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# 1 Topics for First Midterm

### 1.1 Basic Definations

norm

see note basic:definations:norm

inner product

see note basic:definations:inner product

metric / distance functions

see note basic:definations:metric

open and closed subset of metric space

see note basic:definations:metricspace-openset and basic:definations:metricspace-closedset

### 1.2 Basic Theorems

EVT Extreme value theorem

IVT Intermediate value theorem

MVT Mean value theorem

IVFT Inverse Function Theorem

IPFT Implicit Function Theorem

# 1.3 Basic topology of metric spaces

closure

the set with all its limit points

interior

union of all open set contained in A

exterior

union of all open set disjoint from A

boundary

points that are neither interior nor exterior

 $\mathbf{limits} \ f: A \subseteq X \to Y$ 

 $f(x) \to y_0$  as  $x \to x_0$  if  $\forall$  open  $V \ni y_0 \exists$  open  $U \ni x_0 [x \in U \cap A \land x \neq x_0 \to f(x) \in V]$ 

**continuity** f is cts at  $x_0$  if  $x_0$  is isolated point or  $(\lim_{x\to x_0} f(x)) = f(x_0)$ 

Cauchy sequences A sequences  $\langle x_i \rangle$  is Cauchy if

$$\forall \varepsilon \exists N [n, m > N \implies d(x_m, x_n) < \varepsilon]$$

**completeness** A metric space X is complete if every Cauchy sequences converge (to some point in X).

**compact sets** every open cover of X has a finite subcover

**connected sets** X cannot be divided into two disjoint nonempty closed/open/clopen sets.

**relatively open sets** p26 A is relatively open in  $Y \subseteq X$  if  $\exists$  open  $U \subseteq X$  such that  $A = U \cap Y$ 

**Proposition**  $f: X \to Y$  is cts iff  $\forall$  open  $V \in Y$ ,  $F^{-1}(V)$  is open in X. Similarly for closed.

Bolzano-Weierstrass property

A subset  $E \in \mathbb{R}^n$  satisfies the BW property if every suquence has a convergent subsequence.

Bolzano-Weierstrass theorem  $E \in \mathbb{R}^n$  satisfies the BW property iff E is closed and bounded.

**Heine-Borel theorem**  $E \in \mathbb{R}^n$  is compact iff E is closed and bounded.

**Application/(topological invariant)** Suppose  $f: X \to Y$  is continuous and X is compact then f(X) is compact

**Extreme value theorem** Suppose  $f: X \to \mathbb{R}$  is continuous and X is compact then  $\exists x_0 \in X$  such that  $f(x) \leq f(x_0) \forall x \in X$ .

**Path connected** A set E is path connected if  $\forall x, y \in E$ ,  $\exists$  continuous map  $f : [a, b] \to E$  such that f(a) = x and f(b) = y.

**Proposition** If E is connected, and  $f: E \to Y$  is continuous then f(E) is connected

**Proposition** If E is path connected then E is connected.

**Intermediate Value Theorem** Suppose  $E \in \mathbb{R}$  is connected and  $f: E \to \mathbb{R}$  is continuous. Suppose f(x) = a and f(y) = b for some  $x, y \in E$  and a < b. Then  $\forall a < c < b \exists$  some  $z \in E$  such that f(z) = c.

The  $\epsilon$ -neighborhood theorem Let X be a compact subspace of  $\mathbb{R}$ ; Let U be an open set of  $\mathbb{R}^n$  containing X, Then there is an  $\epsilon > 0$  such that the  $\epsilon$ -neighborhood of X is contained in U.

Cauchy-Schwarz inequality; all norms on a finite-dimensional vector space are equivalent; Bolzano Weierstrass theorem; Heine-Borel theorem; the con- tinuous image of a compact set is compact; the continuous image of a connected set is connected; intermediate value theorem; extreme value theorem. minima and maxima of continuous functions on compact sets

### 1.4 Differentiation

#### **Derivative**

- definition of the derivative
- partial derivatives
- directional derivatives

chain rule

- $(f \circ g) = (f' \circ g) \cdot g'$
- $\bullet \ \frac{df}{dx} = \frac{df}{dg} \cdot \frac{dg}{dx}$

continuity and differentiability

- differentiable implies continuity
- $\bullet$   $C^1$  implies differentiable
- $\bullet$   $C^2$  implies equality of mixed partial derivatives

Jacobian matrix

$$Jf = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \cdots & \frac{\partial f_m}{\partial x_n} \end{bmatrix}$$

continuously differentiable functions TODO

higher order derivatives TODO

gradient TODO

geometry of the Jacobian, the rows, the columns TODO

## 1.5 Max-min problems

Multi-index Notation see note

Taylor's theorem[TODO] see note

basic facts about the gradient

critical points

the Hessian

quadratic forms

classification of critical points

max-min problems with constraints

Lagrange multipliers

# 1.6 Instructor's comment

General Comments: Should you memorize proofs of theorems? It is very hard to memorize all proofs of all theorems. In the long run, it is much more efficient, as well as useful and interesting, to first try to understand the proofs, and internalize the methods of proof, as well as possible; then to remember just an outline of the proof, or some key idea; roughly speaking, the minimum you would need to allow yourself to reconstruct the proof out of your base of general knowledge/understanding. Remember: it is important to know not simply whether something is true, but why it is true.

# 2 Basic knowledge

## 2.1 Definations

**norm** A function  $p: V \to \mathbb{R}$  such that

For all  $a \in F$  and all  $u, v \in V$ 

- $p(v) \ge 0 \land [p(v) = 0 \iff v = 0]$  (separates points)
- p(av) = |a|p(v) (absolute homogeneity)
- $p(u+v) \le p(u) + p(v)$  (triangle inequality)

inner product A function  $\langle x,y \rangle: V \times V \to \mathbb{R}$  such that

For all  $x, y, z \in V$  and  $c \in \mathbb{F}$ .

- $\bullet \langle x, y \rangle = \langle y, x \rangle$
- $\langle x + y, z \rangle = \langle x, z \rangle + \langle y, z \rangle$
- $\langle cx, y \rangle = c \langle x, y \rangle = \langle x, cy \rangle$
- $\langle x, x \rangle > 0$  if  $x \neq 0$

**metric** A function  $d: X \times X \to \mathbb{R}$  such that

For all  $x, y, z \in X$ 

- $d(x,y) \ge 0$
- $d(x,y) = 0 \iff x = y$
- d(x,y) = d(y,x)
- $d(x,z) \le d(x,y) + d(y,z)$

 $\epsilon$ -neighborhood  $\mathbf{U}(x;\epsilon) = \{y | d(x,y) < \epsilon\}$ 

open set in metric space A set  $U \subseteq X$  is said to be open in X if

 $\forall x \in U \exists \epsilon > 0 [\mathbf{U}(x; \epsilon) \subseteq U]$ 

note that finite intersections and arbitrary unions of open set are open set

closed set in metric space A set contains all its limit point.

note that closed set is complement of open set in topology

### 2.2 Theorems

#### Extreme value theorem

Suppose  $f: X \to \mathbb{R}$  is continuous and X is compact,

then  $\exists x_0 \in X$  such that  $\forall x \in X. f(x) \leq f(x_0)$ .

### Intermediate Value Theorem

Suppose  $E \in \mathbb{R}$  is connected and  $f: E \to \mathbb{R}$  is continuous.

Suppose f(x) = a and f(y) = b for some  $x, y \in E$  and a < b.

Then  $\forall a < c < b \exists$  some  $z \in E$  such that f(z) = c.

# Mean Value Theorem

Suppose  $\phi: [a,b] \to \mathbb{R}$  is

- continuous at each point of **closed** interval [a, b]
- differentiable at each point of **open** interval (a, b)

Then there exists a point  $c \in (a, b)$  such that  $\phi(b) - \phi(a) = \phi'(c)(b - a)$ .

# 3 Abbreviation

 $\mathbf{cts} \ \, \mathbf{Continuous}$ 

msr Measure

# 4 Notation and Terminology

# 4.1 Derivative

```
Df(a) derivative of f at a f'(a; u) directional derivative of f at a respect to vector u. D_j f(a) j^{\text{th}} \text{partial derivative of } f \text{ at } a. f_i i^{\text{th}} \text{ component function of } f. \vec{\nabla} g gradient of g, \vec{\nabla} g = \mathbf{grad} g = \sum_i (D_i g) e_i Jf Jacobian matrix, J_{ij} = D_j f_i(a)
```

# 4.2 Multi-index Notation

$$\alpha = (\alpha_1, \dots, \alpha_n)$$
$$|\alpha| = \alpha_1 + \dots + \alpha_n$$
$$\alpha! = \alpha_1! \dots \alpha_n!$$
$$x^{\alpha} = x_1^{\alpha_1} \dots x_n^{\alpha_n}$$

# 5 Measure zero

### measure zero

Let  $A \subseteq \mathbb{R}^n$ . We say A has measure zero in  $\mathbb{R}^n$  if for every  $\epsilon > 0$ , there is a covering  $Q_1, Q_2, \ldots$  of A by countably many rectangles such that  $\sum_{i=1}^{\infty} v(Q_i) < \epsilon$ . If this inequality holds, we often say that the <u>total volume</u> of the rectangles  $Q_1, Q_2, \ldots$  is less than  $\epsilon$ .

### oscillation

Given  $a \in Q$  define  $A_{\delta} = \{f(x)|x \in Q \land |x-a| < \delta\}$ . Let  $M_{\delta}(f) = \sup A_{\delta}$ , and let  $m_{\delta}(f) = \inf A_{\delta}$ , define oscillation at f by  $\operatorname{osc}(f;a) = \inf_{\delta>0} [M_{\delta}(f) - m_{\delta}(f)]$ .

• f is cts at a iff osc(f; a) = 0

### 5.1

### 5.1.1 Theorem {Munkers-11.1}

- 1. If  $B \subseteq A$  and A has measure zero in  $\mathbb{R}^n$ , the so does B.
- 2. Let A be the union of the collection of sets  $A_1, A_2, \ldots$  If each  $A_i$  has measure zero, so does A.
- 3. A set A has measure zero in  $\mathbb{R}^n$  if and only i

# 5.1.2 Theorem {Munkers-11.2}

# 5.2 Taylor's theorem[TODO]

TODO, theorem, remainder

# 6 Differentiation

### 6.1 Derivative

#### 6.1.1 Differentiable

f is differentiable at a if there is an n by m matrix B such that

$$\frac{f(a+h) - f(a) - B \cdot h}{|h|} \to 0 \quad \text{as} \quad h \to 0$$

The matrix B is unique.

#### 6.1.2 Directional derivative

Given  $u \in \mathbb{R}^m$  which  $u \neq 0$  define

$$f'(a; u) = \lim_{t \to 0} \frac{f(a + tu) - f(a)}{t}$$

Provide the limit exists.

#### 6.1.3 Partial derivative

Define the  $j^{\text{th}}$  partial derivative of f at a to be the directional derivative of f at a with respect to the vector  $e_j$ , provide derivative exists.

$$D_j f(a) = \lim_{t \to 0} \frac{f(a + te_j) - f(a)}{t}$$

### 6.1.4 Continuously Differentiable

A function is  $C^1$  if all of its partial derivatives are continous. A function is  $C^r$  if all of its partial derivatives are  $C^{r-1}$ .

### 6.2 Theorems

### Munkers.5.1

If f is differentiable at a then all directional derivative of f at a exist and  $f'(a; u) = Df(a) \cdot u$ 

### Munkers.5.2

If f is differentiable at a then f is continuous at a.

#### Munkers.5.3

If f is differentiable at a then  $Df(a) = [D_1f(a) \quad D_2f(a) \quad \cdots \quad D_mf(a)].$ 

### Munkers.5.4

- a. [f is differentiable at a]  $\Leftrightarrow \forall i[f_i \text{ is differentiable at } a]$ .
- b. If f is differentiable at a, then its derivative is the n by m matrix whose  $i^{\text{th}}$  row is the derivative of the function  $f_i$ .  $(Df(a))_i = Df_i(a)$

## 6.3 Continuously Differentiable Functions

### Munkers 6.1

If  $f:[a,b]\to\mathbb{R}$  is continuous on [a,b] and differentiable on (a,b), then there exists  $c\in(a,b)$  such that f(b)-f(a)=f'(c)(b-a).

### Munkers 7.3

Let A be open in  $\mathbb{R}^m$ ; let  $f: A \to \mathbb{R}$  be differentiable on A. If A contains the line segment with end points a and a+h, then there is a point c=a+th with 0 < t < 1 of this line segment such that f(a+h) - f(a) = (Df(c))h.

#### Munkers 6.2

Let A be open in  $\mathbb{R}^m$ . Suppose that the partial derivative  $D_i f_i(x)$  of the component function of f exists at each point x of A and are continuous on A. Then f is differentiable at each point of A.

### Munkers 6.3

Let A be open in  $\mathbb{R}^m$ , let  $f: A \to \mathbb{R}$  be a function of class  $\mathbb{C}^2$ . Then for each  $a \in A$ :  $D_k D_i f(a) = D_j D_k f(a)$ .

## 6.4 Inverse Function Theorem

Let A be open in  $\mathbb{R}^n$ . Let  $f: A \to \mathbb{R}^n$  be of class  $C^r$ .

**IF** Df(x) is invertible at  $a \in A$ .

**THEN** There exists a neighborhood of a such that

- $f|_U$  is injective AND f(U) = V open in  $\mathbb{R}^n$
- the inverse function is of class  $C^r$
- $f^{-1}(y) = [f'(f^{-1}(y))]^{-1}$

# 6.5 Implicit Function Theorem

### Munkers 9.1

Let A be open in  $\mathbb{R}^{k+n}$ , B be open in  $\mathbb{R}^k$ .

Let  $f:A\to\mathbb{R}^n,\,g:B\to\mathbb{R}^n$  be differentiable.

Write f in the form f(x,y), for  $x \in \mathbb{R}^k$  and  $y \in \mathbb{R}^n$ .

IF f(x, g(x)) = 0 AND  $\frac{\partial f}{\partial y}$  is invertible

THEN 
$$Dg(x) = -\left[\frac{\partial f}{\partial y}(x,g(x))\right]^{-1} \cdot \frac{\partial f}{\partial x}(x,g(x))$$

Suppose  $f: A \to \mathbb{R}^n$  be of class  $C^r$ .

Write f in the form f(x, y), for  $x \in \mathbb{R}^k$  and  $y \in \mathbb{R}^n$ .

**IF** 
$$(a,b) \in A$$
 AND  $f(a,b) = 0$  AND  $\det \frac{\partial f}{\partial y}(a,b) \neq 0$ 

**THEN** There exists  $B \in \mathbb{R}^k$ ,  $a \in B$  and a unique  $g : B \to \mathbb{R}^n$  such that g(a) = b AND  $\forall x \in B. f(x, g(x)) = 0$  AND g is  $C^r$ 

# 7 Integration

# 7.1 Fundamental theorem of Calculus

- If f is continuous on [a, b], and if  $F(X) = \int_a^x f$  for  $x \in [a, b]$ , then F'(x) exists and equals f(x).
- If ...