

Hyunin Lee

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Education

University of California, Berkeley

Ph.D. in Mechanical Engineering

CA, United States

Aug. 2022 –

Seoul National University

B.S in Mechanical Engineering; summa cum laude

Seoul, Rep.of.Korea

Mar. 2015 – Feb. 2022

Research Area

Reinforcement Learning, Multi-Modal Learning, AI Safety

Publications / C: CONFERENCE, J: JOURNAL, P: PREPRINT

[P2] Cross-attention Secretly Performs Orthogonal Alignment in Recommendation models.

H. Lee, Y. Zhang, H. Nguyen, X. Liu, N. Park, C. Jung, Y. Wang, Z. Wang, S. Sojoudi, X. Feng. *preprint*.
[pdf/blog]

[P1] A Prospect Theoretic Rationality: Loss Aversion Can Accelerate Reinforcement Learning

H. Lee, C. Park, S. Sojoudi, N. Mehr. *preprint*. [pdf]

[C5] Position: AI Safety Must Embrace an Antifragile Perspective.

M. Jin, H. Lee. *ICML*. 2025. [pdf]

[C4] A Black Swan Hypothesis: The Role of Human Irrationality in AI Safety.

H. Lee, C. Park, D. Abel, M. Jin. *ICLR*. 2025 & *ICLR 2025 Advances in Financial AI Workshop* (Oral, Top 1.2%). [pdf]

[C3] Pausing Policy Learning in Non-stationary Reinforcement Learning.

H. Lee, M. Jin, J. Lavaei, and S. Sojoudi. *ICML*. 2024. (Oral, Top 1.2%) [pdf/codes/talk]

[J3] Policy-based Primal-Dual Methods for Concave CMDP with Variance Reduction.

D. Ying, M. Guo, H. Lee, Y. Ding, J. Lavaei, and Z. Shen. *JAIR*. 2025. [pdf /codes]

[C2] Tempo Adaptation in Non-stationary Reinforcement Learning.

H. Lee, Y. Ding, J. Lee, M. Jin, J. Lavaei, and S. Sojoudi. *NeurIPS*. 2023 [pdf/codes/slides]

[J2] Beyond Exact Gradients: Convergence of Stochastic Soft-Max Policy Gradient Methods with Entropy Regularization.

Y. Ding, J. Zhang, H. Lee, and J. Lavaei. *IEEE TAC*. 2025 [pdf]

[C1] Initial State Interventions for Deconfounded Imitation Learning.

S. Pfrommer, Y. Bai, H. Lee, and S. Sojoudi. *IEEE CDC*. 2023. [pdf]

[J1] Explainable Deep Learning Model for EMG Based Finger Angle Estimation Using Attention.

H. Lee, D. Kim, and Y. Park. *IEEE TNSRE*. vol. 30, pp. 1877-1886 2022. [pdf/codes]

Work Experience

Meta

Research Scientist Intern

May 2025 – Oct 2025

Ranking AI Research Team

- Researched on transformer-based **multi-modal recommendation model**, enhancing ranking performance in sparse data setting. (Intern manager: Yong Zhang, Xue Feng)
- Proposed a novel cross-attention mechanism—orthogonal alignment—achieving 1.5x improvement in **scaling law efficiency**, validated on both Meta ranking model and public baselines. [p1]

OpenAI

Research Associate

Mar 2025 – Aug 2025

Human Data (Research) Team

- Engaged with the safety and preparedness team to evaluate an AI agent’s ability to replicate ML research and to create a comprehensive rubric that defines objective success criteria for accurately reproducing given ML papers. (Hired by Benjamin Kinsella)

University of California, Berkeley

Graduate Student Researcher

Aug 2022 – Present

Advisor: Prof. Somayeh Sojoudi

- Investigating **non-stationary reinforcement learning** and optimization under distributional shift. [p1, p2]
- Investigating **Human-AI alignment** focusing on ensuring **safe AI systems** in the presence of unpredictable or non-standard human behaviour. [p1, p2, p3]

OUTTA [Homepage] [LinkedIn]

Co-Founder

Aug 2021 – Present

Seoul, South Korea

- Deliver online AI courses to **800+ students** annually across South Korea.

Knowledge AI

Machine Learning Engineer

Jul 2021 – Jul 2022

Boston, MA

- Implemented a **Bayesian inference algorithm** in Python to quantify students’ mastery of mathematics topics.
- Developed a question-recommendation deep-learning system for an online math-learning platform, boosting student performance.

Seoul National University

Undergraduate Research Intern

Mar 2021 – Nov 2021

Soft Robotics & Bionics Lab

- Designed an **attention-based sequential decision-making algorithm** in Python to predict finger-joint angles from forearm EMG signals, improving accuracy by more than 10%.

Seoul National University

Undergraduate Research Intern

Sep. 2020 – Jun. 2021

Robot Learning Lab

- Develop **deep generative Q learning algorithm** to reconstruct a reward kernel using Python [pdf] [video]

Academic Activity

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| Reviewer | ICLR 2024-2025, ICML 2024-2025, NeurIPS 2024-2025, RLC 2025, AISTATS 2025 |
| Program Chair Committee | AAAI 2025 |

Teaching Experience

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| Graduate Student Instructor, Statistics and Data Science for Engineers | Fall, Spring 2025 |
| Graduate Student Instructor, Dynamic Systems and Feedback | Fall 2024 |
| Teaching Tutor, Math and Physics for Freshman | Spring 2019, Spring 2020 |
| Teaching Assistant, Dynamic | Fall 2019 |
| Teaching Assistant, Mechanical Product Design | Fall 2020 |

Grants and Honors

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| Berkeley Summer Research Fellowship <i>Mechanical Engineering Department</i> | Summer 2024 |
| NeurIPS scholar award <i>Conference on Neural Information Processing Systems</i> | Dec. 2023 |
| Kwanjeong Abroad Scholarship <i>Kwanjeong Educational Foundation</i> | Fall 2022 – Present |
| Berkeley Fellowship for Graduate Study <i>Graduate Division</i> | Fall 2022 – Spring 2023 |

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| National Science & Technology Scholarship <i>Korea Student Aid Foundation</i> | Spring 2017, Fall 2019 |
| | Spring 2020, Fall 2020 |
| Certificate of Appreciation (OUTTA) <i>Dean, college of Engineering, Seoul National University</i> | Jun. 2021 |
| Scholarship to Academic Excellence <i>Seoul National University</i> | Spring 2015, Fall 2015 |
| | Spring 2016, Fall 2016 |

Graduate courses

Specialization: Non-convex Optimization & Reinforcement Learning

Theoretical statistics I, II, Probability Theory I, II

Convex Optimization (convex optimization, robust optimization)

Mathematical Programming II (Advanced optimization theory, non-convex optimization)

Advanced control system I (canonical state-space representation forms, Lyapunov stability, LQR control)

Experiential advanced control design I, II (model predictive control, kalman filter)

Linear System, Nonlinear System

Technical Skills

Languages: Python (Advanced), MatLab (Advanced), C++

Software library, platform : Pytorch (Advanced), Tensorflow. Gurobi (Advanced), CPLEX (Advanced)