# **Gradient Descent**

## Part 1

 $\min f(\mathbf{x})$ 

- $f(\mathbf{x})$  is continuously differentiable.
- $f(\mathbf{x})$  is convex.

**Definition:** A set C is convex if the line segment between any two points in C lies in C. that is  $\forall x_1, x_2 \in C$ , and  $\forall \theta \in [0, 1]$ , we have  $\theta x_1 + (1 - \theta)x_2 \in C$ .

**Definition:** A function  $f: \mathbb{R}^n \to \mathbb{R}$  is convex if dom f is convex and if  $\mathbf{x}, \mathbf{y} \in \mathrm{dom} f$  and  $\theta \in [0,1]$ , we have  $f(\theta \mathbf{x} + (1-\theta)\mathbf{y}) \leq \theta f(\mathbf{x}) + (1-\theta)f(\mathbf{y})$ .

**Definition:** A function is strict convex if strict inequality holds where  $\mathbf{x} \neq \mathbf{y}$  and  $\theta \in [0, 1]$ .

**Definition:** A function is strongly convex with parameter u if  $f - \frac{u}{2} ||\mathbf{x}||^2$  is convex.

**Theorem 1:** Suppose that f is continuously differentiable. Then f is convex if and only if  $\operatorname{dom} f$  is convex and  $f(\mathbf{y}) \geq f(\mathbf{x}) + \langle \nabla f(\mathbf{x}), \mathbf{y} - \mathbf{x} \rangle, \forall \mathbf{x}, \mathbf{y} \in \operatorname{dom} f$ .

**Proof:** 

 $(\Rightarrow)$ 

$$egin{aligned} f(\mathbf{x} + heta(\mathbf{y} - \mathbf{x})) &\leq f(\mathbf{x}) + heta[f(\mathbf{y}) - f(\mathbf{x})] \ f(\mathbf{y}) - f(\mathbf{x}) &\geq \lim_{ heta o 0} rac{f(\mathbf{x} + heta(\mathbf{y} - \mathbf{x}))}{ heta} \ ($$
方向导数  $) &= \langle 
abla f(\mathbf{x}), \mathbf{y} - \mathbf{x} 
angle \end{aligned}$ 

 $(\Leftarrow)$ 

$$\mathbf{z} = \theta \mathbf{x} + (1 - \theta) \mathbf{y}$$

$$f(\mathbf{x}) > f(\mathbf{z}) + \langle \nabla f(\mathbf{z}), \mathbf{x} - \mathbf{z} \rangle$$
 (1)

$$f(\mathbf{y}) \ge f(\mathbf{z}) + \langle \nabla f(\mathbf{z}), \mathbf{y} - \mathbf{z} \rangle$$
 (2)

 $\theta(1) + (1 - \theta)(2)$ 可得。

**Corollary:** Suppose f is continuously differentiable. Then f is convex iff  $\operatorname{dom} f$  is convex and  $\langle \nabla f(\mathbf{x}) - \nabla f(\mathbf{y}), \mathbf{x} - \mathbf{y} \rangle \geq 0$ .

**Theorem 2:** Suppose that f is continuously differentiable. Then f is convex iff  $\mathrm{dom} f$  is convex and  $\nabla^2 f(\mathbf{x}) \geq 0$ .

**Proof:** 

 $(\Rightarrow)$ 

Let  $\mathbf{x}_t = \mathbf{x} + t\mathbf{s}$ , t > 0. Then

 $(\Leftarrow)$ 

$$egin{aligned} g(t) &= f(\mathbf{x} + t\mathbf{s}) \ g'(0) &= \langle 
abla f(\mathbf{x}), \mathbf{s} 
angle \ g''(0) &= \langle 
abla^2 f(\mathbf{x}), \mathbf{s} 
angle \ g''(0) &= \langle 
abla^2 f(\mathbf{x}), \mathbf{s} 
angle \ g''(0) &= \int_0^1 g'(t) dt \ &= g(0) + \int_0^1 [g'(0) + \int_0^t g''(\tau) d au] dt \ &\geq g(0) + g'(0) \ f(\mathbf{x} + \mathbf{s}) &\geq f(\mathbf{x}) + \langle 
abla f(\mathbf{x}), \mathbf{s} 
angle \end{aligned}$$

**Theorem 3:** Suppose f is continuously differentiable. Then  $\mathbf{x}^* \in \arg\min_{\mathbf{x}} f(\mathbf{x})$  iff  $\nabla f(\mathbf{x}^*) = 0$ ,  $f(\mathbf{y}) \geq f(\mathbf{x}) + \langle \nabla f(\mathbf{x}), \mathbf{y} - \mathbf{x} \rangle = f(\mathbf{x})$ .

#### Part 2

$$\min f(\mathbf{x})$$

- The objective function  $f(\mathbf{x})$  is continuously differentiable.
- $f(\mathbf{x})$  is convex.
- ullet  $\exists \mathbf{x}^* \in \mathrm{dom} f$ , s.t.  $f(\mathbf{x}^*) = f^* = \min f(\mathbf{x})$ .
- The gradient of f is Lipschitz continuous, that is,  $\|\nabla f(\mathbf{x}) \nabla f(\mathbf{y})\| \leq L\|\mathbf{x} \mathbf{y}\|$ , L > 0.

## **Algorithm: Gradient Descent**

Input: An initial point  $\mathbf{x_0}$ , a constant  $\alpha \in (0, \frac{2}{L})$ , k = 0 while the termination condition does not hold, do k = k + 1  $\mathbf{x_{k+1}} = \mathbf{x_k} - \alpha \nabla f(\mathbf{x_k})$ 

end while

# **Convergence Rate**

**Definition:** Suppose that the sequence  $\{a_k\}$  converges to a number L. Then, the sequence is said to converge linearly to L if there exists a number  $\mu \in (0,1)$ , s.t.  $\lim_{k \to \infty} \frac{|a_{k+1} - L|}{|a_k - L|} = \mu$ .

**Lemma 1:** Suppose that a function  $f \in C^1$ . If  $\nabla f$  is Lipschitz continuous with Lipschitz constant L, then

$$f(\mathbf{y}) \leq f(\mathbf{x}) + \langle 
abla f(\mathbf{x}), \mathbf{y} - \mathbf{x} 
angle + rac{L}{2} \|\mathbf{y} - \mathbf{x}\|^2.$$

**Proof:** 

$$\begin{split} f(\mathbf{y}) - f(\mathbf{x}) &= \int_{\mathbf{x}}^{\mathbf{y}} \nabla f(\mathbf{z}) \mathbf{dz} \\ &= \int_{0}^{1} \langle \nabla f(\mathbf{x} + t(\mathbf{y} - \mathbf{x})), \mathbf{y} - \mathbf{x} \rangle dt \\ &= \langle \nabla f(\mathbf{x}), \mathbf{y} - \mathbf{x} \rangle + \int_{0}^{1} \langle \nabla f(\mathbf{x} + t(\mathbf{y} - \mathbf{x})) - \nabla f(\mathbf{x}), \mathbf{y} - \mathbf{x} \rangle dt \\ &\leq \langle \nabla f(\mathbf{x}), \mathbf{y} - \mathbf{x} \rangle + \int_{0}^{1} \|\nabla f(\mathbf{x} + t(\mathbf{y} - \mathbf{x})) - \nabla f(\mathbf{x})\| \|\mathbf{y} - \mathbf{x}\| dt \\ &\leq \langle \nabla f(\mathbf{x}), \mathbf{y} - \mathbf{x} \rangle + L \|\mathbf{y} - \mathbf{x}\|^{2} \int_{0}^{1} t dt \\ &= \langle \nabla f(\mathbf{x}), \mathbf{y} - \mathbf{x} \rangle + \frac{L}{2} \|\mathbf{y} - \mathbf{x}\|^{2} \end{split}$$

(与凹凸性无关)

**Lemma 2** (**Descent Lemma**): Suppose that a function  $f \in C^1$ . If  $\nabla f$  is Lipschitz continuous with Lipschitz constant L > 0, then  $\forall \{\mathbf{x_k}\}$  generated by the Gradient Descent Algorithm satisfies

$$f(\mathbf{x_{k+1}}) \leq f(\mathbf{x_k}) - lpha(1 - rac{Llpha}{2}) \|
abla f(\mathbf{x_k})\|^2.$$

(这也是为什么算法约定 $\alpha \in (0, \frac{2}{L})$ )

下面证明算法可以收敛到最小值,在前提条件下,可以考虑证明:

$$\lim_{k o \infty} 
abla f(\mathbf{x_k}) = 
abla f(\lim_{k o \infty} \mathbf{x_k}) = 0.$$

#### **Proof:**

由Lemma 2,

$$\begin{split} \|\nabla f(\mathbf{x_k})\|^2 &\leq \frac{f(\mathbf{x_k}) - f(\mathbf{x_{k+1}})}{\alpha(1 - \frac{L\alpha}{2})} \\ \sum_k \|\nabla f(\mathbf{x_k})\|^2 &\leq \frac{f(\mathbf{x_0}) - f(\mathbf{x_{k+1}})}{\alpha(1 - \frac{L\alpha}{2})} \\ &\leq \frac{f(\mathbf{x_0}) - f^*}{\alpha(1 - \frac{L\alpha}{2})} \end{split}$$

这个求和存在固有上界,故

$$\lim_{k o \infty} 
abla f(\mathbf{x_k}) = 0$$

# **Efficiency and limitations**

**Theorem:** Consider the Problem  $(\min f(x))$  and the sequence generated by the Gradient Descent Algorithm. Then the sequence value  $f(\mathbf{x_k})$  tends to the optimum function value in a rate of  $O(\frac{1}{k})$ .

1. If 
$$\alpha \in (0, \frac{1}{L})$$

$$f(\mathbf{x_k}) - f^* \leq rac{1}{k}(rac{1}{2lpha}\|\mathbf{x_0} - \mathbf{x}^*\|^2)$$

2. If 
$$lpha \in (rac{1}{L},rac{2}{L})$$

$$f(\mathbf{x_k}) - f^* \leq rac{1}{k}(rac{1}{2lpha}\|\mathbf{x_0} - \mathbf{x}^*\|^2 + rac{Llpha - 1}{2 - Llpha}(f(\mathbf{x_0}) - f(\mathbf{x}^*)))$$

**Proof:** 

As 
$$\mathbf{x_{k+1}} = \mathbf{x_k} - \alpha \nabla f(\mathbf{x_k})$$
 and  $f(\mathbf{y}) \leq f(\mathbf{x}) + \langle \nabla f(\mathbf{x}), \mathbf{y} - \mathbf{x} \rangle + \frac{L}{2} \|\mathbf{y} - \mathbf{x}\|^2$ , 
$$f(\mathbf{x_{k+1}}) \leq f(\mathbf{x_k}) - (\frac{1}{\alpha} - \frac{L}{2}) \|\mathbf{x_{k+1}} - \mathbf{x_k}\|^2$$
$$f(\mathbf{x_{k+1}}) - f^* \leq f(\mathbf{x_k}) - f^* - (\frac{1}{\alpha} - \frac{L}{2}) \|\mathbf{x_{k+1}} - \mathbf{x_k}\|^2$$

Consider the convexity of f,

$$\begin{split} f(\mathbf{x_{k+1}}) - f(\mathbf{x^*}) &\leq \langle \nabla f(\mathbf{x_k}), \mathbf{x_k} - \mathbf{x^*} \rangle - (\frac{1}{\alpha} - \frac{L}{2}) \| \mathbf{x_{k+1}} - \mathbf{x_k} \|^2 \\ &= -\frac{1}{\alpha} \langle \mathbf{x_{k+1}} - \mathbf{x_k}, \mathbf{x_k} - \mathbf{x^*} \rangle - (\frac{1}{\alpha} - \frac{L}{2}) \| \mathbf{x_{k+1}} - \mathbf{x_k} \|^2 \\ &= -\frac{1}{2\alpha} (\| \mathbf{x_{k+1}} - \mathbf{x^*} \|^2 - \| \mathbf{x_{k+1}} - \mathbf{x_k} \|^2 - \| \mathbf{x_k} - \mathbf{x^*} \|^2) - (\frac{1}{\alpha} - \frac{L}{2}) \| \mathbf{x_{k+1}} - \mathbf{x_k} \|^2 \\ &= \frac{1}{2\alpha} (\| \mathbf{x_k} - \mathbf{x^*} \|^2 - \| \mathbf{x_{k+1}} - \mathbf{x^*} \|^2) - (\frac{1}{2\alpha} - \frac{L}{2}) \| \mathbf{x_{k+1}} - \mathbf{x_k} \|^2 \end{split}$$

Summing up the inequalities,

$$k(f(\mathbf{x_k}) - f(\mathbf{x^*})) \le \sum_{i=0}^{k-1} (f(\mathbf{x_{i+1}}) - f(\mathbf{x^*}))$$

$$\le \frac{1}{2\alpha} (\|\mathbf{x_0} - \mathbf{x^*}\|^2 - \|\mathbf{x_k} - \mathbf{x^*}\|^2) - (\frac{1}{2\alpha} - \frac{L}{2}) \sum_{i=0}^{k-1} \|\mathbf{x_{i+1}} - \mathbf{x_i}\|^2$$

1. If 
$$lpha \in (0, rac{1}{L})$$
,  $rac{1}{2lpha} - rac{L}{2} > 0$ , then

$$k(f(\mathbf{x_k}) - f(\mathbf{x^*})) \le \frac{1}{2\alpha} \|\mathbf{x_0} - \mathbf{x^*}\|^2.$$

2. If 
$$lpha \in (\frac{1}{L}, \frac{2}{L})$$
,  $\frac{1}{2lpha} - \frac{L}{2} > 0$ , then

$$egin{aligned} k(f(\mathbf{x_k}) - f(\mathbf{x^*})) &\leq rac{1}{2lpha} (\|\mathbf{x_0} - \mathbf{x^*}\|^2 - \|\mathbf{x_k} - \mathbf{x^*}\|^2) + rac{Llpha - 1}{2lpha} \sum_{i=0}^{k-1} \|\mathbf{x_{i+1}} - \mathbf{x_i}\|^2 \ &\leq rac{1}{2lpha} \|\mathbf{x_0} - \mathbf{x^*}\|^2 + rac{Llpha - 1}{2lpha} \sum_{i=0}^{\infty} \|\mathbf{x_{i+1}} - \mathbf{x_i}\|^2 \ &\leq rac{1}{2lpha} \|\mathbf{x_0} - \mathbf{x^*}\|^2 + rac{Llpha - 1}{2lpha} rac{2lpha}{2 - Llpha} (f(\mathbf{x_0}) - f(\mathbf{x^*})) (Lemma\ 2) \end{aligned}$$

Remark:  $\|\mathbf{x_k} - \mathbf{x^*}\|$  doesn't always converge to 0.