

# Macroeconomic Theory

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## The Supply Side

### New Keynesian Phillips Curve

Remember we have derived the NKPC in terms of marginal cost:

$$\pi_t = \beta E_t\{\pi_{t+1}\} + \lambda (mc_t + \mu)$$

where  $\lambda \equiv \frac{(1-\theta)(1-\beta\theta)}{\theta} \Theta$ ,  $\Theta = \frac{1-\alpha}{1-\alpha+\alpha\epsilon}$

The marginal cost is:

$$mc_t = (w_t - p_t) - (z_t - \alpha n_t + \log(1 - \alpha))$$

## The Supply Side

Using labor supply and technology

We used the labor supply condition:

$$w_t - p_t = \sigma c_t + \varphi n_t$$

Combined with technology  $n_t = \frac{1}{1-\alpha}(y_t - z_t)$  and goods market equilibrium to obtain:

$$mc_t = \left(\sigma + \frac{\varphi+\alpha}{1-\alpha}\right) y_t - \left(1 + \frac{\varphi+\alpha}{1-\alpha}\right) z_t - \log(1 - \alpha)$$

## The Supply Side

Flexible prices and output gap

In the flexible prices equilibrium, real marginal cost is constant and equal to  $-\mu$ :

$$mc = \left(\sigma + \frac{\varphi+\alpha}{1-\alpha}\right) y_t^n - \left(1 + \frac{\varphi+\alpha}{1-\alpha}\right) z_t - \log(1 - \alpha)$$

where  $y_t^n$  is the natural level of output.

Combining with the NKPC, we get the dynamic IS curve:

$$\tilde{y}_t = E_t\{\tilde{y}_{t+1}\} - \frac{1}{\sigma}(i_t - E_t\{\pi_{t+1}\} - r_t^n)$$

where  $\tilde{y}$  is the output gap.

## Notes on the NKM Solution

The three-equation system

Consider the NKM model with:

**Monetary Policy Rule:**

$$i_t = \rho + \phi_\pi \pi_t + v_t$$

**Dynamic IS Curve:**

$$\tilde{y}_t = E_t\{\tilde{y}_{t+1}\} - \frac{1}{\sigma}(i_t - E_t\{\pi_{t+1}\} - r_t^n)$$

**New Keynesian Phillips Curve:**

## Notes on the NKM Solution

### Key definitions

- ▷  $\tilde{y}_t$  is the **output gap**
- ▷  $r_t^n$  is the **natural rate** of real interest rate — the rate that implies zero output gap
- ▷  $r_t^n = \rho - \sigma(1 - \rho_z)\psi_{yz}z_t$

## Household First Order Conditions

Classical model conditions

The first order conditions with respect to  $C_t$  and  $A_t$  are:

**Labor Supply:**

$$w_t - p_t = \sigma c_t + \varphi n_t$$

**Euler Equation:**

$$c_t = E_t\{c_{t+1}\} - \frac{1}{\sigma}(i_t - E_t\{\pi_{t+1}\} - \rho)$$

## Notes on the NKM Solution

### System reduction

Three endogenous variables:  $i_t, \pi_t, \tilde{y}_t$

Two exogenous variables:  $z_t, v_t$

Substitute the monetary policy rule into the IS curve:

$$\tilde{y}_t = E_t\{\tilde{y}_{t+1}\} - \frac{1}{\sigma}(\rho + \phi_\pi \pi_t + v_t - E_t\{\pi_{t+1}\} - r_t^n)$$

Combined with the New Keynesian Phillips Curve:

$$\pi_t = \beta E_t\{\pi_{t+1}\} + \kappa \tilde{y}_t$$

## Notes on the NKM Solution

### Solution guess

Assume a unique solution where endogenous variables respond to state variables:

$$\tilde{y}_t = \psi_{yu} u_t$$

$$\pi_t = \psi_{\pi u} u_t$$

where  $u_t = v_t - (r_t^n - \rho)$  is the difference between the two shocks.

We need to determine the unknown coefficients  $\psi_{yu}$ ,  $\psi_{\pi u}$  through guess and verify.

## Notes on the NKM Solution

Simplified case: monetary shock only

For simplicity, consider  $z_t = 0$  (no technology shock), so  $r_t^n = \rho$  and  $u_t = v_t$

Assume  $v_t \sim N(0, 1)$  is i.i.d. Plugging our guess into the model:

$$\tilde{y}_t = E_t\{\tilde{y}_{t+1}\} - \frac{1}{\sigma}(\phi_\pi \pi_t + u_t - E_t\{\pi_{t+1}\})$$

This becomes:

$$\tilde{y}_t = -\frac{1}{\sigma}(\phi_\pi \psi_{\pi u} + 1)u_t$$

## Notes on the NKM Solution

### Using the NKPC

Using our guess in the NKPC:

$$\pi_t = \beta E_t\{\pi_{t+1}\} + \kappa \tilde{y}_t$$

Substituting the guess:

$$\pi_t = \beta E_t\{\psi_{\pi u} u_{t+1}\} + \kappa \psi_{yu} u_t$$

Since  $E_t u_{t+1} = 0$ :

$$\pi_t \equiv \kappa \psi_{yu} u_t$$

## Notes on the NKM Solution

### Solving for coefficients

To be consistent with our guess, we need:

$$\psi_{yu} = -\frac{1}{\sigma}(\phi_\pi \psi_{\pi u} + 1)$$

$$\psi_{\pi u} = \kappa \psi_{yu}$$

Solving these two equations yields:

$$\psi_{yu} = -\frac{1}{\sigma + \phi_\pi \kappa}$$

## Notes on the NKM Solution

### Uniqueness condition

To ensure unique solution, check eigenvalues of matrix  $A_T$  are less than unity:

$$\begin{bmatrix} \tilde{y}_t \\ \pi_t \end{bmatrix} = A_T \begin{bmatrix} E_t\{\tilde{y}_{t+1}\} \\ E_t\{\pi_{t+1}\} \end{bmatrix} + B_T u_t$$

where  $u_t \equiv \hat{r}_t^n - v_t$  and

$$A_T \equiv \Omega \begin{bmatrix} \sigma & 1 - \beta\phi_\pi \\ \sigma\kappa & \kappa + \beta\sigma \end{bmatrix}; B_T \equiv \Omega \begin{bmatrix} 1 \\ \kappa \end{bmatrix}$$

## Notes on the NKM Solution

### Jump variables intuition

The dynamics require both variables to have free initial values:

- ▷ After a shock, both output gap and inflation can take correct values ensuring unique solution
- ▷ Both variables are **jump variables** (like consumption in Ramsey model)
- ▷ Unlike capital in Ramsey (state variable), these have no predetermined values
- ▷ State variables require eigenvalue larger than unity in the system formulation

## General Solution

Ensuring unique solution

How to solve and ensure unique solution (saddle property)?

Rewrite the system:

$$\begin{bmatrix} E_t\{\tilde{y}_{t+1}\} \\ E_t\{\pi_{t+1}\} \end{bmatrix} = A_D \begin{bmatrix} \tilde{y}_t \\ \pi_t \end{bmatrix} + B_D u_t$$

Decouple dynamics using decomposition:

$$A_D = C \Lambda C^{-1}$$

## General Solution

### System transformation

The system becomes:

$$\begin{bmatrix} E_t\{\tilde{y}_{t+1}\} \\ E_t\{\pi_{t+1}\} \end{bmatrix} = C \Lambda C^{-1} \begin{bmatrix} \tilde{y}_t \\ \pi_t \end{bmatrix} + B_D u_t$$

Premultiply by  $C^{-1}$ :

$$C^{-1} \begin{bmatrix} E_t\{\tilde{y}_{t+1}\} \\ E_t\{\pi_{t+1}\} \end{bmatrix} = \Lambda C^{-1} \begin{bmatrix} \tilde{y}_t \\ \pi_t \end{bmatrix} + C^{-1} B_D u_t$$

## General Solution

Forward iteration

Rearranging:  $X_t = \Lambda^{-1}E_t X_{t+1} - \Lambda^{-1}Du_t$

Using Law of Iterated Expectations  $E_t E_{t+1} = E_t$ :

$$X_t = \sum_{i=1}^{\infty} (\Lambda^{-1})^i E_t [X_{t+i} - Du_{t+i}] - \Lambda^{-1}Du_t$$

Since  $E_t [Du_{t+i}] = 0$  for  $i > 0$  and both eigenvalues greater than 1:

$$X_t = -\Lambda^{-1}Du_t$$

Transforming back to original system:

# Optimal Price Condition

## Basic formulation

The optimal price condition gives:

$$p_t^* = (1 - \beta\theta) \sum_{k=0}^{\infty} (\beta\theta)^k E_t \left( (\psi_{t+k} + \mu) - \frac{\alpha\epsilon}{1-\alpha} (p_t^* - p_{t+k}) \right)$$

which can be rewritten as:

$$p_t^* = (1 - \beta\theta) \sum_{k=0}^{\infty} (\beta\theta)^k E_t (\Theta(\psi_{t+k} - p_{t+k} + \mu) + p_{t+k})$$

$$\text{where } \Theta = \frac{1-\alpha}{1-\alpha+\alpha\epsilon}$$

## Optimal Price Condition

Recursive form

The recursive form is:

$$p_t^* = (1 - \beta\theta) (\Theta(\psi_t - p_t + \mu) + p_t) + \beta\theta E_t p_{t+1}^*$$

Subtracting  $p_{t-1}$ :

$$p_t^* - p_{t-1} = (1 - \beta\theta) (\Theta(\psi_t - p_t + \mu) + p_t) - p_{t-1} + \beta\theta E_t p_{t+1}^*$$

Using  $\pi_t = p_t - p_{t-1} = (1 - \theta)(p_t^* - p_{t-1})$  to get the NKPC:

$$\pi_t = \lambda(\psi_t - p_t + \mu) + \beta E_t \{\pi_{t+1}\}$$

## NK-Phillips Curve

Final form

Replacing in the NKPC:

$$\pi_t = \beta E_t\{\pi_{t+1}\} + \lambda (mc_t + \mu)$$

where:

- ▷  $mc_t = \psi_t - p_t$  is the marginal cost
- ▷  $\lambda \equiv \frac{(1-\theta)(1-\beta\theta)}{\theta} \Theta$
- ▷  $\Theta = \frac{1-\alpha}{1-\alpha+\alpha\epsilon}$

(Solve forward to get the forward-looking structure)

# Equilibrium

Goods market clearing

Clearing in the continuum of goods markets:

$$Y_t(i) = C_t(i)$$

Aggregating:

$$Y_t \equiv \left( \int_0^1 Y_t(i)^{1-\frac{1}{\epsilon}} di \right)^{\frac{\epsilon}{\epsilon-1}} = C_t$$

In log-linear form:

## Labor Market Clearing

Aggregation across firms

Labor market clearing:

$$N_t = \int_0^1 N_t(i) di$$

Using firm labor demand:

$$N_t = \int_0^1 \left( \frac{Y_t(i)}{Z_t} \right)^{\frac{1}{1-\alpha}} di$$

This gives:

## Labor Market Clearing

Labor supply and marginal cost

The labor supply is:

$$w_t - p_t = \sigma c_t + \varphi n_t$$

Using labor demand and technology:

$$mc_t = (w_t - p_t) - (z_t - \alpha n_t + \log(1 - \alpha))$$

Substituting:

$$mc_t = (\sigma y_t + \varphi n_t) - (z_t - \alpha n_t + \log(1 - \alpha))$$

## Natural Level of Output and Markup Gap

Flexible prices benchmark

The natural level of output prevails with flexible prices (constant markup):

$$mc = \left( \sigma + \frac{\varphi+\alpha}{1-\alpha} \right) y_t^n - \left( 1 + \frac{\varphi+\alpha}{1-\alpha} \right) z_t - \log(1-\alpha)$$

The marginal cost gap is therefore:

$$(mc_{t|t} - mc) = \left( \sigma + \frac{\varphi+\alpha}{1-\alpha} \right) (y_t - y_t^n)$$

# The New Keynesian Phillips Curve

## Final specification

Substituting the marginal cost gap gives the NKPC:

$$\pi_t = \beta E_t\{\pi_{t+1}\} + \lambda \left( \sigma + \frac{\varphi + \alpha}{1 - \alpha} \right) (y_t - y_t^n)$$

More compactly:

$$\pi_t = \beta E_t\{\pi_{t+1}\} + \kappa \tilde{y}_t$$

This is the first equation of our NK model.

## The C-S Condition (Dynamic IS)

From Euler equation to output gap

The Euler condition plus goods market equilibrium gives:

$$y_t = E_t\{y_{t+1}\} - \frac{1}{\sigma}(i_t - E_t\{\pi_{t+1}\} - \rho)$$

Rewritten in terms of output gap:

$$\tilde{y}_t = E_t\{\tilde{y}_{t+1}\} - \frac{1}{\sigma}(i_t - E_t\{\pi_{t+1}\} - r_t^n)$$

where  $r_t^n = \rho - \sigma(1 - \rho_z)\psi_{yz}z_t$  is the **natural rate of interest** (Wicksellian)

## The C-S Condition (Dynamic IS)

Definition of natural rate

Definition of  $r_t^n$ :

$$y_t^n = E_t [y_{t+1}^n] - \frac{1}{\sigma} (r_t^n - \rho)$$

Therefore:

$$r_t^n = \rho + \sigma E_t [y_{t+1}^n - y_t^n]$$

Using the solution  $y_t^n = \psi_y + \psi_{yz} z_t$  and  $z_t = \rho_z z_{t-1} + \epsilon_t^z$

Express the Dynamic IS in terms of  $\tilde{y} = y - y^n$

## The Policy Block

### Completing the model

To determine the nominal side of the economy, we need an equation for the nominal interest rate.

We need a rule that gives **determinacy** of equilibrium.

Without a monetary policy rule, the nominal variables would be indeterminate in this model.

## Interest Rate Rule

### Simple Taylor rule

Consider the following rule:

$$i_t = \rho + \phi_\pi \pi_t + v_t$$

where  $v_t$  is a monetary policy shock.

The complete model is now:

$$\tilde{y}_t = E_t\{\tilde{y}_{t+1}\} - \frac{1}{\sigma}(i_t - E_t\{\pi_{t+1}\} - r_t^n)$$

$$\pi_t = \beta E_t\{\pi_{t+1}\} + \kappa \tilde{y}_t$$

# Dynamics

## Matrix representation

The system is:

$$\begin{bmatrix} \tilde{y}_t \\ \pi_t \end{bmatrix} = A_T \begin{bmatrix} E_t\{\tilde{y}_{t+1}\} \\ E_t\{\pi_{t+1}\} \end{bmatrix} + B_T u_t$$

where  $u_t \equiv \hat{r}_t^n - v_t$  and:

$$A_T \equiv \Omega \begin{bmatrix} \sigma & 1 - \beta\phi_\pi \\ \sigma\kappa & \kappa + \beta\sigma \end{bmatrix}; B_T \equiv \Omega \begin{bmatrix} 1 \\ \kappa \end{bmatrix}$$