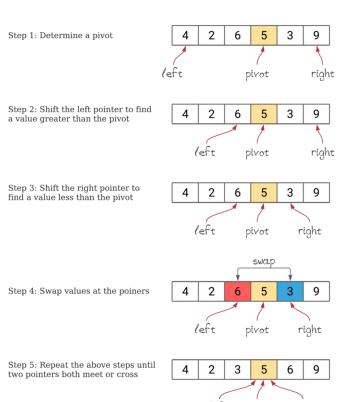
Quicksort (group 2)

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General description of the algorithm

- Based on divide and conquer paradigm
- First, partitions the array into two parts
- Then, sorts the two parts independently
- Finally, it combines the two sorted parts via a simple concatenation

Demonstration: How it works (review code/algorithm)



```
QUICKSORT(A, p, r)
  if p < r
      q = PARTITION(A, p, r)
      QUICKSORT(A, p, q - 1)
      QUICKSORT(A, q + 1, r)
Partition(A, p, r)
  x = A[r]
2 i = p - 1
  for j = p to r - 1
       if A[j] \leq x
          i = i + 1
           exchange A[i] with A[j]
   exchange A[i+1] with A[r]
   return i+1
```

Advantages?

- Quicksort is an inplace sorting algorithm so no new space complexity is created.
- In practice, quicksort is often laster than other O(nlogn) algorithms

Disadvantages?

- Quicksort has a worst complexity of O(n^2). In some cases we are losing complexity time when compared to a better worst case complexity sorting algorithm such as mergeSort
- It has to utilize recursion
- Not always stable

Complexity (in the worst case—that is Big-Oh!)

- Worst case complexity is n^2
 - This can happen when every item of the array is already in order
 - When the pivot is an extreme, requiring the maximum number of iterations
- Best and average case is usually n log (n)
 - Log part comes from dividing into subsequences

Would you recommend this algorithm? Why or why not?

- Primarily recommend its uses for information sorting due to its speed
- Also ideal for commercial computation settings (ex. organizations sorting accounts by name or ID)
- For shorter array sizes quicksort is more efficient than say Merge Sort. If the problem is for smaller cases and "quick" sorting then quicksort can be a solution.
- For situations where the users determine the order to sort by, quicksort may not be the most ideal solution

References

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