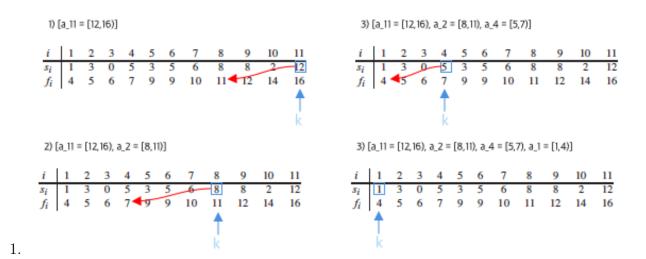
# CSC373 Worksheet 2 Solution

July 26, 2020



This approach is a greedy algorithm because algorithm

- 1) Has the greedy choice: selecting the last activity to start that is compatible with all previously selected activites
- 2) Has the greedy choice that is always part of optimal solution:

#### Claim:

Consider any nonempty subproblem  $S_k$ . Let  $a_m$  be an activity in  $S_k$  with the last activity to start that is compatible with all previously selected activities. Then  $a_m$  is included in some maximum-size subset of mutually compatible activities of  $S_k$ 

*Proof.* Let  $A_k$  be a maximum-size subset of mutually compatible activities in  $S_k$ , and let  $a_j$  be the activity in  $A_k$  with the last activity to start that is compatible with all previously selected activities.

If  $a_j = a_m$ , we are done, since we have shown that  $a_m$  is the maximum-size subset of mutually compatible activities of  $S_k$ .

If  $a_j \neq a_m$ , let the set  $A'_k = A_k = \{a_j\} \cup \{a_m\}$  be  $A_k$  but subtituting  $a_m$  for  $a_j$ . The activities in  $A'_k$  are disjoint, which follow because the activities in  $A_k$  are disjoint,  $a_j$  is the first activity in  $A_k$  to finish, and  $s_j \leq s_m$ .

Since  $|A'_k| = |A_k|$ , we conclude that  $A'_k$  is a maximum-size subset of mutually compatible activities of  $S_k$ , and it includes  $a_m$ .

#### Notes:

- Greedy Algorithm
  - Always makes the choice that looks best at the moment
    - \* Locally optimal solution leads to globally optimal solution
- Activity-selection Problem (Greedy algorithm using dynamic programming)
  - Goal: Selecting maximum size set of mutually compatible activities

## Example:

i	1	2	3	4	5	6	7	8	9	10	11
$s_i$	1	3	0	5	3	5	6	8	8	2	12
$f_i$	4	5	6	7	9	9	10	11	12	14	12 16

- Suppose a set exists  $S = \{a_1 = [s_1, f_1), a_2 = [s_2, f_2), ..., a_n = [s_n, f_n)\}$ 
  - \*  $a_i$  represents an  $i^{th}$  activity
  - \*  $s_i$  represents starting time
  - \*  $f_i$  represents finishing time
  - \*  $0 \le s_i < f_i < \infty$
  - \*  $a_1, ..., a_n$  sorted in monotonically increasing order of finish time

i.e.

$$f_1 < f_2 < f_3 < \dots < f_{n-1} < f_n$$

\*  $a_i$  and  $a_j$  are **compatible**, if intervals  $[s_i, f_i)$  and  $[s_j, f_j)$  don't overlap

i.e

$$s_i \ge f_j$$
 and  $s_j \ge f_i$ 

- Steps
  - 1. Think about dynamic programming solution
    - \* Construct optimal solution using two subproblems

 $S_{ij}$ : activities that start after activity  $a_i$  finishes and before activity  $a_j$  starts

i.e.

$$S_{19} = \{a_4 = [5, 7), a_6 = [5, 9), a_7 = [6, 10)\}$$

 $A_{ij}$ : maximum set of mutually compatible activities in  $S_{ij}$  (including  $a_k$ )

- $A_{ik} = A_{ij} \cap S_{ik}$
- $A_{kj} = A_{ij} \cap S_{kj}$
- $A_{ij} = A_{ik} \cup \{a_k\} \cup Akj$
- · So,  $|A_{ij}| = |A_{ik}| + |A_{kj}| + 1$
- \* Verify that optimal solution  $A_{ij}$  must include optimal solution to the two subproblems for  $S_{kj}$

Let  $A'_{kj}$  be another mutually compatible activities in  $S_{kj}$  where  $|A'_{kj}| > |A_{kj}|$ .

Then we could use  $A'_{kj}$  in a solution to subproblem of  $S_{ij}$ 

Then we have  $|A_{ik}| + |A'_{kj}| + 1 > |A_{jk}| + |A_{kj}| + 1 = |A_{ij}|$  mutually compatible activites

This contradicts assumption that  $A_{ij}$  is an optimal solution

\* Verify that optimal solution  $A_{ij}$  must include optimal solution to the two subproblems for  $S_{ik}$ 

The same applies for activities in  $S_{ik}$ 

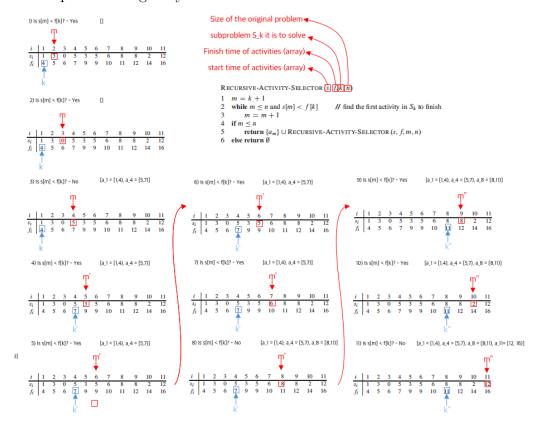
- 2. Observe that only one choice greedy choice, and that when we make the greedy choice, only one subproblem remains
  - \* Steps
    - 1. Make a greedy choice
      - · Choose an activity that makes the most resource possible (intuition)
      - · Choose an acitivty that finishes the earliest (intuition)
    - 2. Solve a subproblem: Find activities that start after  $a_1$  finishes
    - 3. Verify that making greedy choices always arrive at optimal solution

### Theorem 16.1 (Page 418):

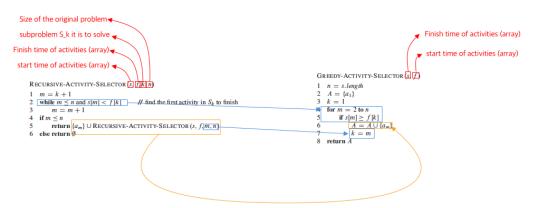
Consider any non-empty subproble  $S_k$ , and let  $a_m$  be an activity in  $S_k$  with the earliest finish time. Then  $a_m$  is included in some maximum-size

subset of mutually compatible activities of  $S_k$ 

3. Develop recursive greedy solution



4. Convert the recursive algorithm into iterative one



#### 2. • Greedy Choice

- Choose  $x_i$  that is greater than the current maximum as the upper bound of unit length closed interval

- Choose  $x_i$  that is smaller than the current minimum as the lower bound of unit length closed interval

## Example:

$$\{0, 1, 2, 3, 4, 5\} \rightarrow [0, 5]$$

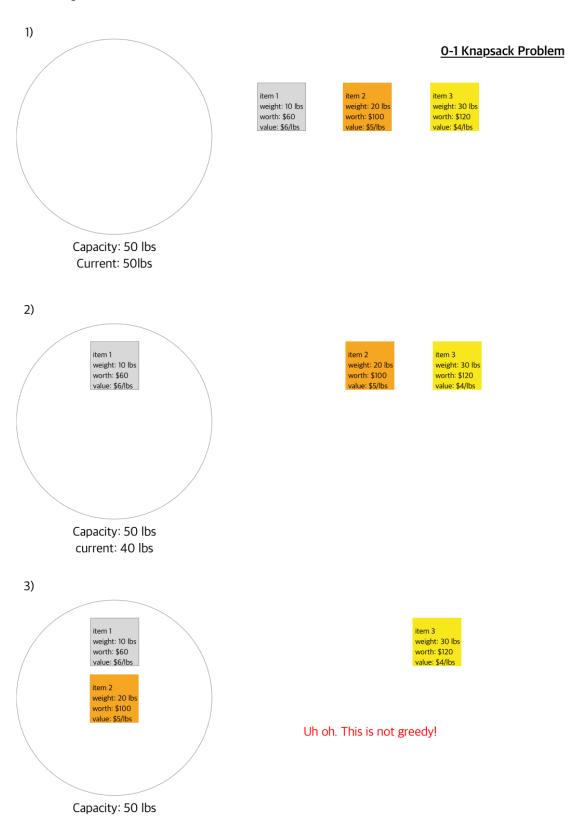
$$\{0, -1, 3, 5, 2\} \rightarrow [-1, 5]$$

- Optimal Substructure
- Algorithm

#### Notes:

- I am having difficulty providing optimal substructure to problem
- Unit length
  - [1, 25, 2.25] includes all  $x_i$  such that  $1.25 \le x_i \le 2.25$ .
- Greedy-choice property and optimal substructure to problem are the two key ingredients
- Summary of Steps for Greedy Algorithm
  - 1. Determine the optimal structure of the problem
  - 2. Develop a recursive solution.
  - 3. Show that if we make the greedy choice, then only one subproblem remains
  - 4. Prove that it is always safe to make the greedy choice
  - 5. Develop a reursive algorithm that implements the greedy strategy
  - 6. Convert the recursive algorithm to an iterative algorithm
- Criteria for Greedy Algorithm
  - 1. Greedy-choice property
    - Exists if we can assemble a globally optimal solution by making a locally optimal (greedy) choices
  - 2. Optimal Substructure
    - Exists if an optimal solution to the problem contains within it optimal solutions to subproblems.
- Greedy vs Dynamic Programming

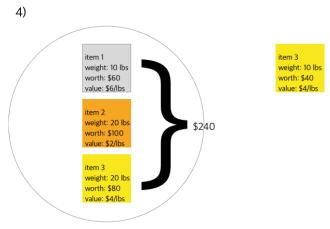
# $-\,$ 0-1 Knapsack Problem



current: 20 lbs

# – Fractional Knapsack Problem





Capacity: 50 lbs current: 20 lbs