Single-Source Shortest Path

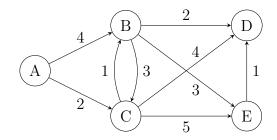


Figure 1: A weighted directed graph G_2

1. The Bellman-Ford algorithm

```
Bellman-Ford(G, w, s)
    // initialization
 1
 2
    for each vertex v \in V
 3
         v.d = +Infty
         v.pi = Nil
 4
 5
    s.d = 0
    for i = 1 to |V| - 1
 6
 7
         for each edge (u, v) \in E
              // relax if needed
 8
 9
              if v.d > u.d + w(u, v)
10
                    v.d = u.d + w(u, v)
                   v.pi = u
11
12
    // check whether there is negative-weight cycle
13
    for each edge (u, v) \in E
         if v.d > u.d + w(u, v)
14
15
              return False
    return True, \{v.d : v \in V\}, \{v.pi : v \in V\}
```

	d					pi				
	Α	В	С	D	Е	A	В	С	D	Е
Init	0	∞	∞	∞	∞	Nil	Nil	Nil	Nil	Nil
1										
2										
3										
4										
Check										

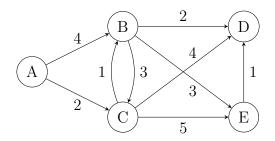


Figure 2: A weighted directed graph G_2

2. Dijkstra's algorithm

```
Dijkstra(G, w, s)
    // initialization
 2
    for each vertex v \in V
         v.d = +Infty
 3
 4
         v.pi = Nil
    s.d = 0
 5
    /\!\!/ priority queue keyed by d
 6
    Q = V
 7
 8
    while Q not Empty
         u = \text{Extract-Min}(Q)
 9
         for each edge (u, v) \in E
10
               // relax if needed
11
               if v.d > u.d + w(u, v)
12
13
                    v.d = u.d + w(u, v)
                    v.pi = u
14
15
    return \{v.d : v \in V\}, \{v.pi : v \in V\}
```