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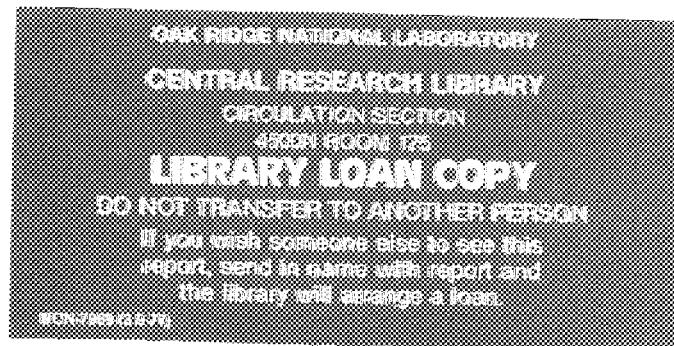
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An Introduction to Chordal Graphs and Clique Trees

Jean R. S. Blair
Barry W. Peyton



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Engineering Physics and Mathematics Division

**AN INTRODUCTION TO CHORDAL GRAPHS
AND CLIQUE TREES**

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AN INTRODUCTION TO CHORDAL GRAPHS AND CLIQUE TREES

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Abstract

Clique trees and chordal graphs have carved out a niche for themselves in recent work on sparse matrix algorithms, due primarily to research questions associated with advanced computer architectures. This paper is a unified and elementary introduction to the standard characterizations of chordal graphs and clique trees. The pace is leisurely, as detailed proofs of all results are included. We also briefly discuss applications of chordal graphs and clique trees in sparse matrix computations.

1. Introduction

It is well known that *chordal graphs* model the sparsity structure of the Cholesky factor of a sparse positive definite matrix [39]. Of the many ways to represent a chordal graph, a particularly useful and compact representation is provided by *clique trees* [24,45].¹ Until recently, *explicit* use of the properties of chordal graphs or clique trees in sparse matrix computations was rarely needed. For example, chordal graphs are mentioned in a single exercise in George and Liu [16]. However, chordal graphs and clique trees have found a niche in more recent work in this area, primarily due to various research questions associated with advanced computer architectures. For instance, the multifrontal method [8], which was developed to obtain good performance on vector supercomputers, can be expressed very succinctly in terms of a clique tree representation of the underlying chordal graph [34,37].

This paper is intended as an update to the graph theoretical results presented and proved in Rose [39], which predated the introduction of clique trees. Our goal is to provide a unified introduction to chordal graphs and clique trees for those interested in sparse matrix computations, though we hope it will be of use to those in other application areas in which these graphs play a major role. We have striven to write a primer, not a survey article: we present a limited number of well known results of fundamental importance, and prove all the results in the paper. The pacing is intended to be leisurely, and the organization is intended to enable the reader to read selected topics of interest in detail.

The paper is organized as follows. Section 2 contains the standard well known characterizations of chordal graphs and presents the maximum cardinality search algorithm for computing a *perfect elimination ordering*. Section 3 presents several characterizations of the clique trees of a chordal graph, including a *maximum spanning tree* property that is probably not as widely known as the others are. Section 4 ties together certain concepts and results from the previous two sections: it identifies the *minimal vertex separators* in a chordal graph with edges in any one of its clique trees, and it also shows that the maximum cardinality search algorithm is just Prim's algorithm in disguise. Finally, Section 5 briefly discusses recent applications of chordal graphs and clique trees to specific questions arising in sparse matrix computations.

2. Chordal graphs

An undirected graph is *chordal* (*triangulated*, *rigid circuit*) if every cycle of length greater than three has a *chord*: namely, an edge connecting two nonconsecutive vertices on the cycle. After introducing graph notation and terminology in Section 2.1, we present two standard characterizations of chordal graphs in Sections 2.2 and 2.3.

¹All technical terms used in this section are defined later in the paper.

The latter of these two sections shows that chordal graphs are characterized by possession of a *perfect elimination ordering* of the vertices. The *maximum cardinality search* algorithm is a linear-time procedure for generating a perfect elimination ordering. Section 2.4 describes this algorithm and proves it correct. The necessary definitions and references for each of these results are given in the appropriate subsection.

2.1. Graph terminology

We assume familiarity with elementary concepts and definitions from graph theory, such as tree, edge, undirected graph, connected component, etc. Golumbic [20] provides a good review of this material. Here we introduce some of the graph notation and terminology that will be used throughout the paper. Other concepts from graph theory will be introduced as needed in later sections of the paper.

We let $G = (V, E)$ denote an *undirected graph* with *vertex set* V and *edge set* E . The number of vertices is denoted by $n = |V|$ and the number of edges by $e = |E|$. For any vertex set $S \subseteq V$, consider the edge set $E(S) \subseteq E$ given by

$$E(S) := \{(u, v) \in E \mid u, v \in S\}.$$

We let $G(S)$ denote the *subgraph of G induced by S* , namely the subgraph $(S, E(S))$. At times it will be convenient to consider the induced subgraph of G obtained by removing a set of vertices $S \subseteq V$ from the graph; hence we define $G \setminus S$ by

$$G \setminus S := G(V - S).$$

Two vertices $u, v \in V$ are said to be *adjacent* if $(u, v) \in E$. Also, the edge $(u, v) \in E$ is said to be *incident with* both vertices u and v . The set of vertices adjacent to v in G is denoted by $\text{adj}_G(v)$. Similarly, the set of vertices adjacent to $S \subseteq V$ in G is given by

$$\text{adj}_G(S) := \{v \in V \mid v \notin S \text{ and } (u, v) \in E \text{ for some vertex } u \in S\}.$$

(The subscript G often will be suppressed when the graph is known by context.) An induced subgraph $G(S)$ is *complete* if the vertices in S are pairwise adjacent in G . In this case we also say that S is *complete in G* .

We let $[v_0, v_1, \dots, v_k]$ denote a *simple path* of length k from v_0 to v_k in G , i.e., $v_i \neq v_j$ for $i \neq j$ and $(v_i, v_{i+1}) \in E$ for $0 \leq i \leq k - 1$. Similarly, $[v_0, v_1, \dots, v_k, v_0]$ denotes a *simple cycle* of length $k + 1$ in G . Finally, a *chord* of a path (cycle) is any edge joining two nonconsecutive vertices of the path (cycle).

Definition 1. An undirected graph $G = (V, E)$ is *chordal* (*triangulated*, *rigid circuit*) if every cycle of length greater than three has a chord.

Clearly, any induced subgraph of a chordal graph is also chordal, a fact that is

useful in several of the proofs that follow.

2.2. Minimal vertex separators

A subset $S \subset V$ is a *separator* of G if two vertices in the same connected component of G are in two distinct connected components of $G \setminus S$. If a and b are two vertices separated by S then S is said to be an *ab-separator*. The set S is a *minimal separator* of G if S is a separator and no proper subset of S separates the graph; likewise S is a *minimal ab-separator* if S is an *ab-separator* and no proper subset of S separates a and b into distinct connected components. When the pair of vertices remains unspecified, we refer to S as a *minimal vertex separator*. It does not necessarily follow that a minimal vertex separator is also a minimal separator of the graph. For instance, in Figure 2.1 the set $S = \{b, e\}$ is a minimal *dc*-separator; nevertheless, S is not a minimal separator of G since $\{e\} \subset S$ is also a separator of G . Minimal vertex separators are used to

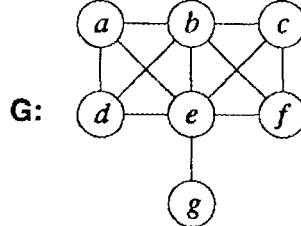


Figure 2.1: Minimal *dc*-separator $\{b, e\}$ is not a minimal separator of G .

characterize chordal graphs in Theorem 2.1, which is due to Dirac [6]. The proof is taken from Peyton [34], which, in turn, closely follows the proof given by Golumbic [20].

Theorem 2.1 (Dirac [6]). *A graph G is chordal if and only if every minimal vertex separator of G is complete in G .*

Proof: Assume every minimal vertex separator of G is complete in G , and let $\mu = [v_0, \dots, v_k, v_0]$ be any cycle of length greater than three in G (i.e., $k \geq 3$). If $(v_0, v_2) \in E$, then μ has a chord. If not, then there exists a v_0v_2 -separator S (e.g., $S = V - \{v_0, v_2\}$); furthermore, any such separator must contain v_1 and v_i for some i , $3 \leq i \leq k$. Choose S to be a minimal v_0v_2 -separator so that S , by assumption, is complete in G . It follows that (v_1, v_i) is a chord of μ , which proves the “if” part of the result.

Now assume G is chordal and let S be a minimal *ab*-separator of G . Let $G(A)$ and $G(B)$ be the connected components of $G \setminus S$ containing a and b , respectively. It suffices to show that for any two distinct vertices in S , say x and y , we have $(x, y) \in E$. Since S is minimal, each vertex $v \in S$ is adjacent to some vertex in A and some vertex in B ; otherwise, $S - \{v\}$ would be an *ab*-separator contrary to the minimality of S . Thus, there exist paths $\mu = [x, a_1, \dots, a_r, y]$ and $\nu = [y, b_1, \dots, b_t, x]$ where each $a_i \in A$ and each $b_i \in B$ (see Figure 2.2). Further, choose μ and ν so that they are

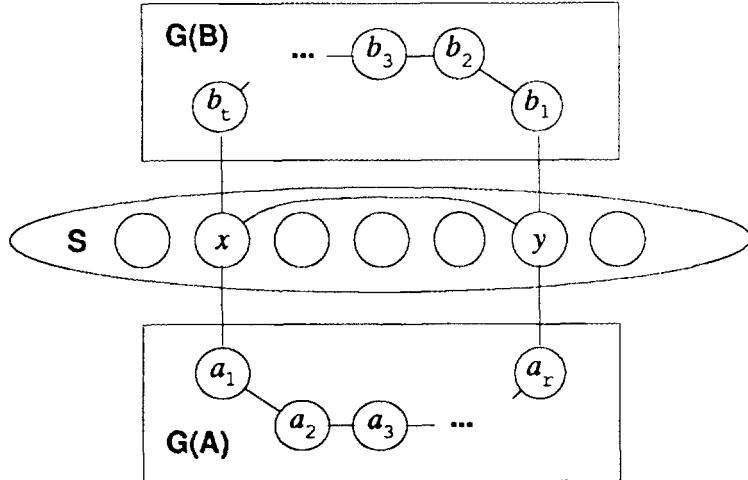


Figure 2.2: Cycle in proof of Theorem 2.1 that induces chord (x, y) .

of the smallest possible length greater than one, and combine them to form the cycle $\sigma = [x, a_1, \dots, a_r, y, b_1, \dots, b_t, x]$. Since G is chordal and σ is a cycle of length greater than three, σ must have a chord. Any chord of σ incident with a_i , $1 \leq i \leq r$, would either join a_i to another vertex in μ contrary to the minimality of r , or would join a_i to a vertex in B , which is impossible because S separates A from B in G . Consequently, no chord of σ is incident with a vertex a_i , $1 \leq i \leq r$, and by the same argument no chord of the cycle is incident with a vertex b_j , $1 \leq j \leq t$. It follows that the only possible chord is (x, y) . ■

Remark In reality, $r = t = 1$, otherwise $[x, a_1, \dots, a_r, y, x]$ or $[y, b_1, \dots, b_t, x, y]$ is a chordless cycle of length greater than three.

2.3. Perfect elimination orderings

We need the following terminology before we can state and prove the main result in this section. An *ordering* α of G is a bijection $\alpha : V \rightarrow \{1, 2, \dots, n\}$. Often it will be convenient to denote an ordering by using it to index the vertex set, so that $\alpha(v_i) = i$ for $1 \leq i \leq n$ where i will be referred to as the *label* of v_i . Let v_1, v_2, \dots, v_n be an ordering of V . For $1 \leq i \leq n$, we define \mathcal{L}_i to be the set of vertices with labels greater than $i - 1$:

$$\mathcal{L}_i := \{v_i, v_{i+1}, \dots, v_n\}.$$

The *monotone adjacency set* of v_i , denoted $madj_G(v_i)$, is given by

$$madj_G(v_i) := \{v_j \in adj(v_i) \mid j > i\} = adj_G(v_i) \cap \mathcal{L}_{i+1}.$$

Again, the subscript G often will be suppressed where the graph is known by context.

A vertex v is *simplicial* if $\text{adj}(v)$ induces a complete subgraph of G . The ordering α is a *perfect elimination ordering* (PEO) if for $1 \leq i \leq n$, the vertex v_i is simplicial in the graph $G(\mathcal{L}_i)$. As shown below in Lemma 1, every nontrivial chordal graph has a simplicial vertex (actually, at least two). Theorem 2.2, which states that chordal graphs are characterized by the possession of a PEO, follows easily from Lemma 1. The proofs are again taken from Peyton [34], which, in turn, closely follow arguments found in Golumbic [20].

Lemma 1 (Dirac [6]). *Every chordal graph G has a simplicial vertex. If G is not complete, then it has two nonadjacent simplicial vertices.*

Proof: The lemma is trivial if G is complete. For the case where G is not complete we proceed by induction on the number of vertices n . Let G be a chordal graph with $n \geq 2$ vertices, including two nonadjacent vertices a and b . If $n = 2$, both vertices of the graph are simplicial since both are isolated (i.e., $\text{adj}(a) = \text{adj}(b) = \emptyset$). Suppose $n > 2$ and assume that the lemma holds for all such graphs with fewer than n vertices. Since a and b are nonadjacent, there exists an ab -separator (e.g., the set $V - \{a, b\}$). Suppose S is a minimal ab -separator of G , and let $G(A)$ and $G(B)$ be the connected components of $G \setminus S$ containing a and b , respectively. The induced subgraph $G(A \cup S)$ is a chordal graph having fewer vertices than G ; hence, by the induction hypothesis one of the following must hold: Either $G(A \cup S)$ is complete and every vertex of A is a simplicial vertex of $G(A \cup S)$, or $G(A \cup S)$ has two nonadjacent simplicial vertices, one of which must be in A since, by Theorem 2.1, S is complete in G . Because $\text{adj}_G(A) \subseteq A \cup S$, every simplicial vertex of $G(A \cup S)$ in A is also a simplicial vertex of G . By the same argument, B also contains a simplicial vertex of G , thereby completing the proof. ■

Theorem 2.2 (Fulkerson and Gross [10]). *A graph G is chordal if and only if G has a perfect elimination ordering.*

Proof: Suppose G is chordal. We proceed by induction on the number of vertices n to show the existence of a PEO of G . The case $n = 1$ is trivial. Suppose $n > 1$ and every chordal graph with fewer vertices has a PEO. By Lemma 1, G has a simplicial vertex, say v . Now $G \setminus \{v\}$ is a chordal graph with fewer vertices than G ; hence, by induction it has a PEO, say β . If α orders the vertex v first, followed by the remaining vertices of G in the order determined by β , then α is a PEO of G .

Conversely, suppose G has a PEO, say α , given by v_1, v_2, \dots, v_n . We seek a chord of an arbitrary cycle μ in G of length greater than three. Let v_i be the vertex on μ whose label i is smaller than that of any other vertex on μ . Since α is a PEO, $\text{madj}(v_i)$ is complete; whence μ has at least one chord: namely, the edge joining the two neighboring vertices of v_i in μ . ■

2.4. Maximum cardinality search

Rose, Tarjan, and Lueker [40] introduced the first linear-time algorithm for producing a PEO, known as the *lexicographic breadth first search* algorithm. In a set of unpublished lecture notes, Tarjan [43] introduced a simpler algorithm known as the *maximum cardinality search* (MCS) algorithm. Tarjan and Yannakakis [45] later described MCS algorithms for both chordal graphs and acyclic hypergraphs. The MCS algorithm for chordal graphs orders the vertices in reverse order beginning with an arbitrary vertex $v \in V$ for which it sets $\alpha(v) = n$. At each step the algorithm selects as the next vertex to label an unlabeled vertex adjacent to the largest number of labeled vertices, with ties broken arbitrarily. A high-level description of the algorithm is given in Figure 2.3. We refer the reader to Tarjan and Yannakakis [45] for details on how to implement the algorithm to run in $O(n + e)$ time.

```

 $\mathcal{L}_{n+1} \leftarrow \emptyset;$ 
for  $i \leftarrow n$  to 1 step  $-1$  do
    Choose a vertex  $v \in V - \mathcal{L}_{i+1}$  for which
         $|\text{adj}(v) \cap \mathcal{L}_{i+1}|$  is maximum;
     $\alpha(v) \leftarrow i$ ; [ $v$  becomes  $v_i$ ]
     $\mathcal{L}_i \leftarrow \mathcal{L}_{i+1} \cup \{v_i\}$ ;
end for

```

Figure 2.3: Maximum cardinality search (MCS).

The following lemma and theorem prove that the MCS algorithm produces a PEO. The lemma provides a useful characterization of the orderings of a chordal graph that are *not* perfect elimination orderings. Edelman, Jamison, and Shier [9,42] prove similar results while studying the notion of convexity in chordal graphs. Theorem 2.3 is then proved by showing that every ordering that is *not* a PEO is also *not* an MCS ordering. The proof is taken from Peyton [34]. Later in Section 4.2, we will provide a more intuitive view of how the MCS algorithm works: it can be viewed as a special implementation of Prim's algorithm applied to the *weighted clique intersection graph of G* (defined in Section 3.4).

Lemma 2. *An ordering α of the vertices in a graph G is not a perfect elimination ordering if and only if for some vertex v , there exists a chordless path of length greater than one from $v = \alpha^{-1}(i)$ to some vertex in \mathcal{L}_{i+1} through vertices in $V - \mathcal{L}_i$.*

Proof: Suppose α is *not* a PEO. There exists then by Lemma 1 a vertex $u \in V$ for which $\text{madj}(u)$ is not complete in G ; hence, there exist two vertices $v, w \in \text{madj}(u)$ joined by no edge in E . Without loss of generality assume that $i = \alpha(v) < \alpha(w)$.

Then $[v, u, w]$ is a chordless path of length two from $v = \alpha^{-1}(i)$ to $w \in \mathcal{L}_{i+1}$ through $u \in V - \mathcal{L}_i$.

Conversely, suppose there exists a chordless path $\mu = [u_0, u_1, \dots, u_r]$ of length $r \geq 2$ from $u_0 = \alpha^{-1}(i)$ to $u_r \in \mathcal{L}_{i+1}$ through vertices $u_j \in V - \mathcal{L}_i$, $1 \leq j \leq r-1$. Let u_k , where $1 \leq k \leq r-1$, be the internal vertex in μ whose label $\alpha(u_k)$ is smaller than that of any other internal vertex in μ . Then $madj(u_k)$ includes two nonadjacent vertices: namely, the two neighboring vertices of u_k in μ . It follows that α is not a PEO. ■

Theorem 2.3 (Tarjan [43], Tarjan and Yannakakis [45]). *Every maximum cardinality search ordering of a chordal graph G is a perfect elimination ordering.*

Proof: Let α be any ordering of a chordal graph G that is *not* a PEO. We will show that the ordering α *cannot* be generated by the MCS algorithm.

By Lemma 2, for some vertex u_0 there exists a chordless path $\mu = [u_0, u_1, \dots, u_{r-1}, u_r]$ of length $r \geq 2$ from $u_0 = \alpha^{-1}(i)$ to $u_r \in \mathcal{L}_{i+1}$ through vertices $u_j \in V - \mathcal{L}_i$, $1 \leq j \leq r-1$. (See Figure 2.4.) Choose u_0 so that the label $i = \alpha(u_0)$ is maximum among all the vertices of G for which such a chordless path exists.

To show that α is not an MCS ordering it suffices to show that there exists some vertex $w \in V - \mathcal{L}_{i+1}$ for which $|adj(w) \cap \mathcal{L}_{i+1}|$ exceeds $|adj(u_0) \cap \mathcal{L}_{i+1}|$. We will show that the vertex $u_{r-1} \in \mu$ is indeed such a vertex. Note that $adj(u_0) \cap \mathcal{L}_{i+1}$ and $madj(u_0)$ are by definition identical, and thus it suffices to show that

$$madj(u_0) \subset adj(u_{r-1}) \cap \mathcal{L}_{i+1}. \quad (2.1)$$

For the trivial case $madj(u_0) = \emptyset$, the theorem holds since u_{r-1} is adjacent to $u_r \in \mathcal{L}_{i+1}$. Assume instead that $madj(u_0) \neq \emptyset$, and choose a vertex $x \in madj(u_0)$. To see that x is also adjacent to u_{r-1} , consider the path $\gamma = [x, u_0, \dots, u_{r-1}, u_r]$ pictured in Figure 2.4. The maximality of i implies that every path of length greater than one having the following two properties will have a chord: a) the endpoints of the path are both numbered greater than i , and b) the interior vertices are numbered less than the minimum of the endpoints. The path γ satisfies these two properties and hence has a chord. Moreover, since $\mu = [u_0, u_1, \dots, u_r]$ has no chords, every chord of γ is incident with x . Let u_k be the vertex in γ adjacent to x which has the largest subscript. If $k \neq r$ then $[x, u_k, \dots, u_r]$ is a chordless path, again contrary to the maximality of i ; hence $(x, u_r) \in E$.

It follows that $\sigma = [x, u_0, \dots, u_{r-1}, u_r, x]$ is a cycle of length greater than three in G (recall that $r \geq 2$). Since G is chordal, σ must have a chord, and, as argued above, any such chord must be incident with x . Let u_t be the vertex in σ with the highest subscript other than r , for which $(x, u_t) \in E$. If $t \neq r-1$, then $[x, u_t, \dots, u_r, x]$ is a chordless cycle of length greater than 3, contrary to the chordality of G . In consequence, $(x, u_{r-1}) \in E$ for all $x \in madj(u_0)$. But u_{r-1} is also adjacent to $u_r \in \mathcal{L}_{i+1} - madj(u_0)$, whence (2.1) holds, completing the proof. ■

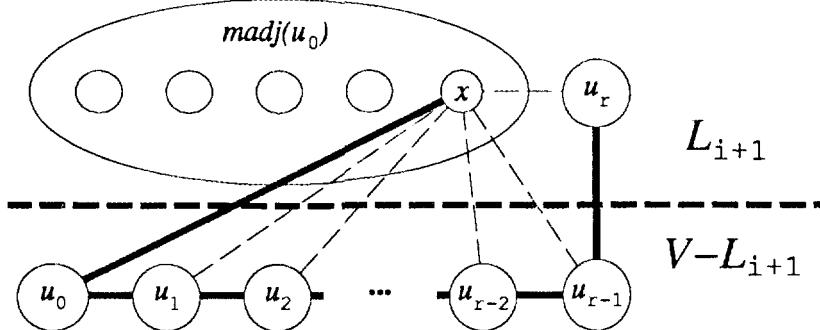


Figure 2.4: Illustration for the proof of Theorem 2.3. The dark solid edges exist by hypothesis; existence of the lighter broken edges is argued in the proof and the remark that follows it.

Remark In the preceding proof the argument leading to the inclusion of (x, u_{r-1}) in E can be repeated for every edge (x, u_j) , $1 \leq j \leq r - 2$. In consequence we have

$$madj(u_0) \subseteq adj(u_j) \cap \mathcal{L}_{i+1} \text{ for } 1 \leq j \leq r - 2. \quad (2.2)$$

Statement (2.1) implies that if the MCS algorithm “tried” to generate α , then as the vertex to be labeled with i is chosen, the priority of u_{r-1} would be greater than that of u_0 . Similarly, (2.2) implies that the priority of each vertex u_j ($1 \leq j \leq r - 2$) would be at least as great as that of u_0 .

3. Characterizations of clique trees

Let $G = (V, E)$ be any graph. A *clique* of G is any *maximal* set of vertices that is complete in G , and thus a clique is properly contained in no other clique. We will refer to a “submaximal clique” as complete in G , as we did in the previous section. Henceforth $\mathcal{K}_G = \{K_1, K_2, \dots, K_m\}$ denotes the set containing the cliques of G , and m will be the number of cliques.

The reader may verify that the graph in Figure 3.1 is a chordal graph with four cliques, each of size three. The graph in Figure 3.1 will be used throughout this section to illustrate results and key points. For convenience we shall refer to the vertices of this graph as v_1, v_2, \dots, v_7 ; e.g., the vertex labeled “6” will be referred to as v_6 . Note that the labeling of the vertices is a PEO of the graph.

For any chordal graph G there exists a subset of the set of trees on \mathcal{K}_G known as *clique trees*. Any one of these clique trees can be used to represent the graph, often in a very compact and efficient manner [24,46], as we shall see in Section 4. This section contains a unified and elementary presentation of several key properties of clique trees, each of which has been shown, somewhere in the literature, to characterize the set of

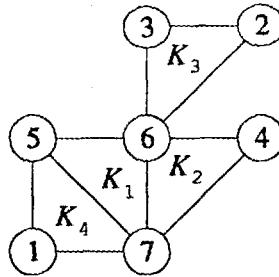


Figure 3.1: Chordal graph with seven vertices and four cliques.

clique trees associated with a chordal graph.

The notion of clique trees was introduced independently by Buneman [5], Gavril [12], and Walter [46]. The property we use to introduce and define clique trees in Section 3.1 is a simple variant of one of the key properties introduced in their work. We use this variant because, in our experience, it is more readily apprehended by those who are studying this material for the first time. Section 3.2 presents the short argument needed to show that the more recent variant is equivalent to the original.

Clique trees have found application in relational databases, where they can be viewed as a subclass of *acyclic hypergraphs*, which are heavily used in that area. Open problems in relational database theory motivated the pioneering work of Bernstein and Goodman [2], Beeri, Fagin, Maier, and Yannakakis [1], and Tarjan and Yannakakis [45]. Our two final characterizations of clique trees, presented in Sections 3.3 and 3.4, are based on results from these papers. Section 3.5 summarizes these results, and also illustrates these results in negative form using the example in Figure 3.1.

Throughout this section it will be convenient to assume that G is connected. All the results can nevertheless be applied to a disconnected graph by applying them successively to each connected component; thus no loss of generality is incurred by the restriction. Note also that Sections 3.2, 3.3, and 3.4 can be read independently of one another, but any of these three subsections should be read only after reading Section 3.1. As in the previous section, needed definitions and specific references to the literature are given in the appropriate subsections.

3.1. Definition using the clique-intersection property

Assume that G is a connected graph (not necessarily chordal), and consider its set of maximal cliques \mathcal{K}_G . In this section we consider the set of trees on \mathcal{K}_G that satisfy the following *clique-intersection* property:

For every pair of distinct cliques $K, K' \in \mathcal{K}_G$, the set $K \cap K'$ is contained in every clique on the path connecting K and K' in the tree.

As an example of a tree that satisfies the clique-intersection property, consider the tree shown in Figure 3.2, whose vertices are the cliques of the chordal graph in Figure 3.1. The reader may verify that this tree indeed satisfies the clique-intersection property:

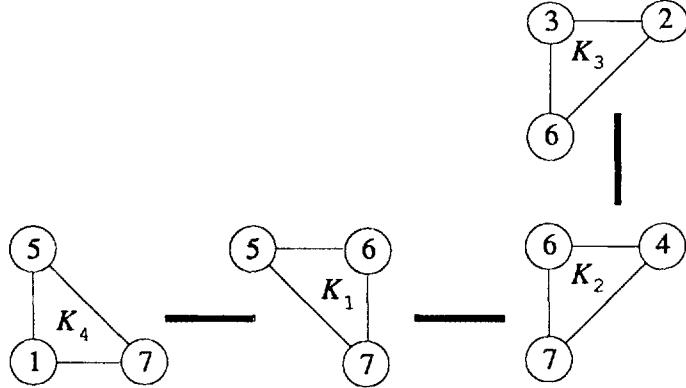


Figure 3.2: A tree on the cliques of the chordal graph in Figure 3.1, which satisfies the clique-intersection property.

for example, the set $K_4 \cap K_2 = \{v_7\}$ is contained in K_1 , which is the only clique on the path from K_4 to K_2 in the tree. The reader may also verify that the only other tree on $\{K_1, K_2, K_3, K_4\}$ that satisfies the clique-intersection property is obtained from the tree in Figure 3.2 by replacing the edge (K_3, K_2) with (K_3, K_1) .

We will show in Theorem 3.1 below that G is chordal if and only if there exists a tree on \mathcal{K}_G that satisfies the clique-intersection property. For any given chordal graph G , we shall let $\mathcal{T}_G^{\text{ct}}$ denote the nonempty set of trees $T = (\mathcal{K}_G, \mathcal{E}_T)$ that satisfy the clique intersection property, and we shall refer to any member of $\mathcal{T}_G^{\text{ct}}$ as a *clique tree* of the underlying chordal graph G . In Section 3.2, we prove the original version of this result, which was introduced independently by Buneman [5], Gavril [12], and Walter [46].

To prove the main result of this subsection, we require two more definitions and a simple lemma. A vertex K in a tree T is a *leaf* if it has precisely one neighbor in T (i.e., $|\text{adj}_T(K)| = 1$). We let $\mathcal{K}_G(v) \subseteq \mathcal{K}_G$ denote the set of cliques containing the vertex v . The following simple characterization of simplicial vertices has been useful in various applications. This result has been used widely in the literature [7,19,23,24,45], and has been formally stated and proven in at least two places [23,24].

Lemma 3. *A vertex is simplicial if and only if it belongs to precisely one clique.*

Proof: Suppose a vertex v belongs to two cliques $K, K' \in \mathcal{K}_G$. Maximality of the cliques implies the existence of two distinct nonadjacent vertices $u \in K - K'$ and $u' \in K' - K$. Since both u and u' are adjacent to v , it follows that v is not simplicial.

Assume now that the vertex v belongs to one and only one clique $K \in \mathcal{K}_G$. Note that v is adjacent to a vertex $u \neq v$ if and only if there exists a clique of G to which both u and v belong. Consequently $\text{adj}(v) = K - \{v\}$, whence v is simplicial. ■

The first part of the following proof closely resembles the argument given by Gavril [12] to prove a result that shall be presented in the next section. The second half was improvised for this paper, and resembles the first half in many of its features.

Theorem 3.1. *A connected graph G is chordal if and only if there exists a tree $T = (\mathcal{K}_G, \mathcal{E}_T)$ for which the clique-intersection property holds.*

Proof: We proceed by induction on the number of vertices n to show the “only if” part. The base step $n = 1$ is obvious. For the induction step, let G be a chordal graph with $n \geq 2$ vertices and assume the result is true for all chordal graphs having fewer than n vertices. By Lemma 1, G has a simplicial vertex, say v . Let K be the single clique of G that contains v (see Lemma 3), and consider the induced subgraph $G' = G \setminus \{v\}$. Since G' is a chordal graph with $n - 1$ vertices, by the induction hypothesis there exists a tree $T' = (\mathcal{K}_{G'}, \mathcal{E}_{T'})$ that satisfies the clique-intersection property.

To complete the proof of the “only if” part, there are two cases to consider. First, suppose $K' = K - \{v\}$ remains maximal in G' (i.e., $K' \in \mathcal{K}_{G'}$). It is trivial to show that $\mathcal{K}_{G'} = \mathcal{K}_G \cup \{K'\} - \{K\}$, and we leave it for the reader to verify this. It follows that the only difference between the cliques of G and G' is the presence in G of the simplicial vertex v in K and the absence of v from the corresponding clique K' of G' . In consequence, the intersection of any pair of cliques in G is identical to the intersection of the corresponding pair in G' . Let T be the tree on \mathcal{K}_G obtained from T' by replacing K' with K . Since T' has the clique-intersection property, it follows that T has this property as well, thereby completing the argument for the first case.

Now, suppose $S' = K - \{v\}$ is not a maximal clique in G' (i.e., $S' \notin \mathcal{K}_{G'}$). Since $n \geq 2$ and G is connected, v is not an isolated vertex, and we have

$$S' = K - \{v\} = adj(v) \neq \emptyset.$$

Since S' is complete in G' , there exists a clique $P \in \mathcal{K}_{G'} = \mathcal{K}_G - \{K\}$ for which $S' \subset P$. (As before, we leave it for the reader to verify that $\mathcal{K}_{G'} = \mathcal{K}_G - \{K\}$.) Let T be the tree on \mathcal{K}_G obtained by adding the clique K and the edge (K, P) to T' . We now verify that T satisfies the clique-intersection property. Because T' satisfies the clique-intersection property, the set $K_1 \cap K_2$ is contained in every clique on the path from K_1 to K_2 in T whenever neither K_1 nor K_2 is K . Consider now the set $K \cap K''$ where $K'' \in \mathcal{K}_G - \{K\} = \mathcal{K}_{G'}$. Since $K - \{v\} \subset P$ and v belongs to no clique in $\mathcal{K}_G - \{K\}$, it follows that $K'' \cap K \subset P$. Because T' satisfies the clique-intersection property, the set $K \cap K'' = P \cap K''$ is contained in every clique on the path from K to K'' in T , and T therefore satisfies the clique-intersection property as well.

To prove the “if” part, let $G = (V, E)$ be a graph and suppose there exists a tree $T = (\mathcal{K}_G, \mathcal{E}_T)$ that satisfies the clique-intersection property. Again we proceed by induction on n to show that G is chordal. The base step $n = 1$ is obvious. For the induction step, let G be a graph with $n \geq 2$ vertices and assume the result is true for all graphs having fewer than n vertices.

Let K and P be respectively a leaf of T and its sole neighbor (i.e., “parent”) in T . By maximality of the cliques there exists a vertex $v \in K - P$. The vertex v moreover cannot belong to any clique $K' \in \mathcal{K}_G - \{K, P\}$, for were it otherwise the clique P , which is on the path from K to K' in T , would not contain the set $K \cap K'$. Consequently v belongs to no other clique but K , whence by Lemma 3 it is a simplicial vertex of G .

Consider the reduced graph $G' = G \setminus \{v\}$ and let $K' = K - \{v\}$. If $K' \not\subset P$, then the “reduced” tree T' for G' is obtained simply by replacing K with K' in T ; if $K' \subset P$, then T' is obtained by removing from T the vertex K and the single edge (K, P) incident with it in T . As before, in the first case, $\mathcal{K}_{G'} = \mathcal{K}_G \cup \{K'\} - \{K\}$; in the second case, $\mathcal{K}_{G'} = \mathcal{K}_G - \{K\}$. In either case, it is trivial to verify that the tree T' satisfies the clique-intersection property. From the induction hypothesis it follows that G' is chordal. Let β be any PEO of G' . A PEO of G can then be obtained by ordering v first, followed by the remaining vertices of G in the order determined by β . Thus by Theorem 2.2, G is also chordal, giving us the result. ■

3.2. The induced-subtree property

In this section we are concerned with the set of all trees on \mathcal{K}_G that satisfy the *induced-subtree* property:

For every vertex $v \in V$, the set $\mathcal{K}_G(v)$ induces a subtree of T .

We shall let $\mathcal{T}_G^{\text{ist}}$ denote the set of all trees on \mathcal{K}_G that satisfy the induced-subtree property.

Consider again the clique tree in Figure 3.2. Observe that each of the sets $\mathcal{K}_G(v_3) = \{K_3\}$ and $\mathcal{K}_G(v_6) = \{K_1, K_2, K_3\}$ induces a subtree of this tree. The reader may verify that this tree satisfies the induced-subtree property. It is trivial to prove that the clique-intersection and induced-subtree properties are indeed equivalent.

Theorem 3.2. For any connected graph G , we have $\mathcal{T}_G^{\text{ist}} = \mathcal{T}_G^{\text{ct}}$.

Proof: To see that $\mathcal{T}_G^{\text{ct}} \subseteq \mathcal{T}_G^{\text{ist}}$, let $T_{\text{ct}} \in \mathcal{T}_G^{\text{ct}}$ and consider the set of cliques $\mathcal{K}_G(v)$ for some vertex $v \in V$. Choose two cliques $K, K' \in \mathcal{K}_G(v)$. Since the set $K \cap K'$ lies in every clique on the path joining K and K' in T_{ct} , it follows that the vertex $v \in K \cap K'$ also lies in each clique along this path. In consequence, the induced subgraph $T_{\text{ct}}(\mathcal{K}_G(v))$ is connected and hence a subtree of G . It follows that $T_{\text{ct}} \in \mathcal{T}_G^{\text{ist}}$, whence $\mathcal{T}_G^{\text{ct}} \subseteq \mathcal{T}_G^{\text{ist}}$, as desired.

To see that $\mathcal{T}_G^{\text{ist}} \subseteq \mathcal{T}_G^{\text{ct}}$, let $T_{\text{ist}} \in \mathcal{T}_G^{\text{ist}}$. Choose two cliques $K, K' \in \mathcal{K}_G$, and consider the set $K \cap K'$. For each vertex $v \in K \cap K'$, the set $\mathcal{K}_G(v)$ induces a subtree of T_{ist} (i.e., a connected subgraph of T_{ist}); and thus the vertex v lies in each clique along the path joining K and K' in T_{ist} . It follows that $T_{\text{ist}} \in \mathcal{T}_G^{\text{ct}}$, whence $\mathcal{T}_G^{\text{ist}} \subseteq \mathcal{T}_G^{\text{ct}}$, as desired. ■

We thus have the following well known result from the literature.

Theorem 3.3 (Buneman [5], Gavril [12], Walter [46]). *A connected graph G is chordal if and only if there exists a tree $T = (\mathcal{K}_G, \mathcal{E}_T)$ for which the induced-subtree property holds.*

Proof: The result follows immediately from Theorems 3.1 and 3.2. ■

3.3. The running intersection property

A total ordering of the cliques in \mathcal{K}_G , say K_1, K_2, \dots, K_m , has the *running intersection property* (RIP) if for each clique K_j , $2 \leq j \leq m$, there exists a clique K_i , $1 \leq i \leq j-1$, such that

$$K_j \cap (K_1 \cup K_2 \cup \dots \cup K_{j-1}) \subset K_i. \quad (3.1)$$

For any RIP ordering of the cliques, we construct a tree T_{rip} on \mathcal{K}_G by making each clique K_j adjacent to a “parent” clique K_i identified by (3.1). (Since more than one clique K_i , $1 \leq i \leq j-1$, may satisfy (3.1), the parent may not be uniquely determined.) We let $\mathcal{T}_G^{\text{rip}}$ be the set containing every tree on \mathcal{K}_G that can be constructed from an RIP ordering in this manner. We define a *reverse topological ordering* of any rooted tree as an ordering that numbers each parent *before* any of its children. Finally, note that any RIP ordering is a reverse topological ordering of a rooted tree constructed from the ordering in the manner specified above.

The ordering K_1, K_2, K_3, K_4 of the cliques shown in Figure 3.1 is an RIP ordering; a corresponding RIP-induced parent function is displayed in Figure 3.3. Note that the parent function specifies precisely the edges of the clique tree in Figure 3.2. Indeed, we can show that for any connected graph G , we have $\mathcal{T}_G^{\text{rip}} = \mathcal{T}_G^{\text{ct}}$.

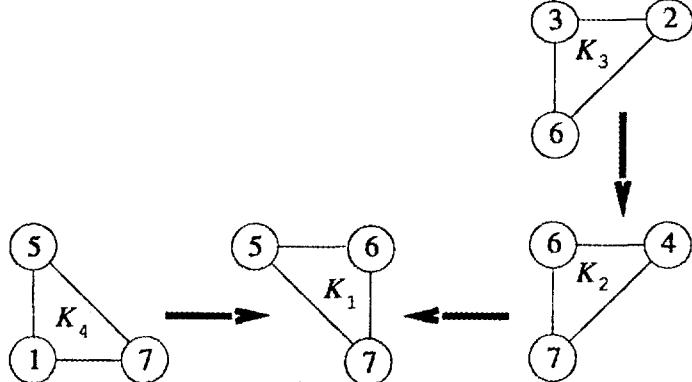


Figure 3.3: Clique tree in Figure 3.2 is an RIP tree. Arrows point from child to parent.

Theorem 3.4 (Beeri, Fagin, Maier, Yannakakis [1]). *For any connected graph G , we have $\mathcal{T}_G^{\text{rip}} = \mathcal{T}_G^{\text{ct}}$.*

Proof: We first show that $\mathcal{T}_G^{\text{ct}} \subseteq \mathcal{T}_G^{\text{rip}}$. Let $T_{\text{ct}} \in \mathcal{T}_G^{\text{ct}}$; choose $R \in \mathcal{K}_G$; and root T_{ct} at R . Consider any reverse topological ordering $R = K_1, K_2, \dots, K_m$ of the rooted tree T_{ct} . For any clique K_j , $2 \leq j \leq m$, let K_p be its parent clique in the rooted tree (whence $1 \leq p \leq j-1$). Now, for $1 \leq i \leq j-1$, the clique K_i cannot be a descendant of K_j , hence K_p is on the path in T_{ct} connecting K_j and K_i . The clique-intersection property implies that $K_j \cap K_i \subseteq K_p$. This implies that $K_j \cap (K_1 \cup K_2 \cup \dots \cup K_{j-1}) \subseteq K_p$; furthermore, K_p cannot be a subset of K_j by maximality, so the containment is proper. Thus, $T_{\text{ct}} \in \mathcal{T}_G^{\text{rip}}$, and we have $\mathcal{T}_G^{\text{ct}} \subseteq \mathcal{T}_G^{\text{rip}}$.

To see that $\mathcal{T}_G^{\text{rip}} \subseteq \mathcal{T}_G^{\text{ct}}$, consider a tree $T = (\mathcal{K}_G, \mathcal{E}) \notin \mathcal{T}_G^{\text{ct}}$. We will show that $T \notin \mathcal{T}_G^{\text{rip}}$. Since $T \notin \mathcal{T}_G^{\text{ct}}$, there exists then a pair of distinct cliques $K, K' \in \mathcal{K}_G$ such that the set $K \cap K'$ is not contained in at least one clique on the path connecting K and K' in the tree. Choose two such cliques $K, K' \in \mathcal{K}_G$ that minimize the length of the path from K to K' in T . The key observation on which our argument depends is that the set $K \cap K'$ belongs to *no* clique on the path connecting K and K' in the tree, except K and K' . Let K_1, K_2, \dots, K_m be any reverse topological ordering of T for arbitrary root $K_1 \in \mathcal{K}_G$. It suffices to show that (3.1) does not hold for some parent-child pair in T .

Consider the path $\mu = [K = K_{i_0}, K_{i_1}, \dots, K_{i_s} = K']$ in T . Let K_{i_t} be the clique with *lowest* index among the cliques in μ , and without loss of generality assume that $i_0 > i_s$. Since under the given reverse topological ordering K_{i_0} is a proper descendant of $K_{i_t} \in \mu$, the clique K_{i_1} is necessarily the parent of K_{i_0} in the rooted tree, and hence $i_0 > i_1$. Our choice of K ($= K_{i_0}$) and K' ($= K_{i_s}$) implies that (a) $s \geq 2$, and (b) $K_{i_0} \cap K_{i_r} \not\subseteq K_{i_r}$ for each r , $1 \leq r \leq s-1$. In consequence, we have $K_{i_0} \cap K_{i_s} \not\subseteq K_{i_1}$, whence (3.1) does not hold for the parent-child pair K_{i_1} and K_{i_0} , which completes the proof. ■

Remark In the preceding proof, the argument that $\mathcal{T}_G^{\text{ct}} \subseteq \mathcal{T}_G^{\text{rip}}$ verifies that any reverse topological ordering of a clique tree $T_{\text{ct}} \in \mathcal{T}_G^{\text{ct}}$ is an RIP ordering of the cliques.

3.4. The maximum-weight spanning tree property

Associated with each chordal graph G is a *weighted clique intersection graph*, W_G , defined as follows. The vertex set of W_G is the set of cliques \mathcal{K}_G . Two distinct cliques $K, K' \in \mathcal{K}_G$ are connected by an edge if and only if their intersection is nonempty; moreover, each such edge (K, K') is assigned a positive weight given by $|K \cap K'|$. We let $\mathcal{T}_G^{\text{mst}}$ be the set containing every *maximum-weight spanning tree* (MST) of W_G .

Figure 3.4 shows W_G for the chordal graph in Figure 3.1, and highlights the edges of the clique tree in Figure 3.2. Observe that the highlighted clique tree is a maximum-weight spanning tree of W_G , with edge weights that sum to five. Bernstein and Goodman [2] first showed that for any chordal graph G , we have $\mathcal{T}_G^{\text{mst}} = \mathcal{T}_G^{\text{ct}}$. Our proof of this result is similar to that given by Gavril [13].

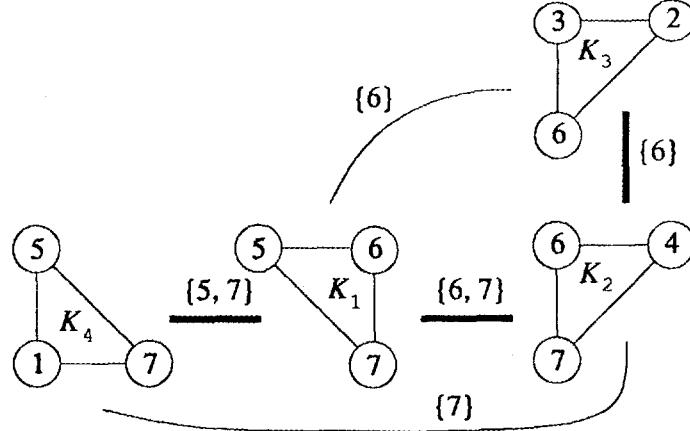


Figure 3.4: Weighted clique intersection graph for graph in Figure 3.1. Bold edges belong to the clique tree in Figure 3.2. Also shown are the intersection sets upon which the weights are based.

Our argument requires two ideas commonly used in the study of maximum-weight (minimum-weight) spanning tree algorithms. First, let $T = (\mathcal{K}_G, \mathcal{E}_T)$ be a spanning tree of W_G . It is well known that T is a maximum-weight spanning tree if and only if for every pair of cliques $K, K' \in \mathcal{K}_G$ for which $(K, K') \notin \mathcal{E}_T$, the weight of every edge on the path joining K and K' in T is no smaller than $|K \cap K'|$ (see, for example, Tarjan [44, pp. 71–72]). Second, given an edge (K, K') in a tree, we define the *fundamental cut set* (see Gibbons [18, p. 58]) associated with the edge as follows. The removal of (K, K') from the tree partitions the vertices of T into precisely two sets, say \mathcal{K}_1 and \mathcal{K}_2 . The fundamental cut set associated with (K, K') consists of every edge with one vertex in \mathcal{K}_1 and the other in \mathcal{K}_2 , including (K, K') itself.

Theorem 3.5 (Bernstein and Goodman [2]). *For any connected chordal graph G , $\mathcal{T}_G^{\text{mst}} = \mathcal{T}_G^{\text{ct}}$.*

Proof: We first show that $\mathcal{T}_G^{\text{ct}} \subseteq \mathcal{T}_G^{\text{mst}}$. Let $T_{\text{ct}} \in \mathcal{T}_G^{\text{ct}}$ and choose two cliques K and K' that are not connected by an edge in T_{ct} . Consider the cycle formed by adding the edge $\{K, K'\}$ to T_{ct} . By Theorem 3.1 every edge along this cycle has weight no smaller than $|K \cap K'|$, whence T_{ct} is a maximum-weight spanning tree of W_G .

To see that $\mathcal{T}_G^{\text{mst}} \subseteq \mathcal{T}_G^{\text{ct}}$, choose $T_{\text{mst}} \in \mathcal{T}_G^{\text{mst}}$. By Theorem 3.1, $\mathcal{T}_G^{\text{ct}} \neq \emptyset$. Choose $T_{\text{ct}} \in \mathcal{T}_G^{\text{ct}}$ that has a maximum number of edges in common with T_{mst} . Assume for the purpose of contradiction that there is an edge (K_1, K_2) of T_{mst} that is not an edge of T_{ct} . Consider the fundamental cut set (in W_G) associated with the edge (K_1, K_2) of T_{mst} and also the cycle (in T_{ct}) obtained by adding the edge (K_1, K_2) to T_{ct} . Any cycle containing one edge from the cut set must contain another edge from the cut set as well. Select from the cycle in T_{ct} one of the edges $(K_3, K_4) \neq (K_1, K_2)$ that belongs

to the cut set.

Note that the edge (K_3, K_4) is an edge of T_{ct} , but it is not an edge of T_{mst} . Since T_{ct} is a clique tree, it follows from Theorem 3.1 that $K_1 \cap K_2 \subseteq K_3 \cap K_4$. However, if $K_1 \cap K_2$ were a proper subset of $K_3 \cap K_4$, then replacing (K_1, K_2) in T_{mst} with (K_3, K_4) would result in a spanning tree of greater weight, contrary to the maximality of T_{mst} 's weight. Hence, $K_1 \cap K_2 = K_3 \cap K_4$. Consider the tree obtained by replacing (K_3, K_4) in T_{ct} with the edge (K_1, K_2) . The reader can easily verify that the resulting tree is a clique tree. The new clique tree moreover has one more edge in common with T_{mst} than originally possessed by T_{ct} , giving us the contradiction we seek. Consequently, $T_{mst} = T_{ct}$, and the result holds. ■

3.5. Summary

The following corollary summarizes the results presented in this section.

Corollary 1. *For every connected graph G , we have*

$$\mathcal{T}_G^{ct} = \mathcal{T}_G^{ist} = \mathcal{T}_G^{rip}.$$

Furthermore, G is chordal if and only if this set is nonempty, in which case we have

$$\mathcal{T}_G^{ct} = \mathcal{T}_G^{ist} = \mathcal{T}_G^{rip} = \mathcal{T}_G^{mst}.$$

Based on Corollary 1, we henceforth drop the superscripts from our notation and shall use \mathcal{T}_G to denote the set of clique trees of G . Finally, Figure 3.5 illustrates Corollary 1 in negative form. We now verify that the tree displayed in this figure

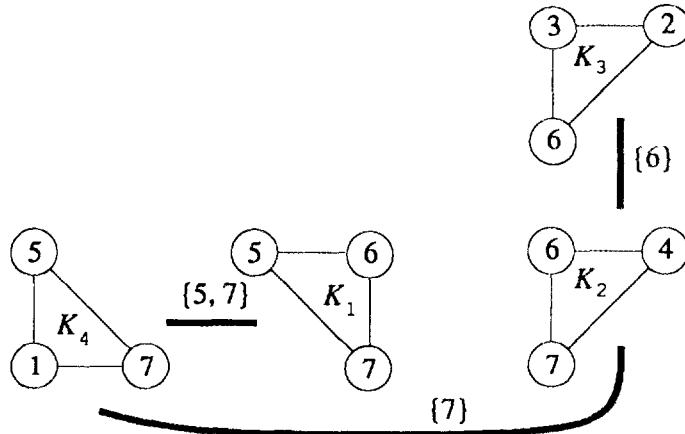


Figure 3.5: Not a clique tree of the graph in Figure 3.1.

indeed satisfies none of the characterizations of a clique tree:

[CT] The set $K_1 \cap K_2$ is not contained in K_4 .

[IST] $\mathcal{K}_G(v_6)$ does not induce a subtree.

[RIP] The reverse topological ordering K_3, K_2, K_4, K_1 is not an RIP ordering: $K_1 \cap (K_4 \cup K_2 \cup K_3) = K_1$, which is, of course, contained in no other clique. It follows then from the remark after Theorem 5 that the tree is not an RIP tree.

[MST] The weight of the tree, which is four, is submaximal by one.

4. Clique trees, separators, and MCS revisited

This section ties together some of the results and concepts presented separately in Sections 2 and 3. Section 4.1 presents results that link the edges in a clique tree with the minimal vertex separators of the underlying chordal graph. Section 4.2 presents an efficient algorithm for computing a clique tree. This algorithm, which is a simple extension of the MCS algorithm, is shown to be an implementation of Prim's algorithm for finding a maximum-weight spanning tree of the weighted clique intersection graph W_G . New definitions and notation will be introduced as needed, and appropriate references to the literature will be given in each subsection. As in the previous section, we assume without loss of generality that G is connected.

4.1. Clique tree edges and minimal vertex separators

Choose a clique tree $T \in \mathcal{T}_G$ and let $S = K_i \cap K_j$ for some edge $(K_i, K_j) \in \mathcal{E}_T$. Let $T_i = (\mathcal{K}_i, \mathcal{E}_i)$ and $T_j = (\mathcal{K}_j, \mathcal{E}_j)$ denote the two subtrees obtained by removing the edge (K_i, K_j) from T , with $K_i \in \mathcal{K}_i$ and $K_j \in \mathcal{K}_j$. We also define vertex sets $V_i \subset V$ and $V_j \subset V$ by

$$V_i := \left(\bigcup_{K \in \mathcal{K}_i} K \right) - S$$

and

$$V_j := \left(\bigcup_{K \in \mathcal{K}_j} K \right) - S.$$

We first prove two technical lemmas, the second of which shows that the set $S = K_i \cap K_j$ separates V_i from V_j in G . These two results are then used in the proof of Theorem 4.1 to show that for any clique tree $T \in \mathcal{T}_{ct}$ the set $S' \subset V$ is a minimal vertex separator if and only if $S' = K \cap K'$ for some edge $(K, K') \in \mathcal{E}_T$. The results in this section have appeared in both Ho and Lee [21] and Lundquist [33]. The proofs of Lemma 5 and Theorem 4.1 are similar to arguments given by Lundquist [33].

Lemma 4. *The sets V_i , V_j , and S form a partition of V .*

Proof: Let $T, S, K_i, K_j, \mathcal{K}_i, \mathcal{K}_j, V_i$, and V_j be as defined as in the first paragraph of the subsection. Clearly, $V = V_i \cup V_j \cup S$, and S is disjoint from both V_i and V_j . Hence it suffices to show that $V_i \cap V_j = \emptyset$. By way of contradiction assume there exists a vertex $v \in V_i \cap V_j$. It follows that v belongs to some clique $K \in \mathcal{K}_i$ and also belongs to some clique $K' \in \mathcal{K}_j$. Since $T \in \mathcal{T}_G$, the vertex v belongs to every clique along the path joining K and K' in T , which necessarily includes both K_i and K_j . In consequence, $v \in S = K_i \cap K_j$, which is impossible since both V_i and V_j are disjoint from S , whence the result follows. ■

Lemma 5. If $S = K_i \cap K_j$ and $(K_i, K_j) \in \mathcal{E}_T$ for some $T \in \mathcal{T}_G$, then S is a vw -separator for every pair of vertices $v \in V_i$ and $w \in V_j$.

Proof: Again let $T, S, K_i, K_j, \mathcal{K}_i, \mathcal{K}_j, V_i$, and V_j be as defined in the first paragraph of the subsection. To prove the result it suffices to show that there exists no edge $(v, w) \in E_G$ with $v \in V_i$ and $w \in V_j$. Now, if $(v, w) \in E_G$, then there exists a clique $K \in \mathcal{K}_G$ for which $v, w \in K$. If $K \in \mathcal{K}_i$ then clearly $v, w \in S \cup V_i$. Moreover since by Lemma 4, V_i, V_j , and S form a partition of V , it follows that neither v nor w belongs to V_j . Likewise, if $K \in \mathcal{K}_j$ then $v, w \in S \cup V_j$, and neither v nor w belongs to V_i . In consequence, no edge in E_G joins two vertices $v \in V_i$ and $w \in V_j$, which concludes the proof. ■

Theorem 4.1. Let $T \in \mathcal{T}_G$. The set $S \subset V$ is a minimal vertex separator of G if and only if $S = K \cap K'$ for some edge $(K, K') \in \mathcal{E}_T$.

Proof: For the “if” part let $T \in \mathcal{T}_G$, and let $S = K \cap K'$, for some edge $(K, K') \in \mathcal{E}_T$. Consider two vertices $v \in K - S$ and $w \in K' - S$. By Lemma 5, S is a vw -separator. Moreover, since both v and w are adjacent to every vertex in S , it follows that S is a minimal vw -separator, as desired.

To prove the “only if” part, choose $T \in \mathcal{T}_G$ and let S be a minimal vw -separator of G . Since $(v, w) \notin E$, the sets $\mathcal{K}_G(v)$ and $\mathcal{K}_G(w)$ induce disjoint subtrees of T . Choose $K \in \mathcal{K}_G(v)$ and $K' \in \mathcal{K}_G(w)$ to minimize the distance in T between K and K' . Consider the path $\mu = [K = K_0, K_1, \dots, K_{r-1}, K_r = K']$ in T , where $r \geq 1$. Define $S_i := K_i \cap K_{i+1}$ for $0 \leq i \leq r - 1$, and let $\mathcal{S} := \{S_0, S_1, \dots, S_{r-1}\}$. We will show that $S \in \mathcal{S}$, which suffices to prove the result.

First, to see that $S_i \subseteq S$ for at least one set $S_i \in \mathcal{S}$, suppose (for the purpose of contradiction) that $S_i \not\subseteq S$ for every $S_i \in \mathcal{S}$, and choose $x_i \in S_i - S$ for each member of \mathcal{S} . Since $x_i \in K_i \cap K_{i+1}$ ($0 \leq i \leq r - 1$), we have a path $[v, x_0, x_1, \dots, x_{r-1}, w]$ joining v and w in $G \setminus S$, contrary to our assumption that S is a vw -separator. It follows that $S_i \subseteq S$ for at least one set $S_i \in \mathcal{S}$.

Now select $S_i \in \mathcal{S}$ for which $S_i \subseteq S$, and consider the two subtrees obtained by removing the edge (K_i, K_{i+1}) from T . Let T_v be the subtree containing $K_0 \ni v$, and let T_w be the subtree containing $K_r \ni w$. Since S_i is contained in the vw -separator S , we clearly have $v, w \notin S_i$. Hence, by Lemma 5, S_i is a vw -separator. Since S is

moreover a minimal vw -separator, we have $S = S_i = K_i \cap K_{i+1}$ where $(K_i, K_{i+1}) \in \mathcal{E}_T$, as required. ■

For a clique tree $T = (\mathcal{K}_G, \mathcal{E}_T) \in \mathcal{T}_G$, consider the set containing every *distinct* set $K \cap K'$ where $(K, K') \in \mathcal{E}_T$. It follows immediately from Theorem 4.1 that this set is the same for every clique tree $T \in \mathcal{T}_G$. In light of Theorem 4.1, we shall refer to the members of this invariant set as *separators*. For any clique tree $T = (\mathcal{K}_G, \mathcal{E}_T) \in \mathcal{T}_G$ consider the multiset of separators defined by

$$\mathcal{M}_T := \{K \cap K' \mid (K, K') \in \mathcal{E}_T\}.$$

That this multiset is the same for all clique trees $T \in \mathcal{T}_G$ is an immediate consequence of a result by Ho and Lee [21]; the result was also proven by Lundquist [33]. The proof is taken directly from Blair and Peyton [4].

Theorem 4.2 (Ho and Lee [21], Lundquist [33]). *The multiset of separators is the same for every clique tree $T \in \mathcal{T}_G$.*

Proof: For the purpose of contradiction, suppose there exist two distinct clique trees $T, T' \in \mathcal{T}_G$ for which $\mathcal{M}_T \neq \mathcal{M}_{T'}$. From among the clique trees $T' \in \mathcal{T}_G$ for which $\mathcal{M}_{T'} \neq \mathcal{M}_T$, choose T' so that it shares as many edges as possible with T . (Note that T and T' cannot share the same edge set, for then they also would share the same multiset of separators.)

Let (K_1, K_2) be an edge of T that does not belong to T' . As in the proof of Theorem 3.5, consider the fundamental cut set (in W_G) associated with the edge (K_1, K_2) of T and also the cycle (in T') obtained by adding the edge (K_1, K_2) to T' . Recall that any cycle containing one edge from the cut set must contain another edge from the cut set as well. Select from the cycle in T' one of the edges $(K_3, K_4) \neq (K_1, K_2)$ that belongs to the cut set. Note that the edge (K_3, K_4) is an edge of T' but not an edge of T .

Since $T \in \mathcal{T}_{ct}$, it follows by Theorem 3.1 that $K_3 \cap K_4 \subseteq K_1 \cap K_2$; similarly, since $T' \in \mathcal{T}_{ct}$, it follows by Theorem 3.1 that $K_1 \cap K_2 \subseteq K_3 \cap K_4$; hence $K_3 \cap K_4 = K_1 \cap K_2$. By Theorem 3.5, the replacement of (K_3, K_4) in T' with (K_1, K_2) results in a clique tree, which, moreover, clearly has the same multiset of separators that T' has. Contrary to our assumption about T' , the modified tree shares one more edge with T , and thus result follows. ■

4.2. MCS and Prim's algorithm

Prim's algorithm [38] is an efficient method for computing a maximum-weight (minimum-weight) spanning tree of a weighted graph. Thus, by Theorem 3.5, Prim's algorithm applied to the weighted clique intersection graph W_G computes a clique tree $T \in \mathcal{T}_G$. At any point the algorithm has constructed a subtree of the eventual maximum-weight

spanning tree T , and at each step it adds one more clique and edge to this subtree. Let $\hat{\mathcal{K}} \subset \mathcal{K}_G$ be the cliques in the subtree constructed thus far. As the next edge to be added, the algorithm chooses the heaviest edge that joins $\hat{\mathcal{K}}$ to $\mathcal{K}_G - \hat{\mathcal{K}}$. For a proof that Prim's algorithm correctly computes a maximum-weight spanning tree, we refer the reader to Tarjan [44, pp. 73–75] or Gibbons [18, pp. 40–42]. A version of Prim's algorithm formulated specifically for our problem is given in Figure 4.1.

```

 $\mathcal{E}_T \leftarrow \emptyset;$ 
Choose  $K \in \mathcal{K}_G$ ;
 $\hat{\mathcal{K}} \leftarrow \{K\}$ ;
for  $r \leftarrow 2$  to  $m$  do
    Choose cliques  $K \in \hat{\mathcal{K}}$  and  $K' \in \mathcal{K}_G - \hat{\mathcal{K}}$ 
        for which  $|K \cap K'|$  is maximum;
     $\mathcal{E}_T \leftarrow \mathcal{E}_T \cup \{(K, K')\}$ ;
     $\hat{\mathcal{K}} \leftarrow \hat{\mathcal{K}} \cup \{K'\}$ ;
end for

```

Figure 4.1: Prim's algorithm for finding a maximum-weight spanning tree of the weighted clique intersection graph W_G .

In this section we will show that the MCS algorithm applied to a chordal graph G can be viewed as an implementation of Prim's algorithm applied to W_G . In Section 4.2.1 we show that since the MCS algorithm generates a PEO, it can easily detect the cliques in \mathcal{K}_G during the course of the computation. Section 4.2.2 shows that 1) the MCS algorithm can be viewed as a block algorithm that “searches” the cliques in \mathcal{K}_G one after the other, and 2) the order in which the cliques are searched is precisely the order in which the cliques are searched by Prim's algorithm in Figure 4.1. Using the results in Sections 4.2.1 and 4.2.2, we also show how to supplement the MCS algorithm with a few additional statements so that it detects the cliques and a set of clique tree edges as it generates a PEO. A detailed statement of this algorithm appears at the end of Section 4.2.2.

The close connection between the MCS algorithm and Prim's algorithm was, to our knowledge, first presented by Blair, England, and Thomason [3]. Several of the proofs in this section are similar to arguments given by Lewis *et al.* [24]. Though the techniques discussed in this section can be implemented to run quite efficiently, there are more efficient ways to compute a clique tree when certain data structures that arise in sparse matrix computations are available. The reader should consult Lewis *et al.* [24] for details on how to compute a clique tree in the course of solving a sparse positive definite linear system.

4.2.1. Detecting the cliques

In this subsection we show that the MCS algorithm can easily and efficiently detect the cliques in \mathcal{K}_G . To do so we exploit the fact that MCS computes a PEO. We shall use the following result from Fulkerson and Gross [10].

Lemma 6 (Fulkerson and Gross [10]). *Let v_1, v_2, \dots, v_n be a perfect elimination ordering of G . The set of maximal cliques \mathcal{K}_G contains precisely the sets $\{v_i\} \cup \text{madj}(v_i)$ for which there exists no vertex v_j , $j < i$, such that*

$$\{v_i\} \cup \text{madj}(v_i) \subset \{v_j\} \cup \text{madj}(v_j). \quad (4.1)$$

Proof: Choose $K \in \mathcal{K}_G$ and let $v_i \in K$ be the vertex whose label i assigned by the PEO is lowest among the labels assigned to a vertex of K . Consider the vertex set $\{v_i\} \cup \text{madj}(v_i)$. Since K consists of v_i and neighbors of v_i with labels larger than i , clearly $K \subseteq \{v_i\} \cup \text{madj}(v_i)$. Because the ordering is a PEO, the set $\{v_i\} \cup \text{madj}(v_i)$ must be complete in G . Thus by maximality of the clique K we have $K = \{v_i\} \cup \text{madj}(v_i)$, and moreover it follows that (4.1) holds for no vertex v_j , $j < i$.

Now, let $K = \{v_i\} \cup \text{madj}(v_i)$ and suppose that (4.1) holds for no vertex v_j , $j < i$. Since the ordering is a PEO, clearly K is complete in G . If K is submaximal, then there exists a vertex $v_j \in V - K$ that is adjacent to every vertex of K . But the existence of such a vertex v_j is impossible: if $j > i$ then $v_j \in \text{madj}(v_i)$, contrary to $v_j \in V - K$; if $j < i$ then (4.1) holds for v_j , contrary to our assumption. In consequence, no such vertex v_j exists, and the result follows. ■

Throughout the remainder of the paper we let v_1, v_2, \dots, v_n be a PEO obtained by applying the MCS algorithm to a connected chordal graph G . We shall call v_{i_r} the *representative vertex* of K_r whenever $K_r = \{v_{i_r}\} \cup \text{madj}(v_{i_r})$; that is, we let $v_{i_1}, v_{i_2}, \dots, v_{i_m}$ be the representative vertices of the cliques K_1, K_2, \dots, K_m , respectively, where $i_1 > i_2 > \dots > i_m$. Thus the ordering K_1, K_2, \dots, K_m specifies the order in which the cliques are searched by the MCS algorithm.

As the MCS algorithm generates a PEO it can easily detect the representative vertices and hence can easily collect the cliques in \mathcal{K}_G . Condition 2 in the next lemma provides a test for determining when a vertex in an MCS ordering is *not* a representative vertex. Lemma 8 then provides a simple test for detecting the representative vertices.

Lemma 7. *Let v_1, v_2, \dots, v_n be a perfect elimination ordering obtained by applying the maximum cardinality search algorithm to a connected chordal graph G . For each vertex label i , $1 \leq i \leq n - 1$, the following are equivalent:*

1. $\{v_{i+1}\} \cup \text{madj}(v_{i+1}) \notin \mathcal{K}_G$.
2. $|\text{adj}(v_i) \cap \mathcal{L}_{i+1}| = |\text{adj}(v_{i+1}) \cap \mathcal{L}_{i+2}| + 1$.
3. $\{v_i\} \cup \text{madj}(v_i) = \{v_i, v_{i+1}\} \cup \text{madj}(v_{i+1})$.

Proof: First we state two inequalities that prove useful here and in later proofs. Note that the maximum cardinality selection criterion ensures that the following inequality holds true when v_{i+1} ($1 \leq i \leq n - 1$) is selected to be labeled:

$$|\text{adj}(v_i) \cap \mathcal{L}_{i+2}| \leq |\text{adj}(v_{i+1}) \cap \mathcal{L}_{i+2}|. \quad (4.2)$$

Equation (4.2) along with the fact that $\mathcal{L}_{i+1} = \mathcal{L}_{i+2} \cup \{v_{i+1}\}$, gives us

$$|\text{adj}(v_i) \cap \mathcal{L}_{i+1}| \leq |\text{adj}(v_{i+1}) \cap \mathcal{L}_{i+2}| + 1. \quad (4.3)$$

Assume that the first condition in the statement of the lemma holds for v_{i+1} , and consider the vertex v_i selected by the MCS algorithm at the next step. When the algorithm selects v_i there exists (by Lemma 6) a vertex $u \in V - \mathcal{L}_{i+1}$ that is adjacent to every vertex in $\{v_{i+1}\} \cup \text{madj}(v_{i+1})$. In light of (4.3), the existence of such a vertex u ensures that the vertex v_i chosen by the MCS algorithm (perhaps $v_i = u$) satisfies the second condition.

Assume now that the second condition in the statement of the lemma holds for the two vertices v_i and v_{i+1} . It immediately follows that

$$|\text{madj}(v_i)| = |\{v_{i+1}\} \cup \text{madj}(v_{i+1})|.$$

Consequently, to prove that the third condition holds true it suffices to show that $\text{madj}(v_i) \subseteq \{v_{i+1}\} \cup \text{madj}(v_{i+1})$. Now if it were the case that $v_{i+1} \notin \text{adj}(v_i)$, then from (4.2) and the fact that $\mathcal{L}_{i+1} = \mathcal{L}_{i+2} \cup \{v_{i+1}\}$ we would have

$$|\text{adj}(v_i) \cap \mathcal{L}_{i+1}| \leq |\text{adj}(v_{i+1}) \cap \mathcal{L}_{i+2}|,$$

contrary to our assumption that condition 2 holds true. It follows then that v_{i+1} is adjacent to v_i in G . Now choose $v_k \in \text{madj}(v_i) - \{v_{i+1}\}$. Clearly $k \geq i + 2$; moreover, since $\{v_i\} \cup \text{madj}(v_i)$ is complete in G , v_k is necessarily adjacent to $v_{i+1} \in \text{madj}(v_i)$; whence $v_k \in \text{madj}(v_{i+1})$, giving us condition 3.

Finally, by Lemma 6 the first condition follows immediately from the third, which completes the proof. ■

Further extending the result in Lemma 7, we obtain the following technique for detecting the representative vertices of \mathcal{K}_G while generating the MCS ordering.

Lemma 8. Let v_1, v_2, \dots, v_n be a perfect elimination ordering obtained by applying the maximum cardinality search algorithm to a connected chordal graph G . Then \mathcal{K}_G contains precisely the following sets: $\{v_1\} \cup \text{madj}(v_1)$ and $\{v_{i+1}\} \cup \text{madj}(v_{i+1})$, $1 \leq i \leq n - 1$, for which

$$|\text{adj}(v_i) \cap \mathcal{L}_{i+1}| \leq |\text{adj}(v_{i+1}) \cap \mathcal{L}_{i+2}|. \quad (4.4)$$

Proof: From Lemma 6 it follows that $\{v_1\} \cup \text{madj}(v_1) \in \mathcal{K}_G$. Consider the set $\{v_{i+1}\} \cup \text{madj}(v_{i+1})$ where $1 \leq i \leq n-1$. It follows from (4.3) and the equivalence of conditions 1 and 2 in Lemma 7 that $\{v_{i+1}\} \cup \text{madj}(v_{i+1})$ is a member of \mathcal{K}_G if and only if (4.4) holds. This concludes the proof. ■

4.2.2. MCS as a block algorithm

Clearly, the MCS algorithm can detect the cliques in \mathcal{K}_G by determining at each step whether or not (4.4) holds. With the next lemma we show that the MCS algorithm can be viewed as a block algorithm that searches the cliques of \mathcal{K}_G one after the other.

Lemma 9. Let v_1, v_2, \dots, v_n be a perfect elimination ordering obtained by applying the maximum cardinality search algorithm to a connected chordal graph G , and let $v_{i_1}, v_{i_2}, \dots, v_{i_m}$ be the representative vertices of the cliques K_1, K_2, \dots, K_m , respectively, where $i_1 > i_2 > \dots > i_m$. Then

$$\mathcal{L}_{i_r} = \bigcup_{s=1}^r K_s \quad (4.5)$$

for each r , $1 \leq r \leq m$.

Proof: Choose r , $1 \leq r \leq m$, and assume $v_j \notin \mathcal{L}_{i_r}$, i.e., $j < i_r$. Since clearly $v_j \notin \{v_{i_s}\} \cup \text{madj}(v_{i_s})$ for each s , $1 \leq s \leq r$, it follows by Lemma 6 that $v_j \notin \bigcup_{s=1}^r K_s$. Now assume $v_j \in \mathcal{L}_{i_r}$ and for convenience of notation define $i_0 := n+1$. Choose s , $1 \leq s \leq r$, for which $i_s \leq j < i_{s-1}$. If $j = i_s$, then clearly $v_j \in K_s = \{v_j\} \cup \text{madj}(v_j)$. If $i_s < j$, then by repeated application of condition 3 of Lemma 7, we have

$$\begin{aligned} K_s &= \{v_{i_s}\} \cup \text{madj}(v_{i_s}), \\ &= \{v_{i_s}, v_{i_s+1}\} \cup \text{madj}(v_{i_s+1}), \\ &\vdots \\ &= \{v_{i_s}, v_{i_s+1}, \dots, v_j\} \cup \text{madj}(v_j). \end{aligned}$$

Consequently, $v_j \in K_s$, and the result follows. ■

It follows from Lemma 9 that the MCS algorithm labels the vertices contiguously in blocks as follows:

$$\begin{aligned} \{v_{i_1}, v_{i_1+1}, \dots, v_n = v_{i_0-1}\} &= K_1 \\ \{v_{i_2}, v_{i_2+1}, \dots, v_{i_1-1}\} &= K_2 - K_1 \\ \{v_{i_3}, v_{i_3+1}, \dots, v_{i_2-1}\} &= K_3 - \bigcup_{s=1}^2 K_s \\ &\vdots \end{aligned}$$

$$\{v_1 = v_{i_m}, v_{i_m+1}, \dots, v_{i_{m-1}-1}\} = K_m - \bigcup_{s=1}^{m-1} K_s.$$

For convenience we define the function $clique : V \rightarrow \{1, \dots, m\}$ by $clique(v_j) := r$ where $i_0 := n + 1$ and $v_j \in \{v_{i_r}, v_{i_r+1}, \dots, v_{i_{r-1}-1}\}$ (i.e., $i_r \leq j < i_{r-1}$). Clearly $clique(v)$ is the lowest index of a clique that contains v ; that is,

$$clique(v) = \min\{r \mid v \in K_r\}.$$

The following lemma is needed to provide a means of detecting the edges of a clique tree, and it is also critical in the proof of the main result in this subsection.

Lemma 10. *Let v_1, v_2, \dots, v_n be a perfect elimination ordering obtained by applying the maximum cardinality search algorithm to a connected chordal graph G , and let $v_{i_1}, v_{i_2}, \dots, v_{i_m}$ be the representative vertices of the cliques K_1, K_2, \dots, K_m , respectively, where $i_1 > i_2 > \dots > i_m$. For any integer r , $1 \leq r \leq m - 1$, there exists an integer p , $1 \leq p \leq r$, such that*

$$K_{r+1} \cap \mathcal{L}_{i_r} = K_{r+1} \cap K_p. \quad (4.6)$$

Moreover, Equation (4.6) is satisfied when $p = clique(v_j)$, where v_j is the vertex in $K_{r+1} \cap \mathcal{L}_{i_r}$ with smallest label j .

Proof: Let $1 \leq r \leq m - 1$. From Lemma 9 it follows that for $1 \leq p \leq r$ we have

$$K_{r+1} \cap K_p \subseteq K_{r+1} \cap \mathcal{L}_{i_r}.$$

To prove the result it suffices to show that $K_{r+1} \cap \mathcal{L}_{i_r} \subseteq K_p$. Now consider the set $K_{r+1} \cap \mathcal{L}_{i_r}$, and choose $v_j \in K_{r+1} \cap \mathcal{L}_{i_r}$ with smallest label j . Clearly $K_{r+1} \cap \mathcal{L}_{i_r}$ is complete in G and moreover

$$K_{r+1} \cap \mathcal{L}_{i_r} \subseteq \{v_j\} \cup madj(v_j). \quad (4.7)$$

Choose p , $1 \leq p \leq r$, for which $i_p \leq j < i_{p-1}$. (Note that $p = clique(v_j)$.) By the same argument used in the proof of Lemma 9, we have

$$\{v_j\} \cup madj(v_j) \subseteq K_p. \quad (4.8)$$

Combining (4.7) and (4.8), we obtain the result. ■

From Lemmas 9 and 10 it follows that any MCS clique ordering is also an RIP ordering. Furthermore, Lemma 10 shows specifically how to use the *clique* function to obtain the edges of a clique tree in an efficient manner. (This technique for determining a clique tree parent function was introduced by Tarjan and Yannakakis [45] and also

appears in Lewis et al. [24].) It follows that the MCS algorithm can generate a clique tree by 1) detecting the cliques via representative vertices (Lemma 8) and 2) choosing as the parent of K_{r+1} the clique K_p for which $p = \text{clique}(v_j)$ where j is the smallest label in $K_{r+1} \cap \mathcal{L}_{i_r}$. The following result shows that any clique tree generated in this fashion could also be generated by Prim's algorithm applied to W_G .

Theorem 4.3. *Any order in which the cliques are searched by the maximum cardinality search algorithm is also an order in which the cliques are searched by Prim's algorithm applied to W_G .*

Proof: Let K_1, K_2, \dots, K_m be an ordering of \mathcal{K}_G generated by the MCS algorithm. Choose r , $1 \leq r \leq m-1$. To show that this clique ordering is also a search order for Prim's algorithm applied to W_G (see Figure 4.1), it suffices to show that there exists p ($1 \leq p \leq r$) for which

$$|K_{r+1} \cap K_p| = \max_{\substack{1 \leq s \leq r \\ r+1 \leq t \leq m}} |K_t \cap K_s|. \quad (4.9)$$

To prove that (4.9) holds, choose any s and t for which $1 \leq s \leq r < t \leq m$. Consider the vertex $v_j \in K_{r+1} \cap \mathcal{L}_{i_r}$ for which j is minimum, and let $p = \text{clique}(v_j)$. By Lemma 10, we can write

$$K_{r+1} \cap K_p = K_{r+1} \cap \mathcal{L}_{i_r}. \quad (4.10)$$

Lemma 9 and the discussion following that result imply that v_{i_r-1} is the vertex from $K_{r+1} - \mathcal{L}_{i_r}$ whose label is maximum. By repeated application of condition 3 of Lemma 7 (as needed) we obtain the following:

$$\begin{aligned} K_{r+1} &= \{v_{i_{r+1}}\} \cup \text{madj}(v_{i_{r+1}}), \\ &= \{v_{i_{r+1}}, v_{i_{r+1}+1}\} \cup \text{madj}(v_{i_{r+1}+1}), \\ &\vdots \\ &= \{v_{i_{r+1}}, \dots, v_{i_r-2}, v_{i_r-1}\} \cup \text{madj}(v_{i_r-1}). \end{aligned}$$

In consequence we have

$$K_{r+1} \cap \mathcal{L}_{i_r} = \text{adj}(v_{i_r-1}) \cap \mathcal{L}_{i_r}. \quad (4.11)$$

Now, if

$$|K_t \cap \mathcal{L}_{i_r}| > |\text{adj}(v_{i_r-1}) \cap \mathcal{L}_{i_r}|,$$

then for $u \in K_t - \mathcal{L}_{i_r} \neq \emptyset$, we have

$$|\text{adj}(v_{i_r-1}) \cap \mathcal{L}_{i_r}| < |\text{adj}(u) \cap \mathcal{L}_{i_r}|,$$

contrary to the maximum cardinality search criterion by which the vertices were labeled. It follows then that

$$|\text{adj}(v_{i_r-1}) \cap \mathcal{L}_{i_r}| \geq |K_t \cap \mathcal{L}_{i_r}|. \quad (4.12)$$

Finally, Lemma 9 implies that

$$|K_t \cap \mathcal{L}_{i_r}| \geq |K_t \cap K_s|. \quad (4.13)$$

Combining (4.10), (4.11), (4.12), and (4.13) shows that (4.9) holds, giving us the result. ■

From the results in this subsection, we obtain an expanded version of the MCS algorithm, which computes a clique tree in addition to a PEO. The MCS algorithm is shown in Figure 2.3, and the expanded algorithm is shown in Figure 4.2. We emphasize

```

prev_card ← 0;
 $\mathcal{L}_{n+1} \leftarrow \emptyset;$ 
s ← 0;
 $\mathcal{E}_T \leftarrow \emptyset;$ 
for  $i \leftarrow n$  to 1 step  $-1$  do
    Choose a vertex  $v \in V - \mathcal{L}_{i+1}$  for which
         $|\text{adj}(v) \cap \mathcal{L}_{i+1}|$  is maximum;
     $\alpha(v) \leftarrow i$ ; [ $v$  becomes  $v_i$ ]
    new_card ←  $|\text{adj}(v_i) \cap \mathcal{L}_{i+1}|$ ;
    if new_card ≤ prev_card then [begin new clique]
        s ← s + 1;
         $K_s \leftarrow \text{adj}(v_i) \cap \mathcal{L}_{i+1}$ ; [= madj( $v$ )]
        if new_card ≠ 0 then [get edge to parent]
            k ←  $\min\{j \mid v_j \in K_s\}$ ;
            p ← clique( $v_k$ );
             $\mathcal{E}_T \leftarrow \mathcal{E}_T \cup \{K_s, K_p\}$ ;
        end if
    end if
    clique( $v_i$ ) ← s;
     $K_s \leftarrow K_s \cup \{v_i\}$ ;
     $\mathcal{L}_i \leftarrow \mathcal{L}_{i+1} \cup \{v_i\}$ ;
    prev_card ← new_card;
end for
```

Figure 4.2: An expanded version of MCS, which implements Prim's algorithm in Figure 4.1.

that the primary purpose of this section is to establish the connection between the MCS

algorithm and Prim's algorithm (applied to W_G), and Theorem 4.3 demonstrates that the detailed algorithm in Figure 4.2 can be viewed as a special implementation of Prim's algorithm shown in Figure 4.1. Some of the details necessary to represent a chordal graph as a clique tree have been discussed here; for a complete discussion of this topic the reader should consult the papers [24,45]. It is worth noting that a clique tree is often a much more compact and more computationally efficient data structure than the adjacency lists usually used to represent G .

5. Applications

In this section we briefly review a few recent applications of chordal graphs and clique trees in sparse matrix computations.

5.1. Terminology

Let $Ax = b$ be a sparse symmetric positive definite system of linear equations, whose Cholesky factorization is denoted by $A = LL^T$. Direct methods for solving such linear systems store and compute only the nonzero entries of the Cholesky factor L . This factorization generally introduces *fill* (or *fill-in*) into the matrix; that is, some of the zero entries in A become nonzero entries in L .

Assume the coefficient matrix A is $n \times n$. We associate a graph $G_A = (V, E_A)$ with the matrix A in the usual way: the vertex set is given by $V = \{v_1, v_2, \dots, v_n\}$, with two vertices v_i and v_j joined by an edge in E_A if and only if $a_{ij} \neq 0$. We define the *filled graph* $G_F = (V, E_F)$ in precisely the same way, where $F := L + L^T$. Note that G_F is a *chordal supergraph* of G_A ($E_A \subseteq E_F$) [39], and the order in which the unknowns are eliminated is a PEO for the corresponding filled graph G_F .

5.2. Elimination trees

More commonly used than the clique tree, the *elimination tree* associated with the ordered graph G_A has proven very useful in sparse matrix computations. The elimination tree $T_A = (V, E_T)$ for an irreducible graph G_A is a rooted tree defined by a parent function as follows: for each vertex v_j , $1 \leq j \leq n - 1$, the parent of v_j is v_i , where the first off-diagonal nonzero entry in column j of L occurs in row $i > j$. If G_A is reducible, one obtains a forest rather than a tree. A *topological ordering* of T_A is any ordering of the vertices that numbers each parent with a label larger than that of any of its children. The order in which the unknowns are eliminated, for example, is a topological ordering of the tree T_A , and, in fact, any topological ordering of the tree is a PEO of G_F . Elimination trees evidently were introduced by Schreiber [41], though they had earlier been used implicitly in a number of algorithms and applications. Liu [31] has provided a survey of the many uses of elimination trees in sparse matrix computations.

Liu has also discovered an interesting connection between clique trees and elimination trees. To facilitate our discussion of this connection we need to introduce the following concepts and results. If \mathcal{F} is a finite family of nonempty sets, then the *intersection graph* of \mathcal{F} is obtained by representing each set in \mathcal{F} by a vertex and connecting two vertices by an edge if and only if the intersection of the corresponding sets is nonempty. A *subtree graph* is an intersection graph where \mathcal{F} is a family of subtrees of a specific tree. Buneman [5], Gavril [12], and Walter [46] independently discovered that the set of chordal graphs coincides with the set of subtree graphs in a result that further extends Theorem 3.3.

Theorem 3.2 provides an obvious way to represent a chordal graph $G := G_F$ as a subtree graph. Choose any clique tree $T_{ct} \in \mathcal{T}_G$, and consider the family of subtrees of T_{ct} given by

$$\mathcal{F} = \{\mathcal{K}_G(v) \mid v \in V\}.$$

Since two vertices are adjacent to one another in G if and only if there exists a clique $K \in \mathcal{K}_G$ to which both vertices belong, it follows that for each pair of vertices $u, v \in V$, we have $(u, v) \in E$ if and only if the subtree induced by $\mathcal{K}_G(u)$ intersects the subtree induced by $\mathcal{K}_G(v)$. In consequence, G is a subtree graph for the family of subtrees \mathcal{F} in any clique tree $T_{ct} \in \mathcal{T}_G$.

Liu has shown how elimination trees provide another way to view chordal graphs as subtree graphs. Let the *row vertex set*, denoted $Struct(L_{i,*})$, be defined by

$$Struct(L_{i,*}) := \{v_j \mid \ell_{ij} \neq 0\}.$$

Liu [27] has shown that each row vertex set $Struct(L_{i,*})$ induces a subtree of T_A rooted at v_i . In consequence, G_F is a subtree graph for the family of subtrees induced by the row vertex sets of L . For a full discussion of this result, consult Liu [31].

5.3. Equivalent orderings

The fill added to G_A contains precisely the edges needed to make the order in which the unknowns of the linear system are eliminated a PEO of the filled graph G_F [39]. Usually, the primary objective in reordering the linear system is to reduce the storage (i.e., fill) and work required by the factorization. Every PEO of G_F results in precisely the same factorization storage and work requirement [29]. It is common practice in this setting to define all perfect elimination orderings of G_F as *equivalent orderings*.

Before advanced machine architectures entered the marketplace, there was little reason to consider choosing one PEO of G_F over another. Generally, whatever ordering was produced by the fill-reducing ordering algorithm (e.g., nested dissection [14,15] or minimum degree [17,26]) was accepted without modification. But this situation has changed to some extent with the advent of vector supercomputers, powerful RISC-based workstations, and a wide variety of parallel architectures. Algorithms designed for such

machines may benefit by choosing one PEO of G_F over the others in order to optimize some secondary objective function. (There is still the underlying assumption that a good fill-reducing ordering is desired, though this assumption is subject to question more than it once was and deserves further study.) The following summarizes a few algorithms designed to produce an equivalent ordering that optimizes some secondary objective function.

Reordering for stack storage reduction One of the first algorithms of this type was a simple algorithm due to Liu [28] for finding, among all topological orderings of the elimination tree, an ordering that minimizes the auxiliary storage required by the multifrontal factorization algorithm. In addition, Liu [29] gives a heuristic for finding an equivalent ordering that further reduces auxiliary storage for multifrontal factorization. Finding an optimal equivalent ordering for this problem is still an open question.

Jess and Kees reordering Short elimination trees can be useful when the factorization is to be performed in parallel. Jess and Kees [22] introduced a simple greedy heuristic for finding an equivalent ordering that reduces elimination tree height. Liu [30] has shown that the Jess and Kees ordering scheme minimizes elimination tree height among all equivalent orderings. Liu and Mirzaian [25] introduced an $O(n + |E_F|)$ implementation of the Jess and Kees scheme. Lewis, Peyton, and Pothen [24] used a clique tree of G_F to obtain an $O(n + q)$ -time implementation of the Jess and Kees algorithm where $q = \sum_{i=1}^m |K_i|$, which in practice is substantially smaller than $|E_F|$. Because a PEO of G_F is known *a priori*, a clique tree of G_F can be obtained in $O(n)$ time using output from the symbolic factorization step of the solution process [24].

A block Jess and Kees reordering Blair and Peyton [4] have studied a block form of the Jess and Kees algorithm that generates a clique tree $T \in \mathcal{T}_G$ of minimum diameter. The primary motivation for this algorithm is to minimize the number of expensive communication calls to the general router on a fine-grained parallel machine [19]. The time complexity of their algorithm is also $O(n + q)$ in the sparse matrix setting, where a PEO is known *a priori*. A similar algorithm motivated by the same application was given by Gilbert and Schreiber [19].

Partitioning (and reordering) for parallel triangular solution A related problem is the following: Find a partition of the columns in the factor L with as few members as possible, such that for each partition member, the elementary elimination matrices associated with that member can be multiplied together without increasing the storage requirement for the factor. Such a partition and its associated PEO is desirable for implementing sparse triangular solution on a fine-grained massively parallel machine. Pothen and Alvarado [37] have solved this problem when the ordering is restricted to topological orderings of the elimination tree. Peyton, Pothen, and Yuan [36] have

developed an $O(n + |EF|)$ algorithm that solves the problem for the larger set of all equivalent orderings; they are also working on an $O(n + q)$ clique-tree-based algorithm for solving the problem [35].

5.4. Clique trees and the multifrontal method

Block algorithms have become increasingly important on advanced machine architectures, both in dense and sparse matrix computations [11]. The multifrontal factorization algorithm [8,32] is perhaps the canonical example in sparse matrix computation. That clique trees, which represent chordal graphs in block form, might be a useful tool in explaining the multifrontal method is not at all surprising.

Clique trees provide the framework for presenting the multifrontal algorithm in Peyton, Pothen, and Sun [34,38]. The clique tree is rooted and ordered by a postordering of the tree, and each clique K has associated with it a frontal matrix $F(K)$. Let K and P be respectively a clique and its parent in the clique tree. The columns of $F(K)$ are partitioned into two sets: the factor columns of $F(K)$ correspond to the vertices in $K \setminus P$, and the update columns of $F(K)$ correspond to the vertices in $K \cap P$. For further details consult the two references given above.

Due to its simplicity, the *supernodal elimination tree* is more commonly used in descriptions of the multifrontal algorithm. Liu's survey article [32], for example, uses the supernodal elimination tree to describe the block version of the algorithm.

5.5. Future progress on the “ordering” problem

Finally, we anticipate that a solid understanding of chordal graphs and clique trees will play a role in future progress in the difficult area of analyzing and understanding ordering heuristics. The problem of finding a fill-minimizing ordering of an arbitrary graph is NP-hard [48]. Consequently, progress in understanding the “ordering” problem will probably require a better understanding of the broad but nonetheless highly restricted classes of graphs G_A that arise in various application areas. If there is some progress in that area, then we further speculate that creating and/or analyzing ordering algorithms for these classes of graphs will involve many interesting properties and features of chordal graphs and clique trees. Some will be the results presented in this paper; perhaps others will be new, or at least a fresh look at familiar concepts.

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