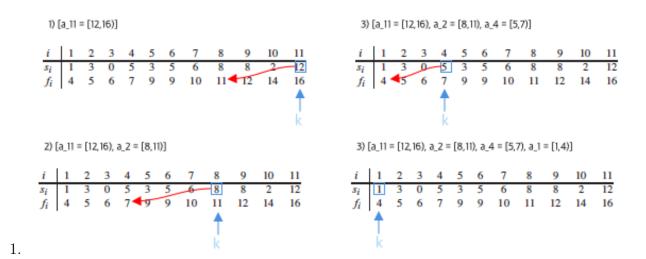
CSC373 Worksheet 2 Solution

July 26, 2020



This approach is a greedy algorithm because algorithm

- 1) Has the greedy choice: selecting the last activity to start that is compatible with all previously selected activites
- 2) Has the greedy choice that is always part of optimal solution:

Claim:

Consider any nonempty subproblem S_k . Let a_m be an activity in S_k with the last activity to start that is compatible with all previously selected activities. Then a_m is included in some maximum-size subset of mutually compatible activities of S_k

Proof. Let A_k be a maximum-size subset of mutually compatible activities in S_k , and let a_j be the activity in A_k with the last activity to start that is compatible with all previously selected activities.

If $a_j = a_m$, we are done, since we have shown that a_m is the maximum-size subset of mutually compatible activities of S_k .

If $a_j \neq a_m$, let the set $A'_k = A_k = \{a_j\} \cup \{a_m\}$ be A_k but subtituting a_m for a_j . The activities in A'_k are disjoint, which follow because the activities in A_k are disjoint, a_j is the first activity in A_k to finish, and $s_j \leq s_m$.

Since $|A'_k| = |A_k|$, we conclude that A'_k is a maximum-size subset of mutually compatible activities of S_k , and it includes a_m .

Notes:

- Greedy Algorithm
 - Always makes the choice that looks best at the moment
 - * Locally optimal solution leads to globally optimal solution
- Activity-selection Problem (Greedy algorithm using dynamic programming)
 - Goal: Selecting maximum size set of mutually compatible activities

Example:

i	1	2	3	4	5	6	7	8	9	10	11
s_i	1	3	0	5	3	5	6	8	8	2	12
f_i	4	5	6	7	9	9	10	11	12	14	12 16

- Suppose a set exists $S = \{a_1 = [s_1, f_1), a_2 = [s_2, f_2), ..., a_n = [s_n, f_n)\}$
 - * a_i represents an i^{th} activity
 - * s_i represents starting time
 - * f_i represents finishing time
 - * $0 \le s_i < f_i < \infty$
 - * $a_1, ..., a_n$ sorted in monotonically increasing order of finish time

i.e.

$$f_1 < f_2 < f_3 < \dots < f_{n-1} < f_n$$

* a_i and a_j are **compatible**, if intervals $[s_i, f_i)$ and $[s_j, f_j)$ don't overlap

i.e

$$s_i \ge f_j$$
 and $s_j \ge f_i$

- Steps
 - 1. Think about dynamic programming solution
 - * Construct optimal solution using two subproblems

 S_{ij} : activities that start after activity a_i finishes and before activity a_j starts

i.e.

$$S_{19} = \{a_4 = [5, 7), a_6 = [5, 9), a_7 = [6, 10)\}$$

 A_{ij} : maximum set of mutually compatible activities in S_{ij} (including a_k)

- $A_{ik} = A_{ij} \cap S_{ik}$
- $A_{kj} = A_{ij} \cap S_{kj}$
- $A_{ij} = A_{ik} \cup \{a_k\} \cup Akj$
- · So, $|A_{ij}| = |A_{ik}| + |A_{kj}| + 1$
- * Verify that optimal solution A_{ij} must include optimal solution to the two subproblems for S_{kj}

Let A'_{kj} be another mutually compatible activities in S_{kj} where $|A'_{kj}| > |A_{kj}|$.

Then we could use A'_{kj} in a solution to subproblem of S_{ij}

Then we have $|A_{ik}| + |A'_{kj}| + 1 > |A_{jk}| + |A_{kj}| + 1 = |A_{ij}|$ mutually compatible activites

This contradicts assumption that A_{ij} is an optimal solution

* Verify that optimal solution A_{ij} must include optimal solution to the two subproblems for S_{ik}

The same applies for activities in S_{ik}

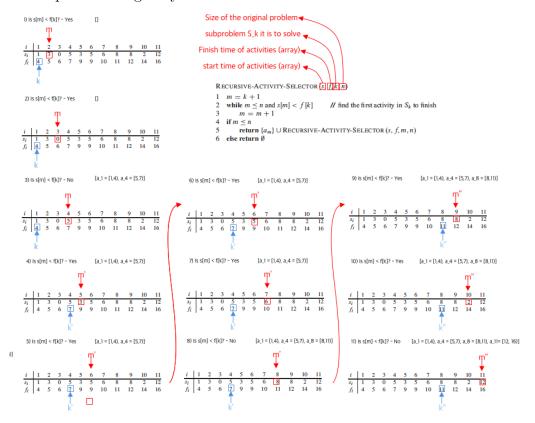
- 2. Observe that only one choice greedy choice, and that when we make the greedy choice, only one subproblem remains
 - * Steps
 - 1. Make a greedy choice
 - · Choose an activity that makes the most resource possible (intuition)
 - · Choose an acitivty that finishes the earliest (intuition)
 - 2. Solve a subproblem: Find activities that start after a_1 finishes
 - 3. Verify that making greedy choices always arrive at optimal solution

Theorem 16.1 (Page 418):

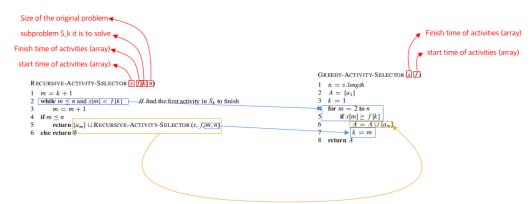
Consider any non-empty subproble S_k , and let a_m be an activity in S_k with the earliest finish time. Then a_m is included in some maximum-size

subset of mutually compatible activities of S_k

3. Develop recursive greedy solution



4. Convert the recursive algorithm into iterative one



2. • Greedy Choice

- Choose x_i that is greater than the current maximum as the upper bound of unit length closed interval
- Choose x_i that is smaller than the current minimum as the lower bound of unit length closed interval

Example:

$$\{0, 1, 2, 3, 4, 5\} \rightarrow [0, 5]$$

$$\{0, -1, 3, 5, 2\} \rightarrow [-1, 5]$$

• Optimal Substructure

Let I be the following instance of the problem: Let n be the number of items, and let x_i be the i^{th} point in the set.

Let $A = [x_{\min}, x_{\max}]$ be the solution. The greedy algorithm works by assigning $x_{\min} = \min(x_{\min}, x_n)$ and $x_{\max} = \max(x_{\max}, x_n)$, and then continuing by solving the subproblem

$$I' = (n - 1, \{x_1, ..., x_{n-1}\})$$
(1)

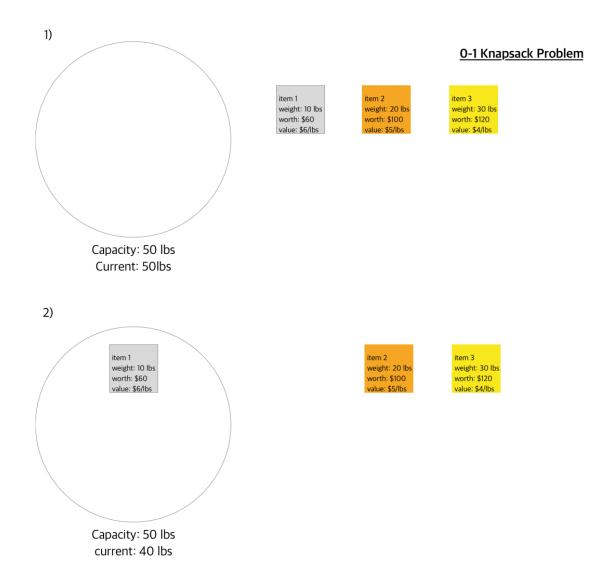
until n = 0.

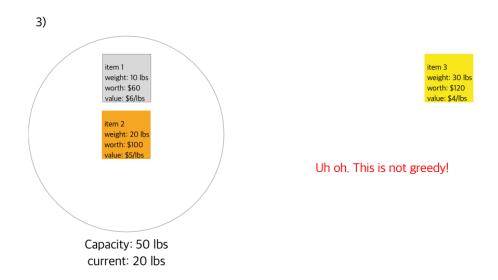
We need to show that the strategy gives optimal solution.

Notes:

- Stopped because it's taking too much time.
- I struggled on this problem.
- I am having difficulty arguing why the algorith is correct
 - How can i generate a claim?
- Unit length
 - [1, 25, 2.25] includes all x_i such that $1.25 \le x_i \le 2.25$.
- Greedy-choice property and optimal substructure to problem are the two key ingredients
- Summary of Steps for Greedy Algorithm
 - 1. Determine the optimal structure of the problem
 - 2. Develop a recursive solution.
 - 3. Show that if we make the greedy choice, then only one subproblem remains
 - 4. Prove that it is always safe to make the greedy choice
 - 5. Develop a reursive algorithm that implements the greedy strategy

- 6. Convert the recursive algorithm to an iterative algorithm
- Criteria for Greedy Algorithm
 - 1. Greedy-choice property
 - Exists if we can assemble a globally optimal solution by making a locally optimal (greedy) choices
 - 2. Optimal Substructure
 - Exists if an optimal solution to the problem contains within it optimal solutions to subproblems.
- Greedy vs Dynamic Programming
 - -0-1 Knapsack Problem





Fractional Knapsack Problem

