05_Support_Vector_Machine

5.0 A Quick View

What does it do?

- Find an optimized separating plane to
 - Separate samples of 2 classes
 - Maximize the margins

Summary

	G	Constraint	Solution
Reg	$G = \sum_{i=1}^N \lambda_i - rac{1}{2} \sum_{i=1}^N \sum_{j=1}^N (\lambda_i \lambda_j) \cdot (y_i y_j) \cdot \mathbf{x}_i^ op \mathbf{x}_j$	$egin{cases} \lambda_i \geq 0 \ \sum_{i=1}^N \lambda_i y_i = 0 \end{cases}$	$f(\mathbf{x}) = (\sum_{i=1}^N \lambda_i y_i)$
SfMg	$G = \sum_{i=1}^N \lambda_i - rac{1}{2} \sum_{i=1}^N \sum_{j=1}^N (\lambda_i \lambda_j) \cdot (y_i y_j) \cdot \mathbf{x}_i^ op \mathbf{x}_j$	$\left\{egin{aligned} 0 \leq \lambda_i \leq C \ \sum_{i=1}^N \lambda_i y_i = 0 \end{aligned} ight.$	$f(\mathbf{x}) = (\sum_{i=1}^N \lambda_i y_i)$
NLin	$G = \sum_{i=1}^N \lambda_i - rac{1}{2} \sum_{i=1}^N \sum_{j=1}^N (\lambda_i \lambda_j) \cdot (y_i y_j) \cdot K(\mathbf{x}_i, \mathbf{x}_j)$	$egin{cases} \lambda_i \geq 0 \ \sum_{i=1}^N \lambda_i y_i = 0 \end{cases}$	$f(\mathbf{x}) = \sum_{i=1}^N \lambda_i y_i I$

5.1 Margin

5.1.1 Motive

Given

- A set of multi-dimensional linearly separable classes
 - $\mathcal{X} = \{\mathbf{x}_1, \mathbf{x}_2, \cdots, \mathbf{x}_N\}$
- Two classes to categorize samples in \mathcal{X} :
 - $\omega = \{\omega_{(1)}, \omega_{(2)}\}$
- A mapping relation of $\mathcal{D} \in \mathcal{X} \times \omega$

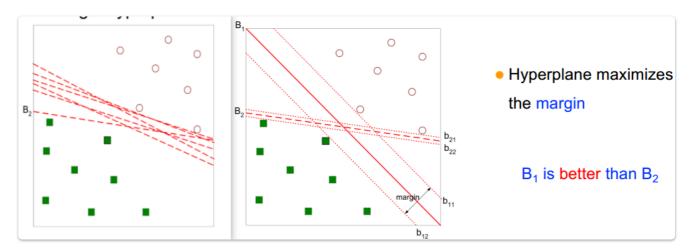
–
$$\mathcal{D} = \{raket{\mathbf{x}_1, \omega_1}raket{\mathbf{x}_2, \omega_2} \cdots, raket{\mathbf{x}_N, \omega_N}\}$$

Do

• Find a hyperplane $\mathbf{w}^{\top}\mathbf{x} + b = 0$ that separates the two classes.

w is the normal vector of this hyperplane.

From multiple possible solutions, we want the one that maximizes the margin.



5.1.2 Distance to Hyperplane

i The distance from each sample x_i to the hyperplane is:

$$r = rac{\mathbf{w}^ op \mathbf{x}_i + b}{\|\mathbf{w}\|}$$

Proof. Suppose that \mathbf{x}_p is the projection of a data sample \mathbf{x}_i on the hyperplane $\mathbf{w}^{\top}\mathbf{x}+b=0$. Therefore,

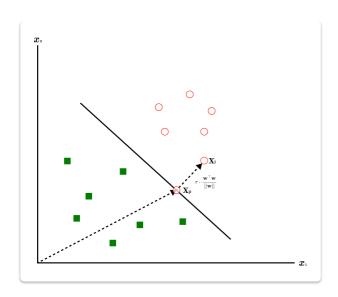
$$\mathbf{x}_i = \mathbf{x}_p + r \cdot \frac{\mathbf{w}}{\|\mathbf{w}\|}$$

namely,

$$\begin{split} \mathbf{w}^{\top} \mathbf{x}_i + b &= \mathbf{w}^{\top} (\mathbf{x}_p + r \cdot \frac{\mathbf{w}}{\|\mathbf{w}\|}) + b \\ &= \mathbf{w}^{\top} \mathbf{x}_p + b + r \cdot \frac{\mathbf{w}^{\top} \mathbf{w}}{\|\mathbf{w}\|} \\ &= 0 + r \cdot \frac{\mathbf{w}^{\top} \mathbf{w}}{\|\mathbf{w}\|} \\ &= r \cdot \frac{\mathbf{w}^{\top} \mathbf{w}}{\|\mathbf{w}\|} \end{split}$$

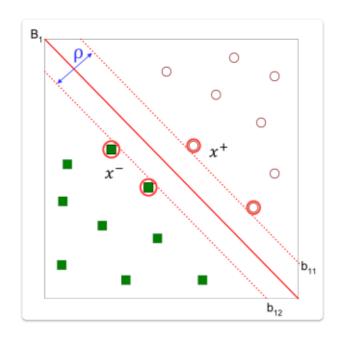
Thus,

$$egin{aligned} r &= (\mathbf{w}^{ op} \mathbf{x}_i + b) \cdot rac{||\mathbf{w}||}{\mathbf{w}^{ op} \mathbf{w}} \ &= (\mathbf{w}^{ op} \mathbf{x}_i + b) \cdot rac{||\mathbf{w}||}{||\mathbf{w}||^2} \ &= rac{\mathbf{w}^{ op} \mathbf{x}_i + b}{||\mathbf{w}||} \end{aligned}$$



5.1.3 Support Vectors and Margin

- Support Vectors are:
 - A subset of training samples
 - Samples closes to the hyperplane
- **1** Margin ρ is the distance between support vectors.
 - The hyperplane is to maximize the margin ρ .



In the above graph, there are 3 hyperplanes:

$$B_1: \mathbf{w}^{\top}\mathbf{x} + b = 0$$

$$b_{11}: \mathbf{w}^{\top}\mathbf{x} + b = +1$$

$$b_{12}: \mathbf{w}^{\top}\mathbf{x} + b = -1$$

Where \mathbf{x}^+ and \mathbf{x}^- lies on the hyperplanes b_{11} and b_{12} . Then:

$$\mathbf{w}^{\top}(\mathbf{x}^{+} - \mathbf{x}^{-}) = \mathbf{w}^{\top}\mathbf{x}^{+} - \mathbf{w}^{\top}\mathbf{x}^{-}$$

$$= (\mathbf{w}^{\top}\mathbf{x}^{+} + b) - (\mathbf{w}^{\top}\mathbf{x}^{-} + b)$$

$$= (1) - (-1)$$

$$= 2$$

The margin would be:

$$ho = rac{\mathbf{w}^{ op}(\mathbf{x}^{+} - \mathbf{x}^{-})}{\|\mathbf{w}\|} \ = rac{2}{\|\mathbf{w}\|}$$

5.2 Quadratic Optimization

5.2.1 Formulation

Let

- $\mathcal{X} = \{\mathbf{x}_1, \mathbf{x}_2, \cdots, \mathbf{x}_N\}$ be the data set
- $y=\{y_1,y_2,\cdots,y_N\}\subset\{-1,1\}^N$ be the class labels of the corresponding data in \mathcal{X} .
- Find the optimal w such that:
 - $ho = rac{2}{\|\mathbf{w}\|}$ is maximized, and

$$egin{aligned} egin{aligned} \mathbf{w}^ op \mathbf{x}_i + b \geq 1 & ext{if } y_i = +1 \ \mathbf{w}^ op \mathbf{x}_i + b \leq -1 & ext{if } y_i = -1 \end{aligned} ext{ for } i = 1, 2, \cdots, N$$

Maximizing the margin $ho = \frac{2}{\|\mathbf{w}\|}$ is equivalent to minimizing:

$$\frac{1}{2}\|\mathbf{w}\|^2 = \frac{1}{2}\mathbf{w}^\top\mathbf{w}$$

- ★ The formulated quadratic optimization problem of SVM is:
- Minimize: $\frac{1}{2} \|\mathbf{w}\|^2$
- With constraint: $y_i(\mathbf{w}^\top + b) \ge 1, \ \forall \ 1, 2, \cdots, N$

5.2.2 Lagrangian of Quadratic Optimization

★ The Lagrangian of the quadratic optimization problem is:

$$L(\mathbf{w},b) = rac{1}{2}\mathbf{w}^ op \mathbf{w} + \sum_{i=1}^N \lambda_i (1-y_i(\mathbf{w}^ op \mathbf{x}_i + b))$$

where $\lambda_1, \lambda_2, \cdots, \lambda_N \geq 0$ is the Lagrangian multiplier of all the data points in \mathcal{X} respectively.

- ★ At the end, only the support vector's Lagrangian multiplier would be non-zero.
- That is $\lambda_i \neq 0$ if and only if \mathbf{x}_i is a support vector.
- Non-support vectors won't contribute to the hyper plane.

Suppose that we have already found a series of such Lagrangian multipliers. To optimize L, we compute the partial derivatives of L with respect to \mathbf{w} and b.

Optimize L w.r.t. w.

$$egin{aligned} rac{dL}{d\mathbf{w}} &= \mathbf{w} + rac{dL}{d\mathbf{w}} \sum_{i=1}^N \lambda_i - (\lambda_i y_i) \mathbf{w}^ op \mathbf{x}_i - (\lambda_i y_i b) \ &= \mathbf{w} + \sum_{i=1}^N -\lambda_i y_i \mathbf{x}_i \ &= \mathbf{w} - \sum_{i=1}^N \lambda_i y_i \mathbf{x}_i \end{aligned}$$

Let $\frac{dL}{d\mathbf{w}} = 0$.

$$\mathbf{w} = \sum_{i=1}^N \lambda_i y_i \mathbf{x}_i$$

Optimize L w.r.t. b

$$egin{aligned} rac{dL}{db} &= 0 + rac{dL}{db} \sum_{i=1}^N \lambda_i - (\lambda_i y_i) \mathbf{w}^ op \mathbf{x}_i - (\lambda_i y_i b) \ &= \sum_{i=1}^N -\lambda_i y_i \ &= -\sum_{i=1}^N \lambda_i y_i \end{aligned}$$

Let $\frac{dL}{db} = 0$.

$$\sum_{i=1}^N \lambda_i y_i = 0$$

★ Therefore, the optimized weight and bias of this quadratic is:

$$\mathbf{w} = \sum_{i=1}^N \lambda_i y_i \mathbf{x}_i$$

* with a constraint of:

$$\sum_{i=1}^N \lambda_i y_i = 0$$

with respect to $\lambda_1, \lambda_2, \cdots, \lambda_N \geq 0$.

5.2.3 Dual Problem

Get λ with optimized L

Substitute $\mathbf{w}=\sum_{i=1}^N \lambda_i y_i \mathbf{x}_i$ and $\sum_{i=1}^N \lambda_i y_i = 0$ into $L(\mathbf{w},b)$ would result in:

$$\begin{split} L(\mathbf{w},b) &= \frac{1}{2} \left(\sum_{i=1}^{N} \lambda_{i} y_{i} \mathbf{x}_{i} \right)^{\top} \left(\sum_{i=1}^{N} \lambda_{i} y_{j} \mathbf{x}_{i} \right) \\ &+ \sum_{i=1}^{N} \lambda_{i} (1 - y_{i} \left(\left(\sum_{j=1}^{N} \lambda_{j} y_{j} \mathbf{x}_{j} \right)^{\top} \mathbf{x}_{i} + b \right)) \\ &= \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} (\lambda_{i} \lambda_{j}) \cdot (y_{i} y_{j}) \cdot \mathbf{x}_{i}^{\top} \mathbf{x}_{j} \\ &+ \sum_{i=1}^{N} \lambda_{i} - \sum_{i=1}^{N} (\lambda_{i} y_{i}) \cdot \left(\sum_{j=1}^{N} (\lambda_{j} y_{j}) \cdot \mathbf{x}_{j}^{\top} \mathbf{x}_{i} + b \right) \\ &= \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} (\lambda_{i} \lambda_{j}) \cdot (y_{i} y_{j}) \cdot \mathbf{x}_{i}^{\top} \mathbf{x}_{j} \\ &+ \sum_{i=1}^{N} \lambda_{i} - \sum_{i=1}^{N} \left(\sum_{j=1}^{N} (\lambda_{i} y_{i}) \cdot (\lambda_{j} y_{j}) \cdot \mathbf{x}_{j}^{\top} \mathbf{x}_{i} + b (\lambda_{i} y_{i}) \right) \\ &= \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} (\lambda_{i} \lambda_{j}) \cdot (y_{i} y_{j}) \cdot \mathbf{x}_{i}^{\top} \mathbf{x}_{j} \\ &+ \sum_{i=1}^{N} \lambda_{i} - \sum_{i=1}^{N} \sum_{j=1}^{N} (\lambda_{i} \lambda_{j}) \cdot (y_{i} y_{j}) \cdot \mathbf{x}_{i}^{\top} \mathbf{x}_{j} \\ &+ \sum_{i=1}^{N} \lambda_{i} \\ &+ b \sum_{i=1}^{N} \sum_{j=1}^{N} (\lambda_{i} y_{i}) \\ &= \sum_{i=1}^{N} \lambda_{i} - \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} (\lambda_{i} \lambda_{j}) \cdot (y_{i} y_{j}) \cdot \mathbf{x}_{i}^{\top} \mathbf{x}_{j} \end{split}$$

The original criterion function is now with respect to only λ . That is:

$$G(\lambda) = \sum_{i=1}^N \lambda_i - rac{1}{2} \sum_{i=1}^N \sum_{j=1}^N (\lambda_i \lambda_j) \cdot (y_i y_j) \cdot \mathbf{x}_i^ op \mathbf{x}_j$$

Optimize $G(\lambda)$ by computing:

$$rac{dG}{d\lambda_i}, \ orall i=2,3,\cdots,N$$

Check the solutions if they satisfy the constraint of:

$$egin{cases} \lambda_i > 0 \ \sum_{i=1}^N \lambda_i y_i = 0 \end{cases}$$

5.2.4 Solutions: Regular

Maximize:

$$G(\lambda) = \sum_{i=1}^N \lambda_i - rac{1}{2} \sum_{i=1}^N \sum_{j=1}^N (\lambda_i \lambda_j) \cdot (y_i y_j) \cdot \mathbf{x}_i^ op \mathbf{x}_j$$

with constraint:

$$egin{cases} \lambda_i \geq 0 \ \sum_{i=1}^N \lambda_i y_i = 0 \end{cases}$$

The dual solution is:

$$f(\mathbf{x}) = (\sum_{i=1}^N \lambda_i y_i \mathbf{x}_i)^ op \mathbf{x} + b$$

with:

$$egin{cases} \mathbf{w} = \sum_{i=1}^{N} \lambda_i y_i \mathbf{x}_i \ b = y_k - (\sum_{i=1}^{N} \lambda_i y_i \mathbf{x}_i^ op) \mathbf{x}_k \end{cases}$$

5.3 Soft Margin Classification

5.3.1 Problem Setup

There exists conditions that training samples can't be separated.

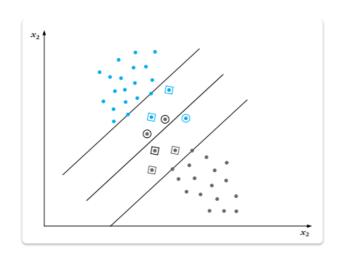
- In this case, no hyperplane could satisfy $y_i(\mathbf{w}^{ op}\mathbf{x}+b)>1, \ orall \mathbf{x}.$
- i.e., $\neg \exists \mathbf{w}, b, \forall \mathbf{x}, \ y_i(\mathbf{w}^\top \mathbf{x} + b) > 1$

Training samples belong to one of the three possible categories.

- Correctly Classified: Samples outside the margin.
 - $y_i(\mathbf{w}^\top + b) > 1$
- Margin Violation: Samples within the margin, but correctly classified.

•
$$y_i(\mathbf{w}^\top + b) > 1$$

- Misclassified samples:
 - $ullet y_i(\mathbf{w}^ op + b) < 0$



5.3.2 Slack Variables & Parameter C 松弛因子与C参数

Assignment of ξ_i

Assign slack variables $\xi_1, \xi_2, \dots, \xi_N \geq 0$ to all the samples in \mathcal{X} .

• Correctly Classified: $\xi_i=0$

• Margin Violation: $0 \le \xi_i \le 1$

• Misclassified Variables: $\xi_i > 1$

i About slack variables ξ_i .

• ξ_i allows misclassification of difficult or noisy samples.

• The resulting is called a Soft Margin.

• If ξ_i is sufficiently large, every constraint will be forced to be satisfied.

• ξ_i is based on the output of the discriminant function $f(\mathbf{x}) = \mathbf{w}^{\top}\mathbf{x} + b$.

• ξ_i approximates the number of mis-classified samples.

Intuitive Optimization

The optimization problem becomes:

• Minimize: $\frac{1}{2}\|\mathbf{w}\|^2 + C\sum_{i=1}^N \xi_i$

• With constraint: $y_i(\mathbf{w}^ op + b) \geq 1 - \xi_i, \ orall \ 1, 2, \cdots, N$

 $oldsymbol{1}$ The parameter C is a user-selected regularization parameter.

• A trade-off parameter between:

error and

margin

• Effects of parameter C:

• Smaller C = Large Margin & More error, allows constraints to be easily ignored.

• Larger C = Narrow Margin & Less error, constraints is hard to ignore.

• $C = \infty$ = Hard Margin, which enforces all constraints.

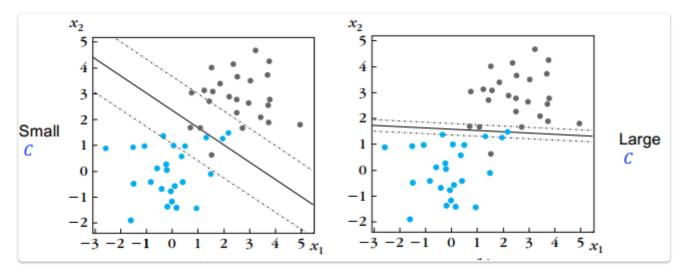
Corresponding Dual Problem

Which transfer to the dual problem as

$$G(\lambda) = \sum_{i=1}^N \lambda_i - rac{1}{2} \sum_{i=1}^N \sum_{j=1}^N (\lambda_i \lambda_j) \cdot (y_i y_j) \cdot \mathbf{x}_i^ op \mathbf{x}_j$$

with the constraints of:

$$egin{cases} 0 \leq \lambda_i \leq C \ \sum_{i=1}^N \lambda_i y_i = 0 \end{cases}$$



5.3.3 Solutions: Soft Margin

Maximize:

$$G(\lambda) = \sum_{i=1}^N \lambda_i - rac{1}{2} \sum_{i=1}^N \sum_{j=1}^N (\lambda_i \lambda_j) \cdot (y_i y_j) \cdot \mathbf{x}_i^ op \mathbf{x}_j$$

with constraint:

$$\left\{egin{aligned} 0 \leq \lambda_i \leq C \ \sum_{i=1}^N \lambda_i y_i = 0 \end{aligned}
ight.$$

The dual solution is:

$$f(\mathbf{x}) = (\sum_{i=1}^N \lambda_i y_i \mathbf{x}_i)^ op \mathbf{x} + b$$

with:

$$egin{cases} \mathbf{w} = \sum_{i=1}^{N} \lambda_i y_i \mathbf{x}_i \ \ b = y_k (1 - \xi_k) - (\sum_{i=1}^{N} \lambda_i y_i \mathbf{x}_i^ op) \mathbf{x}_k \end{cases}$$

5.4 Non-Linear SVM

5.4.0 Basics

Why Non-Linear SVM?

Datasets may be too hard for linear separation.

What does it do?

- Transform data into a higher dimensional space H,
 - via a mapping function Φ
 - such that the data appears of the form $\Phi(\mathbf{x}_i)\Phi(\mathbf{x}_i)$.
- Linear separation in **H** is *equivalent* to non-linear separation in the original input space.

Problems

- High dimensionality results in high computation burden.
- Hard to obtain a good estimation.

5.4.1 Kernel Function

- A kernel of two data is:
 - The inner product between the vectors
 - $ullet K(\mathbf{x}_i,\mathbf{x}_j) = \mathbf{x}_i^ op \mathbf{x}_j$

Suppose that each data point is mapped into high-dimensional space via transformation of:

$$\Phi: \mathbf{x} \mapsto \phi(\mathbf{x})$$

Then, the kernel of two data becomes:

$$K(\mathbf{x}_i, \mathbf{x}_j) = \phi(\mathbf{x}_i)^{\top} \phi(\mathbf{x}_j)$$

We could compute $K(\mathbf{x}_i, \mathbf{x}_j)$ without computing $\phi(\mathbf{x}_i)$ and $\phi(\mathbf{x}_j)$ explicitly.

5.4.2 Compute Kernel

We could compute kernel $K(\mathbf{x}_i, \mathbf{x}_j)$ in the original space. Suppose that the original space is of 2 dimensions. Let $K(\mathbf{x}_i, \mathbf{x}_j) = (1 + \mathbf{x}_i^{\top} \mathbf{x}_j)^2$, then $K(\mathbf{x}_i, \mathbf{x}_j) = (1 + \mathbf{x}_i^{\top} \mathbf{x}_j)^2$.

Proof.

$$egin{align*} K(\mathbf{x}_i,\mathbf{x}_j) &= (1+\mathbf{x}_i^{ op}\mathbf{x}_j)^2 \ &= (1+[x_{i1} \quad x_{i2}] \begin{bmatrix} x_{j1} \ x_{j2} \end{bmatrix})^2 \ &= \left(1+(x_{i1}x_{j1}+x_{i2}x_{j2})
ight)^2 \ &= 1+(x_{i1}x_{j1}+x_{i2}x_{j2})^2 - 2((x_{i1}x_{j1}+x_{i2}x_{j2})) \ &= x_{i1}^2x_{j1}^2+x_{i2}^2x_{j2}^2+2x_{i1}x_{j1}x_{i2}x_{j2}+2x_{i1}x_{j1}+2x_{i2}x_{j2}+1 \ &= \left[x_{i1}^2 \quad x_{i2}^2 \quad \sqrt{2}x_{i1}x_{i2} \quad \sqrt{2}x_{i1} \quad \sqrt{2}x_{i2} \quad 1\right] \begin{bmatrix} x_{j1}^2 \ x_{j2}^2 \ \sqrt{2}x_{j1}x_{j2} \ \sqrt{2}x_{j1} \ \sqrt{2}x_{j2} \ 1 \end{bmatrix} \ &= \phi(\mathbf{x}_i)^{ op}\phi(\mathbf{x}_j) \end{split}$$

where

$$\phi(\mathbf{x}) = \phi(egin{bmatrix} x_1 \ x_2 \end{bmatrix}) = egin{bmatrix} x_1^2 \ x_2^2 \ \sqrt{2}x_1x_2 \ \sqrt{2}x_1 \ \sqrt{2}x_2 \ 1 \end{bmatrix}$$

5.4.3 Kernel Examples

	Kernel	Mapping
Linear	$K(\mathbf{x}_i,\mathbf{x}_j) = \mathbf{x}_i^ op \mathbf{x}_j$	$oldsymbol{\Phi}: \mathbf{x} \mapsto \phi(\mathbf{x}) = \mathbf{x}$
Polynomial	$K(\mathbf{x}_i,\mathbf{x}_j) = (1+\mathbf{x}_i^ op \mathbf{x}_j)^p$	$oldsymbol{\Phi}: \mathbf{x} \mapsto \phi(\mathbf{x}) \in \mathbb{R}^{rac{(d+p)!}{p!d!}}$
Sigmoid	$K(\mathbf{x}_i,\mathbf{x}_j) = anh(eta_0\mathbf{x}_i^ op\mathbf{x}_j + eta_1)$	
Gaussian	$K(\mathbf{x}_i,\mathbf{x}_j) = e^{rac{\ x_i-x_j\ ^2}{2\sigma}}$	$oldsymbol{\Phi}: \mathbf{x} \mapsto \phi(\mathbf{x}) \in \mathbb{R}^{\infty}$

5.4.4 Solutions: Non-Linear

Maximize:

$$G(\lambda) = \sum_{i=1}^N \lambda_i - rac{1}{2} \sum_{i=1}^N \sum_{j=1}^N (\lambda_i \lambda_j) \cdot (y_i y_j) \cdot K(\mathbf{x}_i, \mathbf{x}_j)$$

with constraint:

$$egin{cases} \lambda_i \geq 0 \ \sum_{i=1}^N \lambda_i y_i = 0 \end{cases}$$

The dual solution:

$$f(\mathbf{x}) = \sum_{i=1}^N \lambda_i y_i K(\mathbf{x}_i, \mathbf{x}) + b$$

5.5 Examples

Non-Linear

Given

Suppose we have five 1-D datapoints:

•
$$x_1 = 1, x_2 = 2, x_3 = 3, x_4 = 5, x_5 = 6$$

• Their corresponding classes are:

•
$$y_1 = 1, y_2 = 1, y_3 = -1, y_4 = -1, y_5 = 1$$

• Use the degree-2 polynomial kernel:

$$-K(x_i,x_j)=(x_ix_j+1)^2$$

Do

Step 1. Find λ_i .

Maximize:

$$G(\lambda) = \sum_{i=1}^N \lambda_i - rac{1}{2} \sum_{i=1}^N \sum_{j=1}^N (\lambda_i \lambda_j) \cdot (y_i y_j) \cdot (1 + x_i x_j)^2$$

with constraint:

$$\sum_{i=1}^N \lambda_i y_i = 0$$

Using a quadratic problem solver, we obtain:

$$\lambda_1 = 0, \ \lambda_2 = 2.5, \ \lambda_3 = 0, \ \lambda_4 = 7.333, \ \lambda_5 = 4.833$$

Step 2. Calculate.

The support vectors are:

$$x_2=2,\ x_4=5,\ x_5=6$$

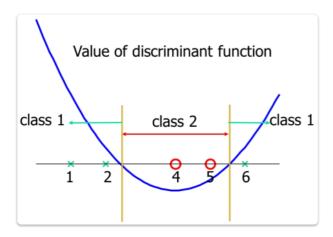
The discriminant function is:

$$egin{split} f(x) &= \sum_{i=1}^N \lambda_i y_i K(x_i,x) + b \ &= \sum_{i=1}^N \lambda_i y_i (1+x_i x)^2 + b \ &= 2.5 \cdot 1 \cdot (1+2x)^2 + 7.333 \cdot (-1) \cdot (1+5x)^2 + 4.833 \cdot 1 \cdot (1+6x)^2 + b \ &= 0.6667 x^2 - 5.333 x + b \end{split}$$

Given that f(6) = 1, b = 9.

We obtained the discriminant function of:

$$f(x) = 0.6667x^2 - 5.333x + 9$$



Linear

Given

Suppose we have three 2-D data points.

$$\bullet \ \ \mathbf{x}_1 = {2 \choose 1}, \ \mathbf{x}_2 = {1 \choose 2}, \ \mathbf{x}_3 = {3 \choose 3}$$

Their corresponding labels are:

•
$$y_1 = 1, y_2 = -1, y_3 = -1$$

• Use the trivial kernel:

–
$$K(\mathbf{x}_i,\mathbf{x}_j) = \mathbf{x}_i^ op \mathbf{x}_j$$

Do

Step 1. Find λ .

$$G(\lambda) = \sum_{i=1}^N \lambda_i - rac{1}{2} \sum_{i=1}^N \sum_{j=1}^N (\lambda_i \lambda_j) \cdot (y_i y_j) \cdot \mathbf{x}_i^ op \mathbf{x}_j$$

1-1. Constraint:

$$egin{aligned} \sum_{i=1}^N \lambda_i y_i &= 0 \Longrightarrow \ \lambda_1 - \lambda_2 - \lambda_3 = 0 \ \Longrightarrow \ \lambda_1 &= \lambda_2 + \lambda_3 \end{aligned}$$

1-2. Express $G(\lambda)$ with λ_1 , λ_2 and λ_3 .

$$rac{1}{2} \sum_{i=1}^N (\lambda_i \lambda_j) \cdot (y_i y_j) \cdot \mathbf{x}_i^ op \mathbf{x}_j = \sum_{i=1}^N \lambda_i - G(\lambda)$$

$$egin{aligned} \Longrightarrow rac{1}{2} \sum_{i=1}^{N} \Big(\ & (\lambda_{i}\lambda_{1}) \cdot (y_{i}y_{1}) \cdot \mathbf{x}_{i}^{ op} \mathbf{x}_{1} + \ & (\lambda_{i}\lambda_{2}) \cdot (y_{i}y_{2}) \cdot \mathbf{x}_{i}^{ op} \mathbf{x}_{2} + \ & (\lambda_{i}\lambda_{3}) \cdot (y_{i}y_{3}) \cdot \mathbf{x}_{i}^{ op} \mathbf{x}_{3} \end{aligned} \ egin{aligned} \Big) = \sum_{i=1}^{N} \lambda_{i} - G(\lambda) \end{aligned}$$

$$egin{aligned} \Longrightarrow & rac{1}{2} \Big(\ & (\lambda_1 \lambda_1) \cdot (y_1 y_1) \cdot \mathbf{x}_1^ op \mathbf{x}_1 + (\lambda_1 \lambda_2) \cdot (y_1 y_2) \cdot \mathbf{x}_1^ op \mathbf{x}_2 + (\lambda_1 \lambda_3) \cdot (y_1 y_3) \cdot \mathbf{x}_1^ op \mathbf{x}_3 + \ & (\lambda_2 \lambda_1) \cdot (y_2 y_1) \cdot \mathbf{x}_2^ op \mathbf{x}_1 + (\lambda_2 \lambda_2) \cdot (y_2 y_2) \cdot \mathbf{x}_2^ op \mathbf{x}_2 + (\lambda_2 \lambda_3) \cdot (y_2 y_3) \cdot \mathbf{x}_2^ op \mathbf{x}_3 + \ & (\lambda_3 \lambda_1) \cdot (y_3 y_1) \cdot \mathbf{x}_3^ op \mathbf{x}_1 + (\lambda_3 \lambda_2) \cdot (y_3 y_2) \cdot \mathbf{x}_3^ op \mathbf{x}_2 + (\lambda_3 \lambda_3) \cdot (y_3 y_3) \cdot \mathbf{x}_3^ op \mathbf{x}_3 \\ \Big) = \sum_{i=1}^N \lambda_i - G(\lambda) \end{aligned}$$

$$\begin{split} \Longrightarrow \frac{1}{2} \Big(\\ 5\lambda_1^2 - 4\lambda_1\lambda_2 - 9\lambda_1\lambda_3 \\ - 4\lambda_1\lambda_2 + 5\lambda_2^2 + 9\lambda_2\lambda_3 \\ - 9\lambda_1\lambda_3 + 9\lambda_3\lambda_3 + 18\lambda_3^2 \\ \Big) = \lambda_1 + \lambda_2 + \lambda_3 - G(\lambda) \end{split}$$

$$\Longrightarrow G(\lambda) = -rac{1}{2}(5\lambda_1^2 + 5\lambda_2^2 + 18\lambda_3^2 - 8\lambda_1\lambda_2 - 18\lambda_1\lambda_3 + 18\lambda_2\lambda_3) \ + (\lambda_1 + \lambda_2 + \lambda_3)$$

$$\Longrightarrow G(\lambda) = -rac{1}{2}(5(\lambda_2+\lambda_3)^2+5\lambda_2^2+18\lambda_3^2-8(\lambda_2+\lambda_3)\lambda_2-18(\lambda_2+\lambda_3)\lambda_3+18\lambda_2\lambda_3) \ +((\lambda_2+\lambda_3)+\lambda_2+\lambda_3)$$

$$\Longrightarrow G(\lambda) = -\lambda_2^2 - rac{5}{2}\lambda_3^2 - \lambda_2\lambda_3 + 2\lambda_2 + 2\lambda_3$$

1-3. Minimize $G(\lambda)$

$$\frac{\partial G}{\partial \lambda_3} = 0$$

$$\implies \frac{\partial}{\partial \lambda_3} \left(-\lambda_2^2 + (2 - \lambda_3)\lambda_2 + (2\lambda_3 - \frac{5}{2}\lambda_3^2) \right) = 0$$

$$\implies 2\lambda_2 + \lambda_3 - 2 = 0$$

$$\frac{\partial G}{\partial \lambda_3} = 0$$

$$\implies \frac{\partial}{\partial \lambda_3} \left(-\frac{5}{2}\lambda_3^2 + (2 - \lambda_2)\lambda_3 + (2\lambda_2 - \lambda_2^2) \right) = 0$$

$$\implies \lambda_2 + 5\lambda_3 - 2 = 0$$

1-4. Summarize.

$$\begin{cases} \lambda_1 - \lambda_2 - \lambda_3 = 0 \\ 2\lambda_2 + \lambda_3 = 2 \\ \lambda_2 + 5\lambda_3 = 2 \end{cases}$$

$$\implies \begin{bmatrix} 1 & -1 & -1 \\ 0 & 2 & 1 \\ 0 & 1 & 5 \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 2 \end{bmatrix}$$

$$\implies \begin{cases} \lambda_1 = \frac{10}{9} \\ \lambda_2 = \frac{8}{9} \\ \lambda_3 = \frac{2}{9} \end{cases}$$

Step 2. Calculate.

The discriminant function is

$$egin{aligned} f(\mathbf{x}) &= \sum_{i=1}^N \lambda_i y_i \mathbf{x}_i^ op \mathbf{x} + b \ &= (rac{10}{9}[2 \quad 1] - rac{8}{9}[1 \quad 2] - rac{2}{9}[3 \quad 3])\mathbf{x} + b \ &= \left[rac{2}{3} \quad -rac{4}{3}
ight]\mathbf{x} + b \end{aligned}$$

Get b:

$$f(\mathbf{x}_1) = 1$$
 $\Longrightarrow f(\begin{bmatrix} 2 \\ 1 \end{bmatrix}) = 1$
 $\Longrightarrow \begin{bmatrix} \frac{2}{3} & -\frac{4}{3} \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} + b = 1$
 $\Longrightarrow \frac{4}{3} - \frac{4}{3} + b = 1$
 $\Longrightarrow b = 1$

Therefore, the discriminant function would be:

$$f(\mathbf{x}) = egin{bmatrix} rac{2}{3} & -rac{4}{3} \end{bmatrix} \mathbf{x} + 1$$