- 1. a) False
 - b) True
 - c) True
 - d) True
 - e) True

Notes

• User Mode

- Is restricted
- Executing code has no ability to directly access hardware or reference memory $_{[1]}$
- Crashes are always recoverable ^[1]
- Is where most of the code on our computer / applications are executed [3]

• Kernel Mode

- Is previleged (non-restricted)
- Executing code has complete and unrestricted access to the underlying hardware
 [3]
- Is generally reserved for the lowest-level, most trusted functions of the operating system [1]
- Is fatal to crash; it will halt the entire PC (i.e the blue screen of death) [3]

• Interrupt

- Are signals sent to the CPU by external devices, normally I/O devices. [2]
- Tells the CPU to stop its current activities and execute the appropriate part of the operating system (**Interrupt Handler**). [2]
- Has three different types ^[2]

1) Hardware Interupts

- * Are generated by hardware devices to signal that they need some attention from the OS.
- * May be due to receiving some data

Examples

- · Keystrokes on the keyboard
- · Receiving data on the ethernet card
- * May be due to completing a task which the operating system previous requested

Examples

Transfering data between the hard drive and memory

2) Software Interupts

* Are generated by programs when a system call is requested

3) Traps

- * Are generated by the CPU itself
- * Indicate that some error or condition occured for which assistance from the operating system is needed

• Content Switch

- Is switching from running a user level process to the OS kernel and often to other user processes before the current process is resumed
- Happens during a timer interrupt or system call
- Saves the following states for a process during a context switch
 - * Stack Pointer
 - * Program Counter
 - * User Registers
 - * Kernel State
- May hinder performance

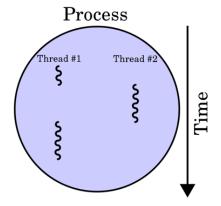
• System Call

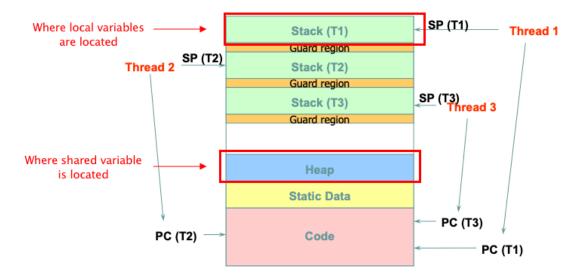
Example

- yield()
 - * Is a system call
 - * Causes the calling thread to relinquish the CPU
 - * Places the current thread at the end of the run queue
 - * Schedules another thread to run

• Thread

- Is a lightweight process that can be managed independently by a schdeduler [4]
- Improves the application performance using parallelism. (e.g peach)





- A thread is bound to a single process
- A process can have multiple threads
- Has two types

* User-level Threads:

- · Are implemented by users and kernel is not aware of the existence of these threads
- · Are represented by a program counter(PC), stack, registers and a small process control block
- · Are small and much faster than kernel level threads

* Kernel-level Threads:

- · Are handled by the operating system directly
- · Thread management is done by the kernel
- · Are slower than user-level threads

• Process

- Is a program in execution
- Is named by it's process ID or PID
- Can be described by the following states at any point in time
 - * Address Space
 - * CPU Registers
 - * Program Counter
 - * Stack Pointer
 - * I/O Information

(wait. this is PCB)

- Exists in one of many different **process states**, including
 - 1. Running
 - 2. Ready to Run

3. Blocked

* Different events (Getting Scheduled, descheduled, or waiting for I/O) transitions one of these states to the other

• Signals

- Provides a way to communicate with the process
- Can cause job to stop, continue, or terminate
- Can be delivered to an application
 - * Stops the application from whatever its doing
 - * Runs Signal handler (some code in application to handle the signal)
 - * When finished, the process resumes previous behavior

Spinlock

- Is the simplest lock to build
- Uses a lock variable
 - * 0 (available/unlock/free)
 - * 1 (acquired/locked/held)
- Has two operations
 - 1. acquire()

2. release()

```
boolean test_and_set(boolean *lock)
{
     boolean old = *lock;
     *lock = True;
     return old;
}
boolean lock;

void acquire(boolean *lock) {
     while(test_and_set(lock));
}

void release(boolean *lock) {
     *lock = false;
```

- Allows a single thread to enter critical section at a time

}

- Spins using CPU cycles until the lock becomes available.
- May spin forever

• Scheduling policies

- Are algorithms for allocating CPU resources to concurrent tasks deployed on (i.e., allocated to) a processor (i.e., computing resource) or a shared pool of processors [5]
- Are sometimes called **Discipline**
- Covers the following algorithms in textbook
 - * First In First Out
 - * Shortest Job First
 - * Shortest Time-to-completion First
 - * Round Robin
 - * Multi-level Feedback Queue

References

- 1) Coding Horror, Understanding User and Kernel Mode, link
- 2) Kansas State University, Basics of How Operating Systems Work, link
- 3) Kansas State University, Glossary, link
- 4) Tutorials Point, User-level threads and Kernel-level threads, link
- 5) Science Direct, Scheduling Policy, link