Control Abstraction + Data Types

Programming Language Theory

Topics

- Control Abstraction
 - Subprogram
- Data Types
 - Type System
 - Type Equivalence & Compatibility

- One of the two most important concepts of programming language, along with Data Abstraction.
- For a complex, large software, the main goal or requirement can be achieved,
 - by satisfying many smaller requirements.
 - Concept of Divide and Conquer.

- Suppose we're developing a mobile shopping app.
- We need the following functionalities.
 - Read product data.
 - Display products in the app.
 - Search for products.
 - Manage Customer information.

- Product Reviews
- Payment.
- Manage Purchases.
- Manage Delivery options.

- It is not a good idea to implement all these things in one big program.
- Instead, we can implement subprograms provide each function.
 - We can hide implementation details and separate them from design.
 - Easily switch to different implementation.
 - We only need to know how to use such subprograms.

Subprogram

- Also called procedure or function.
- As we talked about before, we will use subprogram, procedure, and function together as synonyms.
- Although subprogram is the most general term, let's use function for this lecture.
 - Since it is more familiar, and more similar to what we will describe later in this lecture.

Function

- A function is a piece of code,
 - which is identified by its name,
 - is given a local environment of its own,
 - and exchanges information with the other parts of code using parameters, return value and non-local environment.
- We can define (or declare) a function and use (or call) the function.

Parameter Passing

- Parameter passing is one of the important ways for a subprogram to communicate with the other parts of a program.
- We can consider three kinds of parameters in subprogram's viewpoint.
 - IN parameters: communicate from the caller to callee.
 - OUT parameters: from the callee to the caller.
 - IN/OUT parameters: bidirectional communication.

Parameter Passing

- There are various *parameter passing modes*, which we will discuss in this lecture.
- For further explanation, we need to consider two terms.
 - Formal parameters: these parameters are the ones appeared in the declaration of a function.
 - Actual parameters: also known as arguments. These are the ones passed to a function in a function call.

Call by Value

- It is a mode which corresponds to an IN parameter.
- Actual parameters can be expressions.
 - At the time of a call, actual parameters are evaluated and their *r-values* are associated with formal parameters.
 - When the function terminates, formal parameters are destroyed, hence these values are lost.
- Call by value (or pass by value) is the most simple and popular mode.
 - It is the only parameter passing mode in C and Java.

Call by Reference

- In this mode, parameters can be used both input and output (IN/OUT).
- Actual parameters must be expressions with *I-values*.
- When a function is called, *actual parameters' I-values* are associated with formal parameters *aliasing*.
- In C++
 - void func(MyObject& obj);
 - MyObject x; func(x);
- Java has no call by reference: its variable model is reference model, but parameter passing itself is not call by reference.

Call by Reference

 Java has no call by reference: its variable model is reference model, but parameter passing itself is call by value only.

```
    class A { int v; } swap(x, y);
    void swap (A a1, A a2) {
        int tmp = a1.v; a1.v = a2.v; a2.v = tmp; //simulate call by ref.
        A tmp2 = a1; a1 = a2; a2 = tmp2; //What happens?
    }
```

- Two references of objects in type A are copied and passed to swap().
- You can change the value of their member variables using reference model (α1.ν).
- But you can't actually swap two variables x and y.

Call by Constant

- In case of a parameter is not modified in the body of a function,
 - maintain semantics of call by value, while implementing it using call by reference.
 - parameters are considered *read-only*.
 - In C++
 - void func(const MyObject& obj);

Call by Result

- It is a mode implements output-only communication.
- Actual parameters must be expressions with I-values.
 - **Backward assignment**: the values of formal parameters are copied to locations obtained using actual parameters' *I-values* after a function terminates.
 - void foo(result int x) $\{x = 5;\}$ int y = 2;foo(y); //y = 5 after this call.

Call by Value-Result

- Combination of Call by Value and Call by Result.
- Implement bidirectional communication.
- Actual parameters must give *I-values*.
- At the call, r-values of actual parameters are assigned to formal parameters (Call by Value).
- Then value of formal parameters are copied backward using I-values of actual parameters (Call by Result).
 - void foo(val-res int x) $\{x = x + 1;\}$ int y = 2;foo(y); //y = 3 after this call.

Call by Value-Result

- Difference to call by reference.
 - void foo(val-res/ref int x, val-res/ref int y) {
 x = 1; y = 3;
 if(x == y) y = 1; //x == y → true if call by ref. aliasing.
 - int a = 2; foo(a, a); //a is 3 after the call by value-result, 1 after call by ref.

Call by Name

- This mode is no longer used by modern programming languages.
- Although it is conceptually important, we will not discuss details of the method in this lecture.
- Simply speaking, it is a method to replace formal parameter names in the function body with actual parameter names.

```
    void foo(name int x) { x = 1; }
int y = 2;
foo(y); → void foo(int y) { y = 1; }
```

Call by Name

• However, simple replacements may cause a problem.

```
    int x = 0;
    int foo(name int y) {
    int x = 2;
    return x + y;
    }
    int a = foo(x + 1);
```

```
    int x = 0;
    int foo(name int y) {
    int z = 2;
    return z + y;
    }
    int a = foo(x + 1);
```

 Hence it is necessary to pass actual parameters as well as their evaluation environment.

Higher-Order Functions

- A function is considered *higher order*, if
 - it accepts functions as parameters,
 - or it returns a function.
- This mechanism is supported by many programming languages, especially in functional languages.

Functions as Parameters

- On the right, there is an example C code using a function as a parameter.
- Function f is passed as a parameter to g.
- Variable x is defined multiple times.
- In function g, which binding of x should be used?
 - Which environment should be checked for name x?

```
int x = 1;
int f(int y) {
    return x+y;
int g(function<int(int)> h) {
    int x = 2;
    return h(3)+x;
int main(){
    //Functions as parameters
    int x = 4;
    int z = g(f);
```

Deep and Shallow Binding

 Deep Binding: uses the environment active when the link between f and h are made.

Shallow Binding: uses the environment active when the call to f (using h) occurs.

```
int x = 1;
int f(int y) {
    return x+y;
int g(function<int(int)> h) {
    int x = 2;
    (return h(3)+x;)
int main(){
   //Functions as parameters
```

Deep and Shallow Binding

Static Scope + Deep Binding

•
$$h(3) = 4$$
, $g(f) = 6$

Dynamic Scope + Deep Binding

•
$$h(3) = 7$$
, $g(f) = 9$

Dynamic Scope + Shallow Binding

•
$$h(3) = 5$$
, $g(f) = 7$

int x = 1; int f(int y) { return x+y; x = 1 } int g(function<int(int)> h) { int x = 2; return h(3)+x; x = 2 } int main(){ //Functions as parameters

int x = 4;

int z = g(f); x = 4

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What defines the Environment?

- Visibility Rules.
- Exceptions in Visibility Rules need to consider re-defined names, use names after declaration.
- Scope Rules.
- Parameter Passing Modes.
- Binding Policy.

Functions as Results

- Function can return another function as a result.
- With static scope, the call k() is actually calling s, and x = 1 in s.
 - Environment is also considered in the returned function.
- Hence the result of calling_s() is actually a closure.

```
int x = 1;
int s() {
    return x+1;
function<int()> calling_s() {
    return s;
int main(){
    //Functions as results
    int x = 4;
    function<int()> k = calling_s();
    int y = k();
```

Closure

- A Closure is a pair of (expression, environment),
 - which the environment includes all the free variables in the expression.
- Free variables are the variables used in the expression, but not declared in the environment.
 - In Python, they have a special distinction, so that global variables are not free variables.
 - But usually, global variables are free variables, unless they are declared again in the local environment.

Data Types

Data Type

- A **Data Type** is a homogeneous collection of values and a set of operations applicable to the values for manipulation.
 - Homogeneous: Same or similar kind (→ heterogeneous).
 - Values + Operations: Data type is not only about the values, but also includes operations.
 - e.g.) We need different operations for integers, strings and arrays.

Type System

- A programming language has its own *Type System* Information and Rules to manage data types.
- A type system usually consists of
 - A set of predefined types,
 - Mechanisms to support definition of new types,
 - Mechanisms to control types such as *equivalence* rules, *compatibility* rules and *type inference*.

Denotable, Expressible, Storable

- Values are,
 - Denotable, if we can put a name on them.
 - Variable (names), Function (names).
 - Expressible, if we can get them from a complex expression.
 - Numbers, strings, even memory locations in C, which can be appeared in an expression.
 - Storable (or updatable), if we can store them in a variable.
 - Variable vs. Function although code fragments of functions are stored in a disk, we cannot update them in a program.

Static and Dynamic Type Checking

- Dynamic Type Checking: type constraints are checked during runtime.
- Static Type Checking: checking of type constraints are conducted at compile time.
 - No runtime type checking execution is more efficient.
 - Design of static type checking is more complex, and compilation takes longer.
 - But compilation happens only a few times, while executions are frequent.

Static and Dynamic Type Checking

- Static type checking requires conservative type constraints.
 - Type checking is often excessive, so that it reports some errors which won't happen at runtime.
- In the example code, x = "PL" violates type constraints.
 int x = 0;
 if(x > 0)
 - However, this code won't be executed during runtime. x = "PL"; x = 1+2;
- Because determining whether a program causes a type error is undecidable.

Necessity of Combination

- Almost all high-level programming languages are doing both static and dynamic type checking.
- Although a language employs static type checking, it requires dynamic checking for some cases.
 - e.g.) Array index bound check.
 - If an array's size is dynamically decided, then the check for its index boundaries must be dynamic too.

Scalar and Composite Types

- Scalar Type: no aggregation of different values.
 - Booleans, characters, integers, real numbers.
 - Enumerations
 - type days = { Mon, Tue, Wed, Thu, Fri, Sat, Sun }
 - Intervals: 1...10
- Composite Types: Non-scalar types.
 - Record (or structure), Array (or vector), Set, Pointer, Functions, Recursive Types, etc.
 - These types may have different operations.

Type Equivalence

- Name Equivalence two types are equivalent if their names are identical.
- Structural Equivalence two types are equivalent if their structures are identical.
- Declaration Equivalence two types are equivalent if they are declared together.
- Referential Transparency: Two equivalent types can be substituted each other in any context, without change the meaning of programs.
- Modern languages are often using one rule with exceptions.

Name Equivalence

Let's use a pseudo language for type definition.

```
type <type_name> = <expression>;
type Type1 = int;
type Type2 = int;
type Type3 = 1..100;
type Type4 = 1..100;
```

- Name equivalence is very restrictive rule all the types above are different.
- Java, C++ use name equivalence for most of their types.

Structural Equivalence

- Two types are equivalent if they have the same structure.
- More loose constraints.

```
type Type1 = int;
type Type2 = int;
type Type3 = 1..100;
type Type4 = 1..100;
```

- Type1/Type2 are equivalent, and Type3/Type4 are equivalent.
- Java arrays, C arrays and typedef.

Structural Equivalence

- There are some ambiguous cases.
- Different field names.

```
• type Type1 = struct {
    int a;
    int b;
}
type Type2 = struct {
    int n;
    int m;
}
```

• Are Type1/Type2 equivalent? - it depends on the language, but often types with different field names considered different.

Structural Equivalence

Recursive Types.

```
• type Type1 = struct {
    int a;
    Type2 b;
}
type Type2 = struct {
    int a;
    Type1 b;
}
```

• Are Type1/Type2 equivalent? - Type check cannot solve such mutual recursion, hence they are considered not equivalent.

Declaration Equivalence

- In the middle of name and structural equivalence.
- Weak name equivalence: Consider types are equivalent for simple renaming or if they are declared together (e.g. Pascal).

```
• type Type1 = int;
type Type2 = Type1;
type Type3 = 1..100;
type Type4 = 1..100;
```

Type1/Type2 are equivalent, but Type3/Type4 are still different.

Type Compatibility

- Type T is compatible with type S, if a value of type T can be used in any context where a value of type S is used.
- More specifically, types T and S are compatible when,
- 1. Types T and S are equivalent.
 - Referential transparency.
- 2. T's values are the subset of S's values.
 - intervals 1..10, 1..100.

Type Compatibility

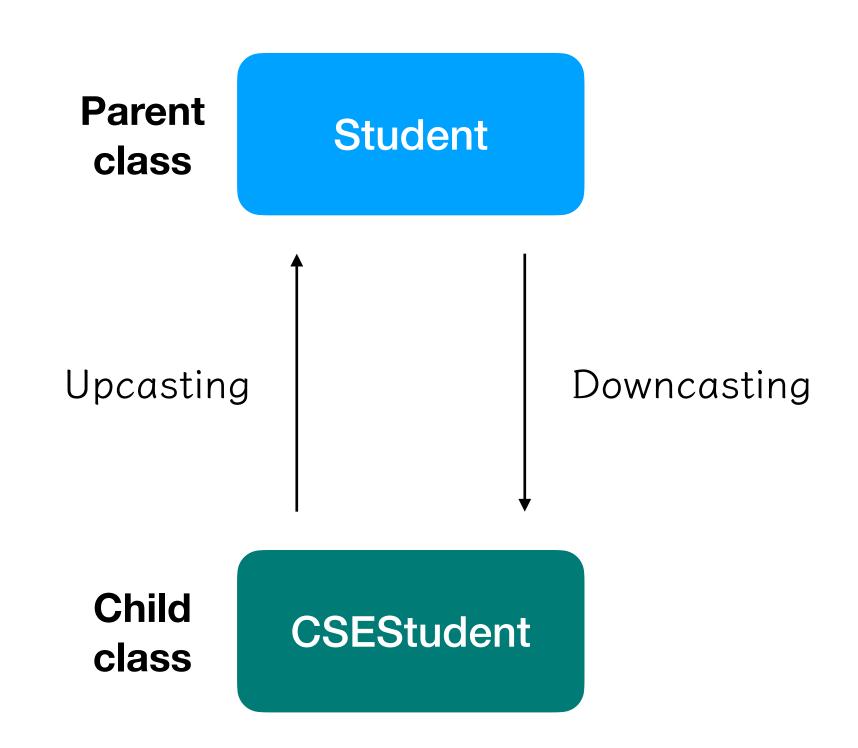
- 3. All the operations of S can be applicable to T.
 - type S = struct { int a; }
 type T = struct { int a; char b; }
 - Only possible operation of S is accessing the field a.
 - T⊄S, but we can apply operations of S by taking only a of T.
- 4. T's values are correspond to values of S, in a canonical fashion.
 - T: int S: float. T is not a subset of S, but we can use int for float (e.g. 2 for 2.0).
- 5. T's values can be converted to values of S with transformation.
 - float can be converted to int by rounding (e.g., rounding down in C).

Type Conversion

- Implicit Conversion (coercion): also called forced conversion. Type conversions are done by the compiler.
 - When types T and S are compatible, conversions are automatically done even programmers didn't specify.
- **Explicit Conversion (cast)**: Programmers explicitly indicate the type conversion.
 - S s = (S) t;

Upcasting vs. Downcasting

- Casting between inherited classes can be possible.
- Upcasting: Converting child to parent.
 - Implicit conversion is possible.
 - e.g.) Student s = new CSEStudent();
- Downcasting: Converting parent to child.
 - Need explicit conversion.
 - e.g.) CSEStudent c = (Student)s;



Type Checking and Inference

- Type Checking: when an expression E and type T are given, verify whether E is of type T.
 - int f(int a) { return a+1; }
 - a+1 should be int.
- Type Inference: only an expression E is given, derive the type of E.
 - def f(a): return a+1
 - 1 is int and + takes two integers, hence a is int, and function f() is int->int.

Type Safety

- All these type checking and inference are to secure type safety of a language.
- A type system (or a language) is *type safe*, when no program can violate the distinction of types defined in the language.
- Theoretically, type safety is more restricted than you think.
 - Unsafe Languages: like C, C++, languages with pointers to access memory directly (memory safety issue).
 - Locally Safe Languages: some languages (e.g.Pascal) contain some unsafe parts.
 - Safe Languages: in theory, these languages don't generate any hidden type errors (e.g. Scheme, ML, Java).

Summary

- Control Abstraction
 - Subprograms
 - Parameter Passing
 - Binding Policy
 - Higher-Order Functions
- Data Types
 - Type Equivalence and Compatibility
 - Type Checking, Inference and Safety