

Linear and Nonlinear Computation Models
(CSE 4190.313)

Final Exam: June 11, 2010

(Solutions)

Problem	Score	Problem	Score
1		6	
2		7	
3		8	
4		9	
5		Total	

Name: _____

ID No: _____

Dept: _____

Phone: _____

E-mail: _____

1. (10 points) Suppose A has eigenvalues 0, 3, 5 with independent eigenvectors $\mathbf{u}, \mathbf{v}, \mathbf{w}$.

- (a) (3 points) Give a basis for the nullspace and a basis for the column space.
- (b) (4 points) Find particular solution to $A\mathbf{x} = \mathbf{v} + \mathbf{w}$. Find all solutions.
- (c) (3 points) Show that $A\mathbf{x} = \mathbf{u}$ has no solution.

(a) \mathbf{u} : a basis for the nullspace of A ($\because A\mathbf{u} = \mathbf{0}$)

\mathbf{v}, \mathbf{w} : a basis for the column space of A

$$(\because A(\alpha\mathbf{v} + \beta\mathbf{w}) = 3\alpha\mathbf{v} + 5\beta\mathbf{w} \text{ for all } \alpha, \beta \in \mathbb{R})$$

(b) Let $\mathbf{x}_p = \frac{1}{3}\mathbf{v} + \frac{1}{5}\mathbf{w}$, then

$$A\mathbf{x}_p = \frac{1}{3} \cdot 3\mathbf{v} + \frac{1}{5} \cdot 5\mathbf{w} = \mathbf{v} + \mathbf{w}.$$

$\therefore \mathbf{x}_p$ is a particular solution

Let $\mathbf{x} = \alpha\mathbf{u} + \frac{1}{3}\mathbf{v} + \frac{1}{5}\mathbf{w}$ for all $\alpha \in \mathbb{R}$,

$$\text{then } A\mathbf{x} = \mathbf{0} + \frac{1}{3} \cdot 3\mathbf{v} + \frac{1}{5} \cdot 5\mathbf{w} = \mathbf{v} + \mathbf{w}$$

$\therefore \mathbf{x}$ is a general solution.

(c) If $\mathbf{u} = A\mathbf{x}$ for some \mathbf{x} , then

$\mathbf{u} (\neq \mathbf{0})$ is in the column space of A and

$\mathbf{u} = \alpha\mathbf{v} + \beta\mathbf{w}$ for some $\alpha, \beta \in \mathbb{R}$.

($\alpha \neq 0$ or $\beta \neq 0$)

$\mathbf{0} = A\mathbf{u} = 3\alpha\mathbf{v} + 5\beta\mathbf{w} \neq \mathbf{0}$, $\mathbf{x} \rightarrow$ 두 가지의 방정식을 풀면
 \rightarrow This means $\mathbf{u}, \mathbf{v}, \mathbf{w}$ are dependent \Rightarrow \mathbf{u} 는 \mathbf{v}, \mathbf{w} 의 linear combination!

Thus $A\mathbf{x} = \mathbf{u}$ has no solution

2. (10 points) True or false: If the n columns of S (eigenvectors of A) are independent, then

- (a) (2 points) A is invertible,
- (b) (3 points) A is diagonalizable,
- (c) (2 points) S is invertible,
- (d) (3 points) S is diagonalizable.

Justify your answer.

(a) False

For A may have a zero eigenvalue]

(b) True

For $AS = S\Lambda \Rightarrow S^T AS = \Lambda$]

(c) True

For S has rank n]

(d) False

For counterexample:

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 4 \end{bmatrix}, S = \begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix}$$

$$\Rightarrow S^T AS = \begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix}$$

But, S is not diagonalizable

S has $\lambda = 3$ as a double eigenvalue

$$\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow x_2 = 0$$

Thus, all eigenvectors of S are $\begin{bmatrix} \alpha \\ 0 \end{bmatrix}$, $\alpha \in \mathbb{R}$

$\therefore S$ has no two independent columns]

3. (10 points) If the transformation T is a reflection across the 45° line in the plane, find its matrix with respect to the standard basis $\mathbf{v}_1 = (1, 0), \mathbf{v}_2 = (0, 1)$, and also with respect to $\mathbf{V}_1 = (1, 1), \mathbf{V}_2 = (1, -1)$. Show that those matrices are similar.

$$[T]_{\mathbf{v} \rightarrow \mathbf{v}} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$[T]_{\mathbf{V} \rightarrow \mathbf{V}} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$M = [I]_{\mathbf{V} \rightarrow \mathbf{v}} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

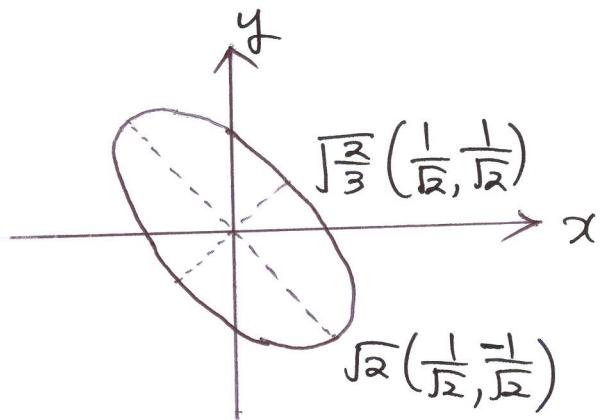
$$M^{-1} = [I]_{\mathbf{v} \rightarrow \mathbf{V}} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$[T]_{\mathbf{V} \rightarrow \mathbf{V}} = M^{-1} [T]_{\mathbf{v} \rightarrow \mathbf{v}} M$$

$$\left(\frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \right. \\ \left. = \frac{1}{2} \begin{bmatrix} 2 & 0 \\ 0 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \right)$$

\therefore The two matrices are similar.

4. (10 points) Draw the tilted ellipse $x^2 + xy + y^2 = 1$ and find the half-lengths of its axes from the eigenvalues of the corresponding matrix A .



$$\begin{bmatrix} 1 & \frac{1}{2} \\ \frac{1}{2} & 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} \frac{3}{2} & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$$

eigenvalues unit eigenvectors

$$x^2 + xy + y^2 = \frac{3}{2} \left(\frac{x}{\sqrt{2}} + \frac{y}{\sqrt{2}} \right)^2 + \frac{1}{2} \left(\frac{x}{\sqrt{2}} - \frac{y}{\sqrt{2}} \right)^2$$

Half-leng of the major axis : $\sqrt{2}$

— || — the minor axis : $\sqrt{\frac{2}{3}}$

5. (10 points)

- (a) (5 points) Find $U\Sigma V^T$ if A has orthogonal columns $\mathbf{w}_1, \dots, \mathbf{w}_n$ of lengths $\sigma_1, \dots, \sigma_n$.
 (b) (5 points) If an $m \times n$ matrix Q has orthogonal columns, what is Q^+ ?

(a)

$$A = \left(\begin{array}{c|c|c|c|c|c} & & m & & n & \\ \hline \mathbf{w}_1 / \sigma_1 & \cdots & \mathbf{w}_n / \sigma_n & | & \sigma_1 & \cdots & \sigma_n \\ \hline & & & \vdots & & \vdots & \vdots \\ & & & \mathbf{v}_1 & \cdots & \mathbf{v}_m & \mathbf{v}_1 \\ & & & & \ddots & & \mathbf{v}_m \\ \hline & & & & & & I_{n \times n} \end{array} \right)$$

$(m-n)$
orthonormal
vectors

(b)

$$Q = \left[\begin{array}{c|c|c|c} & & n & \\ \hline \mathbf{q}_1 / \|\mathbf{q}_1\| & \cdots & \mathbf{q}_n / \|\mathbf{q}_n\| & \left[\begin{array}{c|c|c} \|\mathbf{q}_1\| & & \\ \hline \vdots & \ddots & \\ \hline \|\mathbf{q}_n\| & & \end{array} \right] \end{array} \right]$$

$$Q^+ = \left[\begin{array}{c|c|c} & & \\ \hline \frac{1}{\|\mathbf{q}_1\|} & \cdots & \frac{\mathbf{q}_1^T / \|\mathbf{q}_1\|}{\|\mathbf{q}_n\|} \\ \hline & \ddots & \vdots \\ & & \frac{\mathbf{q}_n^T / \|\mathbf{q}_n\|}{\|\mathbf{q}_n\|} \end{array} \right]$$

$$= \left[\begin{array}{c|c} & \\ \hline \frac{\mathbf{q}_1^T / \mathbf{q}_1^T \mathbf{q}_1}{\mathbf{q}_1^T \mathbf{q}_1} & \\ \hline \vdots & \\ \hline \frac{\mathbf{q}_n^T / \mathbf{q}_n^T \mathbf{q}_n}{\mathbf{q}_n^T \mathbf{q}_n} & \end{array} \right]$$

6. (10 points) Find the minimum values of

$$R_1(\mathbf{x}) = \frac{x_1^2 - x_1x_2 + x_2^2}{x_1^2 + x_2^2}, \quad \text{and} \quad R_2(\mathbf{x}) = \frac{x_1^2 - x_1x_2 + x_2^2}{4x_1^2 + x_2^2},$$

$$(a) \quad A_1 = \begin{bmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & 1 \end{bmatrix} \quad (\lambda-1)^2 - \frac{1}{4} = 0$$

$$\lambda_{\min} = \frac{1}{2}, \quad \lambda_{\max} = \frac{3}{2}$$

$$\therefore \min R_1(\mathbf{x}) = \lambda_{\min} = \frac{1}{2}$$

$$(b) \quad R_2(\mathbf{x}) = \frac{\frac{1}{4}(2x_1)^2 - \frac{1}{2}(2x_1)x_2 + x_2^2}{(2x_1)^2 + x_2^2}$$

$$= \frac{\frac{1}{4}y_1^2 - \frac{1}{2}y_1y_2 + y_2^2}{y_1^2 + y_2^2} \quad \begin{pmatrix} y_1 = 2x_1 \\ y_2 = x_2 \end{pmatrix}$$

$$A_2 = \begin{bmatrix} \frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & 1 \end{bmatrix} \Rightarrow \begin{aligned} & (\lambda - \frac{1}{4})(\lambda - 1) - \frac{1}{4^2} \\ & = \lambda^2 - \frac{5}{4}\lambda + \frac{3}{4^2} \\ & = \left(\lambda - \frac{5}{8}\right)^2 - \frac{13}{8^2} \end{aligned}$$

$$\therefore \lambda_{\min} = \frac{5-\sqrt{13}}{8}$$

$$\therefore \min R_2(\mathbf{x}) = \lambda_{\min}$$

$$= \frac{5-\sqrt{13}}{8}$$

7. (10 points) Show that for any two different vectors of the same length, $\|\mathbf{x}\| = \|\mathbf{y}\|$, the Householder transformation with $\mathbf{v} = \mathbf{x} - \mathbf{y}$ gives $H\mathbf{x} = \mathbf{y}$ and $H\mathbf{y} = \mathbf{x}$.

$$\begin{aligned}
 H\mathbf{x} &= \left[\mathbf{I} - 2 \cdot \frac{(\mathbf{x}-\mathbf{y})(\mathbf{x}-\mathbf{y})^T}{(\mathbf{x}-\mathbf{y})^T(\mathbf{x}-\mathbf{y})} \right] \mathbf{x} \\
 &= \mathbf{x} - 2 \cdot \frac{(\mathbf{x}-\mathbf{y}) \cdot (\mathbf{x}^T \mathbf{x} - \mathbf{y}^T \mathbf{x})}{\mathbf{x}^T \mathbf{x} - \mathbf{y}^T \mathbf{x} - \mathbf{x}^T \mathbf{y} + \mathbf{y}^T \mathbf{y}} \\
 &= \mathbf{x} - (\mathbf{x}-\mathbf{y}) \cdot \frac{2(\mathbf{x}^T \mathbf{x} - \mathbf{x}^T \mathbf{y})}{2\mathbf{x}^T \mathbf{x} - 2\mathbf{x}^T \mathbf{y}} \quad \begin{array}{l} \text{as } \mathbf{x}^T \mathbf{x} = \mathbf{y}^T \mathbf{y} \\ \mathbf{x}^T \mathbf{y} = \mathbf{y}^T \mathbf{x} \end{array} \\
 &= \mathbf{x} - \mathbf{x} + \mathbf{y} \\
 &= \mathbf{y} \\
 H\mathbf{y} &= \mathbf{y} - 2 \cdot \frac{(\mathbf{x}-\mathbf{y})(\mathbf{x}-\mathbf{y})^T}{(\mathbf{x}-\mathbf{y})^T(\mathbf{x}-\mathbf{y})} \cdot \mathbf{y} \\
 &= \mathbf{y} - (\mathbf{x}-\mathbf{y}) \cdot \frac{2(\mathbf{x}^T \mathbf{y} - \mathbf{y}^T \mathbf{y})}{\mathbf{x}^T \mathbf{x} - \mathbf{y}^T \mathbf{x} - \mathbf{x}^T \mathbf{y} + \mathbf{y}^T \mathbf{y}} \\
 &= \mathbf{y} + (\mathbf{x}-\mathbf{y}) \cdot \frac{2(\mathbf{y}^T \mathbf{y} - \mathbf{x}^T \mathbf{y})}{2\mathbf{y}^T \mathbf{y} - 2\mathbf{x}^T \mathbf{y}} \\
 &= \mathbf{y} + \mathbf{x} - \mathbf{y} \\
 &= \mathbf{x}
 \end{aligned}$$

8. (10 points) Find the tridiagonal matrix HAH^{-1} that is similar to

$$A = \begin{bmatrix} 1 & 3 & 4 \\ 3 & 1 & 0 \\ 4 & 0 & 0 \end{bmatrix}.$$

$$\mathbf{v} = \begin{bmatrix} 0 \\ 3 \\ 4 \end{bmatrix} + \begin{bmatrix} 0 \\ 5 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 8 \\ 4 \end{bmatrix}$$

$$\begin{aligned} H &= I - 2 \cdot \frac{\mathbf{v} \cdot \mathbf{v}^T}{\mathbf{v}^T \cdot \mathbf{v}} \\ &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \frac{2}{80} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 64 & 32 \\ 0 & 32 & 16 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & -0.6 & -0.8 \\ 0 & -0.8 & 0.6 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} HAH^{-1} &= HAH \\ &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & -0.6 & -0.8 \\ 0 & -0.8 & 0.6 \end{bmatrix} \begin{bmatrix} 1 & 3 & 4 \\ 3 & 1 & 0 \\ 4 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -0.6 & -0.8 \\ 0 & -0.8 & 0.6 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 3 & 4 \\ -5 & -0.6 & 0 \\ 0 & -0.8 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -0.6 & -0.8 \\ 0 & -0.8 & 0.6 \end{bmatrix} \\ &= \begin{bmatrix} 1 & -5 & 0 \\ -5 & 0.36 & 0.48 \\ 0 & 0.48 & 0.64 \end{bmatrix} \end{aligned}$$

9. (20 points) In solving the following matrix equation

$$\begin{bmatrix} 3 & -1 \\ -1 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

- (a) (5 points) using the Jacobi method,
- (b) (5 points) the Gauss-Seidel method, and
- (c) (10 points) the SOR,

compute the maximum absolute eigenvalues of their respective crucial matrices $S^{-1}T$:

$$(a) S^{-1}T = \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix}^{-1} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & \frac{1}{3} \\ \frac{1}{3} & 0 \end{bmatrix}$$

$$\therefore \lambda = \pm \frac{1}{3}, \quad |\lambda|_{\max} = \frac{1}{3} = \mu_{\max}$$

$$(b) S^{-1}T = \begin{bmatrix} 3 & 0 \\ -1 & 3 \end{bmatrix}^{-1} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & \frac{1}{3} \\ 0 & \frac{1}{9} \end{bmatrix}$$

$$\lambda_1 = 0, \lambda_2 = \frac{1}{9}, \quad |\lambda|_{\max} = \frac{1}{9} = \left(\frac{1}{3}\right)^2$$

$$(c) S^{-1}T = \begin{bmatrix} 3 & 0 \\ -\omega & 3 \end{bmatrix}^{-1} \begin{bmatrix} 3(1-\omega) & \omega \\ 0 & 3(1-\omega) \end{bmatrix}$$

$$= \begin{bmatrix} 1-\omega & \frac{1}{3}\omega \\ \frac{1}{3}\omega & 1-\omega + \frac{1}{9}\omega^2 \end{bmatrix}$$

$$\omega_{opt} = \frac{2(1 - \sqrt{1 - \mu_{\max}^2})}{\mu_{\max}^2} = 18 \left(1 - \sqrt{\frac{8}{9}}\right)$$

$$|\lambda|_{\max} = \omega_{opt} - 1 = \underbrace{17 - 12\sqrt{2}}$$