

Concurrent Programming

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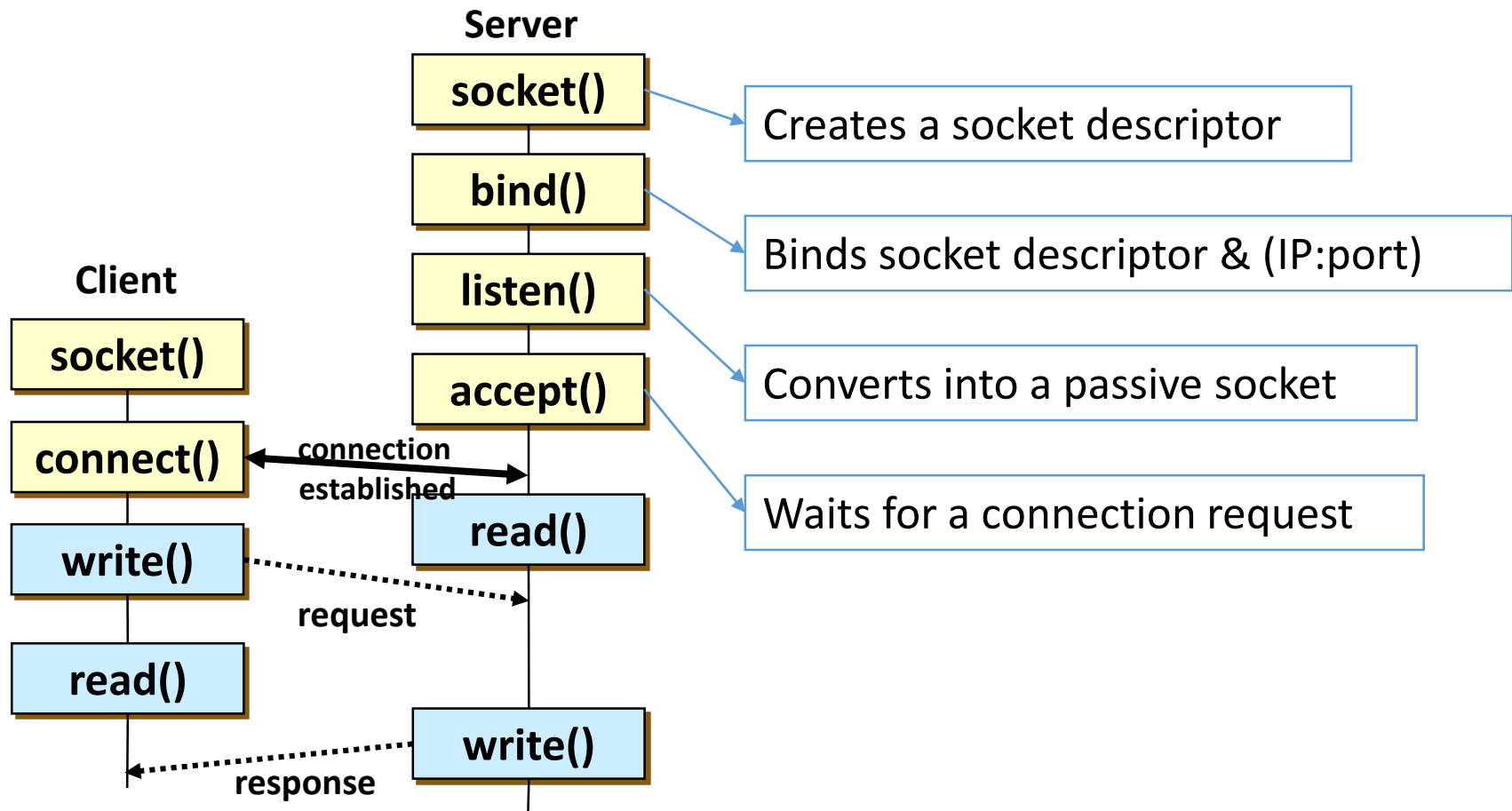
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Server

Connection-oriented service



Echo Server Revisited

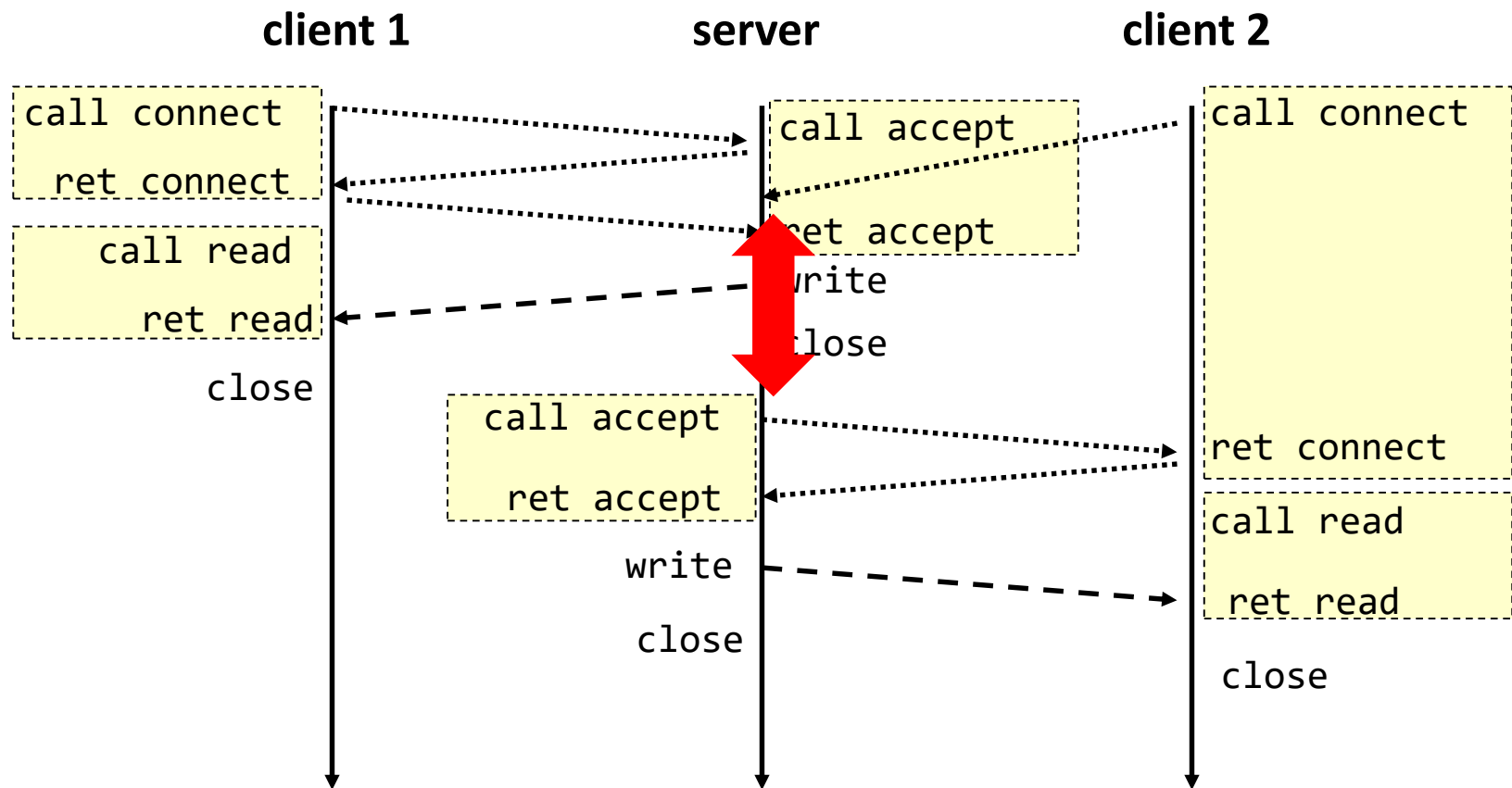
```
int main (int argc, char *argv[]) {
    ...
    listenfd = socket(AF_INET, SOCK_STREAM, 0);

    bzero((char *)&saddr, sizeof(saddr));
    saddr.sin_family = AF_INET;
    saddr.sin_addr.s_addr = htonl(INADDR_ANY);
    saddr.sin_port = htons(port);
    bind(listenfd, (struct sockaddr *)&saddr, sizeof(saddr));

    listen(listenfd, 5);
    while (1) {
        connfd = accept(listenfd, (struct sockaddr *)&caddr, &clen);
        while ((n = read(connfd, buf, MAXLINE)) > 0) {
            printf ("got %d bytes from client.\n", n);
            write(connfd, buf, n);
        }
        close(connfd);
    }
}
```

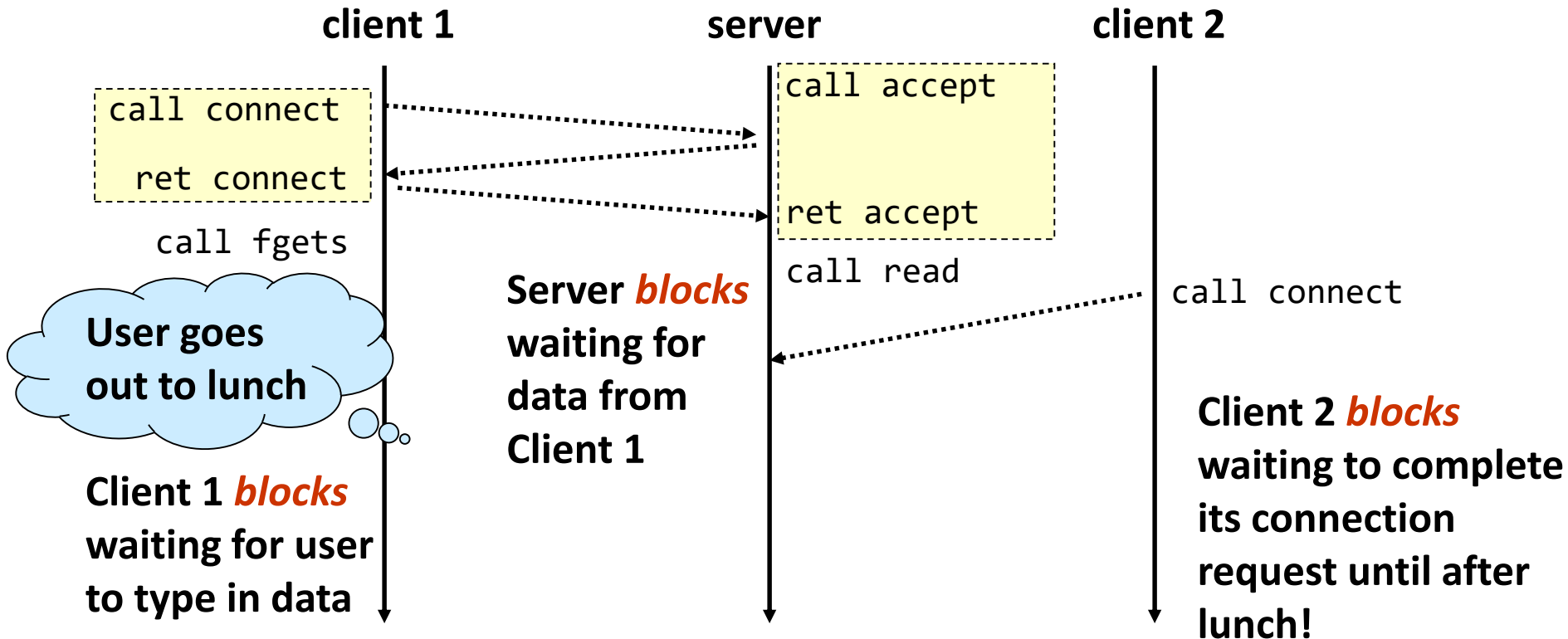
Iterative Servers (1)

- One request at a time



Iterative Servers (2)

■ Fundamental flaw



■ Solution: use concurrent servers instead

- Use multiple concurrent flows to serve multiple clients at the same time.

Creating Concurrent Flows

■ Processes

- Kernel automatically interleaves multiple logical flows.
- Each flow has its own private address space.

■ Threads

- Kernel automatically interleaves multiple logical flows.
- Each flow shares the same address space.
- Hybrid of processes and I/O multiplexing

■ I/O multiplexing with `select()`

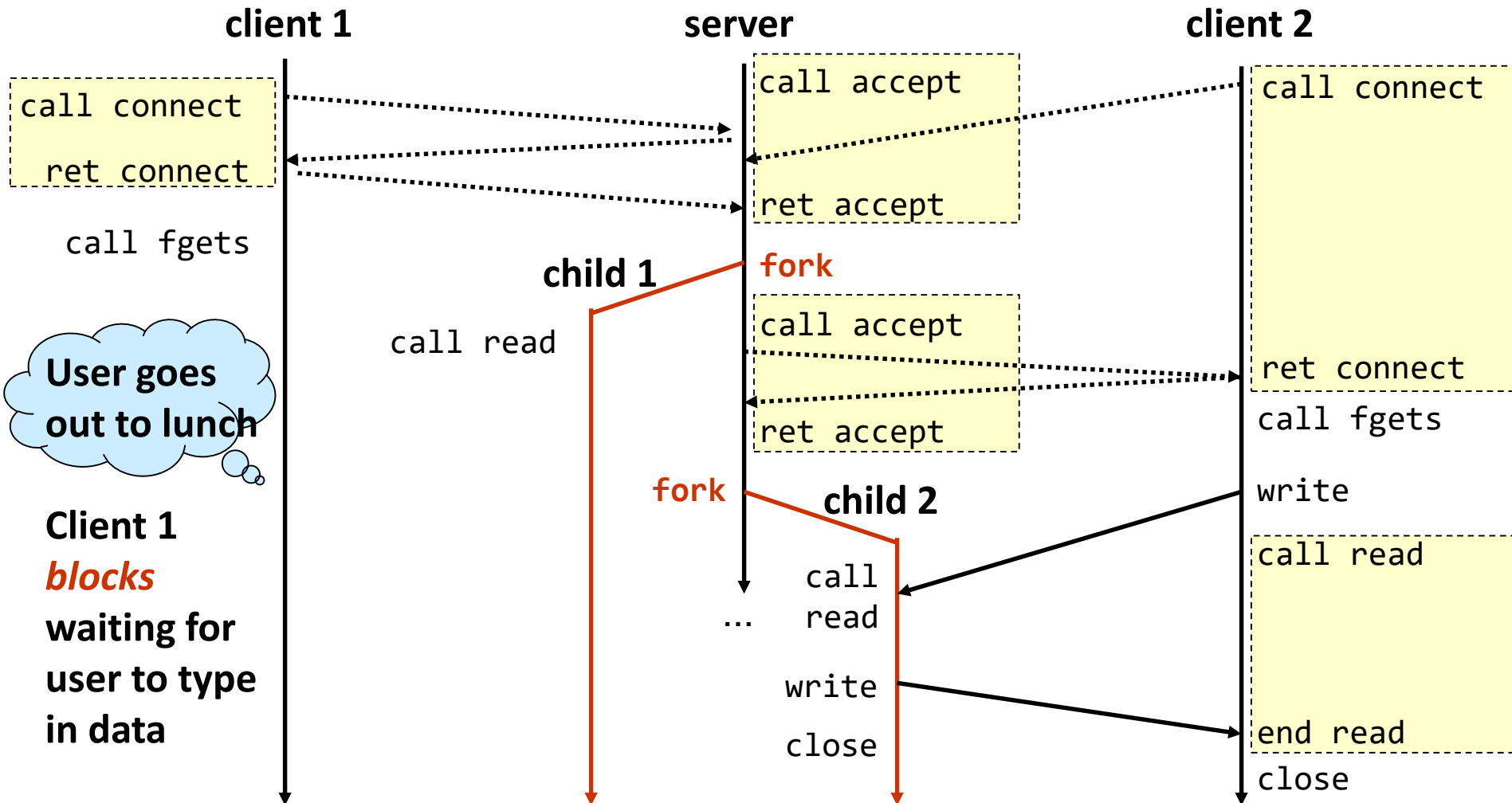
- User manually interleaves multiple logical flows
- Each flow shares the same address space
- Popular for high-performance server designs.

Concurrent Programming



Process-based

Process-based Servers



Implementation Issues

- **Servers should restart `accept()` if it is interrupted by a transfer of control to the `SIGCHLD` handler**
 - Not necessary for systems with POSIX signal handling.
 - Required for portability on some older Unix systems.
- **Server must reap zombie children**
 - to avoid fatal memory leak
- **Server must close its copy of `connfd`.**
 - Kernel keeps reference for each socket.
 - After `fork()`, `refcnt(connfd) = 2`
 - Connection will not be closed until `refcnt(connfd) = 0`

Process-based Designs

■ Pros

- Handles multiple connections concurrently.
- Clean sharing model.
 - Descriptors (no), file tables (yes), global variables (no)
- Simple and straightforward.

■ Cons

- Additional overhead for process control.
 - Process creation and termination
 - Process switching
- Nontrivial to share data between processes.
 - Requires IPC (InterProcess Communication) mechanisms: FIFO's, System V shared memory and semaphores

Concurrent Programming



Examples

Exercise

■ “Guess the Number”

– At the same time, multiple client can be served by echo server

■ There should be no memory leakage

– How about closing files?

```
./server [port]
```

```
./client 127.0.0.1 [port]  
Guess? 32  
Up  
Guess? 74  
Down  
Guess? 34  
Correct!  
$
```

```
./client 127.0.0.1 [port]  
Guess? 34  
Up  
Guess? 40  
Down  
Guess? 35  
Correct!  
$
```

```
./client 127.0.0.1 [port]  
Guess? 35  
Down  
Guess? 10  
Up  
Guess? 14  
Correct!  
$
```

Concurrent Programming



Thread-based

“hello, world” Program (1)

```
/*
 * hello.c - Pthreads "hello, world" program
 */
#include "pthread.h"

void *thread(void *vargp);

int main() {
    pthread_t tid;

    pthread_create(&tid, NULL, thread, NULL);
    pthread_join(tid, NULL);
    exit(0);
}

/* thread routine */
void *thread(void *vargp) {
    printf("Hello, world!\n");
    return NULL;
}
```

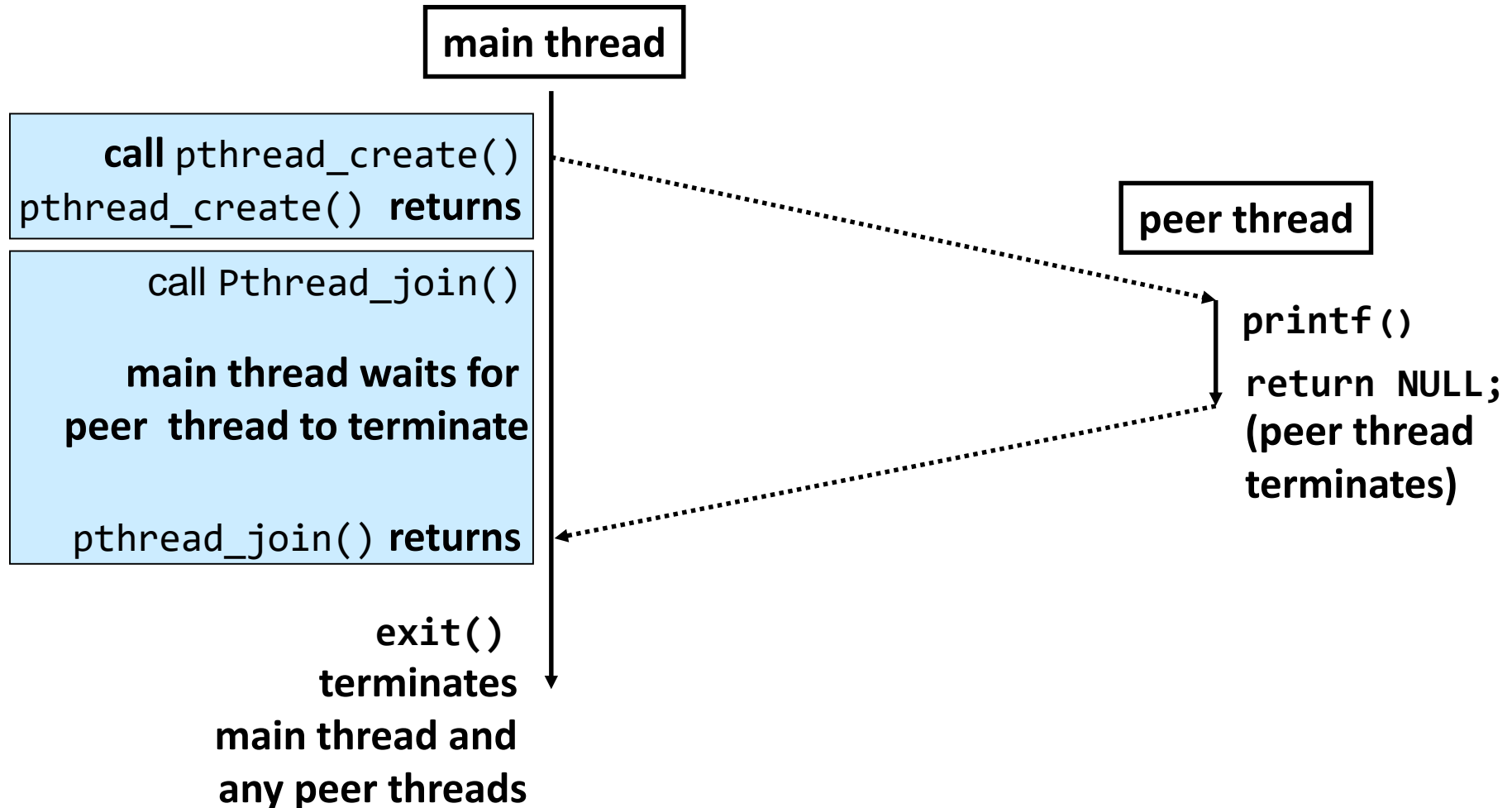
*Thread attributes
(usually NULL)*

*Thread arguments
(void *p)*

*return value
(void **p)*

“hello, world” Program (2)

■ Execution of threaded “hello, world”



Echo Server: Thread-based

```
int main (int argc, char *argv[])
{
    int *connfdp;
    pthread_t tid;
    . . .

    while (1) {
        connfdp = (int *)
                    malloc(sizeof(int));
        *connfdp = accept (listenfd,
                          (struct sockaddr *)&caddr,
                          &caddrlen));

        pthread_create(&tid, NULL,
                      thread_main, connfdp);
    }
}
```

```
void *thread_main(void *arg)
{
    int n;
    char buf[MAXLINE];

    int connfd = *((int *)arg);
    pthread_detach(pthread_self());
    free(arg);

    while((n = read(connfd, buf,
                    MAXLINE)) > 0)
        write(connfd, buf, n);

    close(connfd);
    return NULL;
}
```


Implementation Issues (1)

- **Must run “detached” to avoid memory leak.**
 - At any point in time, a thread is either **joinable** or **detached**.
 - Joinable thread can be reaped and killed by other threads
 - Must be reaped (with **pthread_join()**) to free memory resources.
 - Detached thread cannot be reaped or killed by other threads.
 - Resources are automatically reaped on termination.
 - Exit state and return value are not saved.
 - Default state is joinable.
 - Use **pthread_detach(pthread_self())** to make detached.

Implementation Issues (2)

- **Must be careful to avoid unintended sharing**
 - For example, what happens if we pass the address `connfd` to the thread routine?

```
int connfd;  
.  
.  
pthread_create(&tid, NULL, thread_main, &connfd);  
.  
.  
.
```

- **All functions called by a thread must be thread-safe.**
 - A function is said to be **thread-safe** or **reentrant**, when the function may be called by more than one thread at a time without requiring any other action on the caller's part.

Thread-based Designs

■ Pros

- Easy to share data structures between threads.
 - e.g., logging information, file cache, etc.
- Threads are more efficient than processes.

■ Cons

- Unintentional sharing can introduce subtle and hard-to-reproduce errors!
 - The ease with which data can be shared is both the greatest strength and the greatest weakness of threads.

Thread Safety (1)

■ Thread-safe

- Functions called from a thread must be **thread-safe**.
- We identify four (non-disjoint) classes of thread-unsafe functions:
 - Class 1: Failing to protect shared variables
 - Class 2: Relying on persistent state across invocations
 - Class 3: Returning a pointer to a static variable
 - Class 4: Calling thread-unsafe functions

Thread Safety (2)

- **Class 1: Failing to protect shared variables.**
 - Fix: Use mutex operations.
 - Issue: Synchronization operations will slow down code.

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
int cnt = 0;

/* Thread routine */
void *count(void *arg) {
    int i;

    for (i=0; i<NITERS; i++) {
        pthread_mutex_lock (&lock);
        cnt++;
        pthread_mutex_unlock (&lock);
    }
    return NULL;
}
```

Thread Safety (3)

- **Class 2: Relying on persistent state across multiple function invocations.**
 - Random number generator relies on static state
 - Fix: Rewrite function so that caller passes in all necessary state.

```
/* rand - return pseudo-random integer on 0..32767 */
int rand(void) {
    static unsigned int next = 1;
    next = next*1103515245 + 12345;
    return (unsigned int)(next/65536) % 32768;
}
/* srand - set seed for rand() */
void srand(unsigned int seed) {
    next = seed;
}
```

Thread Safety (4)

■ Class 3: Returning a ptr to a static variable.

■ Fixes:

1. Rewrite code so caller passes pointer to **struct**.

- Issue: Requires changes in caller and callee.

```
struct hostent
*gethostbyname(char *name){
    static struct hostent h;
    <contact DNS and fill in h>
    return &h;
}
```

```
hostp = malloc(...);
gethostbyname_r(name, hostp);
```

2. *Lock-and-copy*

- Issue: Requires only simple changes in caller (and none in callee)
 - However, caller must free memory.

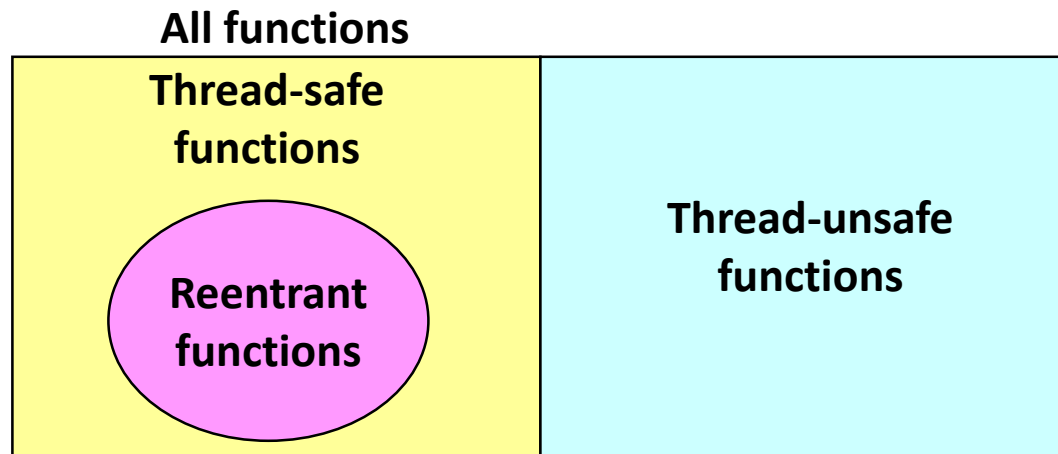
```
struct hostent
*gethostbyname_ts(char *name)
{
    struct hostent *unshared
                                = malloc(...);
    pthread_mutex_lock(&lock); /* lock */
    shared = gethostbyname(name);
    *unshared = *shared; /* copy */
    pthread_mutex_unlock(&lock);
    return q;
}
```

Thread Safety (5)

- **Class 4: Calling thread-unsafe functions.**
 - Calling one thread-unsafe function makes an entire function thread-unsafe.
 - Fix: Modify the function so it calls only thread-safe functions

Reentrant Functions

- A function is **reentrant** iff it accesses NO shared variables when called from multiple threads.
 - Reentrant functions are a proper subset of the set of thread-safe functions.



- NOTE: The fixes to Class 2 and 3 thread-unsafe functions require modifying the function to make it reentrant.

Thread-Safe Library

- All functions in the Standard C Library (at the back of your K&R text) are thread-safe.
 - Examples: **malloc**, **free**, **printf**, **scanf**
- Most Unix system calls are thread-safe, with a few exceptions:

Thread-unsafe function	Class	Reentrant version
asctime	3	asctime_r
ctime	3	ctime_r
gethostbyaddr	3	gethostbyaddr_r
gethostbyname	3	gethostbyname_r
inet_ntoa	3	(none)
localtime	3	localtime_r
rand	2	rand_r

Concurrent Programming



Examples

Example

- **Make chatting server**

- N client + 1 server
- A thread from the server reads messages from 1 client, and sends messages to all other clients
- Must wait when client is full

- **Use pthread_mutex**

- When accessing shared data structure among threads
- When condition variable is needed