Delta_E = \frac{\partial L(\theta_t)}{\partial (d(\theta_t, x))} \cdot \frac{\partial d(\theta_t, x)}{\partial \theta_t} \quad \text{proj}(\theta_t) = \begin{cases} \frac{\theta_t}{||\theta_t||} - \epsilon \text{ if } ||\theta_t|| \geq 1 \\ \theta_t \text{ otherwise} \end{cases}$$

Nickel, Maximillian, and Douwe Kiela. "Poincaré embeddings for learning hierarchical representations." *NeurIPS* 30 (2017).

2.1.1 Poincaré Shallow Models

Poincaré Shallow Embedding

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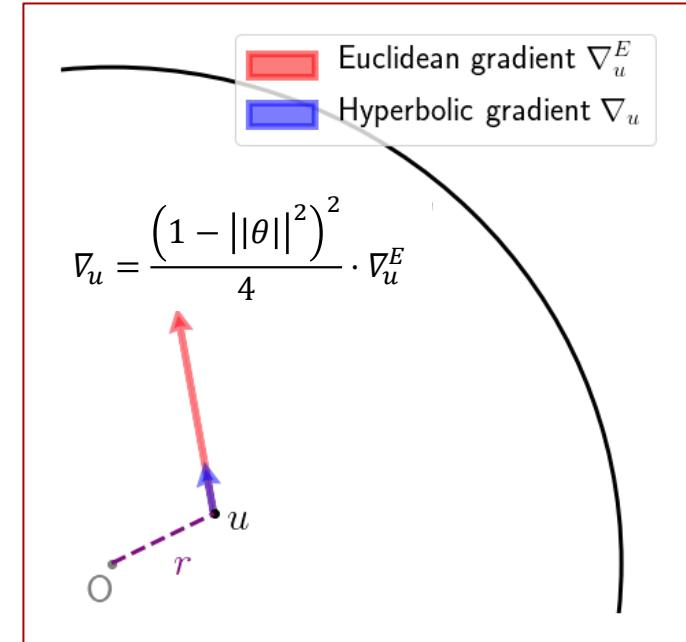
- 1) Without node feature: randomly using uniform distribution
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$$\text{proj}(\theta_t) = \begin{cases} \frac{\theta_t}{||\theta_t||} - \epsilon \text{ if } ||\theta_t|| \geq 1 \\ \theta_t \text{ otherwise} \end{cases}$$



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2.1.1 Results on Poincaré Ball

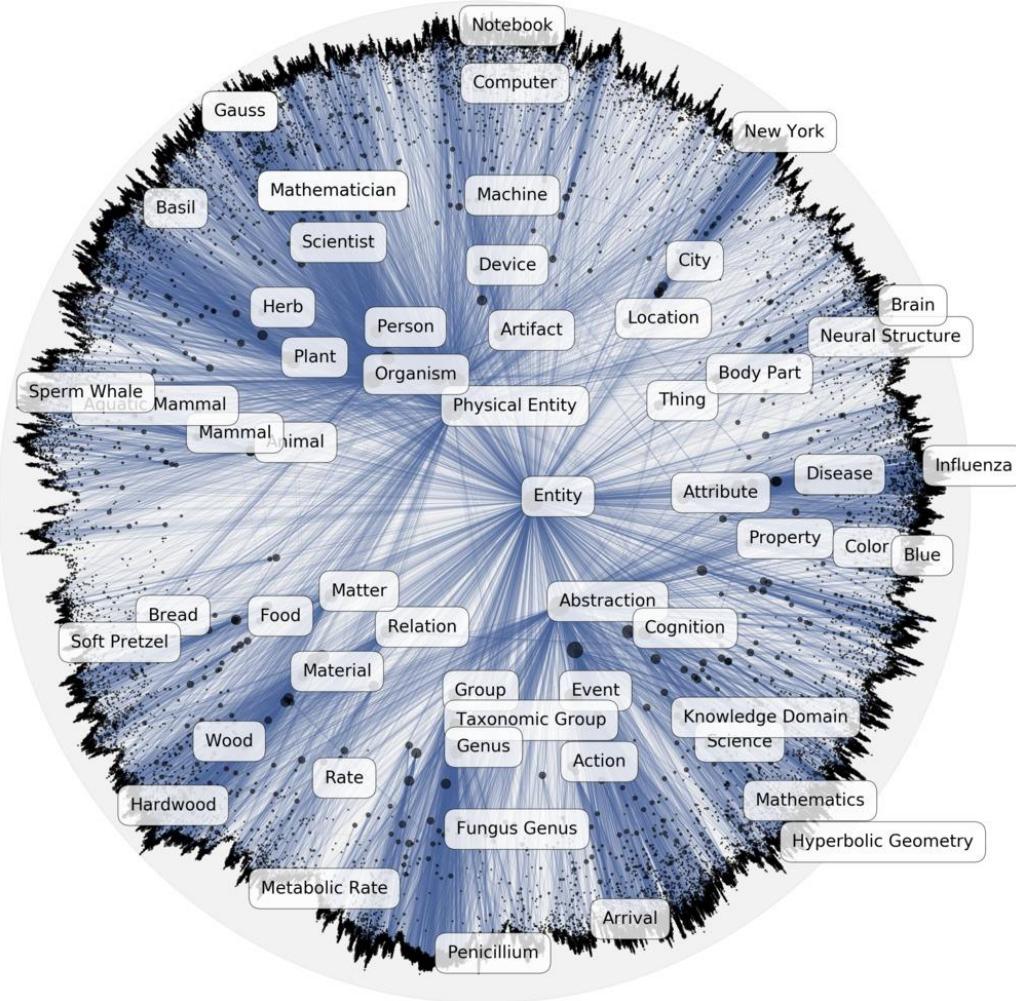
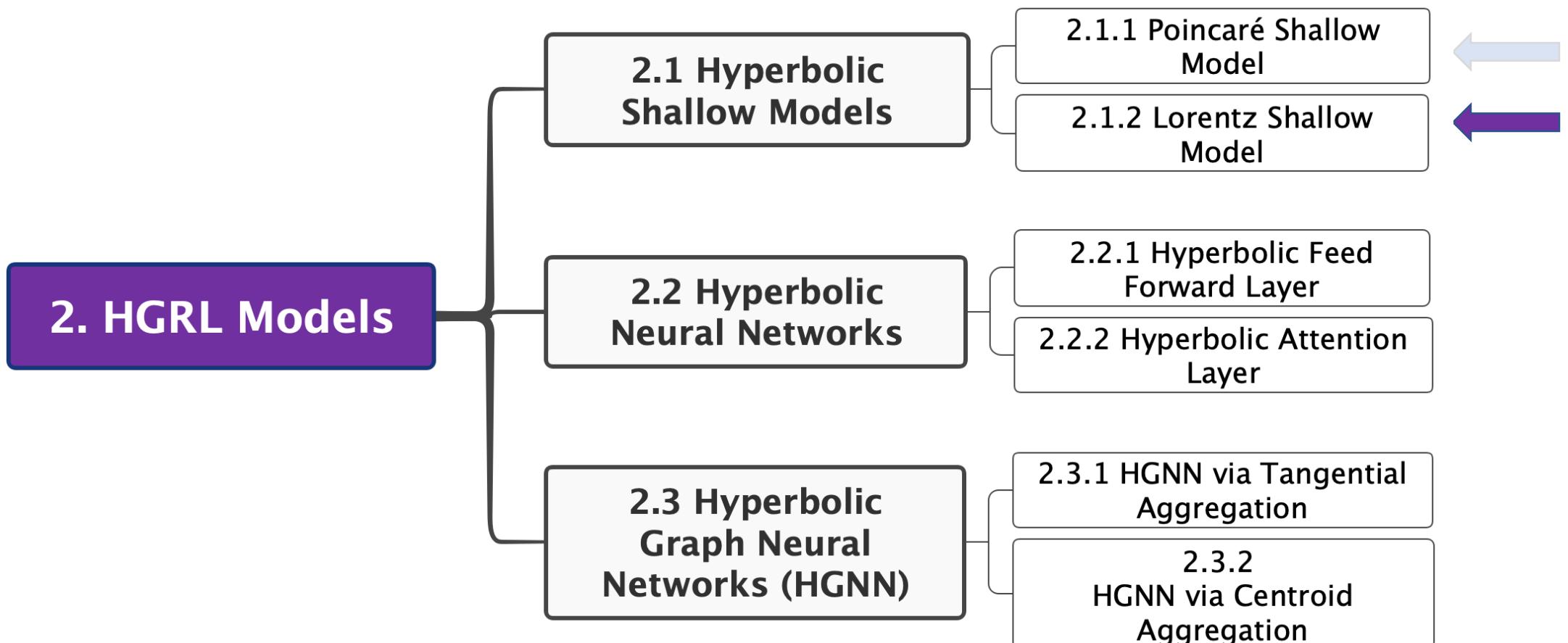


Table: Experimental results on the transitive closure of the WORDNET noun hierarchy. Highlighted cells indicate the best Euclidean embeddings as well as the Poincaré embeddings which achieve equal or better results. Bold numbers indicate absolute best results.

WORDNET Reconstruction	Euclidean	Dimensionality						
		5	10	20	50	100	200	
	Euclidean	Rank MAP	3542.3 0.024	2286.9 0.059	1685.9 0.087	1281.7 0.140	1187.3 0.162	1157.3 0.168
	Translational	Rank MAP	205.9 0.517	179.4 0.503	95.3 0.563	92.8 0.566	92.7 0.562	91.0 0.565
	Poincaré	Rank MAP	4.9 0.823	4.02 0.851	3.84 0.855	3.98 0.86	3.9 0.857	3.83 0.87
WORDNET Link Pred.	Euclidean	Rank MAP	3311.1 0.024	2199.5 0.059	952.3 0.176	351.4 0.286	190.7 0.428	81.5 0.490
		Rank MAP	65.7 0.545	56.6 0.554	52.1 0.554	47.2 0.56	43.2 0.562	40.4 0.559
	Poincaré	Rank MAP	5.7 0.825	4.3 0.852	4.9 0.861	4.6 0.863	4.6 0.856	4.6 0.855

Nickel, Maximilian, and Douwe Kiela. "Poincaré embeddings for learning hierarchical representations." *NeurIPS 30* (2017).

2.1.2 Lorentz Shallow Models



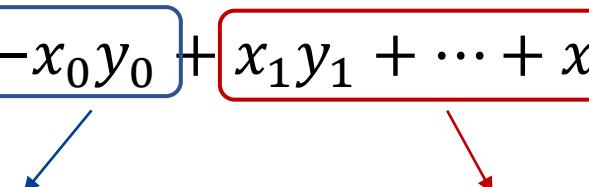
2.1.2 Lorentz Shallow Models

Lorentz Model

(Numerically more stable, simpler formula)

❖ **Definition** $\mathcal{L}^d = \{x \in \mathbb{R}^{d+1}: \langle x, x \rangle_{\mathcal{L}} = -1, x_0 > 0\}$,

where $\langle x, y \rangle_{\mathcal{L}} := \boxed{-x_0y_0} + \boxed{x_1y_1 + \dots + x_dy_d}$.


Time-like Space-like

❖ **Distance** between $u, v \in \mathcal{L}^d$:

$$d_{\mathcal{L}}(u, v) = \text{arcosh}(-\langle u, v \rangle_{\mathcal{L}}).$$

2.1.2 Lorentz Shallow Models

Lorentz Model

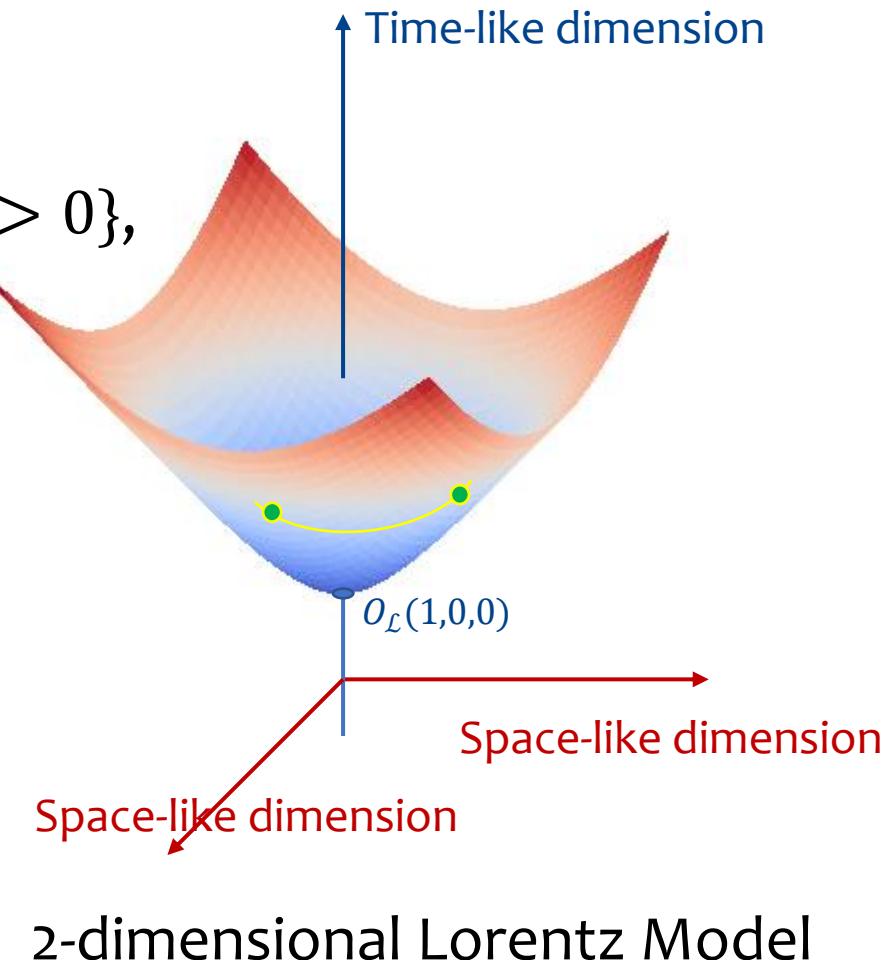
(Numerically more stable, simpler formula)

❖ **Definition** $\mathcal{L}^d = \{x \in \mathbb{R}^{d+1} : \langle x, x \rangle_{\mathcal{L}} = -1, x_0 > 0\}$,

where $\langle x, y \rangle_{\mathcal{L}} := -x_0y_0 + x_1y_1 + \cdots + x_dy_d$.

❖ **Distance** between $u, v \in \mathcal{L}^d$:

$$d_{\mathcal{F}}(u, v) = \operatorname{arccosh}(-\langle x, y \rangle_{\mathcal{F}}).$$



2.1.2 Lorentz Shallow Models

Lorentz Shallow Embedding

- ❖ **Problem** We have a tree-like graph with set of vertices $\mathcal{N} = \{x_i\}_i^n$, and we want to find embeddings $\Theta = \{\theta_i\}_i^n$, that they
 - capture the similarity between vertices (including semantics and structure);
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 - have feasible runtime and memory complexity.

2.1.2 Lorentz Shallow Models

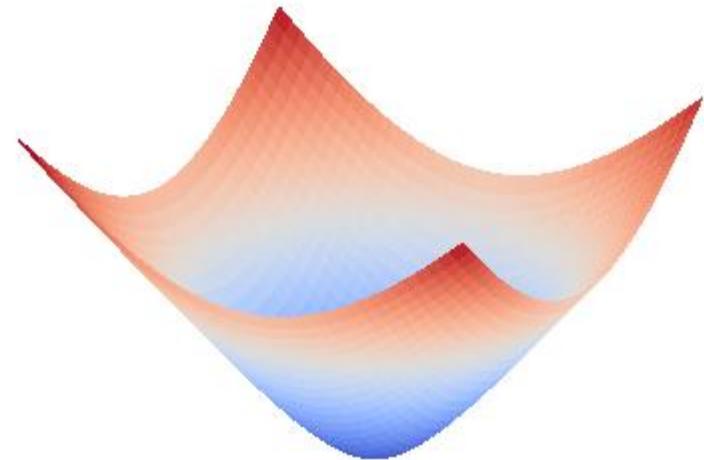
Lorentz Shallow Embedding

❖ Objective

$$\theta^* \leftarrow \operatorname{argmin}_{\theta} L(\Theta),$$

$$s.t. \boxed{\forall \theta_i \in \Theta: \theta_i \in \mathcal{L}^d}$$

$$\theta_{i,0}^2 + \theta_{i,1}^2 + \dots + \theta_{i,d}^2 = -1$$



2-dimensional Lorentz Model

where $L(\theta)$ is task-specific loss function.

2.1.2 Lorentz Shallow Models

Lorentz Shallow Embedding

- 1. Initialization:** all node are projected to Lorentz Model.

- 1) Without node feature: randomly using uniform distribution
- 2) With node feature: using exponential map

2. **Update Θ :** $\theta_{t+1} \rightarrow \exp_{\theta_t}(-\eta_t \cdot \text{grad}f(\theta_t))$,

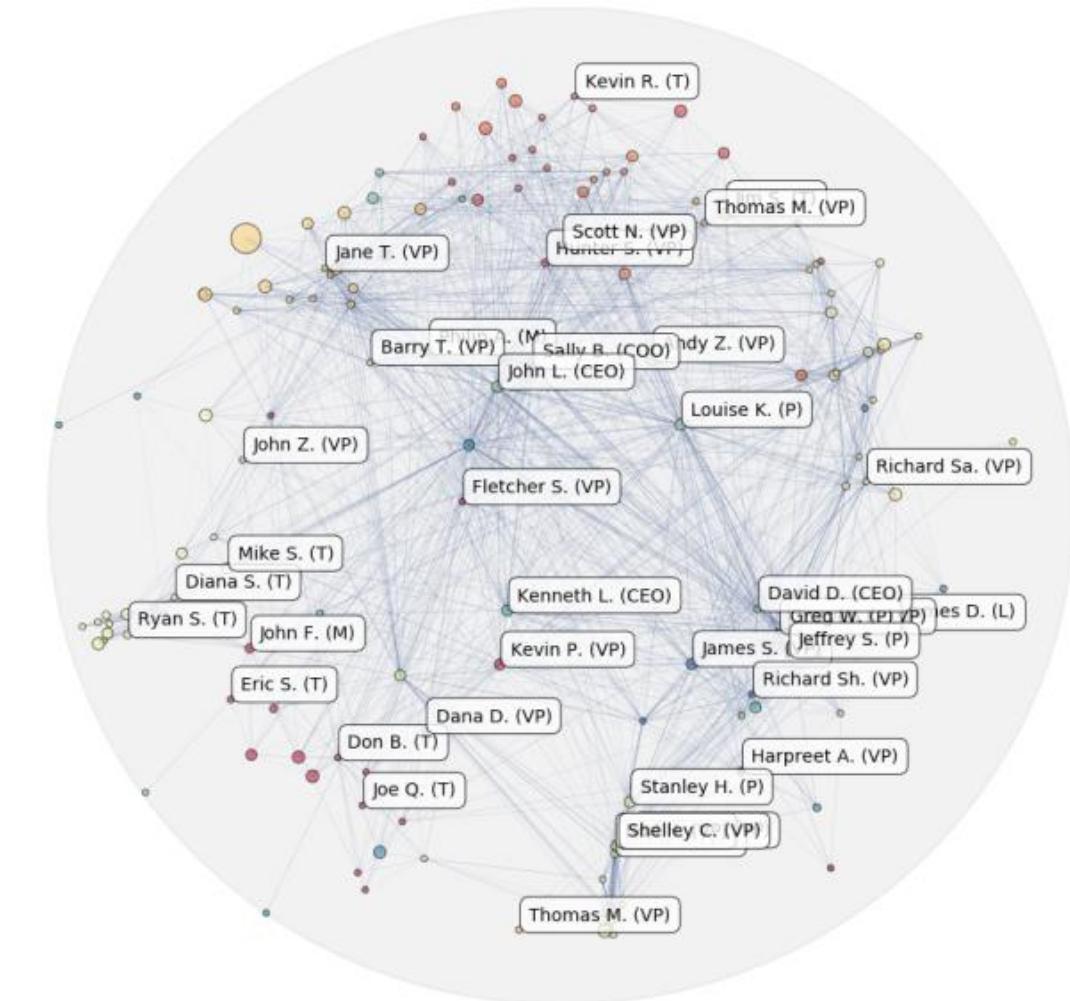
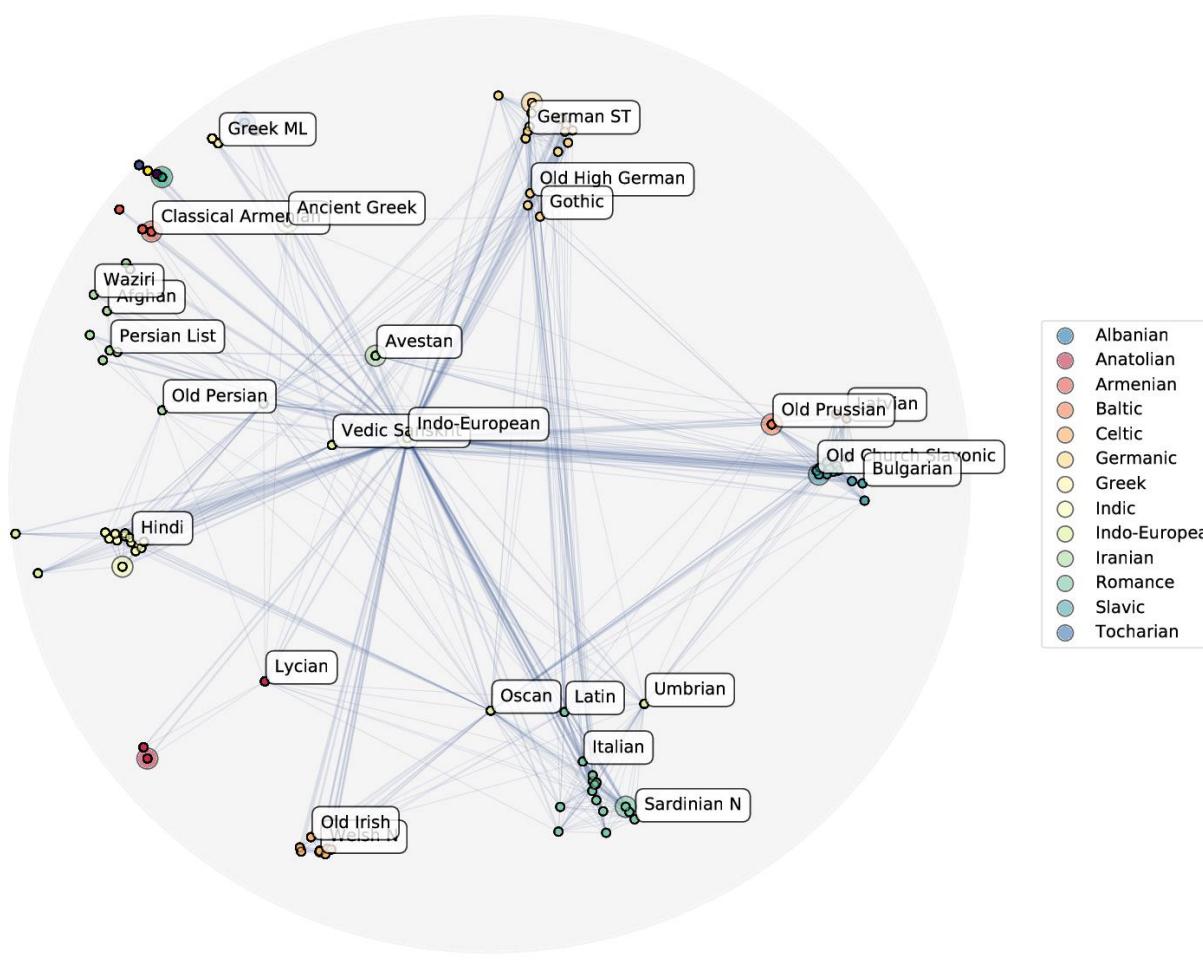
Where $\text{grad } f(\theta_t) \in \mathcal{T}_\theta \mathcal{M}$ denotes the Riemannian gradient and η denotes the learning rate.

Algorithm 1 Riemannian Stochastic Gradient Descent

Input Learning rate η , number of epochs T .
for $t = 1, \dots, T$

$$\begin{aligned}\mathbf{h}_t &\leftarrow g_{\theta_t}^{-1} \nabla f(\theta_t) \\ \text{grad } f(\theta_t) &\leftarrow \text{proj}_{\theta_t}(\mathbf{h}_t) \\ \theta_{t+1} &\leftarrow \exp_{\theta_t}(-\eta \text{grad } f(\theta_t))\end{aligned}$$

2.1.2 Results on Lorentz Model



<https://mnick.github.io/project/geometric-representation-learning/>

Summary

Concepts and functions for hyperbolic geometry

❖ Hyperbolic Models

❖ Manifold and Metric

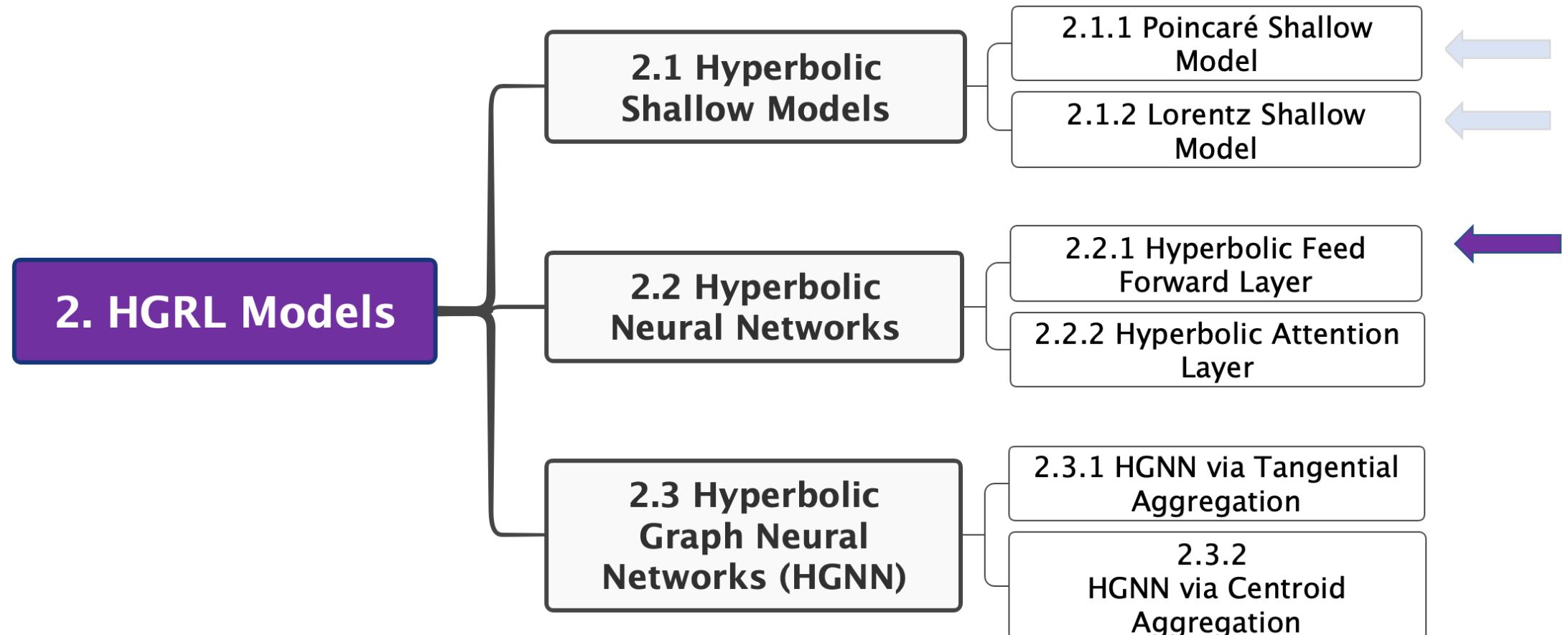
❖ Induced Distance Function

❖ Exponential and Logarithmic Maps

❖ Parallel Transport

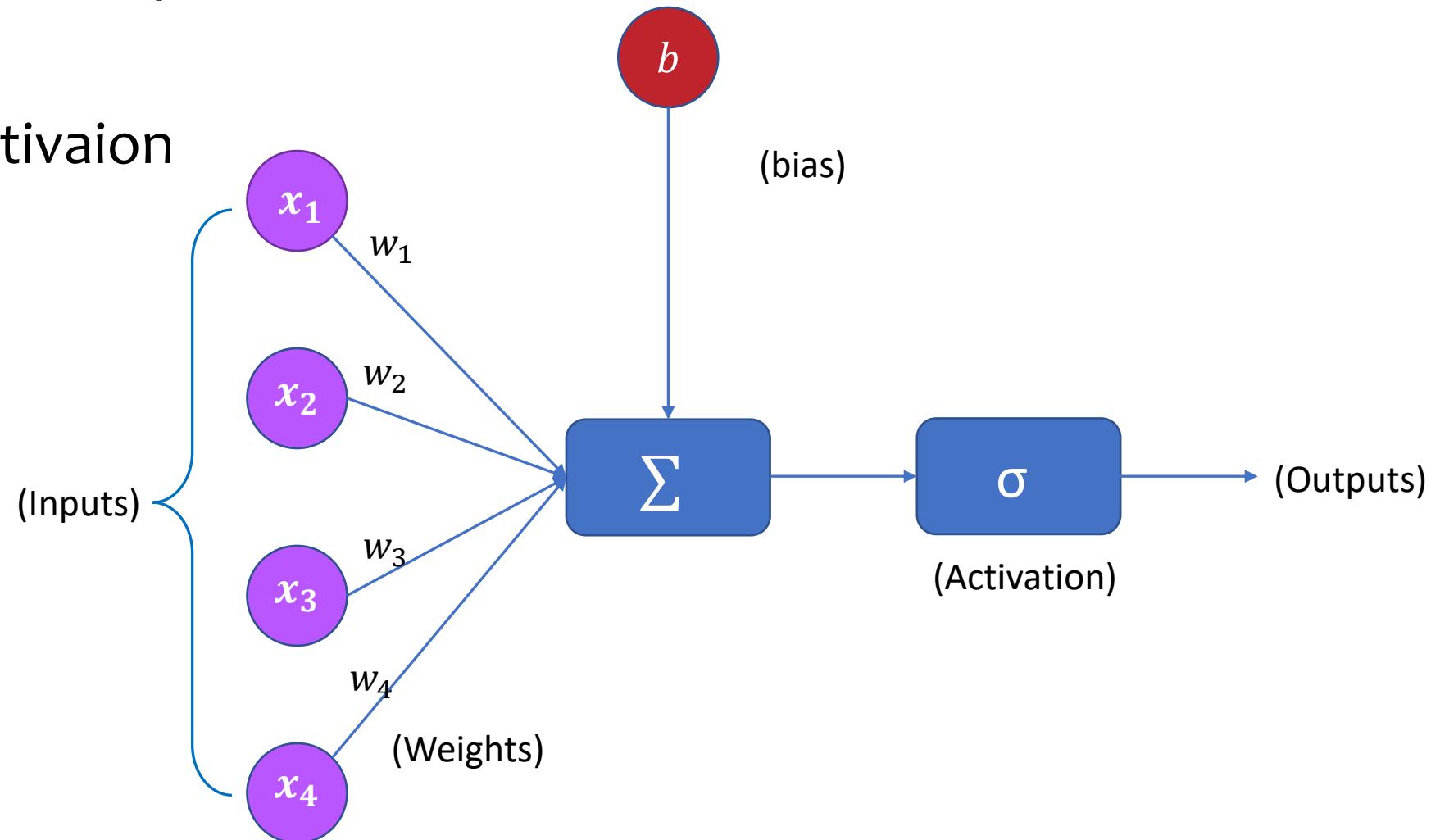
	Poincaré Ball Model	Lorentz Model
Manifold	$\mathcal{B}_c^n = \{x \in \mathbb{R}^n : \langle x, x \rangle_2 < -1/c\}$	$\mathcal{L}_c^n = \{x \in \mathbb{R}^{n+1} : \langle x, x \rangle_{\mathcal{L}} = 1/c\}$
Metric	$g_x^{\mathcal{B}} = (\lambda_x^c)^2 g^{\mathbb{E}^n}$ where $\lambda_x^c = \frac{2}{1+c\ x\ _2^2}$ and $g^{\mathbb{E}^n} = \mathbf{I}_n$	$g_x^{\mathcal{L}} = \eta$, where η is I except $\eta_{0,0} = -1$
Induced distance	$d_{\mathcal{B}}^c(x, y) = \frac{1}{\sqrt{ c }} \cosh^{-1} \left(1 - \frac{2c\ x-y\ _2^2}{(1+c\ x\ _2^2)(1+c\ y\ _2^2)} \right)$	$d_{\mathcal{L}}^c(x, y) = \frac{1}{\sqrt{ c }} \cosh^{-1} (c\langle x, y \rangle_{\mathcal{L}})$
Logarithmic map	$\log_x^c(y) = \frac{2}{\sqrt{ c \lambda_x^c}} \tanh^{-1} \left(\sqrt{ c } \ -x \oplus_c y \ _2 \right) \frac{-x \oplus_c y}{\ -x \oplus_c y\ _2}$	$\log_x^c(y) = \frac{\cosh^{-1}(c\langle x, y \rangle_{\mathcal{L}})}{\sinh(\cosh^{-1}(c\langle x, y \rangle_{\mathcal{L}}))} (y - c\langle x, y \rangle_{\mathcal{L}} x)$
exponential map	$\exp_x^c(v) = x \oplus_c \left(\tanh \left(\sqrt{ c } \frac{\lambda_x^c \ v\ _2}{2} \right) \frac{v}{\sqrt{ c \ v\ _2}} \right)$	$\exp_x^c(v) = \cosh \left(\sqrt{ c } \ v\ _{\mathcal{L}} \right) x + v \frac{\sinh(\sqrt{ c }\ v\ _{\mathcal{L}})}{\sqrt{ c \ v\ _{\mathcal{L}}}}$
Parallel transport	$PT_{x \rightarrow y}^c(v) = \frac{\lambda_x^c}{\lambda_y^c} \text{gyr}[y, -x]v$	$PT_{x \rightarrow y}^c(v) = v - \frac{c\langle y, v \rangle_{\mathcal{L}}}{1+c\langle x, y \rangle_{\mathcal{L}}} (x + y)$

2.2 Hyperbolic Neural Networks



2.2.1 Feed Forward Layer

- Matrix-vector Multiplication
- Bias Addition
- Non-linear Activation

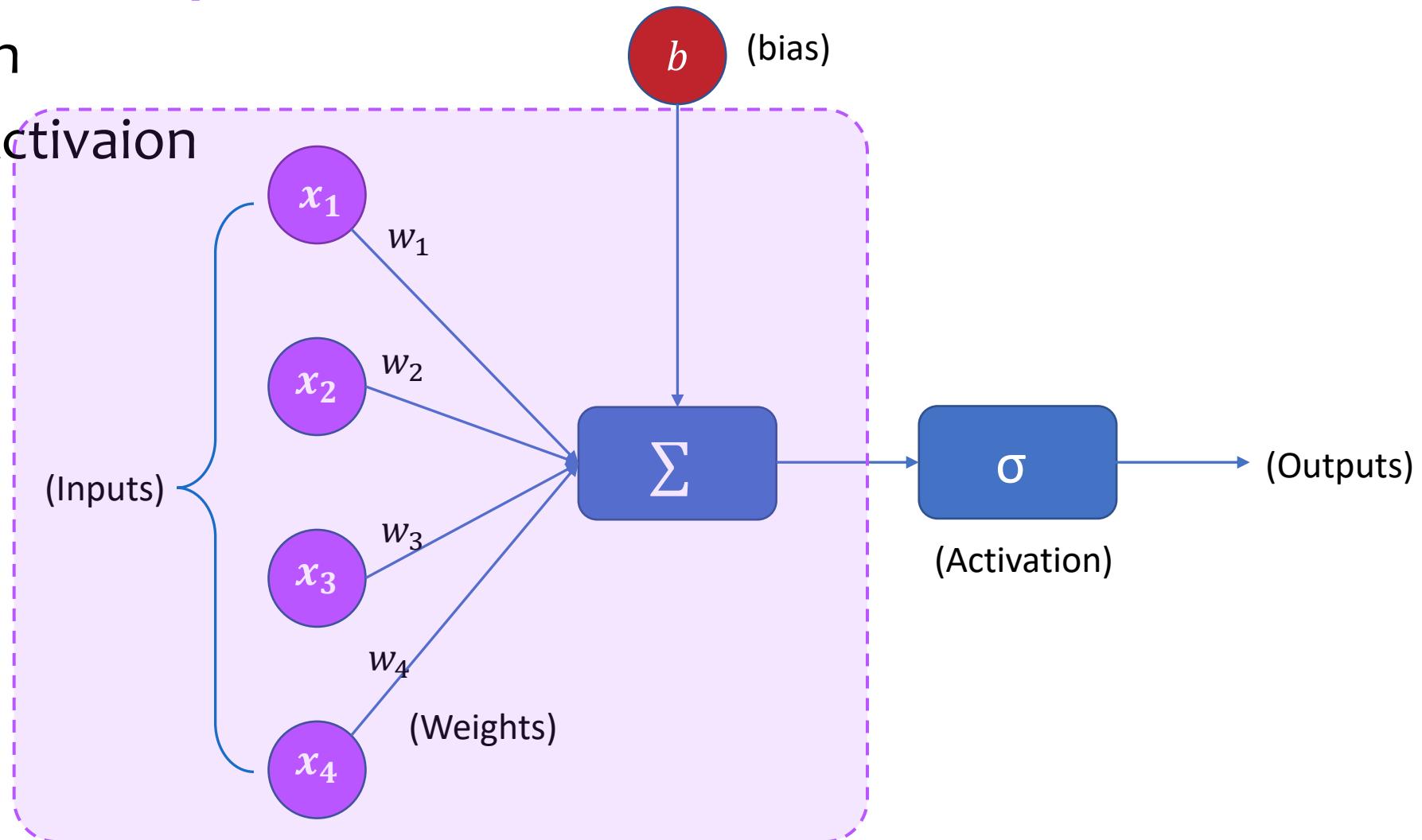


2.2.1 Feed Forward Layer

- Matrix-vector Multiplication

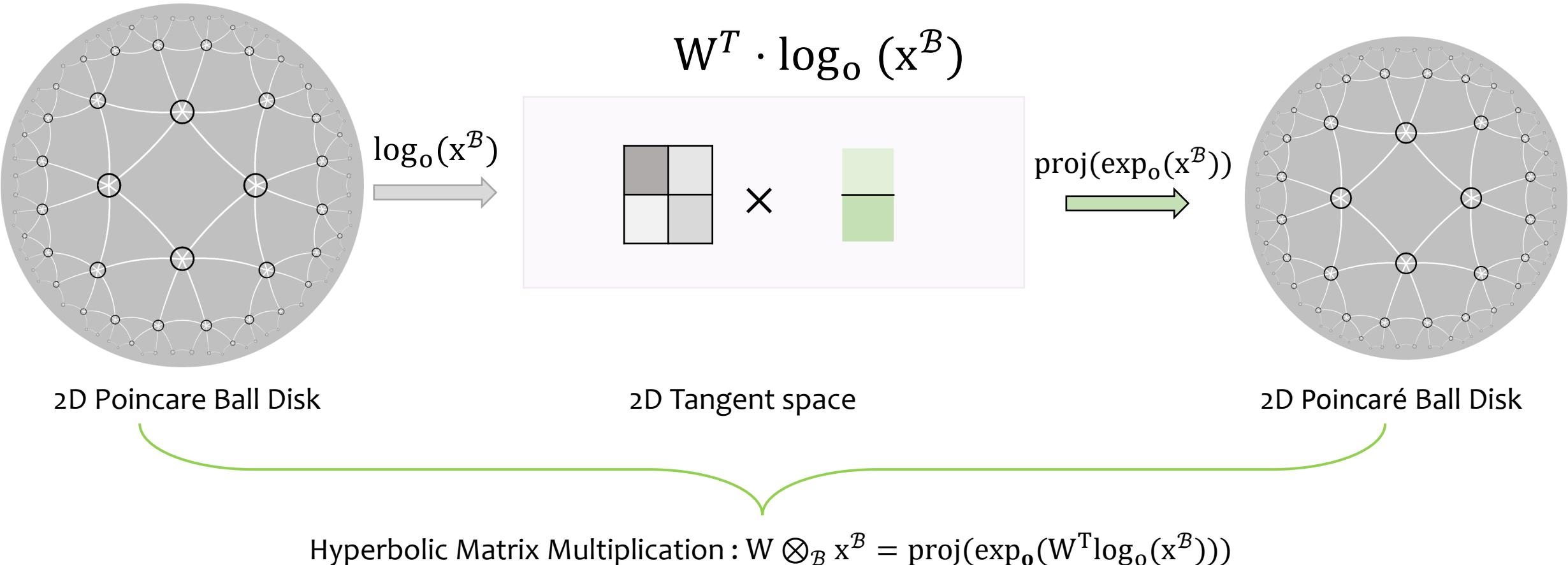
- Bias Addition

- Non-linear Activation



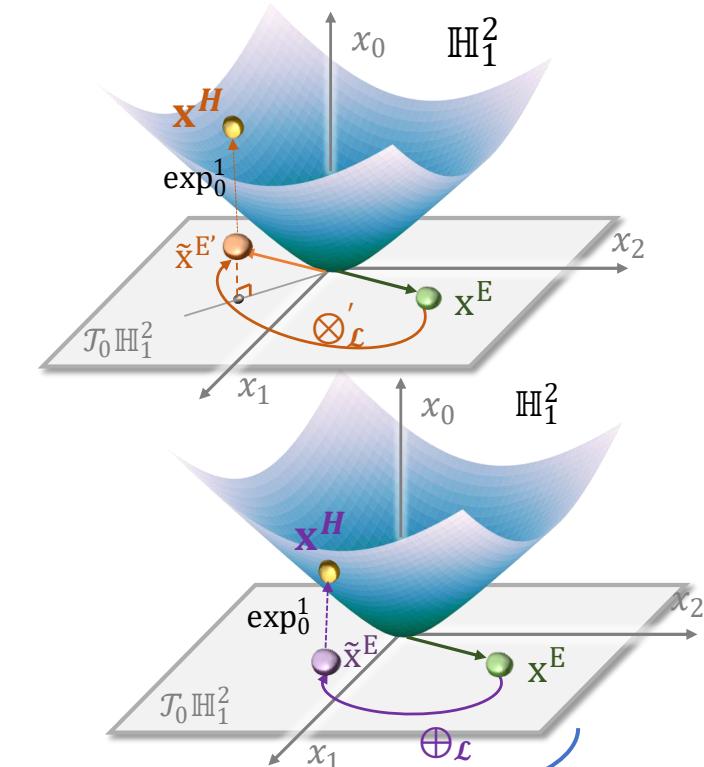
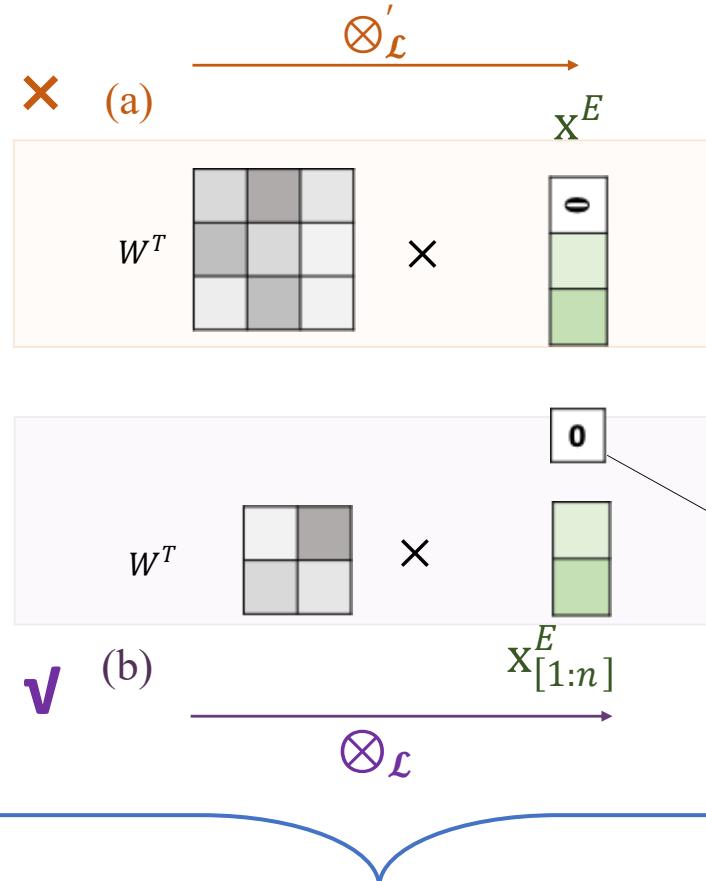
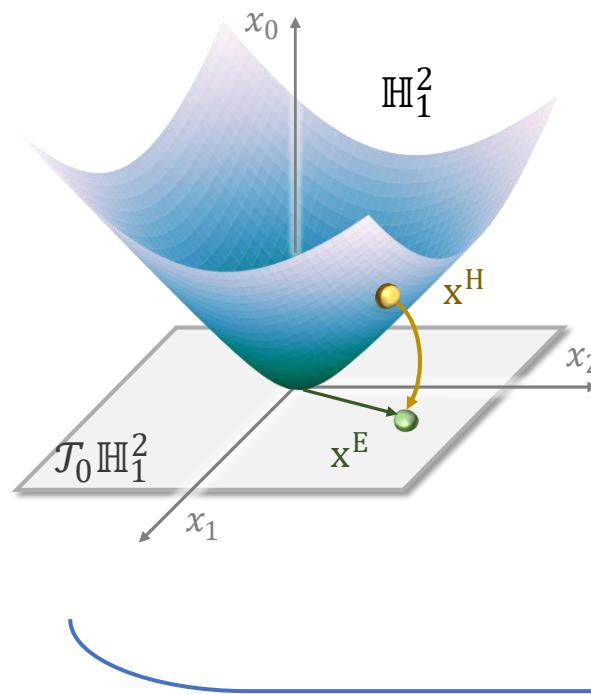
2.2.1 Hyperbolic Feed Forward Layer

- Hyperbolic Matrix-vector Multiplication on Poincaré Ball Model



2.2.1 Hyperbolic Feed Forward Layer

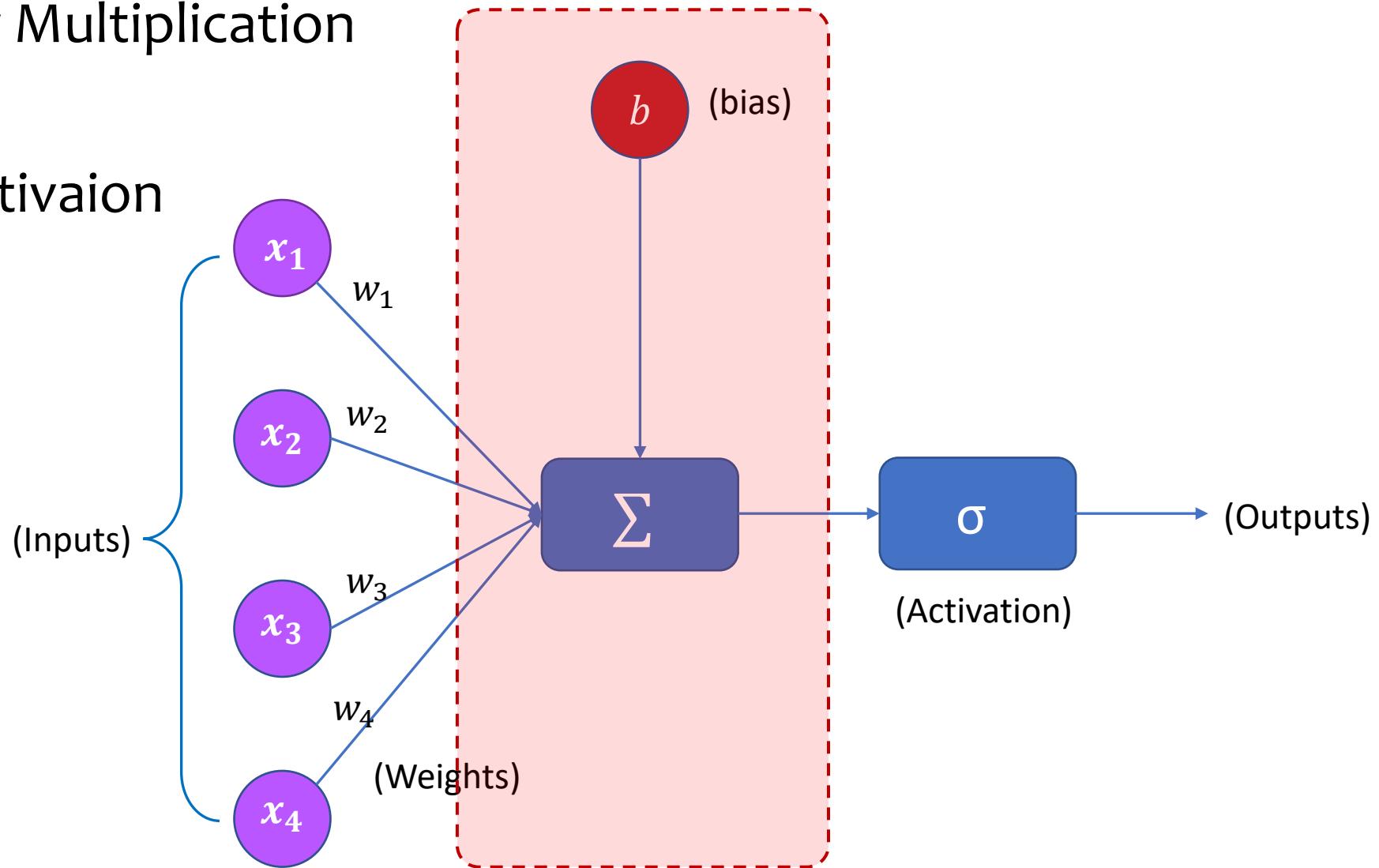
- Hyperbolic Matrix-vector Multiplication on Lorentz Model



$$\text{Hyperbolic Matrix Multiplication : } W \otimes_B x^B = \text{proj}(\exp_{\mathbf{0}}([\mathbf{0}: W^T \log_{\mathbf{0}}(x_{[1:n]}^B)]))$$

2.2.1 Hyperbolic Feed Forward Layer

- Matrix-vector Multiplication
- **Bias Addition**
- Non-linear Activation



2.2.1 Hyperbolic Feed Forward Layer

- Bias addition on Poincaré Ball Model and Lorentz Model

- In Euclidean Space

$$x \leftarrow x + b$$

- In Hyperbolic Space

$$x^H \leftarrow x^H \oplus b = \exp_{x^H} \left(P_{0 \rightarrow x^H}(\log_0(b)) \right)$$

Fig: <https://imgur.com/gallery/tqplYeT>

2.2.1 Hyperbolic Feed Forward Layer

- Bias addition on Poincaré Ball Model and Lorentz Model

- In Euclidean Space

$$x \leftarrow x + b$$

- In Hyperbolic Space

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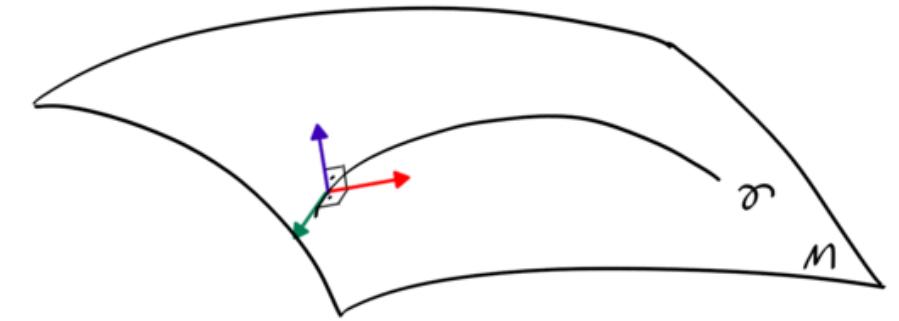
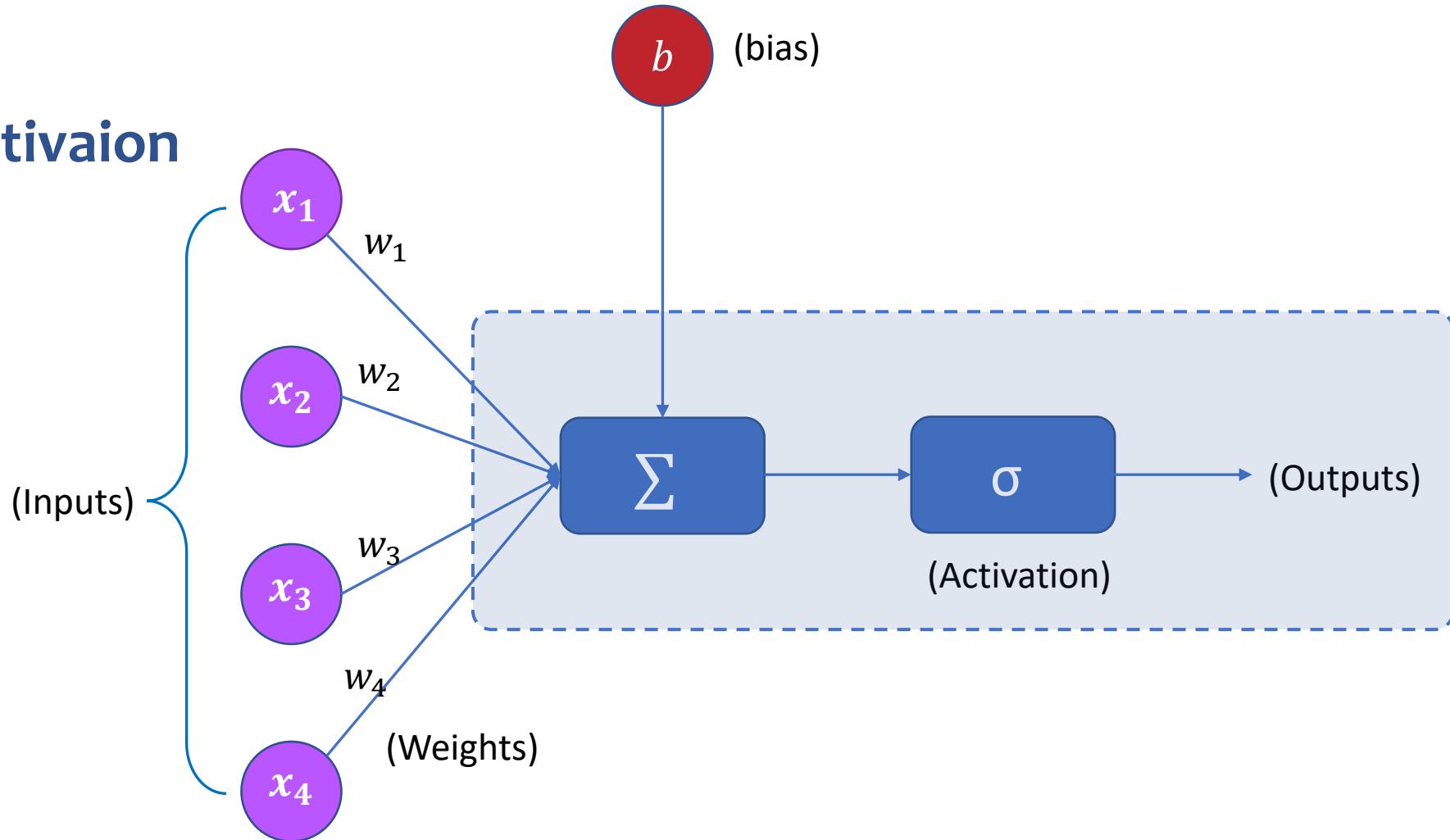


Fig: Parallel Transport

Fig: <https://imgur.com/gallery/tqplYeT>

2.2.1 Hyperbolic Feed Forward Layer

- Matrix-vector Multiplication
- Bias Addition
- Non-linear Activation



2.2.1 Hyperbolic Feed Forward Layer

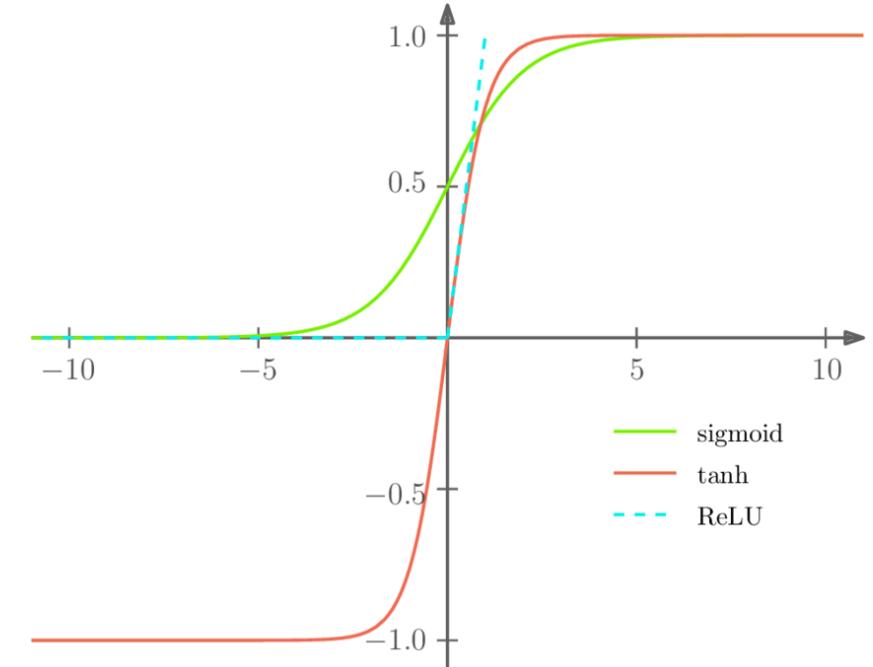
- Non-linear Activation on Poincaré Ball Model and Lorentz Model

- In Euclidean Space

$$x \leftarrow f(x)$$

- In Hyperbolic Space

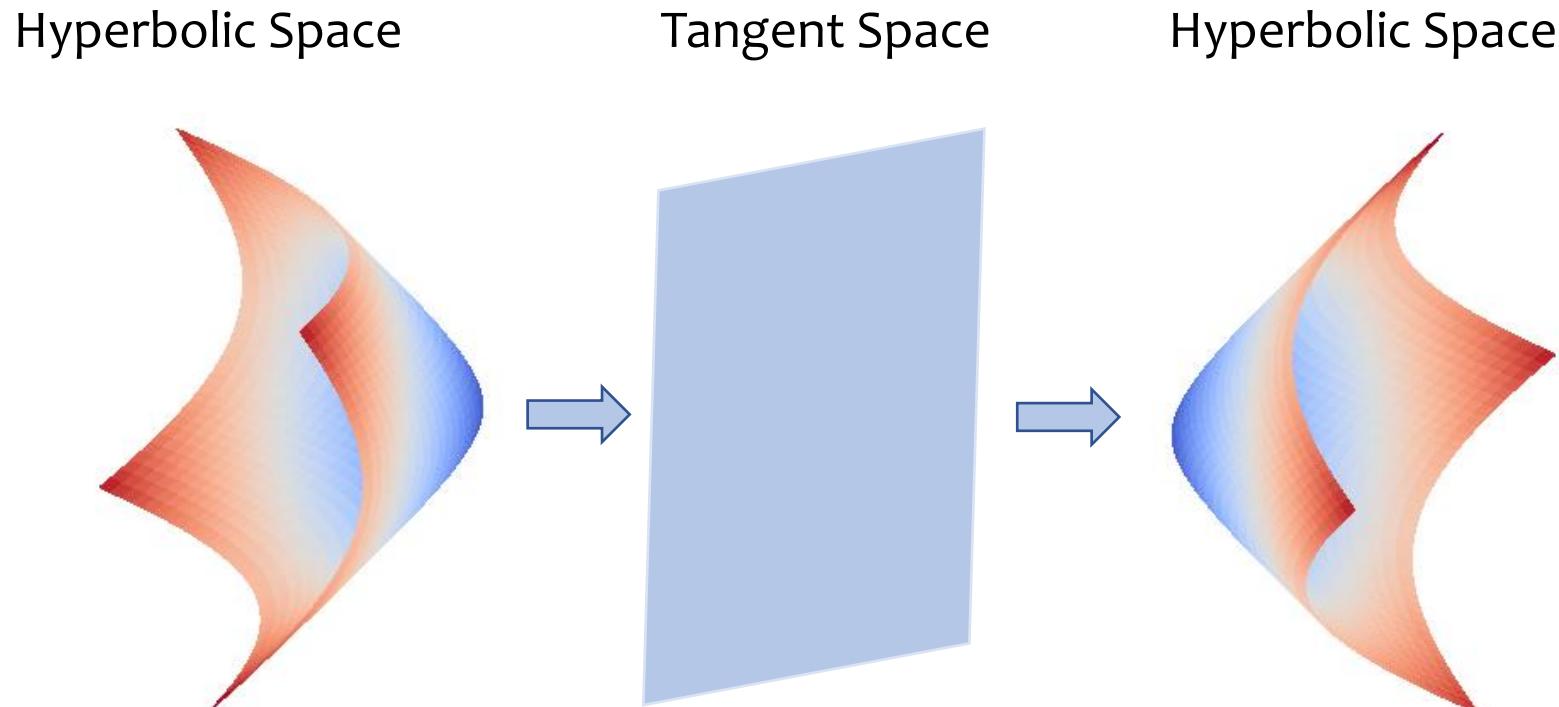
$$x^H \leftarrow f(x^H)$$



$$\text{Update}^{K_{l-1}, K_l}(x^H) := \exp_0^{K_l} \left(f \left(\log_0^{K_{l-1}}(x^H) \right) \right)$$

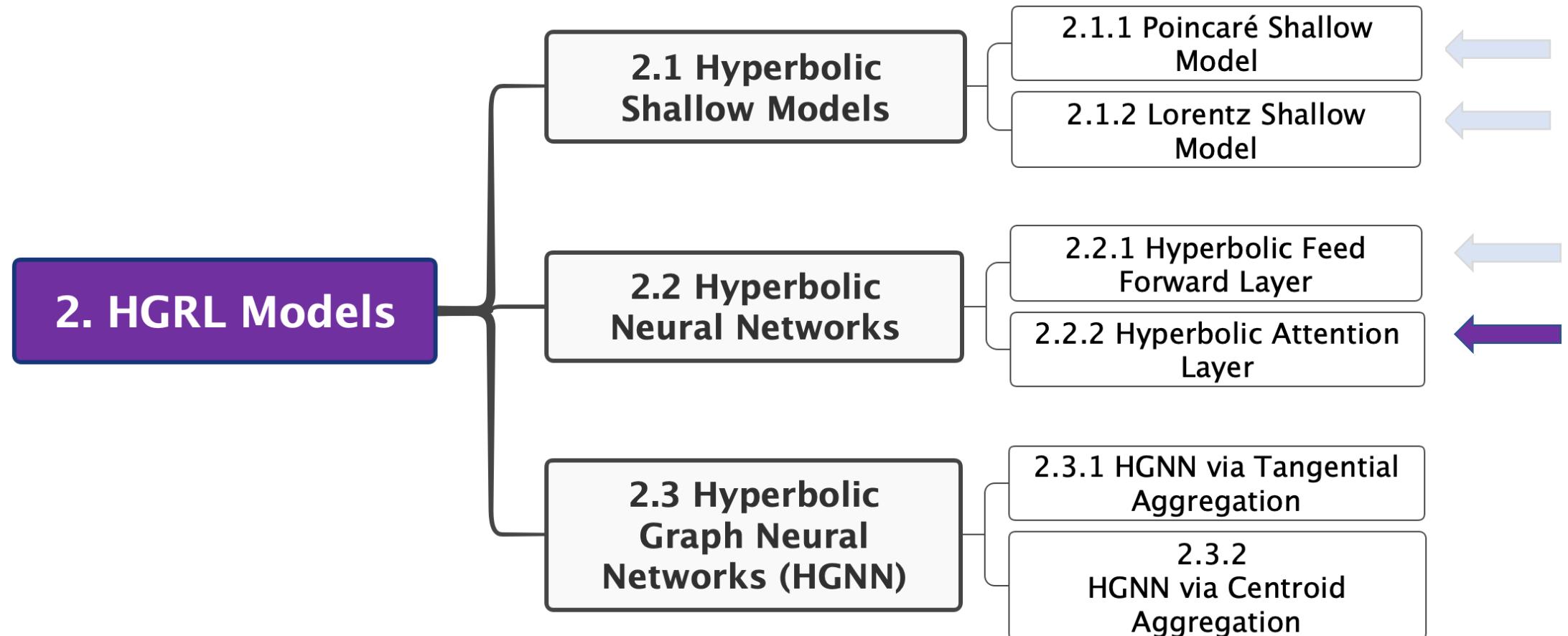
Fig: <https://imgur.com/gallery/tqplYeT>

2.2.1 Uniform Paradigm



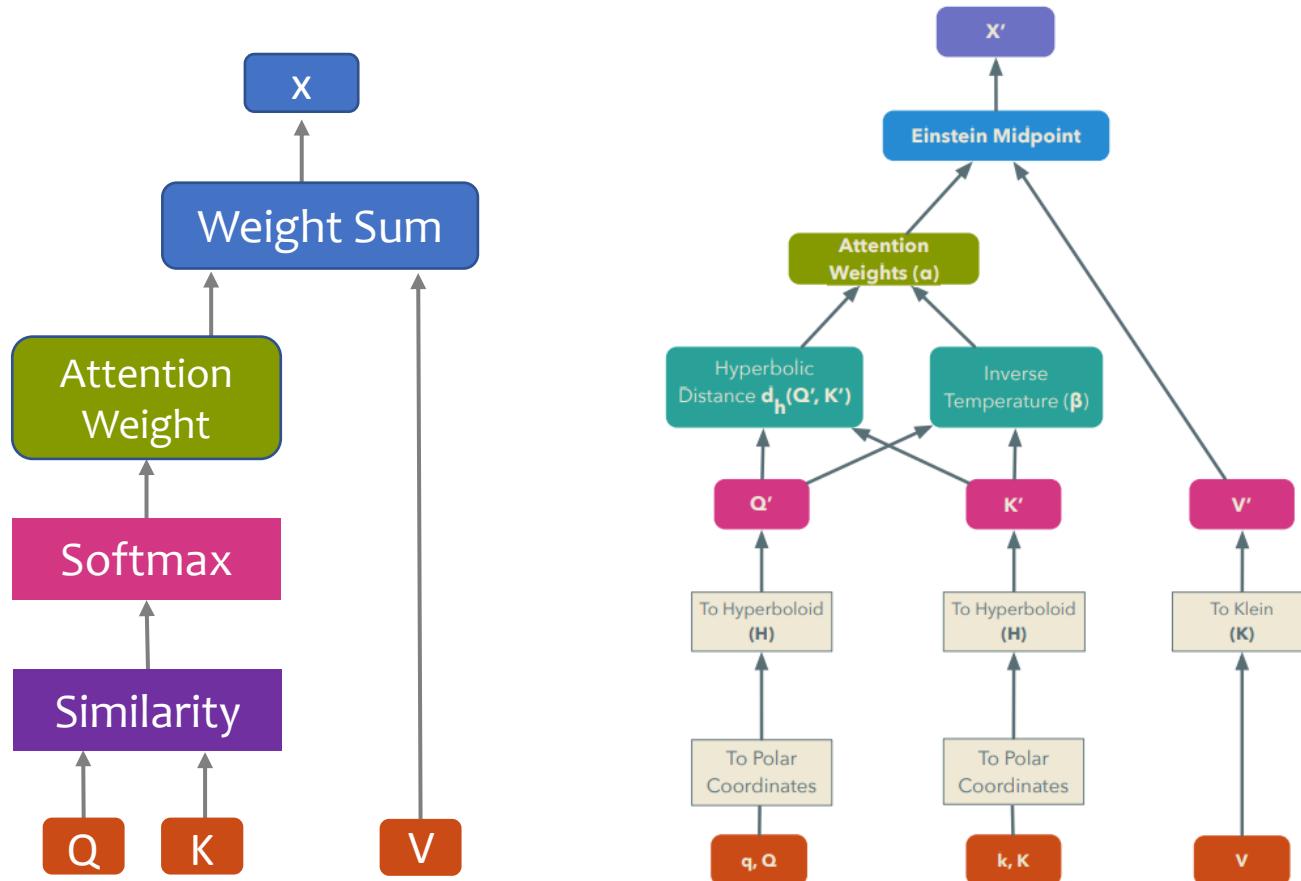
- Hyperbolic space to tangent space
- Operations on tangent space
- Tangent space to Hyperbolic space

2.2 Hyperbolic Neural Networks



2.2 Hyperbolic Neural Networks

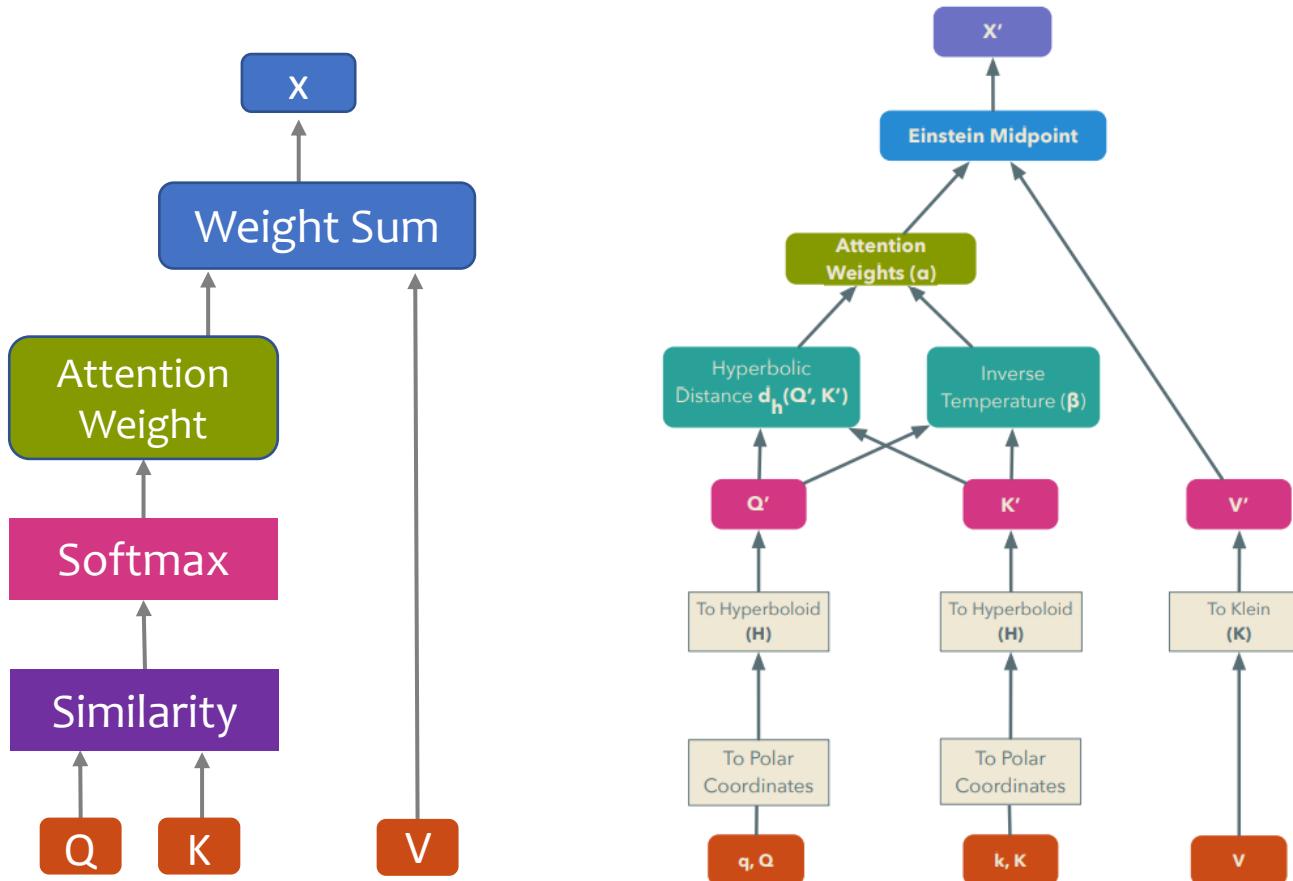
- Hyperbolic Attention Layer



Gulcehre, Caglar, et al. "Hyperbolic attention networks." *arXiv preprint arXiv:1805.09786* (2018).

2.2 Hyperbolic Neural Networks

- Hyperbolic Attention Layer



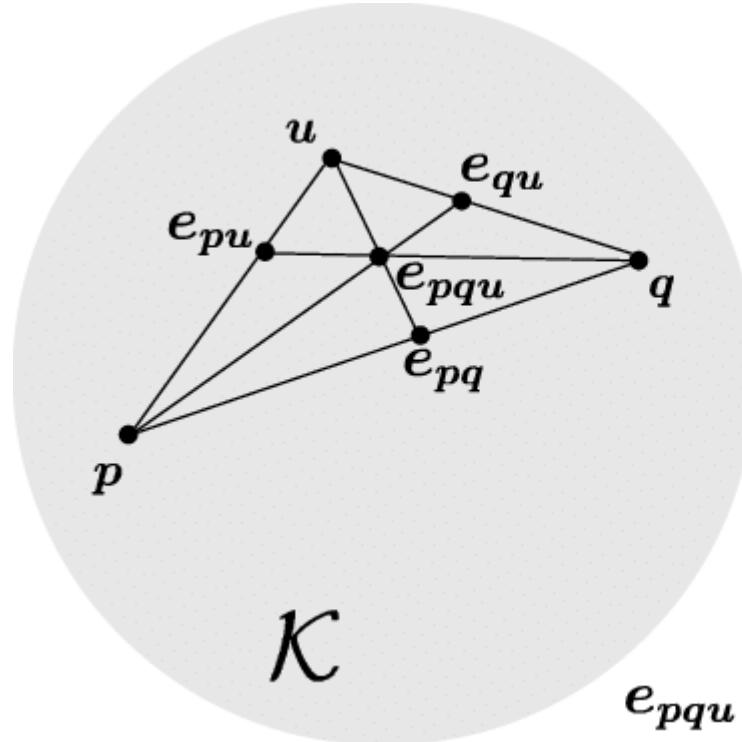
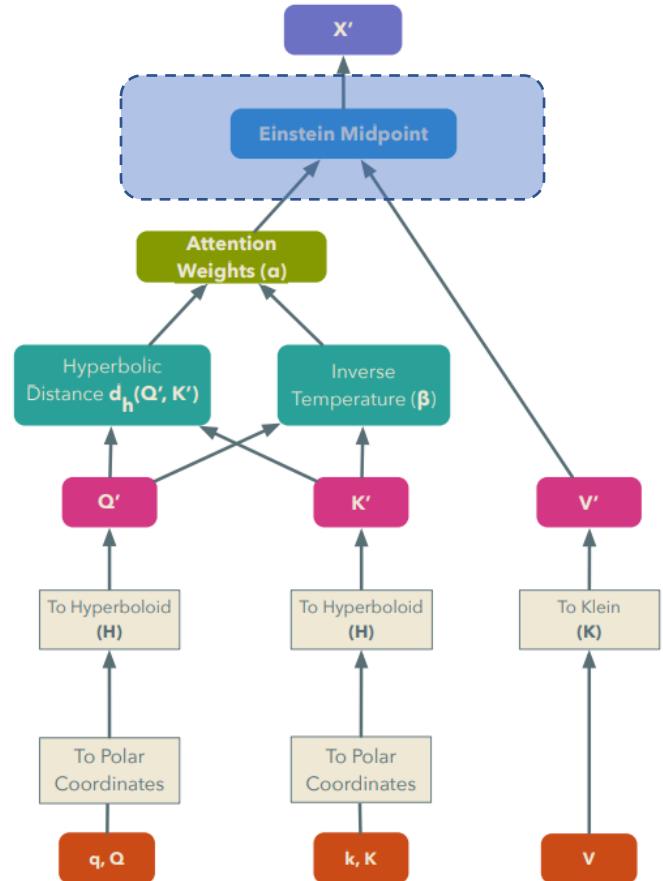
Final Results x :

$$x' = \sum_j \left[\frac{\alpha_{ij}\gamma(v_{ij})}{\sum_\ell \alpha_{i\ell}\gamma(v_{i\ell})} \right] v_{ij}$$

Attention Weights:

$$\alpha(\mathbf{q}_i, \mathbf{k}_i) = f(-\beta d_h(\mathbf{q}_i, \mathbf{k}_j) - c)$$

Einstein Midpoint



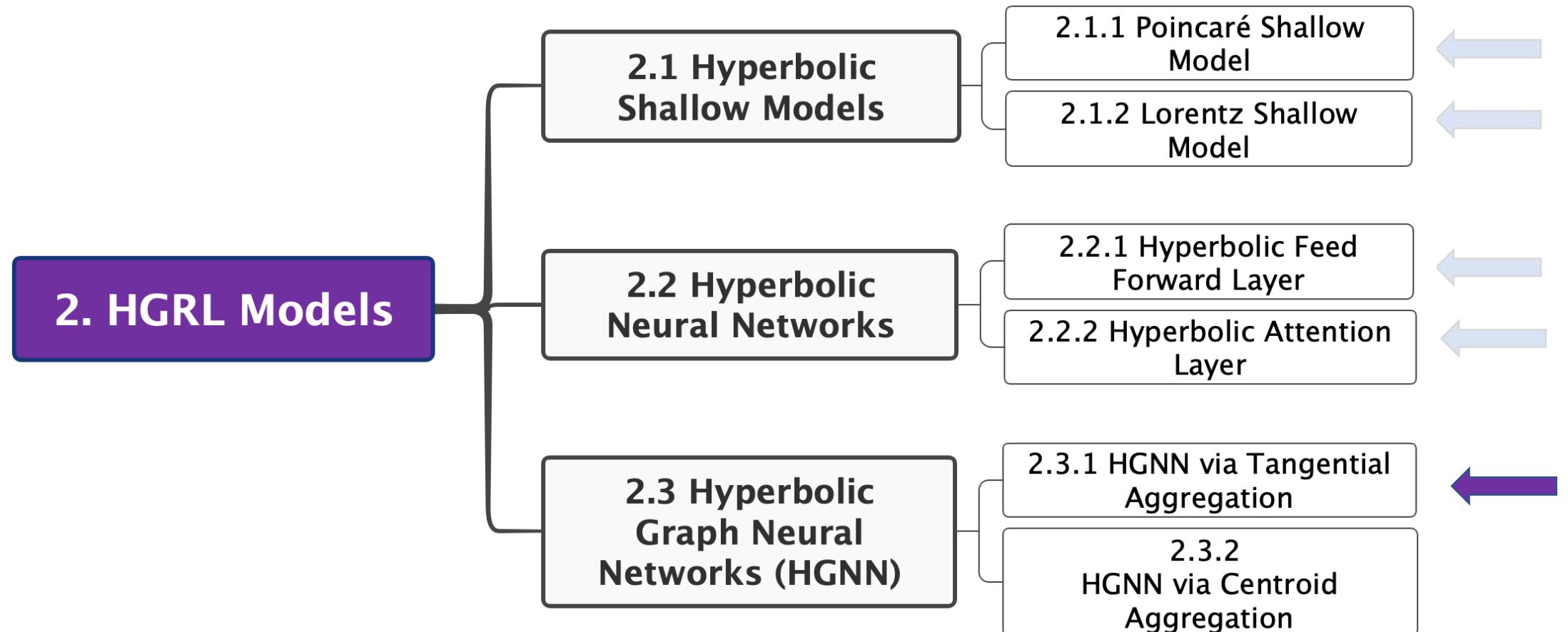
$$e_{pq} = \frac{\gamma_p p + \gamma_q q}{\gamma_p + \gamma_q}$$

$$e_{pu} = \frac{\gamma_p p + \gamma_u u}{\gamma_p + \gamma_u}$$

$$e_{qu} = \frac{\gamma_q q + \gamma_u u}{\gamma_q + \gamma_u}$$

$$e_{pqu} = \frac{\gamma_p p + \gamma_q q + \gamma_u u}{\gamma_p + \gamma_q + \gamma_u}$$

2.2 Hyperbolic Neural Networks

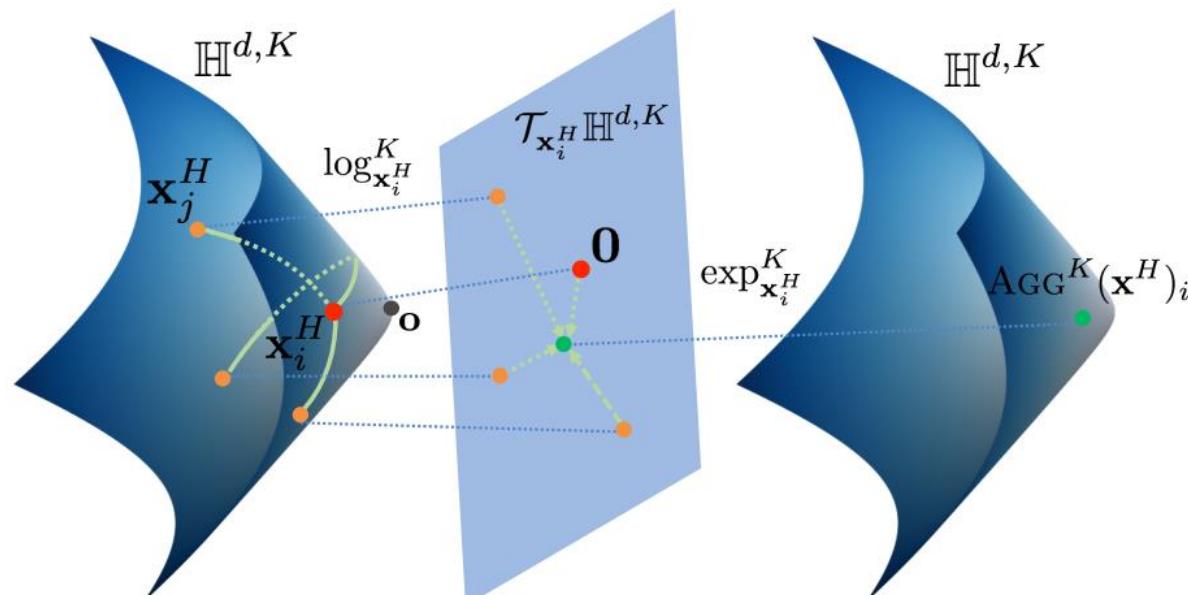


2.3 HGNN via Tangential Aggregation

- Hyperbolic Graph Convolutional Neural Networks

- Feature Transformation (**Message**)
- Neighborhood Aggregation (**Aggregation**)
- Non-linear Activation (**Update**)

- $\mathbf{h}_i^{l,H} = \text{Msg}(\mathbf{x}_i^{l-1,H})$
- $\mathbf{y}_i^{l,H} = \text{AGG}^{K_{l-1}}(\mathbf{h}^{l,H})_i$
- $\mathbf{x}_i^{l,H} = \text{Update}^{K_{l-1}, K_l}(\mathbf{y}_i^{l,H})$



Chami, Ines, et al. "Hyperbolic graph convolutional neural networks." NeurIPS (2019).

2.3 HGNN via Tangential Aggregation

- Input Transformation: $x^{0,H} := \exp_0^K((0, x^{0,E}))$

- **Message:**

$$\mathbf{h}_i^{l,H} = (W^l \otimes^{K_{l-1}} \mathbf{x}_i^{l-1,H}) \oplus^{K_{l-1}} \mathbf{b}^l$$

$$W \otimes^K \mathbf{x}^H := \exp_0^K(W \log_0^K(\mathbf{x}))$$

- **Aggregation:**

$$\mathbf{x}^H \oplus \mathbf{b} := \exp_{\mathbf{x}^H}^K(P_{o \rightarrow \mathbf{x}^H}^K(\mathbf{b}))$$

$$\text{AGG}(\mathbf{x}^H)_i := \exp_{\mathbf{x}_i^H}^K \left(\sum_{j \in N(i)} \boxed{w_{ij}} \log_{\mathbf{x}_i^H}^K(\mathbf{x}_j^H) \right)$$

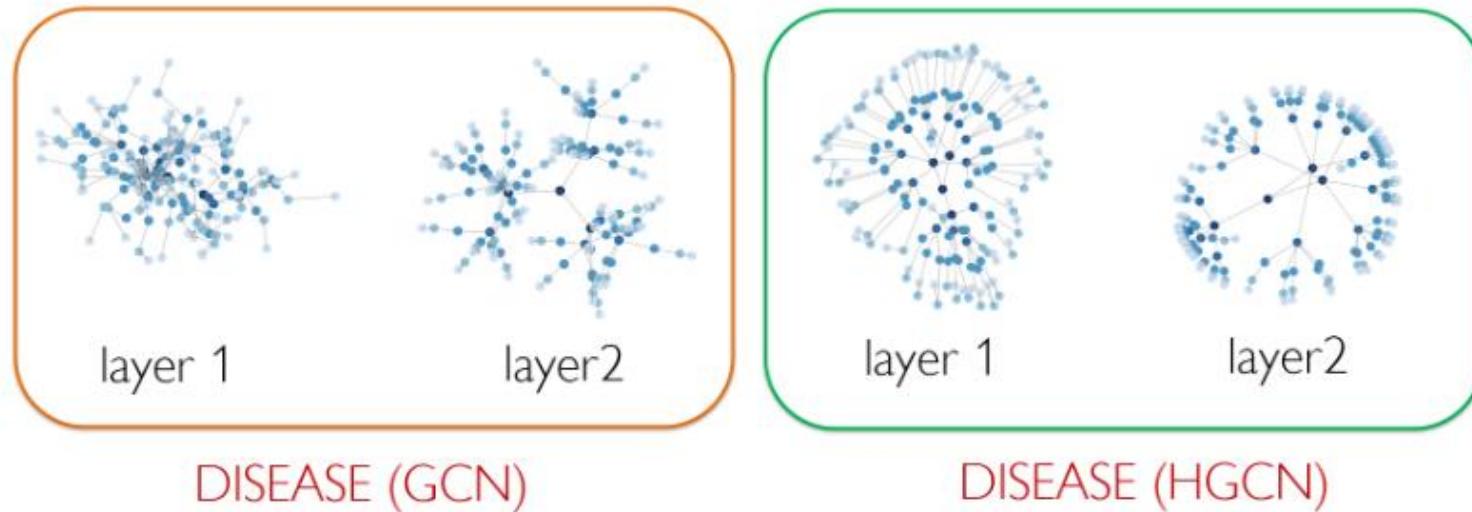
Attention weights

- **Update:**

$$\text{Update}^{K_{l-1}, K_l}(x^H) := \exp_0^{K_l} \left(\sigma \left(\log_0^{K_{l-1}}(x^H) \right) \right)$$

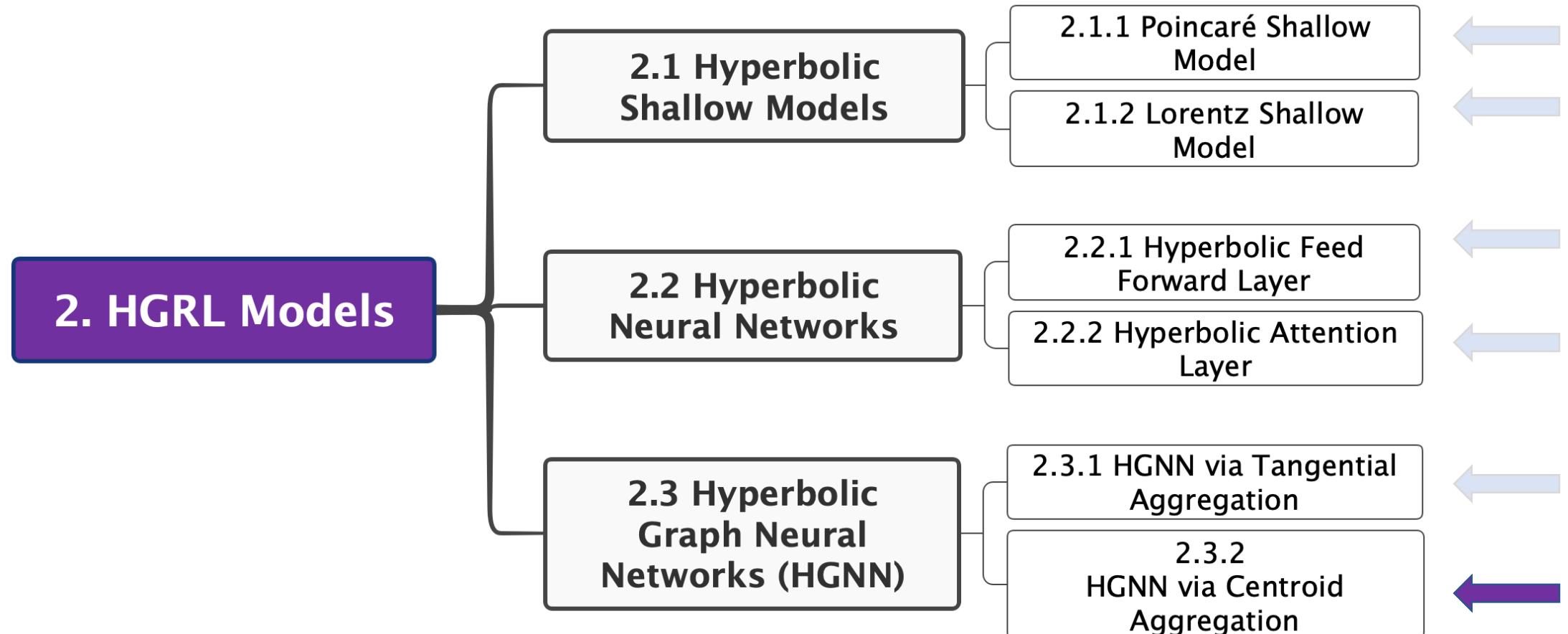
Trainable curvature

2.3 HGNN via Tangential Aggregation



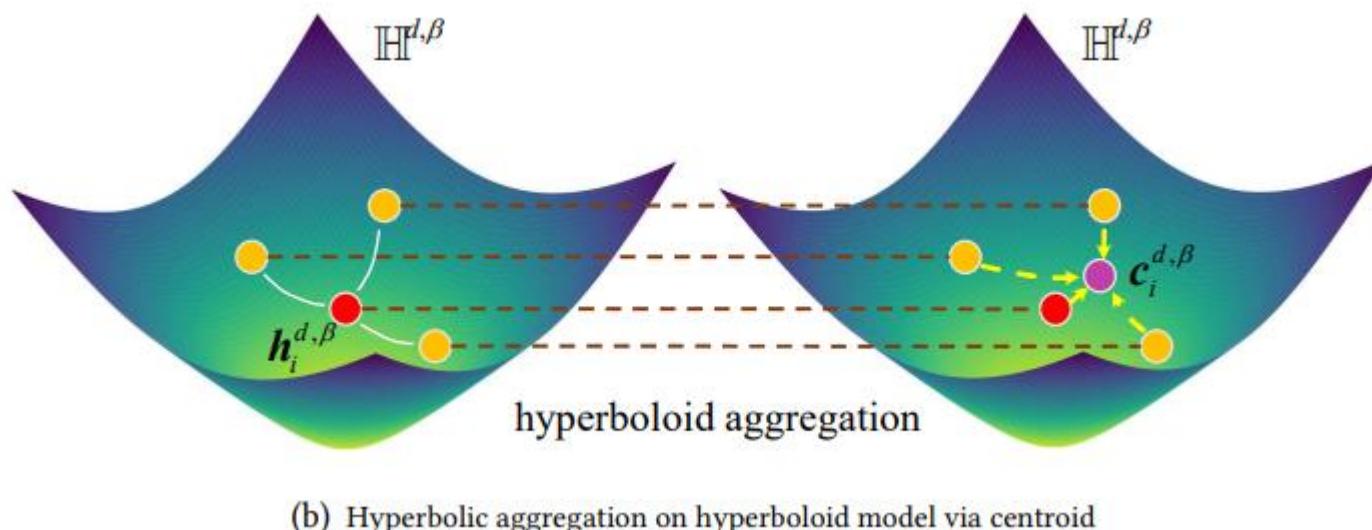
The above show that the 1st layer and 2nd layer embedding for both GCN and HGCN.

HGCN can map the nodes to embeddings of different hyperbolic space with different curvature at each layer, resulting in low distortion embedding for hierarchical data.



2.3 HGNN via Centroid Aggregation

- Hyperbolic Graph Neural Networks
 - Feature Transformation
 - Neighborhood Aggregation
 - Non-linear Activation



Zhang, Yiding, et al. "Lorentzian graph convolutional networks." *The WebConf.* 2021.

2.3 HGNN via Centroid Aggregation

- Input Transformation: $x^{0,H} := \exp_0^K((0, x^{0,E}))$

- **Message:**

$$h_i^{l,H} = (W^l \otimes^{K_{l-1}} x_i^{l-1,H})$$

- **Aggregation:**

$$W \otimes^K x^H := \exp_0^K \left((0, W \log_0^K(x_{[1:n]})) \right)$$

$$\text{AGG}(x^H)_i := \frac{\sum_{j \in N(i)} w_{ij} x_j^H}{\| \sum_{j \in N(i)} w_{ij} x_j^H \|_{\mathcal{L}}}$$

- **Update:**

Edge weights/attention weights

Trainable curvature

$$\text{Update}^{K_{l-1}, K_l}(x^H) := \exp_0^{K_l} \left(0, \sigma \left(\log_0^{K_{l-1}}(x_{[1:n]}^H) \right) \right)$$

Table 4: AUC (%) for link prediction task. The best results are marked by bold numbers.

Dataset	dimension	deepwalk	poincaréEmb	GraphSage	GCN	GAT	HGCN	κ GCN	HAT	LGCN
Disease $\delta_{avg} = 0.00$	8	57.3±1.0	67.9±1.1	65.4±1.4	76.9±0.8	73.5±0.8	84.1±0.7	85.3±0.8	83.9±0.7	89.2±0.7
	16	55.2±1.7	70.9±1.0	68.1±1.0	78.2±0.7	73.8±0.6	91.2±0.6	92.0±0.5	91.8±0.5	96.6±0.6
	32	49.1±1.3	75.1±0.7	69.5±0.6	78.7±0.5	75.7±0.3	91.8±0.3	94.5±0.6	92.3±0.5	96.3±0.5
	64	47.3±0.1	76.3±0.3	70.1±0.7	79.8±0.5	77.9±0.3	92.7±0.4	95.1±0.6	93.4±0.4	96.8±0.4
USA $\delta_{avg} = 0.16$	8	91.5±0.1	92.3±0.2	82.4±0.8	89.0±0.6	89.6±0.9	91.6±0.8	92.0±0.6	92.7±0.8	95.3±0.2
	16	92.3±0.0	93.6±0.2	84.4±1.0	90.2±0.5	91.1±0.5	93.4±0.3	93.3±0.6	93.6±0.6	96.3±0.2
	32	92.5±0.1	94.5±0.1	86.6±0.8	90.7±0.5	91.7±0.5	93.9±0.2	93.2±0.3	94.2±0.6	96.5±0.1
	64	92.5±0.1	95.5±0.1	89.3±0.3	91.2±0.3	93.3±0.4	94.2±0.2	94.1±0.5	94.6±0.6	96.4±0.2
Amazon $\delta_{avg} = 0.20$	8	96.1±0.0	95.1±0.4	90.4±0.3	91.1±0.6	91.3±0.6	93.5±0.6	92.5±0.7	94.8±0.8	96.4±1.1
	16	96.6±0.0	96.7±0.3	90.8±0.5	92.8±0.8	92.8±0.9	96.3±0.9	94.8±0.5	96.9±1.0	97.3±0.8
	32	96.4±0.0	96.7±0.1	92.7±0.2	93.3±0.9	95.1±0.5	97.2±0.8	94.7±0.5	97.1±0.7	97.5±0.3
	64	95.9±0.0	97.2±0.1	93.4±0.4	94.6±0.8	96.2±0.2	97.1±0.7	95.3±0.2	97.3±0.6	97.6±0.5
Cora $\delta_{avg} = 0.35$	8	86.9±0.1	84.5±0.7	87.4±0.4	87.8±0.9	87.4±1.0	91.4±0.5	90.8±0.6	91.1±0.4	92.0±0.5
	16	85.3±0.8	85.8±0.8	88.4±0.6	90.6±0.7	93.2±0.4	93.1±0.4	92.6±0.4	93.0±0.3	93.6±0.4
	32	82.3±0.4	86.5±0.6	88.8±0.4	92.0±0.6	93.6±0.3	93.3±0.3	92.8±0.5	93.1±0.3	94.0±0.4
	64	81.6±0.4	86.7±0.5	90.0±0.1	92.8±0.4	93.5±0.3	93.5±0.2	93.0±0.7	93.3±0.3	94.4±0.2
Pubmed $\delta_{avg} = 0.36$	8	81.1±0.1	83.3±0.5	86.1±1.1	86.8±0.7	87.0±0.8	94.6±0.2	93.5±0.5	94.4±0.3	95.4±0.2
	16	81.2±0.1	85.1±0.5	87.1±0.4	90.9±0.6	91.6±0.3	96.1±0.2	94.9±0.3	96.2±0.3	96.6±0.1
	32	76.4±0.1	86.5±0.1	88.2±0.5	93.2±0.5	93.6±0.2	96.2±0.2	95.0±0.3	96.3±0.2	96.8±0.1
	64	75.3±0.1	87.4±0.1	88.8±0.5	93.6±0.4	94.6±0.2	96.5±0.2	94.9±0.5	96.5±0.1	96.9±0.0
Citeseer $\delta_{avg} = 0.46$	8	80.7±0.3	79.2±1.0	85.3±1.6	90.3±1.2	89.5±0.9	93.2±0.5	92.6±0.7	93.1±0.3	93.9±0.6
	16	78.5±0.5	79.7±0.7	87.1±0.9	92.9±0.7	92.2±0.7	94.3±0.4	93.8±0.4	93.6±0.5	95.4±0.5
	32	73.1±0.4	79.8±0.6	87.3±0.4	94.3±0.6	93.4±0.4	94.7±0.3	93.5±0.5	94.2±0.5	95.8±0.3
	64	72.3±0.3	79.6±0.6	88.1±0.4	95.4±0.5	94.4±0.3	94.8±0.3	93.8±0.5	94.3±0.2	96.4±0.2



GRENOBLE 19-23.09.2022

3. Applications

Contents

1. INTRODUCTION

- 1.1 An Overview of Graph Representation Learning
- 1.2 Brief Introduction of Riemannian Geometry
- 1.3 Motivation of Hyperbolic Graph Representation Learning

2. HYPERBOLIC GRAPH REPRESENTATION LEARNING (HGRL)

- 2.1 Hyperbolic Shallow Models
- 2.2 Hyperbolic Neural Networks
- 2.3 Hyperbolic Graph Neural Networks

3. APPLICATIONS

- 3.1 HGRL for Recommendation Systems
- 3.2 HGRL for Knowledge Graph
- 3.3 HGRL for other Applications

4. ADVANCED TOPICS

- 4.1 Complex Structures
- 4.2 Evolving Interactions
- 4.3 Geometry-Aware Learning
- 4.4 Trustworthy and Scalability

3.1 HGRL for Recommendation Systems

- Recommender System are Everywhere



Music Recommendation



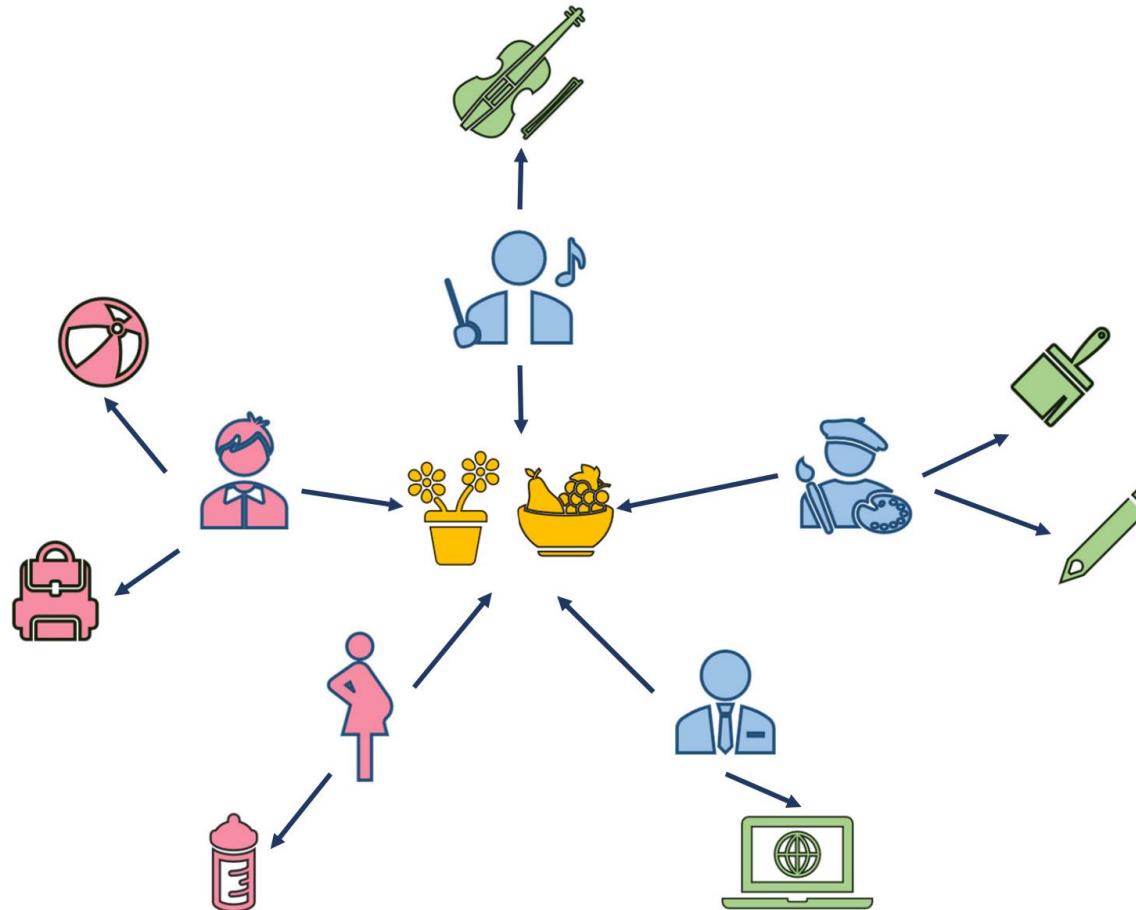
Products Recommendation



News Recommendation

3.1 HGRL for Recommendation Systems

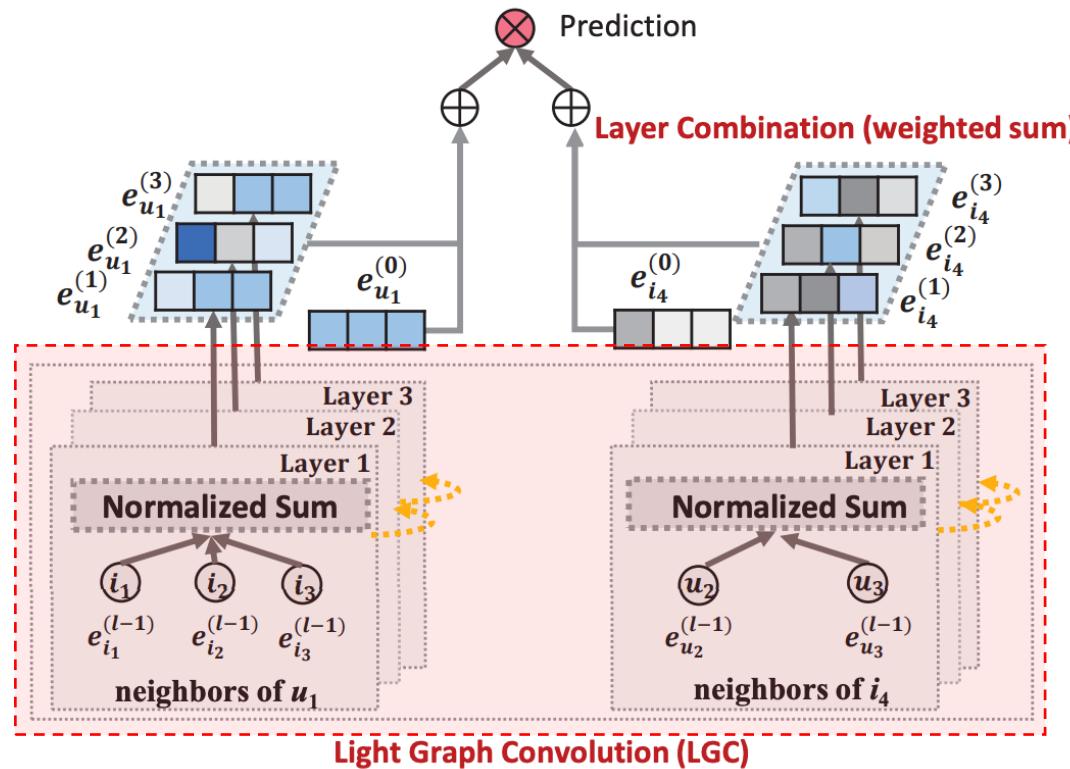
- User-item Networks



Users and items are nodes and the interactions are edges.

3.1 HGRL for Recommendation Systems

- GNN for User-item Network Modeling *in Euclidean Space*

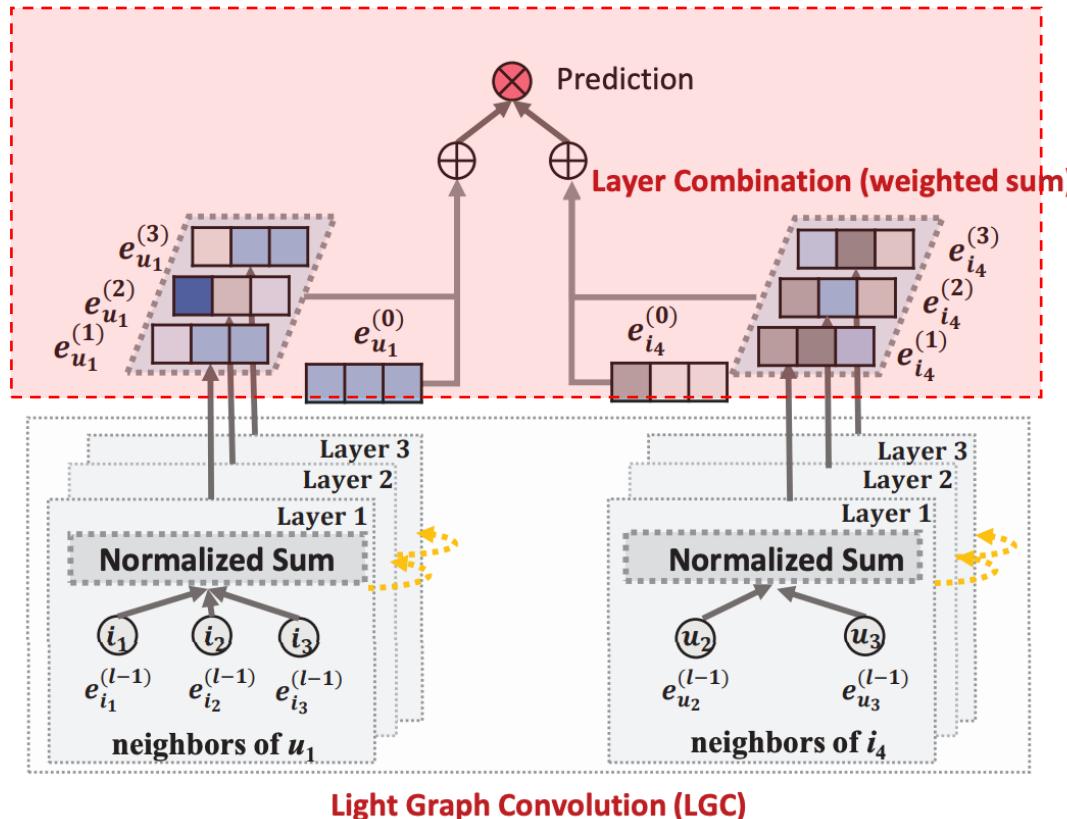


$$\mathbf{e}_u^{(k+1)} = \sum_{i \in \mathcal{N}_u} \frac{1}{\sqrt{|\mathcal{N}_u|} \sqrt{|\mathcal{N}_i|}} \mathbf{e}_i^{(k)},$$
$$\mathbf{e}_i^{(k+1)} = \sum_{u \in \mathcal{N}_i} \frac{1}{\sqrt{|\mathcal{N}_i|} \sqrt{|\mathcal{N}_u|}} \mathbf{e}_u^{(k)}.$$

Note: where \mathbf{e}_u^k and \mathbf{e}_i^k respectively denote the refined embedding of user u and item i after k layers propagation. \mathcal{N}_u denotes the set of items that are interacted by user u , \mathcal{N}_i denotes the set of users that interact with item i .

3.1 HGRL for Recommendation Systems

- GNN for User-item Network Modeling *in Euclidean Space*

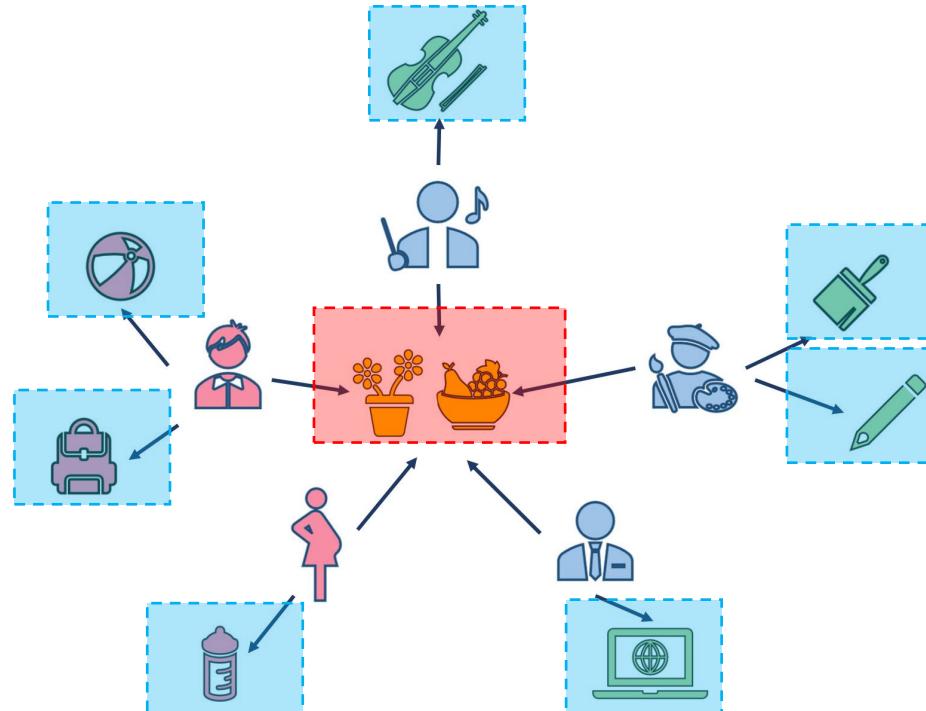


$$\hat{y}_{ui} = \mathbf{e}_u^T \mathbf{e}_i,$$

Note: The model prediction is defined as the inner product of user and item final representations.

3.1 HGRL for Recommendation Systems

- User-item Networks



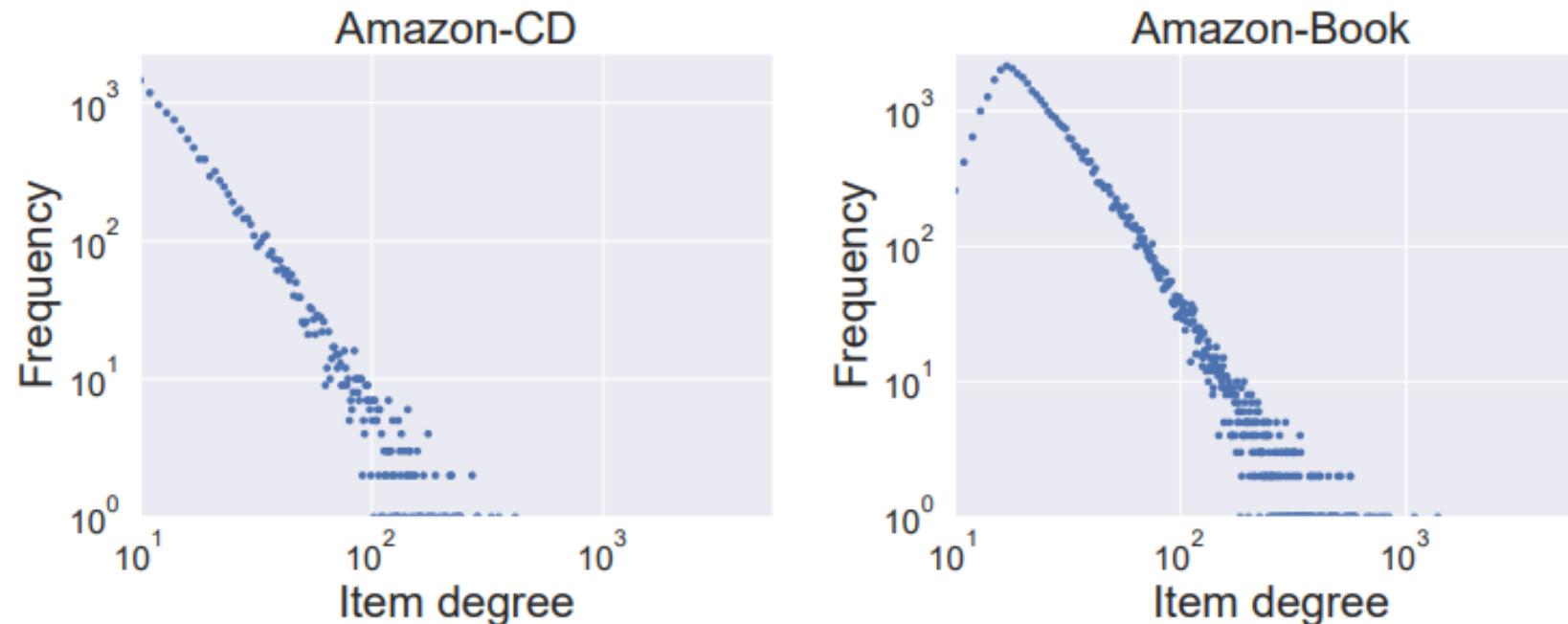
(plotted by Jiahong Liu)

Note: Popular items are competitive while the long-tail item reflects personalized preference or something new.

The popular items are in the minority, whereas the individualized or unpopular items are in the majority.

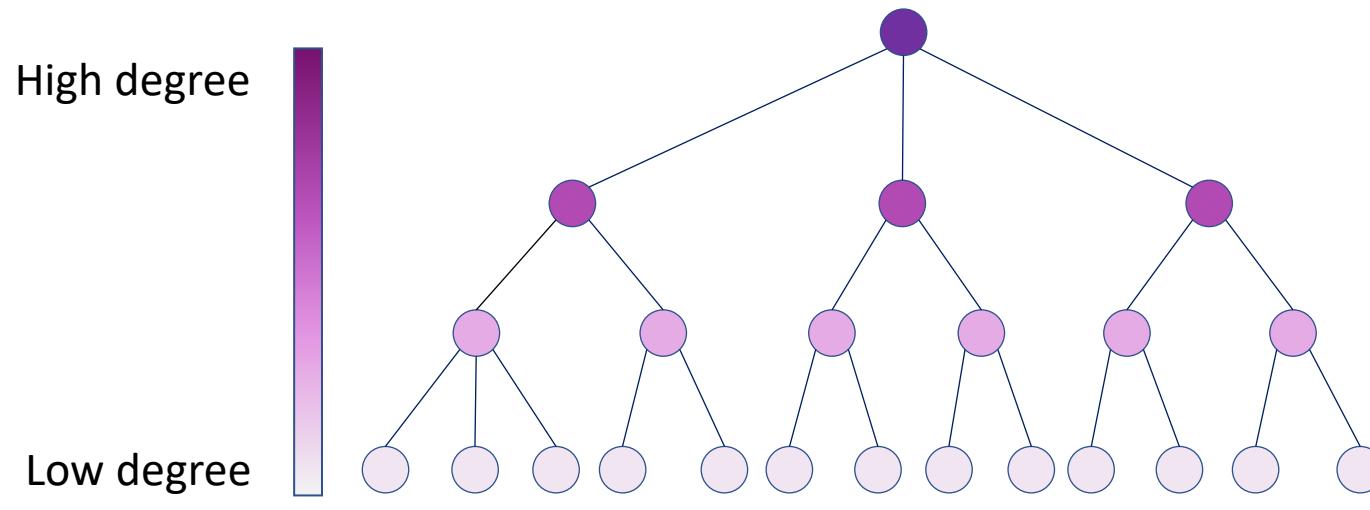
3.1 HGRL for Recommendation Systems

- Degree Distribution



Power-law distribution !!!

3.1 HGRL for Recommendation Systems



Tree-like structure (Power-law distribution)

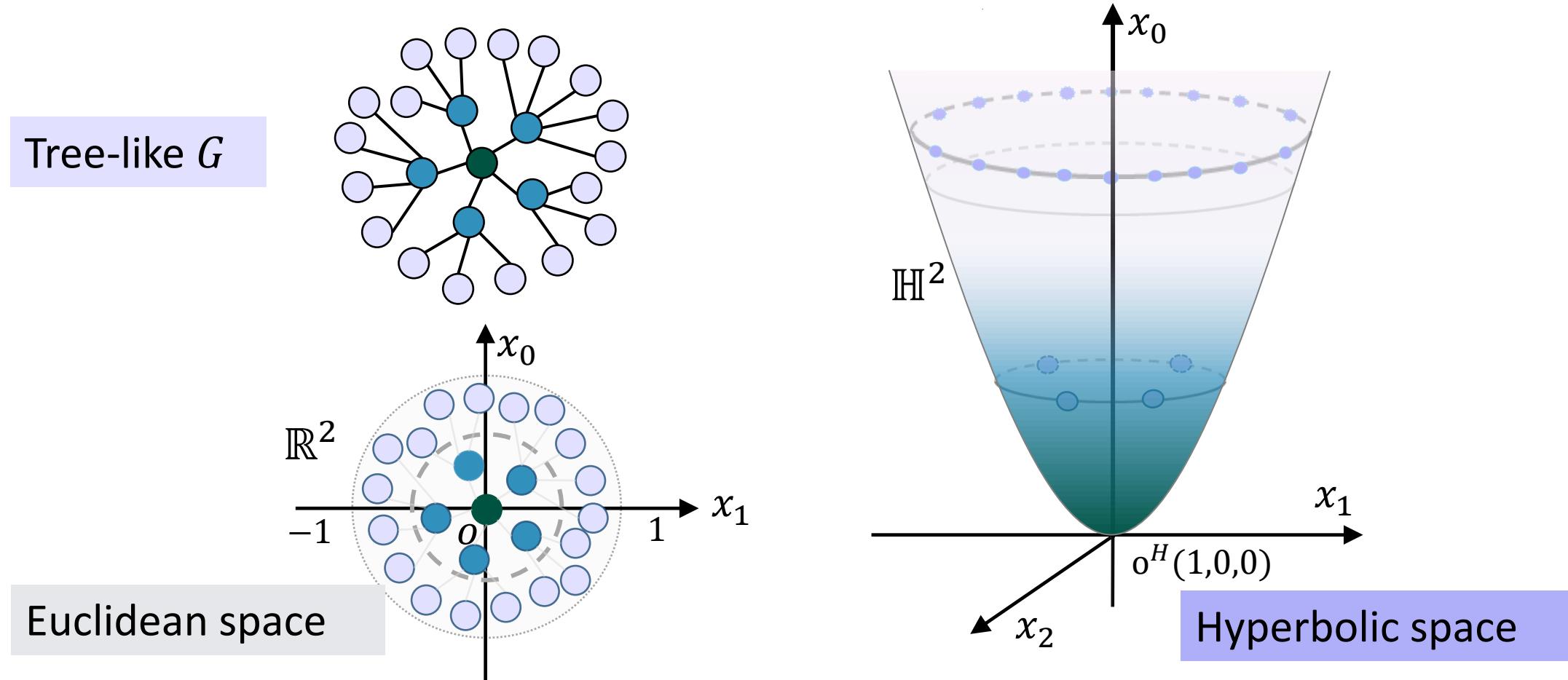
Note:

High degree nodes are liked by the majority which indicates **their popularity is high**.

Low degree nodes are liked by the minority which demonstrates **their popularity is low**.

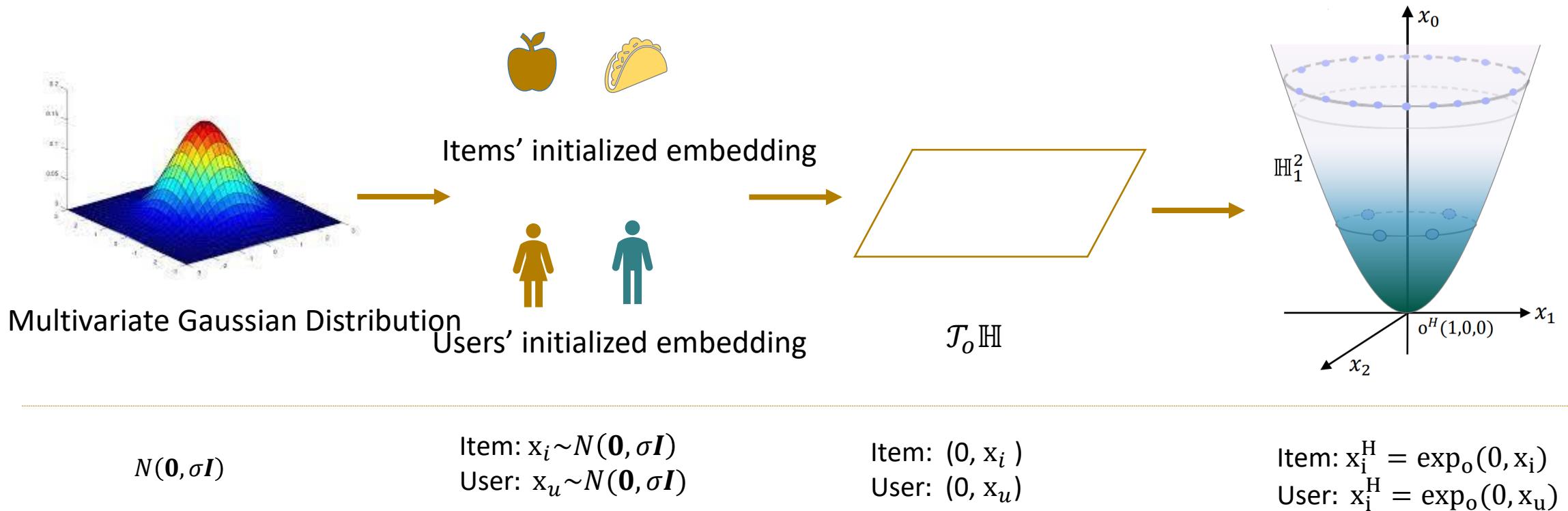
3.1 HGRL for Recommendation Systems

- Embedding Tree-like Graphs



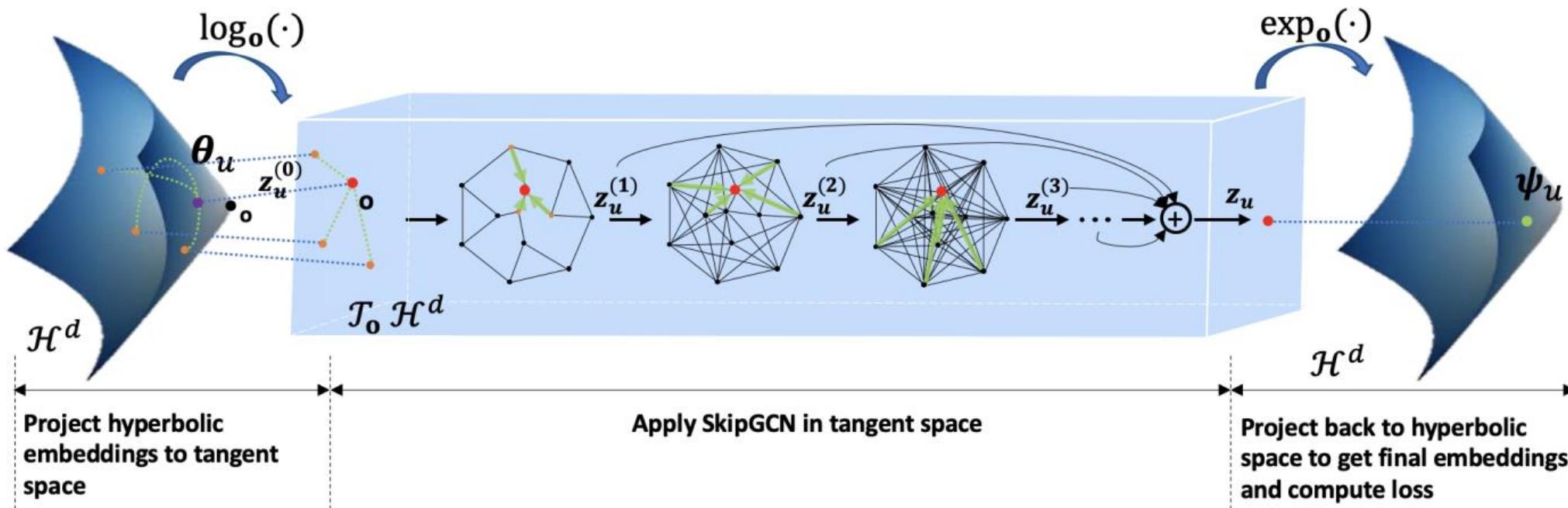
3.1 HGRL for Recommendation Systems

- Hyperbolic Embedding Initializing Layer



3.1 HGRL for Recommendation Systems (WWW'21)

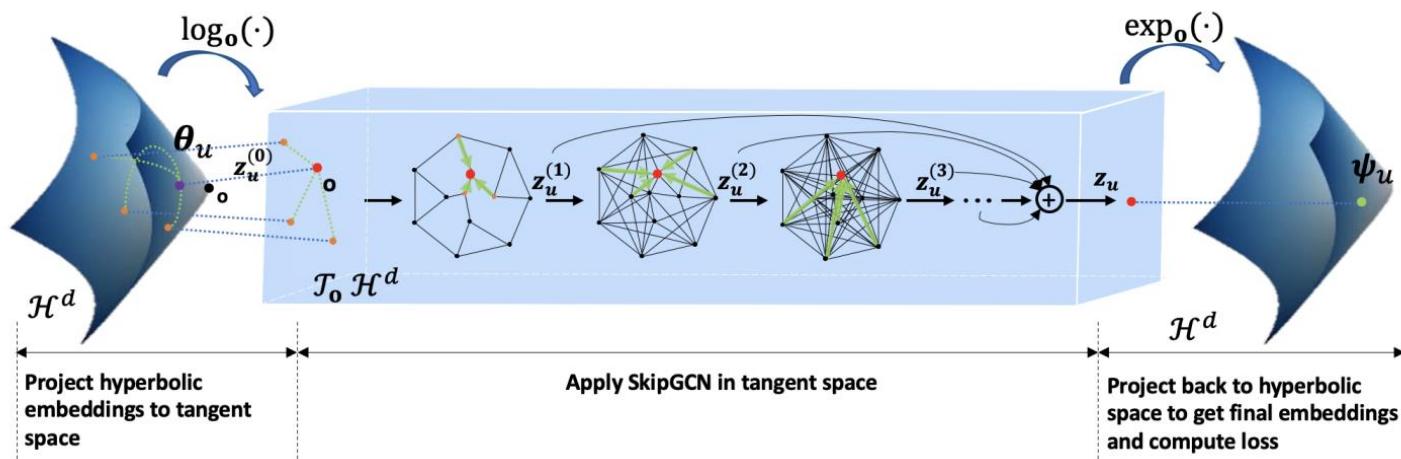
- Hyperbolic Embedding Initializing Layer
- Hyperbolic Message Aggregation



Sun, Jianing, et al. "Hgcf: Hyperbolic graph convolution networks for collaborative filtering." Proceedings of the Web Conference 2021.

3.1 HGRL for Recommendation Systems (WWW'21)

- Hyperbolic Embedding Initializing Layer
- Hyperbolic Message Aggregation
- Loss Function

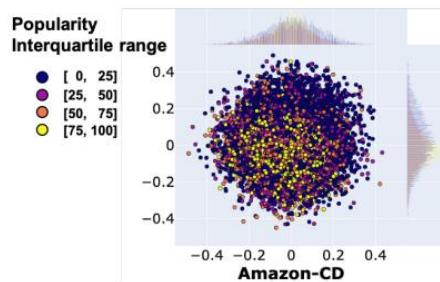


Loss Function

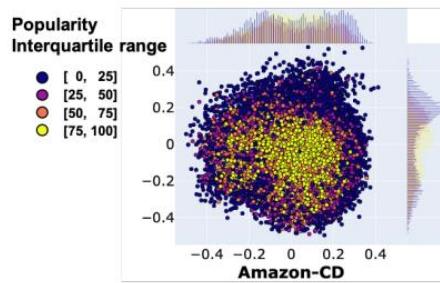
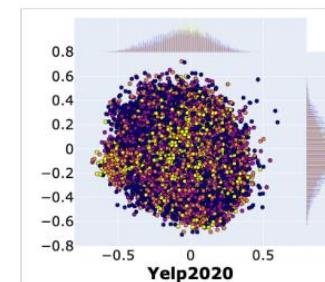
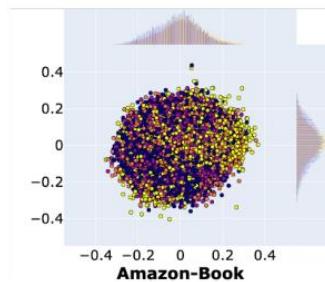
$$L_{\text{margin}}(u, i, j) = \max(d_{\mathcal{L}}(\mathbf{e}_u^H, \mathbf{e}_i^H)^2 - d_{\mathcal{L}}(\mathbf{e}_u^H, \mathbf{e}_j^H)^2 + m, 0)$$

Sun, Jianing, et al. "Hgcf: Hyperbolic graph convolution networks for collaborative filtering." *The WebConf 2021*

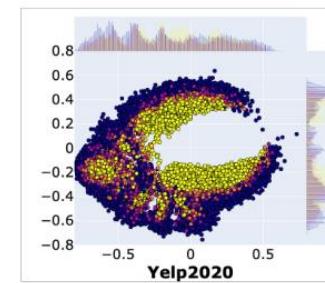
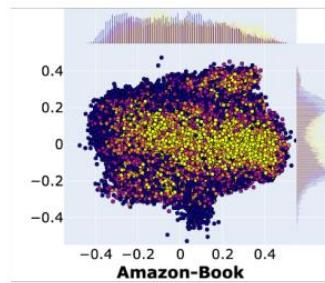
3.1 HGRL for Recommendation Systems (WWW'21)



(a) Item embeddings **before** the graph convolution layers.

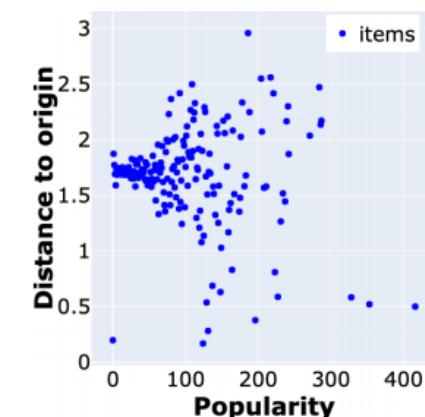


(b) Item embeddings **after** the graph convolution layers.

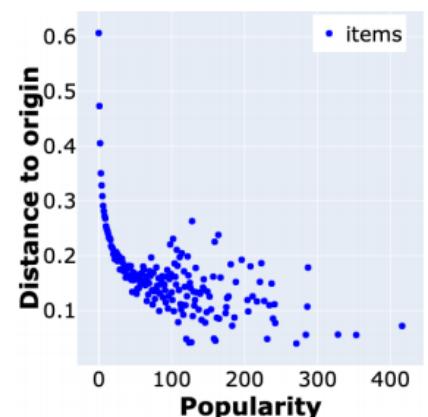


- After the graph convolution layers, a clear hierarchy appears according to popularity.
- In the Amazon datasets this hierarchy is reflected in an almost circular way with the most popular items at the center and the less popular ones away from it.

- BPR tends to cluster less popular items at specific distance from the origin.
- HGCF on the other hand has a clear exponential trend where distance to the origin increases exponentially for less popular items



(a) BPR



(b) HGCF

3.1 HGRL for Recommendation Systems (WSDM '22)

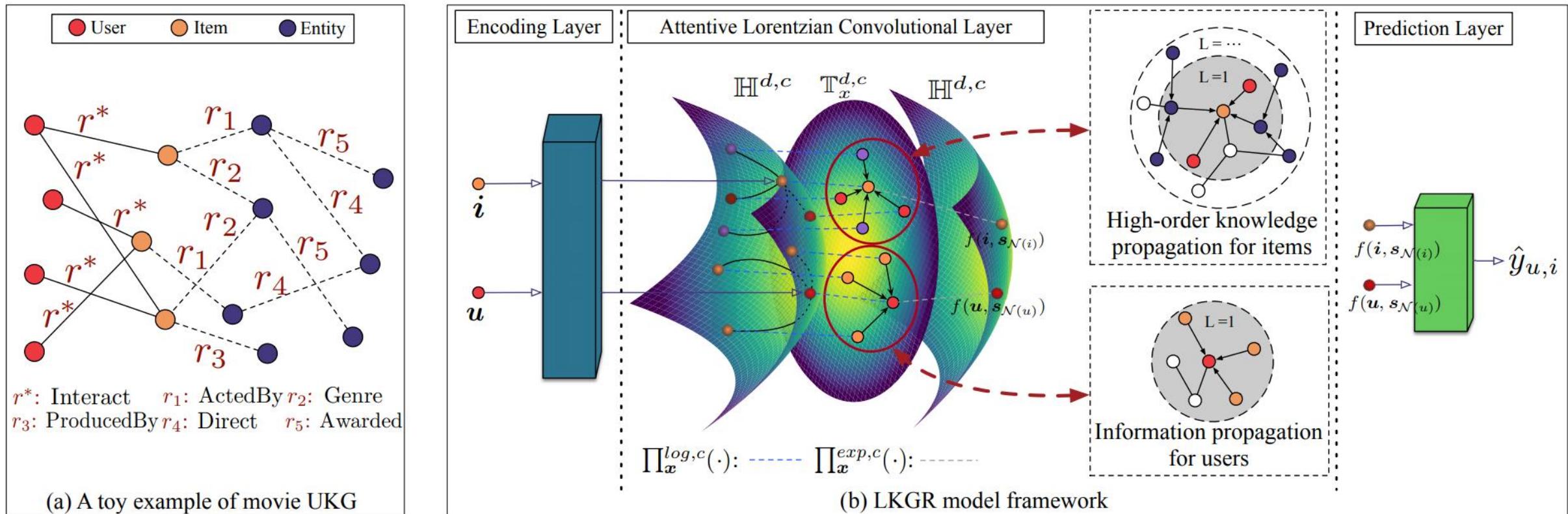
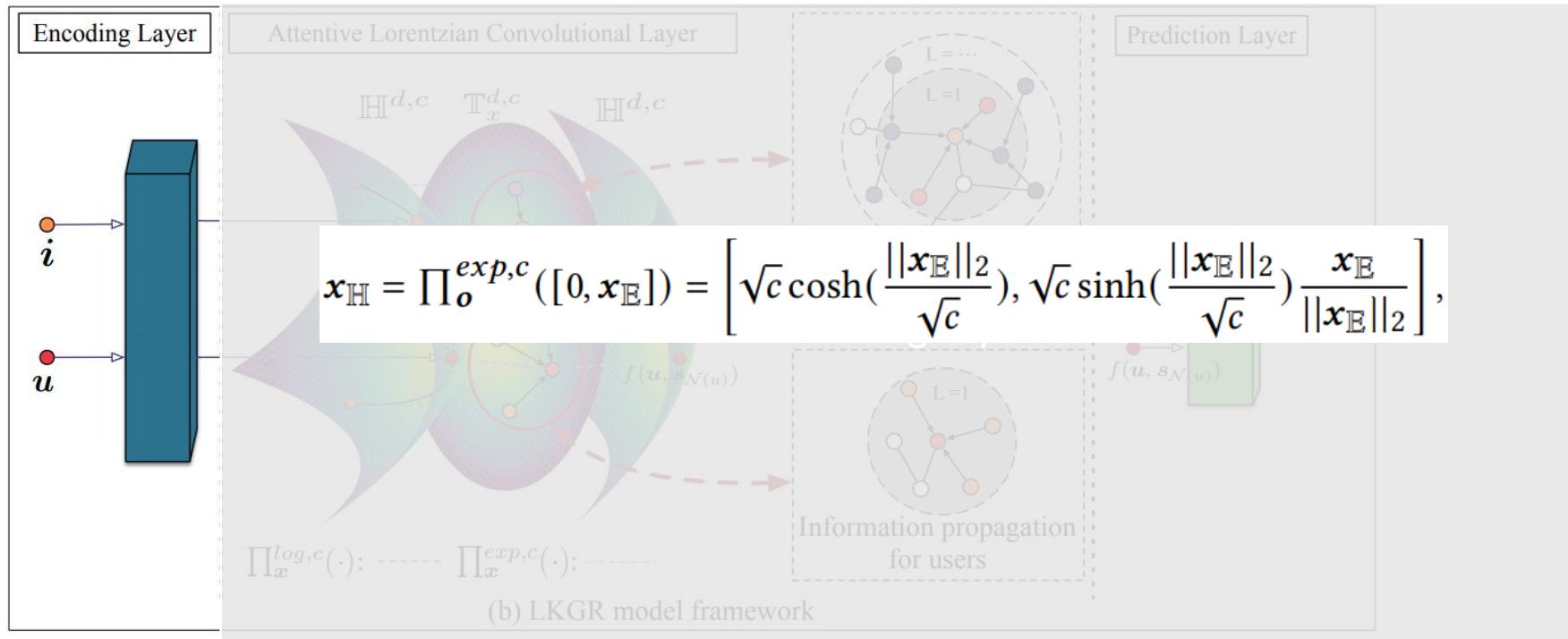


Figure 2: (a) The tripartite graph modeling users, items and KG entities. (b) Illustration of the proposed LKGR model.

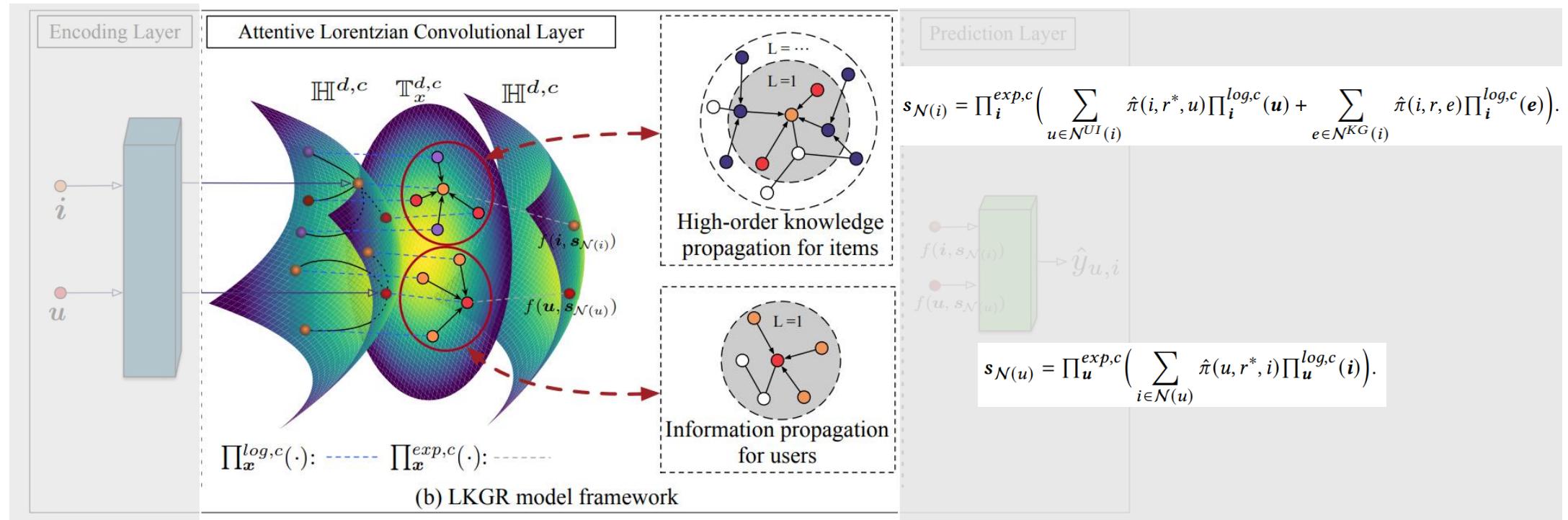
3.1 HGRL for Recommendation Systems (WSDM '22)

- Encoding Layer



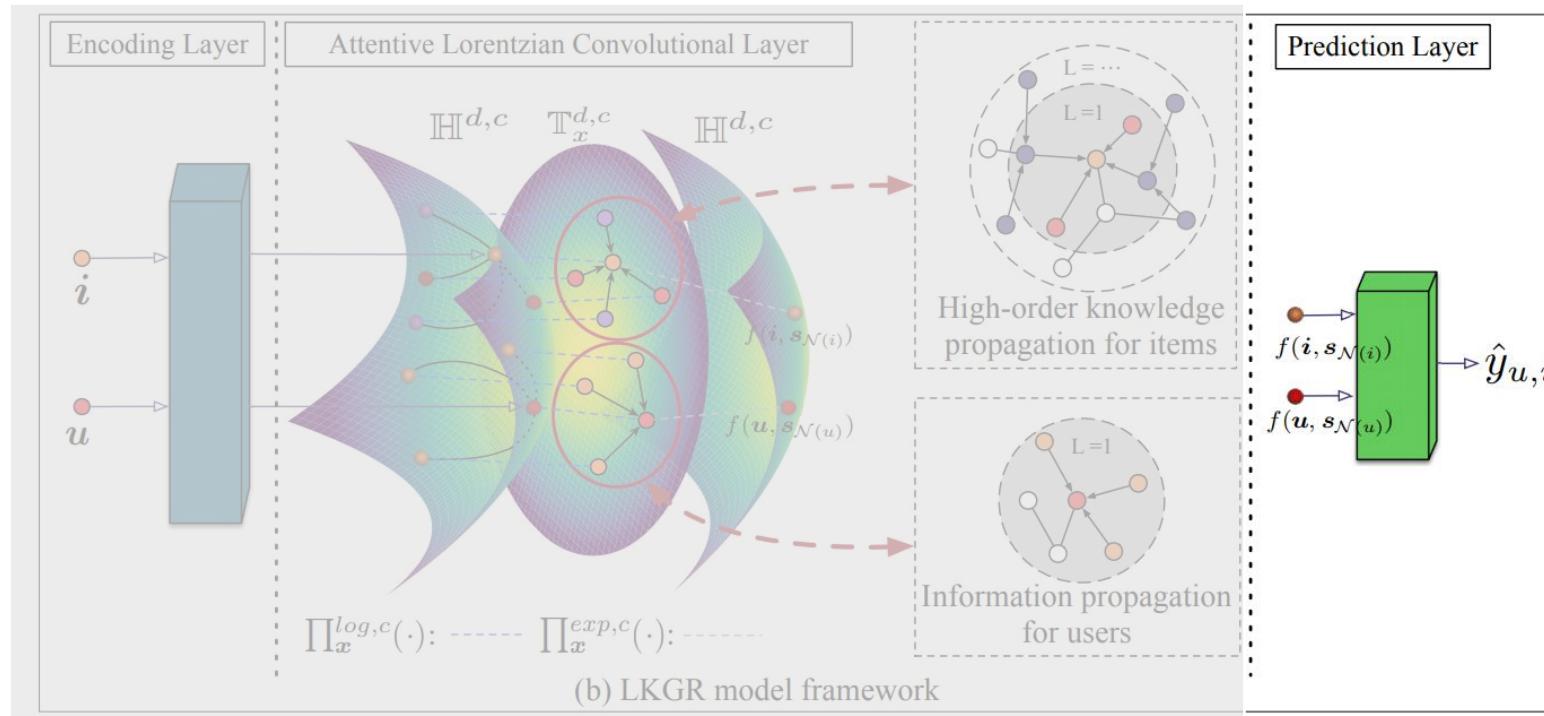
3.1 HGRL for Recommendation Systems (WSDM '22)

- Attentive Lorentzian Convolutional Layer



3.1 HGRL for Recommendation Systems (WSDM '22)

- Prediction Layer



$$\hat{y}_{u,i} = g(\mathbf{u}, \mathbf{i}) = (\prod_o^{\log,c}(\mathbf{u}))^T \prod_o^{\log,c}(\mathbf{i}).$$

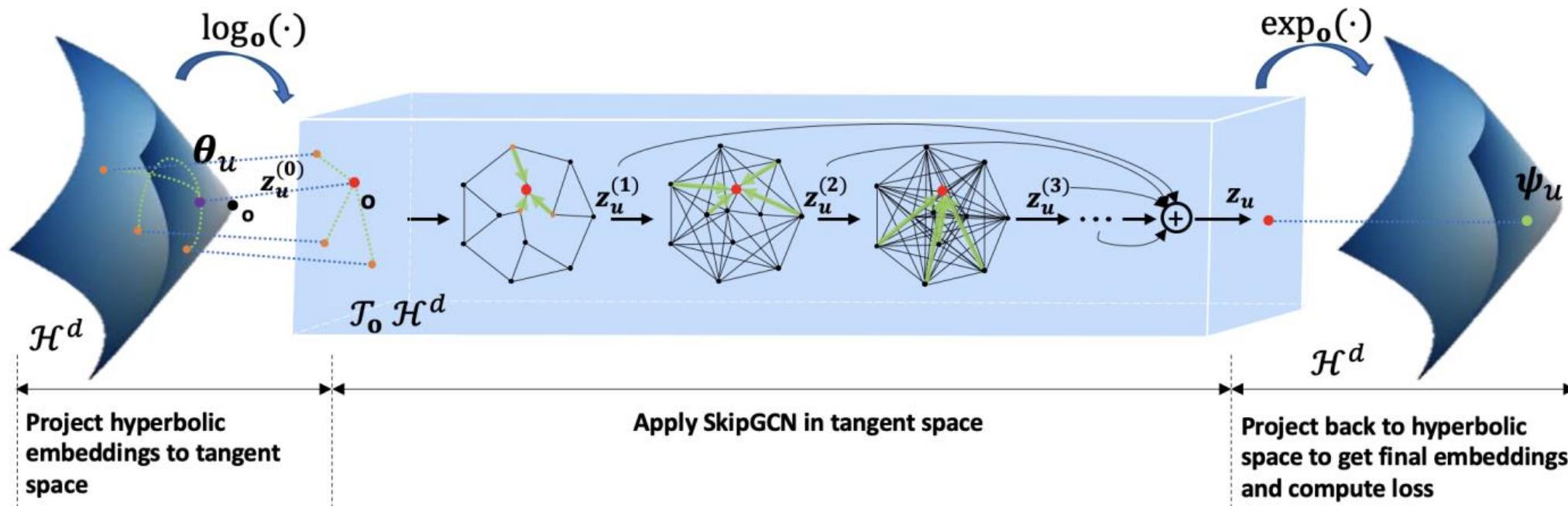
3.1 HGRL for Recommendation Systems (WSDM '22)

Table 2: Average results of Top@20 recommendation task. Underline indicates the second-best model performance. Bold denotes the empirical improvements against second-best models, and * denotes scenarios where a Wilcoxon signed-rank test indicates a statistically significant improvement under 95% confidence level between our model and second-best models.

Model	Book-Crossing		MovieLens-20M		Dianping-Food	
	Recall@20(%)	NDCG@20(%)	Recall@20(%)	NDCG@20(%)	Recall@20(%)	NDCG@20(%)
BPRMF	4.67 (8.7e-3)	2.80 (4.3e-3)	20.48 (1.6e-2)	15.77 (9.1e-3)	19.90 (3.0e-2)	10.79 (2.0e-2)
NFM	3.93 (2.2e-2)	2.17 (1.5e-2)	19.79 (3.3e-2)	14.28 (1.1e-2)	23.85 (3.9e-2)	<u>12.48</u> (3.0e-2)
CKE	4.38 (9.6e-3)	2.24 (4.2e-2)	21.52 (1.2e-2)	15.73 (1.3e-2)	22.24 (3.1e-2)	12.09 (1.5e-2)
RippleNet	7.12 (2.1e-2)	5.09 (1.7e-2)	13.74 (2.6e-2)	9.77 (1.7e-2)	21.20 (4.1e-2)	10.99 (2.0e-2)
KGNN-LS	<u>8.51</u> (2.2e-2)	<u>6.06</u> (1.7e-2)	20.20 (1.0e-2)	15.49 (1.3e-2)	15.52 (4.9e-2)	7.92 (2.9e-2)
KGCN	7.85 (2.9e-2)	5.93 (2.3e-2)	19.24 (3.2e-2)	13.87 (1.6e-2)	19.03 (3.0e-2)	9.34 (1.5e-2)
KGAT	5.34 (6.1e-3)	3.01 (7.9e-3)	<u>21.80</u> (7.7e-3)	<u>16.81</u> (1.1e-2)	15.57 (2.4e-2)	7.67 (1.7e-2)
CKAN	6.19 (1.1e-2)	3.47 (5.3e-3)	17.48 (1.7e-2)	12.48 (1.4e-2)	<u>24.10</u> (3.9e-2)	13.33 (2.0e-2)
LKGR	9.48* (2.3e-2)	6.50* (1.6e-2)	25.14* (4.1e-2)	18.34* (4.7e-2)	24.97* (4.4e-2)	10.45 (1.9e-2)
% Improv.	11.40%	7.26%	15.32%	9.10%	3.61%	N/A

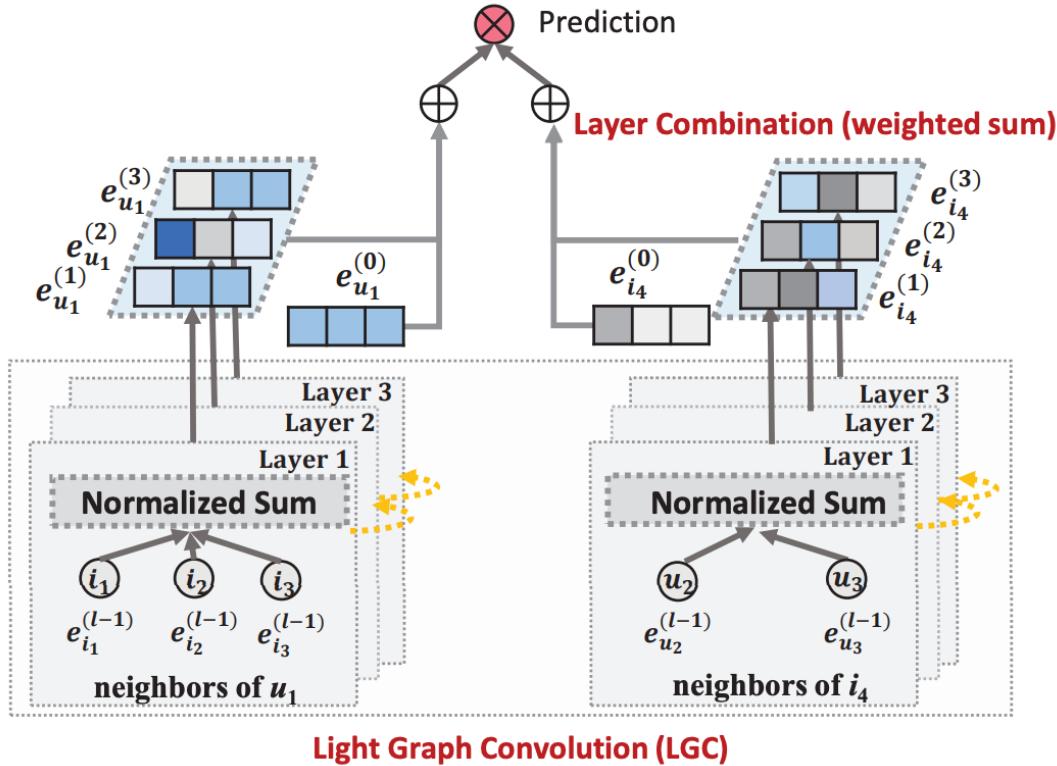
Revisit: HGCF (WWW '21)

- GNN for user-item network modeling in hyperbolic space



Sun, Jianing, et al. "Hgcf: Hyperbolic graph convolution networks for collaborative filtering." *The WebConf 2021*

Revisit: LightGCN (SIGIR '20)



$$\mathbf{e}_u^{(k+1)} = \sum_{i \in N_u} \frac{1}{\sqrt{|N_u|} \sqrt{|N_i|}} \mathbf{e}_i^{(k)},$$

$$\mathbf{e}_i^{(k+1)} = \sum_{u \in N_i} \frac{1}{\sqrt{|N_i|} \sqrt{|N_u|}} \mathbf{e}_u^{(k)}.$$

Note: where \mathbf{e}_u^k and \mathbf{e}_i^k respectively denote the refined embedding of user u and item i after k layers propagation. N_u denotes the set of items that are interacted by user u , N_i denotes the set of users that interact with item i .

Revisit: Experimental Comparison

Table 2: Recall (top table) and NDCG (bottom table) results for all datasets. The best performing model on each dataset and metric is highlighted in bold, and second best model is underlined. Asterisks denote statistically significant Wilcoxon signed rank test for the difference in scores between the best and second best models.

Datasets		BPRMF	WRMF	VAE-CF	TransCF	CML	LRML	SML	NGCF	LightGCN	HAE	HVAE	Ours
Amazon-CD	R@10	0.0779	0.0863	0.0786	0.0518	0.0864	0.0502	0.0475	0.0758	<u>0.0929</u>	0.0666	0.0781	0.0962*
	R@20	0.1200	0.1313	0.1155	0.0791	0.1341	0.0771	0.0734	0.1150	<u>0.1404</u>	0.0963	0.1147	0.1455*
Amazon-Book	R@10	0.0611	0.0623	0.0740	0.0407	0.0665	0.0522	0.0479	0.0658	<u>0.0799</u>	0.0634	0.0774	0.0867*
	R@20	0.0974	0.0919	0.1066	0.0632	0.1023	0.0834	0.0768	0.1050	<u>0.1248</u>	0.0912	0.1125	0.1318*
Yelp2020	R@10	0.0325	0.0470	0.0429	0.0247	0.0363	0.0326	0.0319	0.0458	<u>0.0522</u>	0.0360	0.0421	0.0543*
	R@20	0.0556	0.0793	0.0706	0.0424	0.0638	0.0562	0.0544	0.0764	<u>0.0866</u>	0.0588	0.0691	0.0884*
Datasets		BPRMF	WRMF	VAE-CF	TransCF	CML	LRML	SML	NGCF	LightGCN	HAE	HVAE	Ours
Amazon-CD	N@10	0.0610	0.0651	0.0615	0.0396	0.0639	0.0405	0.0361	0.0591	<u>0.0726</u>	0.0565	0.0629	0.0751*
	N@20	0.0974	0.0817	0.0752	0.0488	0.0813	0.0492	0.0456	0.0718	<u>0.0881</u>	0.0657	0.0749	0.0909*
Amazon-Book	N@10	0.0594	0.0563	0.0716	0.0392	0.0624	0.0515	0.0422	0.0655	<u>0.0780</u>	0.0709	0.0778	0.0869*
	N@20	0.0971	0.0730	0.0878	0.0474	0.0808	0.0626	0.0550	0.0791	<u>0.0938</u>	0.0789	0.0901	0.1022*
Yelp2020	N@10	0.0283	0.0372	0.0353	0.0214	0.0310	0.0287	0.0255	0.0405	0.0461	0.0331	0.0371	<u>0.0458</u>
	N@20	0.0512	0.0506	0.0469	0.0277	0.0428	0.0369	0.0347	0.0513	<u>0.0582</u>	0.0409	0.0465	0.0585*

Questions: In what aspect, hyperbolic model is superior to the Euclidean counterpart?

Sun, Jianing, et al. "Hgcf: Hyperbolic graph convolution networks for collaborative filtering." *The WebConf 2021*

3.1 HGRL for Recommendation Systems

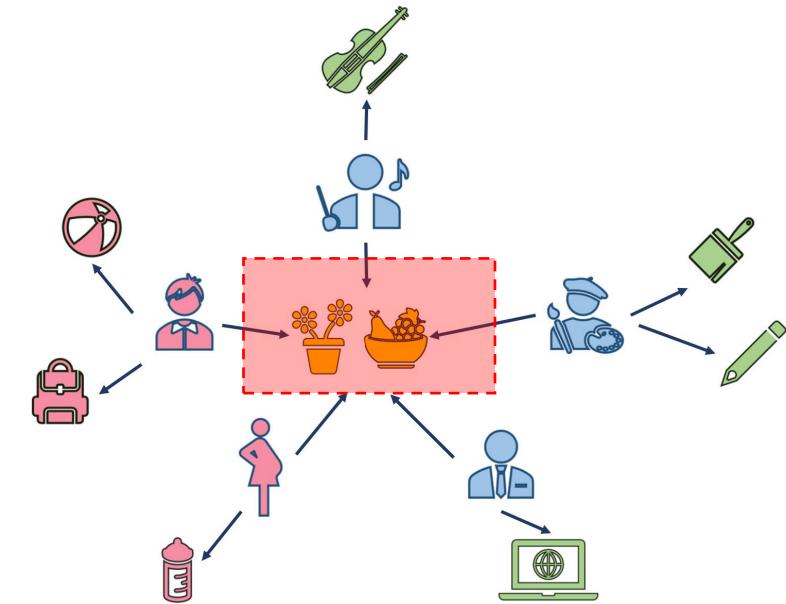
Table 1: Statistics of the experimental data.

Dataset	#User	#Item			#Interactions	Density
		All	H20(%)	T80(%)		
Amazon-CD	22,947	18,395	46	54	422,301	0.10%
Amazon-Book	52,406	41,264	47	53	1,861,118	0.09%
Yelp2020	71,135	45,063	62	37	1,940,014	0.05%

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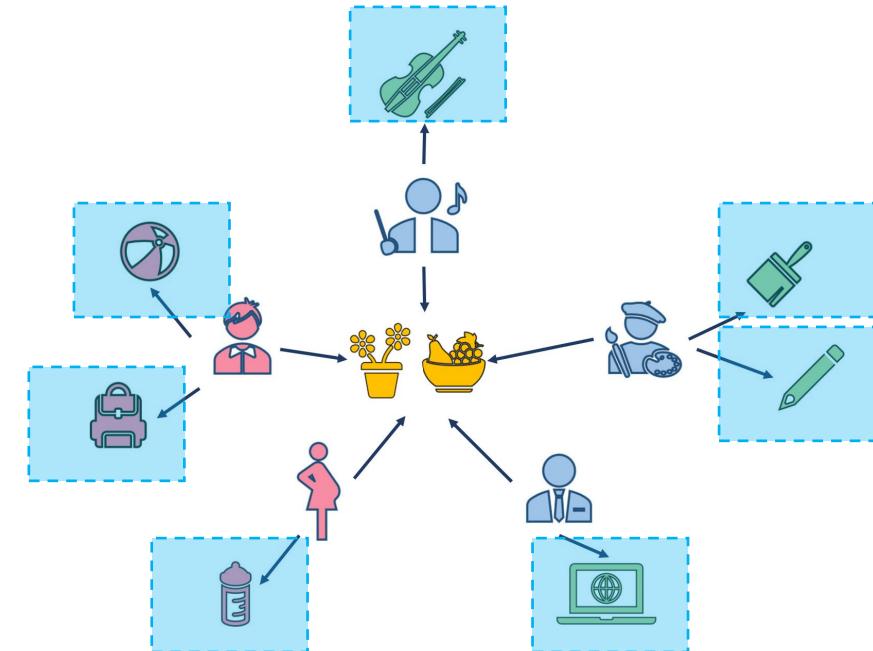


In general, the H20 items account for the minority.

3.1 HGRL for Recommendation Systems

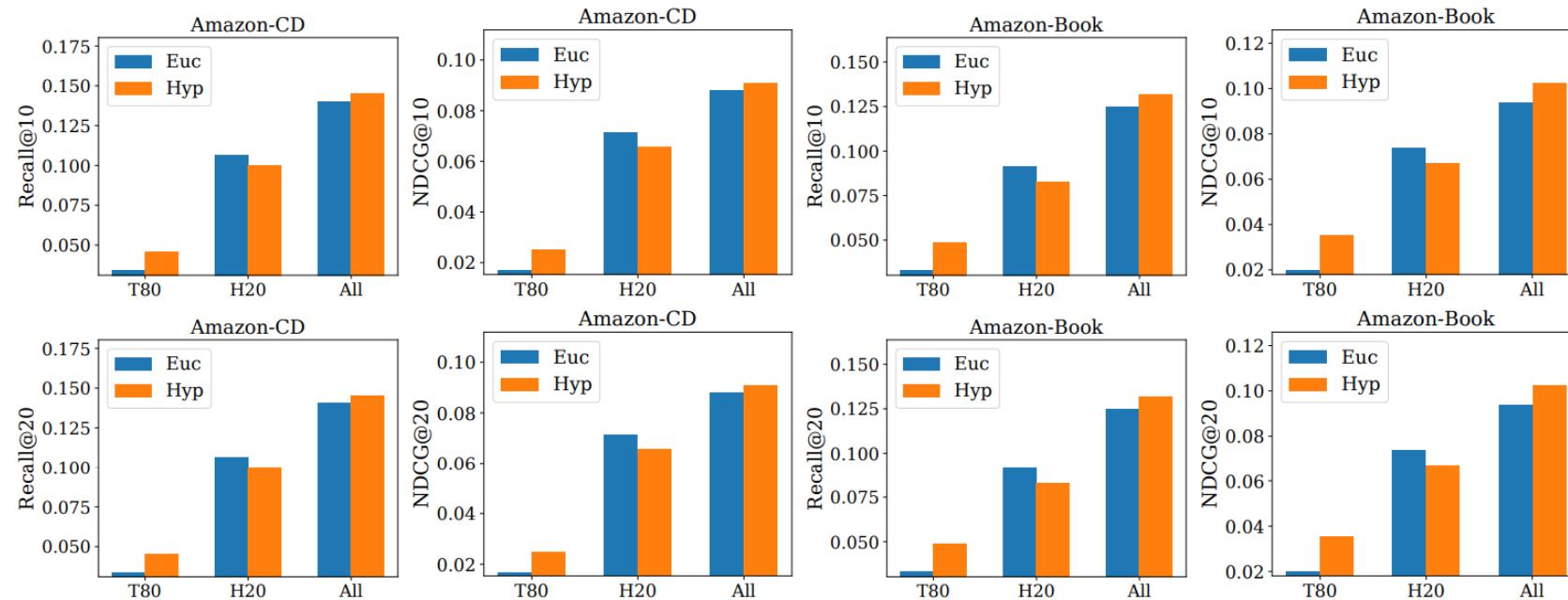
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In general, the T80 items account for the majority.

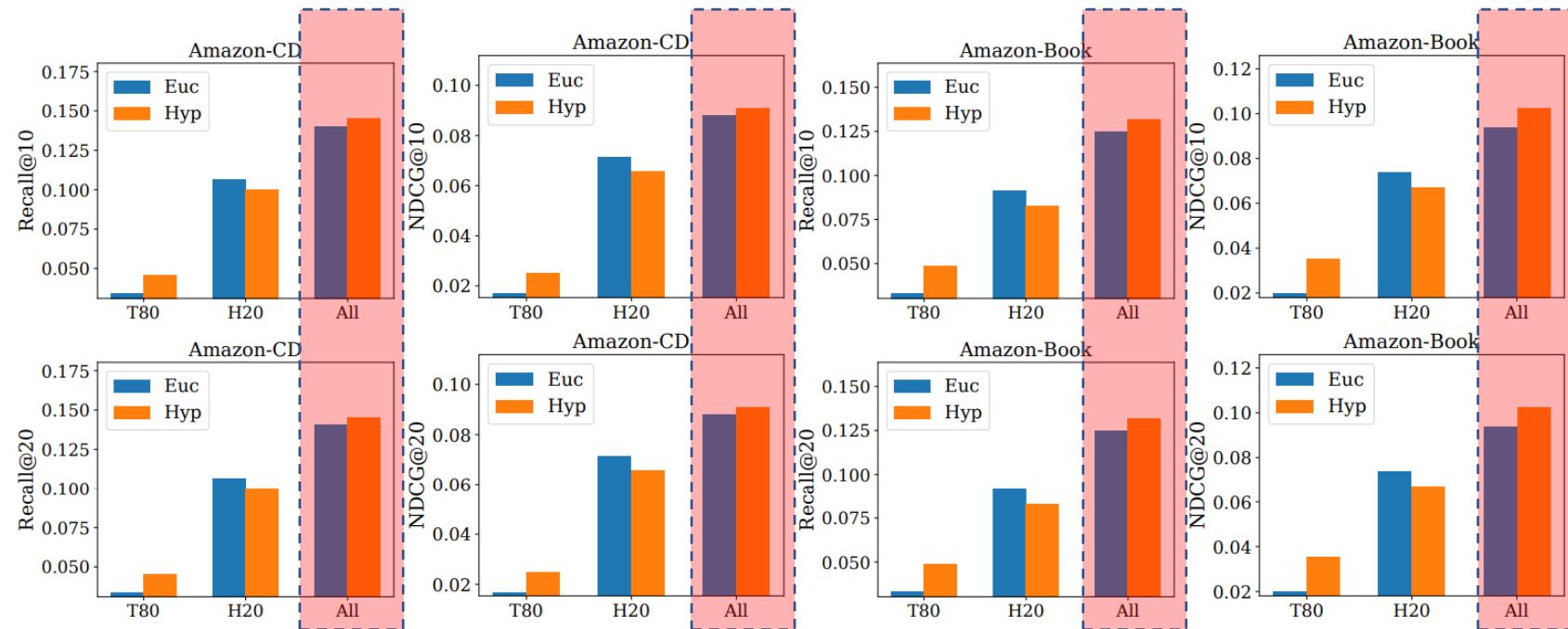
3.1 HGRL for Recommendation Systems (KDD '22)



Observations

- The overall recommendation performance of the hyperbolic model is better than that of the Euclidean model.
- Tail items get greater emphasis in the hyperbolic model as the results on tail items are far beyond that of the Euclidean counterpart.
- Head items receive moderate attention in the hyperbolic model as the performance of HGCF is slightly lower than that of LightGCN.

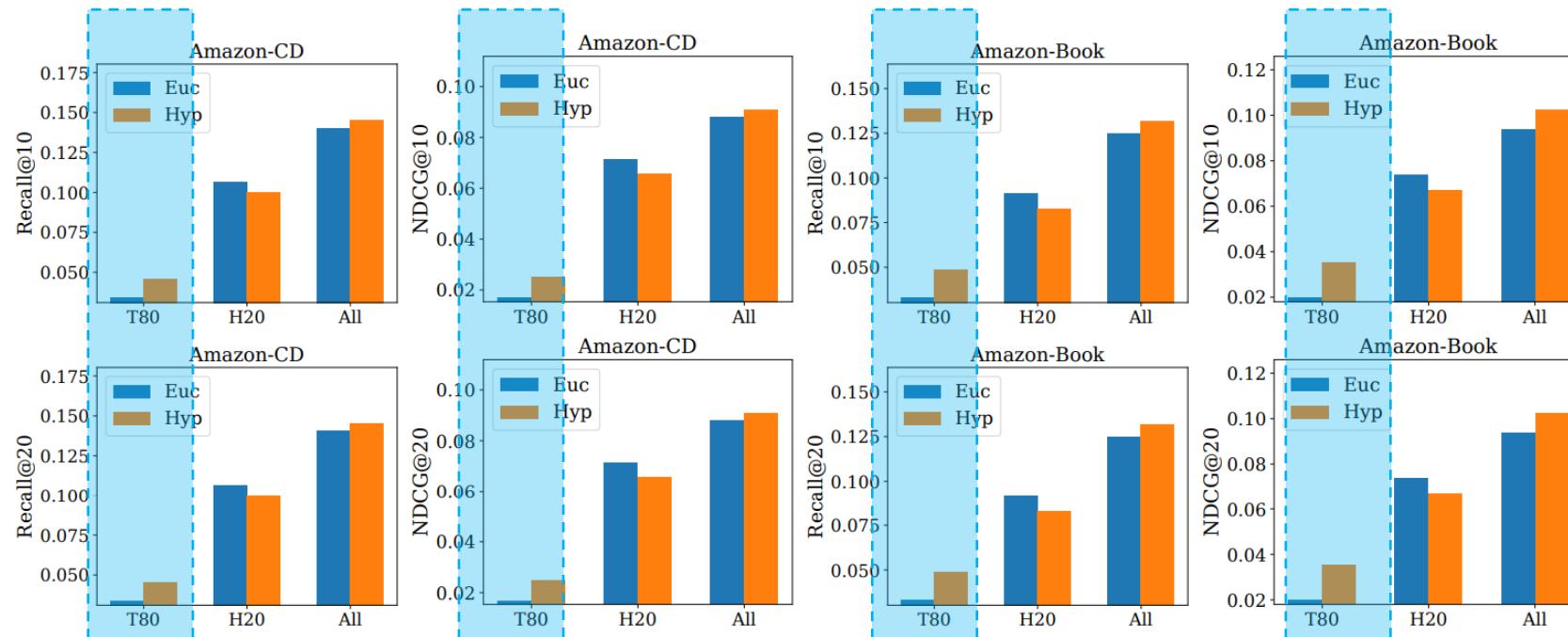
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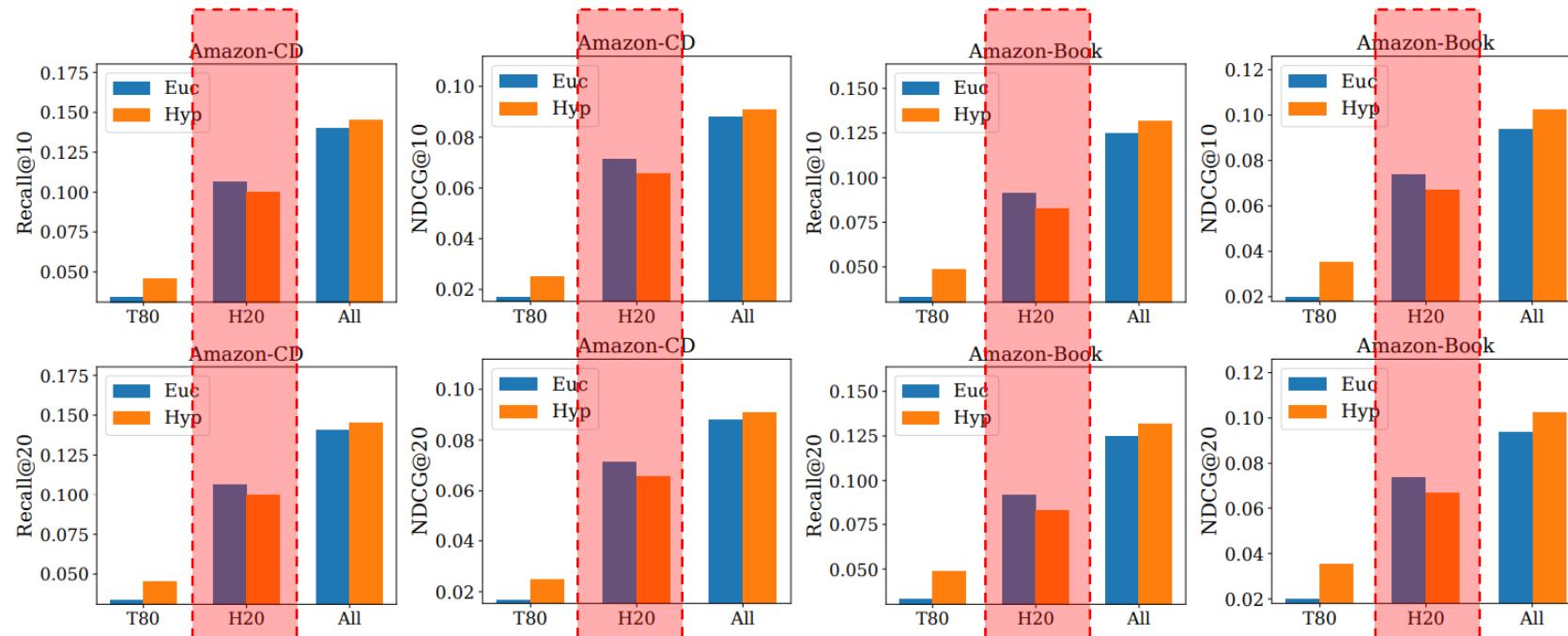
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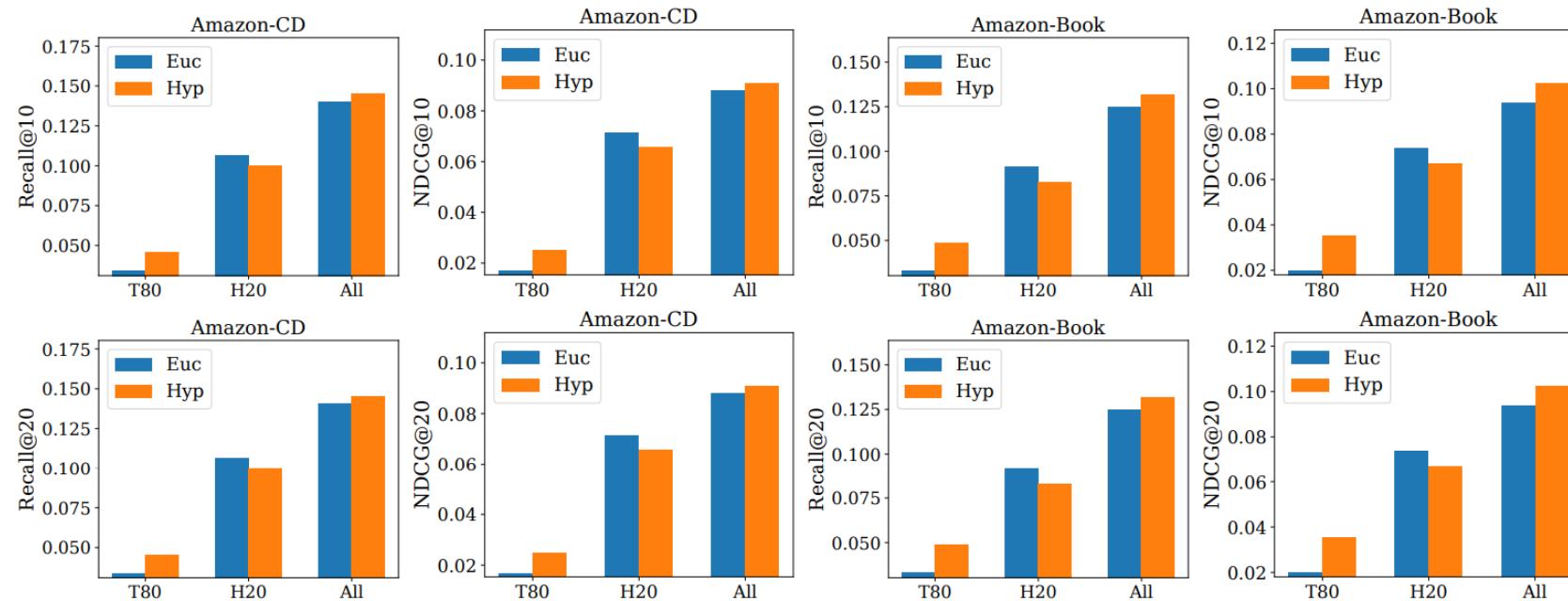
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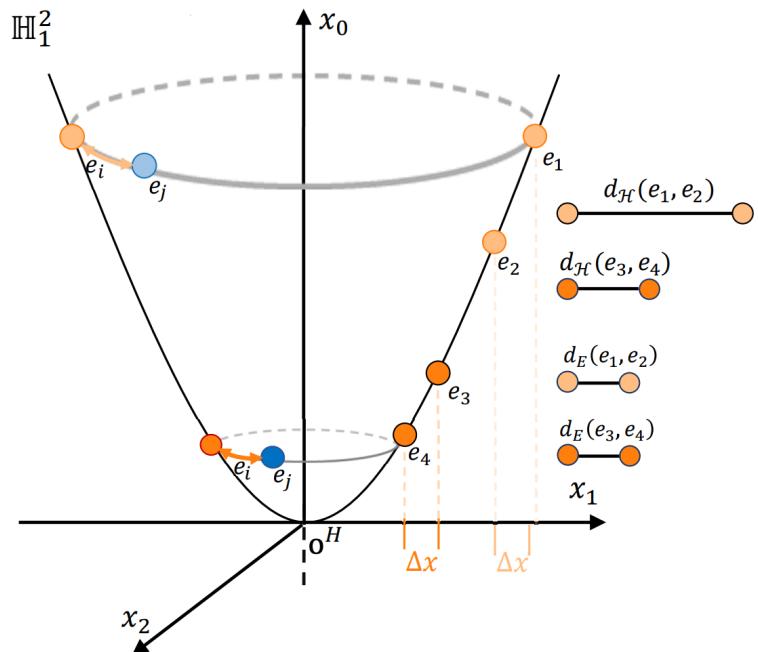
3.1 HGRL for Recommendation Systems (KDD '22)



Problems

- There is still large room for improvement for tail items.
- There is an urgent need to improve the performance on head items.

3.1 HGRL for Recommendation Systems (KDD '22)



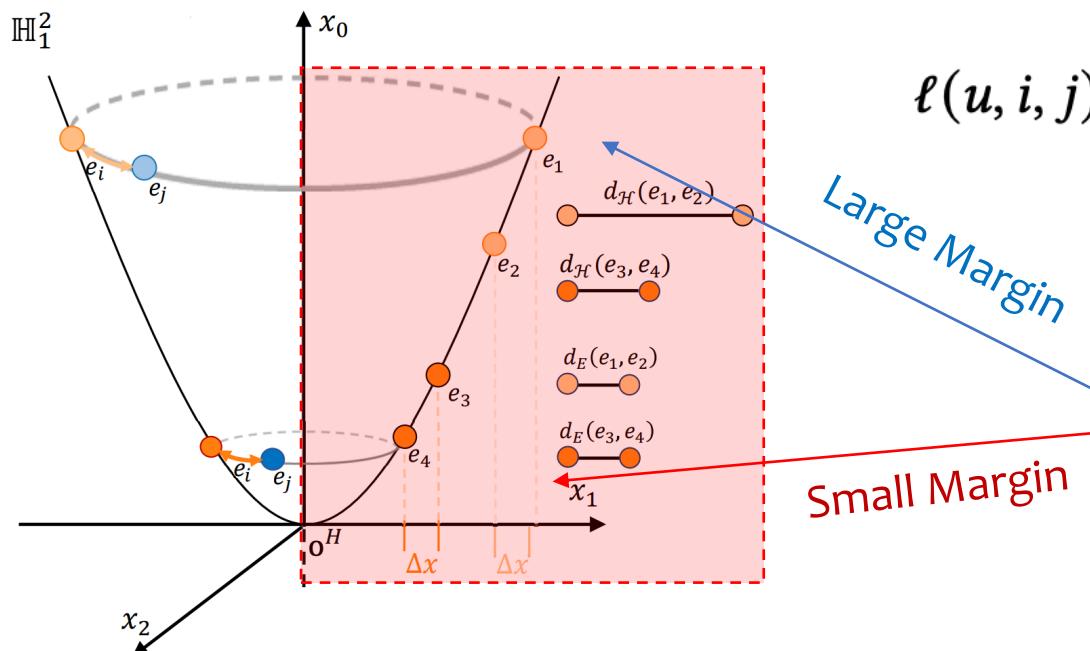
$$\ell(u, i, j) = \max(\underbrace{d_{\mathcal{H}}^2(\mathbf{e}_u, \mathbf{e}_i) - d_{\mathcal{H}}^2(\mathbf{e}_u, \mathbf{e}_j)}_{\text{Pull}} + m, 0),$$

Push

Note: d_H is the hyperbolic distance and m determines the margin between the distance difference between positive pair (u, i) and negative pair (u, j) .

3.1 HGRL for Recommendation Systems (KDD '22)

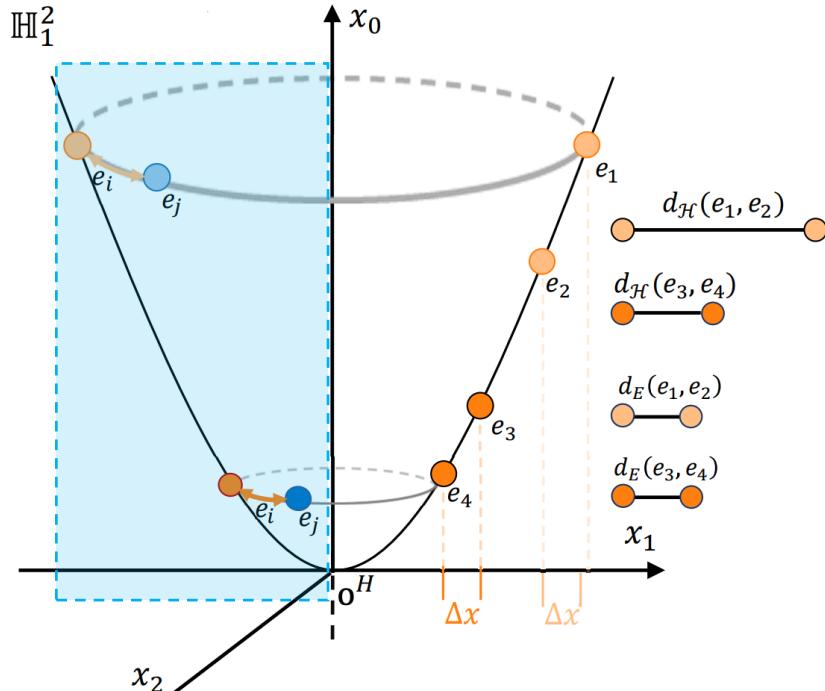
Hyperbolic-aware Margin Learning (HAML)



$$\ell(u, i, j) = \max(\underbrace{d_{\mathcal{H}}^2(\mathbf{e}_u, \mathbf{e}_i) - d_{\mathcal{H}}^2(\mathbf{e}_u, \mathbf{e}_j)}_{\text{Pull}} + m, 0), \quad \underbrace{+m}_{\text{Push}},$$

$$m_{ui}^{\mathcal{H}} = \text{sigmoid}(\delta), \quad \delta = \frac{d_{\mathcal{H}}^2(\mathbf{e}_u, \mathbf{o}) + d_{\mathcal{H}}^2(\mathbf{e}_i, \mathbf{o}) - d_{\mathcal{H}}^2(\mathbf{e}_u, \mathbf{e}_i)}{\mathbf{e}_{u,0}\mathbf{e}_{i,0}},$$

3.1 HGRL for Recommendation Systems (KDD '22)



Informative Sampling

Hyperbolic Informative Negative Sampling

Algorithm 1: HINS algorithm

Input: Hyper parameters n_{neg} ; Item set \mathcal{I} ; the embedding matrix E ; The index of the user u , its current positive item i and its other positive item \mathcal{N}_u in the training set.

Output: The informative item index j .

Random sample n_{neg} items $\mathcal{I}_u^{[n]}$ from $\mathcal{I} \setminus \mathcal{N}_u$;

forall item index \bar{j} in $\mathcal{I}_u^{[n]}$ **do**

 Get the embeddings of the \bar{j} from E , i.e., $\mathbf{e}_{\bar{j}}$;

 Let $j = -1, d_{min} = +\infty$;

 Compute the hyperbolic distance $d_{\mathcal{H}}(\mathbf{e}_{\bar{j}}, \mathbf{e}_i)$;

if $d_{\mathcal{H}}(\mathbf{e}_{\bar{j}}, \mathbf{e}_i) < d_{min}$ **then**

$d_{min} = d_{\mathcal{H}}(\mathbf{e}_{\bar{j}}, \mathbf{e}_i)$;

$j = \bar{j}$;

end

end

Return j ;

3.1 HGRL for Recommendation Systems (KDD '22)

Datasets		WRMF	VAE-CF	TransCF	CML	LRML	SML	NGCF	LightGCN	HAE	HAVE	HGCF	Ours	Δ(%)
Amazon-CD	R@10	0.0863	0.0786	0.0518	0.0864	0.0502	0.0475	0.0758	0.0929	0.0666	0.0781	<u>0.0962</u>	0.1079*	+12.16
	R@20	0.1313	0.1155	0.0791	0.1341	0.0771	0.0734	0.1150	0.1404	0.0963	0.1147	<u>0.1455</u>	0.1586*	+9.00
Amazon-Book	R@10	0.0623	0.0740	0.0407	0.0665	0.0522	0.0479	0.0658	0.0799	0.0634	0.0774	<u>0.0867</u>	0.0965*	+11.30
	R@20	0.0919	0.1066	0.0632	0.1023	0.0834	0.0768	0.1050	0.1248	0.0912	0.1125	<u>0.1318</u>	0.1449*	+9.94
Yelp2020	R@10	0.0470	0.0429	0.0247	0.0363	0.0326	0.0319	0.0458	0.0522	0.0360	0.0421	<u>0.0527</u>	0.0570*	+8.16
	R@20	0.0793	0.0706	0.0424	0.0638	0.0562	0.0544	0.0764	0.0866	0.0588	0.0691	<u>0.0884</u>	0.0948*	+7.24
Datasets		WRMF	VAE-CF	TransCF	CML	LRML	SML	NGCF	LightGCN	HAE	HAVE	HGCF	Ours	Δ(%)
Amazon-CD	N@10	0.0651	0.0615	0.0396	0.0639	0.0405	0.0361	0.0591	0.0726	0.0565	0.0629	<u>0.0751</u>	0.0848*	+12.92
	N@20	0.0817	0.0752	0.0488	0.0813	0.0492	0.0456	0.0718	0.0881	0.0657	0.0749	<u>0.0909</u>	0.1010*	+11.11
Amazon-Book	N@10	0.0563	0.0716	0.0392	0.0624	0.0515	0.0422	0.0655	0.0780	0.0709	0.0778	<u>0.0869</u>	0.0978*	+12.54
	N@20	0.0730	0.0878	0.0474	0.0808	0.0626	0.0550	0.0791	0.0938	0.0789	0.0901	<u>0.1022</u>	0.1142*	+11.74
Yelp2020	N@10	0.0372	0.0353	0.0214	0.0310	0.0287	0.0255	0.0405	0.0461	0.0331	0.0371	<u>0.0458</u>	0.0502*	+9.13
	N@20	0.0506	0.0469	0.0277	0.0428	0.0369	0.0347	0.0513	0.0582	0.0409	0.0465	<u>0.0585</u>	0.0633*	+8.21

The proposed method outperforms all baselines in both Recall and NDCG metrics.

3.1 HGRL for Recommendation Systems (KDD '22)

Datasets	Models	R@20		R@10		R@5		N@20		N@10		N@5	
		H20	T80										
Amazon-CD	LightGCN	0.1062	0.0342	0.0741	0.0188	0.0493	0.0104	0.0712	0.0169	0.0608	0.0118	0.0529	0.0084
	HGCF	0.0998	0.0457	0.0667	0.0295	0.0439	0.0179	0.0658	0.0251	0.0550	0.0201	0.0486	0.0157
	HICF(Ours)	0.1027	0.0559	0.0717	0.0362	0.0476	0.0222	0.0692	0.0318	0.0596	0.0252	0.0527	0.0197
	$\Delta_{\mathcal{H}}(\%)$	+2.91	+22.32	+7.50	+22.71	+8.43	+24.02	+5.17	+26.69	+8.36	+25.37	+8.44	+25.48
Amazon-Book	LightGCN	0.0915	0.0333	0.0624	0.0175	0.0390	0.0104	0.0740	0.0198	0.0635	0.0145	0.0589	0.0104
	HGCF	0.0829	0.0489	0.0550	0.0317	0.0344	0.0197	0.0670	0.0352	0.0578	0.0291	0.0539	0.0251
	HICF(Ours)	0.0898	0.0551	0.0603	0.0362	0.0387	0.0227	0.0738	0.0404	0.0642	0.0336	0.0605	0.0293
	$\Delta_{\mathcal{H}}(\%)$	+8.32	+12.68	+9.64	+14.20	+12.50	+15.23	+10.15	+14.77	+11.07	+15.46	+12.24	+16.73
Yelp2020	LightGCN	0.0836	0.0030	0.0512	0.0010	0.0298	0.0003	0.0567	0.0015	0.0448	0.0006	0.0380	0.0004
	HGCF	0.0788	0.0096	0.0473	0.0054	0.0270	0.0030	0.0526	0.0059	0.0417	0.0043	0.0354	0.0033
	HICF(Ours)	0.0854	0.0094	0.0518	0.0052	0.0299	0.0029	0.0576	0.0057	0.0461	0.0041	0.0395	0.0032
	$\Delta_{\mathcal{H}}(\%)$	+8.38	-2.08	+9.51	-3.70	+10.74	-3.33	+9.51	-3.39	+10.55	-4.65	+11.58	-3.03

For head items, the performances of HICF comprehensively outperform that of HGCF and the improvements are up to 8.43% on Amazon-CD, 12.50% on Amazon-Book, and 11.58% on Yelp.

In addition, HICF narrows the performance gap of the tail items with Euclidean LightGCN on Amazon-CD and Amazon-Book and impressively surpasses the performance of LightGCN on Yelp.

3.1 HGRL for Recommendation Systems (KDD '22)

Datasets	Models	R@20		R@10		R@5		N@20		N@10		N@5	
		H20	T80										
Amazon-CD	LightGCN	0.1062	0.0342	0.0741	0.0188	0.0493	0.0104	0.0712	0.0169	0.0608	0.0118	0.0529	0.0084
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	HICF(Ours)	0.1027	0.0559	0.0717	0.0362	0.0476	0.0222	0.0692	0.0318	0.0596	0.0252	0.0527	0.0197
	$\Delta_{\mathcal{H}}(\%)$	+2.91	+22.32	+7.50	+22.71	+8.43	+24.02	+5.17	+26.69	+8.36	+25.37	+8.44	+25.48
Amazon-Book	LightGCN	0.0915	0.0333	0.0624	0.0175	0.0390	0.0104	0.0740	0.0198	0.0635	0.0145	0.0589	0.0104
	HGCF	0.0829	0.0489	0.0550	0.0317	0.0344	0.0197	0.0670	0.0352	0.0578	0.0291	0.0539	0.0251
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Yelp2020	LightGCN	0.0836	0.0030	0.0512	0.0010	0.0298	0.0003	0.0567	0.0015	0.0448	0.0006	0.0380	0.0004
	HGCF	0.0788	0.0096	0.0473	0.0054	0.0270	0.0030	0.0526	0.0059	0.0417	0.0043	0.0354	0.0033
	HICF(Ours)	0.0854	0.0094	0.0518	0.0052	0.0299	0.0029	0.0576	0.0057	0.0461	0.0041	0.0395	0.0032
	$\Delta_{\mathcal{H}}(\%)$	+8.38	-2.08	+9.51	-3.70	+10.74	-3.33	+9.51	-3.39	+10.55	-4.65	+11.58	-3.03

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3.1 HGRL for Recommendation Systems (KDD '22)

Datasets	Models	R@20		R@10		R@5		N@20		N@10		N@5	
		H20	T80										
Amazon-CD	LightGCN	0.1062	0.0342	0.0741	0.0188	0.0493	0.0104	0.0712	0.0169	0.0608	0.0118	0.0529	0.0084
	HGCF	0.0998	0.0457	0.0667	0.0295	0.0439	0.0179	0.0658	0.0251	0.0550	0.0201	0.0486	0.0157
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	HGCF	0.0829	0.0489	0.0550	0.0317	0.0344	0.0197	0.0670	0.0352	0.0578	0.0291	0.0539	0.0251
	HICF(Ours)	0.0898	0.0551	0.0603	0.0362	0.0387	0.0227	0.0738	0.0404	0.0642	0.0336	0.0605	0.0293
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Yelp2020	LightGCN	0.0836	0.0030	0.0512	0.0010	0.0298	0.0003	0.0567	0.0015	0.0448	0.0006	0.0380	0.0004
	HGCF	0.0788	0.0096	0.0473	0.0054	0.0270	0.0030	0.0526	0.0059	0.0417	0.0043	0.0354	0.0033
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	$\Delta_{\mathcal{H}}(\%)$	+8.38	-2.08	+9.51	-3.70	+10.74	-3.33	+9.51	-3.39	+10.55	-4.65	+11.58	-3.03

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Contents

1. INTRODUCTION

- 1.1 An Overview of Graph Representation Learning
- 1.2 Brief Introduction of Riemannian Geometry
- 1.3 Motivation of Hyperbolic Graph Representation Learning

2. HYPERBOLIC GRAPH REPRESENTATION LEARNING (HGRL)

- 2.1 Hyperbolic Shallow Models
- 2.2 Hyperbolic Neural Networks
- 2.3 Hyperbolic Graph Neural Networks

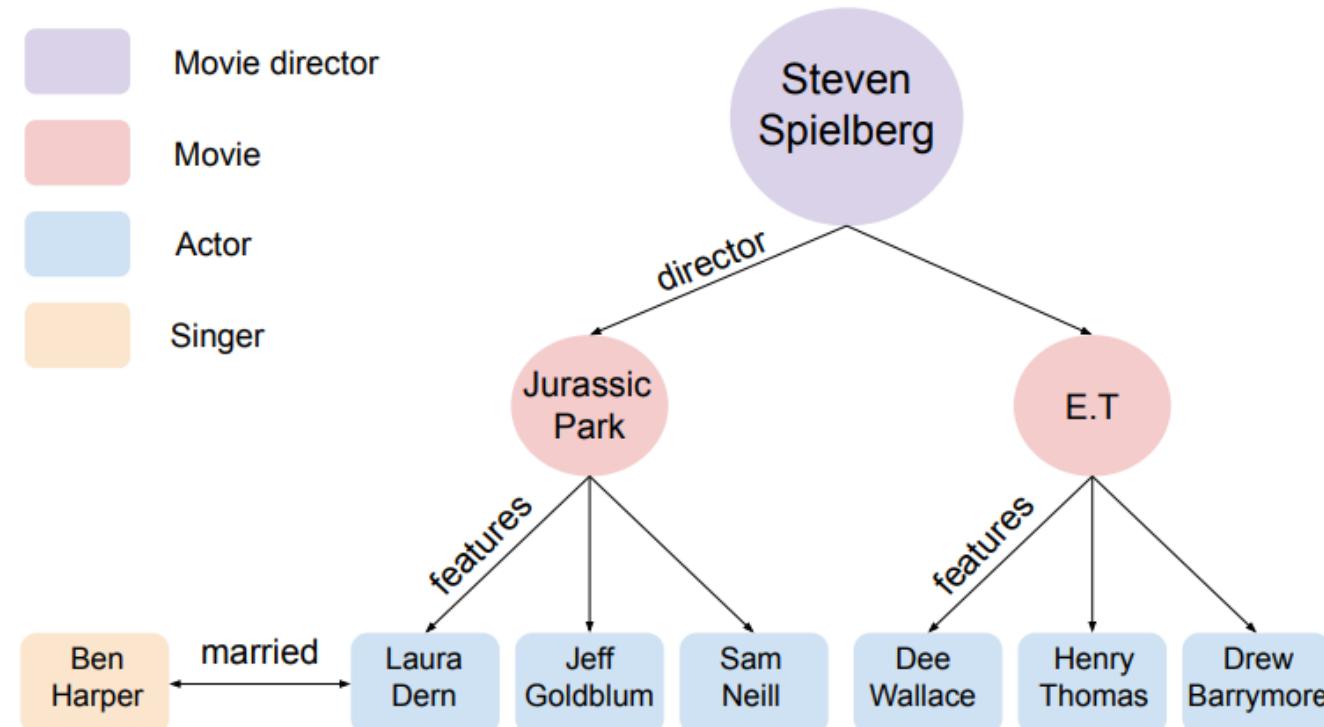
3. APPLICATIONS

- 3.1 HGRL for Recommendation Systems
- 3.2 HGRL for Knowledge Graph
- 3.3 HGRL for other Applications

4. ADVANCED TOPICS

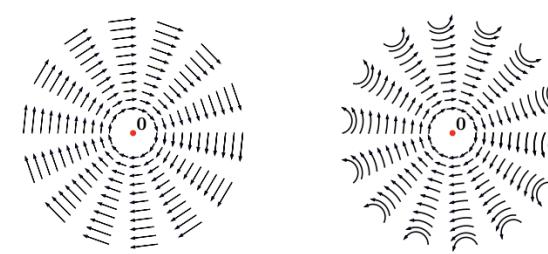
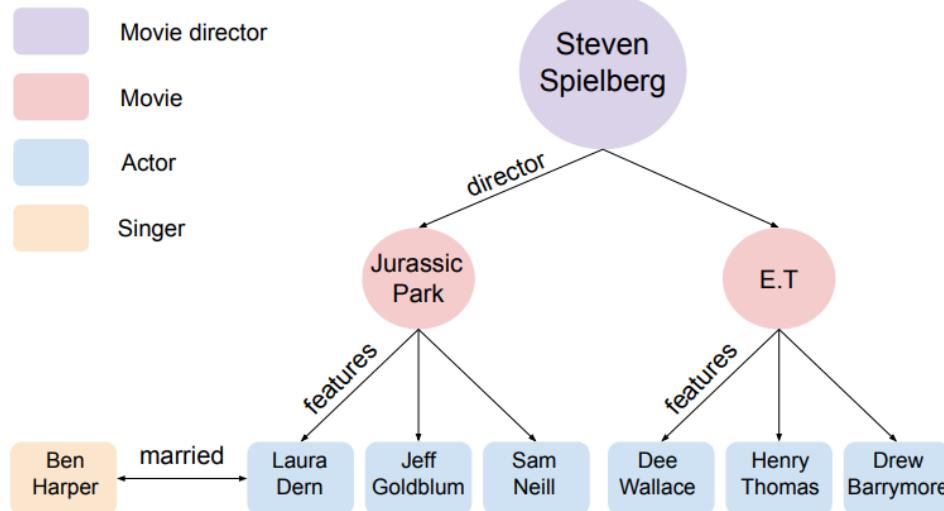
- 4.1 Complex Structures
- 4.2 Evolving Interactions
- 4.3 Geometry-Aware Learning
- 4.4 Trustworthy and Scalability

3.2 HGRL for Knowledge Graph (ACL '19)

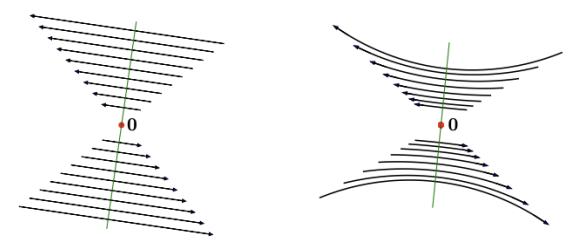


Chami, Ines, et al. "Low-dimensional hyperbolic knowledge graph embeddings." ACL 2019

3.2 HGRL for Knowledge Graph (ACL '19)

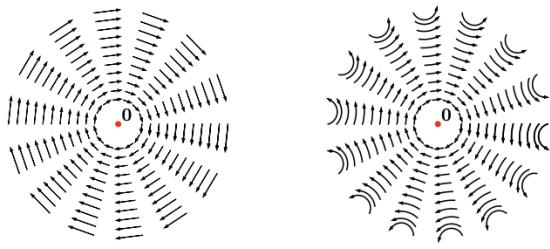


(a) Rotations

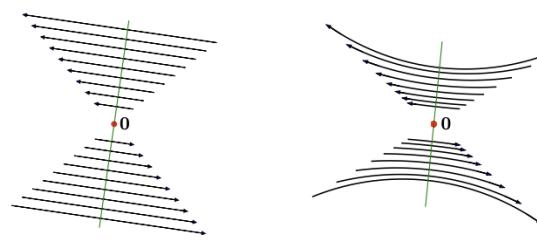


(b) Reflections

3.2 HGRL for Knowledge Graph (ACL '19)



(a) Rotations



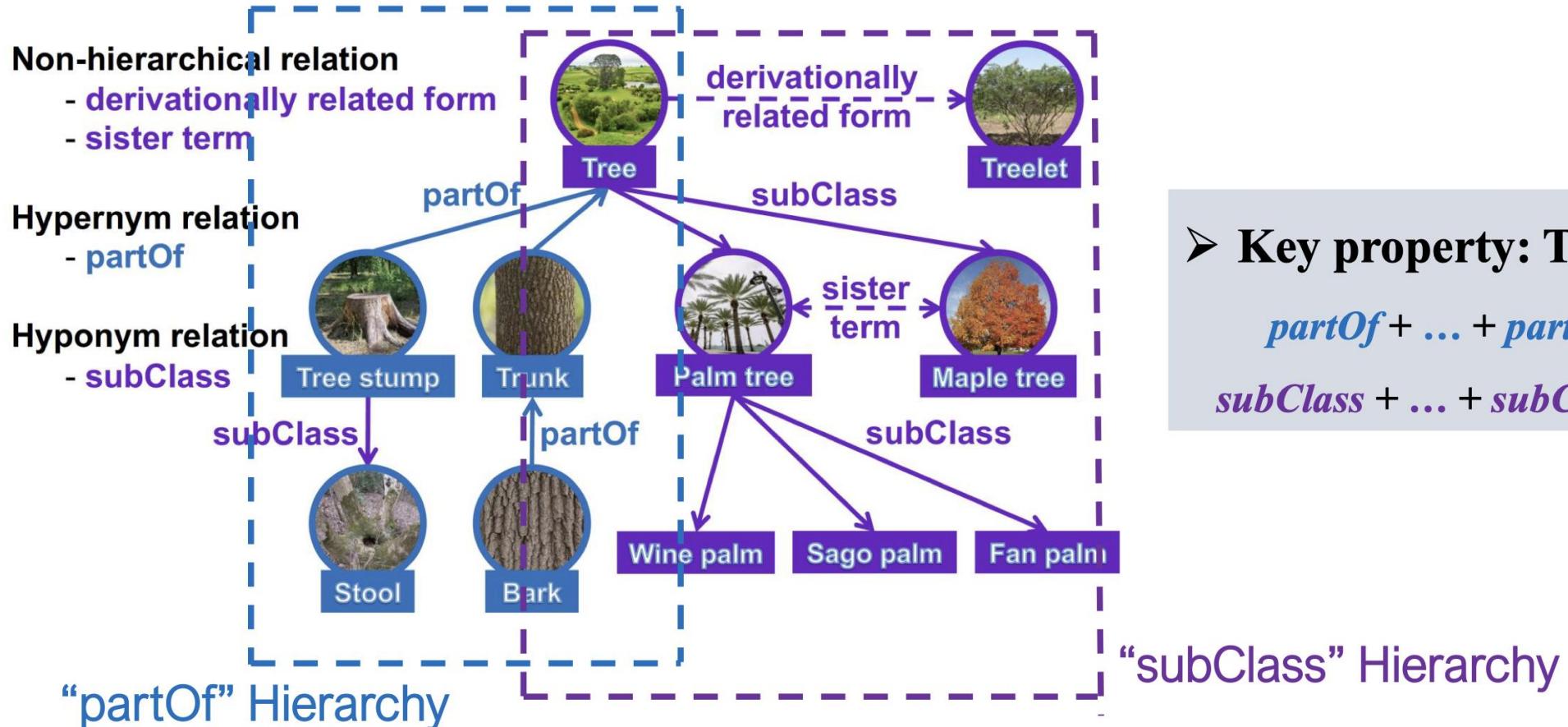
(b) Reflections

$$\text{Rot}(\Theta_r) = \text{diag}(G^+(\theta_{r,1}), \dots, G^+(\theta_{r,\frac{d}{2}})), \quad (4)$$

$$\text{Ref}(\Phi_r) = \text{diag}(G^-(\phi_{r,1}), \dots, G^-(\phi_{r,\frac{n}{2}})), \quad (5)$$

$$\text{where } G^\pm(\theta) := \begin{bmatrix} \cos(\theta) & \mp\sin(\theta) \\ \sin(\theta) & \pm\cos(\theta) \end{bmatrix}. \quad (6)$$

3.2 HGRL for Knowledge Graph (NeurIPS '21)



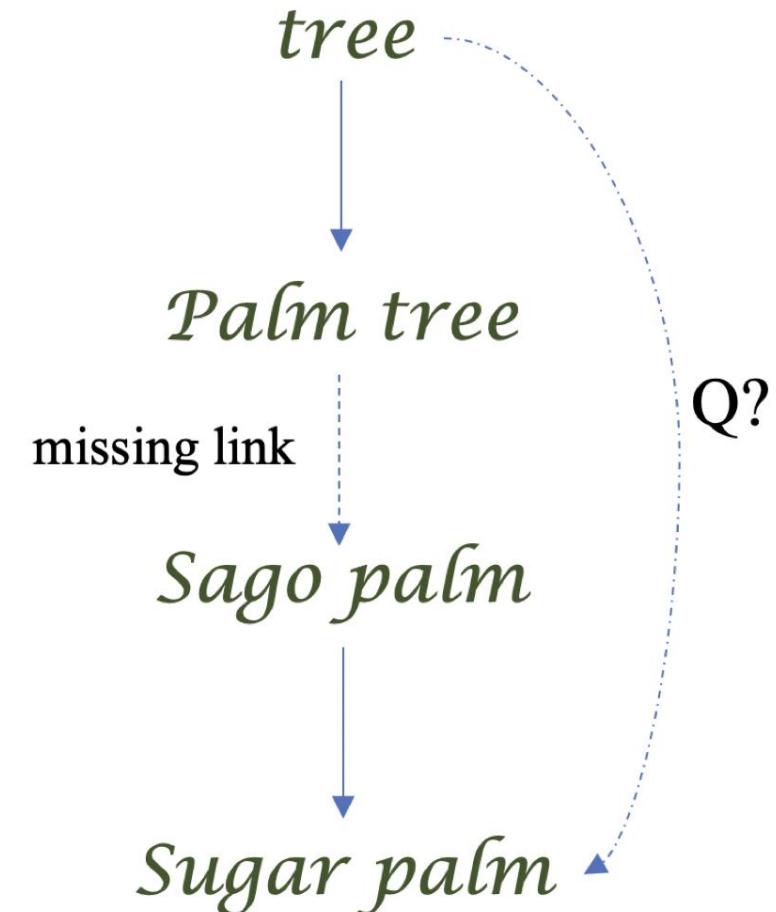
➤ Key property: Transitivity

$$\text{partOf} + \dots + \text{partOf} = \text{partOf}$$

$$\text{subClass} + \dots + \text{subClass} = \text{subClass}$$

3.2 HGRL for Knowledge Graph (NeurIPS '21)

- To do hierarchical reasoning that involves cross-layer connection
 - Ancestor-Descendant Prediction
- Such task requires:
 - Model Transitivity
 - Model non-hierarchical Properties



3.2 HGRL for Knowledge Graph (NeurIPS '21)

Entity → Hyperbolic Cone

Relation

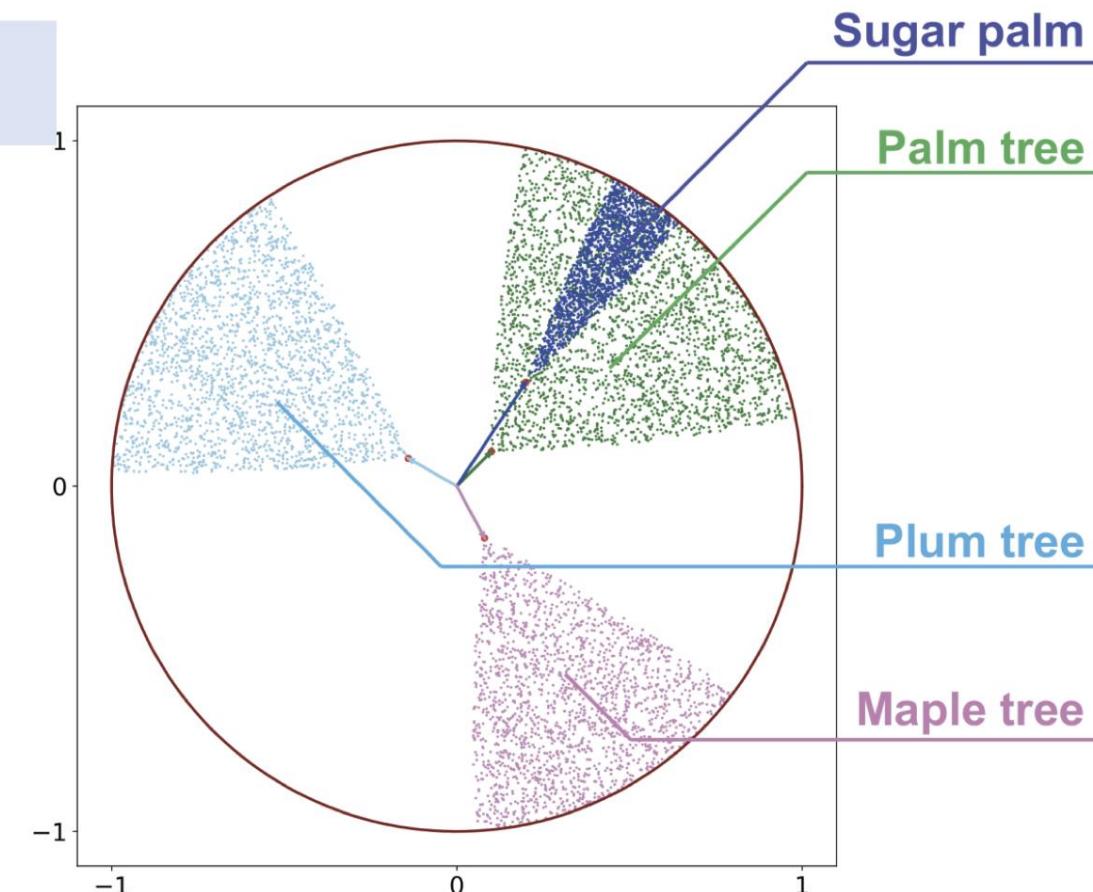


Cone Transformation

Partial ordering



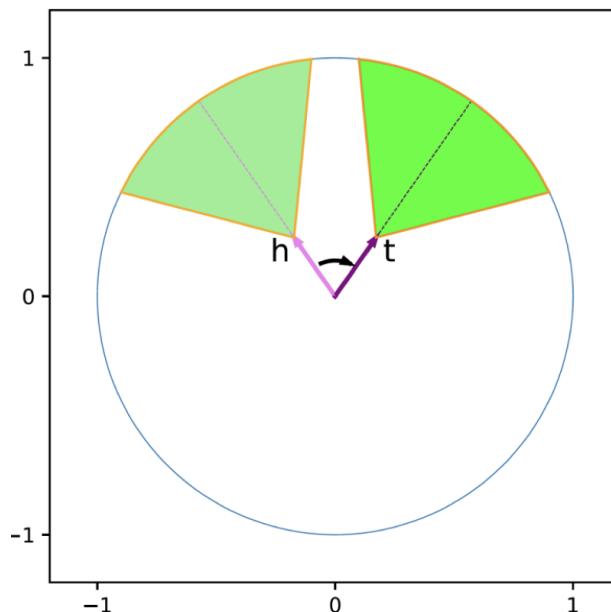
Cone containment



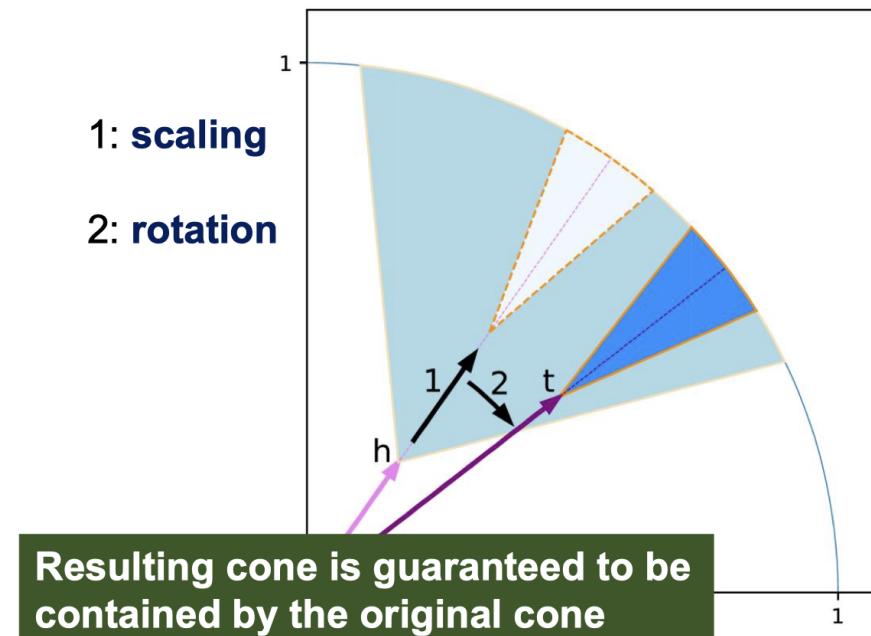
Bai, Yushi, et al. "Modeling heterogeneous hierarchies with relation-specific hyperbolic cones." *NeurIPS* 2021.

3.2 HGRL for Knowledge Graph (NeurIPS '21)

Rotation

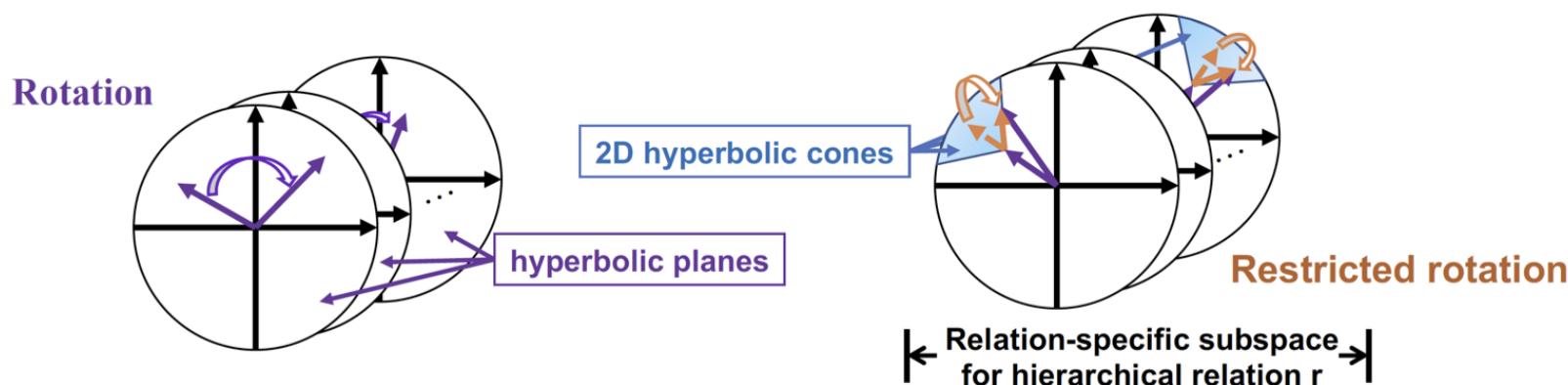


Restricted rotation



3.2 HGRL for Knowledge Graph (NeurIPS '21)

- Motivation behind two kinds of transformations?
 - Restricted rotation: Capture hierarchical property (transitivity)
 - Rotation: Capture other non-hierarchical properties (composition)
- Why allocating subspace for each hierarchical relation?
 - Partial ordering of different hierarchical relations are preserved in different subspaces



Bai, Yushi, et al. "Modeling heterogeneous hierarchies with relation-specific hyperbolic cones." *NeurIPS* 2021.

Contents

1. INTRODUCTION

- 1.1 An Overview of Graph Representation Learning
- 1.2 Brief Introduction of Riemannian Geometry
- 1.3 Motivation of hyperbolic graph representation learning

2. HYPERBOLIC GRAPH REPRESENTATION LEARNING (HGRL)

- 2.1 Hyperbolic Shallow Models
- 2.2 Hyperbolic Neural Networks
- 2.3 Hyperbolic Graph Neural Networks

3. APPLICATIONS

- 3.1 HGRL for Recommendation Systems**
- 3.2 HGRL for Knowledge Graph**
- 3.3 HGRL for other Applications**

4. ADVANCED TOPICS

- 4.1 Complex Structures
- 4.2 Evolving Interactions
- 4.3 Geometry-aware Learning
- 4.4 Trustworthy and Scalability

Hyperbolic Space for Image Embedding

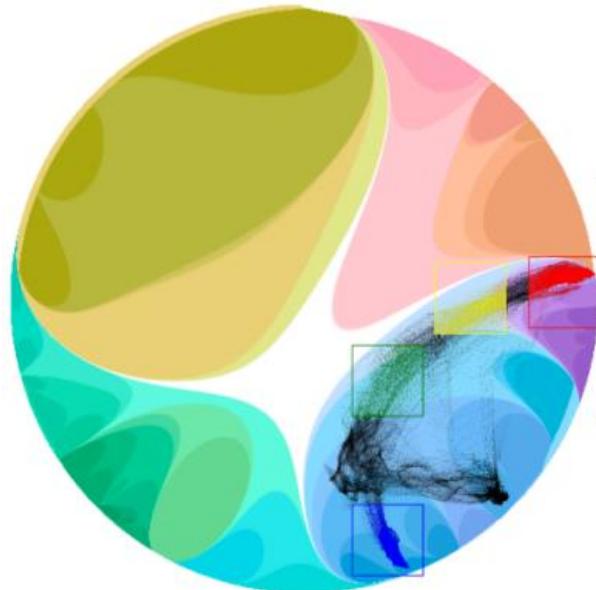


Image segmentation

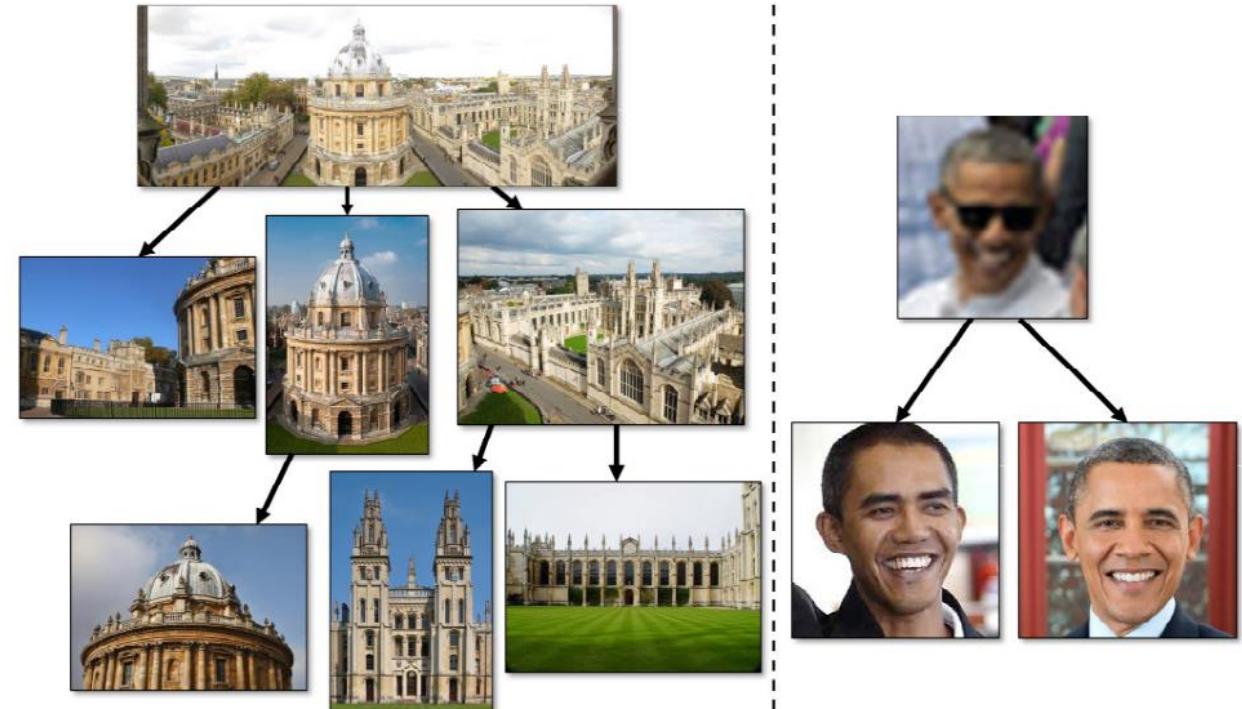
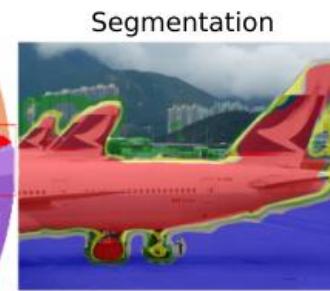
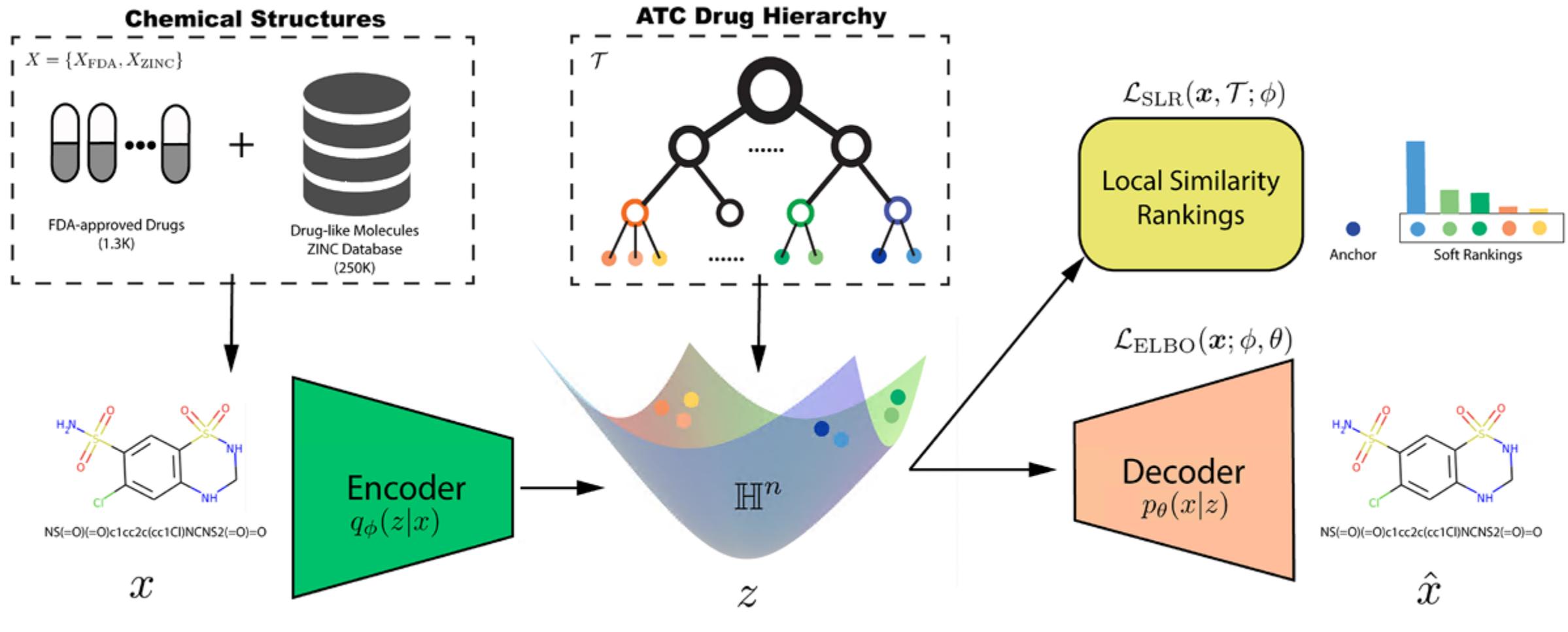


Image classification

Hyperbolic space provides spacious room and additionally present uncertainty information.

Left: GhadimiAtigh, Mina, et al. "Hyperbolic Image Segmentation." CVPR (2022). Right: Khrulkov, Valentin, et al. "Hyperbolic image embeddings." CVPR (2020).

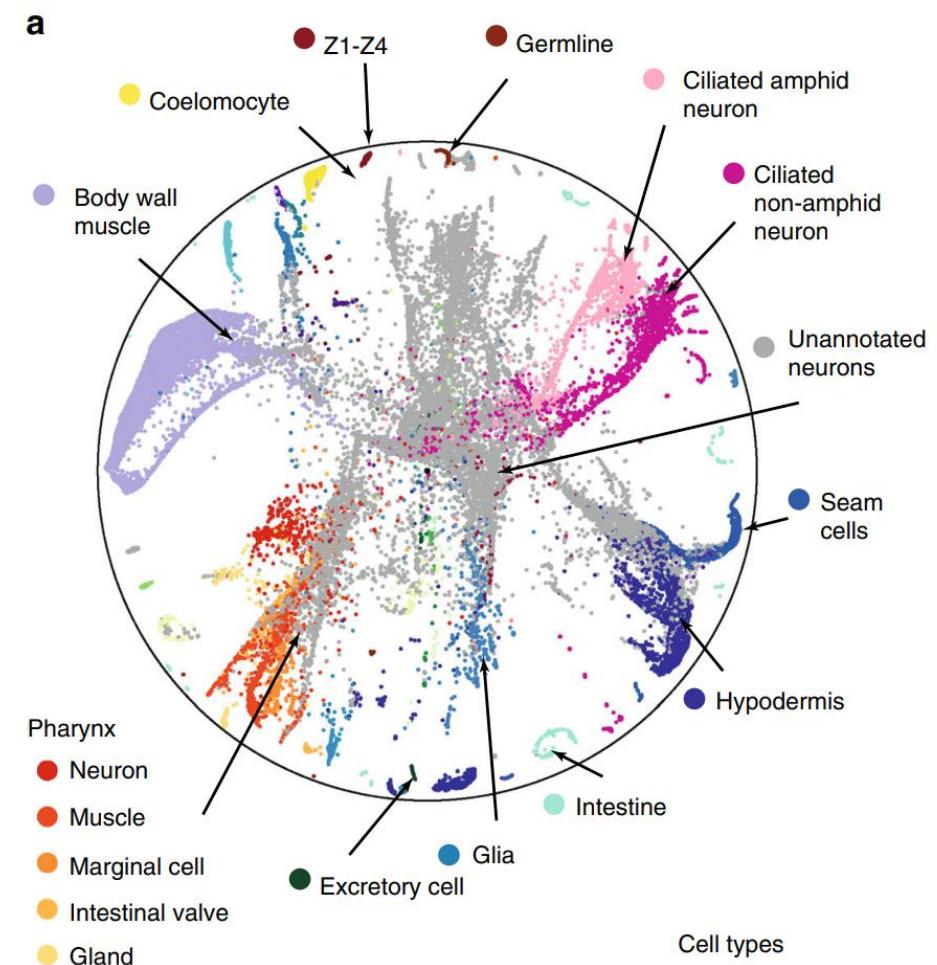
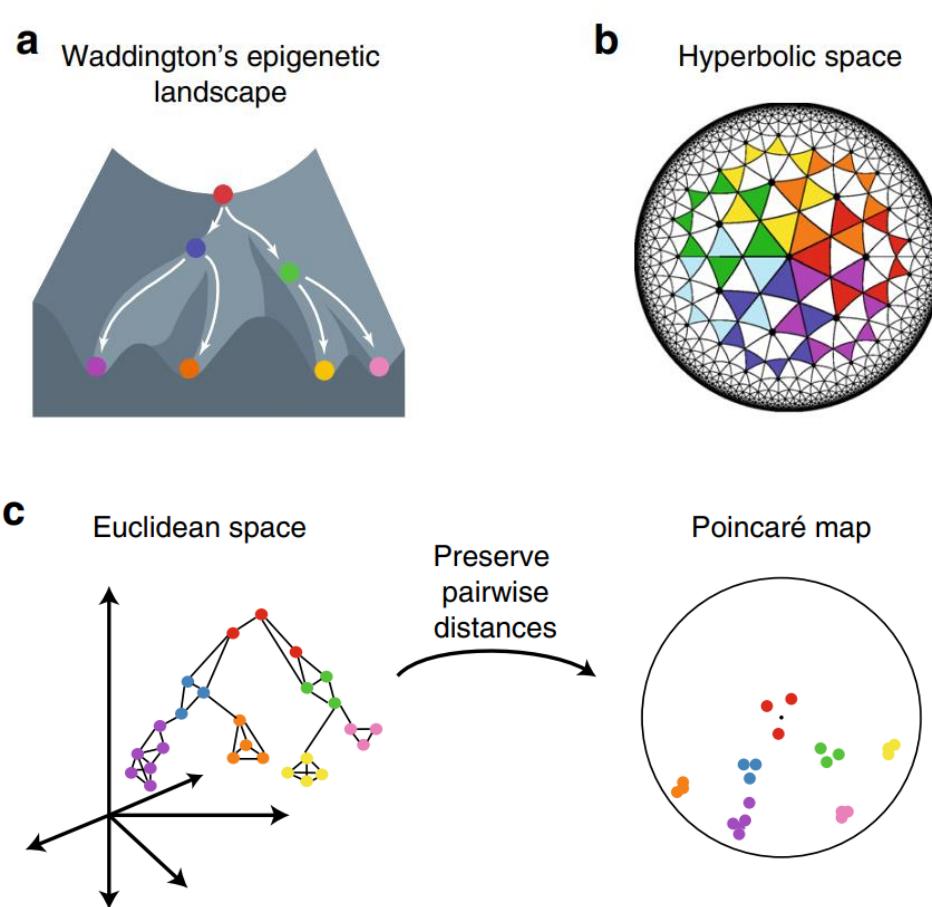
Hyperbolic Space for Drug Generation



Hyperbolic spaces help inject hierarchies knowledge for drug generation.

Yu, Ke, Shyam Visweswaran, and Kayhan Batmanghelich. "Semi-supervised hierarchical drug embedding in hyperbolic space." Journal of chemical information and modeling 60.12 (2020): 5647-5657.

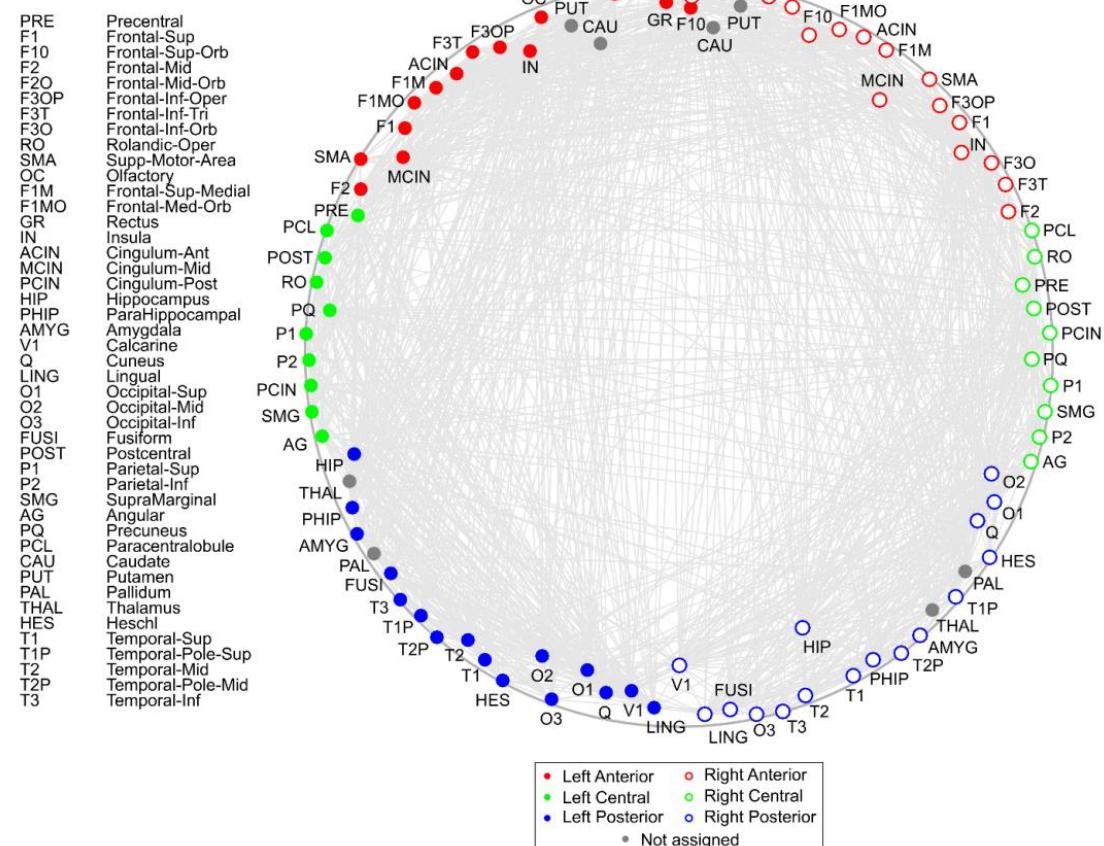
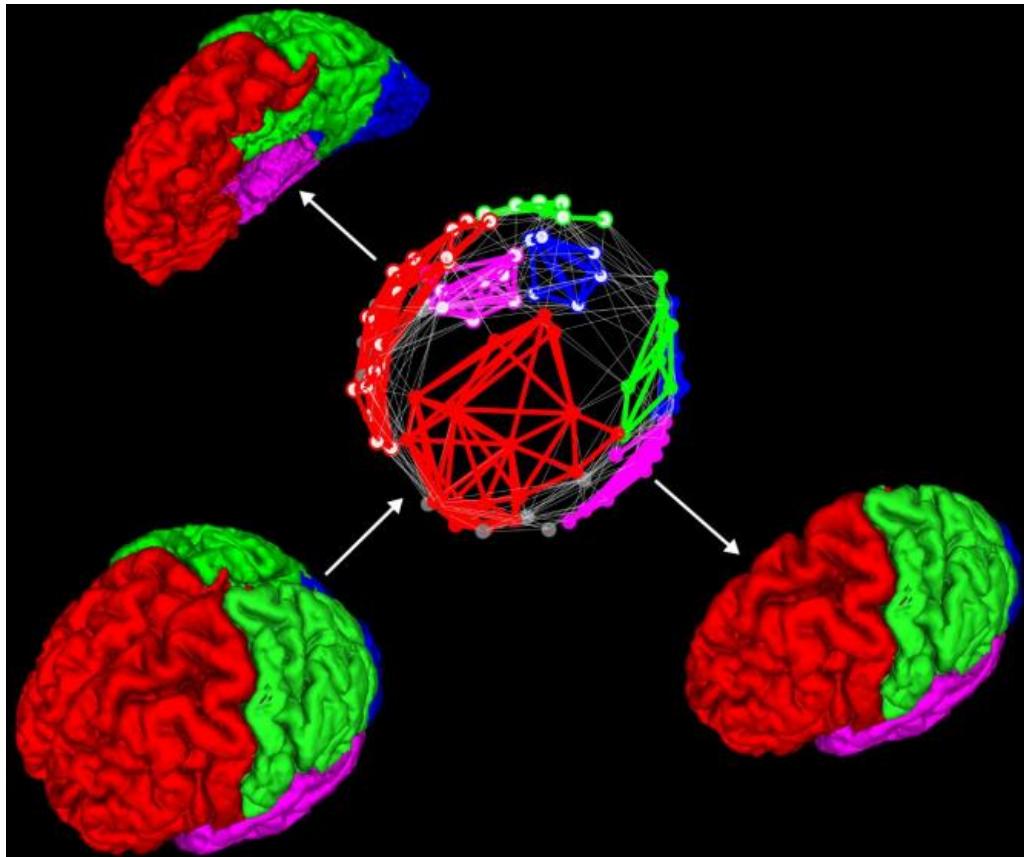
Hyperbolic Space for Cell Analyzing



Hyperbolic maps discover hierarchies and branching processes.

Klimovskaia, Anna, et al. "Poincaré maps for analyzing complex hierarchies in single-cell data." Nature communications 11.1 (2020): 1-9.

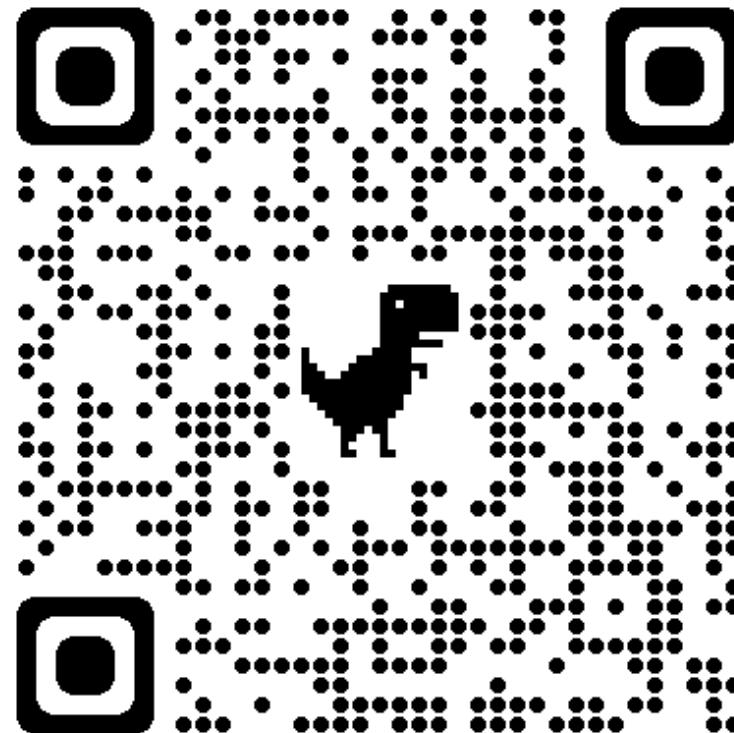
Hyperbolic Space for Brain Structure



Hyperbolic space provides separable room for different sub-structures.

Cacciola, Alberto, et al. "Coalescent embedding in the hyperbolic space unsupervisedly discloses the hidden geometry of the brain." BOOK OF ABSTRACTS. 2017.

Break





GRENOBLE 19-23.09.2022

4. Advanced Topics

Contents

1. INTRODUCTION

- 1.1 An Overview of Graph Representation Learning
- 1.2 Brief Introduction of Riemannian Geometry
- 1.3 Motivation of Hyperbolic Graph Representation Learning

2. HYPERBOLIC GRAPH REPRESENTATION LEARNING (HGRL)

- 2.1 Hyperbolic Shallow Models
- 2.2 Hyperbolic Neural Networks
- 2.3 Hyperbolic Graph Neural Networks

3. APPLICATIONS

- 3.1 HGRL for Recommendation Systems
- 3.2 HGRL for Knowledge Graph
- 3.3 HGRL for other Applications

4. ADVANCED TOPICS

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- 4.2 Evolving Interactions
- 4.3 Geometry-Aware Learning
- 4.4 Trustworthy and Scalability

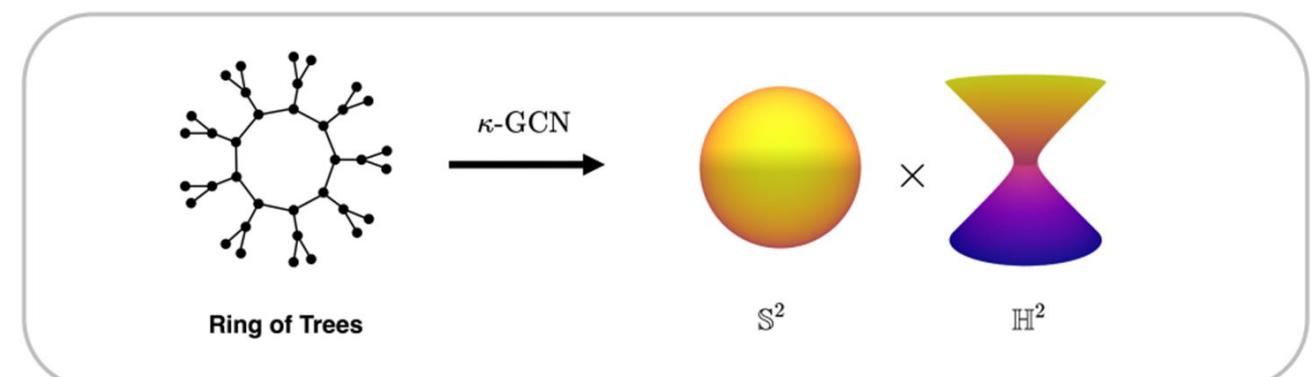
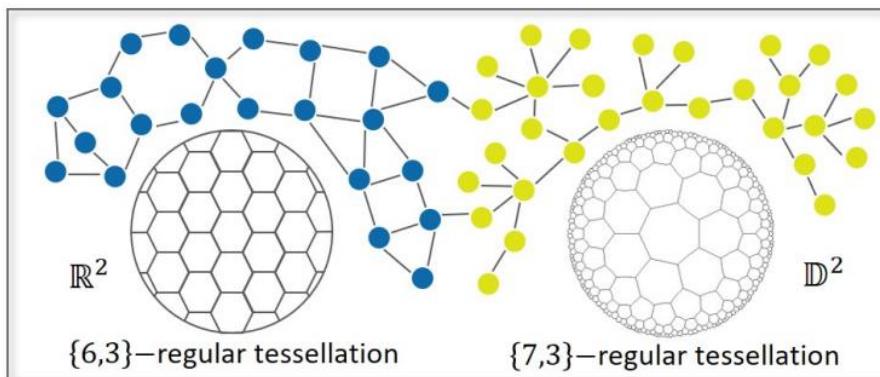
4.1 Complex Structures

➤ Interaction learning of mix spaces

- Constant Curvature Graph Convolutional Networks. ICML 2020
- Graph Geometry Interaction learning. NeurIPS 2020
- Mixed-curvature multi-relational graph neural network for knowledge graph completion. WebConf 2021
- A self-supervised mixed-curvature graph neural network. AAAI2022
- Dual-Geometric Space Embedding Model for Two-View Knowledge Graphs. KDD2022
- ...

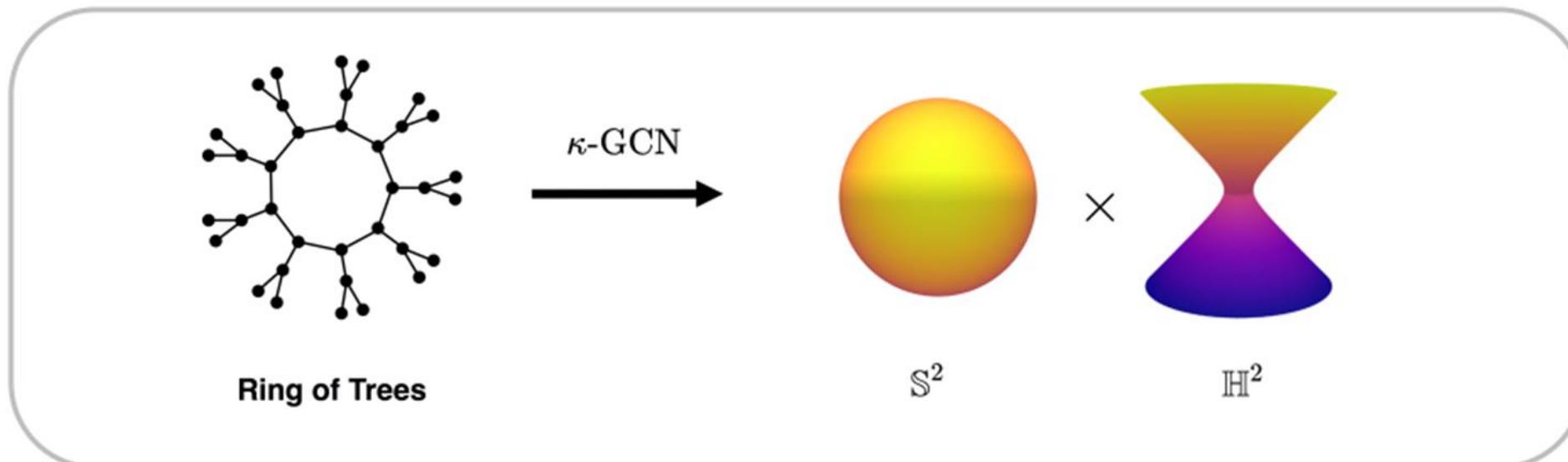
➤ Encapsulate network curvature into embedding space

- Heterogeneous manifolds for curvature-aware graph embedding. ICLR 2022 Workshop
- Hyperbolic Curvature Graph Neural Network. arXiv 2022
- ...



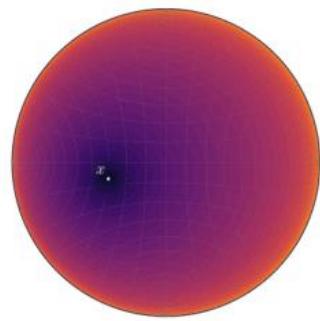
Constant Curvature Graph Convolution Networks

- Embed graphs into **hyperbolic** and **spherical** space

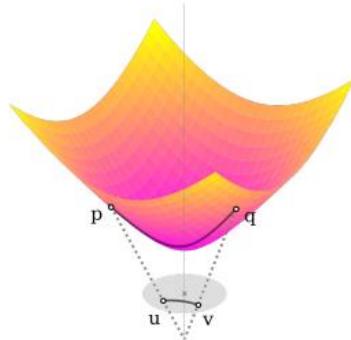


Constant Curvature Graph Convolution Networks

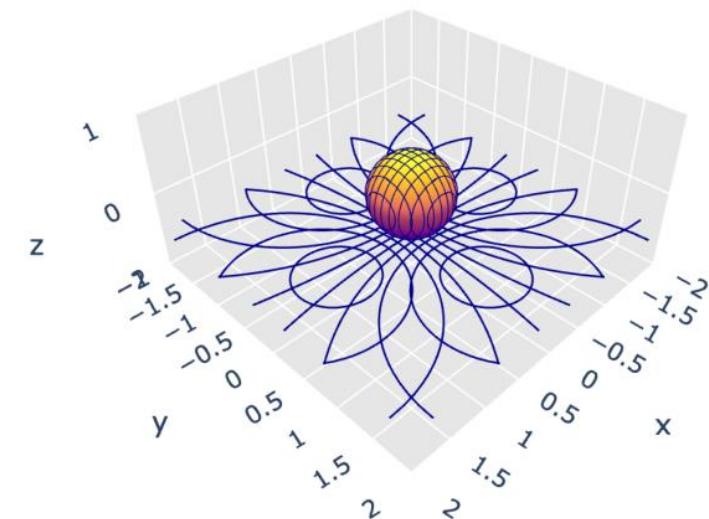
- Unified formalism of the κ – stereographic model for any $\kappa \in \mathbb{R}$



Heatmap of $d_{\mathbb{H}}^{\kappa}$



Projection of hyperboloid



Constant Curvature Graph Convolution Networks

- Unified formalism of the κ – stereographic model for any $\kappa \in \mathbb{R}$:

$$\mathfrak{st}_\kappa^d = \{\mathbf{x} \in \mathbb{R}^d \mid -\kappa \|\mathbf{x}\|_2^2 < 1\}$$

	\mathbb{R}^d	\mathfrak{st}_κ^d
$\mathbf{x} \oplus_\kappa \mathbf{y}$	$\mathbf{x} + \mathbf{y}$	$\frac{(1 - 2\kappa \mathbf{x}^T \mathbf{y} - \kappa \ \mathbf{y}\ ^2) \mathbf{x} + (1 + \kappa \ \mathbf{x}\ ^2) \mathbf{y}}{1 - 2\kappa \mathbf{x}^T \mathbf{y} + \kappa^2 \ \mathbf{x}\ ^2 \ \mathbf{y}\ ^2}$
$r \otimes_\kappa \mathbf{x}$	$r\mathbf{x}$	$\tan_\kappa(r \cdot \tan_\kappa^{-1} \ \mathbf{x}\) \frac{\mathbf{x}}{\ \mathbf{x}\ }$
$\gamma_{\mathbf{x} \rightarrow \mathbf{y}}(t)$	$\mathbf{x} + t(\mathbf{y} - \mathbf{x})$	$\mathbf{x} \oplus_\kappa (t \otimes_\kappa (-\mathbf{x} \oplus_\kappa \mathbf{y}))$

Constant Curvature Graph Convolution Networks

- Extend the vanilla GCN to the constant curvature GCN

$$\mathbf{H}^{(t+1)} = \sigma(\hat{\mathbf{A}}\mathbf{H}^{(t)}\mathbf{W}^{(t)}) \quad \Rightarrow \quad \mathbf{H}^{(l+1)} = \sigma^{\otimes \kappa}(\hat{\mathbf{A}} \boxtimes_{\kappa} (\mathbf{H}^{(l)} \otimes_{\kappa} \mathbf{W}^{(l)}))$$

where $\sigma^{\otimes \kappa}$ is the κ -stereographic version of σ

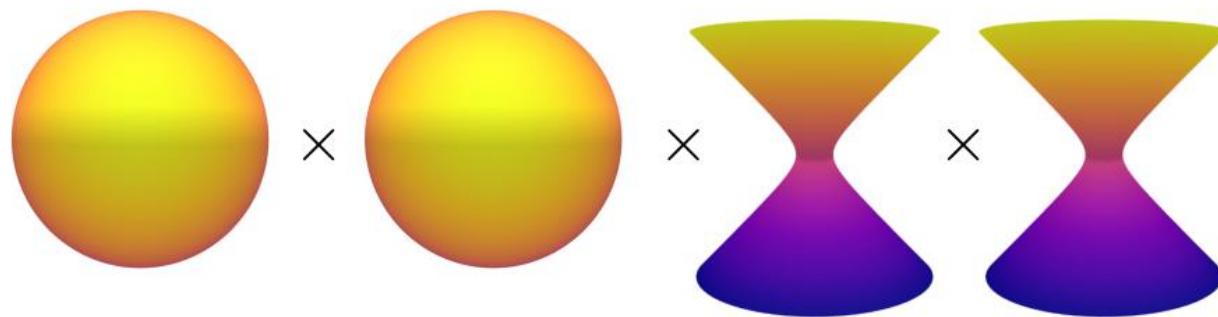
- Learn the curvature to adapt to the geometry of the data

$$\kappa\text{-GCN} \xrightarrow{\kappa \rightarrow 0} \text{GCN}.$$

Constant Curvature Graph Convolution Networks

- Embed in product space via **gyrovector space** structure

$$\mathfrak{st}_{\kappa_1}^d \times \cdots \times \mathfrak{st}_{\kappa_m}^d$$



Constant Curvature Graph Convolution Networks

- Experiments on distortion task
 - Minimize the discrepancy between embedding distances and graph distances

$$L(\mathbf{x}_1, \dots, \mathbf{x}_n) = \frac{1}{n^2} \sum_{i,j} \left(\left(\frac{d_\kappa(\mathbf{x}_i, \mathbf{x}_j)}{d_G(i,j)} \right)^2 - 1 \right)^2$$

- Results on tree (negative curvature), spherical graph (positive curvature) and toroidal graph (product of positive curvature)
 - The best performing architecture is the one that matches the underlying geometry of the graph.

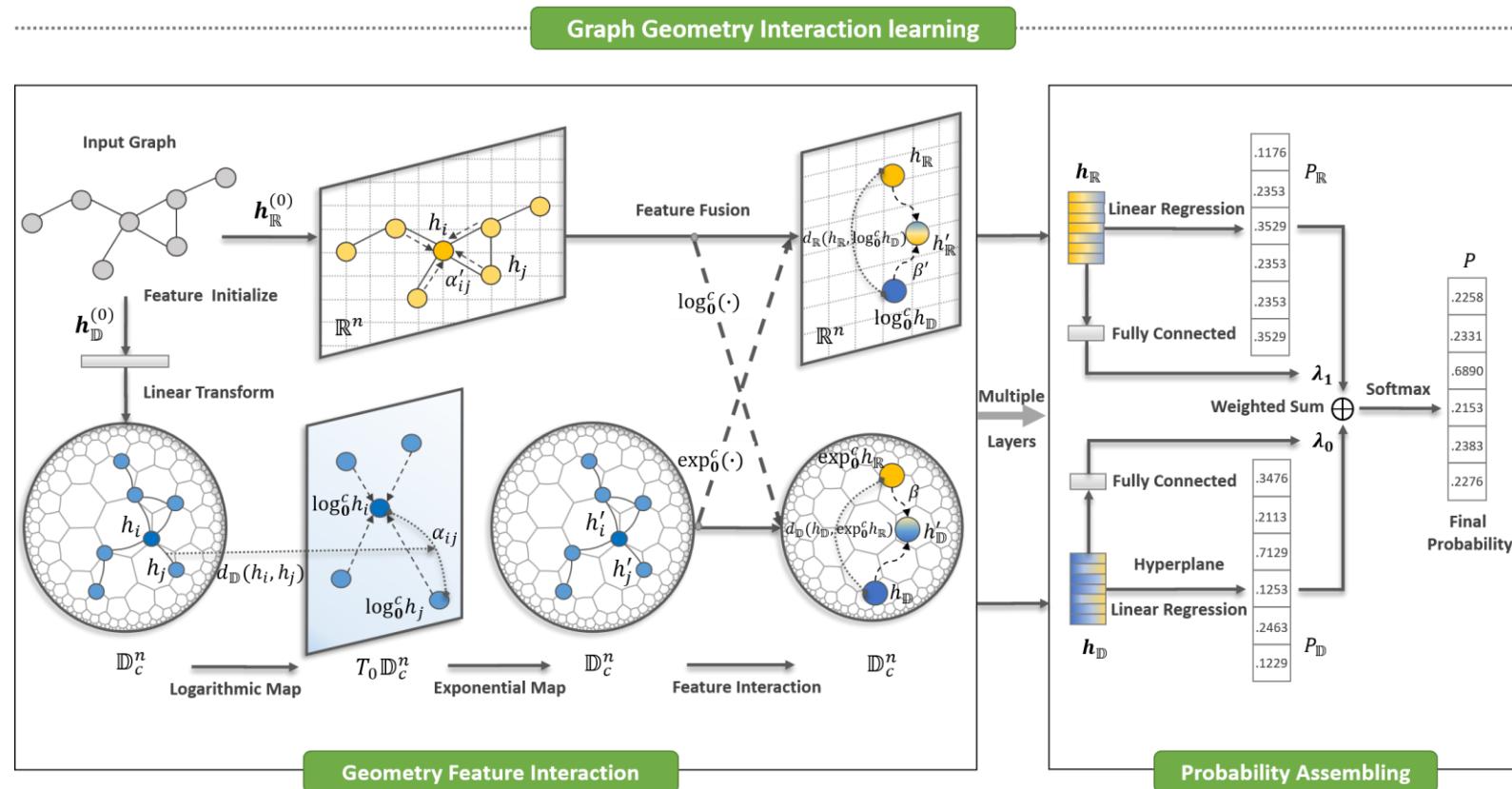
MODEL	TREE	TOROIDAL	SPHERICAL
\mathbb{E}^{10} (GCN)	0.0502	0.0603	0.0409
\mathbb{H}^{10} (κ -GCN)	0.0029	0.272	0.267
\mathbb{S}^{10} (κ -GCN)	0.473	0.0485	0.0337
$\mathbb{H}^5 \times \mathbb{H}^5$ (κ -GCN)	0.0048	0.112	0.152
$\mathbb{S}^5 \times \mathbb{S}^5$ (κ -GCN)	0.51	0.0464	0.0359

Constant Curvature Graph Convolution Networks

- Experiments on Node Classification

MODEL	CITESEER	CORA	PUBMED	AIRPORT
\mathbb{E}^{16} [3]	72.9 ± 0.54	81.4 ± 0.4	79.2 ± 0.39	81.4 ± 0.29
\mathbb{H}^{16} [1]	71 ± 0.49	80.3 ± 0.46	79.8 ± 0.43	84.4 ± 0.41
\mathbb{H}^{16} (κ -GCN)	73.2 ± 0.51	81.2 ± 0.5	78.5 ± 0.36	81.9 ± 0.33
\mathbb{S}^{16} (κ -GCN)	72.1 ± 0.45	81.9 ± 0.45	78.8 ± 0.49	80.9 ± 0.58
PROD-GCN	71.1 ± 0.59	80.8 ± 0.41	78.1 ± 0.6	81.7 ± 0.44

Graph Geometry Interaction Learning(GIL)



Geometry Interaction Learning

- Euclidean space: powerful simplicity and efficiency
- Hyperbolic space: ability for hierarchical structure

Graph Geometry Interaction Learning(GIL)

- Geometry Message Propagation

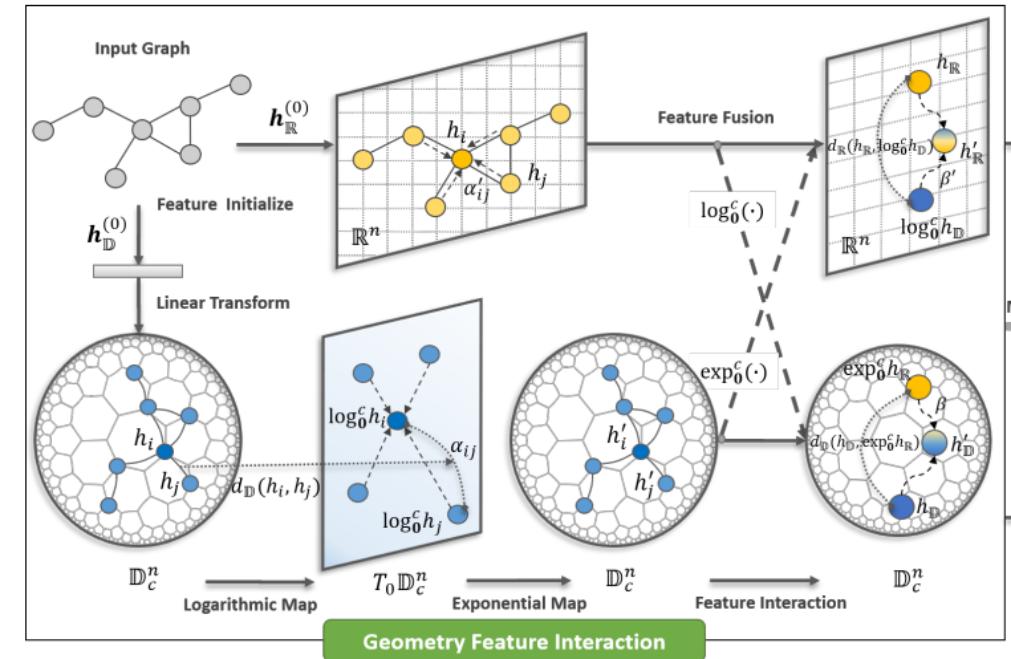
- Dual Feature propagation: propagates neighbor information simultaneously in a Euclidean space and a hyperbolic space via a distance-aware attention mechanism
- Dual Feature Interaction: node features undergo an adaptive adjustment from the dual feature space based on distance similarity

→ hyperbolic distance

similarity

$$h'_{\mathbb{D}_c} = h_{\mathbb{D}_c} \oplus_c (\beta d_{\mathbb{D}_c} (h_{\mathbb{D}_c}, \exp_0^c(h_{\mathbb{R}})) \otimes_c \exp_0^c(h_{\mathbb{R}})),$$
$$h'_{\mathbb{R}} = h_{\mathbb{R}} + (\beta d_{\mathbb{R}} (h_{\mathbb{R}}, \log_0^c(h_{\mathbb{D}_c})) \times \log_0^c(h_{\mathbb{D}_c})),$$

→ Euclidean distance



Graph Geometry Interaction Learning(GIL)

- Probability Assembling

- One classifier

$$P = \text{Euc-Softmax} (f (\log_0^c(X_{\mathbb{D}_c}) || X_{\mathbb{R}})),$$

$$P = \text{Hyp-Softmax} (g (X_{\mathbb{D}_c} || \exp_0^c (X_{\mathbb{R}}))),$$

- Two classifier

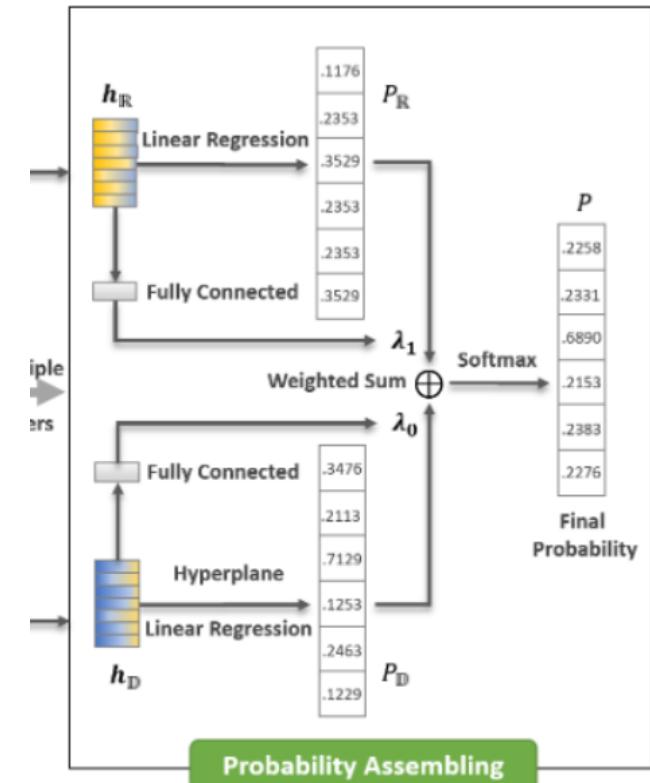
$$P = \lambda_0 P_{\mathbb{D}_c} + \lambda_1 P_{\mathbb{R}},$$

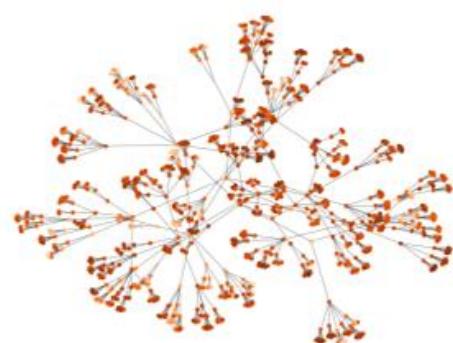
$$\text{s.t. } \lambda_0 + \lambda_1 = 1,$$

Final probability of two parts are determined by the *node features*

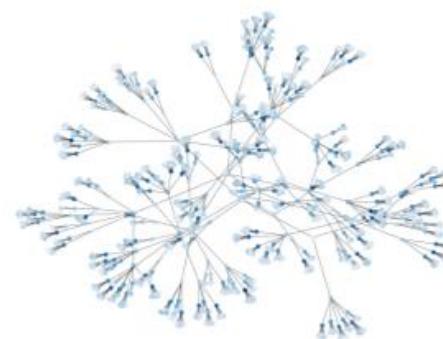
$$\lambda_0 = \text{sigmoid} (FC_0 (\log_0^c (X_{\mathbb{D}_c}^\top))), \lambda_1 = \text{sigmoid} (FC_1 (X_{\mathbb{R}}^\top)),$$

$$[\lambda_0, \lambda_1] = \frac{[\lambda_0, \lambda_1]}{\max (\|[\lambda_0, \lambda_1]\|_2, \epsilon)},$$

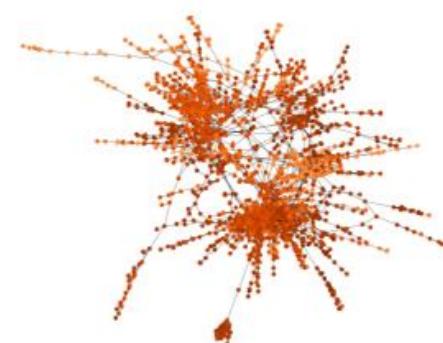




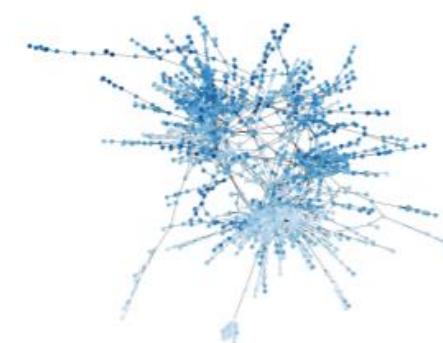
(a) Disease: Hyperbolic



(b) Disease: Euclidean



(c) Citeseer: Hyperbolic



(d) Citeseer: Euclidean

Encapsulate continuous and discrete curvature

- Curvature on network: measures the changes of local connectivity

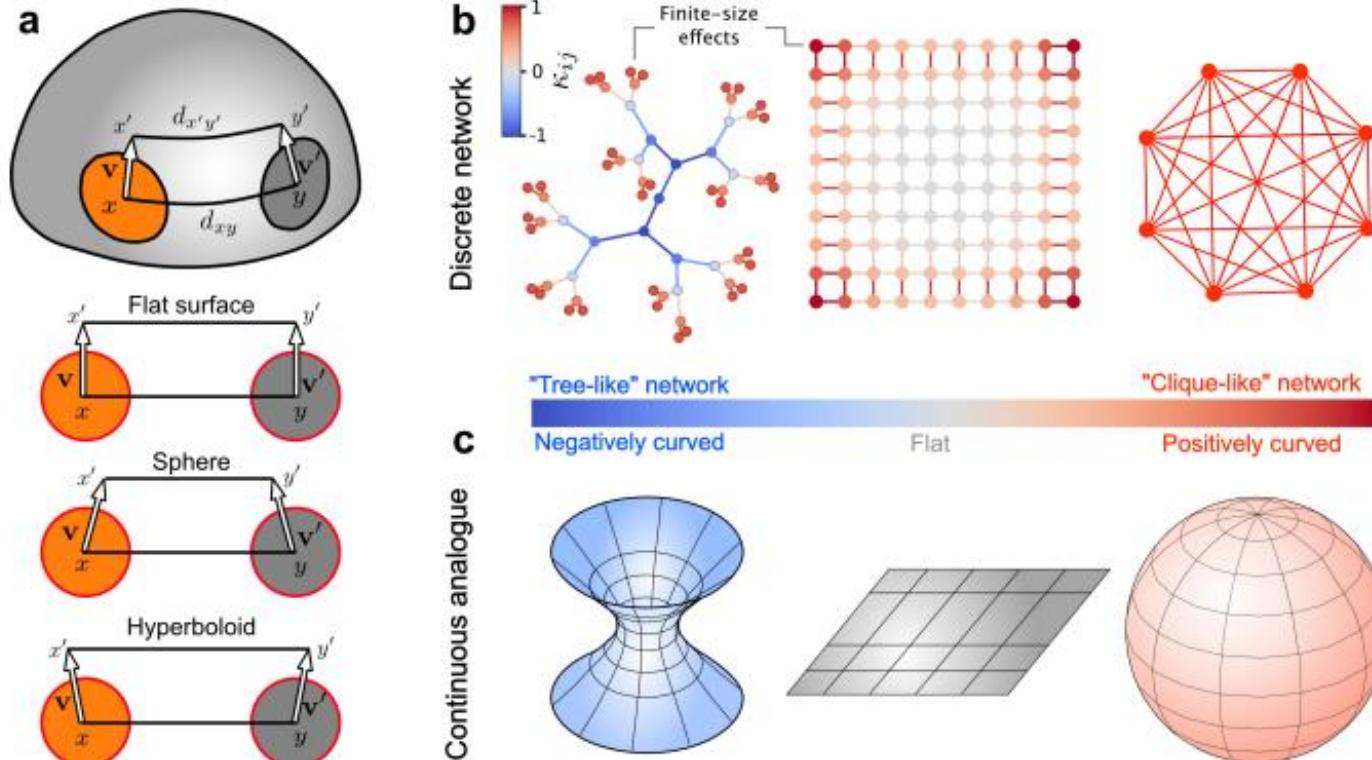
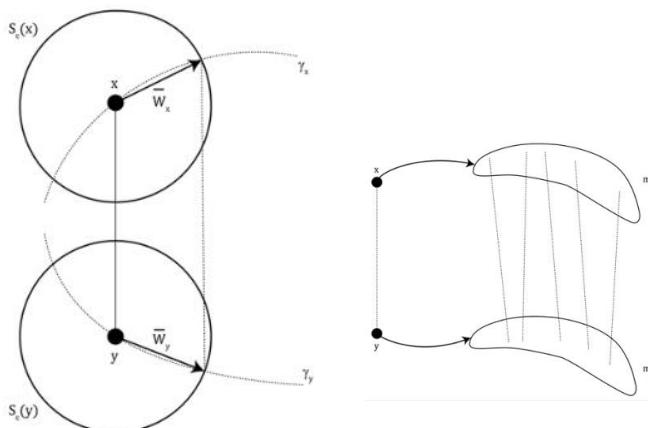


Fig. Ricci and dynamical Ollivier Ricci curvature on canonical surfaces and graph structures

Discrete Ricci Curvature

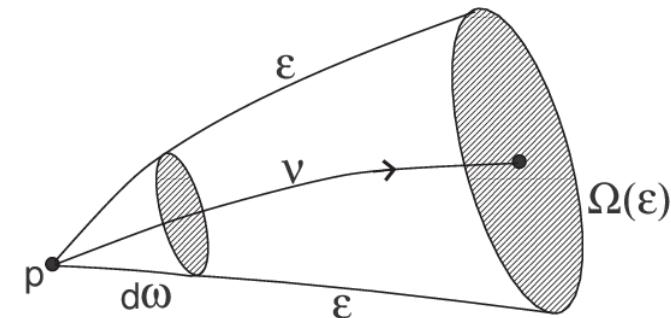
Ollivier-Ricci curvature

- ✓ Basic idea: Optimal transport
- ✓ Emphasizes clustering



Forman-Ricci curvature

- ✓ Basic idea: Dispersion
- ✓ Emphasize network dynamic



Source: Comparative analysis of two discretizations of Ricci curvature for complex networks

Froman-Ricci Curvature

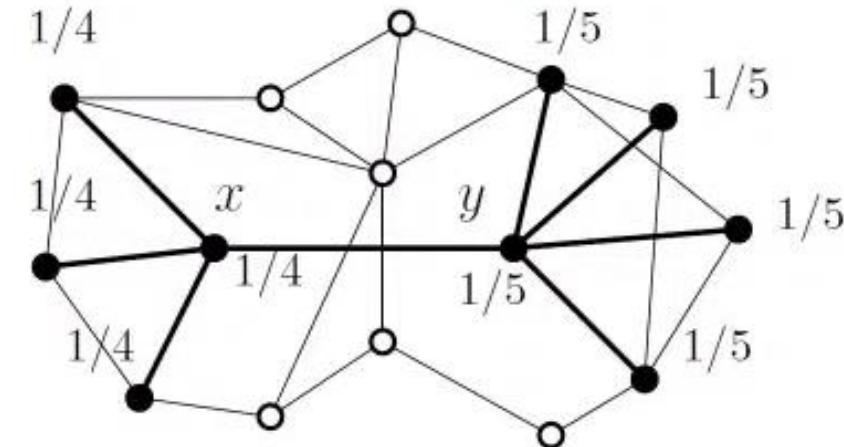
- Quantifies the degree of spread of the vertices
- Consider **triangles** as faces, and Δ_{uv} is the number of triangles that contain u, v . All edges have weight

$$F(u, v) = 4 - \deg(u) - \deg(v) + 3\Delta_{uv}$$

Ollivier-Ricci Curvature

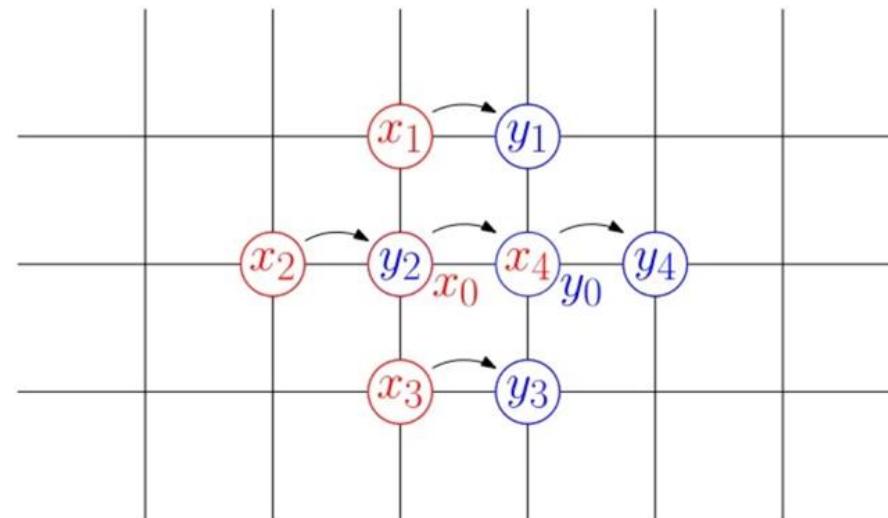
- For an edge xy , consider **the distance** from x 's neighbors to y 's neighbors and compare it with the length of xy
- How to compute the **distance** of x 's neighbors to y 's neighbors?
 - Optimal transport distance

$$\kappa_{xy} = 1 - \frac{W(m_x, m_y)}{d(x, y)},$$



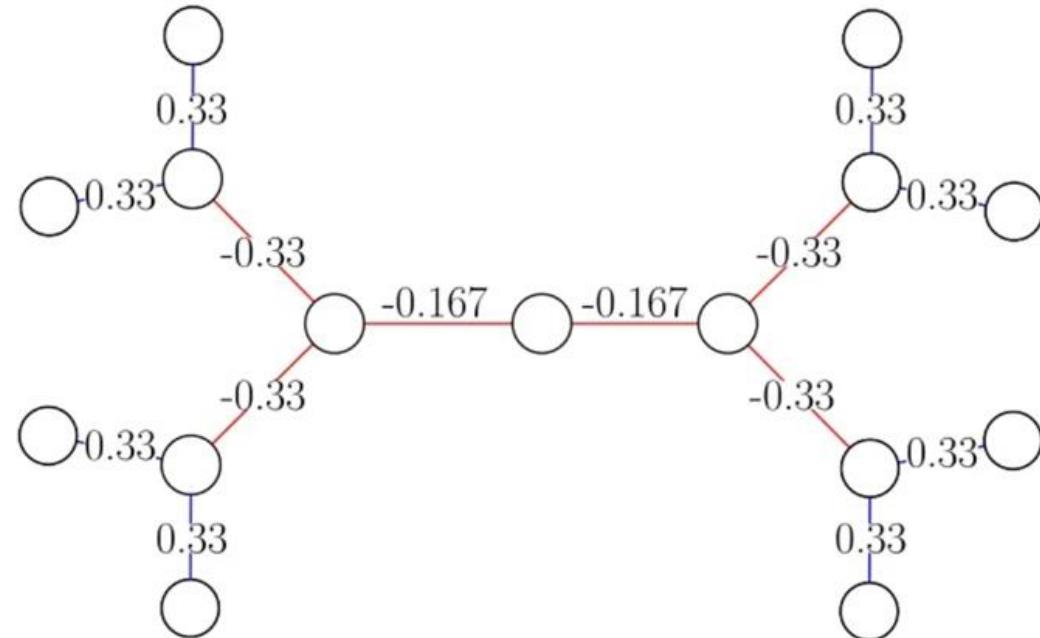
Curvature on Network

- Zero Curvature: 2D grid



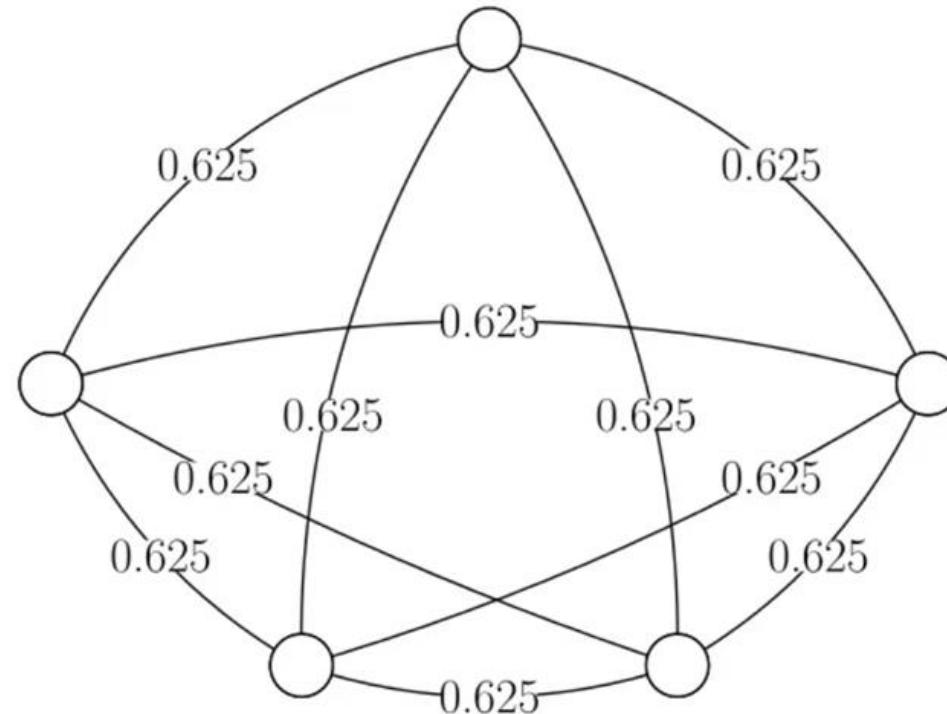
Curvature on Network

- Negative curvature: $k(x, y) = \frac{1}{d_x} + \frac{1}{d_y} - 1$, d_x is degree of x.



Curvature on Network

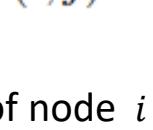
- Positive Curvature: Complete graph

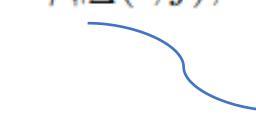


Curvature-aware graph embedding

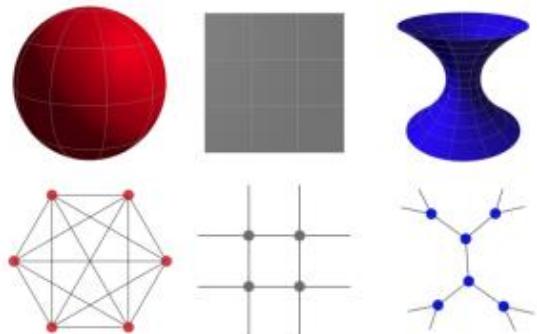
- Adapt an augmented Forman curvature:

$$F(i, j) = 4 - d_i - d_j + 3\gamma \sharp_{\Delta}(i, j), \quad \gamma > 0,$$

Degree of node i 

The number of triangles at the edge (i, j) 

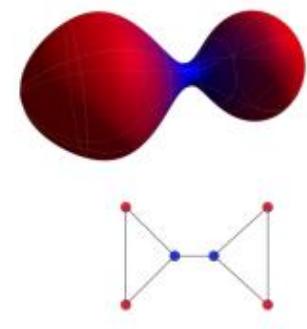
$$F(i) = \frac{1}{d_i} \sum_{j:j \sim i} F(i, j)$$



(a) Space forms (sphere, plane, hyperboloid)



(b) Product manifold



(c) Heterogeneous manifold

Curvature-aware graph embedding

- **Loss function:** Minimize distance and curvature depending loss

$$\mathcal{L}(\{y_i\}) = \mathcal{L}_d(\{y_i\}) + \tau \mathcal{L}_c(\{y_i\}),$$

$$\mathcal{L}_d(\{y_i\}) = \sum_{i,j} \left| \frac{d_{g_h}^2(z_i, z_j) + (r_i - r_j)^2}{d_G^2(x_i, x_j)} - 1 \right|$$

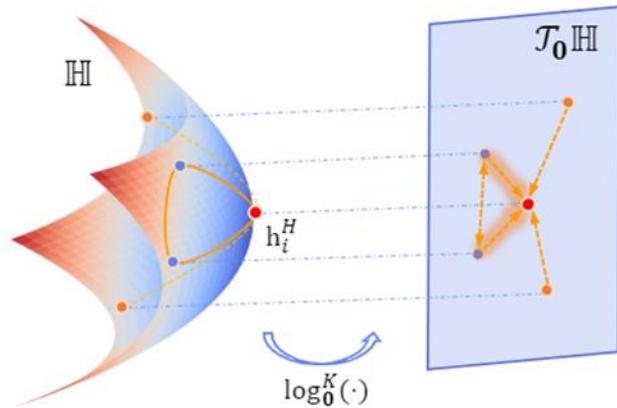
Measures the relative squared distance
Distortion.

$$\mathcal{L}_c(\{y_i\}) = \sum_i \frac{(F(x_i) - R_h - R_\alpha(r_i))^2}{(|F(x_i)| + \epsilon)^2},$$

Measures how close the local geometry
of the manifold around the embedded
nodes resembles that of the graph.

Curvature-aware graph embedding

- Curvature-guided message aggregation



$$\tilde{\mathbf{h}}_i^{\ell,H} = \exp_0^{K_{l-1}} \left(\sum_{j \in N(i)} \tilde{\kappa}_{i,j} \cdot \log_0^{K_{l-1}} (\mathbf{h}_j^{\ell,H}) \right)$$

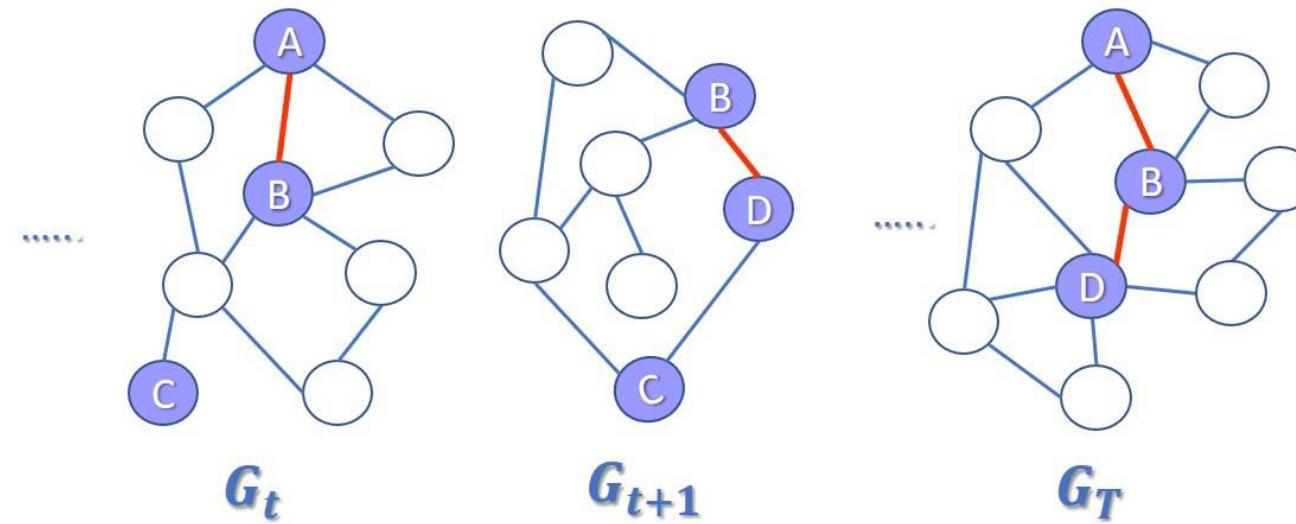
$$\tilde{\kappa}_{i,j} = \text{softmax}_{j \in \mathcal{N}(i)} (\text{MLP}(\kappa_{i,j} - |L_i - L_j|))$$

- Curvature-enhanced message exchange

$$l_{hc+} = \frac{1}{|E_\kappa|} \sum_{(i,j) \in E_\kappa} -\log p(\mathbf{x}_i^{\ell,\mathcal{H}}, \mathbf{x}_j^{\ell,\mathcal{H}}),$$

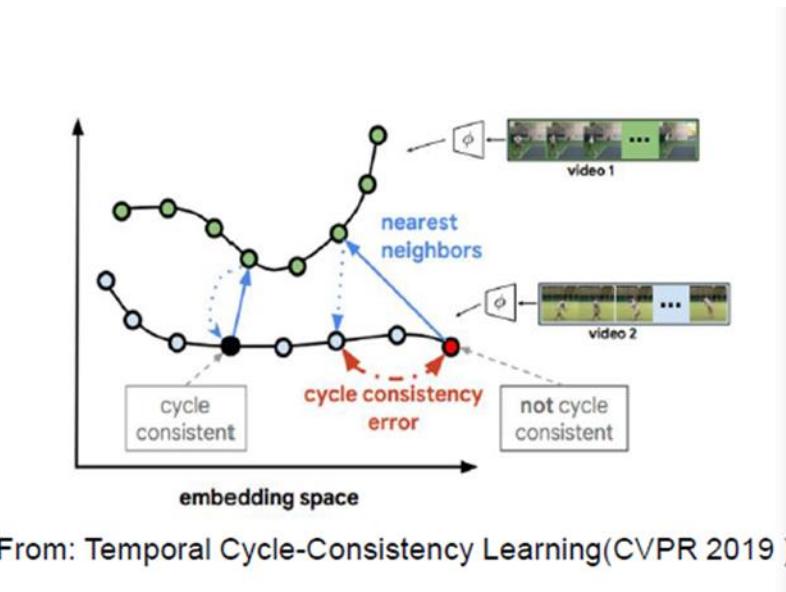
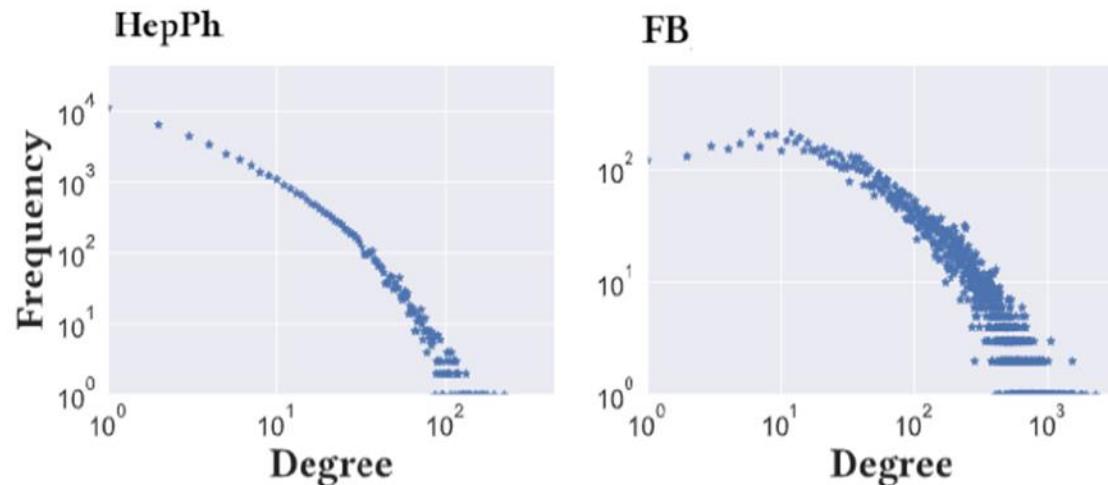
4.2 Evolving Interactions

- Hyperbolic Variational Graph Neural Network for Modeling Dynamic Graphs AAAI2021
- Discrete-time temporal network embedding via implicit hierarchical learning in hyperbolic space KDD2021
- A Self-supervised Riemannian GNN with Time Varying Curvature for Temporal Graph Learning CIKM 2022
- ...



<https://towardsdatascience.com/tdgraphembed-temporal-dynamic-graph-level-embedding-1cc611bc7dbo>

Hyperbolic Temporal Network Embeddings



From: Temporal Cycle-Consistency Learning(CVPR 2019)

Hyperbolic Temporal Network Embeddings

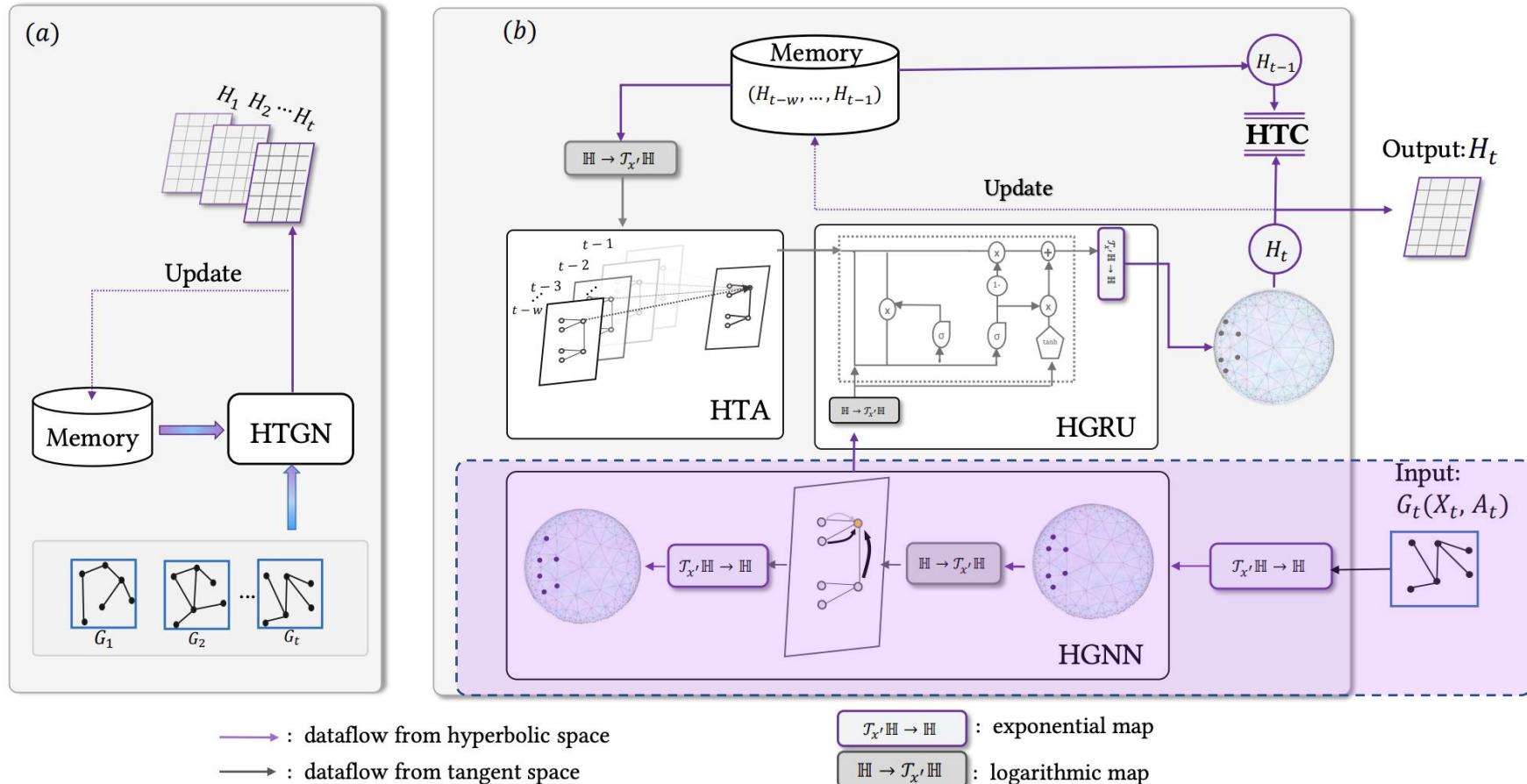


Figure 3: Schematic of HTGN. Figure (a) is a sketch of HTGN illustrating the recurrent paradigm and Figure (b) shows the data flow of an HTGN unit.

Hyperbolic Temporal Network Embeddings

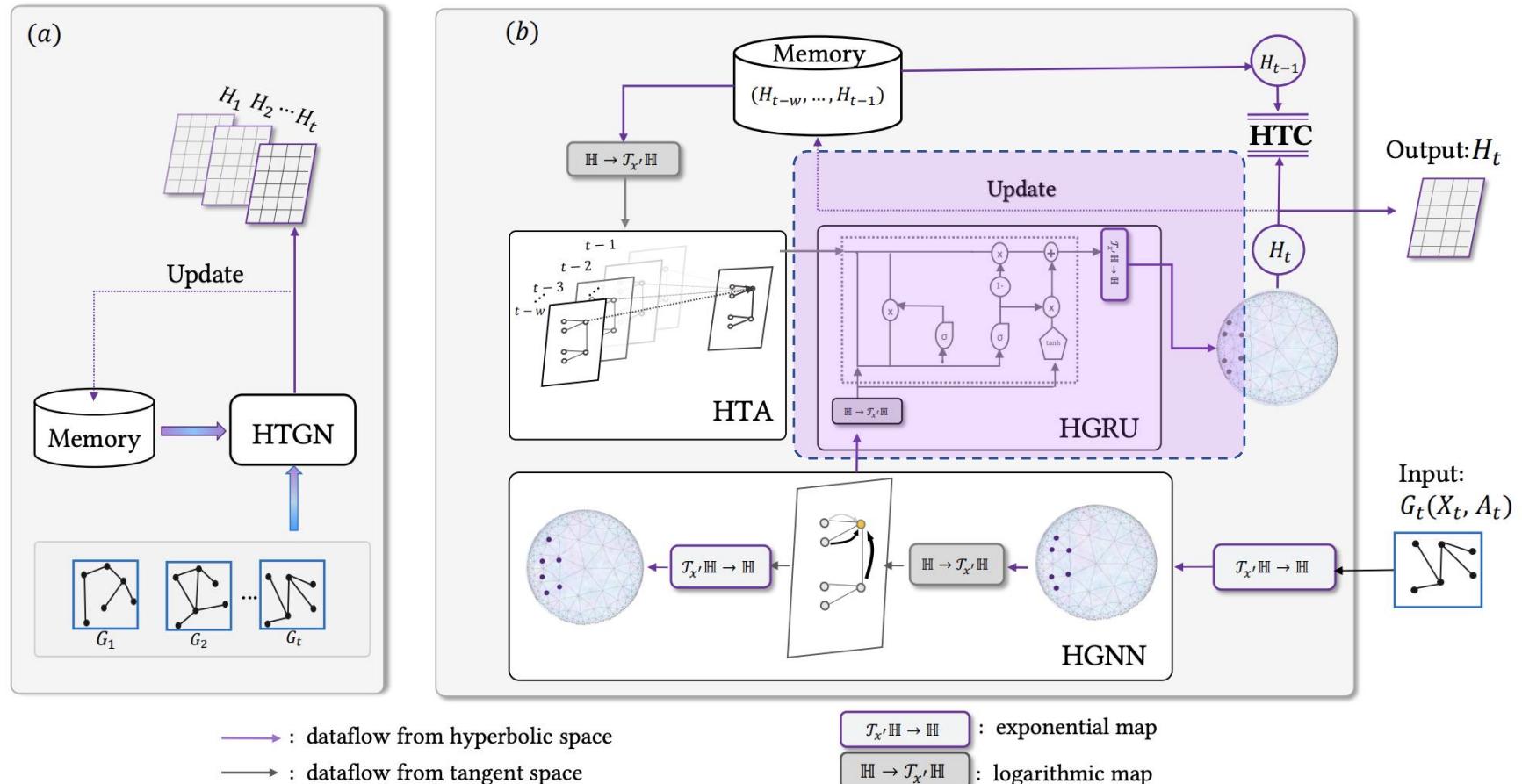


Figure 3: Schematic of HTGN. Figure (a) is a sketch of HTGN illustrating the recurrent paradigm and Figure (b) shows the data flow of an HTGN unit.

Hyperbolic Temporal Network Embeddings

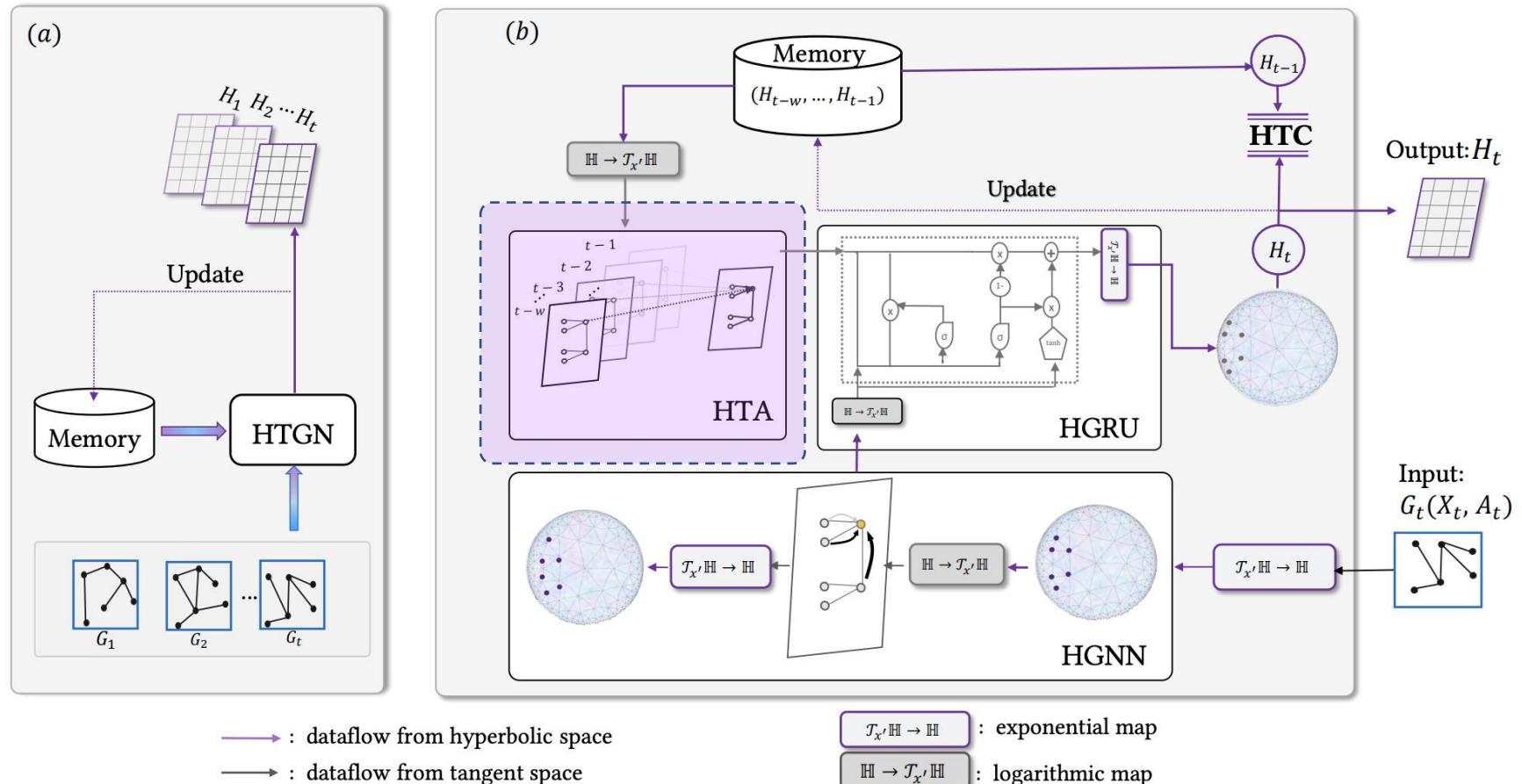


Figure 3: Schematic of HTGN. Figure (a) is a sketch of HTGN illustrating the recurrent paradigm and Figure (b) shows the data flow of an HTGN unit.

Hyperbolic Temporal Network Embeddings

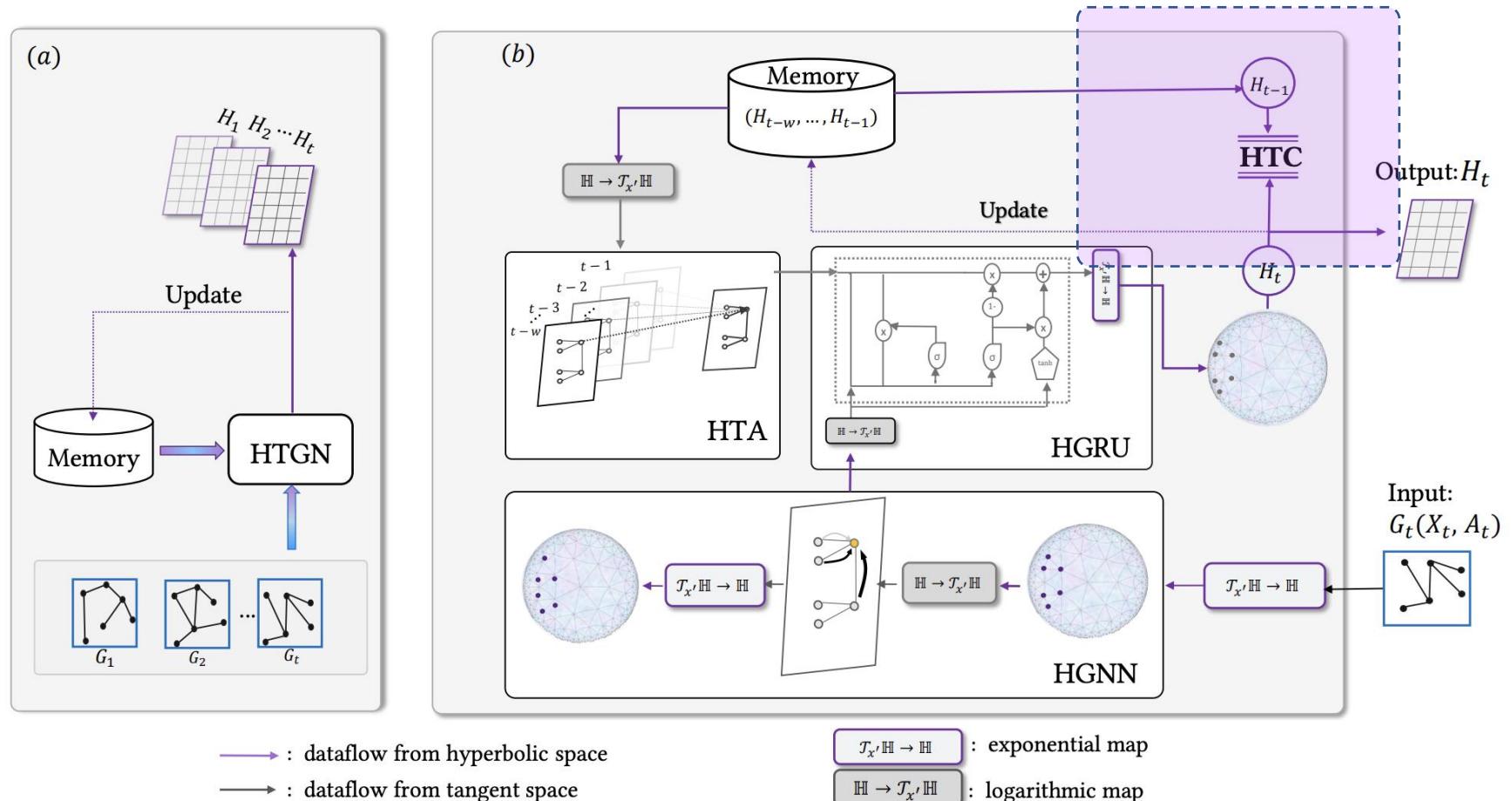


Figure 3: Schematic of HTGN. Figure (a) is a sketch of HTGN illustrating the recurrent paradigm and Figure (b) shows the data flow of an HTGN unit.

Table 2: Dataset statistics.

Datasets	DISEASE	HepPH	FB	AS733	Enron	COLAB
#Snapshots	7	36	36	30	11	10
#Test k	3	6	3	10	3	3
#Nodes	2665	15,330	45,435	6,628	184	315
#Total Edges	2664	976,097	180,011	13,512	790	943
Density $\rho(0.01)^*$	0.41	1.37	0.04	0.2	3.37	0.94
Hyperbolicity δ^*	0.0	1.0	2.0	1.5	1.5	2.0

* 0.01 denotes the value is in units of 0.01.

* The smaller δ indicates the dataset has a more evident hierarchical structure.

Table 3: AUC (left) and AP (right) scores of dynamic link prediction on real-world dynamic graphs.

Dataset	DISEASE	HepPh	AUC				DISEASE	HepPh	AP			
			FB	AS733	Enron	COLAB			FB	AS733	Enron	COLAB
GAE	72.55 ± 1.20	69.44 ± 0.56	63.07 ± 0.93	93.21 ± 1.53	92.50 ± 0.68	84.57 ± 0.64	60.55 ± 1.01	73.61 ± 0.58	65.35 ± 0.90	94.75 ± 0.90	93.48 ± 0.64	87.69 ± 0.44
VGAE	83.08 ± 1.27	72.39 ± 0.11	67.16 ± 0.53	95.76 ± 0.91	91.93 ± 0.34	85.16 ± 0.74	78.34 ± 1.25	75.78 ± 0.06	69.73 ± 0.17	96.42 ± 0.55	93.45 ± 0.49	88.70 ± 0.35
EvolveGCN	73.55 ± 4.23	76.82 ± 1.46	76.85 ± 0.85	92.47 ± 0.04	90.12 ± 0.69	83.88 ± 0.53	73.25 ± 3.44	81.18 ± 0.89	80.87 ± 0.64	95.28 ± 0.01	92.71 ± 0.34	87.53 ± 0.22
GRUGCN	79.25 ± 1.69	82.86 ± 0.53	79.38 ± 1.02	94.96 ± 0.35	92.47 ± 0.36	84.60 ± 0.92	65.26 ± 1.94	85.87 ± 0.23	82.77 ± 0.75	96.64 ± 0.22	93.38 ± 0.24	87.87 ± 0.58
DySAT	73.74 ± 2.28	81.02 ± 0.25	76.88 ± 0.08	95.06 ± 0.21	93.06 ± 0.97	87.25 ± 1.70	63.81 ± 1.86	84.47 ± 0.23	80.39 ± 0.14	96.72 ± 0.12	93.06 ± 1.05	90.40 ± 1.47
VGRNN	86.44 ± 3.12	77.65 ± 0.99	78.11 ± 1.11	95.17 ± 0.62	93.10 ± 0.57	85.95 ± 0.49	82.00 ± 3.83	80.95 ± 0.94	80.40 ± 0.74	96.69 ± 0.31	93.29 ± 0.69	87.77 ± 0.79
HTGN (Ours)	89.65 ± 0.70	91.13 ± 0.14	83.70 ± 0.33	98.75 ± 0.03	94.17 ± 0.17	89.26 ± 0.17	84.63 ± 0.65	89.52 ± 0.28	83.80 ± 0.43	98.41 ± 0.03	94.31 ± 0.26	91.91 ± 0.07
Gain (%)	+3.71	+9.98	+5.44	+3.12	+1.15	+2.30	+3.21	+4.25	+1.24	+1.75	+0.89	+1.67



Figure 4: AUC scores of different embedding dimensions on FB.

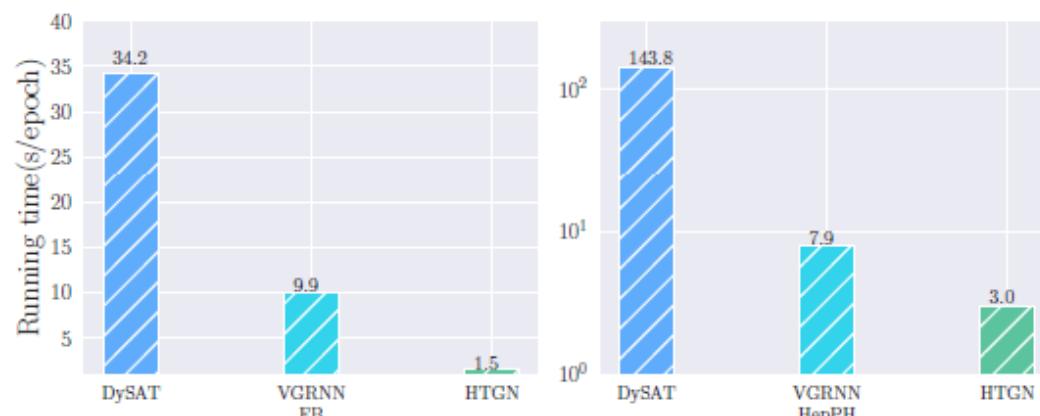


Figure 5: Running time on FB and HepPh.

Geometry-Aware Learning

- Enhancing hyperbolic graph embeddings via contrastive learning. NeurIPS 2021 Workshop
- HRCF: Enhancing collaborative filtering via hyperbolic geometric regularization. WebConf2022
- HICF: Hyperbolic Informative Collaborative Filtering. KDD2022
- ...

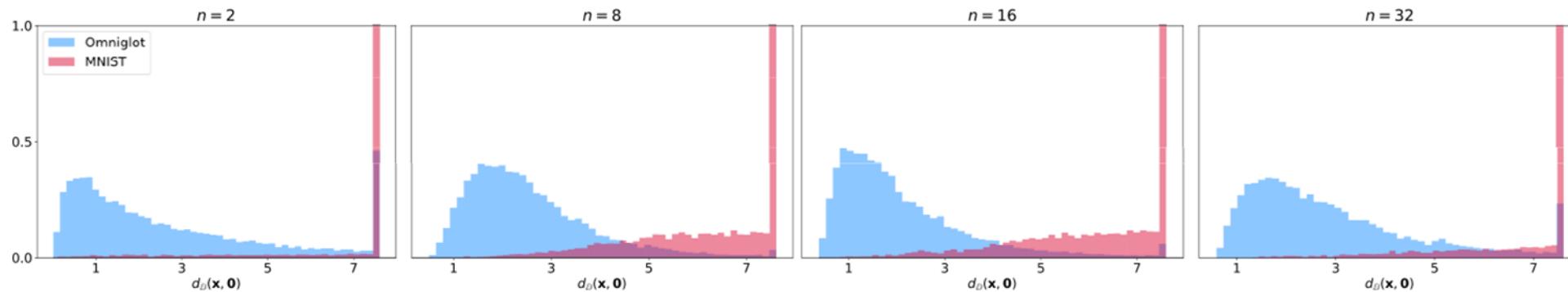


Figure source: Hyperbolic Image Embedding, CVPR 2020

Geometry-Aware Learning

- Hyperbolic space is more spacious in the area of hyperbolic space
 - Maintain the hierarchy but push the embeddings to the boundary

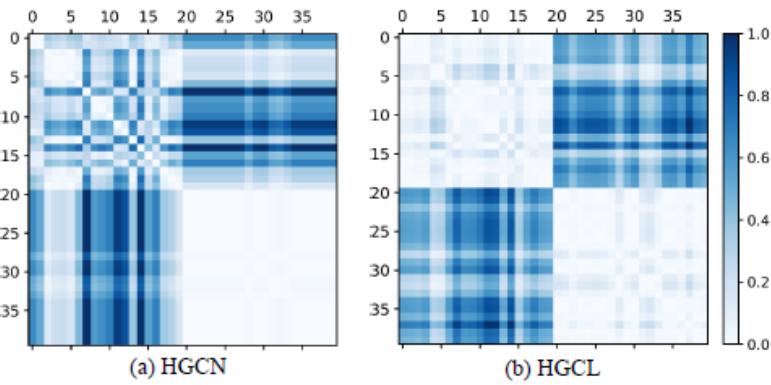


Figure 5: The distance heatmap among inter-class and intra-class embeddings on DISEASE

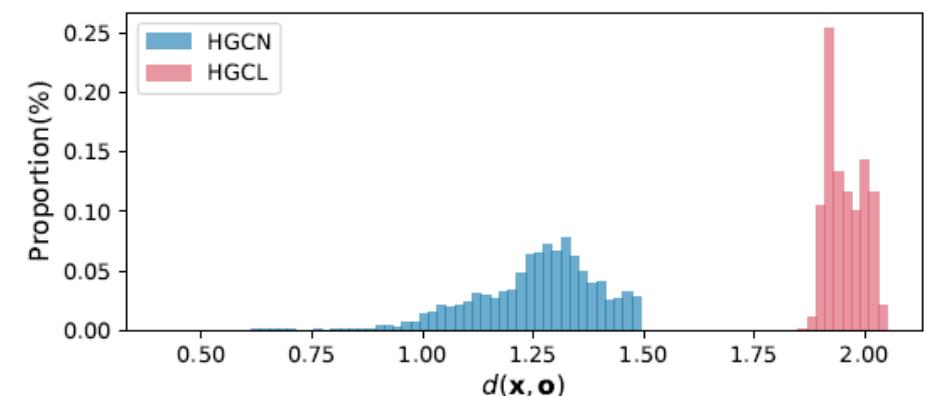
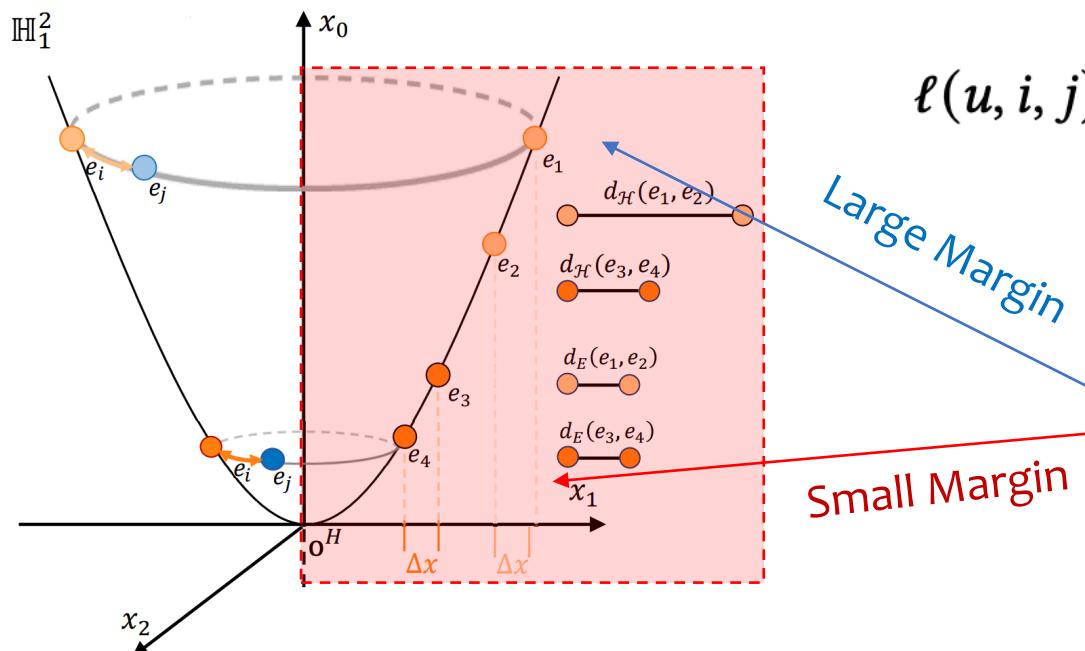


Figure 6: Distribution of the hyperbolic distance to the origin (HDO) embedded into the Poincaré ball on AIRPORT dataset

Geometry-Aware Learning

Hyperbolic-Aware Margin Learning (HAML)



$$\ell(u, i, j) = \max(\underbrace{d_{\mathcal{H}}^2(\mathbf{e}_u, \mathbf{e}_i) - d_{\mathcal{H}}^2(\mathbf{e}_u, \mathbf{e}_j)}_{\text{Pull}} + m, 0),$$

Push

$$m_{ui}^{\mathcal{H}} = \text{sigmoid}(\delta),$$
$$\delta = \frac{d_{\mathcal{H}}^2(\mathbf{e}_u, \mathbf{o}) + d_{\mathcal{H}}^2(\mathbf{e}_i, \mathbf{o}) - d_{\mathcal{H}}^2(\mathbf{e}_u, \mathbf{e}_i)}{\mathbf{e}_{u,0}\mathbf{e}_{i,0}},$$

4.4 Trustworthy and Scalability

- Trustworthy

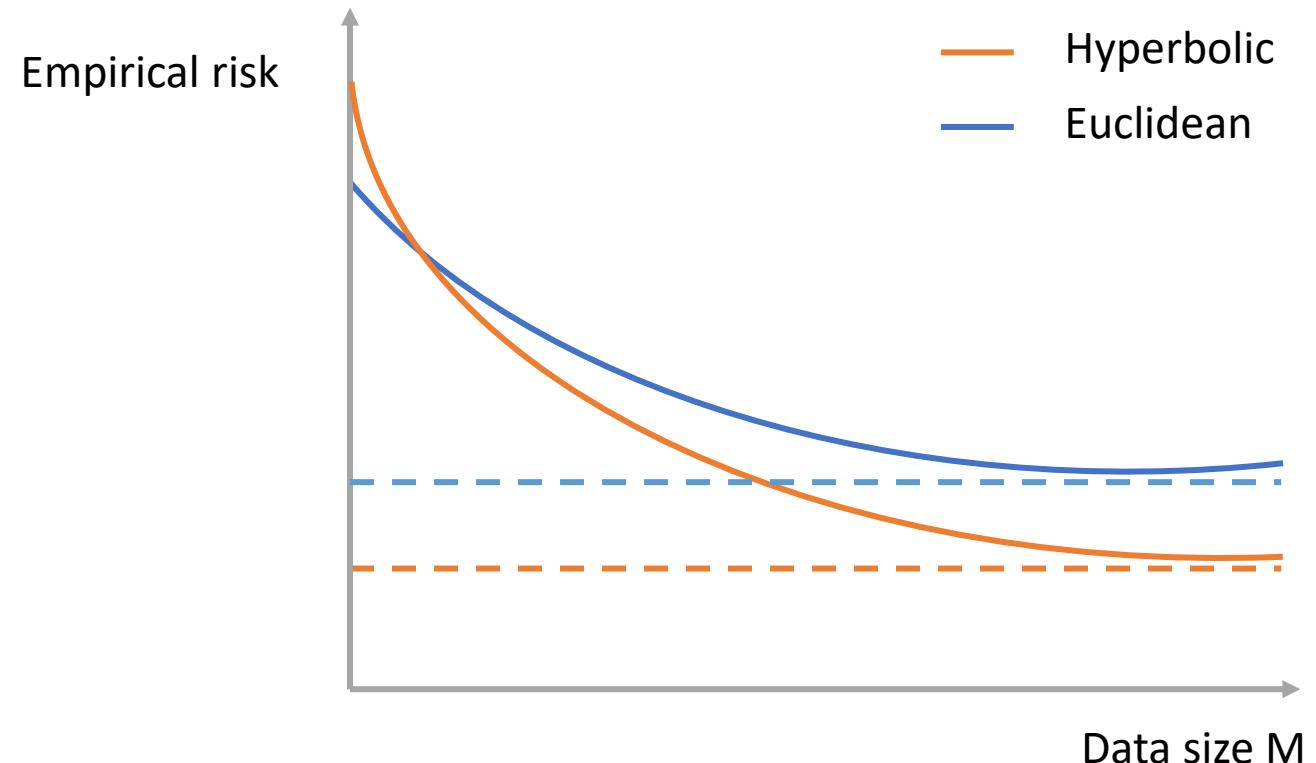
- Where are we in embedding spaces? A Comprehensive Analysis on Network Embedding Approaches for Recommender Systems. KDD 2021
- Generalization Error Bounds for Graph Embedding Using Negative Sampling: Linear vs Hyperbolic. NeurIPS 2021
- ...

- Scalability

- Fully connected hyperbolic neural network. ACL2022
- Towards Scalable Hyperbolic Neural Networks using Taylor Series Approximations. arXiv 2022
- Laplacian Features for Learning with Hyperbolic Space. arXiv 2022
- ...

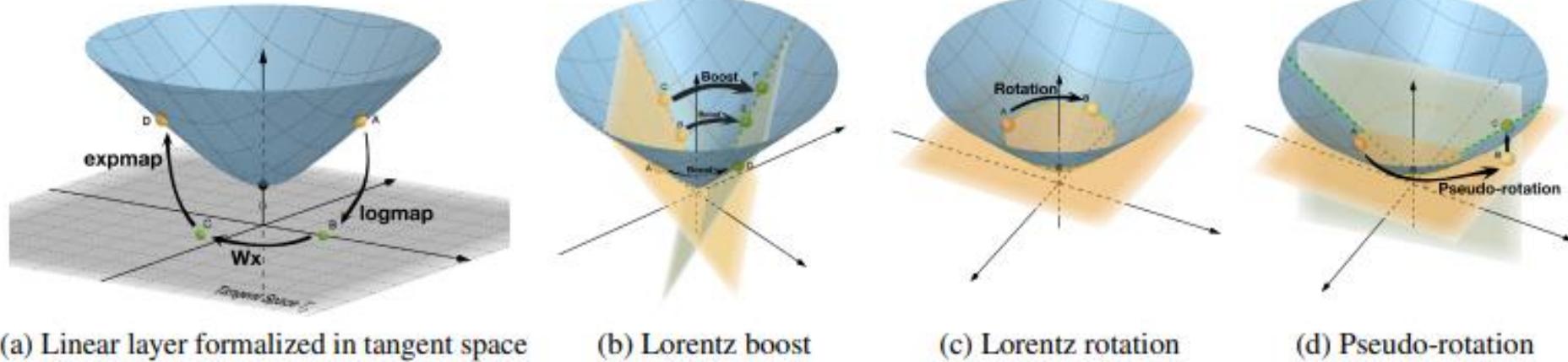
Generalization Error Bounds

- Error is polynomial and exponential with respect to the embedding space's radius in linear and hyperbolic spaces
- An **imbalanced** distribution causes **large** generalization error
- Hyperbolic models give smaller empirical risk to tree-like dataset
- Hyperbolic space shows **advantage** for the case with **large** data size



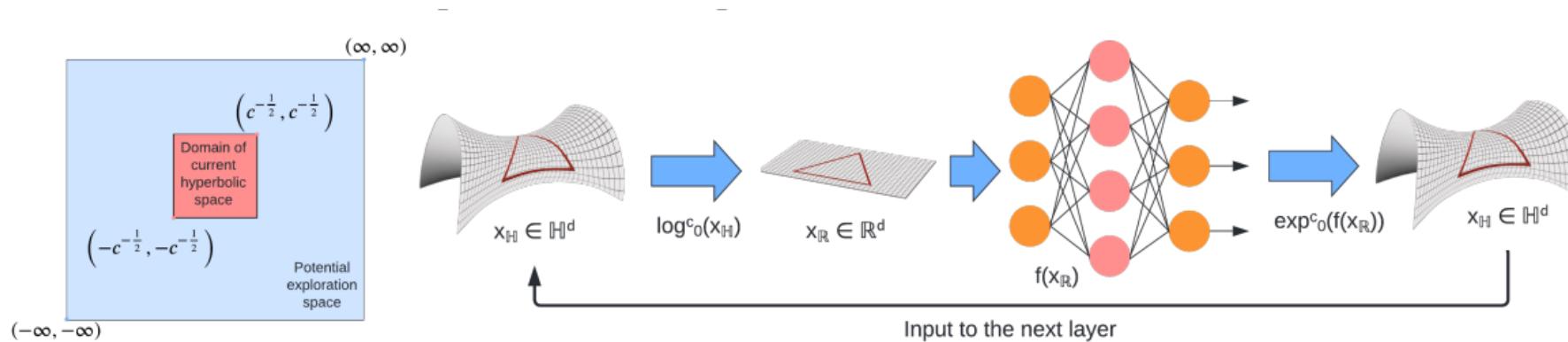
HGNN Accelerating

- A fully hyperbolic framework to build hyperbolic networks based on the Lorentz model
 - Adapting the Lorentz transformations to formalize essential operations of neural network



HGNN Accelerating

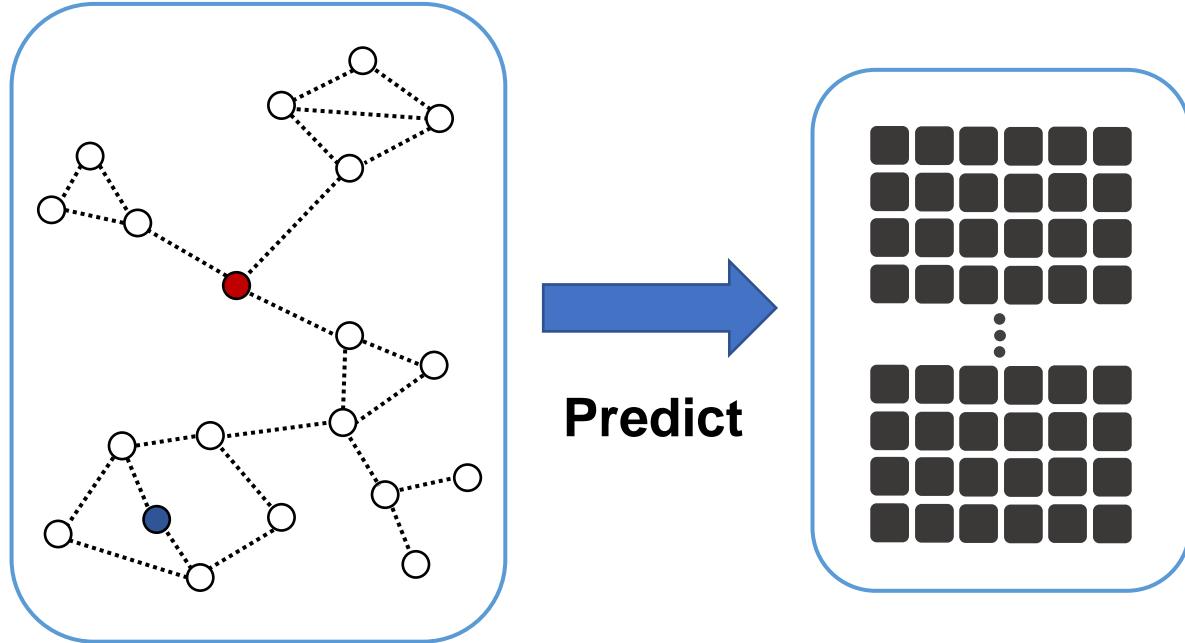
- Propose the approximation of hyperbolic operators using Taylor series expansions



- (a) Restricted \mathbb{H}_c in the exploration space of \mathbb{R} .
(b) Information loss due to frequent \log_0^c and \exp_0^c mapping to operate in the Euclidean space and represent in the hyperbolic space, respectively.

Scalable GNN

How to scaling up GNNs
to large graphs?



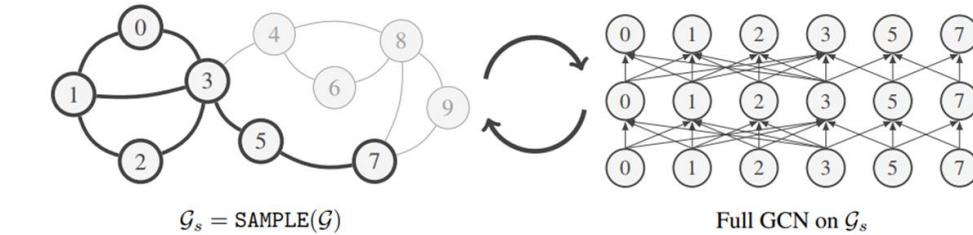
- Sampling-based Methods
- Decoupling-based Methods



High GPU costs and performance reduction

Scalable GNN

- Sampling-based Methods
 - Node-wise Sampling
GraphSAGE
 - Layer-wise Sampling
FastGCN, LADIES
 - Subgraph Sampling
Cluster-GCN, Graphsaint
- Decoupling-based Methods
SGC, SIGN, SAGN



Reduce the size of
the graph on GPU

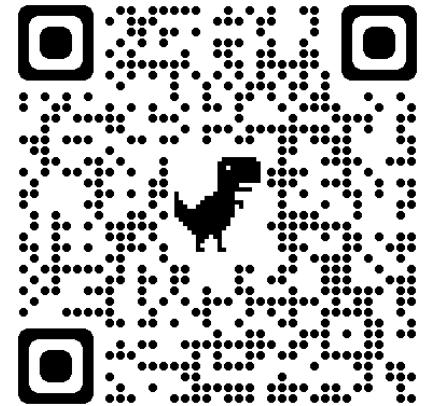
Scalable HGNN?

Summary

- HGRL is a still nascent but promising
 - Compatible, Light, and Fast
- Challenges & Opportunities
 - Domain Applications
 - Complex Structure
 - Evolving Interactions
 - Geometry-aware Learning
 - Trustworthy
 - Scalability
 - ...

Resource

- Survey
 - Hyperbolic Graph Neural Networks: A Review of Methods and Application
 - Hyperbolic Deep Neural Networks: A Survey
- Tools
 - Geoopt: <https://github.com/geoopt/geoopt>
 - PyG: https://github.com/pyg-team/pytorch_geometric
 - <https://github.com/alibaba/Curvature-Learning-Framework>
- Related Tutorial
 - https://www.youtube.com/watch?v=MdPk3qD4Wig&ab_channel=HazyResearch
 - <https://narendra.me/hyperbolic-networks-tutorial/www-2022/>



Acknowledgement



Thanks !